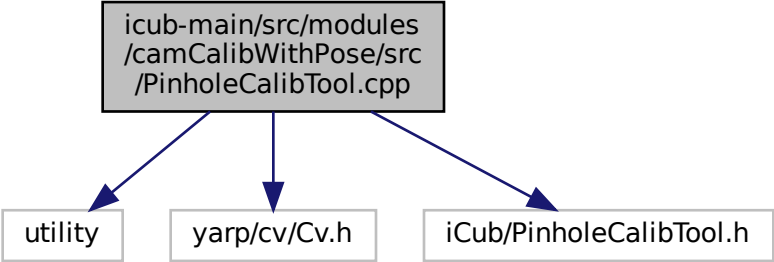


icub-main/src/modules
/camCalibWithPose/src
/PinholeCalibTool.cpp



```
graph TD; A["icub-main/src/modules  
/camCalibWithPose/src  
/PinholeCalibTool.cpp"] --> B["utility"]; A --> C["yarp/cv/Cv.h"]; A --> D["iCub/PinholeCalibTool.h"];
```

The diagram illustrates the dependencies of the file `icub-main/src/modules/camCalibWithPose/src/PinholeCalibTool.cpp`. It is represented as a central box at the top, with three arrows pointing downwards to three separate boxes below it. The first arrow points to a box labeled `utility`. The second arrow points to a box labeled `yarp/cv/Cv.h`. The third arrow points to a box labeled `iCub/PinholeCalibTool.h`.

utility

yarp/cv/Cv.h

iCub/PinholeCalibTool.h