

# PEU 356 Assignment 6

Mohamed Hussien El-Deeb (201900052)

May 26, 2024

## Contents

<b>1</b>	<b>5.5.2</b>	<b>2</b>
	1.1 Problem . . . . .	2
	1.2 Solution . . . . .	2
<b>2</b>	<b>5.5.4</b>	<b>4</b>
	2.1 Problem . . . . .	4
	2.2 Solution . . . . .	4
<b>3</b>	<b>5.6.1</b>	<b>7</b>
	3.1 Problem . . . . .	7
	3.2 Solution . . . . .	7
<b>4</b>	<b>5.6.2</b>	<b>12</b>
	4.1 Problem . . . . .	12
	4.2 Solution . . . . .	12
<b>5</b>	<b>5.7.1</b>	<b>16</b>
	5.1 Problem . . . . .	16
	5.2 Solution . . . . .	16
<b>6</b>	<b>5.7.2</b>	<b>17</b>
	6.1 Problem . . . . .	17
	6.2 Solution . . . . .	17

# 1 5.5.2

## 1.1 Problem

(a) Given (in  $\mathbb{R}^3$ ) the basis  $\varphi_1 = x, \varphi_2 = y, \varphi_3 = z$ , consider the basis transformation  $x \rightarrow z, y \rightarrow y, z \rightarrow -x$ . Find the  $3 \times 3$  matrix  $\mathbb{U}$  for this transformation.

(b) This transformation corresponds to a rotation of the coordinate axes. Identify the rotation and reconcile your transformation matrix with an appropriate matrix  $S(\alpha, \beta, \gamma)$  is of the form,

$$\begin{pmatrix} \cos \gamma \cos \beta \cos \alpha - \sin \gamma \sin \alpha & \cos \gamma \cos \beta \sin \alpha + \sin \gamma \cos \alpha & -\cos \gamma \sin \beta \\ -\sin \gamma \cos \beta \cos \alpha - \cos \gamma \sin \alpha & -\sin \gamma \cos \beta \sin \alpha + \cos \gamma \cos \alpha & \sin \gamma \sin \beta \\ \sin \beta \cos \alpha & \sin \beta \sin \alpha & \cos \beta \end{pmatrix}$$

(c) Form the column vector  $c$  representing (in the original basis)  $f = 2x - 3y + z$ , find the result of applying  $U$  to  $c$ , and show that this is consistent with the basis transformation of part (a).

Note. You do not need to be able to form scalar products to handle this exercise; a knowledge of the linear relationship between the original and transformed functions is sufficient.

## 1.2 Solution

(a)

$$\mathbb{U} = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ -1 & 0 & 0 \end{pmatrix}$$

(b)

$$\mathbb{U}\vec{v} = \vec{v}$$

$$\begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ -1 & 0 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

$$z = x = 0, \quad y = y$$

$$\hat{n} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$$

$$\mathbf{r}' = \mathbf{r} \cos \Phi + \mathbf{r} \times \hat{\mathbf{n}} \sin \Phi + \hat{\mathbf{n}}(\hat{\mathbf{n}} \cdot \mathbf{r})(1 - \cos \Phi)$$

$$\mathbf{r}' = (r_x \hat{i} + r_y \hat{j} + r_z \hat{k}) \cos \Phi + (r_x \hat{k} - r_z \hat{i}) \sin \Phi + r_y (1 - \cos \Phi) \hat{j}$$

$$\mathbf{r}' = \langle r_x \cos \Phi - r_z \sin \Phi, r_y, r_x \sin \Phi + r_z \cos \Phi \rangle$$

$$T = \begin{pmatrix} \cos \Phi & 0 & -\sin \Phi \\ 0 & 1 & 0 \\ \sin \Phi & 0 & \cos \Phi \end{pmatrix}$$

$$\Phi = \frac{3\pi}{2}$$

(C)

$$\begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ -1 & 0 & 0 \end{pmatrix} \begin{pmatrix} 2 \\ -3 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ -3 \\ -2 \end{pmatrix}$$

$$f = 2\varphi_1 - 3\varphi_2 + 1\varphi_3 \rightarrow f' = 1\varphi'_1 - 3\varphi'_2 - 2\varphi'_3$$

It is consistent with the basis transformation of part (a).

