

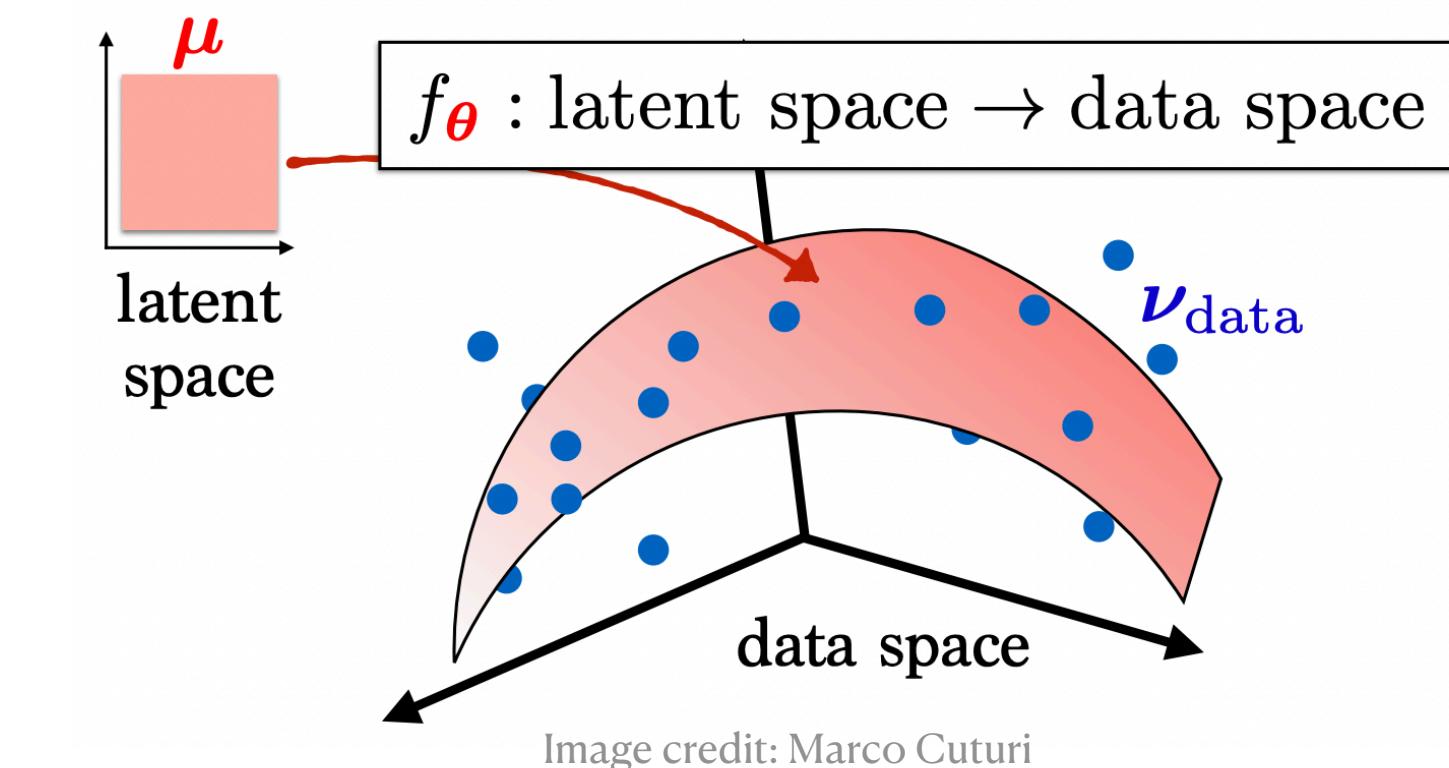
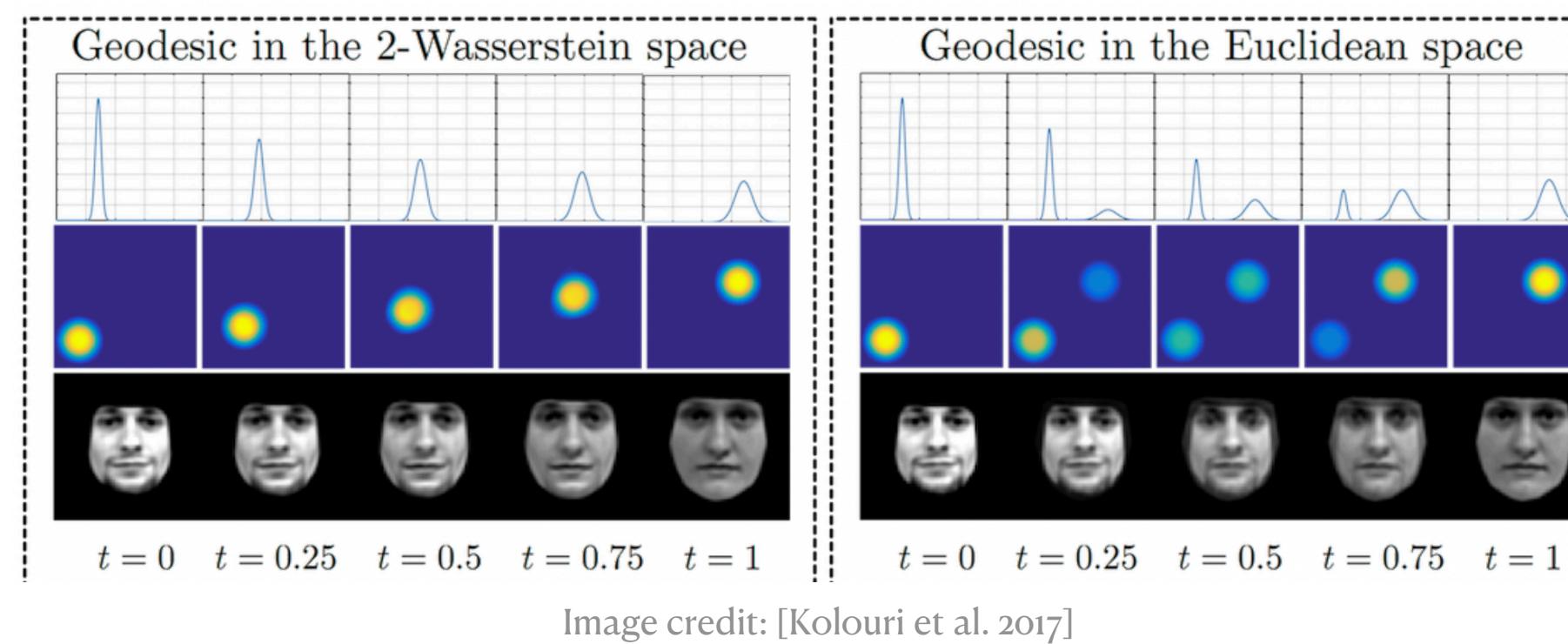
Optimal Transport Metrics

Cambridge MLG Reading Group

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09 February 2022

Why Optimal Transport?

- The natural geometry for **probability measures** supported on a **metric space**
- **Shortest path principle**
 - OT generalises this: one item -> groups of items
- Borrows key geometric properties of underlying “ground” space on which distributions are defined
 - Euclidean metric -> interpolation, barycenters, etc -> Wasserstein space
- Provides a metric (or discrepancy measure) for probability measures with **non-overlapping support**



In this talk

I. Mathematical Formulation of Optimal Transport Theory

Wasserstein Distances

Computational and Statistical Issues

II. Approximate/Regularised OT

Sliced Wasserstein Distances

Sinkhorn Divergences

III. Applications of OT in Machine Learning

IV. Extensions of OT

Unbalanced OT

OT on separate metrics

Mathematical Preliminaries

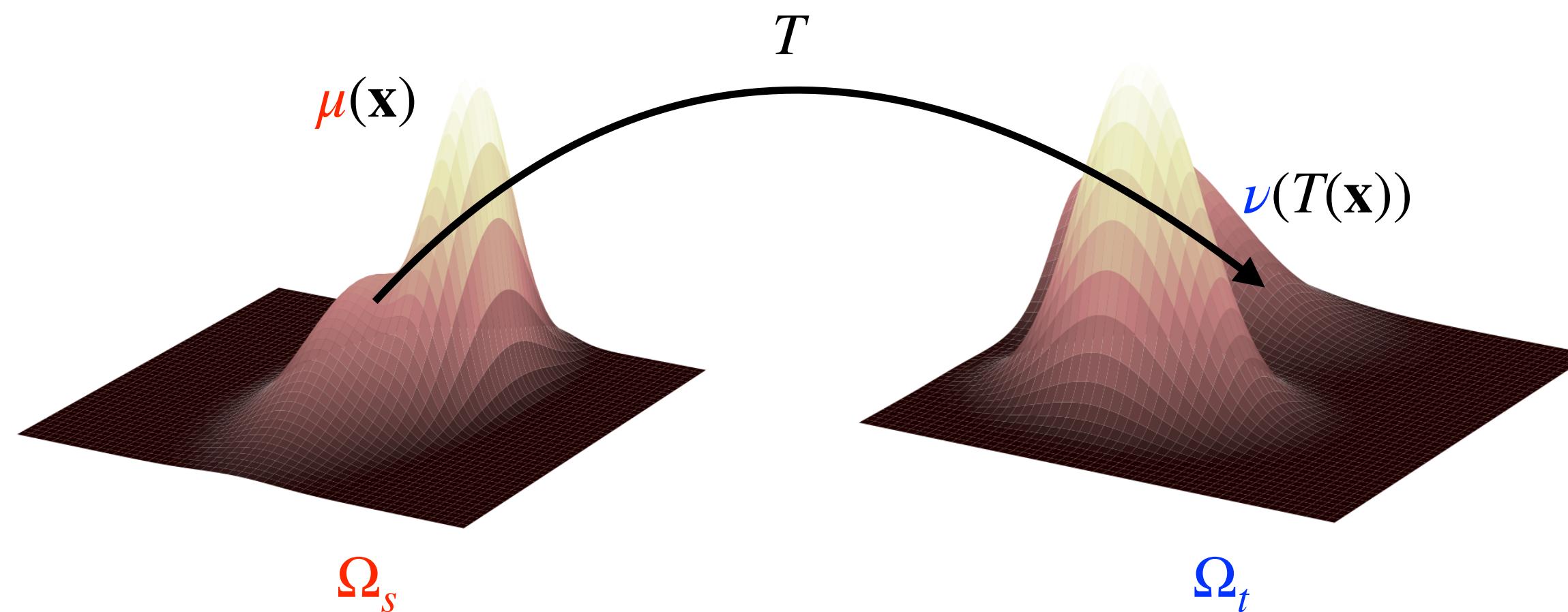
Monge Problem

- [Monge, 1781] How does one move one pile of dirt to another while minimising effort?
- Probability measures $\mu \in P(\Omega_s)$, $\nu \in P(\Omega_t)$, on metric spaces, and a cost function $c : \Omega_s \times \Omega_t \rightarrow \mathbb{R}^+$
- Push-forward operator $T\#$ transfers measures from one space Ω_s to another Ω_t

$$\nu(A) = \mu(T^{-1}(A)), \forall \text{Borel subsets } A \in \Omega_t \quad (\text{conservation of mass})$$

- The Monge formulation wishes to find a mapping $T : \Omega_s \rightarrow \Omega_t$ that minimises

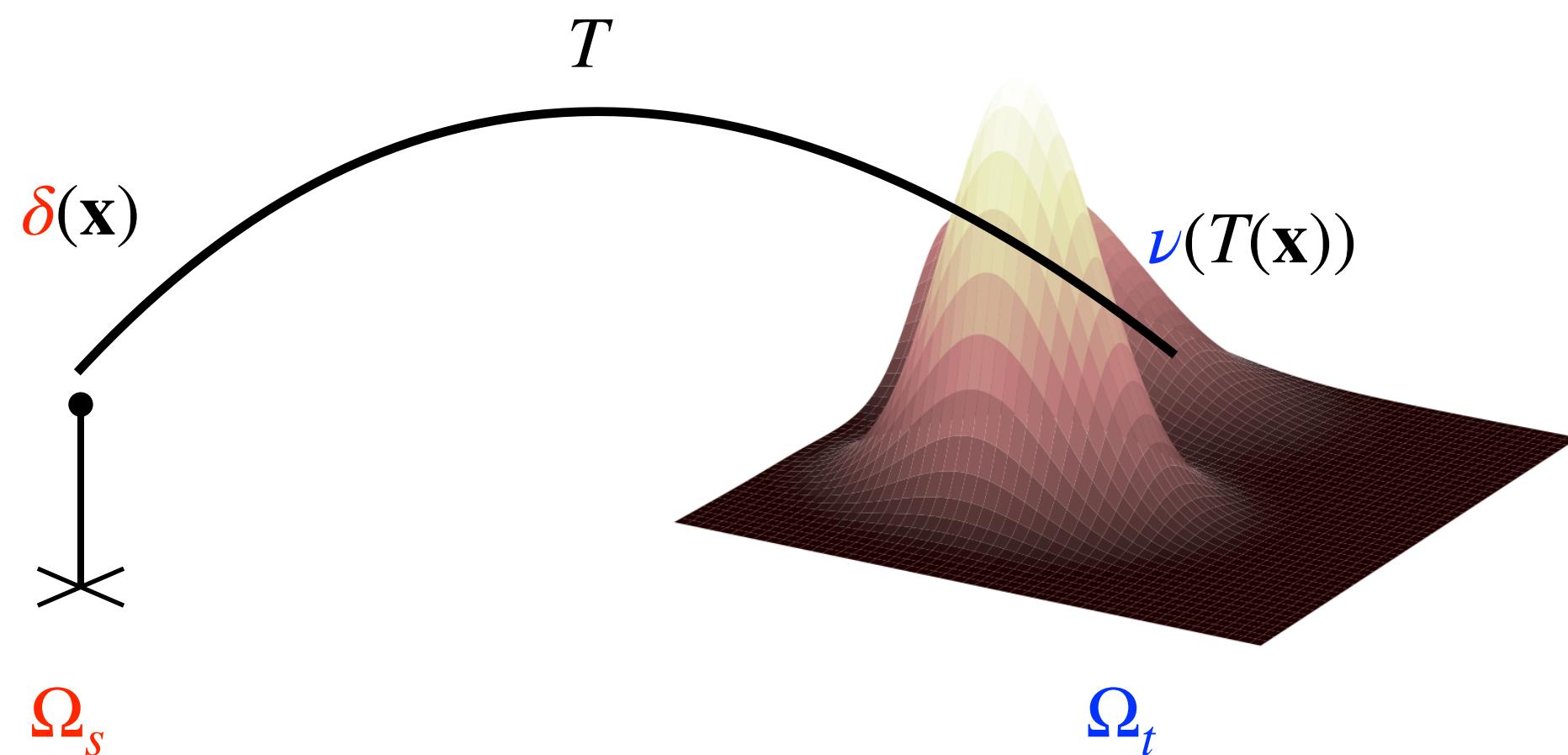
$$\inf_{T\#\mu=\nu} \int_{\Omega_s} c(\mathbf{x}, T(\mathbf{x})) \mu(\mathbf{x}) d\mathbf{x}$$



Monge Problem - Issues

$$\inf_{T \# \mu = \nu} \int_{\Omega_s} c(\mathbf{x}, T(\mathbf{x})) \mu(\mathbf{x}) d\mathbf{x}$$

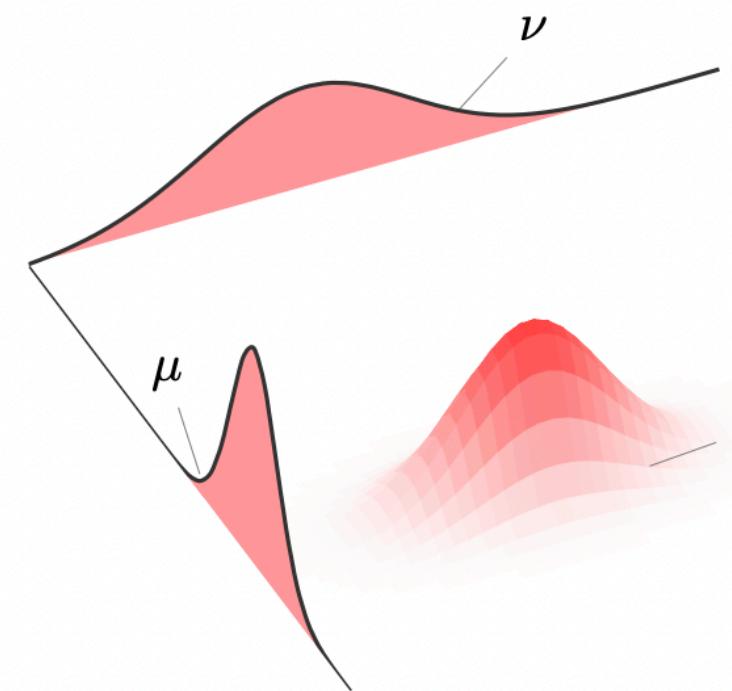
- $T \# \mu = \nu$ is not a convex constraint, *Existence* and *Unicity* of T is not guaranteed
- Can't split mass (one-to-one, but not one-to-many)
- Ex: Can't map Dirac measures δ_x to continuous measures



