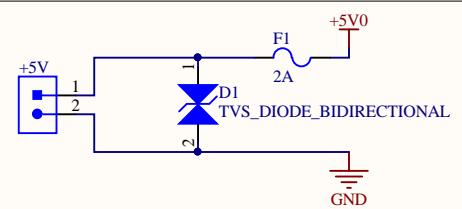
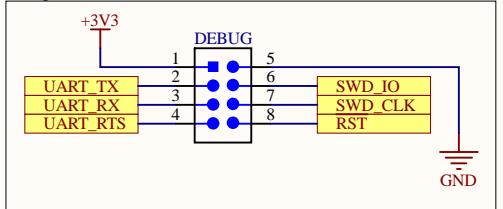


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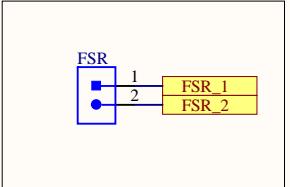
Power Connector



Debug Connector



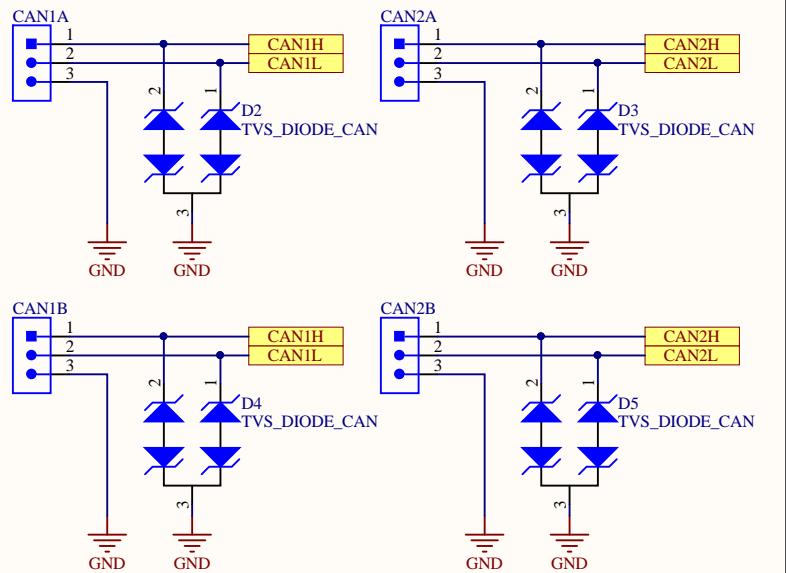
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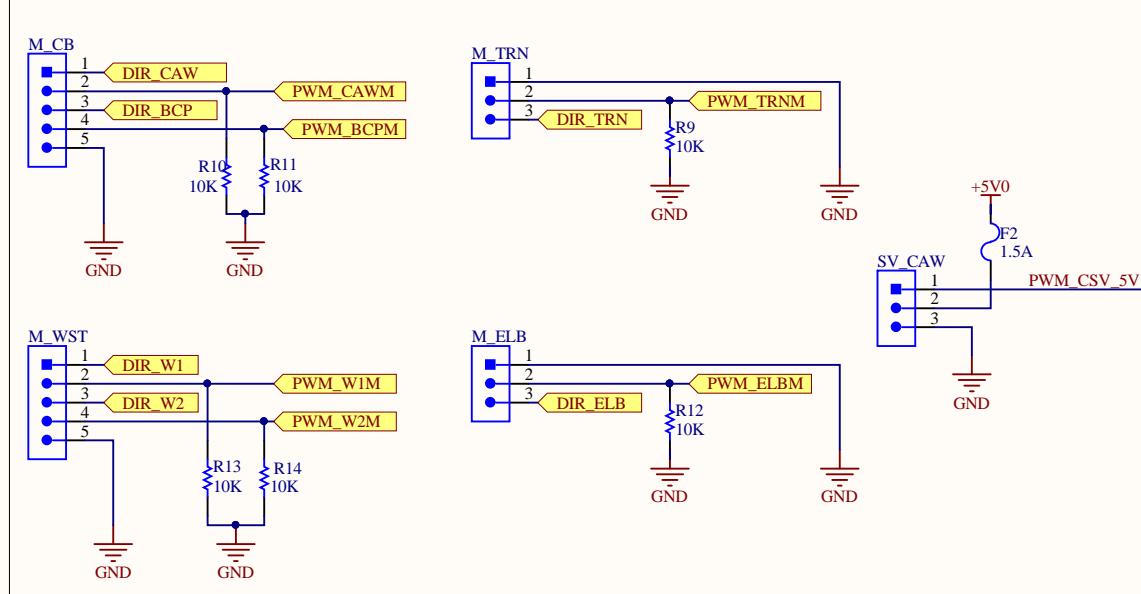
Acronyms Explained

