

icub-main/src/libraries  
/icubmod/embObjMotionControl  
/measuresConverter.h

```
graph TD; A["icub-main/src/libraries  
/icubmod/embObjMotionControl  
/measuresConverter.h"] --> B["yarp/dev/ControlBoardHelper.h"]; A --> C["yarp/dev/ControlBoardPid.h"]
```

yarp/dev/ControlBoardHelper.h

yarp/dev/ControlBoardPid.h