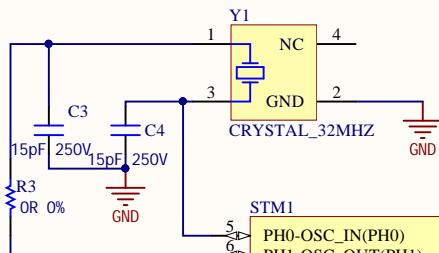


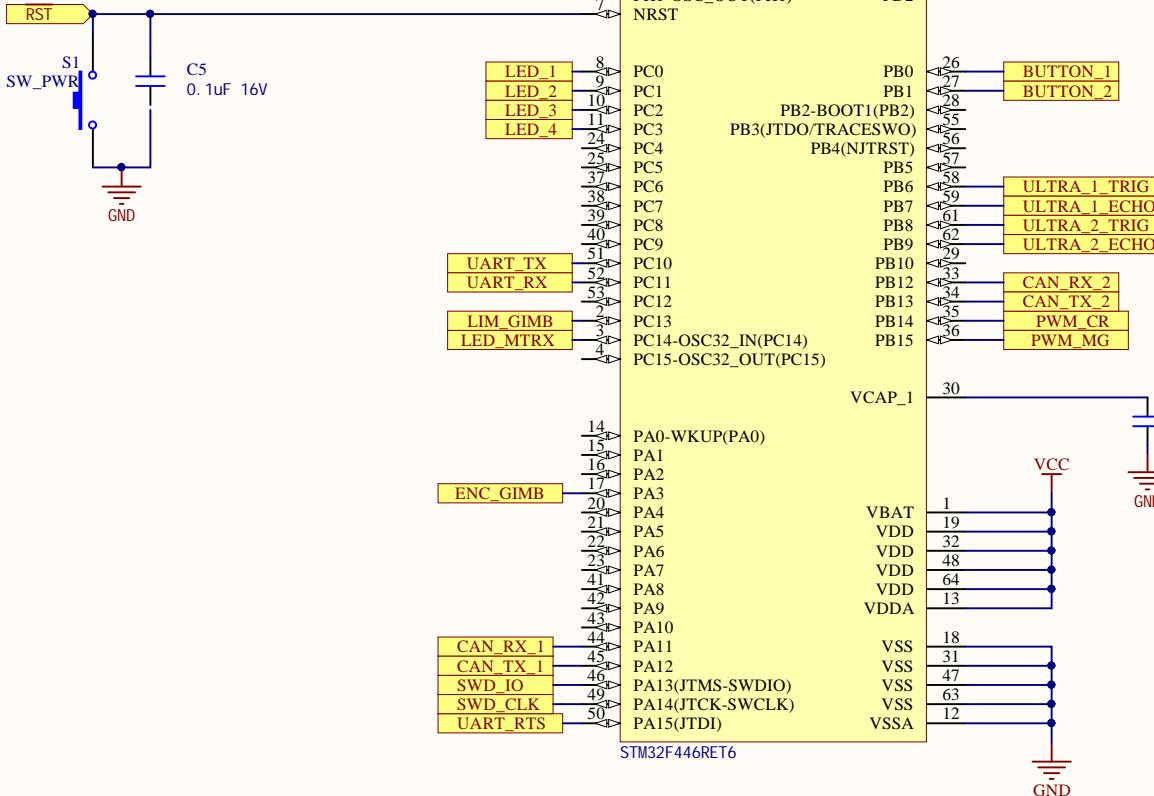
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STM1

