

icub-tutorials/src /anyRobotCartesianInterface /src/fakeMotorDevice/src /fakeMotorDevice.cpp

icub-tutorials/src /anyRobotCartesianInterface

/src/fakeMotorDevice/src

/fakeMotorDeviceClient.cpp

icub-tutorials/src /anyRobotCartesianInterface /src/fakeMotorDevice/src /fakeMotorDeviceServer.cpp