

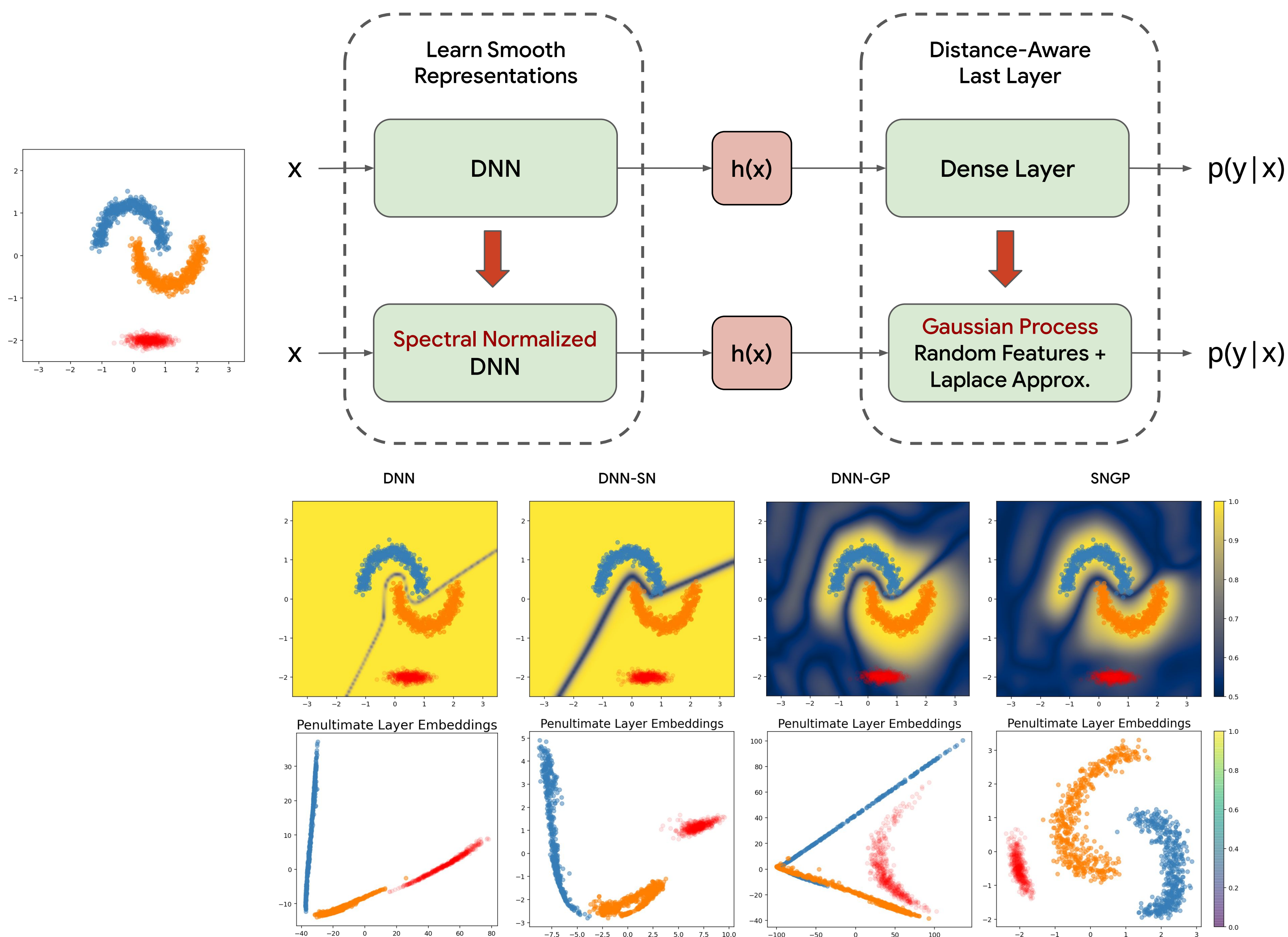
# A Simple Approach to Improve Single-Model Deep Uncertainty via Distance-Awareness