## 2 5.5.4

### 2.1 Problem

The unitary transformation  $U$  that converts an orthonormal basis  $\{\varphi_i\}$  into the basis  $\{\varphi'_i\}$  and the unitary transformation  $V$  that converts the basis  $\{\varphi'_i\}$  into the basis  $\{\chi_i\}$  have matrix representations

$$U = \begin{pmatrix} i \sin \theta & \cos \theta & 0 \\ -\cos \theta & i \sin \theta & 0 \\ 0 & 0 & 1 \end{pmatrix}, \quad V = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos \theta & i \sin \theta \\ 0 & \cos \theta & -i \sin \theta \end{pmatrix}.$$

Given the function  $f(x) = 3\varphi_1(x) - \varphi_2(x) - 2\varphi_3(x)$ ,

(a) By applying  $U$ , form the vector representing  $f(x)$  in the  $\{\varphi'_i\}$  basis and then by applying  $V$  form the vector representing  $f(x)$  in the  $\{\chi_i\}$  basis. Use this result to write  $f(x)$  as a linear combination of the  $\chi_i$ .

(b) Form the matrix products  $UV$  and  $VU$  and then apply each to the vector representing  $f(x)$  in the  $\{\varphi_i\}$  basis. Verify that the results of these applications differ and that only one of them gives the result corresponding to part (a).

### 2.2 Solution

$$\vec{f} = \begin{pmatrix} 3 \\ -1 \\ -2 \end{pmatrix}$$

(a)

$$\begin{pmatrix} i \sin \theta & \cos \theta & 0 \\ -\cos \theta & i \sin \theta & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 3 \\ -1 \\ -2 \end{pmatrix} = \begin{pmatrix} 3i \sin \theta - \cos \theta \\ -3 \cos \theta - i \sin \theta \\ -2 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos \theta & i \sin \theta \\ 0 & \cos \theta & -i \sin \theta \end{pmatrix} \begin{pmatrix} 3i \sin \theta - \cos \theta \\ -3 \cos \theta - i \sin \theta \\ -2 \end{pmatrix} =$$

$$\begin{pmatrix} 3i \sin \theta - \cos \theta \\ \cos \theta(-3 \cos \theta - i \sin \theta) - 2i \sin \theta \\ \cos \theta(-3 \cos \theta - i \sin \theta) + 2i \sin \theta \end{pmatrix} \\
= \begin{pmatrix} 3i \sin \theta - \cos \theta \\ -3 \cos^2 \theta - i \sin \theta \cos \theta - 2i \sin \theta \\ -3 \cos^2 \theta - i \sin \theta \cos \theta + 2i \sin \theta \end{pmatrix}$$

$$f(x) = (3i \sin \theta - \cos \theta) \chi_1(x) +$$

$$(\cos \theta(-3 \cos \theta - i \sin \theta) - 2i \sin \theta) \chi_2(x) +$$

$$(\cos \theta(-3 \cos \theta - i \sin \theta) + 2i \sin \theta) \chi_3(x)$$

(b)

UV was already implicitly calculated in part (a).

