

EE324 CONTROL SYSTEMS LAB

PROBLEM SHEET 4

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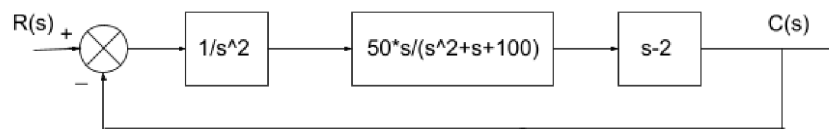
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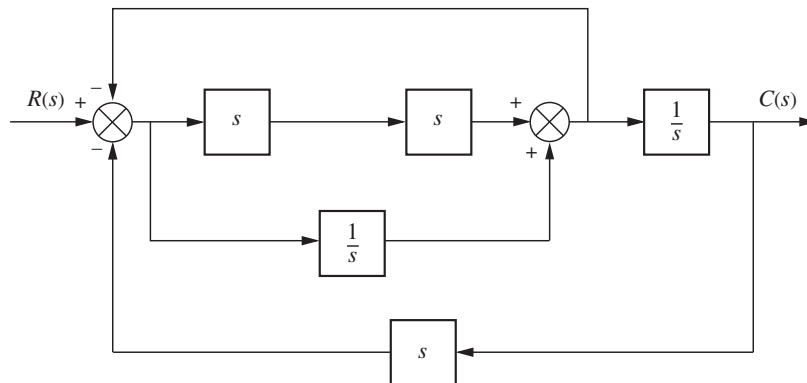
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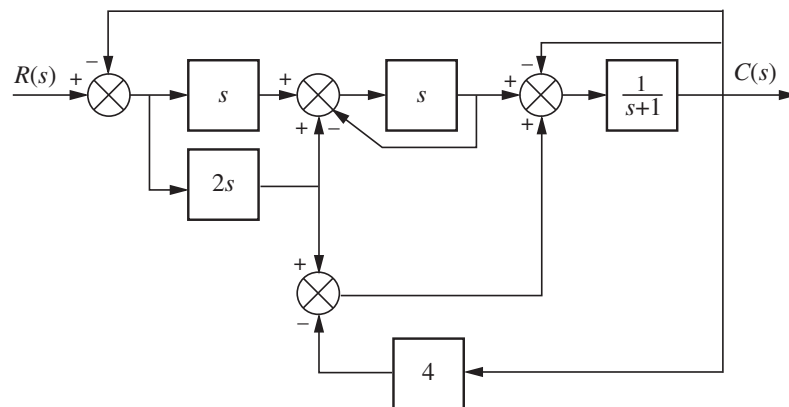
1 Q1



(a)



(b)



(c)

a)

```
> s = %s;
> G1 = 1/s^2;
> G2 = 50*s/(s^2+s+100);
> G3 = s-2;
> G = G1*G2*G3;
> TF = G/(1+G)
TF =
      -100 +50s
      -----
    -100 +150s +1s^2 +s^3
```

Input-Output Transfer Function is

$$TF(s) = \frac{50s - 100}{s^3 + s^2 + 150s - 100}$$

b)

```
> s = %s;
> G1 = s;
> G2 = 1/s;
> G = G1*G1 ;
> G = G+G2;
> G = G*G2;
> H = G1+G1;
> TF = G/(1+G*H)
TF =
      1 +s^3
      -----
    2s +s^2 +2s^4
```

Input-Output Transfer Function is

$$TF(s) = \frac{s^3 + 1}{2s^4 + s^2 + 2s}$$

c)

```
> s = %s;
> G0 = 4;
> G1 = s;
> G2 = 2*s;
> G3 = 1/(s+1);
> GLA = G1 + G2;
> GM = G1/(1+G1);
> GLB = G2;
> GLA = GLA * GM;
> GL = GLA + GLB;
> HR = G0 + 1;
> GR = G3/(1+G3*HR);
> G = GL * GR;
> T = G/(1+G)
T =
    0.3333333s +0.8333333s^2
    -----
      1 +1.5s +s^2
```