Kantorovich Relaxation

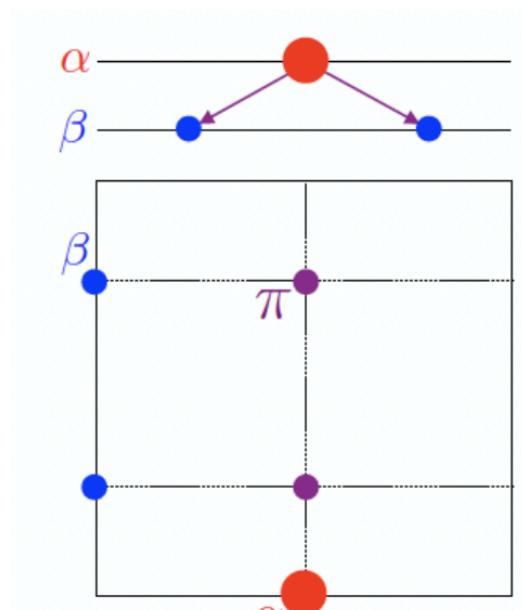
- [Kantorovich, 1942] Relax the requirement of maps T to *probabilistic couplings* $\gamma \in \mathcal{P}(\Omega_s \times \Omega_t)$

$$\gamma \in \mathcal{P} = \left\{ \gamma \geq 0, \int_{\Omega_t} \gamma(\mathbf{x}, \mathbf{y}) d\mathbf{y} = \mu, \int_{\Omega_s} \gamma(\mathbf{x}, \mathbf{y}) d\mathbf{x} = \nu \right\}$$



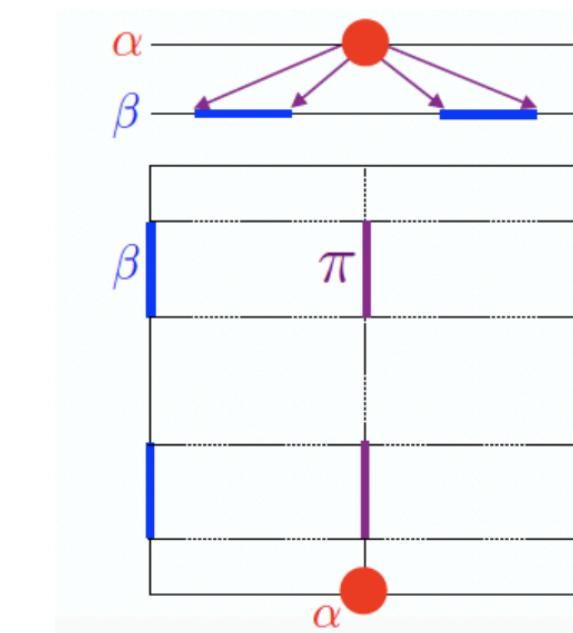
Product Coupling $\gamma = \mu \otimes \nu$

Image credit: Lénaïc Chizat



Coupling for Dirac -> Dirac

Image credit: Remi Flamary



Coupling for Dirac -> Continuous

Image credit: Remi Flamary

- Given $\mu \in P(\Omega_s)$, $\nu \in P(\Omega_t)$, on metric spaces, a cost function $c : \Omega_s \times \Omega_t \rightarrow \mathbb{R}^+$, find couplings γ that minimise

$$\begin{aligned} & \operatorname{argmin}_{\gamma} \int_{\Omega_s \times \Omega_t} c(\mathbf{x}, \mathbf{y}) \gamma(\mathbf{x}, \mathbf{y}) d\mathbf{x} d\mathbf{y} \quad \text{s.t.} \\ \gamma \in \mathcal{P} = & \left\{ \gamma \geq 0, \int_{\Omega_t} \gamma(\mathbf{x}, \mathbf{y}) d\mathbf{y} = \mu, \int_{\Omega_s} \gamma(\mathbf{x}, \mathbf{y}) d\mathbf{x} = \nu \right\} \end{aligned}$$

Kantorovich Dual Formulation

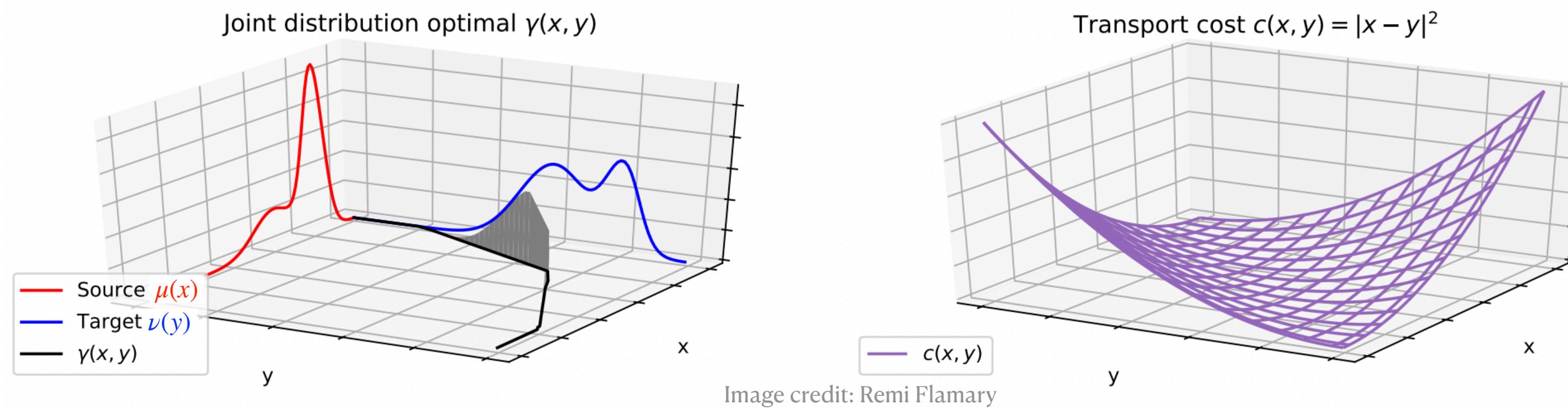
- Instead of optimising over all couplings γ that satisfy the constraints, consider two measurable functions $\phi \in L_1(\mu)$, $\psi \in L_1(\nu)$
 - Reminder: A fn $f: \mathcal{X} \rightarrow \mathcal{Y}$ is Lipschitz continuous if there exists a real constant $K \geq 0$ s.t

$$d_{\mathcal{Y}}(f(x_1), f(x_2)) \leq K d_{\mathcal{X}}(x_1, x_2)$$

Solve

$$\max_{\phi, \psi} \left\{ \int \phi d\mu + \int \psi d\nu \quad \text{s.t.} \quad \phi(\mathbf{x}) + \psi(\mathbf{y}) \leq c(\mathbf{x}, \mathbf{y}) \right\}$$

- The primal and dual formulations solve exactly the same problem at the equality
 - support of $\gamma(\mathbf{x}, \mathbf{y})$ is where $\phi(\mathbf{x}) + \psi(\mathbf{y}) = c(\mathbf{x}, \mathbf{y})$



Semi-dual formulation: c-Conjugates

- Instead of optimising over all possible ϕ, ψ given constraints, can we find the best ψ given a ϕ ?
- Given a ϕ , we need that ψ satisfies for all \mathbf{x}, \mathbf{y}

$$\phi(\mathbf{x}) + \psi(\mathbf{y}) \leq c(\mathbf{x}, \mathbf{y})$$

$$\psi(\mathbf{y}) \leq c(\mathbf{x}, \mathbf{y}) - \phi(\mathbf{x})$$

$$\psi(\mathbf{y}) \leq \inf_{\mathbf{x}} c(\mathbf{x}, \mathbf{y}) - \phi(\mathbf{x})$$

$$\text{define } \phi^c(\mathbf{y}) = \inf_{\mathbf{x}} c(\mathbf{x}, \mathbf{y}) - \phi(\mathbf{x})$$

- Can simplify to a semi-dual formulation that depends on only one function ϕ through the c-conjugate

$$\max_{\phi, \psi} \left\{ \int \phi d\mu + \int \psi d\nu \quad \text{s.t.} \quad \phi(\mathbf{x}) + \psi(\mathbf{y}) \leq c(\mathbf{x}, \mathbf{y}) \right\} \quad \longrightarrow \quad \max_{\phi} \left\{ \int \phi d\mu + \int \phi^c d\nu \right\}$$

Wasserstein Distances

- If $\textcolor{green}{c}(x, y) = D^p(x, y)$, a distance-metric, then for measures $\mu, \nu \in P(\Omega)$, the p-Wasserstein Distance is

- $$W_p^p(\mu, \nu) = \left(\inf_{\gamma \in \mathcal{P}} \iint D(x, y)^p \gamma(dx, dy) \right) = \mathbb{E}_{(x,y) \sim \gamma} [D(x, y)^p]$$

- In dual formulation

- $$W_p^p(\mu, \nu) = \sup_{\phi \in L_1(\mu), \psi \in L_1(\nu)} \int \phi d\mu + \int \psi d\nu, \text{ where } \phi(x) + \psi(y) \leq D^p(x, y)$$

- Special Case of semi-dual formulation - **W_1 Distance**

- Proposition: if $\textcolor{green}{c} = |x - y|$, then $\phi^c = -\phi$ for all ϕ that are 1-Lipschitz.

- $$W_1(\mu, \nu) = \sup_{\phi \text{ is 1-Lipschitz}} \int \phi(d\mu - d\nu)$$

Wasserstein Distances are natural metrics

- W-distances encode very different geometries from standard information divergences (KL, Euclidean)
- W-distances borrow key properties from the underlying distance metric and port them into the space of probability distributions
- Euclidean distance -> interpolation, barycenters, etc

Wasserstein: $W_2^2(\alpha, \beta) \stackrel{\text{def.}}{=} \sup_{f,g} \left\{ \int f d\alpha + \int g d\beta ; f(x) + g(y) \leq \|x - y\|^2 \right\}$

Hellinger: $H^2(\alpha, \beta) \stackrel{\text{def.}}{=} \int (\sqrt{\frac{d\alpha}{dx}} - \sqrt{\frac{d\beta}{dx}})^2 dx$

Kullback-Leibler: $KL(\alpha|\beta) \stackrel{\text{def.}}{=} \int \log(\frac{d\alpha}{d\beta}) d\beta$

Burg: $B(\alpha|\beta) \stackrel{\text{def.}}{=} KL(\beta|\alpha)$

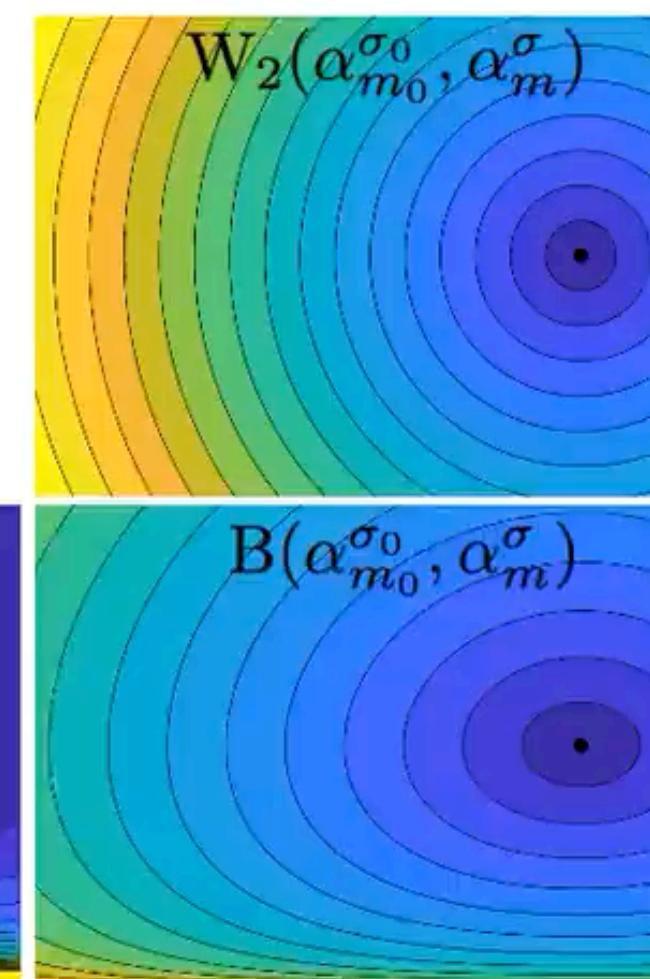
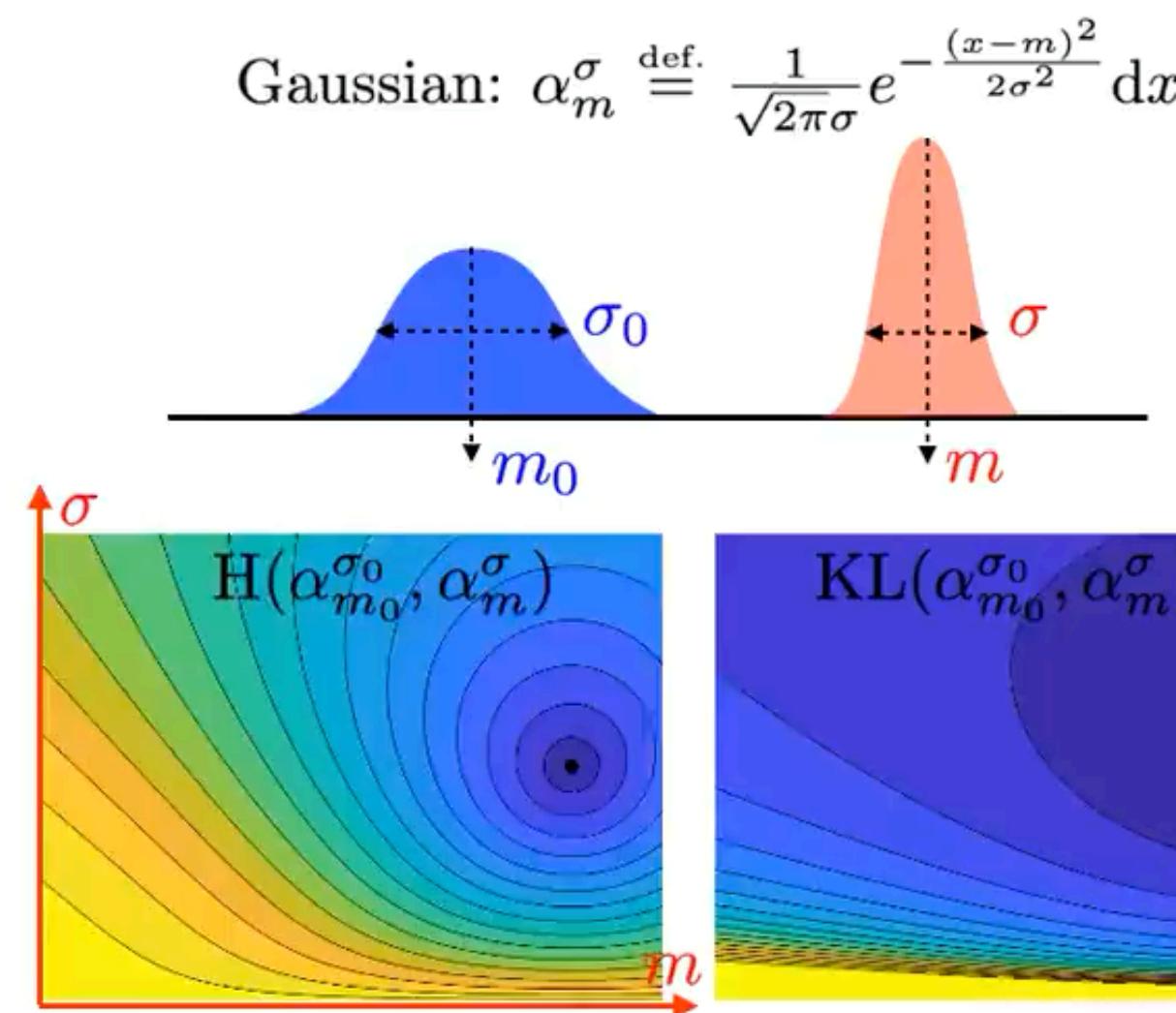


