

X = input space

Y = output space

f = algorithm

$$y = f(x)$$

1) $\forall x \in X \exists y \in Y: y = f(x)$

2) $\exists! y$

Stability (absolute)

$\forall \delta x : x + \delta x \in X \quad \exists k_{abs}$

$$: \|\delta y\|_Y \leq k_{abs} \|\delta x\|_X$$

$$10^{-2}$$

$$10^{16}$$

$$10^{-14}$$

Stability (relative)

$$\forall x \in X : \|x\|_X \neq 0 \Rightarrow \|f(x)\|_Y \neq 0$$

$$\Rightarrow \exists k_{rel} : \frac{\|\delta y\|_Y}{\|y\|_Y} \leq k_{rel} \frac{\|\delta x\|}{\|x\|}$$

$$\|\delta y\| = \|f(x + \delta x) - f(x)\|$$

$$y = f(x) \quad \cancel{y + \delta y} - \cancel{y}$$

Absolute Stabilität:

$$\|f(x + \delta x) - f(x)\|_Y \leq k_{abs} \underbrace{\|\delta x\|}_x$$

$$\frac{\|f(x + \delta x) - f(x)\|}{\|\delta x\|} \leq k_{abs}$$

$$k_{abs} = \sup_{x \in X} \sup_{\delta x} \frac{\|f(x + \delta x) - f(x)\|}{\|\delta x\|}$$

Example

$$X = \mathbb{R}^2$$

$$x \in X$$

$$Y = \mathbb{R}$$

$$x = (x_1, x_2) \in X$$

$$y = x_1 + x_2 \in Y$$

$$\delta x = (\delta x_1, \delta x_2) \in X$$

$$\delta y = \delta x_1 + \delta x_2$$

$$\|f(x + \delta x) - f(x)\| =$$

$$= \|\delta y\| = \|\delta x_1 + \delta x_2\|$$

$$\|x\|_X = \|x\|_{\ell^2} = |x_1| + |x_2|$$

$$\text{l}_p\text{-norm} = \left(\sum_{i=1}^n |x_i|^p \right)^{\frac{1}{p}}$$

$$p=1$$

$$\|y\|_Y = |y|$$

$$\begin{aligned}
 & \frac{\|f(x + \delta x) - f(x)\|}{\|\delta x\|} = \\
 &= \frac{\|\delta y\|}{\|\delta x\|} = \frac{|\delta x_1 + \delta x_2|}{|\delta x_1| + |\delta x_2|} \\
 &\leq \frac{|\delta x_1| + |\delta x_2|}{|\delta x_1| + |\delta x_2|} = 1
 \end{aligned}$$

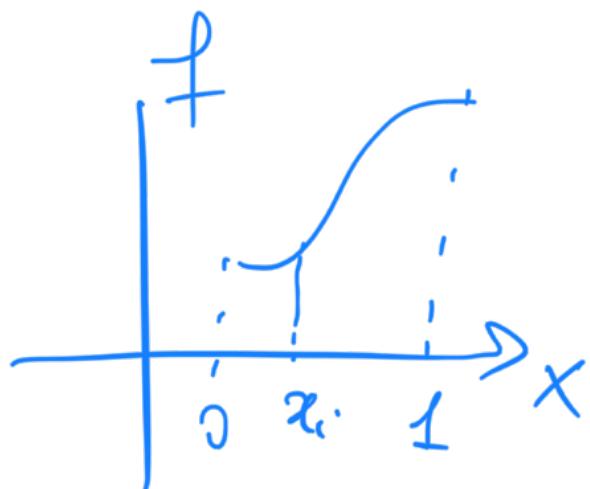
$$k_{abs} = 1$$

$$\begin{aligned}
 & \frac{\|\delta y\|}{\|y\|} \\
 &= \frac{\frac{\|\delta y\|}{\|\delta x\|}}{\frac{\|x\|}{\|x\|}} \leq 1 \\
 &\leq 1 \cdot \frac{\|x\|}{\|y\|} = \frac{|x_1| + |x_2|}{|x_1 + x_2|} \\
 &\leq \frac{|x_1| + |x_2|}{|x_1| + |x_2|} = 1
 \end{aligned}$$

