

A

A

B

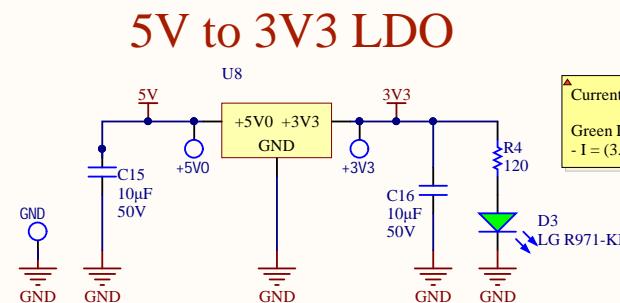
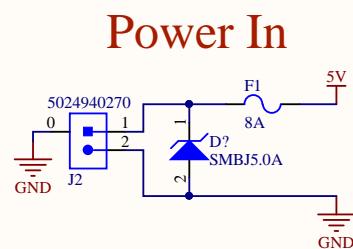
B

C

C

D

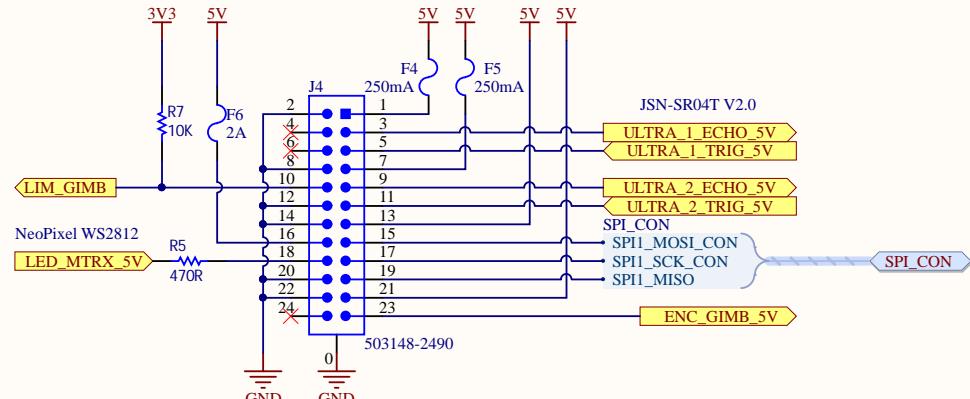
D



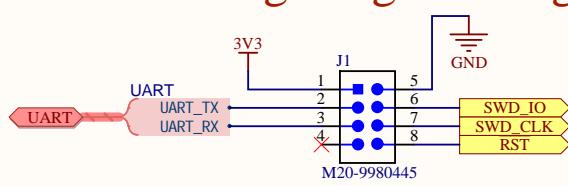
Current Calculations

Green LED voltage drop: 2.2V  
 $I = (3.3-2.2V)/120 = 10.83mA$

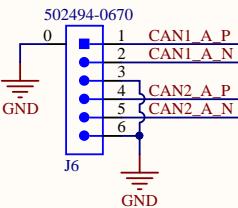
## Sensors/Limit Switch/LED Matrix



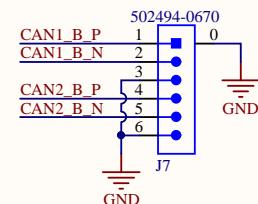
## Debug/Programming



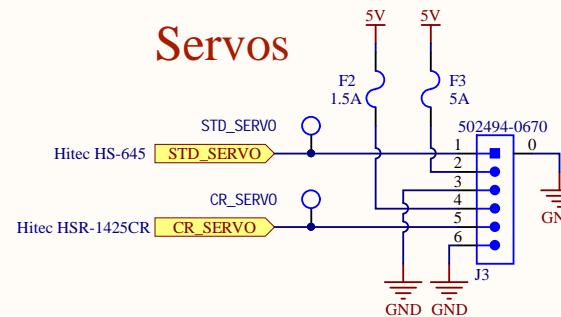
## CAN In



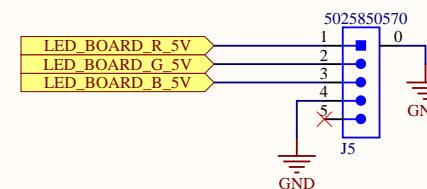
## CAN Out



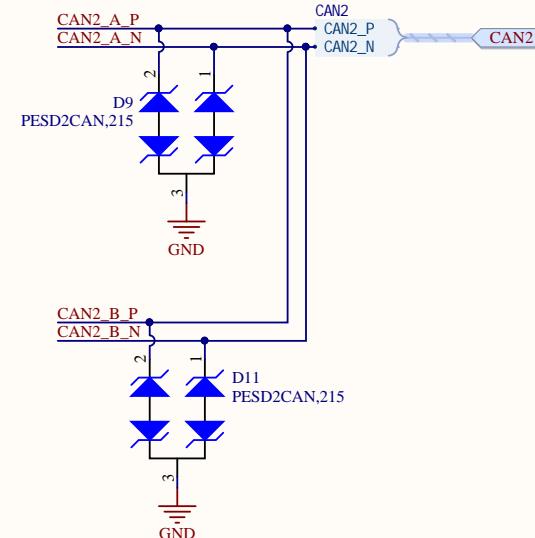
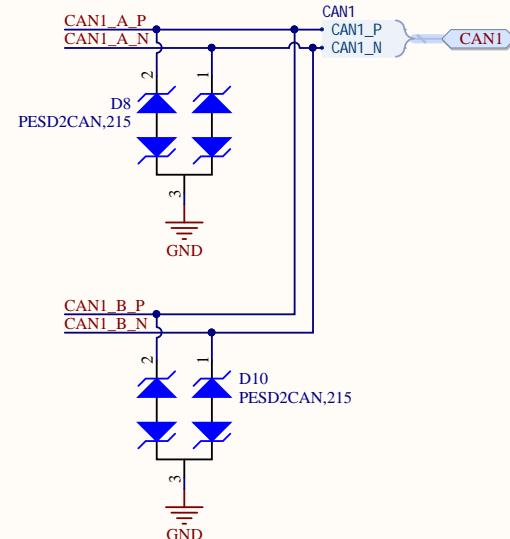
## Servos