Input-Output Transfer Function is (after simplifying result)

$$TF(s) = \frac{5s^2 + 2s}{6s^2 + 9s + 6}$$

2 Q2

$$G(s) = \frac{10}{s(s+2)(s+4)}$$

a)

Scilab function to find the closed-loop transfer function for a given value of K

```
--> function TF = CLTFPositiveUnity(G,K)
>     TF = K*G/(1+K*G);
> endfunction
```

```
> s = %s;
> G = 10/(s*(s+2)*(s+4));
> K = 4.2;
> TF = CLTFPositiveUnity(G,K)
TF =
      42
-----
42 +8s +6s2 +s3
```

b)

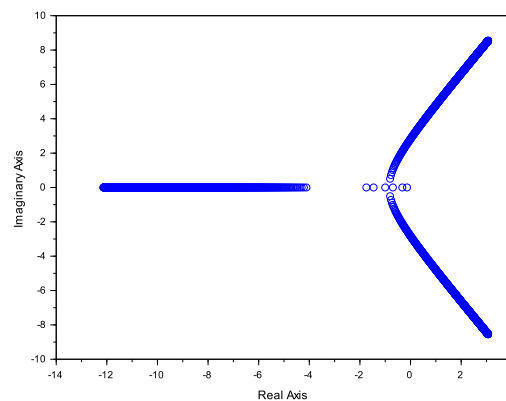


Figure 2.1: $K \in \{0 : 0.1 : 100\}$

Code to obtain Figure 2.1

```
Kvalues = 0:0.1:100;
pR = [];
pI = [];
for i = 1:length(Kvalues)
    K = Kvalues(i);
    TF = CLTFPositiveUnity(G,K);
    [zeroes, poles, k] = tf2zp(TF);
    for j = 1:length(poles)
        p = poles(j);
        pR($+1) = real(p);
        pI($+1) = imag(p);
    end
end
scatter(pR,pI);
xlabel("Real Axis"); ylabel("Imaginary Axis");
xs2pdf(0, 'Q2b');
```

c)

The critical value of K that takes the closed-loop system to the verge of instability is about 4.8

This will happen when a pole has real part 0 but we may not get such pole in simulation. Hence, I have taken the minimum K such that real part of any pole exceeds 0.

Code for finding critical value (if it exists)

```
Kvalues = 0:0.1:100;
Kcritical = -1;
b = 0;
for i = 1:length(Kvalues)
    if b == 1
        break;
    end
    K = Kvalues(i);
    TF = CLTFPositiveUnity(G,K);
    [zeroes, poles, k] = tf2zp(TF);
    for j = 1:length(poles)
        if real(poles(j)) > 0
            Kcritical = K;
            b = 1
            break
        end
    end
end
> disp(Kcritical) // If Kcritical = -1 then there is no such K in Kvalues
4.8000000
```

d)

It is clear from the following code that the system is unstable as number of sign changes > 0 .

A very small negative part demonstrates it's *Criticality*.

For $K = 4.79$ (just less than 4.8) number of sign changes = 0, so that system is still stable.

```
> K = 4.8;
> TF = CLTFPositiveUnity(G,K);
> [r, num] = routh_t(TF.den)
r =
    1.         8.         // s3 row
    6.        48.         // s2 row
   -8.882D-15    0.         // s1 row
    48.         0.         // s0 row
num =
    2.

> K = 4.79;
> TF = CLTFPositiveUnity(G,K);
> [r, num] = routh_t(TF.den)
r =
    1.         8.         // s3 row
    6.        47.9        // s2 row
    0.0166667    0.         // s1 row
    47.9         0.         // s0 row
num =
    0.
```