$$\begin{aligned}
VU &= \begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos \theta & i \sin \theta \\ 0 & \cos \theta & -i \sin \theta \end{pmatrix} \begin{pmatrix} i \sin \theta & \cos \theta & 0 \\ -\cos \theta & i \sin \theta & 0 \\ 0 & 0 & 1 \end{pmatrix} \\
&= \begin{pmatrix} i \sin \theta & \cos \theta & 0 \\ -\cos^2 \theta & i \sin \theta \cos \theta & i \sin \theta \\ -\cos^2 \theta & i \sin \theta \cos \theta & -i \sin \theta \end{pmatrix} \\
&\begin{pmatrix} i \sin \theta & \cos \theta & 0 \\ -\cos^2 \theta & i \sin \theta \cos \theta & i \sin \theta \\ -\cos^2 \theta & i \sin \theta \cos \theta & -i \sin \theta \end{pmatrix} \begin{pmatrix} 3 \\ -1 \\ -2 \end{pmatrix} \\
&= \begin{pmatrix} 3i \sin \theta - \cos \theta \\ -3 \cos^2 \theta - i \sin \theta \cos \theta + 2i \sin \theta \\ -3 \cos^2 \theta - i \sin \theta \cos \theta - 2i \sin \theta \end{pmatrix}
\end{aligned}$$

There is a slight difference between the two results, and only the result of UV corresponds to part (a).

$$\left(UV\vec{f}\right)_2 = \left(VU\vec{f}\right)_3, \quad \left(UV\vec{f}\right)_3 = \left(VU\vec{f}\right)_2$$

### 3 5.6.1

#### 3.1 Problem

(a) Using the two spin functions  $\varphi_1 = \alpha$  and  $\varphi_2 = \beta$  as an orthonormal basis (so  $\langle \alpha | \alpha \rangle = \langle \beta | \beta \rangle = 1, \langle \alpha | \beta \rangle = 0$ ), and the relations

$$S_x \alpha = \frac{1}{2} \beta, \quad S_x \beta = \frac{1}{2} \alpha, \quad S_y \alpha = \frac{1}{2} i \beta, \quad S_y \beta = -\frac{1}{2} i \alpha, \quad S_z \alpha = \frac{1}{2} \alpha, \quad S_z \beta = -\frac{1}{2} \beta,$$

construct the  $2 \times 2$  matrices of  $S_x, S_y$ , and  $S_z$ .

(b) Taking now the basis  $\varphi'_1 = C(\alpha + \beta), \varphi'_2 = C(\alpha - \beta)$ :

(i) Verify that  $\varphi'_1$  and  $\varphi'_2$  are orthogonal,

(ii) Assign  $C$  a value that makes  $\varphi'_1$  and  $\varphi'_2$  normalized,

(iii) Find the unitary matrix for the transformation  $\{\varphi_i\} \rightarrow \{\varphi'_i\}$ .

(c) Find the matrices of  $S_x, S_y$ , and  $S_z$  in the  $\{\varphi'_i\}$  basis.

#### 3.2 Solution

(a)

$$S_x |\alpha\rangle = \frac{1}{2} |\beta\rangle \rightarrow S_x |\alpha\rangle \langle \alpha| = \frac{1}{2} |\beta\rangle \langle \alpha| \longrightarrow (1)$$

$$S_x |\beta\rangle = \frac{1}{2} |\alpha\rangle \rightarrow S_x |\beta\rangle \langle \beta| = \frac{1}{2} |\alpha\rangle \langle \beta| \longrightarrow (2)$$

$$(1) + (2) \longrightarrow S_x (|\alpha\rangle \langle \alpha| + |\beta\rangle \langle \beta|) = \frac{1}{2} (|\beta\rangle \langle \alpha| + |\alpha\rangle \langle \beta|)$$

$$\because \sum_i |\varphi_i\rangle \langle \varphi_i| = I$$

$$S_x = \frac{1}{2} (|\beta\rangle \langle \alpha| + |\alpha\rangle \langle \beta|)$$

$$S_x = \begin{pmatrix} \alpha_1\beta_1 & \frac{\alpha_1\beta_2+\alpha_2\beta_1}{2} \\ \frac{\alpha_1\beta_2+\alpha_2\beta_1}{2} & \alpha_2\beta_2 \end{pmatrix}$$

$$S_y|\alpha\rangle = \frac{i}{2}|\beta\rangle \rightarrow S_y|\alpha\rangle\langle\alpha| = \frac{i}{2}|\beta\rangle\langle\alpha| \longrightarrow (1)$$