## LED Matrix PCB

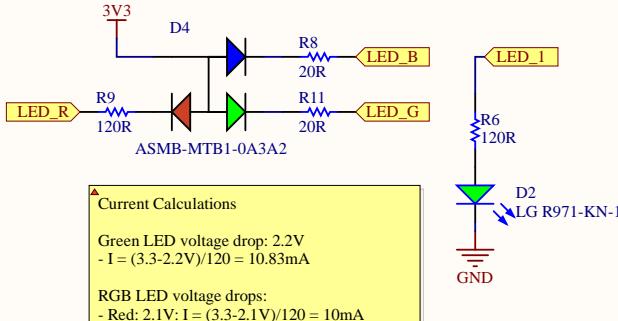


## CAN Protection

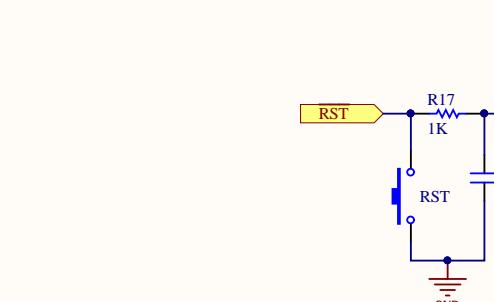


## Test LEDs

A



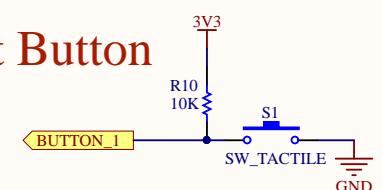
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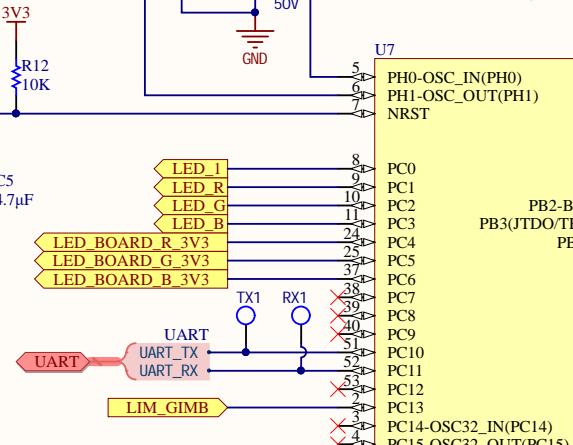
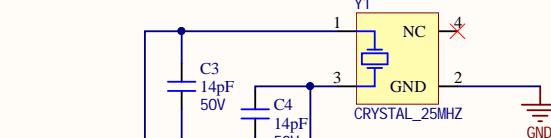
C