Image credit: Gabriel Peyre

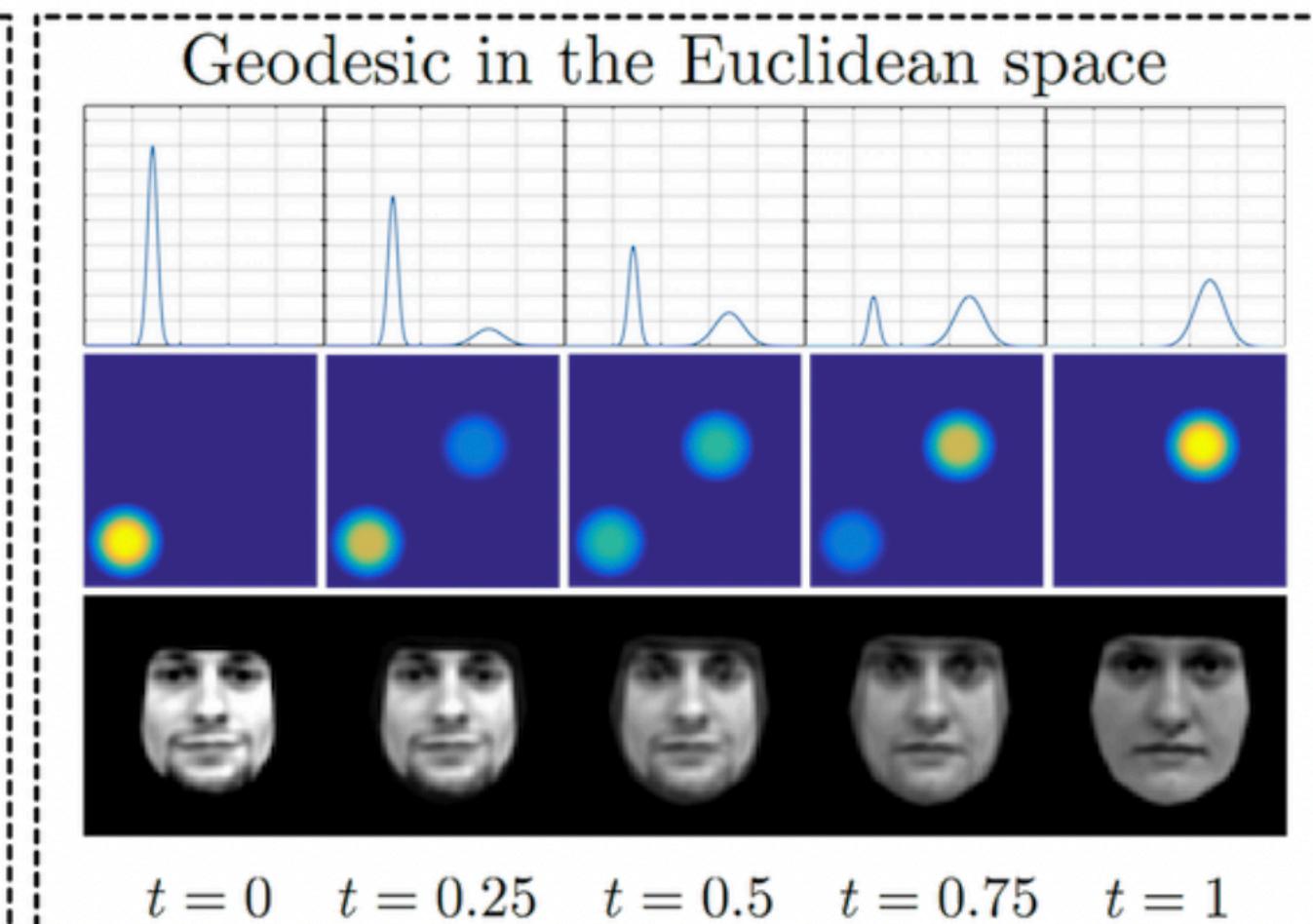
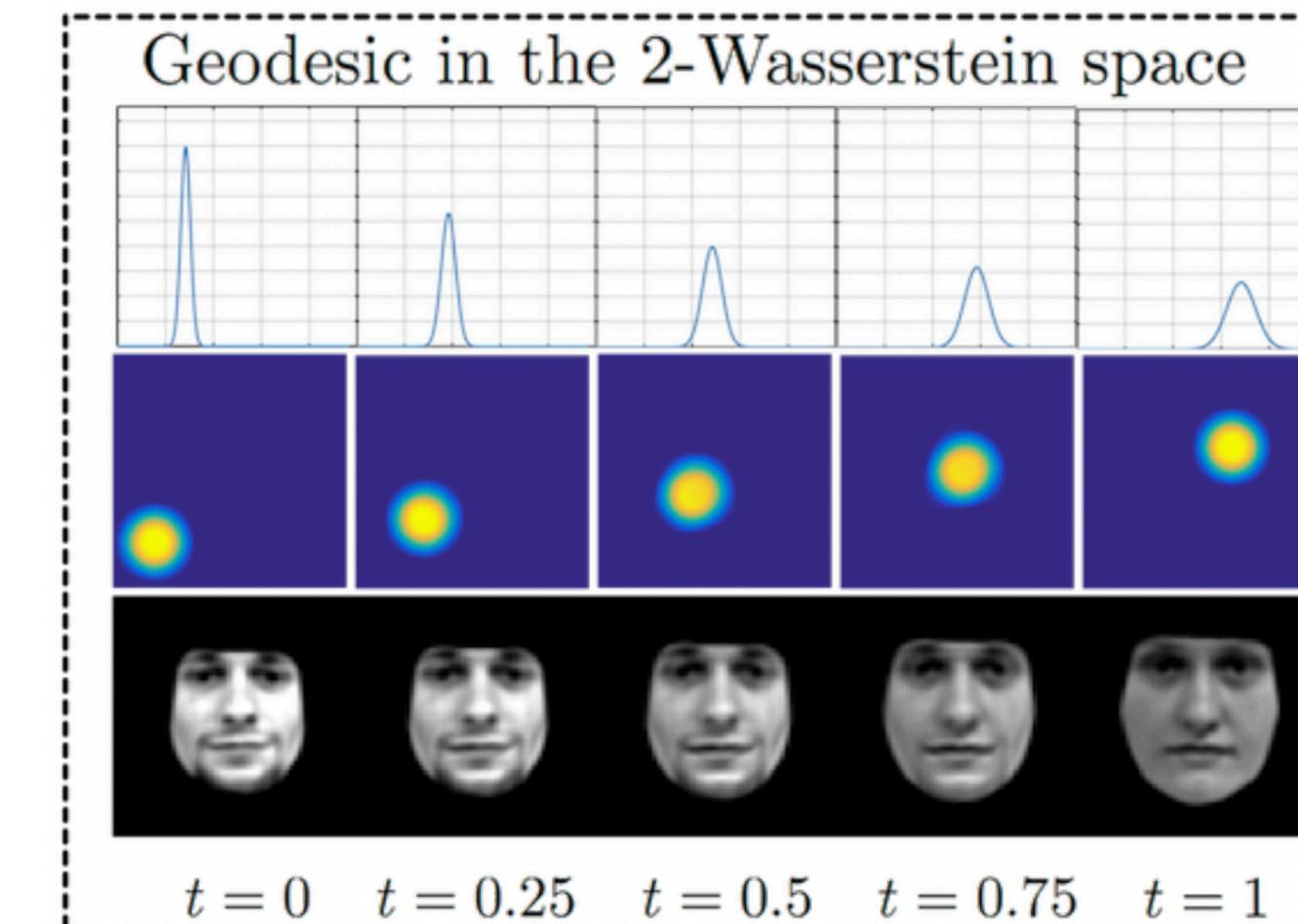


Image credit: [Kolouri et al. 2017]

Wasserstein Distances are natural metrics

- W-distances encode very different geometries from standard information divergences (KL, Euclidean)
- W-distances borrow key properties from the underlying distance metric and port them into the space of probability distributions
- Euclidean distance -> interpolation, barycenters, convexity

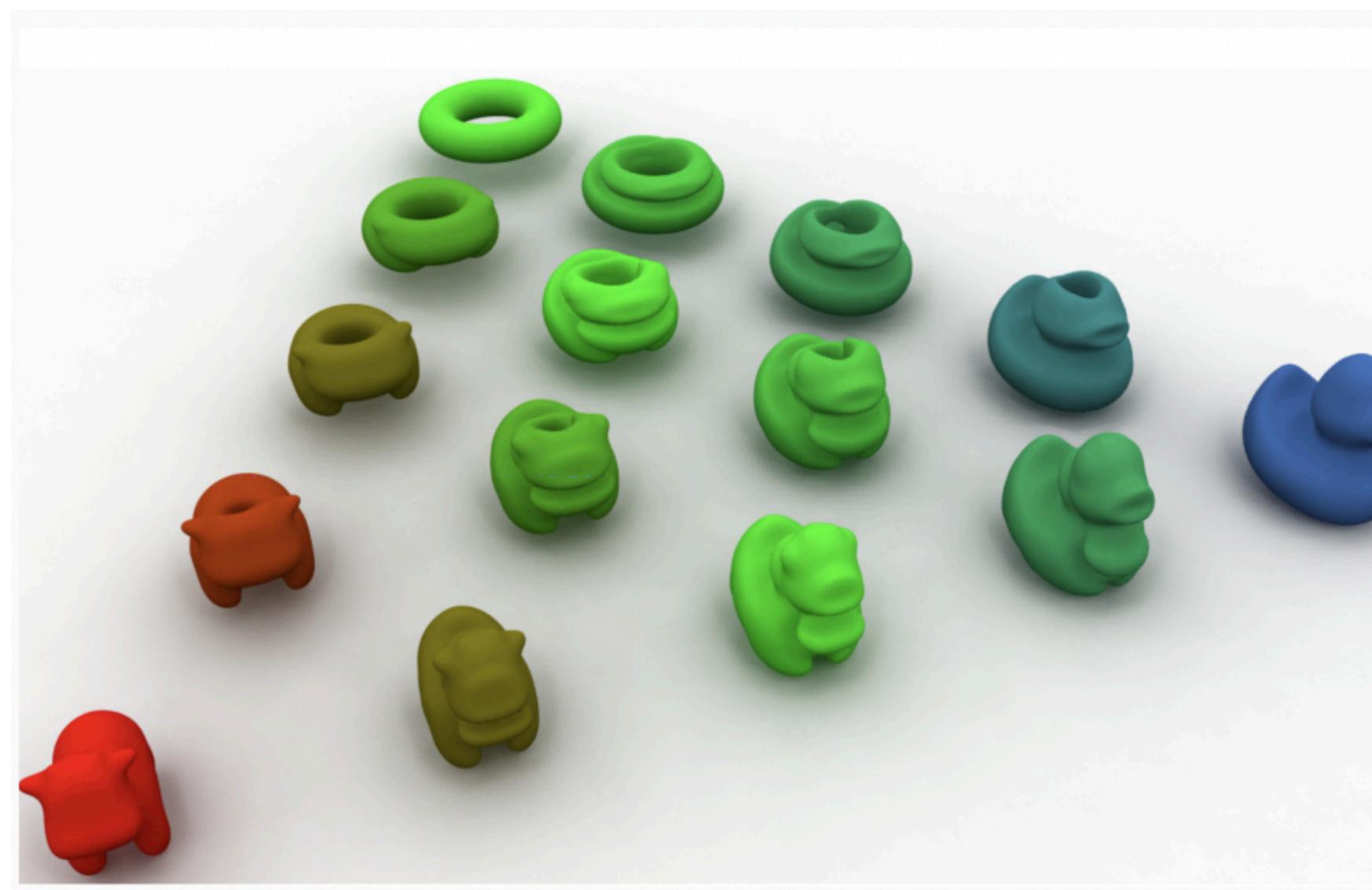
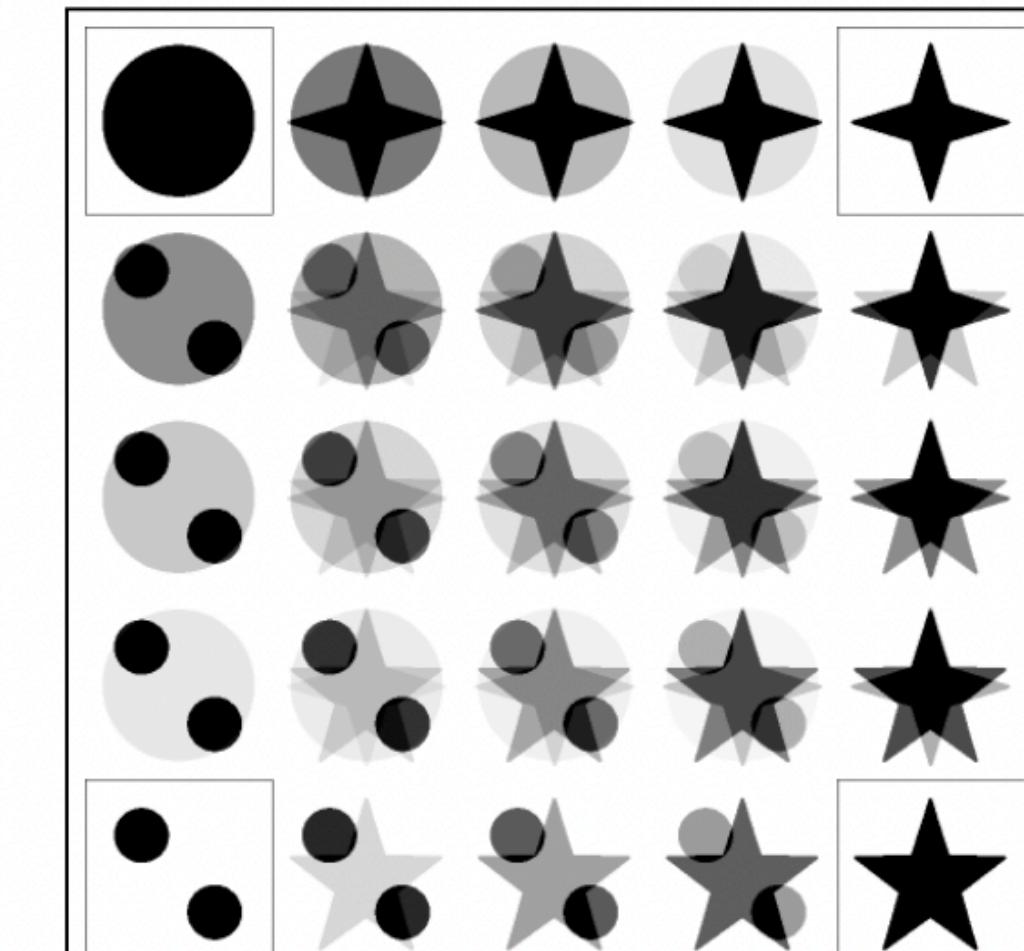
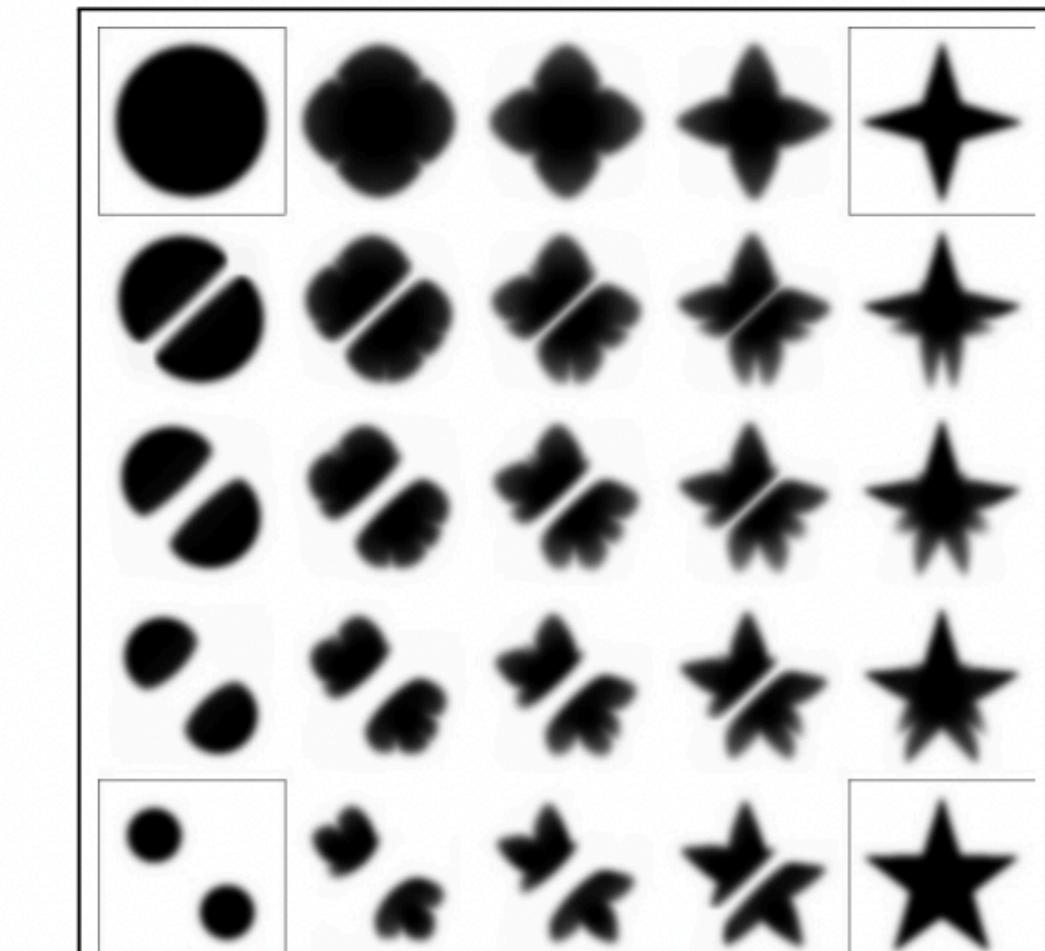