FSR: Force Sensitive Resistor
 CAW: Claw
 WST: Wrist
 BCP: Bicep (Shoulder)
 ELB: Elbow
 TRN: Turntable
 DIR: Direction for motors

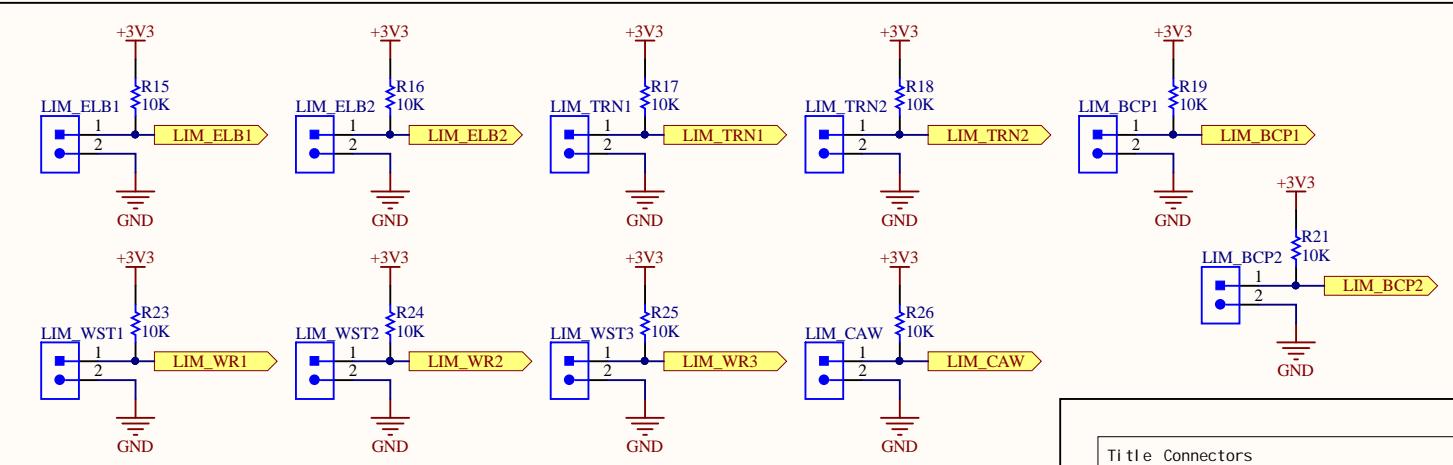
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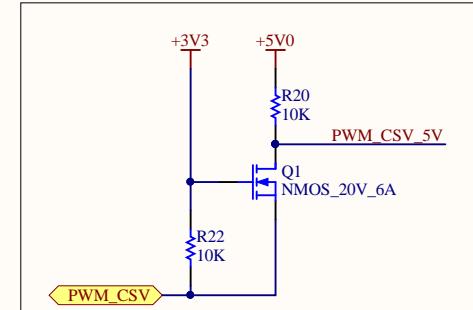
Motors