Jeremiah Liu\*, Shreyas Padhy\*, Jie Ren\*, Zi Lin, Yeming Wen, Ghassen Jerfel, Zack Nado, Jasper Snoek, Dustin Tran, Balaji Lakshminarayanan



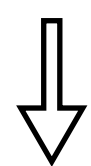
UNIVERSITY OF  
CAMBRIDGE

Google Research



## Distance-Preservation w/ Spectral Normalisation

$$L_1 \|\mathbf{x}_1 - \mathbf{x}_2\|_X \leq \|h(\mathbf{x}_1) - h(\mathbf{x}_2)\|_H \leq L_2 \|\mathbf{x}_1 - \mathbf{x}_2\|_X$$



- Bi-Lipschitz Condition on residual layers is easily satisfied by Spectral Norm  $\|\mathbf{W}\|_2 \leq c$
- Perform  $\mathbf{W}_l = c \frac{\mathbf{W}_l}{\|\mathbf{W}_l\|}$

## Distance-Awareness w/ Gaussian Processes

$$g_{N \times 1} \sim N(\mathbf{0}_{N \times 1}, \sigma^2 * \mathbf{K}_{N \times N}), \mathbf{K}_{i,j} = \exp\left(-\|h_i - h_j\|_2^2 / 2\right)$$



- Approximations for scalability -
  - Random Fourier Feature expansions
  - $\mathbf{K} \approx \Phi\Phi^T \rightarrow g(h_i) \approx \Phi(h_i)^T \mathbf{W}_L$
  - Laplace Approximation for Posterior
  - $p(\mathbf{W}_L | \mathcal{D}) \approx \mathcal{N}(\mathbf{W}_{L, \text{MAP}}, \hat{\Sigma})$

## Competitive on many benchmarks

- Vision: CIFAR10/100, ImageNet (ResNet-50)
- NLP: Intent Detection (BERT)
- Genomics: Sequence Prediction

Method	Accuracy (↑)		ECE (↓)		NLL (↓)	
	Clean	Corrupted	Clean	Corrupted	Clean	Corrupted
<b>Single Model</b>						
DNN	76.2 ± 0.01	40.5 ± 0.01	0.032 ± 0.002	0.103 ± 0.011	0.939 ± 0.01	3.21 ± 0.02
DNN-SN	<b>76.4 ± 0.01</b>	40.6 ± 0.01	0.079 ± 0.001	0.074 ± 0.001	0.96 ± 0.01	3.14 ± 0.02
DNN-GP	76.0 ± 0.01	<b>41.3 ± 0.01</b>	0.017 ± 0.001	0.049 ± 0.001	0.93 ± 0.01	3.06 ± 0.02
<b>SNGP (Ours)</b>	76.1 ± 0.01	41.1 ± 0.01	<b>0.013 ± 0.001</b>	<b>0.045 ± 0.012</b>	<b>0.93 ± 0.01</b>	<b>3.03 ± 0.01</b>
<b>Ensemble Model</b>						
MC Dropout	76.6 ± 0.01	42.4 ± 0.02	0.026 ± 0.002	<b>0.046 ± 0.009</b>	0.919 ± 0.01	2.96 ± 0.01
Deep Ensemble	77.9 ± 0.01	<b>44.9 ± 0.01</b>	<b>0.017 ± 0.001</b>	0.047 ± 0.004	0.857 ± 0.01	2.82 ± 0.01
<b>SNGP Ensemble (Ours)</b>	<b>78.1 ± 0.01</b>	<b>44.9 ± 0.01</b>	0.039 ± 0.001	0.050 ± 0.002	<b>0.851 ± 0.01</b>	<b>2.77 ± 0.01</b>

## SNGP is an uncertainty building block!

- Orthogonal Performance to other methods
  - Ensembling: Deep Ensembles, MC Dropout
  - Augmentations: AugMix