Image credit: [Solomon et al. 2015]



Euclidean barycenter



Wasserstein barycenter

Image credit: [Solomon et al. 2015]

Wasserstein Distances are natural metrics

- W-distances encode very different geometries from standard information divergences (KL, Euclidean)
- W-distances borrow key properties from the underlying distance metric and port them into the space of probability distributions
 - Euclidean distance -> interpolation, barycenters, convexity
- What's the catch?
 - Quite **expensive** to calculate in practice
 - Not **differentiable** generally
 - Statistical properties **don't scale to high-D distributions**

Example - OT for Discrete Distributions

- Consider discrete measures $\mu = \sum_i^n a_i \delta_{\mathbf{x}_i}$, $\nu = \sum_i^m b_j \delta_{\mathbf{y}_j}$, where $\mathbf{x}_i, \mathbf{y}_j \in \Omega$, and $\sum_i^n a_i = 1$, $\sum_j^m b_j = 1$
- Langrangian point clouds ($a_i = \frac{1}{n}$, $b_j = \frac{1}{m}$), Eulerian Histograms ($\mathbf{x}_i, \mathbf{y}_j$ are points on a grid)

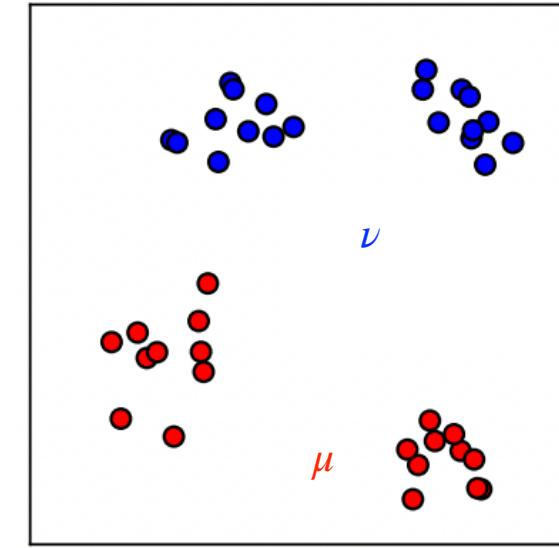


Image credit: Remi Flamary

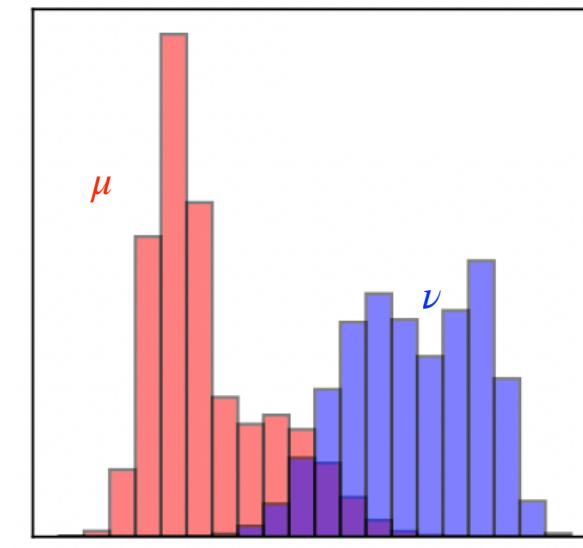


Image credit: Remi Flamary

- Given a cost matrix $\mathbf{C} = c(\mathbf{x}_i, \mathbf{y}_j)$, the optimal coupling between measures is a linear program given by

$$\gamma_0 = \underset{\gamma \in \mathcal{P}}{\operatorname{argmin}} \langle \mathbf{C}, \gamma \rangle_F = \sum_{i,j} \gamma_{i,j} c_{i,j} \text{ where } \mathcal{P} = \left\{ \gamma \in (\mathbb{R}^+)^{n \times m} \mid \gamma \mathbf{1}_n = \mathbf{a}, \gamma \mathbf{1}_m = \mathbf{b} \right\}$$

- Alternative dual formulation is given by $n + m$ variables and nm constraints

$$\max_{\alpha \in \mathbb{R}^n, \beta \in \mathbb{R}^m} \alpha^T \mathbf{a} + \beta^T \mathbf{b} \quad \text{s.t. } \alpha_i + \beta_j \leq c_{i,j} \quad \forall i, j$$

OT for Discrete Distributions - Issues

- Linear Program - no unique solution sometimes, numerical instabilities
 - $W_p^p(\mu, \nu)$ is not differentiable
 - Not parallelisable on GPU hardware
 - Solving a linear problem is $\mathcal{O}((n + m)nm \log(n + m))$
- Assuming we have samples $x_1, \dots, x_n \sim \mu, y_1, \dots, y_m \sim \nu$, what are the considerations involved when computing $W_p^p(\hat{\mu}_n, \hat{\nu}_m)$, where $\hat{\mu}_n = \frac{1}{n} \sum_i \delta_{x_i}, \hat{\nu}_m = \frac{1}{m} \sum_j \delta_{y_j}$?
 - Can we bound $\mathbb{E} \left[|W_p(\mu, \nu) - W_p(\hat{\mu}_n, \hat{\nu}_m)| \right]$?
 - [Peyre et al., 15] If $\Omega = \mathbb{R}^d, d > 3$ then $\mathbb{E} \left[|W_p(\mu, \nu) - W_p(\hat{\mu}_n, \hat{\nu}_m)| \right] = \mathcal{O}(n^{-1/d})$
- What machine learning applications would ideally like
 - Faster, scalable, more stable, differentiable (ideally using autodiff), better statistical convergence

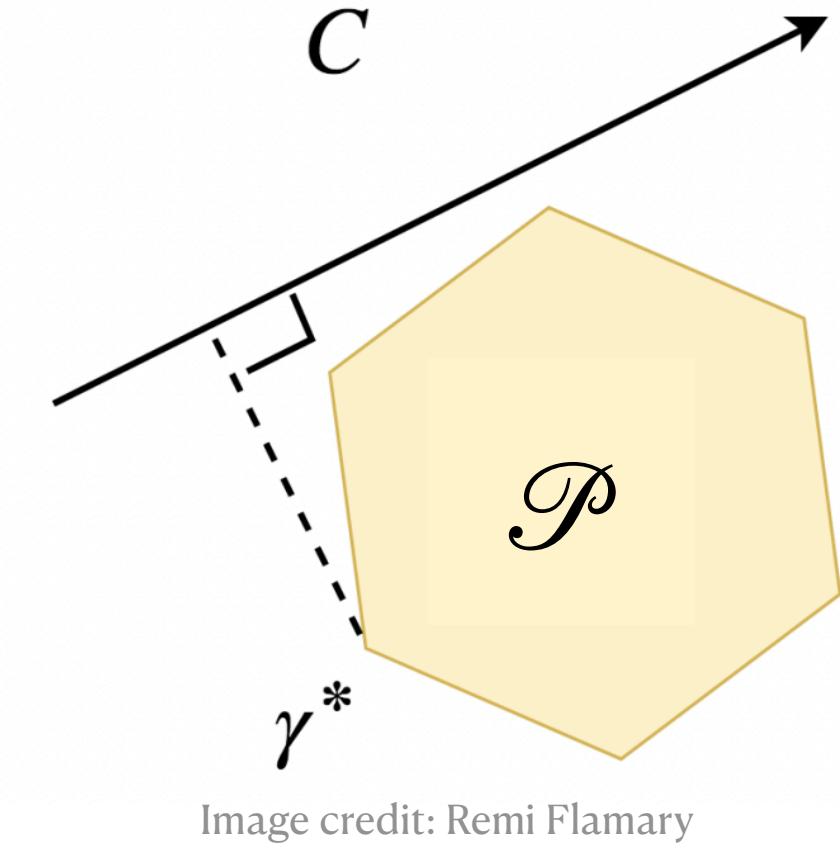


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**Approximate/Regularised
OT**

Sliced Wasserstein Distances

- For 1-D distributions $\Omega \in \mathbb{R}$, the W_p Distance is a function of the quantile functions $F_{\mu}^{-1}(x), F_{\nu}^{-1}(x)$

$$W_p(\mu, \nu) = \int_0^1 c \left(\left| F_{\mu}^{-1}(x) - F_{\nu}^{-1}(x) \right|^p \right) dx$$

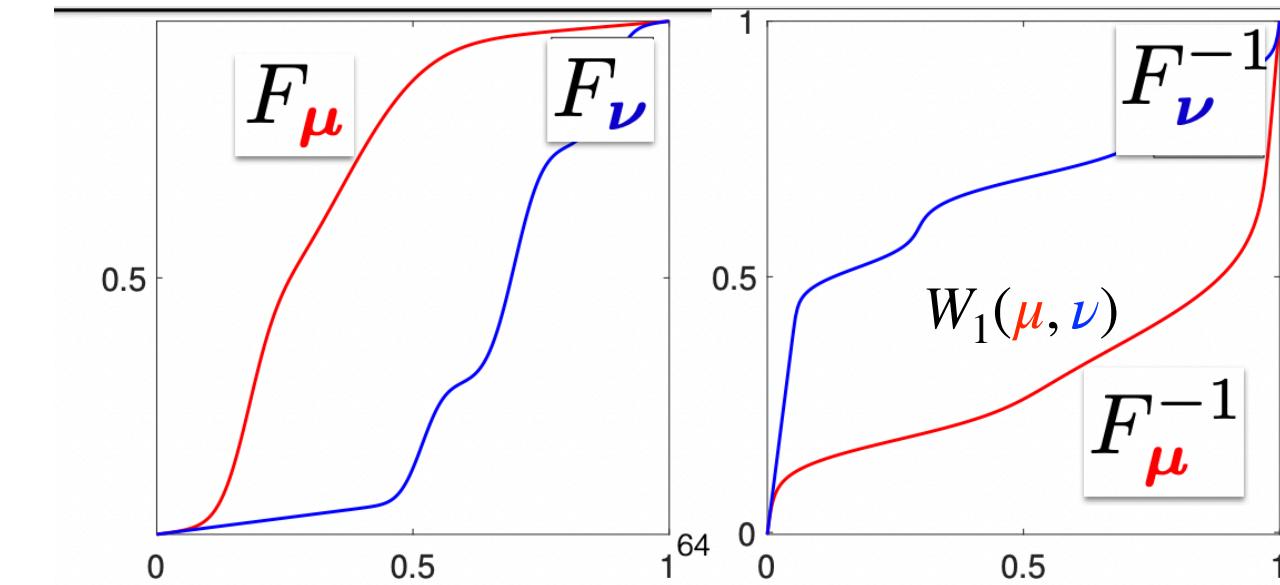


Image credit:Marco Cuturi

- For discrete distributions, very fast $\mathcal{O}(n \log n)$ algorithms exist
- **Idea - Project the high-dimensional distributions into 1 dimension, and calculate 1-D W_p distances**
- [Bonneel et al. 2015, Kolouri et al. 2017] accomplish this using the Radon Transform

$$\mathcal{R}(\mu, \theta) = \int_{\mathbb{S}^{d-1}} \delta(t - x^T \theta) \mu(x) dx, \quad t \in \mathbb{R}, \quad \theta \in \mathbb{S}^{d-1}$$

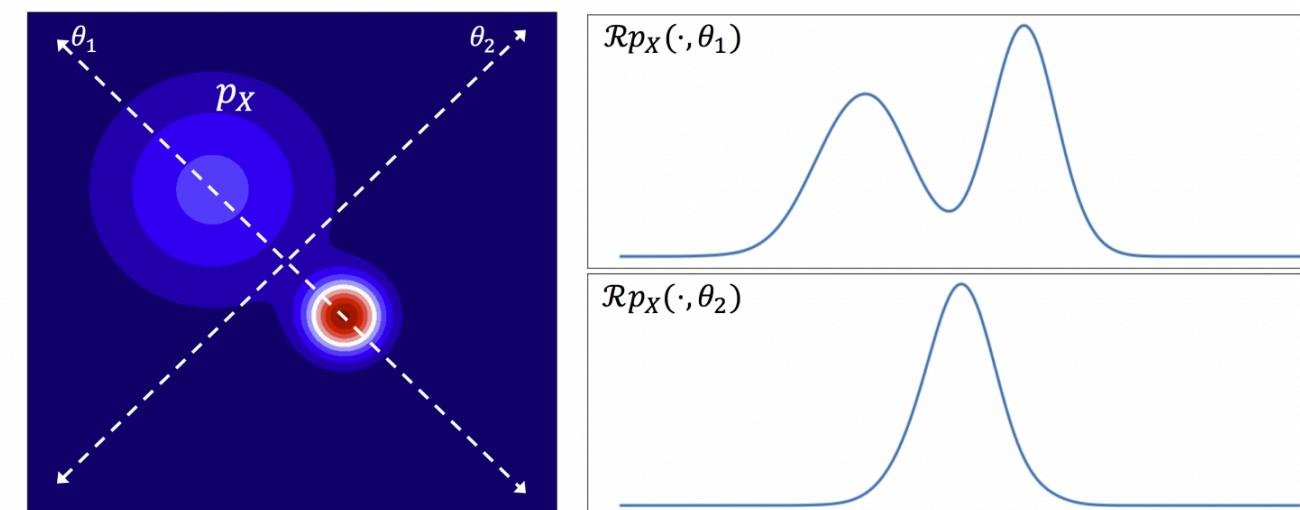


Image credit: [Kolouri et al 2017]

