


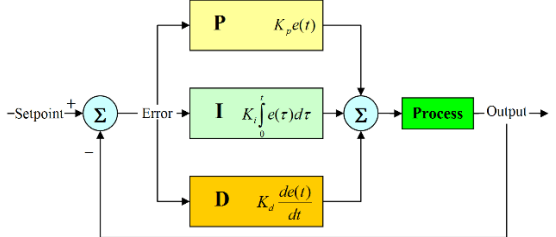
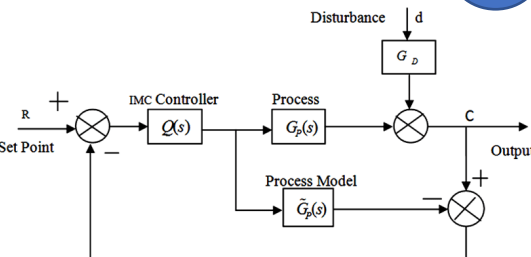
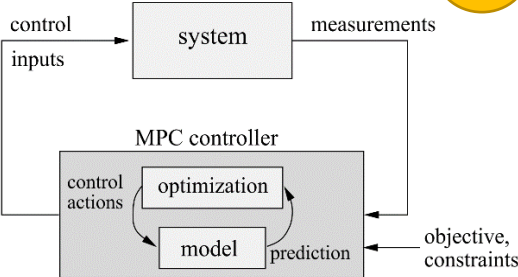







Problems to solve	Alternative 1	Alternative 2	Alternative 3
Process and send commands through user's interface	TKINTER (PYTHON) A 	TERMINAL B 	ELECTRON (JAVASCRIPT) C 
Execute control algorithm for achieving current task	PID C 	IMC B 	MPC A 
Operate robot	ABB IRB 140 ROBOT B 	BAXTER ROBOT A C 	
Execute computer vision algorithms	STEREO CAMERA B 	BAXTER HAND CAMERAS A 	RGB-D CAMERA C 

Concept A

Concept B

Concept C