PH0-OSC_IN(PH0)
PH1-OSC_OUT(PH1)
NRST

BOOT0 PD2



B

C

D

A

A

B

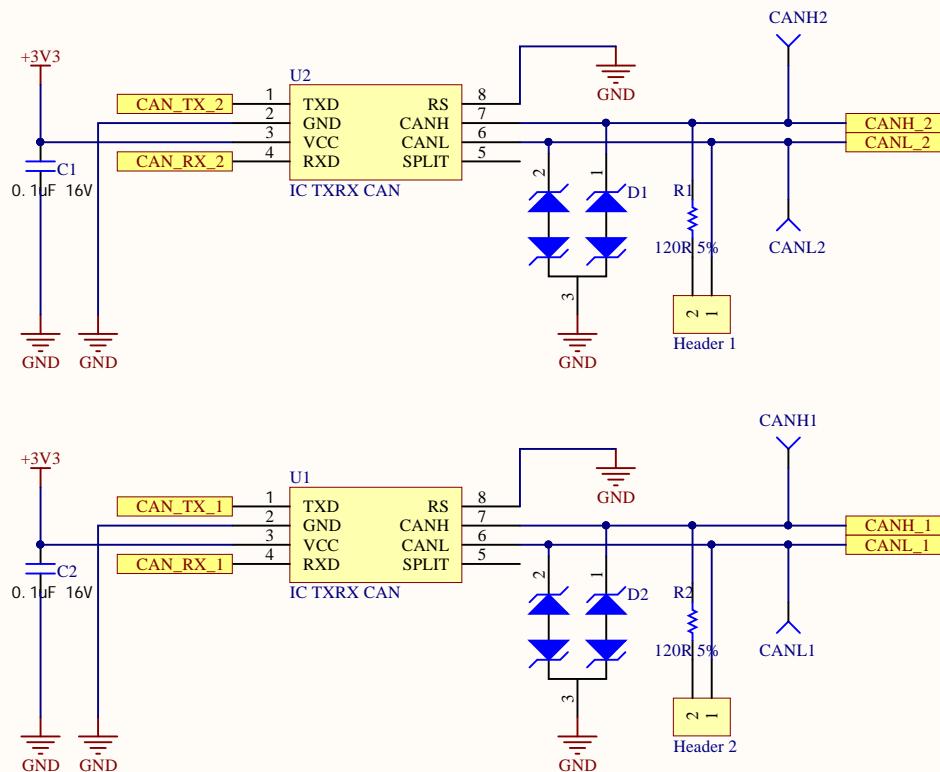
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C

C

D

D

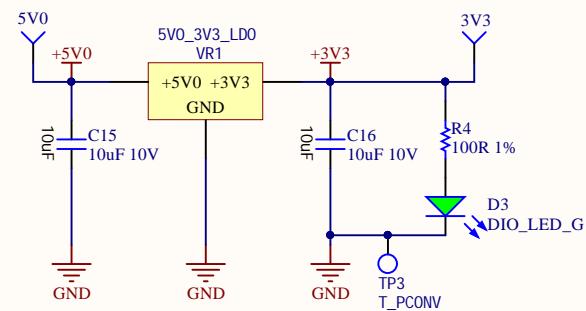


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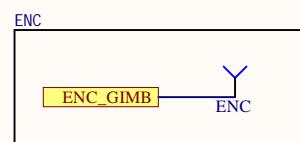
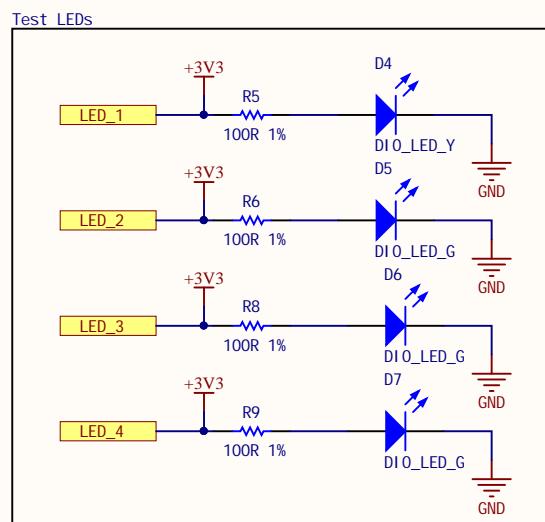
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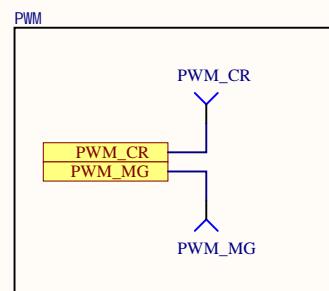
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Title: Gimbal Power Schematic	UW Robotics 200 University Avenue Waterloo Ontario Canada N2L 3G6
Size: Letter	Drawn By: Aidan Gratton
Date: 2019-11-03	Sheet 3 of 5
File: C:\Users\Adrianna\Documents\MarsRover2020-PCB\Projects\Gimbal\Rev1\sch\POWER.SchDoc	UW ROBOTICS TEAM

A

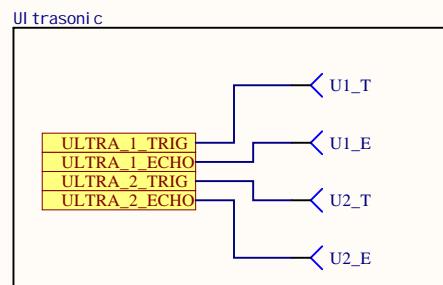
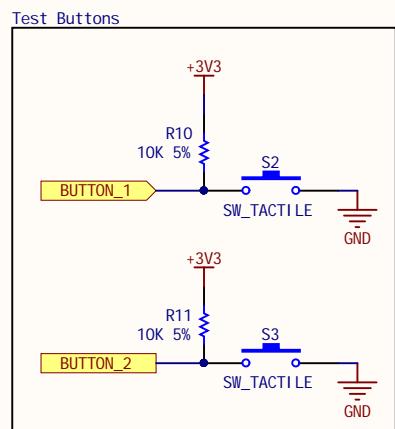


