

A

A

B

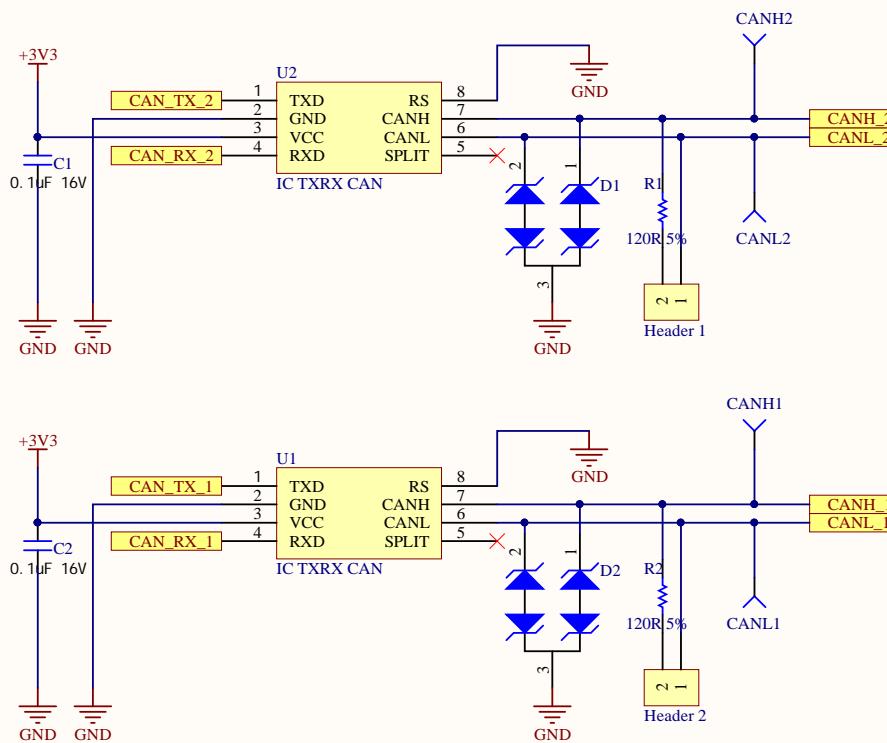
B

C

C

D

D



Title: Gimbal CAN Schematic

Size: Letter | Drawn By: Jing Hao Yao

Date: 2019-12-19

Sheet 12 of 5

UW Robotics
200 University Avenue
Waterloo
Ontario
Canada N2L 3G6

UW ROBOTICS TEAM

A

A

B

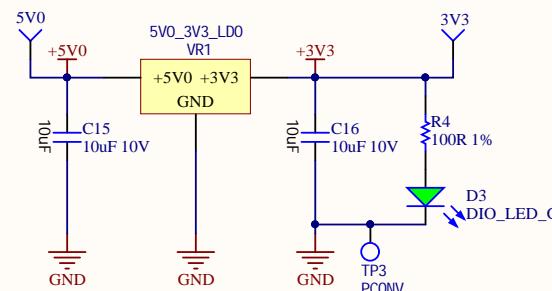
B

C

C

D

D



Title	Gimbal Power Schematic
Size:	Letter
Date:	2019-12-19
File:	C:\Users\gratt\Documents\University Teams\UW Mars Rover\2020 Electrical Repo\MarsRover2020-PCB\Projects\