3 Q3

a)

$$P(s) = s^5 + 3 * s^4 + 5 * s^3 + 4 * s^2 + s + 3$$

```
> P = s^5 + 3*s^4 + 5*s^3 + 4*s^2 + s + 3;
> [r, num] = routh_t(P)
r =
    1.          5.    1.          // s^5 row
    3.          4.    3.          // s^4 row
    3.6666667    0.    0.          // s^3 row
    4.          3.    0.          // s^2 row
   -2.75         0.    0.          // s^1 row
    3.          0.    0.          // s^0 row
num =
    2.
```

b)

$$P(s) = s^5 + 6 * s^3 + 5 * s^2 + 8 * s + 20$$

```
> P = s^5 + 6*s^3 + 5*s^2 + 8*s + 20;
> [r, num] = routh_t(P)
r =
      1          6      8      // s^5 row
      -          -      -
      1          1      1
      eps          5      20  // s^4 row
      ---          -      --
      1          1      1
      -5 +6eps      -20 +8eps  0  // s^3 row
      -----          -----
      eps          eps      1
      -25 +50eps -8eps^2      20      0  // s^2 row
      -----          --      -
      -5 +6eps          1      1
      -2.274D-13 -160eps -64eps^2      0      0  // s^1 row
      -----          -      -
      -25 +50eps -8eps^2          1      1
      20          0      0  // s^0 row
      --          -      -
      1          1      1
num =
    2.
```

c)

$$P(s) = s^5 - 2 * s^4 + 3 * s^3 - 6 * s^2 + 2 * s - 4$$

```
> P = s^5 - 2*s^4 + 3*s^3 - 6*s^2 + 2*s - 4;
> [r, num] = routh_t(P)
r =
    1.         3.         2.           // s^5 row
   -2.        -6.        -4.           // s^4 row
   -8.       -12.         0.           // s^3 row
   -3.        -4.         0.           // s^2 row
  -1.33333333  0.         0.           // s^1 row
   -4.         0.         0.           // s^0 row
num =
    1.
```

d)

$$P(s) = s^6 + s^5 - 6 * s^4 + s^2 + s - 6$$

```
> P = s^6 + s^5 - 6*s^4 + s^2 + s - 6;
> [r, num] = routh_t(P)
r =
    1    -6     1    -6           // s^6 row
    -    --    -    --
    1     1     1     1

    1     0     1     0           // s^5 row
    -    -    -    -
    1     1     1     1

   -6     0    -6     0           // s^4 row
   --    -    --    -
    1     1     1     1

  -24     0     0     0           // s^3 row
  ---    -    -    -
    1     1     1     1

  eps    -6     0     0           // s^2 row
  ---    --    -    -
    1     1     1     1

 -144     0     0     0           // s^1 row
 ----    -    -    -
  eps     1     1     1

 864     0     0     0           // s^0 row
 ----    -    -    -
 -144     1     1     1
num =
    3.
```

4 Q4

a)

To construct a degree 6 polynomial whose R-H table has its entire row corresponding to s^3 to be zero, we need a degree $(3 + 1 = 4)$ even polynomial. Say,

$$P(s) = \underbrace{(s^4 + 16)}_{\text{even}} \cdot (s^4 - 16)$$

$$P(s) = s^6 + 2s^5 + s^4 + 16s^2 + 32s + 16$$

Note that s^4 and s^5 rows are linearly dependent, hence entire row will be 0 in s^3 .

```
> P = (s^4+16)*(s^2+2*s+1)
P =
16 +32s +16s^2 +s^4 +2s^5 +s^6
> [r, num] = routh_t(P)
r =
1      1      16      16          // s^6 row
-      -      --      --
1      1      1      1

2      0      32      0          // s^5 row
-      -      --      -
1      1      1      1

1      0      16      0          // s^4 row
-      -      --      -
1      1      1      1

4      0      0      0          // s^3 row
-      -      -      -
1      1      1      1

eps     16      0      0          // s^2 row
---     --      -      -
1      1      1      1

-64      0      0      0          // s^1 row
---      -      -      -
eps      1      1      1

-1024     0      0      0          // s^0 row
-----     -      -      -
-64      1      1      1
num =
2.
```

b)