$$\text{IMP} \quad \frac{\|x_1 + x_2\|}{\|x_1\| + \|x_2\|} =: K_{\text{rel}}$$

$$|x_1| \sim |x_2|$$

$$x_1, x_2 \leq 0$$



$$f \in C^0([0,1])$$

$$x_i \in [0, 1]$$

$$f'(x_i) \approx \frac{f(x_i+h) - f(x_i)}{h} \quad h \in R^+$$

NUMERICAL APPROX. OF
AN ABSTRACT PROBLEM

$$y = f(x) \rightarrow \begin{array}{l} x_n \\ y_n \text{ depending on } n \\ f_n \end{array}$$

$$x_h \rightarrow x$$

$$x_n$$

$$y_n \rightarrow y$$

$$y_n$$

$$f_n \rightarrow f$$

Numerical approxim. is well

posed $\Leftrightarrow y_n = f_n(x_n)$

is well posed $\forall n$

It is consistent when $x \in X^n$

$$\lim_{n \rightarrow \infty}$$

$$\left\| \underline{f_n(x)} - \underline{f(x)} \right\| = 0$$

$$\forall n$$

It is convergent when $(x_n \rightarrow x)$

$$\lim_{n \rightarrow \infty}$$

$$\left\| \underline{\underline{f_n(x)}} - \underline{\underline{f(x)}} \right\| = 0$$

$$f: g \in C^0([0,1]) \rightarrow$$

$$\rightarrow g'(s) = f(g(s))$$

$s \in [0,1]$

FD



CFD

$$f_n(g) = \frac{g(s + \frac{1}{n}) - g(s)}{\frac{1}{n}}$$

$$h = \frac{1}{n}$$

$$\lim_{n \rightarrow \infty} \| f_n(g) - f(g) \| \Rightarrow$$

⇒ the n. a. is consistent

Lax theorem



$| \quad 0 \quad | \quad 1' \quad x$

$$|x_{l+1} - x_l| = h = \frac{1}{h}$$

N.A is consistent

Convergence \Leftrightarrow stability

$$\begin{aligned} & \| f_h(g) - f(g) \| = \\ & = \| g(s + \frac{1}{h}) - g(s) - g'(s) \| \\ & = \| [g(s + \frac{1}{h}) - g(s)]_h - g'(s) \| = \\ & = \| [g(s) + g'(s)h + \underline{\frac{g''(s)}{2}} h^2 + \\ & + \sum_{k=3}^{\infty} \frac{g^k(s)}{k!} h^{k-1} - g(s)]_h - \underline{g(s)} \]_h - \end{aligned}$$

$$- \|g'(s)\|$$

$$\boxed{h = \frac{1}{n}}$$

$$\begin{aligned} & \|f^h(g) - f(g)\| = \\ &= \left\| \underbrace{\frac{g(s+h) - g(s)}{\frac{1}{n}} - g'(s)} \right\| \\ &= \left\| \underbrace{g(s) + g'(s) \cdot \frac{1}{n} + \frac{g''(s)}{2!} \frac{1}{h^2} + \dots - g(s)} \right\| \\ &\quad - \|g'(s)\| = \left\| \underbrace{\frac{g''(s)}{2!} \frac{1}{h^2} + \dots}_{\frac{1}{h}} \right\| = \\ &= \left\| \underbrace{\left[\frac{g''(s)}{2!} \frac{1}{h} \right]}_{\text{truncation error}} + O\left(\frac{1}{h^2}\right) \right\| \end{aligned}$$