$$S_y|\beta\rangle = -\frac{i}{2}|\alpha\rangle \rightarrow S_y|\beta\rangle\langle\beta| = -\frac{i}{2}|\alpha\rangle\langle\beta| \longrightarrow (2)$$

$$(1) + (2) \longrightarrow S_y(|\alpha\rangle\langle\alpha| + |\beta\rangle\langle\beta|) = \frac{i}{2}(|\beta\rangle\langle\alpha| - |\alpha\rangle\langle\beta|)$$

$$S_y = \frac{i}{2}(|\beta\rangle\langle\alpha| - |\alpha\rangle\langle\beta|)$$

$$S_y = \begin{pmatrix} 0 & \frac{i(\alpha_1\beta_2-\alpha_2\beta_1)}{2} \\ \frac{i(\alpha_2\beta_1-\alpha_1\beta_2)}{2} & 0 \end{pmatrix}$$

$$S_z|\alpha\rangle = \frac{1}{2}|\alpha\rangle \rightarrow S_z|\alpha\rangle\langle\alpha| = \frac{1}{2}|\alpha\rangle\langle\alpha| \longrightarrow (1)$$

$$S_z|\beta\rangle = -\frac{1}{2}|\beta\rangle \rightarrow S_z|\beta\rangle\langle\beta| = -\frac{1}{2}|\beta\rangle\langle\beta| \longrightarrow (2)$$

$$(1) + (2) \longrightarrow S_z(|\alpha\rangle\langle\alpha| + |\beta\rangle\langle\beta|) = \frac{1}{2}(|\alpha\rangle\langle\alpha| - |\beta\rangle\langle\beta|)$$

$$S_z = \frac{1}{2}(|\alpha\rangle\langle\alpha| - |\beta\rangle\langle\beta|)$$

$$S_z = \begin{pmatrix} \frac{\alpha_1^2-\beta_1^2}{2} & \frac{\alpha_1\alpha_2-\beta_1\beta_2}{2} \\ \frac{\alpha_1\alpha_2-\beta_1\beta_2}{2} & \frac{\alpha_2^2-\beta_2^2}{2} \end{pmatrix}$$

(b)



(i)

If we assume  $C = \frac{1}{\sqrt{2}}U$  where  $U$  is a unitary matrix.

$$C^\dagger C = \left( \frac{1}{\sqrt{2}}U \right)^\dagger \frac{1}{\sqrt{2}}U = U^\dagger \frac{1}{\sqrt{2}} \frac{1}{\sqrt{2}}U = \frac{1}{2}U^\dagger U = \frac{1}{2}I$$

$$\langle \varphi'_1 | \varphi'_2 \rangle = \langle C^\dagger C(\alpha + \beta) | \alpha - \beta \rangle = \frac{1}{2} \langle \alpha + \beta | \alpha - \beta \rangle$$

$$= \frac{1}{2} (\langle \alpha | \alpha \rangle - \langle \alpha | \beta \rangle + \langle \beta | \alpha \rangle - \langle \beta | \beta \rangle) = 0$$

Note: if we want  $C$  to be constant  $U$  would just be the identity matrix.

(ii)

$$C = \frac{1}{\sqrt{2}}U$$

Where  $U$  is a unitary matrix.

$$\langle \varphi'_1 | \varphi'_1 \rangle = \langle C(\alpha + \beta) | C(\alpha + \beta) \rangle = \langle C^\dagger C(\alpha + \beta) | (\alpha + \beta) \rangle$$

$$= \frac{1}{2} \langle (\alpha + \beta) | (\alpha + \beta) \rangle = \frac{1}{2} (\langle \alpha | \alpha \rangle + \langle \beta | \beta \rangle + \langle \alpha | \beta \rangle + \langle \beta | \alpha \rangle) = 1$$

$$\langle \varphi'_2 | \varphi'_2 \rangle = \langle C(\alpha - \beta) | C(\alpha - \beta) \rangle = \langle C^\dagger C(\alpha - \beta) | (\alpha - \beta) \rangle$$

$$= \frac{1}{2} \langle (\alpha - \beta) | (\alpha - \beta) \rangle = \frac{1}{2} (\langle \alpha | \alpha \rangle + \langle \beta | \beta \rangle - \langle \alpha | \beta \rangle - \langle \beta | \alpha \rangle) = 1$$

(iii)

$$T = \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{pmatrix}$$

Note: there is a mistake in the question,  $T$  is not a unitary matrix. If we want  $T$  to be unitary, then  $\varphi_2 = -C(\alpha - \beta)$ , there should be a negative sign that was not included. This will not have an effect on the rest of the answers.

If we follow the fix  $T$  would be a unitary matrix.

$$T = \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix}$$

(c)

We simply need to substitute  $\alpha_i \rightarrow \frac{1}{\sqrt{2}}(\alpha_i + \beta_i)$  and  $\beta_i \rightarrow \frac{1}{\sqrt{2}}(\alpha_i - \beta_i)$  into the matrices of  $S_x, S_y$ , and  $S_z$ .

$$S_x = \begin{pmatrix} \alpha_1\beta_1 & \frac{\alpha_1\beta_2 + \alpha_2\beta_1}{2} \\ \frac{\alpha_1\beta_2 + \alpha_2\beta_1}{2} & \alpha_2\beta_2 \end{pmatrix}$$

$$S_y = \begin{pmatrix} 0 & \frac{i(\alpha_1\beta_2 - \alpha_2\beta_1)}{2} \\ -\frac{i(\alpha_1\beta_2 - \alpha_2\beta_1)}{2} & 0 \end{pmatrix}$$

$$S_z = \begin{pmatrix} \frac{\alpha_1^2 - \beta_1^2}{2} & \frac{\alpha_1\alpha_2 - \beta_1\beta_2}{2} \\ \frac{\alpha_1\alpha_2 - \beta_1\beta_2}{2} & \frac{\alpha_2^2 - \beta_2^2}{2} \end{pmatrix}$$

$$S_x' = \begin{pmatrix} \frac{\frac{1}{\sqrt{2}}(\alpha_1 + \beta_1) \frac{1}{\sqrt{2}}(\alpha_1 - \beta_1)}{\frac{\frac{1}{\sqrt{2}}(\alpha_1 + \beta_1) \frac{1}{\sqrt{2}}(\alpha_2 - \beta_2) + \frac{1}{\sqrt{2}}(\alpha_2 + \beta_2) \frac{1}{\sqrt{2}}(\alpha_1 - \beta_1)}{2}} & \frac{\frac{1}{\sqrt{2}}(\alpha_1 + \beta_1) \frac{1}{\sqrt{2}}(\alpha_2 - \beta_2) + \frac{1}{\sqrt{2}}(\alpha_2 + \beta_2) \frac{1}{\sqrt{2}}(\alpha_1 - \beta_1)}{2} \\ \frac{\frac{1}{\sqrt{2}}(\alpha_1 + \beta_1) \frac{1}{\sqrt{2}}(\alpha_2 - \beta_2) + \frac{1}{\sqrt{2}}(\alpha_2 + \beta_2) \frac{1}{\sqrt{2}}(\alpha_1 - \beta_1)}{2} & \frac{1}{\sqrt{2}}(\alpha_2 + \beta_2) \frac{1}{\sqrt{2}}(\alpha_2 - \beta_2) \end{pmatrix}$$

$$S_x' = \begin{pmatrix} \frac{1}{2}(\alpha_1^2 - \beta_1^2) & \frac{\alpha_1\alpha_2 - \beta_1\beta_2}{2} \\ \frac{\alpha_1\alpha_2 - \beta_1\beta_2}{2} & \frac{1}{2}(\alpha_2^2 - \beta_2^2) \end{pmatrix}$$

