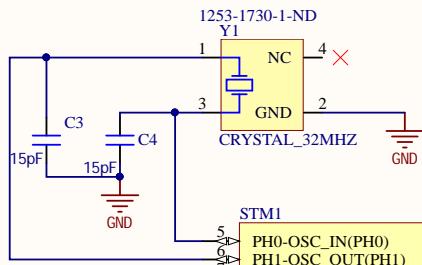


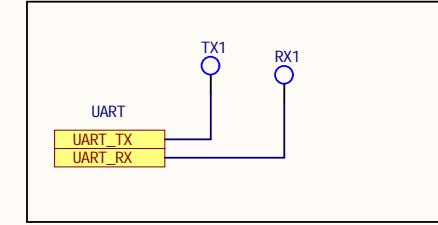
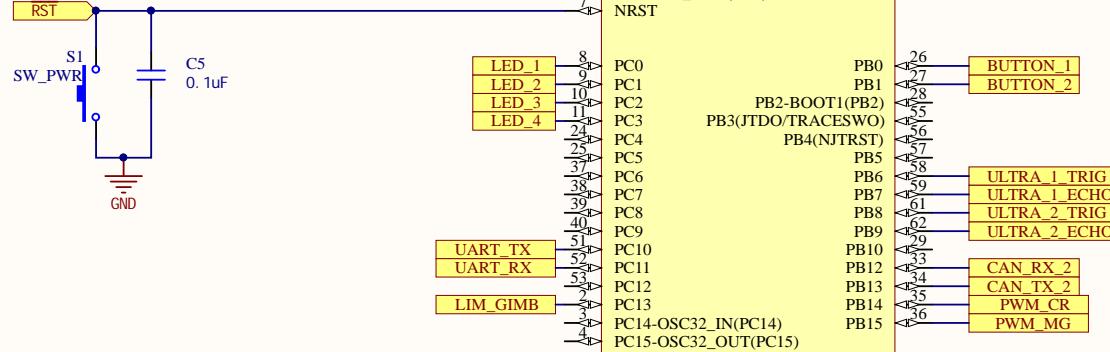
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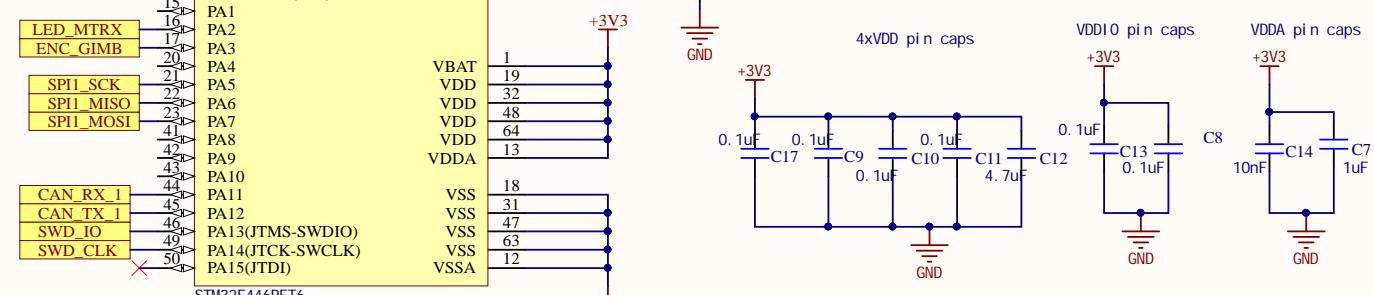
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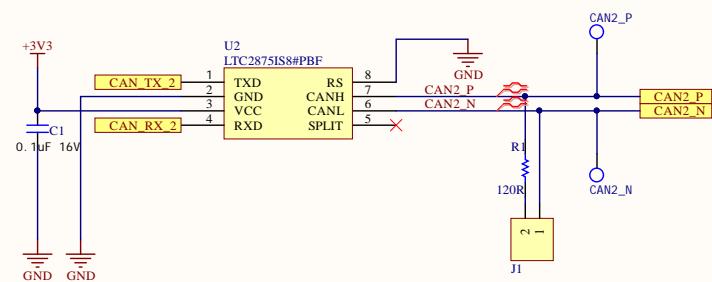
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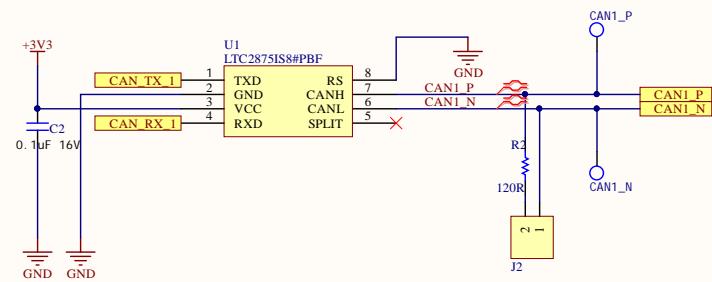
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Title Gimbal CAN Schematic		UW Robotics 200 University Avenue Waterloo Ontario Canada N2L 3G8
Size: Letter	Drawn By: Jing Hao Yao & Aidan Grattan	UW ROBOTICS TEAM
Date: 2020-01-12	Sheet 1 of 5	File: C:\Users\gratt\Documents\University\Design Teams\UW Mars Rover\2020 Electrical Repo\MarsRover2020-PCB\Projects\Gimbal\Rev1\sch\CAN_SchDoc