To construct a degree 8 polynomial whose R-H table has its entire row corresponding to s^3 to be zero, we need a degree $(3 + 1 = 4)$ even polynomial. Say,

$$P(s) = \underbrace{(s^4 + 16)}_{\text{even}} \cdot (s^2 + 2s + 1)^2$$

$$P(s) = s^8 + 4s^7 + 6s^6 + 4s^5 + 17s^4 + 64s^3 + 96s^2 + 64s + 16$$

Note that s^4 and s^5 rows are linearly dependent, hence entire row will be 0 in s^3 .

```
> P = (s^4+16)*(s^2+2*s+1)^2
P =
s^8 +4s^7 +6s^6 +4s^5 +17s^4 +64s^3 +96s^2 +64s +16
> [r, num] = routh_t(P)
r =
 1      6      17      96      16          // s^8 row
-      -      --      --      -
 1      1      1      1      1

 4      4      64      64      0          // s^7 row
-      -      --      --      -
 1      1      1      1      1

 5      1      80      16      0          // s^6 row
-      -      --      --      -
 1      1      1      1      1

3.2      0      51.2      0      0          // s^5 row
---      -      ----      -      -
 1      1      1      1      1

 1      0      16      0      0          // s^4 row
-      -      --      -      -
 1      1      1      1      1

 4      0      0      0      0          // s^3 row
-      -      -      -      -
 1      1      1      1      1

eps      16      0      0      0          // s^2 row
---      --      -      -      -
 1      1      1      1      1

-64      0      0      0      0          // s^1 row
---      -      -      -      -
eps      1      1      1      1

-1024      0      0      0      0          // s^0 row
-----      -      -      -      -
-64      1      1      1      1
num =
2.
```


c)

To construct a degree 6 polynomial whose R-H table has its first entry in its row corresponding to s^3 to be zero, first take a general degree 6 polynomial $a_0 + a_1s + a_2s^2 + a_3s^3 + a_4s^4 + a_5s^5 + a_6s^6$.

s^6	a_6	a_4	a_2
s^5	a_5	a_3	a_1
s^4	$(a_6a_3 - a_5a_4)$	$(a_6a_1 - a_5a_2)$	0
s^3	$a_5(a_6a_1 - a_5a_2) - a_3(a_6a_3 - a_5a_4)$	x	0

Hence, $a_5(a_6a_1 - a_5a_2) = a_3(a_6a_3 - a_5a_4)$.

Now, take $a_6 = 1, a_5 = 2, a_4 = 3, a_3 = 4, a_2 = 5 \rightarrow a_1 = 6$ take a_0 as 7 (a_0 doesn't effect first entry s^3)

$$P = s^6 + 2s^5 + 3s^4 + 4s^3 + 5s^2 + 6s + 7$$

Note that first 2 elements of s^4 and s^5 rows are linearly dependent, hence first element of s^3 row will be 0

```

> P = 7+6*s+5*s^2+4*s^3+3*s^4+2*s^5+s^6;
> [r, num] = routh_t(P)
r =
    1      3      5      7      // s^6 row
    -      -      -      -
    1      1      1      1
    2      4      6      0      // s^5 row
    -      -      -      -
    1      1      1      1
    1      2      7      0      // s^4 row
    -      -      -      -
    1      1      1      1
    eps     -8      0      0      // s^3 row
    ---     --      -      -
    1      1      1      1
    8 +2eps    7      0      0      // s^2 row
    -----    -      -      -
    eps        1      1      1
    -64 -16eps -7eps^2  0      0      0      // s^1 row
    -----    -      -      -
    8 +2eps      1      1      1
    7           0      0      0      // s^0 row
    -           -      -      -
    1           1      1      1
num =
    2.

```