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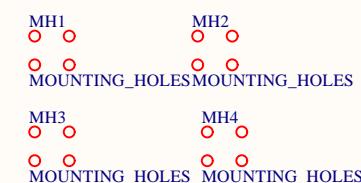
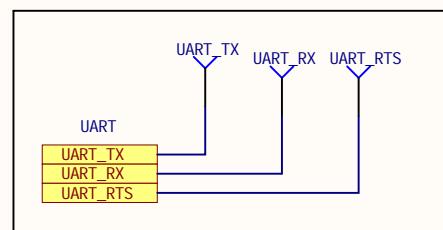


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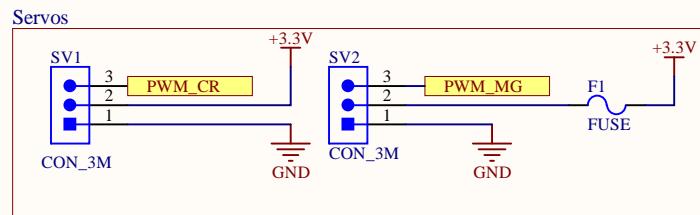
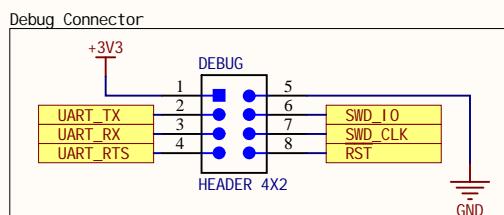
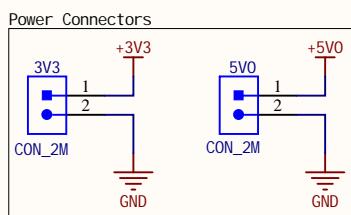
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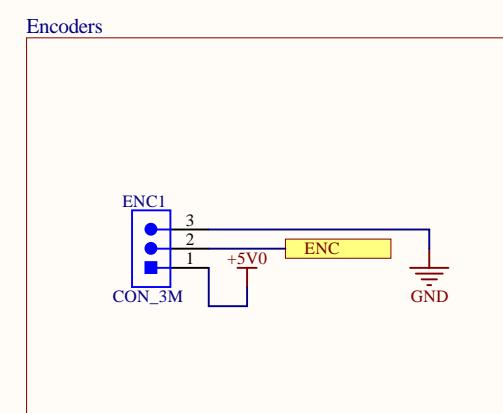
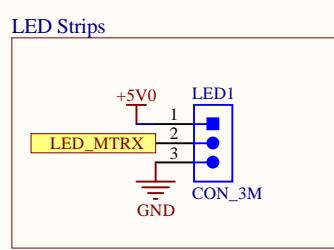
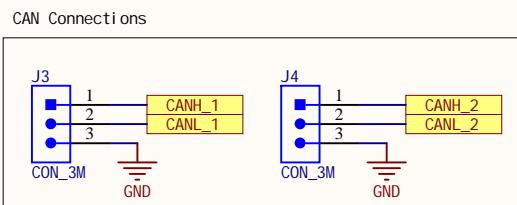
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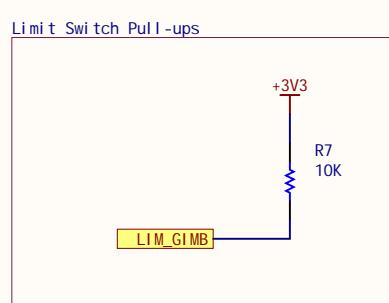
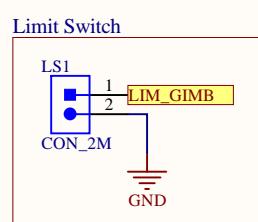
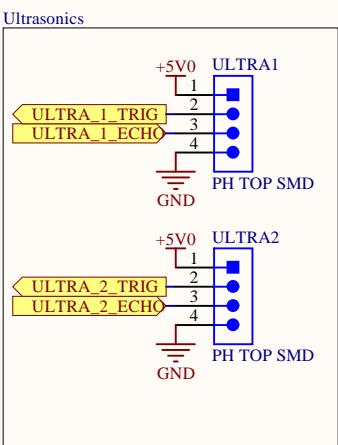
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