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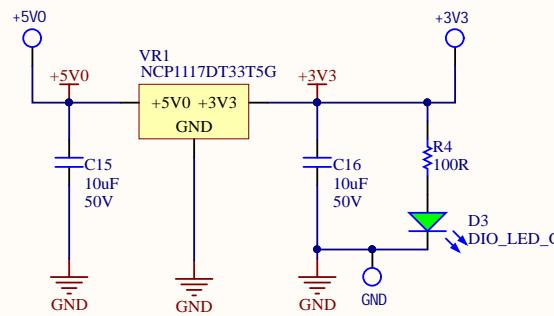
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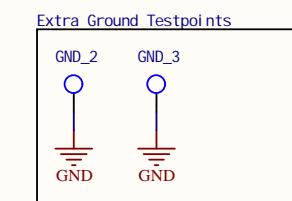
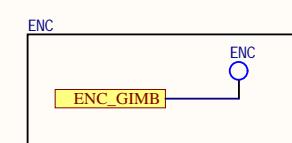
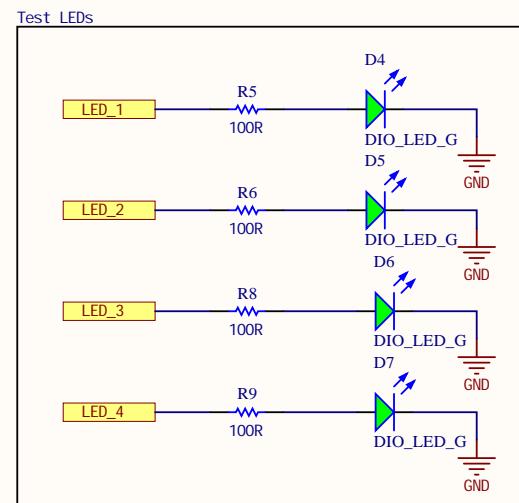
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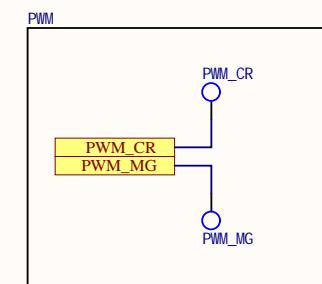
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200 University Avenue
Waterloo
Ontario
Canada N2L 3G6*