truncation error

$$\|f^h(g) - f(g)\| =$$

$$- \|g(s+h) - g(s-h) - g'(s)\|$$

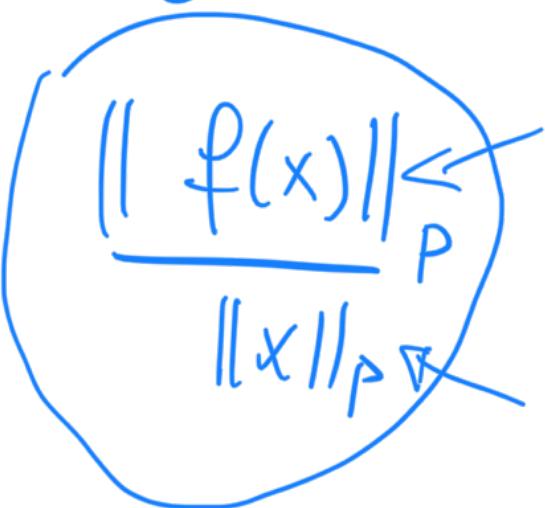
$$\frac{\|f(x') - f(x)\|}{2h} = \delta(x')$$

$$= \dots$$

Operational norm

x, y, f $y = f(x)$

$$\| \cdot \|_* = \sup_{\substack{x \in X \\ \|x\| \neq 0}} \frac{\|f(x)\|_P}{\|x\|_P}$$



$A : R^n \rightarrow R^m$

$X = R^n$ $Y = R^m$

$\Rightarrow * = P \Rightarrow \|A\|_* = \|A\|_P$

$\Rightarrow \|Ax\|_n \leq \|A\|_* \|x\|_n$

$$\|A\|_p = \sup_{\substack{x \in X \\ \|x\|_p \neq 0}} \frac{\|Ax\|_p}{\|x\|_p}$$

Example

$$n=m$$

$$X=Y=\mathbb{R}^n$$

$$y = Ax$$

$$A \in \mathbb{R}^{n \times n}$$

$$\exists k_{abs} : \forall x \in X, \forall \delta x \in X$$

$$: x + \delta x \in X \Rightarrow$$

$$\Rightarrow \frac{\|f(x + \delta x) - f(x)\|_p}{\|\delta x\|_p} \leq k_{abs}$$

$$f(x) = Ax$$

$$f(x + \delta x) = A(x + \delta x) = Ax + A\delta x$$

$$\Rightarrow \frac{\|Ax + A\delta x - Ax\|_p}{\|\delta x\|_p} =$$

$$\frac{\|\delta x\|_P}{\|\delta x\|_P} = \frac{\|A \delta x\|_P}{\|\delta x\|_P} \leq \frac{\|A\|_P \|\delta x\|_P}{\|\delta x\|_P}$$

$$\Rightarrow K_{abs} = \|A\|_P$$

$$\frac{\|sy\|}{\|y\|} \cdot \frac{\|x\|}{\|\delta x\|} \leq \frac{\|A\|_P \frac{\|x\|_P}{\|y\|_P}}{\|y\|_P}$$

$$y = f(x)$$

$$x = f^{-1}(y)$$

$$y = Ax$$

$$\downarrow$$

$$x = A^{-1}y$$

$$\Rightarrow \frac{\|A\|_P \|A^{-1}\|_P \|y\|_P}{\|y\|_P}$$

$$\Rightarrow K_{rel} = \|A\|_P \|A^{-1}\|_P$$

$$\left\{ \begin{array}{l} K_{\text{abs}} = \|A\|_p \\ K_{\text{rel}} = \|A\|_p \|A^{-1}\|_p \end{array} \right.$$

INTERPOLATION PROBLEM

We are going to approximate the elements of a space of infinite dimension by using a finite dimensional subspace (the subspace is generated / spanned by a set of linearly independent vectors)

$$V = C^0([0, 1])$$

$$P^n \subseteq V$$

$$\forall p \in P^n \quad \exists \quad \{w_i\}_{i=1}^n$$

$$p = \sum_{i=1}^n w_i \tilde{v}_i$$

\tilde{v}_i basis of P^n

$$P^n = \text{Span} \left\{ \tilde{v}_i \right\}_{i=1}^n$$

$$P^3 = \text{Span} \left\{ 1, x, x^2, x^3 \right\}$$

$$\begin{aligned} p(x) &= ax^3 + bx^2 + cx + d = \\ &= \sum_{i=0}^3 w_i \tilde{v}_i \end{aligned}$$

