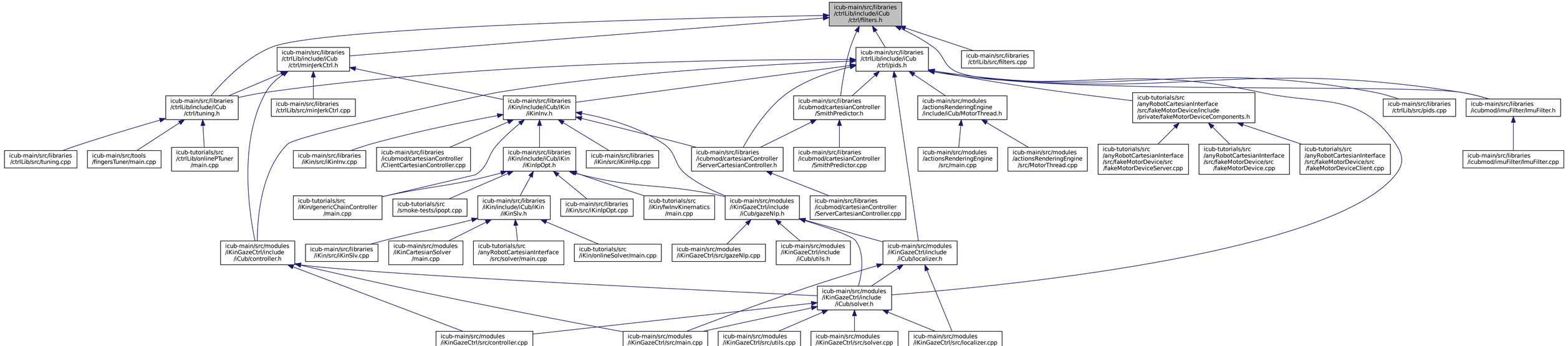
icub-main/src/libraries /ctrlLib/include/iCub /ctrl/filters.h
icub-main/src/libraries /ctrlLib/include/iCub /ctrl/minJerkCtrl.h
icub-main/src/libraries /ctrlLib/include/iCub /ctrl/pids.h
icub-main/src/libraries /ctrlLib/src/filters.cpp
icub-main/src/libraries /ctrlLib/include/iCub /ctrl/tuning.h
icub-main/src/libraries /ctrlLib/src/minJerkCtrl.cpp
icub-main/src/libraries /iKin/include/iCub/iKin /iKinInv.h
icub-main/src/libraries /icubmod/cartesianController /SmithPredictor.h
icub-main/src/modules /actionsRenderingEngine /include/iCub/MotorThread.h
icub-tutorials/src /anyRobotCartesianInterface /src/fakeMotorDevice/include /private/fakeMotorDeviceComponents.h
icub-main/src/libraries /ctrlLib/src/pids.cpp
icub-main/src/libraries /icubmod/imuFilter/ImuFilter.h
icub-main/src/libraries /ctrlLib/src/tuning.cpp
icub-main/src/tools /fingersTuner/main.cpp
icub-tutorials/src /ctrlLib/onlinePTuner /main.cpp
icub-main/src/libraries /iKin/src/iKinInv.cpp
icub-main/src/libraries /icubmod/cartesianController /ClientCartesianController.cpp
icub-main/src/libraries /iKin/include/iCub/iKin /iKinIpOpt.h
icub-main/src/libraries /iKin/src/iKinHlp.cpp
icub-main/src/libraries /icubmod/cartesianController /ServerCartesianController.h
icub-main/src/libraries /icubmod/cartesianController /SmithPredictor.cpp
icub-main/src/modules /actionsRenderingEngine /src/main.cpp
icub-main/src/modules /actionsRenderingEngine /src/MotorThread.cpp
icub-tutorials/src /anyRobotCartesianInterface /src/fakeMotorDevice/src /fakeMotorDeviceServer.cpp
icub-tutorials/src /anyRobotCartesianInterface /src/fakeMotorDevice/src /fakeMotorDevice.cpp
icub-tutorials/src /anyRobotCartesianInterface /src/fakeMotorDevice/src /fakeMotorDeviceClient.cpp
icub-main/src/libraries /icubmod/imuFilter/ImuFilter.cpp
icub-tutorials/src /iKin/genericChainController /main.cpp
icub-tutorials/src /smoke-tests/ipopt.cpp
icub-main/src/libraries /iKin/include/iCub/iKin /iKinSlv.h
icub-main/src/libraries /iKin/src/iKinIpOpt.cpp
icub-tutorials/src /iKin/fwInvKinematics /main.cpp
icub-main/src/modules /iKinGazeCtrl/include /iCub/gazeNlp.h
icub-main/src/libraries /icubmod/cartesianController /ServerCartesianController.cpp
icub-main/src/modules /iKinGazeCtrl/include /iCub/controller.h
icub-main/src/libraries /iKin/src/iKinSlv.cpp
icub-main/src/modules /iKinCartesianSolver /main.cpp
icub-tutorials/src /anyRobotCartesianInterface /src/solver/main.cpp
icub-tutorials/src /iKin/onlineSolver/main.cpp
icub-main/src/modules /iKinGazeCtrl/src/gazeNlp.cpp
icub-main/src/modules /iKinGazeCtrl/include /iCub/utils.h
icub-main/src/modules /iKinGazeCtrl/include /iCub/localizer.h
icub-main/src/modules /iKinGazeCtrl/include /iCub/solver.h
icub-main/src/modules /iKinGazeCtrl/src/controller.cpp
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icub-main/src/modules /iKinGazeCtrl/src/localizer.cpp