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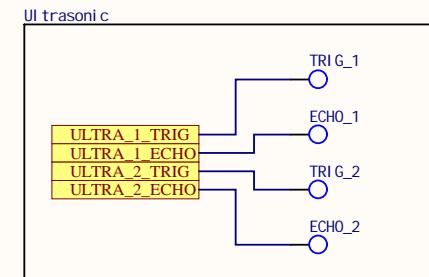
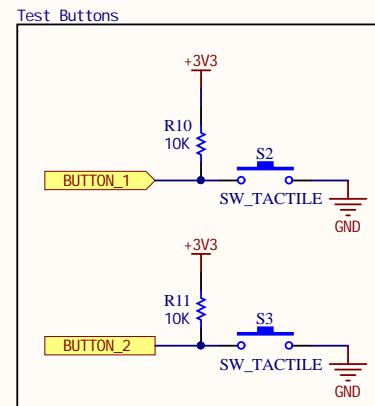


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Title Gimbal Support Schematic

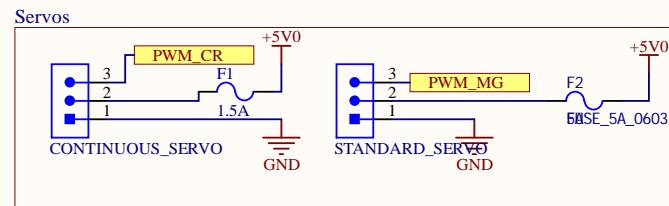
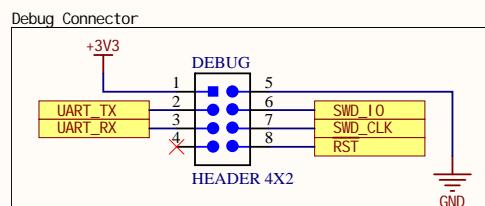
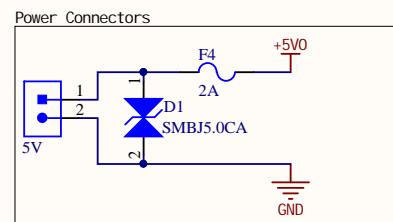
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Date: 2020-01-12 Sheet 4 of 5

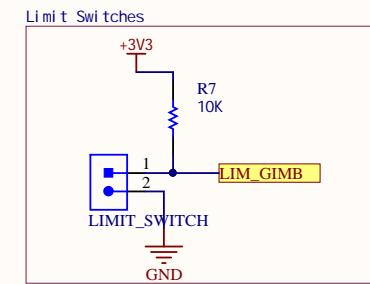
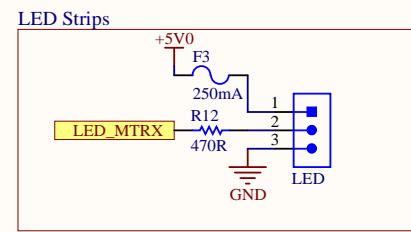
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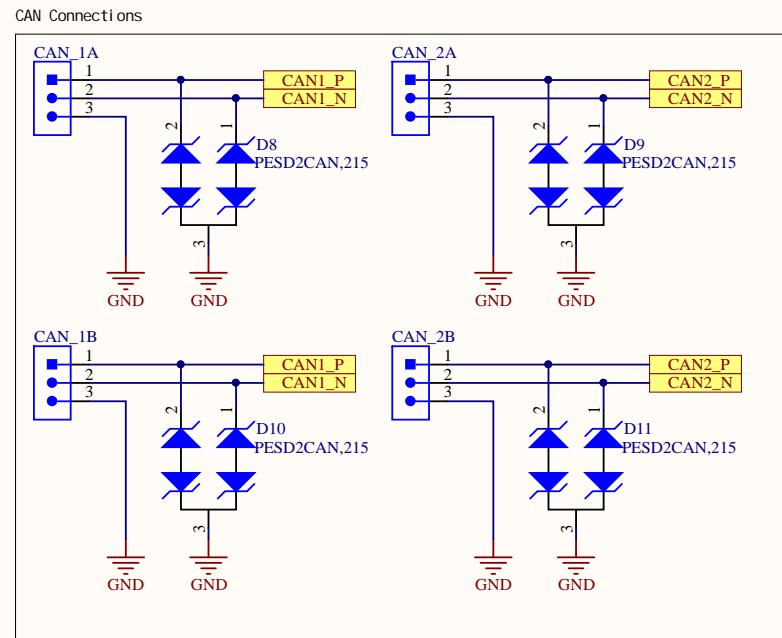
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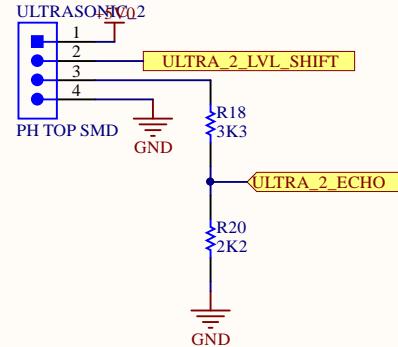
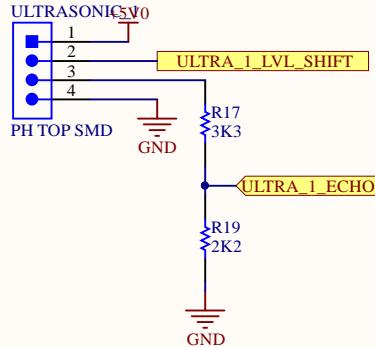


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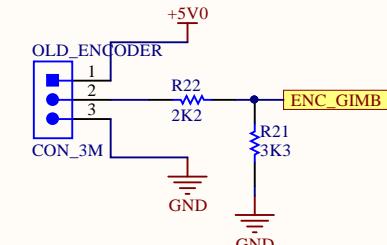


Title	Gimbal Connectors Schematic	UW Robotics 200 University Avenue Waterloo Ontario Canada N2L 3G6
Size:	Letter	Drawn By: Jing Hao Yao & Aidan Grattan
Date:	2020-01-12	Sheet 15 of 5
File:	C:\Users\gratt\Documents\University\Design Teams\UW Mars Rover\2020 Electrical Repo\MarsRover2020-PCB\Projects\	TEAM

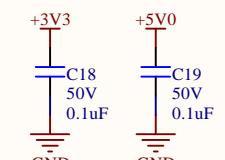
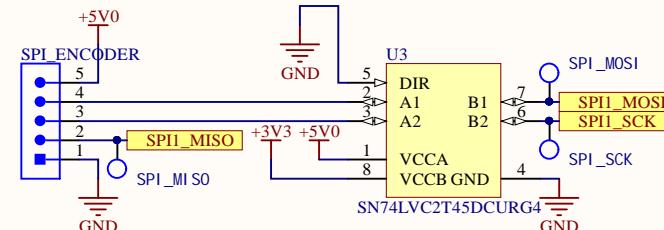
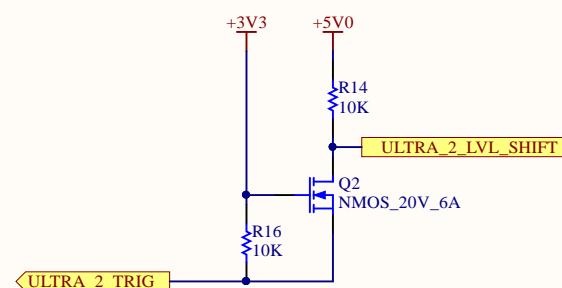
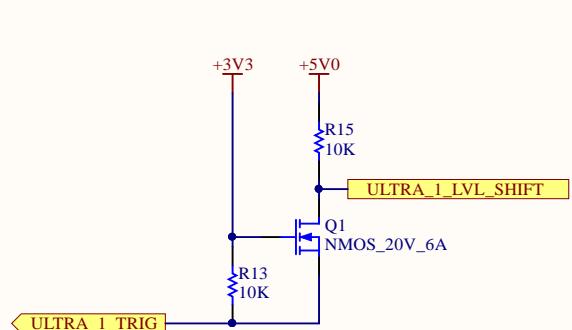
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