Limit Switches



Servo Level Shifter

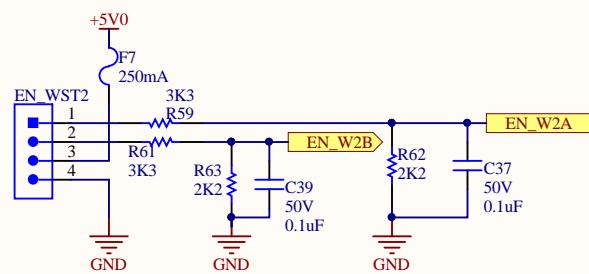
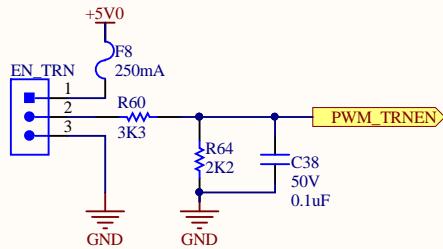
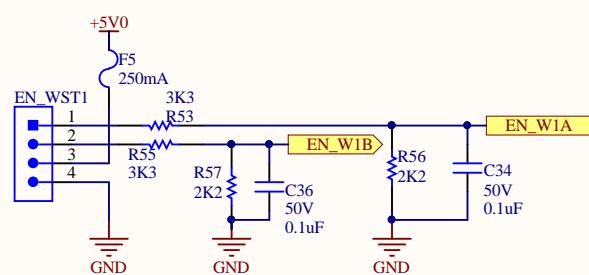
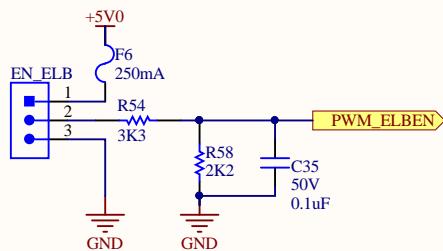
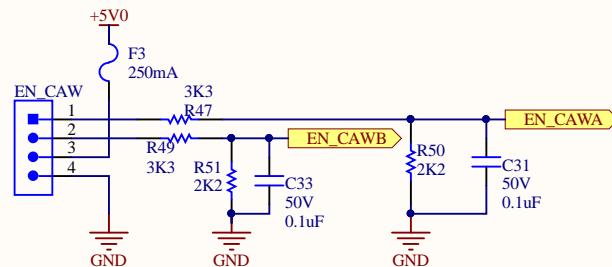
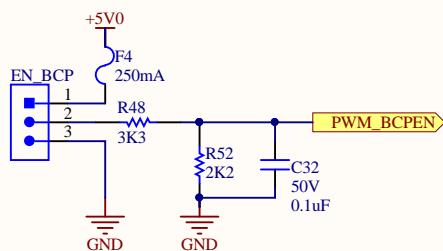


Title Connectors

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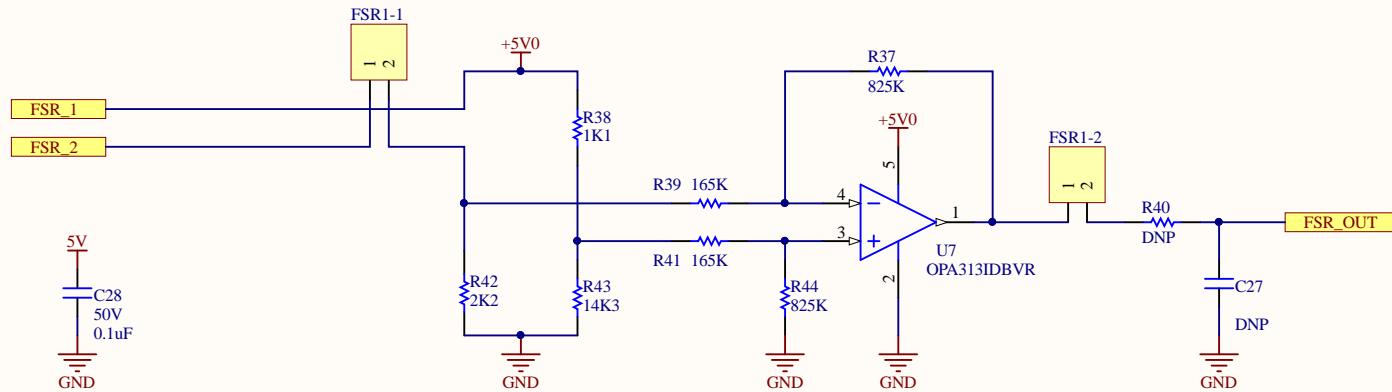


