## BRCP( Bayesian Regression Change Point) for Anomaly Detection

For the changepoint at time  $\tau$ , we assume error function is independent with time, then:

$$y = \begin{cases} f_1(x_t) + \varepsilon_{1,t}, & \text{if } t \le \tau \\ f_2(x_t) + \varepsilon_{2,t}, & \text{if } t > \tau \end{cases}$$
 (1)

 $\tau$  is the time for change point,  $f_1(x_t)$  and  $f_2(x_t)$  are polynomial fuction, y is obvious point value,t is time series index,  $\varepsilon_1$ ,  $\varepsilon_2$  are timeseries data with mean: 0 and variance:  $\sigma_1$ ,  $\sigma_2$ . The detail is below:

## Initialization:

$$l = 0, \alpha^{(0)} = \left\{\alpha_1^{(0)}, \alpha_2^{(0)}, \cdots, \alpha_n^{(0)}\right\} = \left\{1.0/n\,\text{,}\, 1.0/n\,\text{,}\, \cdots\,\text{,}\, 1.0/n\right\}$$

l is iteration number,  $\alpha_i^{(0)}$  stand for the probability that time point i is a change point, n is the size of the time series data.

**Step 1:** Calculate  $\mu_{ki}$  with formula (2):

$$\mu_{kj} = \begin{cases} \sum_{i=j}^{n-1} \alpha_i, & \text{if } k = 1 \text{ and } 1 \le j \le n-1 \\ 0, & \text{if } k = 1 \text{ and } j = n \\ 1 - \mu_{1j}, & \text{if } k = 2 \end{cases}$$
 (2)

 $k=\{1,\!2\},\ j=\{1,\!2,\cdots,n\},$   $\mu_{kj}$  denote the probability for  $\tau\leq j$ 

$$\beta_k = (X^T U_k X)^{-1} X^T U_k Y \tag{3}$$

Step 2: Calculate  $\beta_k$  with formula (3);  $\beta_k = (X^T U_k X)^{-1} X^T U_k Y \qquad (3)$   $X = [x_1, x_2, \cdots, x_n], \ U_k = diag([\mu_{k1}, \mu_{k2}, \cdots, \mu_{kn}]), \ Y = [y_1, y_2, \cdots, y_n] \ \text{and} \ \beta_k \ \text{need meet the}$ condition below:

$$y_t = f_k(x_t) + \varepsilon_{k,t} = x_t \beta_k + \varepsilon_{k,t}$$
 (4)

Step 3: Calculate d<sub>i</sub>, with formula (5):

$$d_{i} = \sum_{j=1}^{i} \log \left( g_{1}(\varepsilon_{1,j}) \right) + \sum_{j=i+1}^{n} \log \left( g_{2}(\varepsilon_{2,j}) \right)$$
 (5)

 $d_i = \sum_{j=1}^i log \left(g_1 \left(\epsilon_{1,j}\right)\right) + \sum_{j=i+1}^n log \left(g_2 \left(\epsilon_{2,j}\right)\right) \tag{5}$   $g_1$  and  $g_2$  are the distribution function of the noise. If the distribution function is Ga ussian, the formula (5) can rewrite as:

$$d_{i} = \sum_{j=1}^{i} \left( \frac{\varepsilon_{1,j}^{2}}{\operatorname{sd}(\varepsilon_{1})^{2}} - 0.5\log(\operatorname{sd}(\varepsilon_{1})) \right) + \sum_{j=i+1}^{n} \frac{\varepsilon_{2,j}^{2}}{\operatorname{sd}(\varepsilon_{2})^{2}} - 0.5\log(\operatorname{sd}(\varepsilon_{2}))$$
(6)

when  $f_k(x_t)$  is a good prediction, we have  $\frac{\varepsilon_{1,j}^2}{sd(\varepsilon_1)^2} \approx \varepsilon_{1,j}^2$  and  $\frac{\varepsilon_{2,j}^2}{sd(\varepsilon_2)^2} \approx \varepsilon_{2,j}^2$ , then:

$$d_{i} \approx \sum_{j=1}^{i} \left( \varepsilon_{1,j}^{2} - 0.5 \log(\operatorname{sd}(\varepsilon_{1})) \right) + \sum_{j=i+1}^{n} \varepsilon_{2,j}^{2} - 0.5 \log(\operatorname{sd}(\varepsilon_{2}))$$
 (7)

 $\textbf{Step 4:} \quad \text{Calculate} \quad \alpha^{(l+1)} = \left\{\alpha_1^{(l+1)}, \alpha_2^{(l+1)}, \cdots, \alpha_n^{(l+1)}\right\} \text{ with formula (8):}$ 

$$\alpha_{i}^{(l+1)} = \frac{\exp(-d_{i}^{2})}{\sum_{i=1}^{n-1} \exp(-d_{i}^{2})}$$
(8)

**Step 5:** If  $\|\alpha^{(l+1)} - \alpha^{(l)}\| < \epsilon$ , then stop the iteration, else come back to step 1.

**Step 6:** 
$$CP = \underset{i}{argmax} \alpha_i^{(l)}$$
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