Sliced Wasserstein Distances

- [Bonneel et al. 2015] p-sliced Wasserstein distance

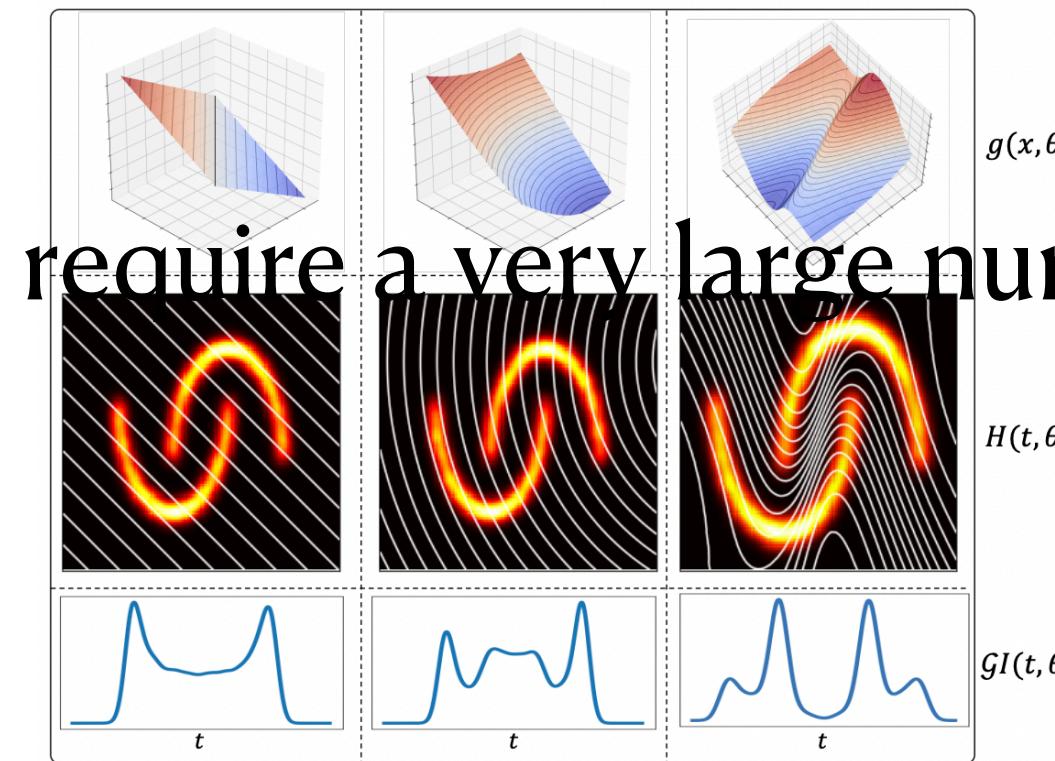
$$pSW_p^p(\mu, \nu) = \int_{\mathbb{S}^{d-1}} W_p^p(\mathcal{R}(\mu, \theta), \mathcal{R}(\nu, \theta)) d\theta$$

$$pSW_{p,K}^p(\mu, \nu) = \sum_l \frac{1}{K} W_p^p(\mathcal{R}(\mu, \theta_l), \mathcal{R}(\nu, \theta_l)), \quad \mathcal{O}(Kn \log n)$$

- [Nadjahi et al, 2020] sliced W-distances are true metrics, topologically equivalent and weaker to W_p

- Statistical convergence $\sim \mathcal{O}(K^{-1/2}n^{-1/2})$

- [Kolouri et al, 2020] generalise this distance by formulating generalised Radon transforms onto general hyper-surfaces



- Still not differentiable, in practise can require a very large number of MC estimates if d is large

Regularised Optimal Transport

- Idea - OT with Regularisation

- Option 1: Add priors to the family of couplings to consider

- Add a regularisation term to the OT formulation, $\gamma_0^\lambda = \operatorname{argmin}_{\gamma \in \mathcal{P}} \langle \gamma, \mathbf{C} \rangle_F + \lambda R(\gamma)$

- [Cuturi, 2013] Entropic Regularisation, $R(\gamma) = \sum_{i,j} \gamma_{i,j} (\log \gamma_{i,j} - 1)$

- [Courty et al., 2016] Group Lasso, $R(\gamma) = \sum_g \sqrt{\sum_{i,j \in \mathcal{G}_g} \gamma_{i,j}^2}$

- Option 2: Relax the requirement for $W_1(\mu, \nu) = \sup_{\phi \text{ is 1-Lipschitz}} \int \phi(d\mu - d\nu)$

- [Makkouva et al., 17] Use RELU Networks with bounded weights

- [Shirdhonkar'08] - Use low-dimensional wavelet decompositions

- Option 3: Change the cost function in $\operatorname{argmin}_{\gamma \in \mathcal{P}} \int_{\Omega_s \times \Omega_t} c(x, y) \gamma(x, y) dx dy$

- [Solomon+, '17] Geodesic Distances on graphs simplify the Linear Program

Entropic Regularised OT

- We have $\gamma_0^\lambda = \operatorname{argmin}_{\gamma \in \mathcal{P}} \langle \gamma, \mathbf{C} \rangle_F + \lambda \sum_{i,j} \gamma_{i,j} (\log \gamma_{i,j} - 1) = \operatorname{argmin}_{\gamma \in \mathcal{P}} \langle \gamma, \mathbf{C} \rangle_F - \lambda \mathbb{H}(\gamma)$
- [Wilson, '69] Define a regularised Wasserstein distance, for $\lambda \geq 0$

$$W_\lambda(\mu, \nu) = \min_{\gamma \in \mathcal{P}} \langle \gamma, \mathbf{C} \rangle_F - \lambda \mathbb{H}(\gamma)$$

- If $\lambda \geq 0$, then the linear program becomes a λ -strongly convex optimisation problem
- Fast and scalable, differentiable - **Sinkhorn's Algorithm**
 - $\mathcal{O}(nm)$ complexity in general, $\simeq \mathcal{O}(n \log n)$ on gridded spaces with convolutions [Solomon et al., '15]
 - Better statistical convergence properties - **Sinkhorn Divergences**

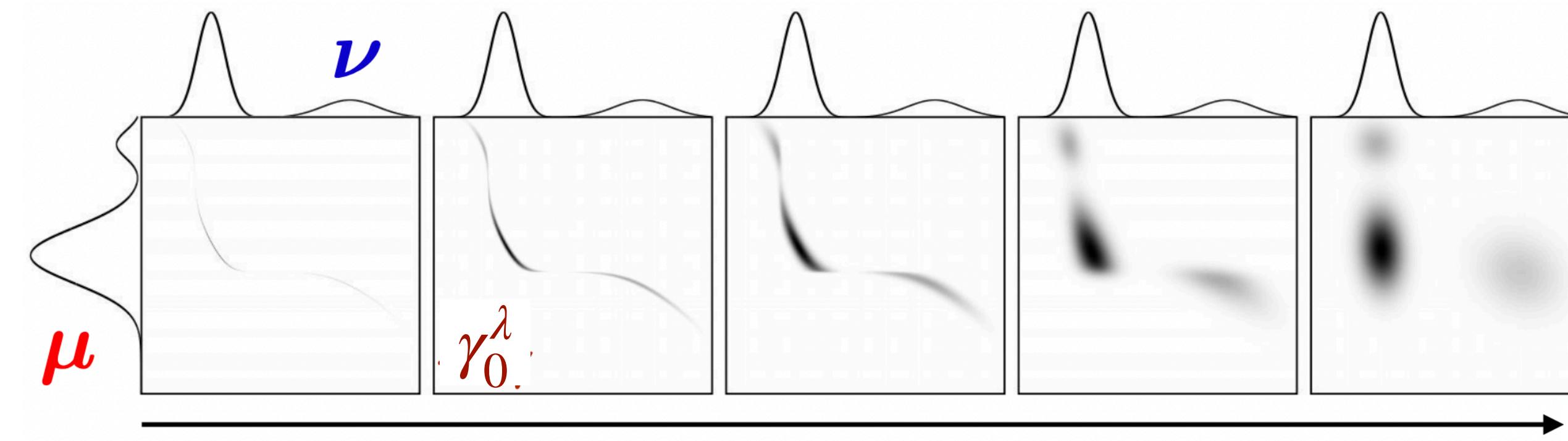


Image credit: Remi Flamary

Sinkhorn's Algorithm - A Fast and Scalable OT Solver

- Proposition: If $\gamma_0^\lambda = \underset{\gamma \in \mathcal{P}}{\operatorname{argmin}} \langle \gamma, \mathbf{C} \rangle_F - \lambda \mathbb{H}(\gamma)$, then there exists $\mathbf{u} \in \mathbb{R}_+^n, \mathbf{v} \in \mathbb{R}_+^m$ such that

$$\gamma_0^\lambda = \operatorname{diag}(\mathbf{u}) \mathbf{K} \operatorname{diag}(\mathbf{v}), \text{ where } \mathbf{K} = e^{-\mathbf{C}/\lambda}$$

- Write down the Lagrangian to solve the convex optimisation problem

$$L(\gamma, \alpha, \beta) = \sum_{ij} \gamma_{i,j} \mathbf{C}_{i,j} + \lambda \gamma_{i,j} (\log \gamma_{i,j} - 1) + \alpha^T (\gamma \mathbf{1} - \mathbf{a}) + \beta^T (\gamma^T \mathbf{1} - \mathbf{b})$$

$$\partial L / \partial \gamma_{i,j} = \mathbf{C}_{i,j} + \lambda \log \gamma_{i,j} + \alpha_i + \beta_j \Rightarrow 0$$

$$\gamma_{i,j} = e^{\frac{\alpha_i}{\beta}} e^{-\frac{\mathbf{C}_{i,j}}{\lambda}} e^{\frac{\beta_j}{\lambda}} = \mathbf{u}_i K_{ij} \mathbf{v}_j$$

Sinkhorn's Algorithm - A Fast and Scalable OT Solver

- Proposition: If $\gamma_0^\lambda = \underset{\gamma \in \mathcal{P}}{\operatorname{argmin}} \langle \gamma, \mathbf{C} \rangle_F - \lambda \mathbb{H}(\gamma)$, then there exists $\mathbf{u} \in \mathbb{R}_+^n, \mathbf{v} \in \mathbb{R}_+^m$ such that

$$\gamma_0^\lambda = \operatorname{diag}(\mathbf{u}) \mathbf{K} \operatorname{diag}(\mathbf{v}), \text{ where } \mathbf{K} = e^{-\mathbf{C}/\lambda}$$

- To solve, first use the marginalisation constraints

$$\begin{cases} \operatorname{diag}(\mathbf{u}) K \operatorname{diag}(\mathbf{v}) \mathbf{1}_m = \mathbf{a} \\ \operatorname{diag}(\mathbf{v}) K^T \operatorname{diag}(\mathbf{u}) \mathbf{1}_n = \mathbf{b} \end{cases}$$

$$\begin{cases} \mathbf{u} \odot K \mathbf{v} = \mathbf{a} \\ \mathbf{v} \odot K^T \mathbf{u} = \mathbf{b} \end{cases}$$

- Fixed-point algorithm, repeat until convergence [Sinkhorn, '67]

$$\mathbf{u} \leftarrow \mathbf{a} / \mathbf{K} \mathbf{v} \quad \text{followed by} \quad \mathbf{v} \leftarrow \mathbf{b} / \mathbf{K}^T \mathbf{u}$$

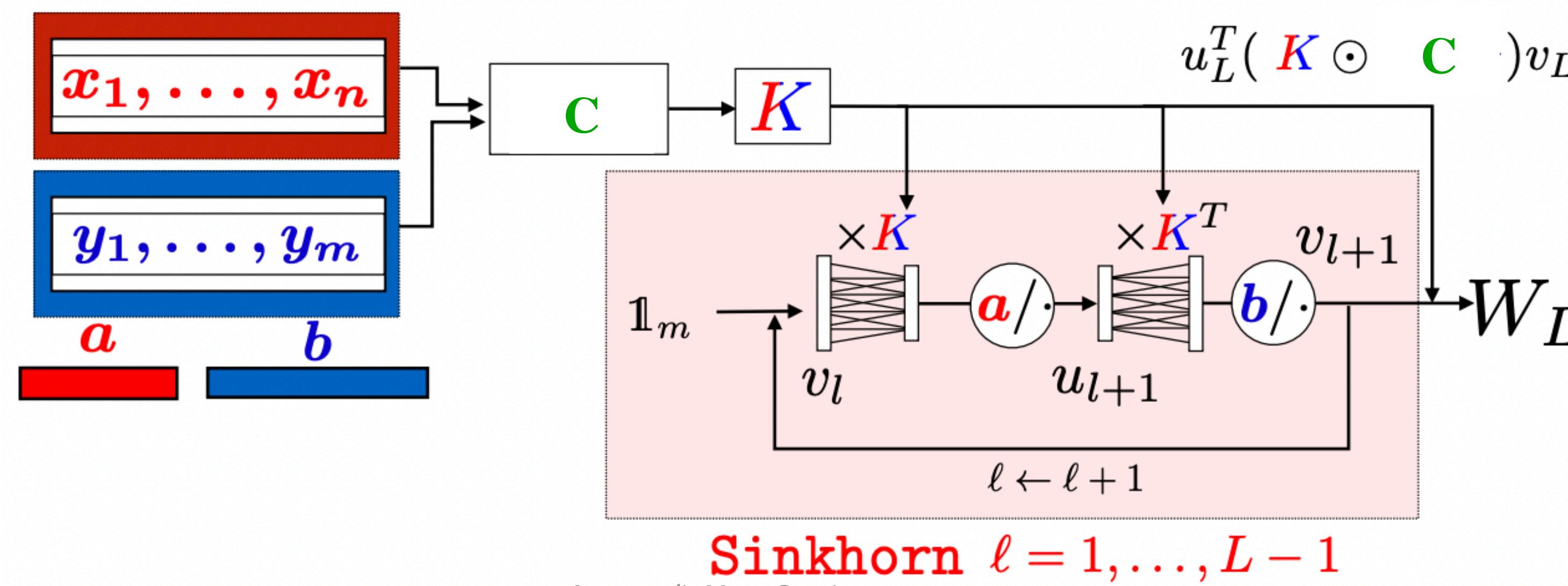
Sinkhorn's Algorithm - A Fast and Scalable OT Solver

- Fixed-point algorithm, repeat until convergence [Sinkhorn, '67]

$$\mathbf{u} \leftarrow \mathbf{a}/\mathbf{K}\mathbf{v} \quad \text{followed by} \quad \mathbf{v} \leftarrow \mathbf{b}/\mathbf{K}^T\mathbf{u}$$

- Define the iterative Wasserstein Distance

$$W_L(\boldsymbol{\mu}, \boldsymbol{\nu}) = \langle \boldsymbol{\gamma}_L, \mathbf{C} \rangle, \quad \text{where } \boldsymbol{\gamma}_L = \text{diag}(\mathbf{u}_L) \mathbf{K} \text{ diag}(\mathbf{v}_L)$$



- $\frac{\partial W_L}{\partial \mathbf{X}}, \frac{\partial W_L}{\partial \mathbf{a}}, \frac{\partial W_L}{\partial \mathbf{Y}}, \frac{\partial W_L}{\partial \mathbf{b}}$ can be computed recursively (and using autodiff)

Sinkhorn's Algorithm - A Fast and Scalable OT Solver

- Computational complexity - $\mathcal{O}((n + m)^2) \times \mathcal{O}(d^2)$
- Linear convergence for $\mathbf{u}, \mathbf{v} \rightarrow$ Rate bounded by λ

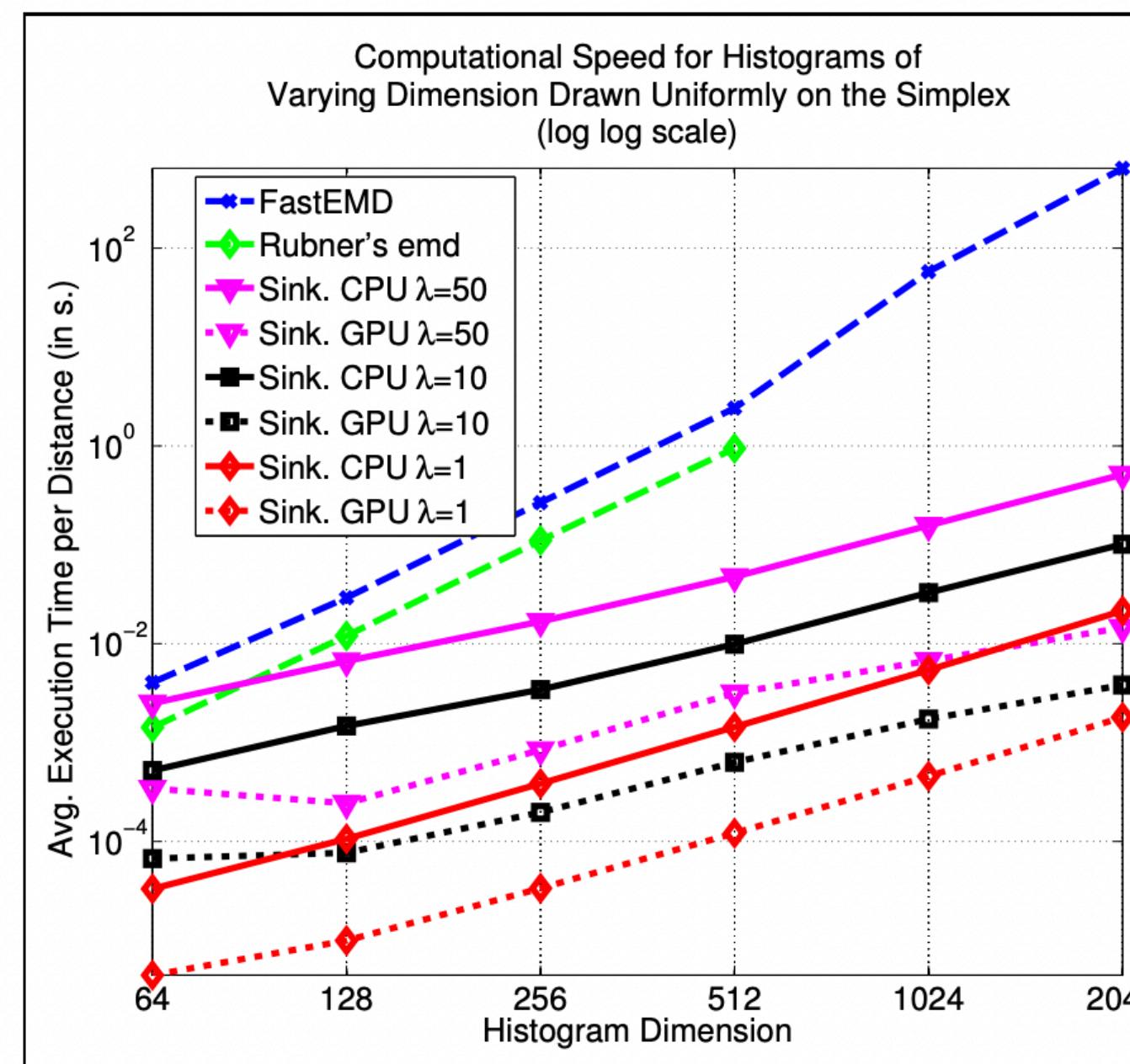


Image credit: [Cuturi et al., 2013]