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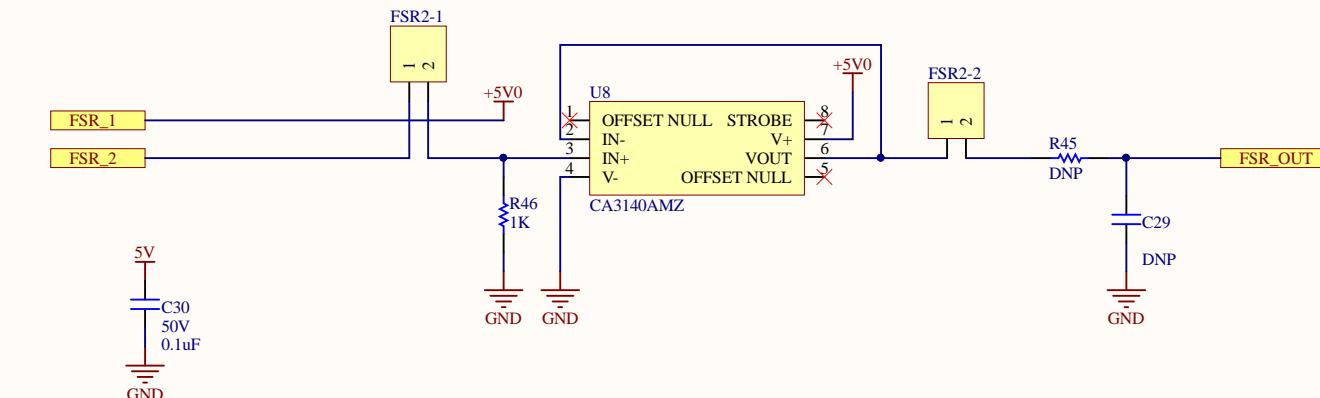
Links to calculations and documentation

<https://docs.google.com/document/d/1rw19DyF2suYmOmllnorCrfqnUpDln50-sqe5KjQKnCs/edit>

<https://docs.google.com/spreadsheets/d/1JzRwpCH-aMdlyAMP5zl6xFD8GIuJzvmOR8Y5Kzd1RN0/edit#gid=0>