$$w_0 \rightarrow d \qquad w_3 \rightarrow a$$

$$w_1 \rightarrow c$$

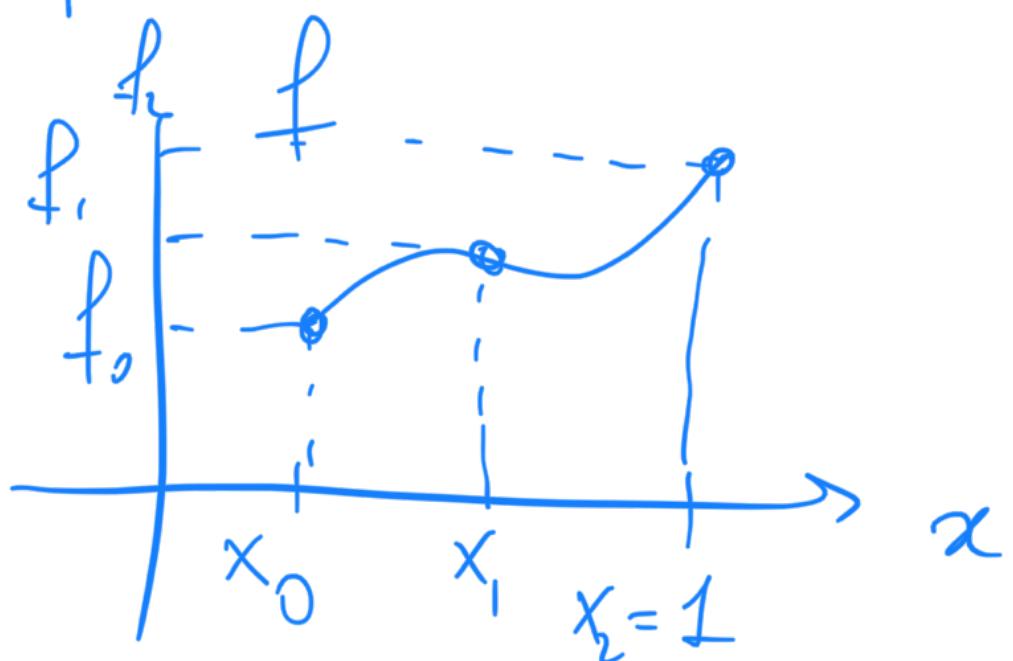
$$W_2 \rightarrow b$$

$$\tilde{V}_i = X^{i-1}$$

$\{x_i\}_{i=1}^n$ interpolation points

$\{f(x_i)\}_{i=1}^n$ values assumed by our function f on int. points

$$P(x_i) = f(x_i) \quad \forall i$$



$$P_2(x) = ax^2 + bx + c$$

r s t D

$$\left\{ \begin{array}{l} P_2(x_0) = f_0 \\ P_2(x_1) = f_1 \\ P_2(x_2) = f_2 \end{array} \right.$$



$$\begin{bmatrix} x_0^2 & x_0 & 1 \\ x_1^2 & x_1 & 1 \\ x_2^2 & x_2 & 1 \end{bmatrix} \begin{Bmatrix} a \\ b \\ c \end{Bmatrix} = \begin{Bmatrix} f_0 \\ f_1 \\ f_2 \end{Bmatrix}$$

$$\underline{V} \quad \underline{\alpha} = \underline{b}$$

Vordermenge metrix

$$\underline{\alpha} = \underline{V}^{-1} \underline{b}$$

CONDITIONING NUMBER OF
THE POLYNOMIAL INTERPOLATION

$$f: C^0([0,1]) \rightarrow \mathbb{R}^n$$

||
~~X~~ Y

$$f: C^0([0,1]) \rightarrow C^0([0,1])$$

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