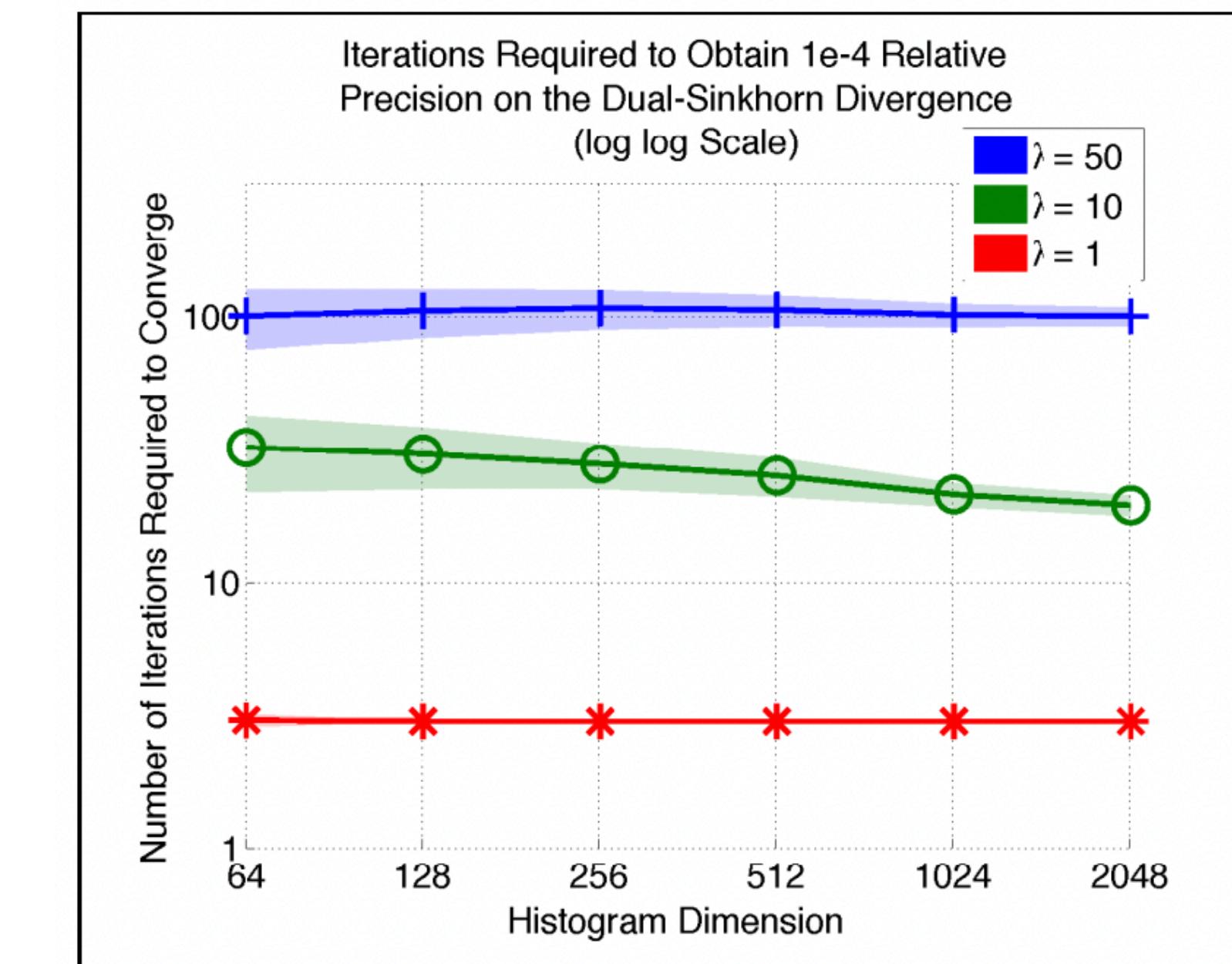


Image credit: [Cuturi et al., 2013]

Sinkhorn's Algorithm as Bregman Projections

- Fixed-point algorithm, repeat until convergence [Sinkhorn, '67]
 $\mathbf{u} \leftarrow \mathbf{a}/\mathbf{K}\mathbf{v}$ followed by $\mathbf{v} \leftarrow \mathbf{b}/\mathbf{K}^T\mathbf{u}$
- [Benamou et al., 2015] show that solving entropic regularised OT is the same as Bregman projections

- Proposition: γ_0^λ is the solution of the following Bregman projection

$$\gamma_0^\lambda = \underset{\gamma \in \mathcal{P}}{\operatorname{argmin}} \text{KL}(\gamma, \mathbf{K})$$

- Can be generalised to calculate Wasserstein barycenters

$$\min_{\mu} \sum_{i=1}^N \lambda_i W_\lambda(\mu, \nu_i) \quad \rightarrow \quad \gamma = [\gamma_1, \dots, \gamma_N] = \underset{\gamma \in \mathcal{P}_i^K}{\operatorname{argmin}} \sum_i \lambda_i \text{KL}(\gamma_i, \mathbf{K})$$

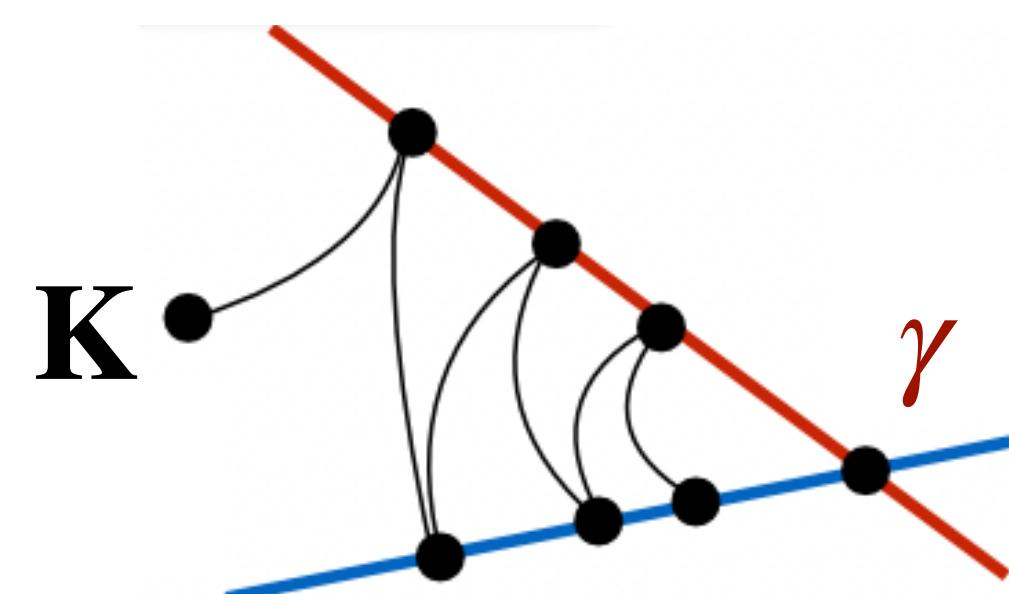


Image credit: Marco

Sinkhorn Divergences

- Given the regularised Wasserstein Distance $W_\lambda(\mu, \nu) = \min_{\gamma \in \mathcal{P}} \langle \gamma, \mathbf{C} \rangle_F - \lambda \mathbb{H}(\gamma)$
- Issue: $W_\lambda(\mu, \mu) \neq 0$
- Fix [Ramdas et al., 2017] : $\overline{W}_\lambda(\mu, \nu) = W_\lambda(\mu, \nu) - \frac{1}{2}W_\lambda(\mu, \mu) - \frac{1}{2}W_\lambda(\nu, \nu)$
 - Sinkhorn Divergences have some nice distance-based and interpolating properties
 - When $\lambda \rightarrow 0$, we re-obtain OT
 - $\lim_{\lambda \rightarrow 0} \overline{W}_\lambda(\mu, \nu) = W_p^p(\mu, \nu)$
 - When $\lambda \rightarrow \infty$, we obtain kernel-based distances (Maximum Mean Discrepancy, Energy Distance)
 - $\lim_{\lambda \rightarrow \infty} \overline{W}_\lambda(\mu, \nu) = E(\mu, \nu) - \frac{1}{2}E(\mu, \mu) - \frac{1}{2}E(\nu, \nu)$, where $E(\mu, \nu) = \langle \mathbf{a}\mathbf{b}^T, \mathbf{C} \rangle$

Sinkhorn Divergences

- Assuming we have samples $x_1, \dots, x_n \sim \mu$, $y_1, \dots, y_m \sim \nu$, what are the considerations involved when computing $W_p^p(\hat{\mu}_n, \hat{\nu}_m)$, where $\hat{\mu}_n = \frac{1}{n} \sum_i \delta_{x_i}$, $\hat{\nu}_m = \frac{1}{m} \sum_j \delta_{y_j}$?

Computational Costs

$$(n + m)^2$$

$$MMD(\mu, \nu) = E(\mu, \nu) - \frac{1}{2}E(\mu, \mu) - \frac{1}{2}E(\nu, \nu)$$

$$\mathcal{O}(1/\sqrt{n})$$

$$\begin{matrix} \uparrow \\ \lambda \rightarrow \infty \end{matrix}$$

$$\mathcal{O}((n + m)^2)$$

$$\overline{W}_\lambda(\mu, \nu) = W_\lambda(\mu, \nu) - \frac{1}{2}W_\lambda(\mu, \mu) - \frac{1}{2}W_\lambda(\nu, \nu)$$

$$\mathcal{O}\left(\frac{1}{\lambda^{d/2}\sqrt{n}}\right)$$

$$\mathcal{O}((n + m)nm \log nm)$$

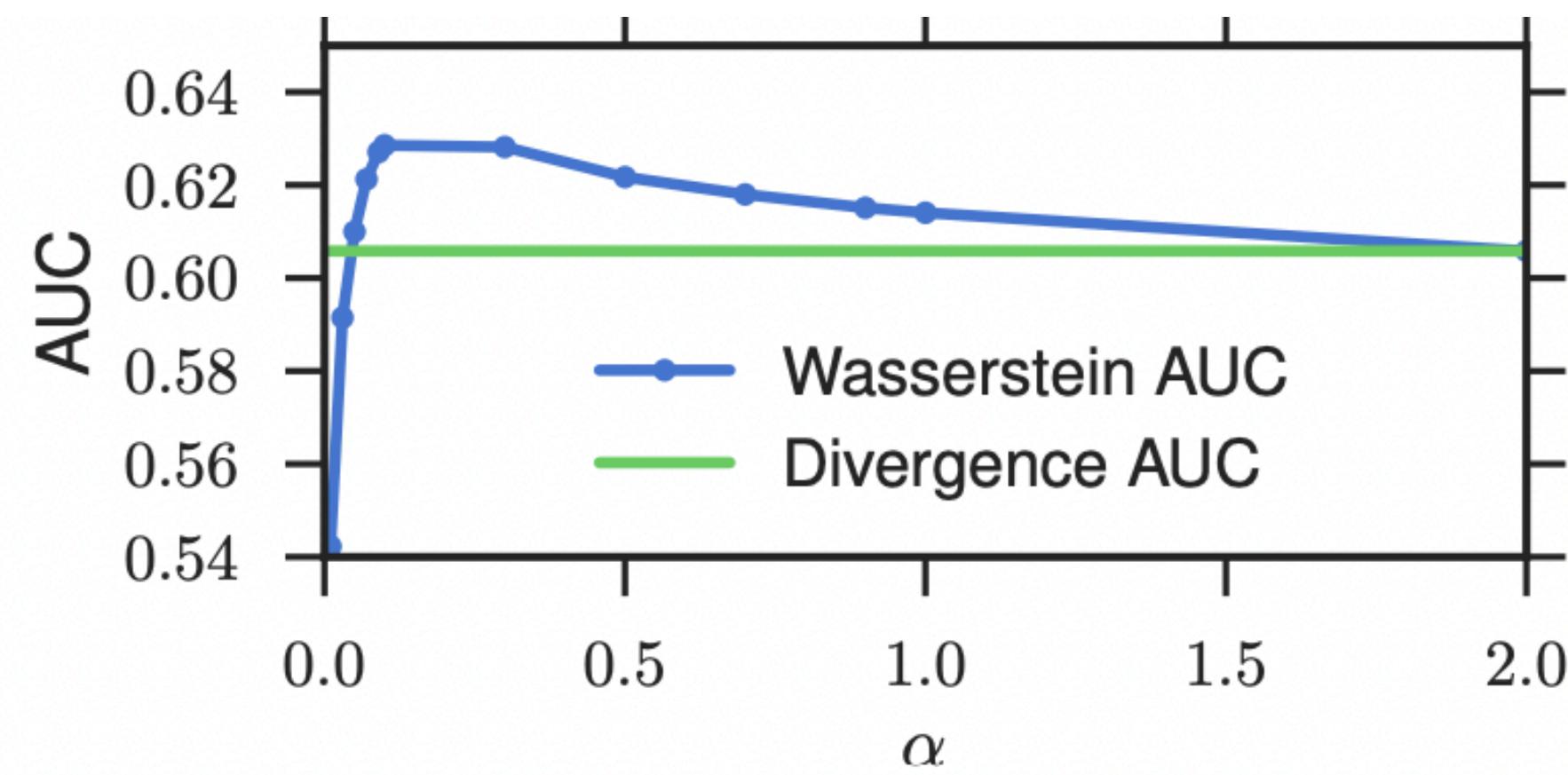
$$W_p^p(\mu, \nu)$$

$$\mathcal{O}(1/n^{1/d})$$

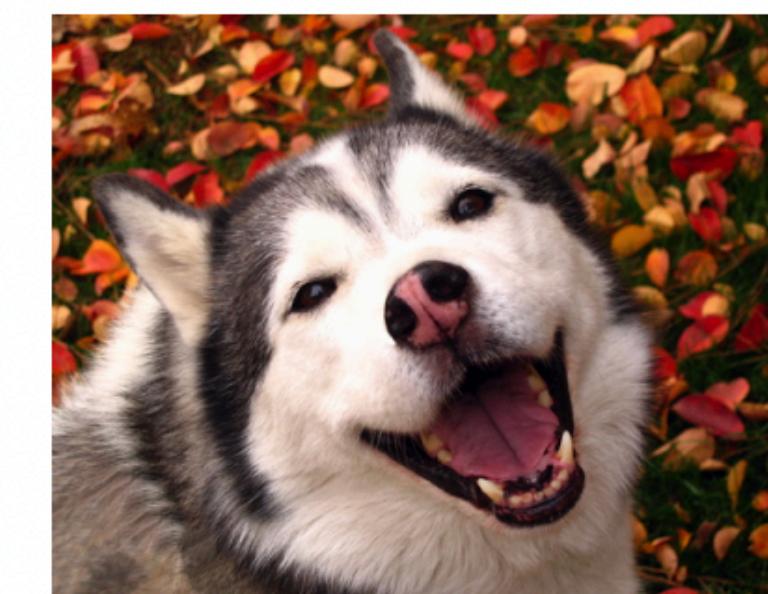
Applications in Machine Learning

OT for Supervised Learning - Wasserstein Loss

- [Frogner et al 2015] Multiclass classification - learn optimal maps from $\mathcal{X} \in \mathbb{R}^d$ to $\mathcal{Y} = \mathbb{R}_+^K$ through $\mathcal{H} = h_\theta : \mathcal{X} \rightarrow \mathcal{Y}$
 - $h_\theta, y \in \Delta^K$ (the K-d simplex), and $\mathbf{C} \in \mathbb{R}_+^{K,K}$ where $\mathbf{C}_{\kappa,\kappa'} = d^p(\kappa, \kappa')$
 - Minimise the entropic regularised Wasserstein Distance $W_p^\lambda(h(\cdot | x), y(\cdot))$
 - Ground-truth metric can encode semantic similarity
 - Flickr Creative Commons 100M dataset : $d^p(\kappa, \kappa') = \|\text{word2vec}(\kappa) - \text{word2vec}(\kappa')\|_2^2$
 - Example labels - travel, square, wedding, art, flower, music, nature, ...