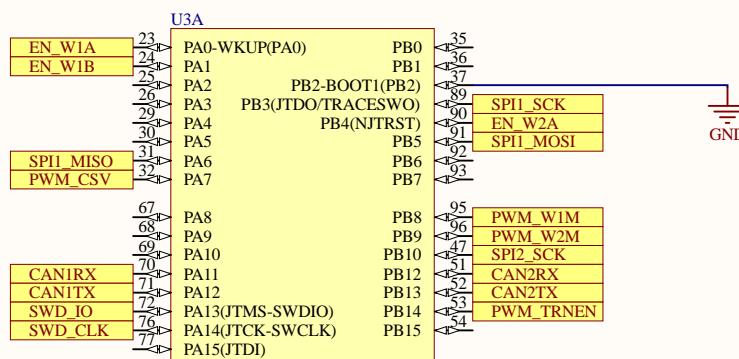
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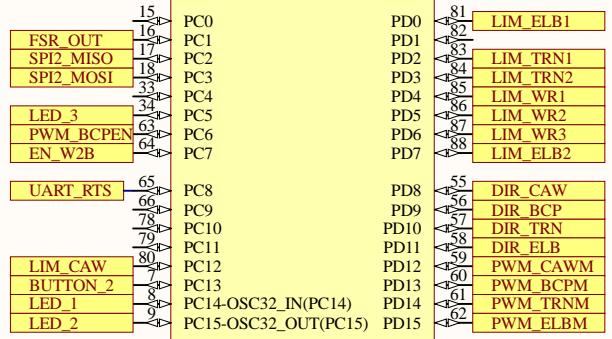
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Title Claw Force Sensor		UW Robotics 200 University Avenue Waterloo Ontario Canada N2L 3G6
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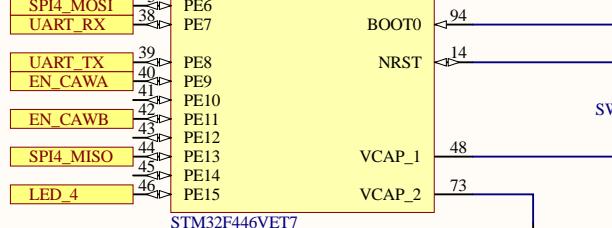
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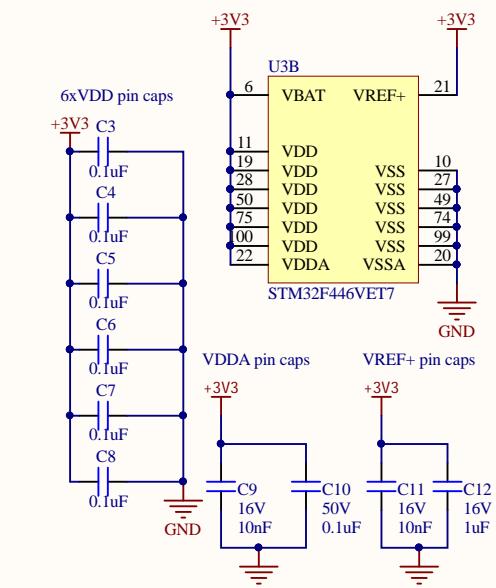
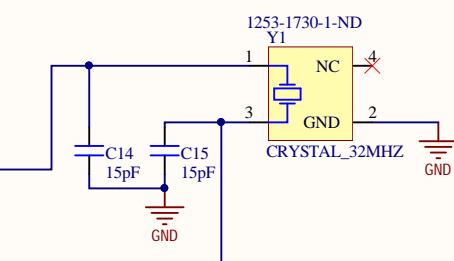
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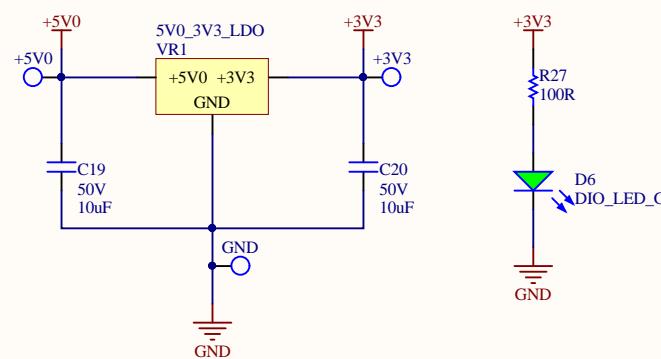


