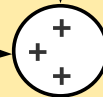
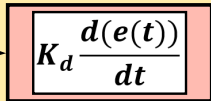
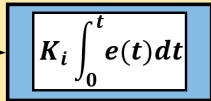
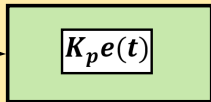


Angle  
Setpoint



$e(t)$



$PID(t)$



$\theta$