Siberian husky



Eskimo dog

OT for Generative Modelling - WGAN

- Let \mathbb{P}_r denote the real data distribution over a metric space Ω (i.e image space of $[0,1]^{h \times w \times 3}$),
- Let Z be a random variable over a space \mathcal{Z} , $g : \mathcal{Z} \times \mathbb{R}^d \rightarrow \Omega$ a function parametrised by $\theta \in \mathbb{R}^d$
- Let \mathbb{P}_θ denote the distribution over $g_\theta(Z)$
- [Arjovsky et al., 2017] trains generative models by minimising the W_1 distance b/w \mathbb{P}_r and \mathbb{P}_θ

$$W_1^1(\mathbb{P}_r, \mathbb{P}_\theta) = \inf_{\gamma \in \mathcal{P}(\mathbb{P}_r, \mathbb{P}_\theta)} \mathbb{E}_{(x,y) \sim \gamma} [\|x - y\|]$$

- Using the semi-dual formulation, where f is a 1-Lipschitz function -

$$W_1^1(\mathbb{P}_r, \mathbb{P}_\theta) = \sup_{\|f\|_L \leq 1} \mathbb{E}_{x \sim \mathbb{P}_r} [f(x)] - \mathbb{E}_{x \sim \mathbb{P}_\theta} [f(x)]$$

- If instead we consider K-Lipschitz functions instead, we get

$$\sup_{\|f\|_L \leq 1} \mathbb{E}_{x \sim \mathbb{P}_r} [f(x)] - \mathbb{E}_{x \sim \mathbb{P}_\theta} [f(x)] \leq \sup_{\|f\|_L \leq K} \mathbb{E}_{x \sim \mathbb{P}_r} [f(x)] - \mathbb{E}_{x \sim \mathbb{P}_\theta} [f(x)] = K \cdot W_1^1(\mathbb{P}_r, \mathbb{P}_\theta)$$

OT for Generative Modelling - WGAN

- Therefore, for parametrised family of functions $\{f_\phi\}_{\phi \in \Phi}$ that are all K-Lipschitz, solve instead

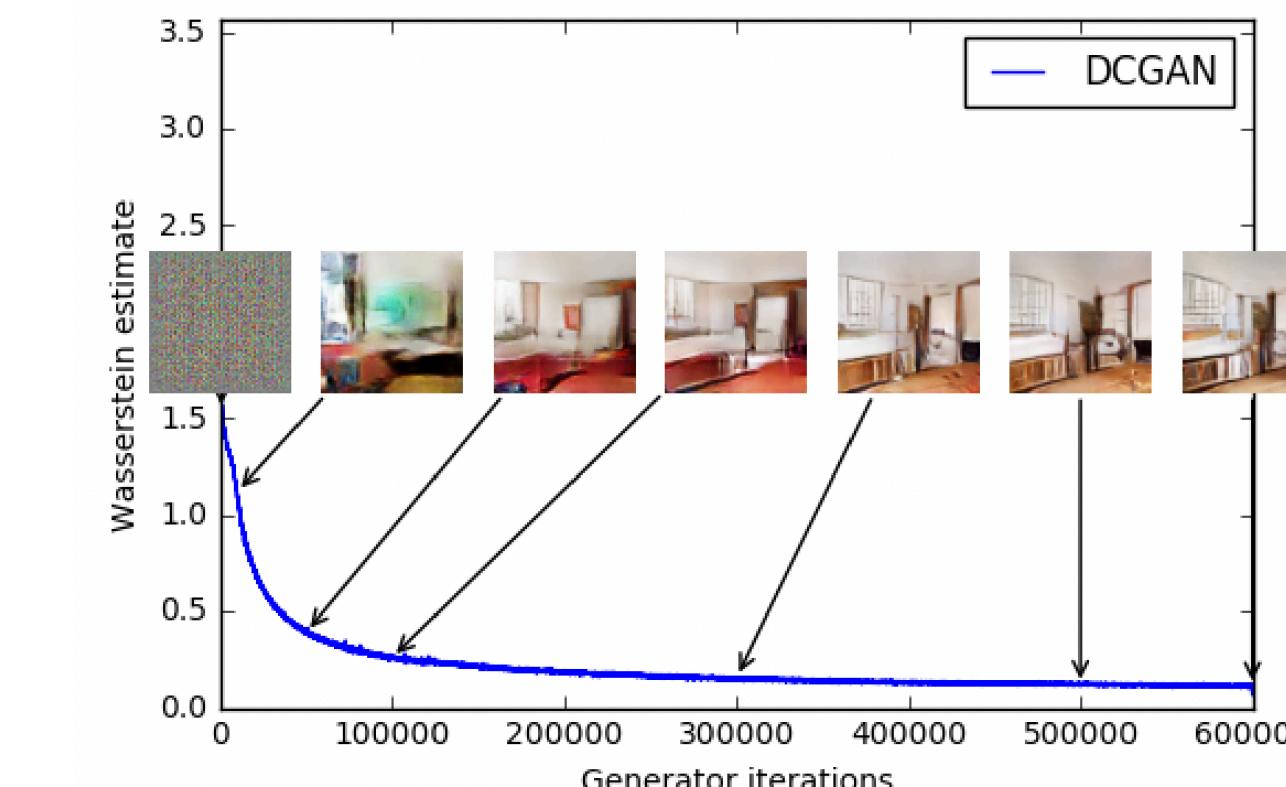
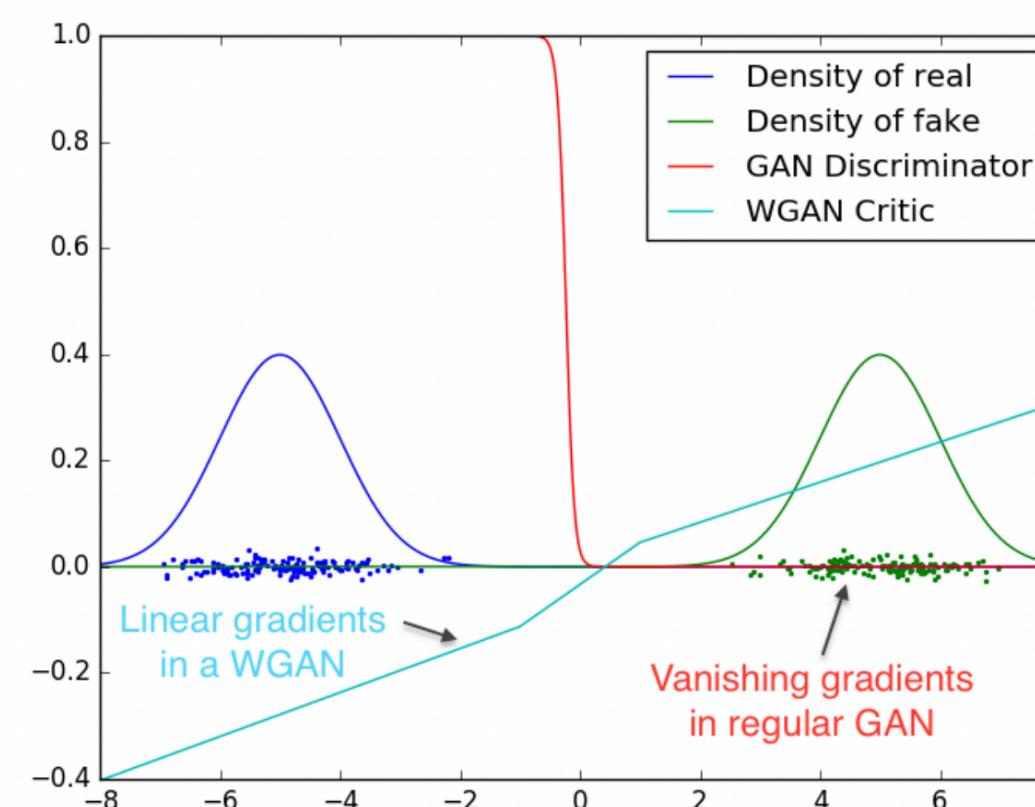
$$W(\mathbb{P}_r, \mathbb{P}_\theta) = \max_{\phi \in \Phi} \mathbb{E}_{x \sim \mathbb{P}_r} [f_\phi(x)] - \mathbb{E}_{z \sim p(z)} [f_\phi(g_\theta(z))]$$

- The paper proves that $W(\mathbb{P}_r, \mathbb{P}_\theta)$ is the W_1 distance unto a multiplicative factor, and further that

$$\nabla_\theta W(\mathbb{P}_r, \mathbb{P}_\theta) = - \mathbb{E}_{z \sim p(z)} [\nabla_\theta f(g_\theta(z))]$$

- K-Lipschitz bound is roughly enforced by gradient clipping

$$\phi \leftarrow \text{clip}(\phi, -c, c)$$



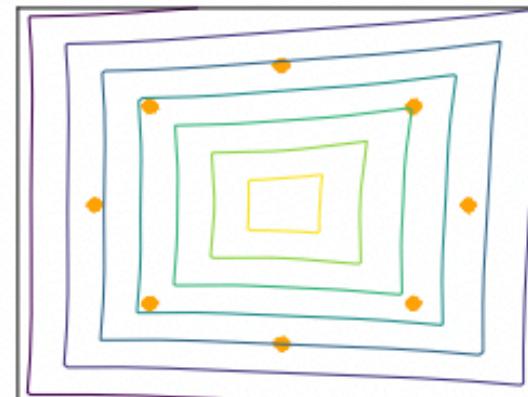
OT for Generative Modelling - Extensions

- [Guljarani et al., 2017] Improved WGAN - Replace weight clipping with constraint on gradient norm

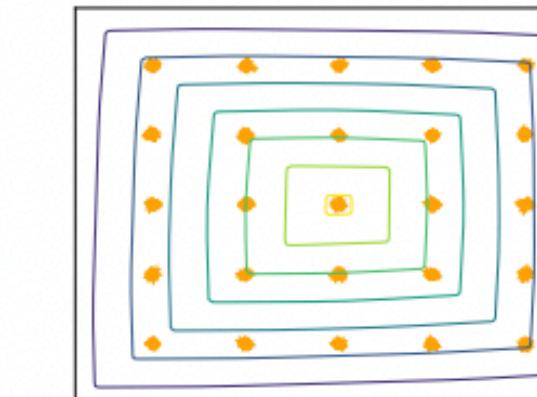
$$\bullet \quad W(\mathbb{P}_r, \mathbb{P}_\theta) = \max_{\phi \in \Phi} \mathbb{E}_{x \sim \mathbb{P}_r} [f_\phi(x)] - \mathbb{E}_{z \sim p(z)} [f_\phi(g_\theta(z))] + \lambda \mathbb{E}_{x \sim \mathbb{P}_r} \left[\left(\|\nabla f_\phi(x)\|_2 - 1 \right)^2 \right]$$

- A differentiable function is 1-Lipschitz i.f.f it has gradients with norm at most 1 everywhere

8 Gaussians



25 Gaussians



Swiss Roll

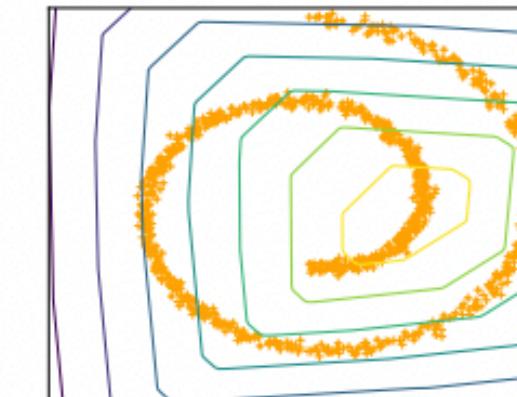
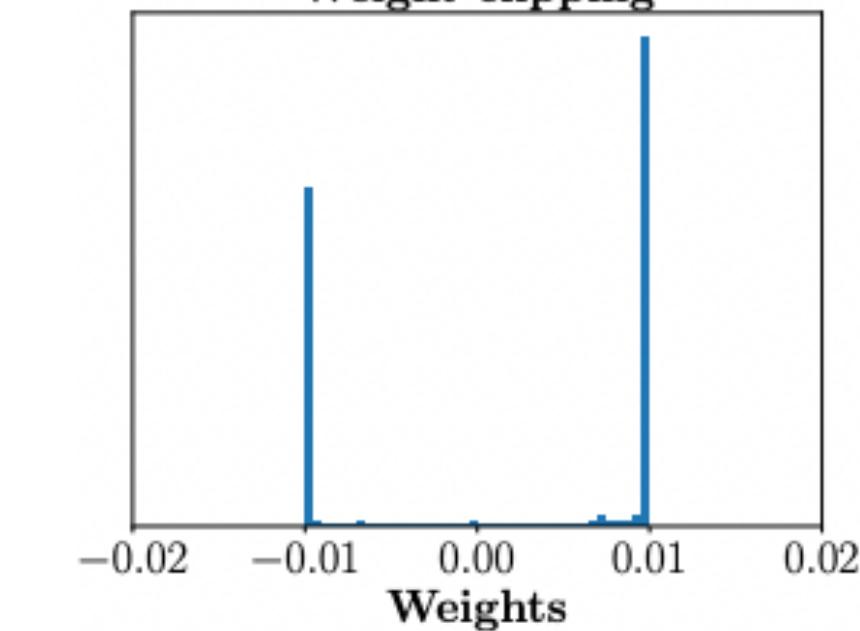


Image credit:[Guljarani et al 2017]

Weight clipping



Gradient penalty

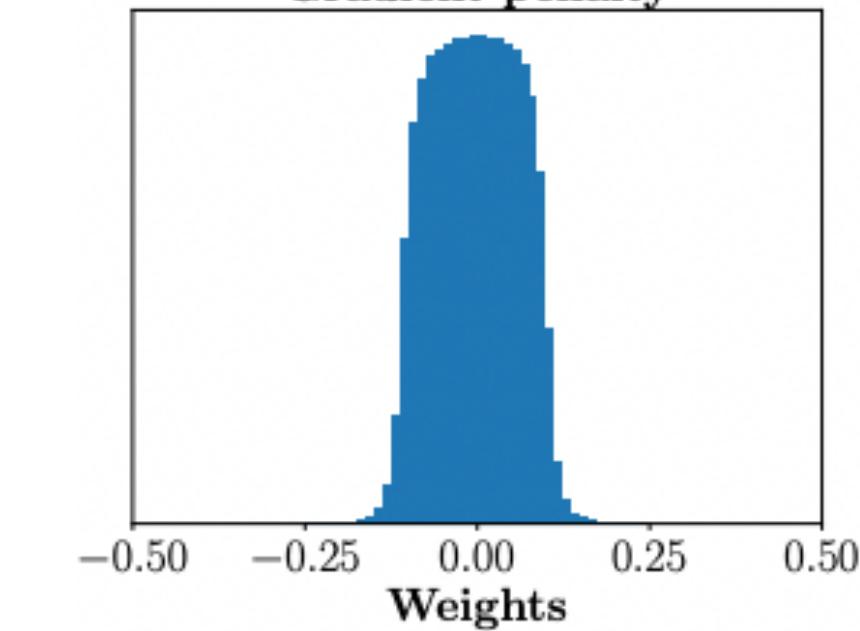
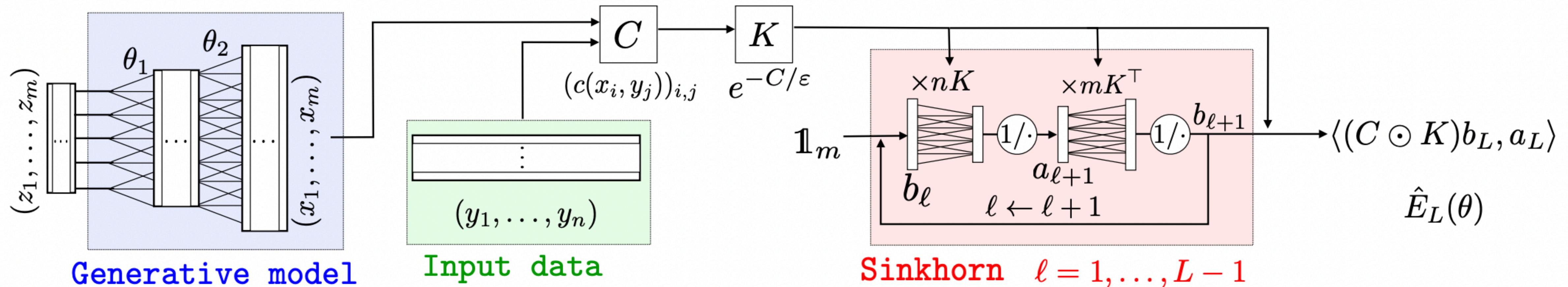