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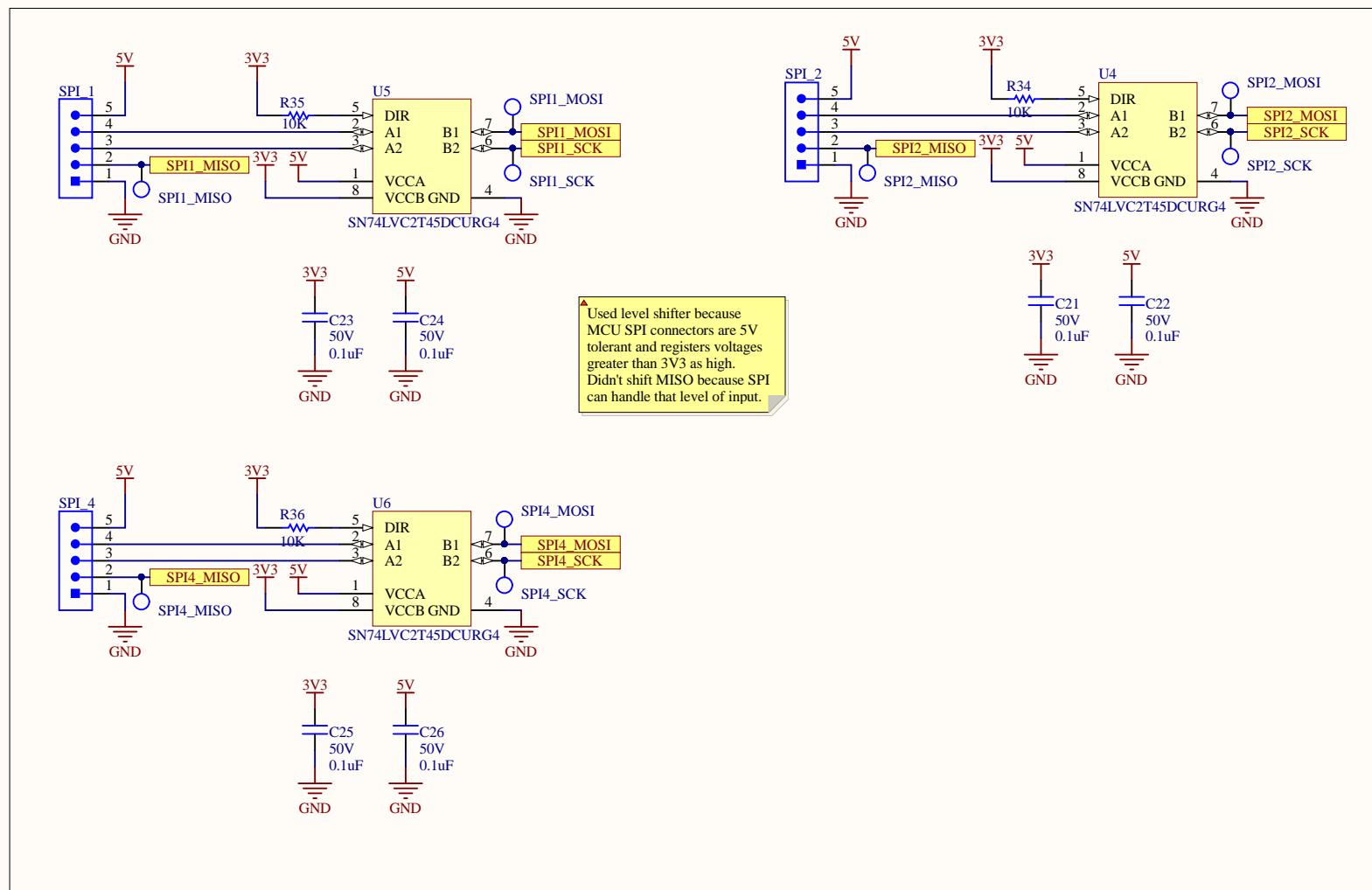


Title Power		UW Robotics 200 University Avenue Waterloo Ontario Canada N2L 3G6	UW ROBOTICS TEAM
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SPI Connectors



Title SPI Connectors

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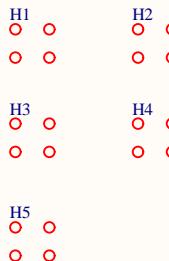
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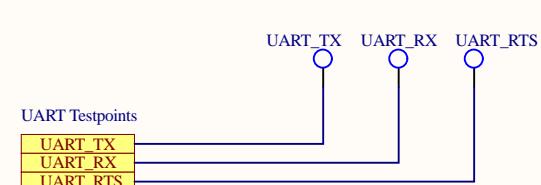
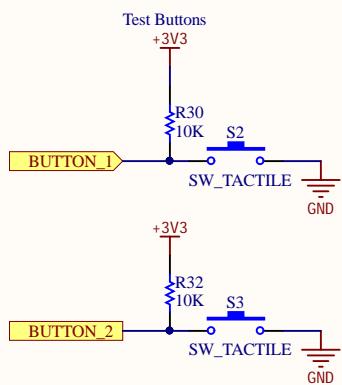
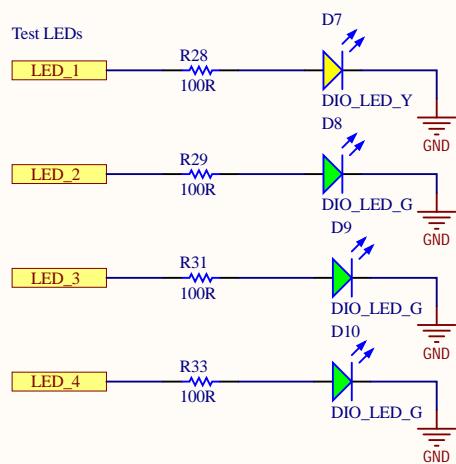
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Title Support

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