**CubeMX is NOT DONE (waiting to hear about potential gimbal mechanical redesign)**

D



## STM32F446RET6



1

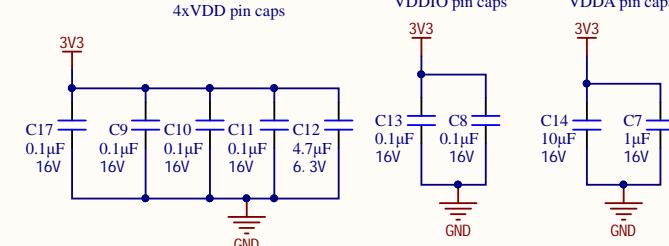
2

3

4

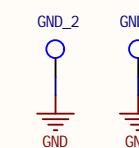
## Decoupling Caps

3



## GND Test Points

B



C



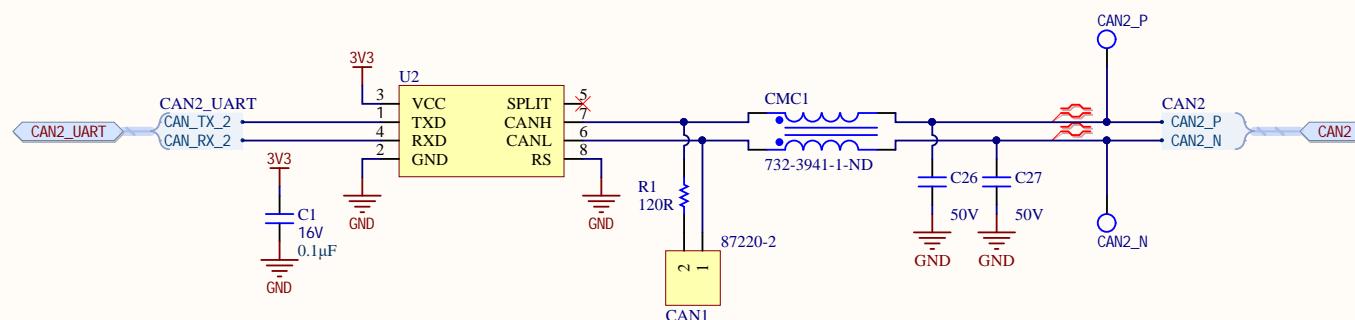
A

A

## CAN Transceivers

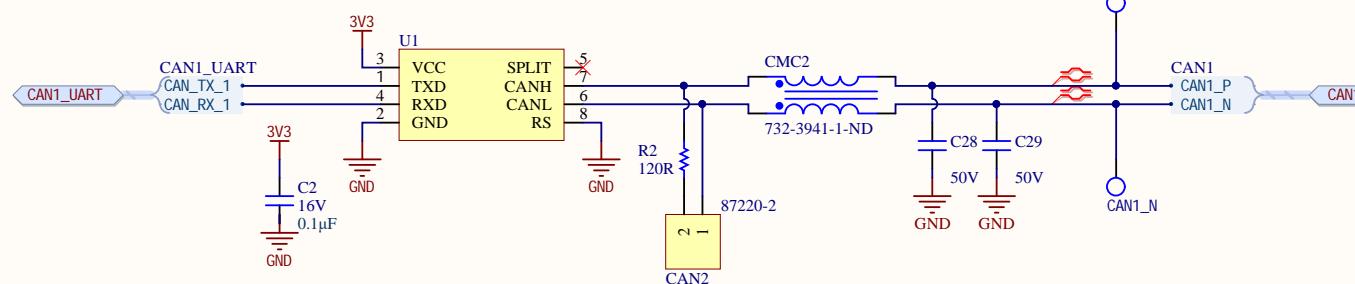
B

B



C

C

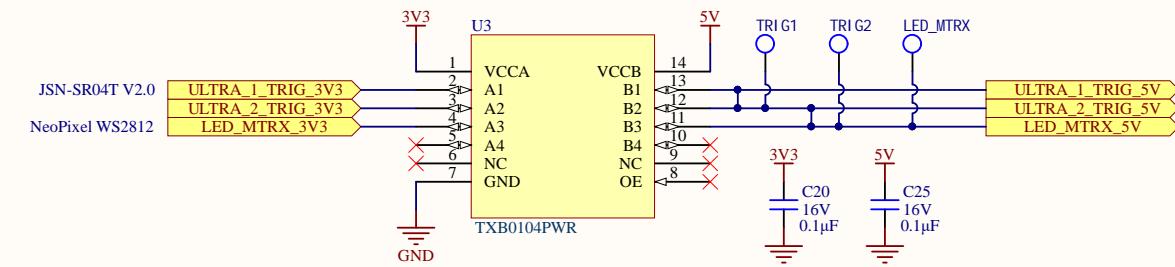


D

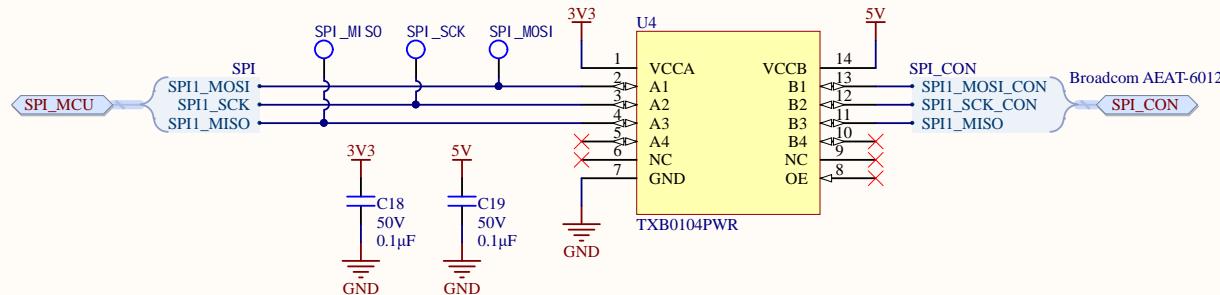
D

Title Gimbal - CAN		UW Robotics 200 University Avenue Waterloo Ontario Canada N2L 3G6	<b>UW ROBOTICS TEAM</b>
Size: Letter	Drawn By: Aidan Gratton & Jing Hao Yao		
Date: 2020-06-02		Sheet 15 of 7	
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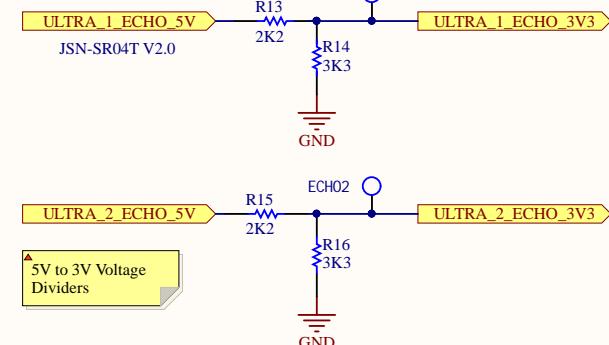
## Ultrasonic/LED Matrix Level Shifters



## SPI Encoder Level Shifter



## Ultrasonic Voltage Dividers



## PWM Encoder Voltage Divider