Image credit:[Guljarani et al 2017]

OT for Generative Modelling - Sinkhorn Divergences

- [Genevay et al., 2017] Generative Models with Sinkhorn Divergences

- Define $\mathbb{P}_r = \frac{1}{N} \sum_{j=1}^N \delta_{y_j}$ the empirical data distribution, $\mathbb{P}_\theta = g_\theta(Z)$
- Generator is trained through $\min_{\theta} \hat{E}_L(\theta) = \overline{W}_\lambda(\mathbb{P}_r, \mathbb{P}_\theta) \simeq 2W_L(\mathbb{P}_r, \mathbb{P}_\theta) - W_L(\mathbb{P}_r, \mathbb{P}_r) - W_L(\mathbb{P}_\theta, \mathbb{P}_\theta)$
- Cost function in general is $c_\phi(x, y) = \|f_\phi(x) - f_\phi(y)\|$ where $f_\phi : \mathcal{X} \rightarrow \mathbb{R}^p$
- $\frac{\partial W_L}{\partial \theta}, \frac{\partial W_L}{\partial \phi}$ can be obtained through autodiff



Extensions to OT

Unbalanced Optimal Transport

- $(\mu(\Omega_s) = \nu(\Omega_t))$ no longer holds true?
- Modify the OT problem into a variational formulation - adding infinite sources/sinks, mass creation
- [Matthias et al 2016] Given two measures $\mu \in M_+(\Omega_s)$, $\nu \in M_+(\Omega_t)$,
 - Choose $0 < m \leq \min\{\mu(\Omega_s), \nu(\Omega_t)\}$
 - Define $\gamma_t = \int_{\Omega_t} \gamma(x, y) dy$, $\gamma_s = \int_{\Omega_s} \gamma(x, y) dx$ and solve
$$\min_{\gamma \in \mathcal{M}_+(\Omega_s \times \Omega_t)} \int c(x, y) d\gamma(x, y) \quad \text{subject to } \gamma_t \leq \mu, \gamma_s \leq \nu, \gamma(\Omega_s \times \Omega_t) = m$$
 - Generalise the Wasserstein distance to this setting with the **Wasserstein Fisher-Rao distance**
$$\widehat{W}_2^2(\mu, \nu) = \min_{\gamma \in M_+(\Omega_s \times \Omega_t)} KL(\gamma_t \mid \mu) + KL(\gamma_s \mid \nu) + \int c_\ell(x, y) d\gamma(x, y)$$
 - [Peyre et al., 2017] General algorithm using entropic regularised WFR with Sinkhorn iterations

OT between different metric spaces

- Can you perform OT between two spaces without $c(x, y)$ or when $\dim(\Omega_s) \neq \dim(\Omega_t)$?
- Extending OT metrics to measures with no common ground space
- [Memoli, 2011] proposed Gromov-Wasserstein distance

$$\mathcal{GW}_p(\mu, \nu) = \left(\min_{\gamma \in \mathcal{P}(\mu, \nu)} \mathcal{L}(D_{i,k}, D'_{j,l}) \times \gamma_{i,j} \times \gamma_{k,l} \right)^{\frac{1}{p}}$$

with $D_{i,k} = \| \mathbf{x}_i^s - \mathbf{x}_k^s \|$, $D'_{j,l} = \| \mathbf{x}_j^t - \mathbf{x}_l^t \|$, $\mathcal{L}(D_{i,k}, D'_{j,l})$ is a dissimilarity metric b/w distances

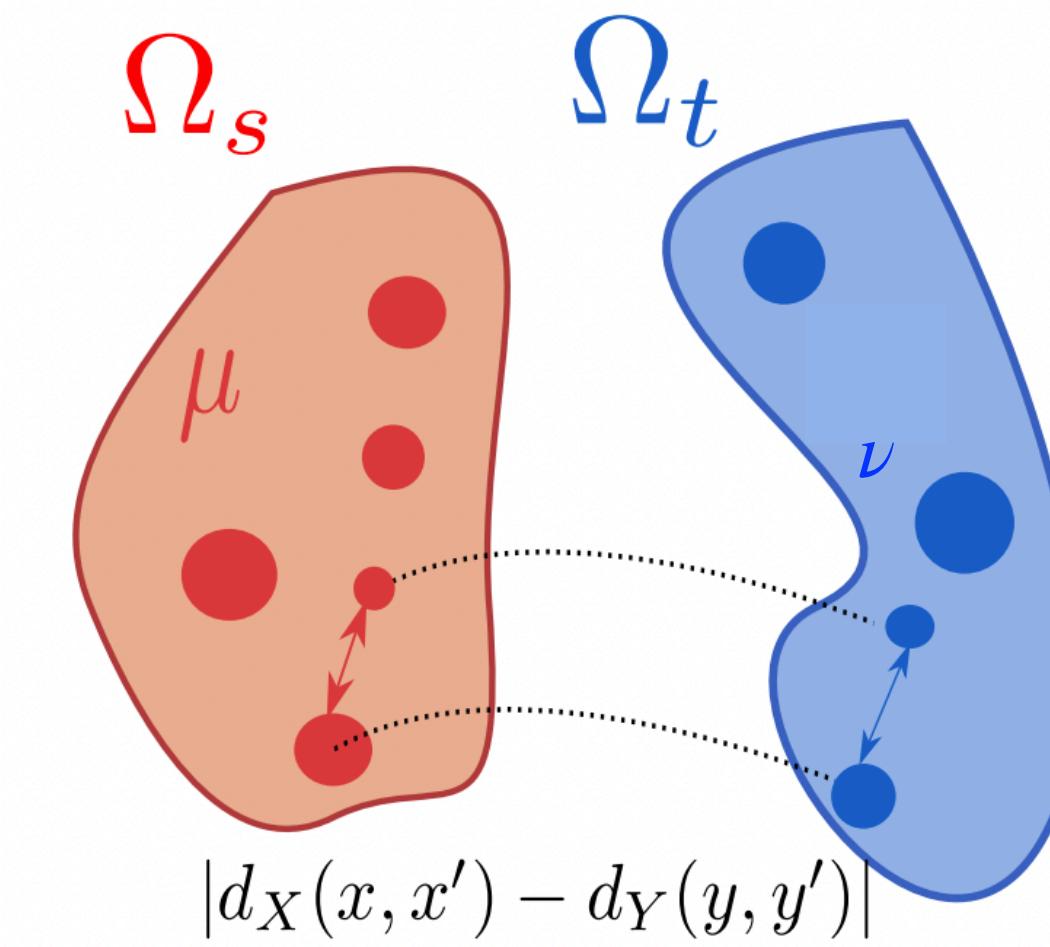
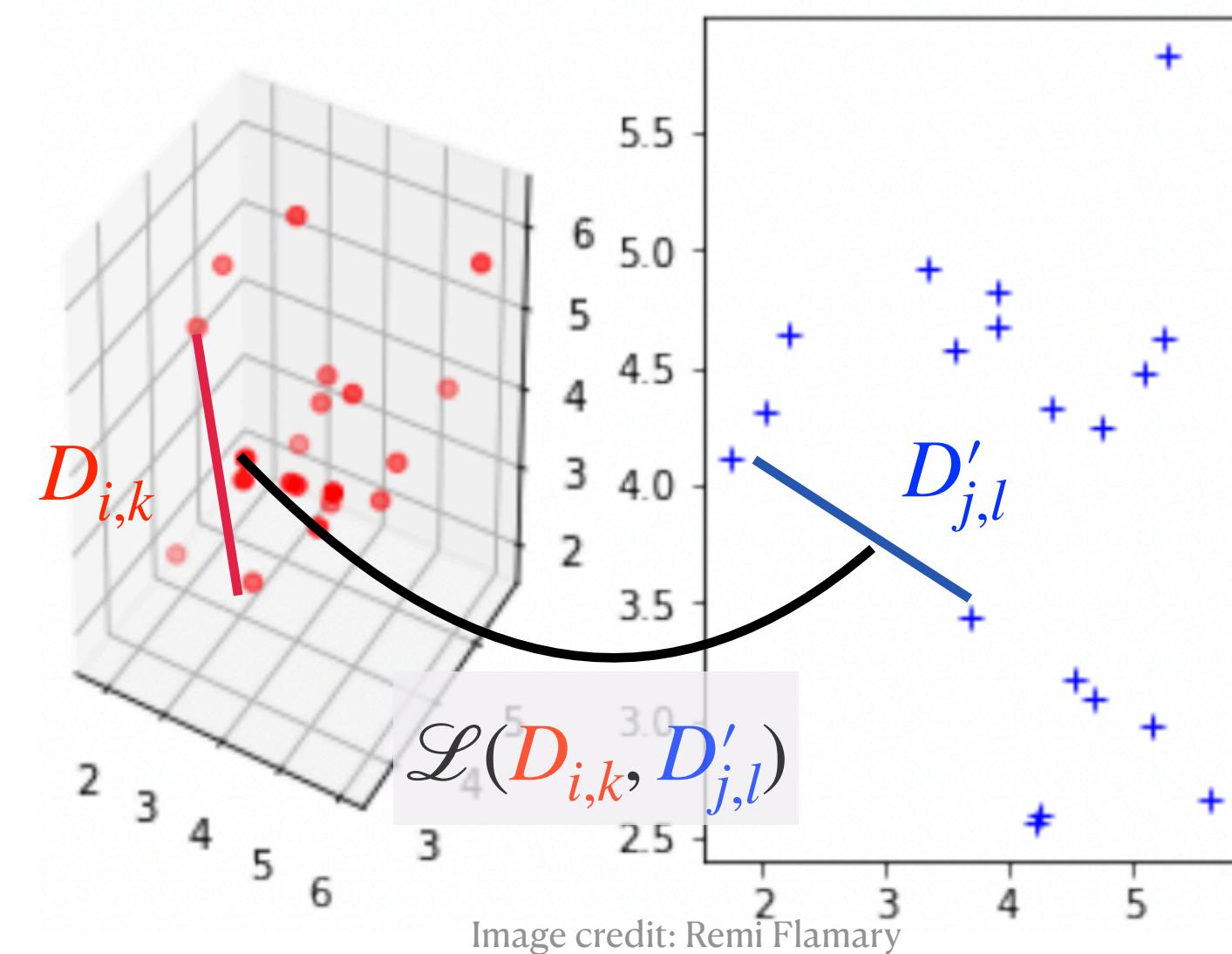


Image credit: Remi Flamary

OT between different metric spaces

- This is a Quadratic Program - Nonconvex, NP-hard
- [Peyre et al., 2016] proposed an entropic regularisation relaxation of this problem

$$\mathcal{GW}_\lambda(\mu, \nu) = \left(\min_{\gamma \in \mathcal{P}(\mu, \nu)} \mathcal{L}(D_{i,k}, D'_{j,l}) \times \gamma_{i,j} \times \gamma_{k,l} \right) - \lambda H(\gamma)$$

- This regularised term can be solved using projected gradient descent/Sinkhorn's algorithm

$$\gamma^{k+1} \leftarrow \operatorname{argmin}_{\gamma^k \in \mathcal{P}} \left\langle \gamma, \mathcal{L}(D_{i,k}, D'_{j,l}) \otimes \gamma^k \right\rangle - \lambda H(\gamma)$$

- Where $\mathbf{K}' = \mathcal{L}(D_{i,k}, D'_{j,l}) \otimes \gamma^k$, the tensor product where $\mathcal{L}(D_{i,k}, D'_{j,l}) \otimes \gamma^k = (\mathcal{L}(D_{i,k}, D'_{j,l}) \gamma_{k,l})_{i,j}$

- Sinkhorn's algorithm returns a stationary point of the nonconvex optimisation problem

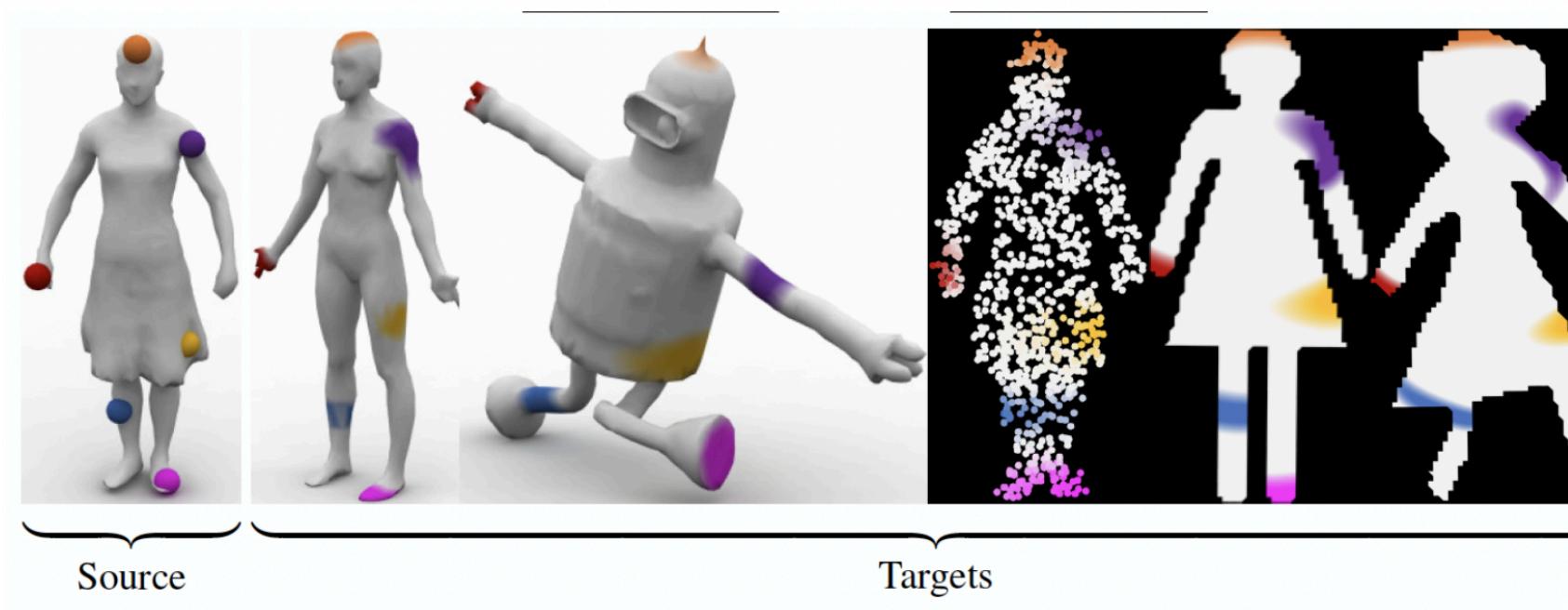


Image credit: [Peyre et al 2016]

Conclusions

- Optimal Transport Theory provides a rigorous and rich mathematical formulation for defining metrics/discrepancy measures between probability measures
- In practise, cheap and efficient approximations have been developed recently
- Applications in generative modelling, supervised learning, computer vision and graphics
- Other cool research to read about
 - [Blanchet et al., 2021] Distributionally Robust Optimisation
 - [Durmus et. Al, 2019] Convergence of Langevin Dynamics Monte Carlo in Wasserstein geometry
 - [Kolouri et al., 2020] Optimal Transport on graphs and arbitrary manifolds through Wasserstein embeddings
 - [Courty et al., 2015] Domain Adaptation with Optimal Transport
 - [Craig et al., 2017] Wasserstein Gradient Flows

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