$$\alpha_1\beta_2 - \alpha_2\beta_1 \rightarrow \frac{1}{2}((\alpha_1 + \beta_1)(\alpha_2 - \beta_2) - (\alpha_2 + \beta_2)(\alpha_1 - \beta_1))$$

$$= \alpha_2\beta_1 - \alpha_1\beta_2$$

$$S_y' = \begin{pmatrix} 0 & -\frac{i(\alpha_1\beta_2-\alpha_2\beta_1)}{2} \\ \frac{i(\alpha_1\beta_2-\alpha_2\beta_1)}{2} & 0 \end{pmatrix}$$

$$S_z' = \begin{pmatrix} \alpha_1\beta_1 & \frac{\alpha_1\beta_2+\alpha_2\beta_1}{2} \\ \frac{\alpha_1\beta_2+\alpha_2\beta_1}{2} & \alpha_2\beta_2 \end{pmatrix}$$

## 4 5.6.2

### 4.1 Problem

For the basis  $\varphi_1 = Cxe^{-r^2}$ ,  $\varphi_2 = Cye^{-r^2}$ ,  $\varphi_3 = Cze^{-r^2}$ , where  $r^2 = x^2 + y^2 + z^2$ , with the scalar product defined as an unweighted integral over  $\mathbb{R}^3$  and with  $C$  chosen to make the  $\varphi_i$  normalized:

(a) Find the  $3 \times 3$  matrix of  $L_x = -i \left( y \frac{\partial}{\partial z} - z \frac{\partial}{\partial y} \right)$ ;

(b) Using the transformation matrix  $U = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1/\sqrt{2} & -i/\sqrt{2} \\ 0 & 1/\sqrt{2} & i/\sqrt{2} \end{pmatrix}$ , find the transformed matrix of  $L_x$ ;

(c) Find the new basis functions  $\varphi'_i$  defined by the transformation  $U$ , and write explicitly (in terms of  $x, y$ , and  $z$ ) the functional forms of  $L_x \varphi'_i$ ,  $i = 1, 2, 3$ .

Hint. Use  $\int e^{-r^2} d^3r = \pi^{3/2}$ ,  $\int x^2 e^{-r^2} d^3r = \frac{1}{2} \pi^{3/2}$ ; the integrals are over  $\mathbb{R}^3$ .

### 4.2 Solution

(a)

$$A_{nm} = \langle \phi_n | \hat{A} | \phi_m \rangle$$

$$L_x = -i \left( y \frac{\partial}{\partial z} - z \frac{\partial}{\partial y} \right)$$

$$\langle \phi_n | L_x | \phi_m \rangle = -i \left\langle \phi_n \left| y \frac{\partial}{\partial z} - z \frac{\partial}{\partial y} \right| \phi_m \right\rangle$$

$$\langle \phi_n | \phi_m \rangle = \int \phi_n^* \phi_m d^3r$$

$$\langle \phi_n | L_x | \phi_m \rangle = -i \int \phi_n^* \left( y \frac{\partial}{\partial z} - z \frac{\partial}{\partial y} \right) \phi_m d^3r$$

$$\begin{aligned}
&= -i|C|^2 \int x_n e^{-r^2} \left( x_2 \frac{\partial}{\partial x_3} - x_3 \frac{\partial}{\partial x_2} \right) x_m e^{-r^2} d^3 r \\
&= -i|C|^2 \int x_n e^{-r^2} \left( x_2 \frac{\partial (x_m e^{-r^2})}{\partial x_3} - x_3 \frac{\partial (x_m e^{-r^2})}{\partial x_2} \right) d^3 r \\
&= -i|C|^2 \int x_n e^{-r^2} \left( x_2 \left( \delta_3^m e^{-r^2} + x_m \frac{\partial e^{-r^2}}{\partial x_3} \right) - x_3 \left( \delta_2^m e^{-r^2} + x_m \frac{\partial e^{-r^2}}{\partial x_2} \right) \right) d^3 r \\
&\quad \frac{\partial e^{-r^2}}{\partial x_i} = -2r \frac{\partial r}{\partial x_i} e^{-r^2} = -2x_i e^{-r^2} \\
&= -i|C|^2 \int x_n e^{-2r^2} (x_2 (\delta_3^m - 2x_m x_3) - x_3 (\delta_2^m - 2x_m x_2)) d^3 r \\
&\quad L_{nm} = i|C|^2 \int e^{-2r^2} x_n (x_3 \delta_2^m - x_2 \delta_3^m) d^3 r \\
&\quad L_{nm} = i|C|^2 \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} e^{-2x_1^2} e^{-2x_2^2} e^{-2x_3^2} x_n (x_3 \delta_2^m - x_2 \delta_3^m) dx_1 dx_2 dx_3
\end{aligned}$$

From this we can see that only the terms with  $n = 2, m = 3$  and  $n = 3, m = 2$  will survive. Because they are the product of two even functions, the rest are have odd symmetry and will integrate to zero.

$$\begin{aligned}
L_{23} &= -i|C|^2 \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} e^{-2x_1^2} e^{-2x_2^2} e^{-2x_3^2} x_2^2 dx_1 dx_2 dx_3 \\
&= -i|C|^2 \int_{-\infty}^{\infty} e^{-2x_1^2} dx_1 \int_{-\infty}^{\infty} x_2^2 e^{-2x_2^2} dx_2 \int_{-\infty}^{\infty} e^{-2x_3^2} dx_3
\end{aligned}$$

$$= -i|C|^2 \left( \frac{\pi^{\frac{3}{2}}}{8\sqrt{2}} \right)$$

$$|C|^2 = \frac{8\sqrt{2}}{\pi^{\frac{3}{2}}}$$

$$L_{23} = -i$$

$$L_{32} = i \frac{8\sqrt{2}}{\pi^{\frac{3}{2}}} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} e^{-2x_1^2} e^{-2x_2^2} e^{-2x_3^2} x_3^2 dx_1 dx_2 dx_3$$

$$= i \frac{8\sqrt{2}}{\pi^{\frac{3}{2}}} \int_{-\infty}^{\infty} e^{-2x_1^2} dx_1 \int_{-\infty}^{\infty} e^{-2x_2^2} dx_2 \int_{-\infty}^{\infty} x_3^2 e^{-2x_3^2} dx_3$$

$$= i \frac{8\sqrt{2}}{\pi^{\frac{3}{2}}} \left( \frac{\pi^{\frac{3}{2}}}{8\sqrt{2}} \right) = i$$

$$L_x = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & -i \\ 0 & i & 0 \end{pmatrix}$$

(b)

U is a unitary matrix. because  $UU^\dagger = I$ .

$$U^{-1} = U^\dagger$$

$$UL_xU^\dagger = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{\sqrt{2}} & -\frac{i}{\sqrt{2}} \\ 0 & \frac{1}{\sqrt{2}} & \frac{i}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & -i \\ 0 & i & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ 0 & \frac{i}{\sqrt{2}} & -\frac{i}{\sqrt{2}} \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{\sqrt{2}} & -\frac{i}{\sqrt{2}} \\ 0 & \frac{1}{\sqrt{2}} & \frac{i}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} 0 & 0 & 0 \\ 0 & \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ 0 & \frac{i}{\sqrt{2}} & \frac{i}{\sqrt{2}} \end{pmatrix}$$

$$= \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{pmatrix}$$

(c)

$$x \rightarrow x, \quad y \rightarrow \frac{1}{\sqrt{2}}(y + iz), \quad z \rightarrow \frac{1}{\sqrt{2}}(y - iz)$$

$$\varphi'_1 = Cxe^{-r^2}$$

$$\varphi'_2 = \frac{C}{\sqrt{2}}(y + iz)e^{-r^2}$$

$$\varphi'_3 = \frac{C}{\sqrt{2}}(y - iz)e^{-r^2}$$

$L_x$  transforms as follows:

$$x \rightarrow 0, \quad y \rightarrow -iz, \quad z \rightarrow iy$$

$$L_x \varphi'_1 = 0$$

$$L_x \varphi'_2 = -\frac{C}{\sqrt{2}}(y + iz)e^{-r^2}$$

$$L_x \varphi'_3 = \frac{C}{\sqrt{2}}(y - iz)e^{-r^2}$$

## 5 5.7.1

### 5.1 Problem

Using the formal properties of unitary transformations, show that the commutator  $[x, p] = i$  is invariant under unitary transformation of the matrices representing  $x$  and  $p$ .

### 5.2 Solution

$$[x, p] = i$$

$$UxU^\dagger = x'$$

$$UpU^\dagger = p'$$

$$[x', p'] = UxU^\dagger UpU^\dagger - UpU^\dagger UxU^\dagger$$

$$= UxpU^\dagger - UpxU^\dagger = U[x, p]U^\dagger = UiU^\dagger = i$$



## 6 5.7.2

### 6.1 Problem

The Pauli matrices

$$\sigma_1 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad \sigma_2 = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \quad \sigma_3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix},$$

have commutator  $[\sigma_1, \sigma_2] = 2i\sigma_3$ . Show that this relationship continues to be valid if these matrices are transformed by

$$\mathbf{U} = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix}.$$

### 6.2 Solution

$$\begin{aligned} \mathbf{U}\sigma_1\mathbf{U}^\dagger &= \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \\ &= \begin{pmatrix} \sin \theta & \cos \theta \\ \cos \theta & -\sin \theta \end{pmatrix} \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \\ &= \begin{pmatrix} \sin 2\theta & \cos 2\theta \\ \cos 2\theta & -\sin 2\theta \end{pmatrix} \end{aligned}$$

$$\begin{aligned} \mathbf{U}\sigma_2\mathbf{U}^\dagger &= \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \\ &= \begin{pmatrix} i \sin \theta & -i \cos \theta \\ i \cos \theta & i \sin \theta \end{pmatrix} \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \\ &= \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \end{aligned}$$

$$\mathbf{U}\sigma_3\mathbf{U}^\dagger = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$$

$$\begin{aligned}
&= \begin{pmatrix} \cos \theta & -\sin \theta \\ -\sin \theta & -\cos \theta \end{pmatrix} \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \\
&= \begin{pmatrix} \cos 2\theta & -\sin 2\theta \\ -\sin 2\theta & -\cos 2\theta \end{pmatrix}
\end{aligned}$$

$$\begin{aligned}
[\mathbf{U}\sigma_1\mathbf{U}^\dagger, \mathbf{U}\sigma_2\mathbf{U}^\dagger] &= \begin{pmatrix} \sin 2\theta & \cos 2\theta \\ \cos 2\theta & -\sin 2\theta \end{pmatrix} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} - \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} \sin 2\theta & \cos 2\theta \\ \cos 2\theta & -\sin 2\theta \end{pmatrix} \\
&= \begin{pmatrix} i \cos 2\theta & -i \sin 2\theta \\ -i \sin 2\theta & -i \cos 2\theta \end{pmatrix} - \begin{pmatrix} -i \cos 2\theta & i \sin 2\theta \\ i \sin 2\theta & i \cos 2\theta \end{pmatrix} \\
&= \begin{pmatrix} 2i \cos 2\theta & -2i \sin 2\theta \\ -2i \sin 2\theta & -2i \cos 2\theta \end{pmatrix} \\
&= 2i\mathbf{U}\sigma_3\mathbf{U}^\dagger
\end{aligned}$$

## References

- [1] G.B. Arfken, H.J. Weber, and F.E. Harris. *Mathematical Methods for Physicists: A Comprehensive Guide*. Elsevier Science, 2013.
- [2] M.H. El-Deeb. [PEU-356 Assignments](#).