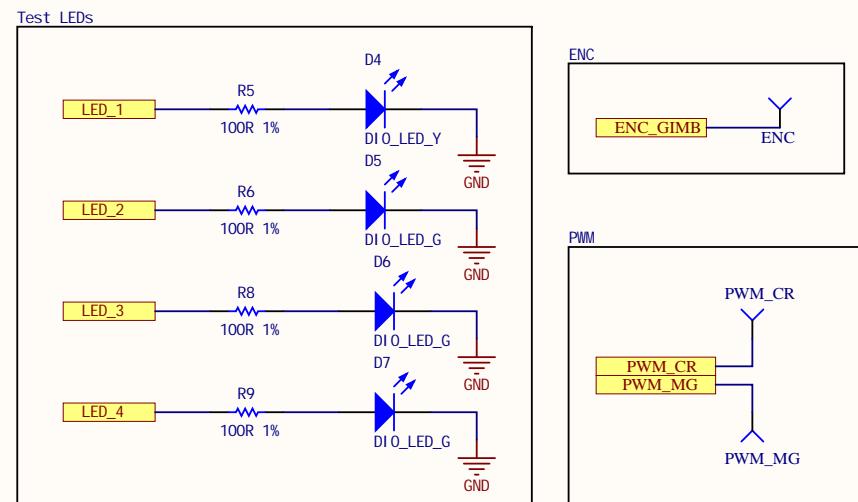
Drawn By: Aidan Gratton

Sheet 13 of 5

UW Robotics
200 University Avenue
Waterloo
Ontario
Canada N2L 3G6

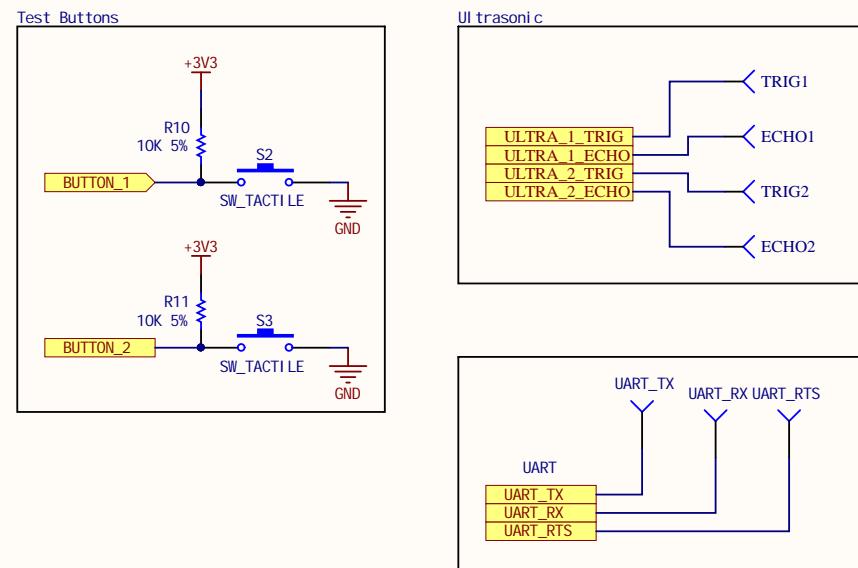
 ROBOTICS
TEAM

A



B

A



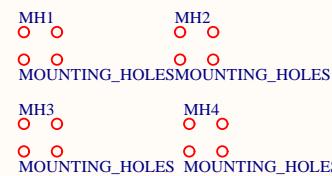
C

B

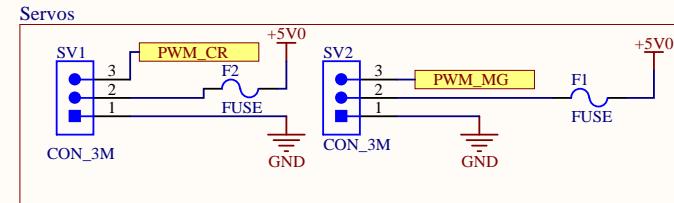
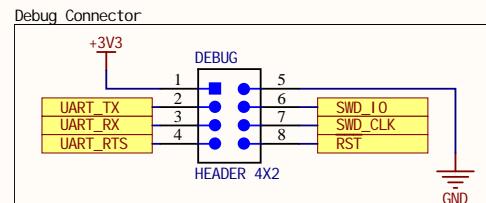
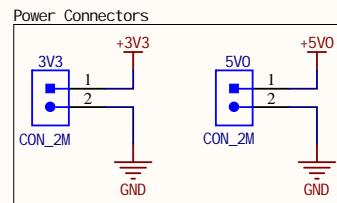
D

C

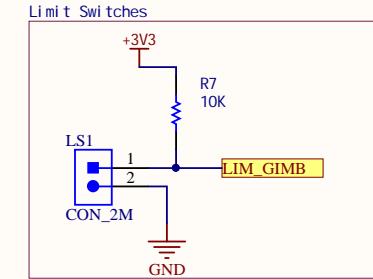
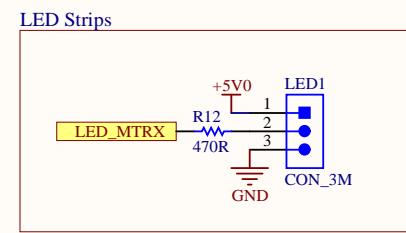
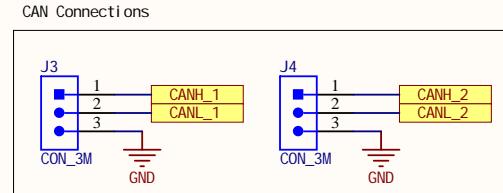
D



A



B



C

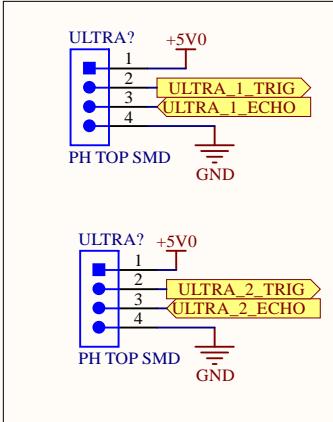
D

Title Gimbal Connecters Schematic	
Size: Letter	Drawn By: Jing Hao Yao & Aidan Gratton
Date: 2019-12-19	Sheet 15 of 5
File: C:\Users\gratt\Documents\University Teams\UW Mars Rover\2020 Electrical Repo\MarsRover2020-PCB\Projects\	

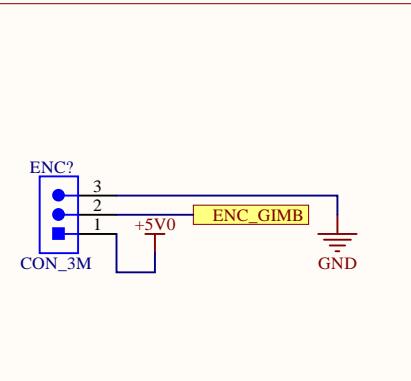
UW Robotics
200 University Avenue
Waterloo
Ontario
Canada N2L 3G6



A



B



C

Title

Size
A4

Number

Revision

Date: 2019-12-19
File: C:\Users\...\Sensors.SchDocSheet of
Drawn By: