## Triangles

1.0.1

Generated by Doxygen 1.8.17

1 Namespace Index	1
1.1 Namespace List	. 1
2 Class Index	3
2.1 Class List	. 3
3 File Index	5
3.1 File List	. 5
4 Namespace Documentation	7
4.1 geom Namespace Reference	. 7
4.1.1 Detailed Description	. 8
4.1.2 Typedef Documentation	
4.1.2.1 VectorD	. 9
4.1.2.2 VectorF	. 9
4.1.3 Function Documentation	. 9
<b>4.1.3.1</b> operator<<() [1/4]	. 9
4.1.3.2 operator==() [1/3]	. 10
4.1.3.3 operator==() [2/3]	. 10
4.1.3.4 operator<<() [2/4]	. 11
<b>4.1.3.5</b> operator<<() [3/4]	. 11
4.1.3.6 operator+()	. 12
4.1.3.7 operator-()	. 12
4.1.3.8 operator*() [1/2]	. 13
4.1.3.9 operator*() [2/2]	. 13
4.1.3.10 operator/()	. 15
4.1.3.11 operator&()	. 15
4.1.3.12 operator%()	. 16
4.1.3.13 operator==() [3/3]	. 17
4.1.3.14 operator"!=()	. 17
4.1.3.15 operator<<() [4/4]	. 18
4.1.4 Variable Documentation	. 18
4.1.4.1 Number	. 18
5 Class Documentation	21
5.1 geom::Line< T > Class Template Reference	. 21
5.1.1 Detailed Description	. 21
5.1.2 Constructor & Destructor Documentation	. 22
5.1.2.1 Line()	. 22
5.1.3 Member Function Documentation	. 22
5.1.3.1 org()	. 22
5.1.3.2 dir()	. 23
5.1.3.3 belongs()	. 23
5.1.3.4 isEqual()	. 23

5.1.3.5 getBy2Points()	. 24
$5.2 \; geom:: Plane < T > Class \; Template \; Reference \; \ldots \; $	. 24
5.2.1 Detailed Description	. 25
5.2.2 Member Function Documentation	. 25
5.2.2.1 dist()	. 25
5.2.2.2 norm()	. 26
<b>5.2.2.3 belongs()</b> [1/2]	. 26
<b>5.2.2.4 belongs()</b> [2/2]	. 26
5.2.2.5 isEqual()	. 27
5.2.2.6 getBy3Points()	. 27
5.2.2.7 getParametric()	. 28
5.2.2.8 getNormalPoint()	. 28
5.2.2.9 getNormalDist()	. 29
$\textbf{5.3 geom::} \textbf{Triangle} < \textbf{T} > \textbf{Class Template Reference} \ . \ . \ . \ . \ . \ . \ . \ . \ . \ $	. 29
5.3.1 Detailed Description	. 29
5.3.2 Constructor & Destructor Documentation	. 30
5.3.2.1 Triangle()	. 30
5.3.3 Member Function Documentation	. 30
5.3.3.1 operator[]()	. 30
$\textbf{5.4 geom::} \textbf{Vector} < \textbf{T} > \textbf{Class Template Reference} \; . \; . \; . \; . \; . \; . \; . \; . \; . \; $	. 31
5.4.1 Detailed Description	. 32
5.4.2 Constructor & Destructor Documentation	. 32
5.4.2.1 Vector() [1/2]	. 33
<b>5.4.2.2 Vector()</b> [2/2]	. 33
5.4.3 Member Function Documentation	. 33
5.4.3.1 operator+=()	. 33
5.4.3.2 operator-=()	. 34
5.4.3.3 operator-()	. 34
5.4.3.4 operator*=() [1/2]	. 34
5.4.3.5 operator/=() [1/2]	. 35
5.4.3.6 dot()	. 35
5.4.3.7 cross()	. 36
5.4.3.8 length2()	. 36
5.4.3.9 length()	. 37
5.4.3.10 normalized()	. 37
5.4.3.11 normalize()	. 37
5.4.3.12 operator[]() [1/2]	. 37
<b>5.4.3.13 operator[]()</b> [2/2]	. 38
5.4.3.14 isPar()	. 38
5.4.3.15 isPerp()	. 39
5.4.3.16 isEqual()	. 39
5.4.3.17 isNumEq()	. 40

5.4.3.18 setThreshold()	4	40
5.4.3.19 getThreshold()	4	41
5.4.3.20 setDefThreshold()	4	41
5.4.3.21 operator*=() [2/2]	4	41
<b>5.4.3.22</b> operator/=() [2/2]	4	41
5.4.4 Member Data Documentation	4	42
5.4.4.1 x	4	42
5.4.4.2 y	4	42
5.4.4.3 z	4	42
		40
6 File Documentation		43
6.1 include/primitives/line.hh File Reference	4	43
6.2 line.hh	4	44
6.3 include/primitives/plane.hh File Reference	4	46
6.4 plane.hh	4	47
6.5 include/primitives/triangle.hh File Reference	4	49
6.6 triangle.hh		50
6.7 include/primitives/vector.hh File Reference		51
6.7.1 Detailed Description		53
6.8 vector.hh		54
6.9 lib/primitives/line.cc File Reference	6	60
6.10 line.cc	6	60
6.11 lib/primitives/plane.cc File Reference	6	60
6.12 plane.cc	6	60
6.13 lib/primitives/triangle.cc File Reference	6	60
6.14 triangle.cc	6	60
6.15 lib/primitives/vector.cc File Reference	6	60
6.16 vector.cc	6	61

# **Chapter 1**

# Namespace Index

1.1 Namespace	List
---------------	------

Here is a list	t of all namespaces with brief descriptions:	
geom		
_	Line.hh Line class implementation	7

2 Namespace Index

# Chapter 2

# **Class Index**

## 2.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

geom::Line< T >	
Line class implementation	21
geom::Plane< T >	
Plane class realization	24
geom::Triangle< T >	
Triangle class implementation	29
geom::Vector< T >	
Vector class realization	31

4 Class Index

# **Chapter 3**

# File Index

## 3.1 File List

Here is a list of all files with brief descriptions:

nclude/primitives/line.hh	13
nclude/primitives/plane.hh	16
nclude/primitives/triangle.hh	19
nclude/primitives/vector.hh	51
ib/primitives/line.cc	30
ib/primitives/plane.cc	30
ib/primitives/triangle.cc	30
ib/primitives/vector.cc	30

6 File Index

## **Chapter 4**

## **Namespace Documentation**

## 4.1 geom Namespace Reference

line.hh Line class implementation

## **Classes**

· class Line

Line class implementation.

class Plane

Plane class realization.

· class Triangle

Triangle class implementation.

class Vector

Vector class realization.

## **Typedefs**

```
• using VectorD = Vector< double >
```

```
using VectorF = Vector< float >
```

#### **Functions**

```
    template<std::floating_point T> std::ostream & operator<< (std::ostream & const Line< T > &line)
        Line print operator.
    template<std::floating_point T> bool operator== (const Line< T > &lhs, const Line< T > &rhs)
        Line equality operator.
    template<std::floating_point T> bool operator== (const Plane< T > &lhs, const Plane< T > &rhs)
        Plane equality operator.
    template<std::floating_point T> std::ostream & operator<< (std::ostream & const Plane< T > &pl
```

```
Plane print operator.
• template<std::floating_point T>
  std::ostream & operator<< (std::ostream &ost, const Triangle< T > &tr)
      Triangle print operator.
• template<std::floating_point T>
  Vector< T > operator+ (const Vector< T > &lhs, const Vector< T > &rhs)
      Overloaded + operator.

    template<std::floating_point T>

  Vector< T > operator- (const Vector< T > &lhs, const Vector< T > &rhs)
      Overloaded - operator.
• template<Number nT, std::floating_point T>
  Vector < T > operator* (const nT &val, const Vector < T > &rhs)
      Overloaded multiple by value operator.
• template<Number nT, std::floating_point T>
  Vector< T > operator* (const Vector< T > &lhs, const nT &val)
      Overloaded multiple by value operator.
• template<Number nT, std::floating_point T>
  Vector< T > operator/ (const Vector< T > &lhs, const nT &val)
      Overloaded divide by value operator.

    template<std::floating_point T>

  T operator& (const Vector< T > &lhs, const Vector< T > &rhs)
      Dot product operator.

    template<std::floating_point T>

  Vector< T > operator% (const Vector< T > &lhs, const Vector< T > &rhs)
      Cross product operator.
• template<std::floating_point T>
  bool operator== (const Vector < T > &lhs, const Vector < T > &rhs)
      Vector equality operator.

    template<std::floating_point T>

  bool operator!= (const Vector< T > &lhs, const Vector< T > &rhs)
      Vector inequality operator.

    template<std::floating_point T>

  std::ostream & operator<< (std::ostream &ost, const Vector< T > &vec)
      Vector print operator.
```

### **Variables**

template < class T >
 concept Number = std::is\_floating\_point\_v < T > || std::is\_integral\_v < T >
 Useful concept which represents floating point and integral types.

## 4.1.1 Detailed Description

line.hh Line class implementation

triangle.hh Triangle class implementation

Plane class implementation.

## 4.1.2 Typedef Documentation

#### 4.1.2.1 VectorD

```
using geom::VectorD = typedef Vector<double>
```

Definition at line 393 of file vector.hh.

## 4.1.2.2 VectorF

```
using geom::VectorF = typedef Vector<float>
```

Definition at line 394 of file vector.hh.

## 4.1.3 Function Documentation

## 4.1.3.1 operator<<() [1/4]

Line print operator.

## **Template Parameters**

```
T - floating point type of coordinates
```

## **Parameters**

in,out	ost	output stream
in	line	Line to print

#### Returns

std::ostream& modified ostream instance

Definition at line 89 of file line.hh.

References geom::Line< T >::dir(), and geom::Line< T >::org().

## 4.1.3.2 operator==() [1/3]

Line equality operator.

## **Template Parameters**

T	- floating point type of coordinates
---	--------------------------------------

## **Parameters**

in	lhs	1st line
in	rhs	2nd line

#### Returns

true if lines are equal false if lines are not equal

Definition at line 105 of file line.hh.

References geom::Line< T >::isEqual().

## 4.1.3.3 operator==() [2/3]

Plane equality operator.

## **Template Parameters**

in	lhs	1st plane	
in	rhs	2nd plane	

#### Returns

true if planes are equal false if planes are not equal

Definition at line 138 of file plane.hh.

References geom::Plane< T >::isEqual().

### 4.1.3.4 operator << () [2/4]

Plane print operator.

#### **Template Parameters**

T	- floating point type of coordinates
---	--------------------------------------

## **Parameters**

in,out	ost	output stream	
in	pl	plane to print	

#### Returns

std::ostream& modified ostream instance

Definition at line 152 of file plane.hh.

References geom::Plane< T >::dist(), and geom::Plane< T >::norm().

## 4.1.3.5 operator << () [3/4]

Triangle print operator.

## **Template Parameters**

T	- floating point type of coordinates
---	--------------------------------------

#### **Parameters**

in,out	ost	output stream
in	tr	Triangle to print

## Returns

std::ostream& modified ostream instance

Definition at line 60 of file triangle.hh.

## 4.1.3.6 operator+()

Overloaded + operator.

## **Template Parameters**

Τ	vector template parameter

## **Parameters**

in	lhs	first vector
in	rhs	second vector

## Returns

Vector<T> sum of two vectors

Definition at line 246 of file vector.hh.

## 4.1.3.7 operator-()

Overloaded - operator.

## **Template Parameters**

T	vector template parameter
---	---------------------------

#### **Parameters**

in	lhs	first vector
in <i>rhs</i>		second vector

## Returns

Vector<T> res of two vectors

Definition at line 262 of file vector.hh.

## 4.1.3.8 operator\*() [1/2]

Overloaded multiple by value operator.

## **Template Parameters**

nΤ	type of value to multiply by
T	vector template parameter

#### **Parameters**

ir	n .	val	value to multiply by
ir	1	rhs	vector to multiply by value

## Returns

Vector<T> result vector

Definition at line 279 of file vector.hh.

## 4.1.3.9 operator\*() [2/2]

```
template<Number nT, std::floating_point T>
Vector<T> geom::operator* (
```

```
const Vector< T > & lhs, const nT & val )
```

Overloaded multiple by value operator.

## **Template Parameters**

nT	type of value to multiply by
T	vector template parameter

#### **Parameters**

in	val	value to multiply by	
in	lhs	vector to multiply by value	

## Returns

Vector<T> result vector

Definition at line 296 of file vector.hh.

## 4.1.3.10 operator/()

Overloaded divide by value operator.

## **Template Parameters**

nT	type of value to divide by		
T	vector template parameter		

## **Parameters**

in	val	value to divide by	
in	lhs	vector to divide by value	

## Returns

Vector<T> result vector

Definition at line 313 of file vector.hh.

## 4.1.3.11 operator&()

```
template<std::floating_point T>
T geom::operator& (
```

```
const Vector< T > & lhs, const Vector< T > & rhs)
```

Dot product operator.

**Template Parameters** 

```
T vector template parameter
```

#### **Parameters**

in	lhs	first vector
in	rhs	second vector

#### Returns

T dot production

Definition at line 329 of file vector.hh.

References geom::Vector< T >::dot().

## 4.1.3.12 operator%()

Cross product operator.

## **Template Parameters**

T	vector template parameter

#### **Parameters**

in	lhs	first vector
in	rhs	second vector

## Returns

T cross production

Definition at line 343 of file vector.hh.

References geom::Vector< T >::cross().

## 4.1.3.13 operator==() [3/3]

Vector equality operator.

## **Template Parameters**

Τ	vector template parameter
---	---------------------------

## **Parameters**

in	lhs	first vector
in	rhs	second vector

#### Returns

true if vectors are equal false otherwise

Definition at line 358 of file vector.hh.

References geom::Vector< T >::isEqual().

## 4.1.3.14 operator"!=()

Vector inequality operator.

## **Template Parameters**

T	vector template parameter

-	in	lhs	first vector
-	in	rhs	second vector

#### Returns

true if vectors are not equal false otherwise

Definition at line 373 of file vector.hh.

## 4.1.3.15 operator << () [4/4]

Vector print operator.

## **Template Parameters**

Т	vector template parameter
---	---------------------------

#### **Parameters**

in,out	ost	output stream
in	vec	vector to print

#### Returns

std::ostream& modified stream instance

Definition at line 387 of file vector.hh.

 $References\ geom:: Vector < T > ::x,\ geom:: Vector < T > ::y,\ and\ geom:: Vector < T > ::z.$ 

## 4.1.4 Variable Documentation

## 4.1.4.1 Number

```
template<class T >
concept geom::Number = std::is_floating_point_v<T> || std::is_integral_v<T>
```

Useful concept which represents floating point and integral types.

@concept Number

Template Parameters				
T	]			

Definition at line 25 of file vector.hh.

## **Chapter 5**

## **Class Documentation**

## 5.1 geom::Line < T > Class Template Reference

Line class implementation.

```
#include <line.hh>
```

## **Public Member Functions**

- Line (const Vector< T > &org, const Vector< T > &dir)
  - Construct a new Line object.
- const Vector< T > & org () const
  - Getter for origin vector.
- const Vector< T > & dir () const
  - Getter for direction vector.
- bool belongs (const Vector < T > &point) const
  - Checks is point belongs to line.
- bool isEqual (const Line &line) const
  - Checks is \*this equals to another line.

## **Static Public Member Functions**

static Line getBy2Points (const Vector< T > &p1, const Vector< T > &p2)
 Get line by 2 points.

## 5.1.1 Detailed Description

template < std::floating\_point T> class geom::Line < T>

Line class implementation.

22 Class Documentation

## **Template Parameters**

Τ	- floating point type of coordinates
1	- noaling point type of coordinates

Definition at line 21 of file line.hh.

## 5.1.2 Constructor & Destructor Documentation

#### 5.1.2.1 Line()

Construct a new Line object.

#### **Parameters**

in	org	origin vector
in	dir	direction vector

Definition at line 111 of file line.hh.

References geom::Line< T >::org().

## 5.1.3 Member Function Documentation

## 5.1.3.1 org()

```
template<std::floating_point T>
const Vector< T > & geom::Line< T >::org
```

Getter for origin vector.

## Returns

const Vector<T>& const reference to origin vector

Definition at line 118 of file line.hh.

 $Referenced \ by \ geom::Plane< T>::belongs(), \ geom::Line< T>::Line(), \ and \ geom::operator<<().$ 

#### 5.1.3.2 dir()

```
template<std::floating_point T>
const Vector< T > & geom::Line< T >::dir
```

Getter for direction vector.

#### Returns

const Vector<T>& const reference to direction vector

Definition at line 124 of file line.hh.

Referenced by geom::Plane< T >::belongs(), and geom::operator<<().

#### 5.1.3.3 belongs()

Checks is point belongs to line.

#### **Parameters**

in	point	const reference to point vector
----	-------	---------------------------------

#### Returns

true if point belongs to line false if point doesn't belong to line

Definition at line 130 of file line.hh.

## 5.1.3.4 isEqual()

Checks is \*this equals to another line.

in	line	const reference to another line
----	------	---------------------------------

24 Class Documentation

#### Returns

true if lines are equal false if lines are not equal

Definition at line 136 of file line.hh.

Referenced by geom::operator==().

### 5.1.3.5 getBy2Points()

Get line by 2 points.

#### **Parameters**

in	p1	1st point
in	p2	2nd point

#### Returns

Line passing through two points

Definition at line 142 of file line.hh.

The documentation for this class was generated from the following file:

• include/primitives/line.hh

## 5.2 geom::Plane < T > Class Template Reference

Plane class realization.

```
#include <plane.hh>
```

## **Public Member Functions**

• T dist () const

Getter for distance.

const Vector< T > & norm () const

Getter for normal vector.

bool belongs (const Vector < T > &point) const

Checks if point belongs to plane.

bool belongs (const Line < T > &line) const

Checks if line belongs to plane.

• bool isEqual (const Plane &rhs) const

Checks is \*this equals to another plane.

## **Static Public Member Functions**

- static Plane getBy3Points (const Vector< T > &pt1, const Vector< T > &pt2, const Vector< T > &pt3)
   Get plane by 3 points.
- static Plane getParametric (const Vector< T > &org, const Vector< T > &dir1, const Vector< T > &dir2)
   Get plane from parametric plane equation.
- static Plane getNormalPoint (const Vector< T > &norm, const Vector< T > &point)
   Get plane from normal point plane equation.
- static Plane getNormalDist (const Vector< T > &norm, T constant)

Get plane form normal const plane equation.

## 5.2.1 Detailed Description

```
template<std::floating_point T> class geom::Plane< T>
```

Plane class realization.

**Template Parameters** 

```
T - floating point type of coordinates
```

Definition at line 24 of file plane.hh.

## 5.2.2 Member Function Documentation

## 5.2.2.1 dist()

```
template<std::floating_point T>
T geom::Plane< T >::dist
```

Getter for distance.

Returns

T value of distance

Definition at line 166 of file plane.hh.

Referenced by geom::operator<<().

26 Class Documentation

## 5.2.2.2 norm()

```
template<std::floating_point T>
const Vector< T > & geom::Plane< T >::norm
```

Getter for normal vector.

#### Returns

const Vector<T>& const reference to normal vector

Definition at line 172 of file plane.hh.

Referenced by geom::operator<<().

## 5.2.2.3 belongs() [1/2]

Checks if point belongs to plane.

#### **Parameters**

in	point	const referene to point vector
----	-------	--------------------------------

#### Returns

true if point belongs to plane false if point doesn't belong to plane

Definition at line 178 of file plane.hh.

## 5.2.2.4 belongs() [2/2]

Checks if line belongs to plane.

in	line	const referene to line

#### Returns

true if line belongs to plane false if line doesn't belong to plane

Definition at line 184 of file plane.hh.

References geom::Line< T >::dir(), and geom::Line< T >::org().

### 5.2.2.5 isEqual()

```
template<std::floating_point T> bool geom::Plane< T >::isEqual ( const\ Plane<\ T\ >\ \&\ rhs\ )\ const
```

Checks is \*this equals to another plane.

#### **Parameters**

in	rhs	const reference to another plane
----	-----	----------------------------------

#### Returns

true if planes are equal false if planes are not equal

Definition at line 190 of file plane.hh.

Referenced by geom::operator==().

## 5.2.2.6 getBy3Points()

Get plane by 3 points.

in	pt1	1st point
in	pt2	2nd point
in	pt3	3rd point

28 Class Documentation

#### Returns

Plane passing through three points

Definition at line 196 of file plane.hh.

## 5.2.2.7 getParametric()

Get plane from parametric plane equation.

#### **Parameters**

in	org	origin vector
in	dir1	1st direction vector
in	dir2	2nd direction vector

#### Returns

**Plane** 

Definition at line 203 of file plane.hh.

References geom::Vector< T >::cross().

## 5.2.2.8 getNormalPoint()

Get plane from normal point plane equation.

in	norm	normal vector
in	point	point lying on the plane

#### Returns

**Plane** 

Definition at line 211 of file plane.hh.

References geom::Vector< T >::normalized().

## 5.2.2.9 getNormalDist()

Get plane form normal const plane equation.

#### **Parameters**

in	norm	normal vector
in	constant	distance

#### Returns

#### **Plane**

Definition at line 218 of file plane.hh.

References geom::Vector< T >::normalized().

The documentation for this class was generated from the following file:

• include/primitives/plane.hh

## 5.3 geom::Triangle < T > Class Template Reference

Triangle class implementation.

```
#include <triangle.hh>
```

## **Public Member Functions**

• Triangle (const Vector< T > &p1, const Vector< T > &p2, const Vector< T > &p3)

Construct a new Triangle object from 3 points.

const Vector< T > & operator[] (std::size\_t idx) const

Overloaded operator[] to get access to vertices.

## 5.3.1 Detailed Description

```
\label{template} \begin{tabular}{ll} template < std::floating\_point T > \\ class geom::Triangle < T > \\ \end{tabular}
```

Triangle class implementation.

30 Class Documentation

## **Template Parameters**

Т	- floating point type of coordinates

Definition at line 24 of file triangle.hh.

## 5.3.2 Constructor & Destructor Documentation

#### 5.3.2.1 Triangle()

```
template<std::floating_point T> geom::Triangle< T >::Triangle ( const Vector< T > & p1, const Vector< T > & p2, const Vector< T > & p3)
```

Construct a new Triangle object from 3 points.

#### **Parameters**

in	p1	1st point
in	p2	2nd point
in	рЗ	3rd point

Definition at line 72 of file triangle.hh.

## 5.3.3 Member Function Documentation

## 5.3.3.1 operator[]()

Overloaded operator[] to get access to vertices.

in   idx   index of vertex
----------------------------

Returns

const Vector<T>& const reference to vertex

Definition at line 78 of file triangle.hh.

The documentation for this class was generated from the following file:

• include/primitives/triangle.hh

## 5.4 geom::Vector < T > Class Template Reference

Vector class realization.

#include <vector.hh>

#### **Public Member Functions**

• Vector (T coordX, T coordY, T coordZ)

Construct a new Vector object from 3 coordinates.

Vector (T coordX={})

Construct a new Vector object with equals coordinates.

Vector & operator+= (const Vector &vec)

Overloaded += operator Increments vector coordinates by corresponding coordinates of vec.

Vector & operator-= (const Vector &vec)

Overloaded -= operator Decrements vector coordinates by corresponding coordinates of vec.

• Vector operator- () const

Unary - operator.

template<Number nType>

Vector & operator\*= (nType val)

Overloaded \*= by number operator.

template<Number nType>

Vector & operator/= (nType val)

Overloaded /= by number operator.

• T dot (const Vector &rhs) const

Dot product function.

Vector cross (const Vector &rhs) const

Cross product function.

• T length2 () const

Calculate squared length of a vector function.

• T length () const

Calculate length of a vector function.

· Vector normalized () const

Get normalized vector function.

Vector & normalize ()

Normalize vector function.

• T & operator[] (size ti)

Overloaded operator [] (non-const version) To get access to coordinates.

• T operator[] (size\_t i) const

32 Class Documentation

Overloaded operator [] (const version) To get access to coordinates.

• bool isPar (const Vector &rhs) const

Check if vector is parallel to another.

• bool isPerp (const Vector &rhs) const

Check if vector is perpendicular to another.

• bool isEqual (const Vector &rhs) const

Check if vector is equal to another.

• template<Number nType>

```
Vector< T > & operator∗= (nType val)
```

• template<Number nType>

Vector < T > & operator/= (nType val)

#### **Static Public Member Functions**

• static bool isNumEq (T lhs, T rhs)

Check equality (with threshold) of two floating point numbers function.

• static void setThreshold (T thres)

Set new threshold value.

• static void getThreshold ()

Get current threshold value.

static void setDefThreshold ()

Set threshold to default value.

#### **Public Attributes**

• T x {}

Vector coordinates.

- Ty{}
- T z {}

## 5.4.1 Detailed Description

```
\label{template} \begin{tabular}{ll} template < std::floating\_point T > \\ class geom::Vector < T > \\ \end{tabular}
```

Vector class realization.

**Template Parameters** 

```
T - floating point type of coordinates
```

Definition at line 34 of file vector.hh.

#### 5.4.2 Constructor & Destructor Documentation

### 5.4.2.1 Vector() [1/2]

Construct a new Vector object from 3 coordinates.

#### **Parameters**

in	coordX	x coordinate
in	coordY	y coordinate
in	coordZ	z coordinate

Definition at line 55 of file vector.hh.

#### 5.4.2.2 Vector() [2/2]

Construct a new Vector object with equals coordinates.

### **Parameters**

in	coordY	coordinate (default to {})
Т11	COUIUX	coordinate (default to {})

Definition at line 64 of file vector.hh.

#### **5.4.3 Member Function Documentation**

### 5.4.3.1 operator+=()

Overloaded += operator Increments vector coordinates by corresponding coordinates of vec.

### **Parameters**

in	vec	vector to incremented with

34 Class Documentation

#### Returns

Vector& reference to current instance

Definition at line 397 of file vector.hh.

References geom::Vector< T >::x, geom::Vector< T >::y, and geom::Vector< T >::z.

#### 5.4.3.2 operator-=()

Overloaded -= operator Decrements vector coordinates by corresponding coordinates of vec.

#### **Parameters**

in <i>vec</i> vec	tor to decremented with
-------------------	-------------------------

#### Returns

Vector& reference to current instance

Definition at line 407 of file vector.hh.

References geom::Vector< T>::x, geom::Vector< T>::y, and geom::Vector< T>::z.

#### 5.4.3.3 operator-()

```
template<std::floating_point T>
Vector< T > geom::Vector< T >::operator-
```

Unary - operator.

Returns

Vector negated Vector instance

Definition at line 417 of file vector.hh.

#### 5.4.3.4 operator\*=() [1/2]

Overloaded \*= by number operator.

## **Template Parameters**

пТуре	numeric type of value to multiply by
-------	--------------------------------------

#### **Parameters**

in   val   value to multiply by
---------------------------------

#### Returns

Vector& reference to vector instance

## 5.4.3.5 operator/=() [1/2]

Overloaded /= by number operator.

#### **Template Parameters**

nType	numeric type of value to divide by
-------	------------------------------------

#### **Parameters**

in	val	value to divide by

#### Returns

Vector& reference to vector instance

## Warning

Does not check if val equals 0

## 5.4.3.6 dot()

Dot product function.

36 Class Documentation

#### **Parameters**

rhs vector to dot product with

#### Returns

T dot product of two vectors

Definition at line 445 of file vector.hh.

References geom::Vector< T >::x, geom::Vector< T >::y, and geom::Vector< T >::z.

Referenced by geom::operator&().

### 5.4.3.7 cross()

Cross product function.

#### **Parameters**

```
rhs vector to cross product with
```

#### Returns

Vector cross product of two vectors

Definition at line 451 of file vector.hh.

References geom::Vector< T >::x, geom::Vector< T >::y, and geom::Vector< T >::z.

Referenced by geom::Plane < T >::getParametric(), and geom::operator%().

#### 5.4.3.8 length2()

```
template<std::floating_point T>
T geom::Vector< T >::length2
```

Calculate squared length of a vector function.

## Returns

T length<sup>^</sup>2

Definition at line 457 of file vector.hh.

#### 5.4.3.9 length()

```
template<std::floating_point T>
T geom::Vector< T >::length
```

Calculate length of a vector function.

Returns

T length

Definition at line 463 of file vector.hh.

#### 5.4.3.10 normalized()

```
template<std::floating_point T>
Vector< T > geom::Vector< T >::normalized
```

Get normalized vector function.

Returns

Vector normalized vector

Definition at line 469 of file vector.hh.

References geom::Vector< T >::normalize().

Referenced by geom::Plane< T >::getNormalDist(), and geom::Plane< T >::getNormalPoint().

#### 5.4.3.11 normalize()

```
template<std::floating_point T>
Vector< T > & geom::Vector< T >::normalize
```

Normalize vector function.

Returns

Vector& reference to instance

Definition at line 477 of file vector.hh.

Referenced by geom::Vector< T >::normalized().

## 5.4.3.12 operator[]() [1/2]

Overloaded operator [] (non-const version) To get access to coordinates.

38 Class Documentation

#### **Parameters**

```
i index of coordinate (0 - x, 1 - y, 2 - z)
```

#### Returns

T& reference to coordinate value

Note

Coordinates calculated by mod 3

Definition at line 486 of file vector.hh.

## 5.4.3.13 operator[]() [2/2]

Overloaded operator [] (const version) To get access to coordinates.

#### **Parameters**

```
i index of coordinate (0 - x, 1 - y, 2 - z)
```

## Returns

T coordinate value

Note

Coordinates calculated by mod 3

Definition at line 502 of file vector.hh.

### 5.4.3.14 isPar()

Check if vector is parallel to another.

#### **Parameters**

in rhs vector to check parallelism w	ith
--------------------------------------	-----

## Returns

true if vector is parallel false otherwise

Definition at line 518 of file vector.hh.

## 5.4.3.15 isPerp()

Check if vector is perpendicular to another.

#### **Parameters**

in	rhs	vector to check perpendicularity with
----	-----	---------------------------------------

## Returns

true if vector is perpendicular false otherwise

Definition at line 524 of file vector.hh.

## 5.4.3.16 isEqual()

```
template<std::floating_point T> bool geom::Vector< T >::isEqual ( const\ Vector<\ T\ >\ \&\ rhs\ )\ const
```

Check if vector is equal to another.

## **Parameters**

in	rhs	vector to check equality with

40 Class Documentation

#### Returns

true if vector is equal false otherwise

Note

Equality check performs using isNumEq(T lhs, T rhs) function

Definition at line 530 of file vector.hh.

References geom::Vector< T >::x, geom::Vector< T >::y, and geom::Vector< T >::z.

Referenced by geom::operator==().

## 5.4.3.17 isNumEq()

Check equality (with threshold) of two floating point numbers function.

#### **Parameters**

in	lhs	first number
in	rhs	second number

### Returns

true if numbers equals with threshold (|lhs - rhs| < threshold) false otherwise

Note

Threshold defined by threshold\_ static member

Definition at line 536 of file vector.hh.

## 5.4.3.18 setThreshold()

Set new threshold value.

#### **Parameters**

Definition at line 542 of file vector.hh.

#### 5.4.3.19 getThreshold()

```
template<std::floating_point T>
void geom::Vector< T >::getThreshold [static]
```

Get current threshold value.

Definition at line 548 of file vector.hh.

#### 5.4.3.20 setDefThreshold()

```
template<std::floating_point T>
void geom::Vector< T >::setDefThreshold [static]
```

Set threshold to default value.

Note

default value equals float point epsilon

Definition at line 554 of file vector.hh.

#### 5.4.3.21 operator\*=() [2/2]

Definition at line 424 of file vector.hh.

#### 5.4.3.22 operator/=() [2/2]

Definition at line 435 of file vector.hh.

42 Class Documentation

#### 5.4.4 Member Data Documentation

#### 5.4.4.1 x

```
template<std::floating_point T>
T geom::Vector< T >::x {}
```

Vector coordinates.

Definition at line 46 of file vector.hh.

Referenced by geom::Vector< T >::cross(), geom::Vector< T >::dot(), geom::Vector< T >::isEqual(), geom::Vector< T >::operator-geom::Vector< T >::operator-<().

#### 5.4.4.2 y

```
template<std::floating_point T>
T geom::Vector< T >::y {}
```

Definition at line 46 of file vector.hh.

Referenced by geom::Vector< T >::cross(), geom::Vector< T >::dot(), geom::Vector< T >::isEqual(), geom::Vector< T >::operator-geom::Vector< T >::operator-<().

#### 5.4.4.3 z

```
template<std::floating_point T>
T geom::Vector< T >::z {}
```

Definition at line 46 of file vector.hh.

Referenced by geom::Vector < T >::cross(), geom::Vector < T >::dot(), geom::Vector < T >::isEqual(), geom::Vector < T >::operator-e(), and geom::operator < < ().

The documentation for this class was generated from the following file:

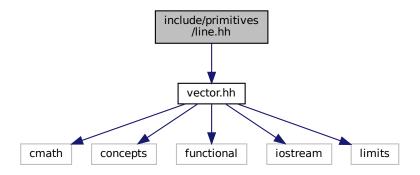
• include/primitives/vector.hh

# **Chapter 6**

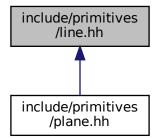
# **File Documentation**

## 6.1 include/primitives/line.hh File Reference

#include "vector.hh"
Include dependency graph for line.hh:



This graph shows which files directly or indirectly include this file:



#### **Classes**

class geom::Line< T >

Line class implementation.

## **Namespaces**

• geom

line.hh Line class implementation

#### **Functions**

```
    template<std::floating_point T>
    std::ostream & geom::operator<< (std::ostream &ost, const Line< T > &line)
        Line print operator.
    template<std::floating_point T>
        bool geom::operator== (const Line< T > &lhs, const Line< T > &rhs)
        Line equality operator.
```

## 6.2 line.hh

```
00001 #ifndef __INCLUDE_PRIMITIVES_LINE_HH_
00002 #define __INCLUDE_PRIMITIVES_LINE_HH_
00004 #include "vector.hh"
00005
00006 /**
00007 * @brief line.hh
00008 * Line class implementation
00009 */
00010
00011 namespace geom
00012 {
00013
00014 /**
00015 * @class Line
00016 * @brief Line class implementation
00017 *
00018 \star @tparam T - floating point type of coordinates 00019 \star/
00020 template <std::floating_point T>
00021 class Line final
00022 {
00023 private:
00024
         \star @brief Origin and direction vectors
00025
00026
00027
         Vector<T> org_{}, dir_{};
00028
00029 public:
00030
          * @brief Construct a new Line object
00031
00032
         * @param[in] org origin vector
* @param[in] dir direction vector
00033
00034
00035
00036
         Line(const Vector<T> &org, const Vector<T> &dir);
00037
00038
          * @brief Getter for origin vector
00039
00040
00041
          * @return const Vector<T>& const reference to origin vector
00042
00043
         const Vector<T> &org() const;
00044
00045
00046
          * @brief Getter for direction vector
00047
00048
           * @return const Vector<T>& const reference to direction vector
```

6.2 line.hh 45

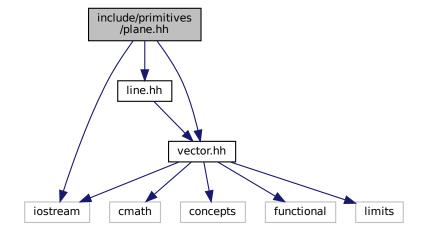
```
00050
        const Vector<T> &dir() const;
00051
00052
00053
        * @brief Checks is point belongs to line
00054
00055
         * @param[in] point const reference to point vector
00056
         * @return true if point belongs to line
00057
         * @return false if point doesn't belong to line
00058
        bool belongs(const Vector<T> &point) const;
00059
00060
00061
00062
        * @brief Checks is *this equals to another line
00063
00064
         \star @param[in] line const reference to another line
         * @return true if lines are equal
00065
00066
         * @return false if lines are not equal
00067
00068
        bool isEqual(const Line &line) const;
00069
00070
00071
         * @brief Get line by 2 points
00072
00073
         * @param[in] p1 1st point
00074
         * @param[in] p2 2nd point
00075
         * @return Line passing through two points
00076
00077
        static Line getBy2Points(const Vector<T> &p1, const Vector<T> &p2);
00078 };
00079
00080 /**
00081 * @brief Line print operator
00082 *
00083 \star @tparam T - floating point type of coordinates
00084 * @param[in, out] ost output stream
00085 * @param[in] line Line to print
      * @return std::ostream& modified ostream instance
00087 */
00088 template <std::floating_point T>
00089 std::ostream &operator (std::ostream &ost, const Line <T> &line)
00090 {
00091 ost « line.org() « " + " « line.dir() « " * t";
00092
       return ost;
00093 }
00094
00095 /**
00096 \star @brief Line equality operator 00097 \star
00098 * @tparam T - floating point type of coordinates
      * @param[in] lhs 1st line
00099
00100 * @param[in] rhs 2nd line
00102 \, * @return false if lines are not equal 00103 \, */
00101 \,\star\, @return true if lines are equal
00104 template <std::floating point T>
00105 bool operator == (const Line < T > & lhs, const Line < T > & rhs)
00106 {
00107
        return lhs.isEqual(rhs);
00108 }
00109
00110 template <std::floating_point T>
00111 Line<T>::Line(const Vector<T> &org, const Vector<T> &dir) : org_{org}, dir_{dir}
00112 {
00113
        if (dir_ == Vector<T>{0})
          throw std::logic_error{"Direction vector equals zero."};
00114
00115 }
00116
00117 template <std::floating_point T>
00118 const Vector<T> &Line<T>::org() const
00119 {
00120
       return org_;
00121 }
00122
00123 template <std::floating_point T>
00124 const Vector<T> &Line<T>::dir() const
00125 {
00126
       return dir_;
00127 }
00128
00129 template <std::floating point T>
00130 bool Line<T>::belongs(const Vector<T> &point) const
00131 {
00132
        return dir_.cross(point - org_) == Vector<T>{0};
00133 }
00134
00135 template <std::floating point T>
```

```
00136 bool Line<T>::isEqual(const Line<T> &line) const
00137 {
00138    return belongs(line.org_) && dir_.isPar(line.dir_);
00139 }
00140
00141 template <std::floating_point T>
00142 Line<T> Line<T>::getBy2Points(const Vector<T> &p1, const Vector<T> &p2)
00143 {
00144    return Line<T>{p1, p2 - p1};
00145 }
00147 } // namespace geom
00148
00149 #endif // __INCLUDE_PRIMITIVES_LINE_HH__
```

## 6.3 include/primitives/plane.hh File Reference

```
#include <iostream>
#include "line.hh"
#include "vector.hh"
```

Include dependency graph for plane.hh:



#### Classes

class geom::Plane< T >

Plane class realization.

## **Namespaces**

• geom

line.hh Line class implementation

6.4 plane.hh 47

#### **Functions**

```
    template<std::floating_point T>
        bool geom::operator== (const Plane< T > &lhs, const Plane< T > &rhs)
        Plane equality operator.
    template<std::floating_point T>
        std::ostream & geom::operator<< (std::ostream &ost, const Plane< T > &pl)
        Plane print operator.
```

## 6.4 plane.hh

```
00001 #ifndef __INCLUDE_PRIMITIVES_PLANE_HH__
00002 #define __INCLUDE_PRIMITIVES_PLANE_HH__
00003
00004 #include <iostream>
00006 #include "line.hh"
00007 #include "vector.hh"
80000
00009 /**
00010 * @brief
00011 * Plane class implementation
00012 */
00013
00014 namespace geom
00015 {
00016
00017 /**
00018 * @class Plane
00019 * @brief Plane class realization
00020 *
00021 \, * @tparam T - floating point type of coordinates 00022 \, */
00023 template <std::floating_point T>
00024 class Plane final
00025 {
00026 private:
        * @brief Normal vector, length equals to 1
*/
00027
00028
00029
        Vector<T> norm_{{}};
00031
00032
00033
         * @brief Distance from zero to plane
00034
00035
        T dist_{};
00036
00037
        * @brief Construct a new Plane object from normal vector and distance
00038
00039
00040
         * @param[in] norm normal vector
00041
         * @param[in] dist distance from plane to zero
00042
00043
        Plane(const Vector<T> &norm, T dist);
00044
00045 public:
00046
00047
         * @brief Getter for distance
00048
00049
         * @return T value of distance
00050
00051
        T dist() const;
00052
00053
00054
         * @brief Getter for normal vector
00055
00056
         * @return const Vector<T>& const reference to normal vector
00057
00058
        const Vector<T> &norm() const;
00059
00060
00061
         * @brief Checks if point belongs to plane
00062
00063
         * @param[in] point const referene to point vector
         * @return true if point belongs to plane
* @return false if point doesn't belong to plane
00064
00065
00066
00067
        bool belongs(const Vector<T> &point) const;
00068
```

```
00070
         * @brief Checks if line belongs to plane
00071
          * @param[in] line const referene to line
* @return true if line belongs to plane
* @return false if line doesn't belong to plane
00072
00073
00074
00076
         bool belongs(const Line<T> &line) const;
00077
00078
00079
          * @brief Checks is *this equals to another plane
00080
00081
          * @param[in] rhs const reference to another plane
00082
          * @return true if planes are equal
00083
          * @return false if planes are not equal
00084
         bool isEqual(const Plane &rhs) const;
00085
00086
00087
00088
          * @brief Get plane by 3 points
00089
00090
          * @param[in] pt1 1st point
00091
          * @param[in] pt2 2nd point
* @param[in] pt3 3rd point
00092
00093
          * @return Plane passing through three points
00094
00095
         static Plane getBy3Points(const Vector<T> &pt1, const Vector<T> &pt2,
00096
                                       const Vector<T> &pt3);
00097
00098
00099
         * @brief Get plane from parametric plane equation
00100
00101
          * @param[in] org origin vector
00102
          * @param[in] dir1 1st direction vector
00103
          * @param[in] dir2 2nd direction vector
00104
          * @return Plane
00105
         static Plane getParametric(const Vector<T> &org, const Vector<T> &dir1,
00106
00107
                                        const Vector<T> &dir2);
00108
00109
          \star @brief Get plane from normal point plane equation
00110
00111
00112
          * @param[in] norm normal vector
00113
          * @param[in] point point lying on the plane
00114
          * @return Plane
00115
00116
         static Plane getNormalPoint(const Vector<T> &norm, const Vector<T> &point);
00117
00118
00119
          * @brief Get plane form normal const plane equation
00120
00121
          * @param[in] norm normal vector
00122
          * @param[in] constant distance
          * @return Plane
00123
00124
00125
         static Plane getNormalDist(const Vector<T> &norm, T constant);
00126 };
00127
00128 /**
00129 * @brief Plane equality operator 00130 *
00131 * @tparam T - floating point type of coordinates

00132 * @param[in] lhs 1st plane

00133 * @param[in] rhs 2nd plane
00134 \star @return true if planes are equal
00135 \star @return false if planes are not equal
00136 */
00137 template <std::floating_point T>
00138 bool operator == (const Plane < T > & lhs, const Plane < T > & rhs)
00139 {
00140
         return lhs.isEqual(rhs);
00141 }
00142
00143 /**
00144 * @brief Plane print operator
00145 *
00146 * @tparam T - floating point type of coordinates

00147 * @param[in, out] ost output stream

00148 * @param[in] pl plane to print

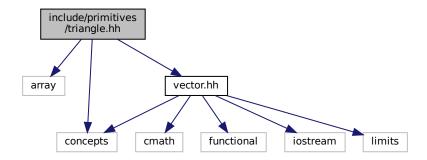
00149 * @return std::ostream& modified ostream instance
00151 template <std::floating_point T>
00152 std::ostream &operator (std::ostream &ost, const Plane T> &pl)
00153 {
        ost « pl.norm() « " * X = " « pl.dist();
00154
00155
        return ost:
```

```
00156 }
00158 template <std::floating_point T>
00159 Plane<T>::Plane(const Vector<T> &norm, T dist) : norm_{n} (norm), dist_{n} (dist)
00160 {
       if (norm == Vector<T>{0})
00161
        throw std::logic_error{"normal vector equals to zero"};
00162
00163 }
00164
00165 template <std::floating_point T>
00166 T Plane<T>::dist() const
00167 {
00168
       return dist ;
00169 }
00170
00171 template <std::floating_point T>
00172 const Vector<T> &Plane<T>::norm() const
00173 {
       return norm_;
00175 }
00176
00177 template <std::floating_point T>
00178 bool Plane<T>::belongs(const Vector<T> &pt) const
00179 {
00180
        return Vector<T>::isNumEq(norm_.dot(pt), dist_);
00181 }
00182
00183 template <std::floating_point T>
00184 bool Plane<T>::belongs(const Line<T> &line) const
00185 {
00186
       return norm .isPerp(line.dir()) && belongs(line.org());
00187 }
00188
00189 template <std::floating_point T>
00190 bool Plane<T>::isEqual(const Plane &rhs) const
00191 {
00192
        return (norm_ * dist_ == rhs.norm_ * rhs.dist_) && (norm_.isPar(rhs.norm_));
00194
00195 template <std::floating_point T>
00196 Plane<T> Plane<T>::getBy3Points(const Vector<T> &pt1, const Vector<T> &pt2,
00197
                                       const Vector<T> &pt3)
00198 {
00199
       return getParametric(pt1, pt2 - pt1, pt3 - pt1);
00200 }
00201
00202 template <std::floating_point T>
00203 Plane<T> Plane<T>::getParametric(const Vector<T> &org, const Vector<T> &dir1,
00204
                                        const Vector<T> &dir2)
00205 {
00206 auto norm = dirl.cross(dir2);
00207 return getNormalPoint(norm, org);
00208 }
00209
00210 template <std::floating_point T>
00211 Plane<T> Plane<T>::getNormalPoint(const Vector<T> &norm, const Vector<T> &pt)
00212 {
00213
       auto normalized = norm.normalized();
00214 return Plane{normalized, normalized.dot(pt)};
00215 }
00216
00217 template <std::floating_point T>
00218 Plane<T> Plane<T>::getNormalDist(const Vector<T> &norm, T dist)
00219 {
00220
       auto normalized = norm.normalized();
00221
       return Plane{normalized, dist};
00222 }
00223
00224 } // namespace geom
00226 #endif // __INCLUDE_PRIMITIVES_PLANE_HH__
```

## 6.5 include/primitives/triangle.hh File Reference

```
#include <array>
#include <concepts>
#include "vector.hh"
```

Include dependency graph for triangle.hh:



#### **Classes**

class geom::Triangle < T >
 Triangle class implementation.

## **Namespaces**

• geom

line.hh Line class implementation

### **Functions**

template<std::floating\_point T>
 std::ostream & geom::operator<< (std::ostream &ost, const Triangle< T > &tr)
 Triangle print operator.

## 6.6 triangle.hh

```
00001 #ifndef __INCLUDE_PRIMITIVES_TRIANGLE_HH_
00002 #define __INCLUDE_PRIMITIVES_TRIANGLE_HH_
00003
00004 #include <array>
00005 #include <concepts>
00006
00007 #include "vector.hh"
00008
00009 /**
00010 * @brief triangle.hh
00011 * Triangle class implementation
00012 */
00013
00014 namespace geom
00015 {
00016
00018 * @class Triangle
00019 * @brief Triangle class implementation
00020 *
00021 \, * @tparam T - floating point type of coordinates 00022 \, */
00023 template <std::floating_point T>
00024 class Triangle final
```

```
00025 {
00026 private:
00027
         * @brief Vertices of triangle
00028
00029
00030
         std::array<Vector<T>, 3> vertices_;
00032 public:
00033 /**
00034
          * @brief Construct a new Triangle object from 3 points
00035
         * @param[in] p1 1st point
* @param[in] p2 2nd point
* @param[in] p3 3rd point
00036
00037
00038
00039
00040
         Triangle(const Vector<T> &p1, const Vector<T> &p2, const Vector<T> &p3);
00041
00042
00043
          * @brief Overloaded operator[] to get access to vertices
00044
00045
          * @param[in] idx index of vertex
00046
          * @return const Vector<T>& const reference to vertex
00047
00048
         const Vector<T> &operator[](std::size_t idx) const;
00049 };
00050
00051 /**
00051 /**

00052 * @brief Triangle print operator

00053 *

00054 * @tparam T - floating point type of coordinates

00055 * @param[in, out] ost output stream

00056 * @param[in] tr Triangle to print

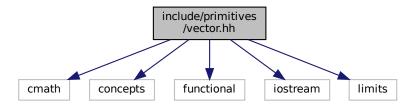
00057 * @return std::ostream& modified ostream instance
00058 */
00059 template <std::floating_point T>
00060 std::ostream &operator«(std::ostream &ost, const Triangle<T> &tr)
00061 {
00062 ost « "Triangle: {";
00063 for (size_t i : {0, 1, 2})

00064 ost « tr[i] « (i == 2 ? "" : ", ");
00065
00066 ost « "}";
00067
00068 return ost;
00069 }
00070
00071 template <std::floating_point T>
00072 Triangle<T>::Triangle(const Vector<T> &p1, const Vector<T> &p2, const Vector<T> &p3)
00073
         : vertices_{p1, p2, p3}
00074 {
00075 }
00076
00077 template <std::floating_point T>
00078 const Vector<T> &Triangle<T>::operator[](std::size_t idx) const
00079 {
08000
         return vertices [idx % 3];
00081 }
00082
00083 \} // namespace geom
00084
00085 #endif // __INCLUDE_PRIMITIVES_TRIANGLE_HH__
```

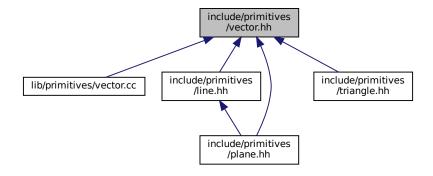
## 6.7 include/primitives/vector.hh File Reference

```
#include <cmath>
#include <concepts>
#include <functional>
#include <iostream>
#include <limits>
```

Include dependency graph for vector.hh:



This graph shows which files directly or indirectly include this file:



## Classes

class geom::Vector < T >
 Vector class realization.

## **Namespaces**

• geom

line.hh Line class implementation

## **Typedefs**

- using geom::VectorD = Vector< double >
- using geom::VectorF = Vector< float >

• template<std::floating\_point T>

#### **Functions**

```
Vector< T > geom::operator+ (const Vector< T > &Ihs, const Vector< T > &rhs)
     Overloaded + operator.

    template<std::floating_point T>

  Vector< T > geom::operator- (const Vector< T > &lhs, const Vector< T > &rhs)
     Overloaded - operator.
• template<Number nT, std::floating_point T>
  Vector< T > geom::operator* (const nT &val, const Vector< T > &rhs)
     Overloaded multiple by value operator.
• template<Number nT, std::floating_point T>
  Vector< T > geom::operator* (const Vector< T > &lhs, const nT &val)
     Overloaded multiple by value operator.
• template<Number nT, std::floating_point T>
  Vector< T > geom::operator/ (const Vector< T > &lhs, const nT &val)
     Overloaded divide by value operator.
• template<std::floating_point T>
  T geom::operator& (const Vector< T > &lhs, const Vector< T > &rhs)
     Dot product operator.
• template<std::floating_point T>
  Vector< T > geom::operator% (const Vector< T > &lhs, const Vector< T > &rhs)
     Cross product operator.

    template<std::floating_point T>

  bool geom::operator== (const Vector< T > &lhs, const Vector< T > &rhs)
      Vector equality operator.

    template<std::floating_point T>

  bool geom::operator!= (const Vector< T > &lhs, const Vector< T > &rhs)
      Vector inequality operator.

    template < std::floating_point T >

  std::ostream & geom::operator<< (std::ostream &ost, const Vector< T > &vec)
      Vector print operator.
```

#### **Variables**

```
    template < class T >
        concept geom::Number = std::is_floating_point_v < T > || std::is_integral_v < T >
        Useful concept which represents floating point and integral types.
```

### 6.7.1 Detailed Description

Vector class implementation

Definition in file vector.hh.

### 6.8 vector.hh

```
00001 #ifndef __INCLUDE_PRIMITIVES_VECTOR_HH
00002 #define __INCLUDE_PRIMITIVES_VECTOR_HH_
00004 #include <cmath>
00005 #include <concepts>
00006 #include <functional>
00007 #include <iostream>
00008 #include <limits>
00009
00010 /**
00011 * @file vector.hh
00012 * Vector class implementation
00013 */
00014
00015 namespace geom
00016 {
00017
00018 /**
00019 * @concept Number
00020 * @brief Useful concept which represents floating point and integral types
00021 *
00022 * @tparam T
00023
00024 template <class T>
00025 concept Number = std::is_floating_point_v<T> || std::is_integral_v<T>;
00026
00027 /
00028 * @class Vector
00029 * @brief Vector class realization
00030 *
00031 \, * @tparam T - floating point type of coordinates 00032 \, */
00033 template <std::floating_point T>
00034 struct Vector final
00035 {
00036 private:
00037
        \star @brief Threshold static variable for numbers comparision
00038
00039
00040
        static inline T threshold_ = 1e3 * std::numeric_limits<T>::epsilon();
00041
00042 public:
00043
         * @brief Vector coordinates
00044
00045
00046
        T x{}, y{}, z{};
00047
00048
00049
         * @brief Construct a new Vector object from 3 coordinates
00050
00051
         * @param[in] coordX x coordinate
         * @param[in] coordY y coordinate
* @param[in] coordZ z coordinate
00052
00053
00054
00055
        Vector(T coordX, T coordY, T coordZ) : x(coordX), y(coordY), z(coordZ)
00056
00057
00058
00059
00060
         * @brief Construct a new Vector object with equals coordinates
00061
00062
         * @param[in] coordX coordinate (default to {})
00063
00064
        explicit Vector(T coordX = {}) : Vector(coordX, coordX, coordX)
00065
00066
00067
00068
         * @brief Overloaded += operator
00069
         * Increments vector coordinates by corresponding coordinates of vec
* @param[in] vec vector to incremented with
00070
00071
00072
         * @return Vector& reference to current instance
00073
00074
        Vector &operator+=(const Vector &vec);
00075
00076
00077
         * @brief Overloaded -= operator
00078
         * Decrements vector coordinates by corresponding coordinates of vec
00079
         * @param[in] vec vector to decremented with
00080
         * @return Vector& reference to current instance
00081
00082
        Vector & operator -= (const Vector & vec);
00083
00084
00085
         * @brief Unary - operator
```

6.8 vector.hh 55

```
00087
        * @return Vector negated Vector instance
00088
00089
       Vector operator-() const;
00090
00091
00092
        * @brief Overloaded *= by number operator
00093
00094
        \star @tparam nType numeric type of value to multiply by
00095
        * @param[in] val value to multiply by
00096
        * @return Vector& reference to vector instance
00097
        */
00098
       template <Number nType>
00099
       Vector & operator *= (nType val);
00100
00101
        * @brief Overloaded /= by number operator
00102
00103
00104
        * @tparam nType numeric type of value to divide by
00105
        * @param[in] val value to divide by
00106
        * @return Vector& reference to vector instance
00107
00108
        * @warning Does not check if val equals 0
00109
00110
        template <Number nType>
00111
        Vector &operator/=(nType val);
00112
00113
        * @brief Dot product function
00114
00115
00116
        \star @param rhs vector to dot product with
00117
        * @return T dot product of two vectors
00118
00119
       T dot(const Vector &rhs) const;
00120
00121
00122
        * @brief Cross product function
00124
        * @param rhs vector to cross product with
00125
        * @return Vector cross product of two vectors
00126
       Vector cross(const Vector &rhs) const;
00127
00128
00129
00130
        * @brief Calculate squared length of a vector function
00131
00132
        * @return T length^2
00133
       T length2() const;
00134
00135
00136
00137
        * @brief Calculate length of a vector function
00138
00139
        * @return T length
00140
00141
       T length() const;
00142
00143
00144
        * @brief Get normalized vector function
00145
00146
        * @return Vector normalized vector
00147
00148
       Vector normalized() const;
00149
00150
00151
        * @brief Normalize vector function
00152
00153
        * @return Vector& reference to instance
00154
00155
       Vector &normalize();
00156
00157
00158
        * @brief Overloaded operator [] (non-const version)
00159
        * To get access to coordinates
        * @param i index of coordinate (0 - x, 1 - y, 2 - z)
00160
00161
        * @return T& reference to coordinate value
00162
00163
        * @note Coordinates calculated by mod 3
00164
00165
       T &operator[](size t i);
00166
00167
00168
        * @brief Overloaded operator [] (const version)
00169
        * To get access to coordinates
        * @param i index of coordinate (0 - x, 1 - y, 2 - z)
00170
00171
        * @return T coordinate value
00172
```

```
* @note Coordinates calculated by mod 3
00174
00175
        T operator[](size_t i) const;
00176
00177
00178
        * @brief Check if vector is parallel to another
00179
00180
         * @param[in] rhs vector to check parallelism with
00181
         \star @return true if vector is parallel
00182
         * @return false otherwise
00183
00184
        bool isPar(const Vector &rhs) const;
00185
00186
00187
         * @brief Check if vector is perpendicular to another
00188
        * @param[in] rhs vector to check perpendicularity with
00189
         * @return true if vector is perpendicular
00190
         * @return false otherwise
00191
00192
00193
        bool isPerp(const Vector &rhs) const;
00194
00195
00196
        * @brief Check if vector is equal to another
00197
00198
        * @param[in] rhs vector to check equality with
         * @return true if vector is equal
00199
00200
         * @return false otherwise
00201
00202
         * @note Equality check performs using isNumEq(T lhs, T rhs) function
00203
00204
        bool isEqual(const Vector &rhs) const;
00205
00206
00207
        * @brief Check equality (with threshold) of two floating point numbers function
00208
        * @param[in] lhs first number
* @param[in] rhs second number
00209
00210
00211
         * @return true if numbers equals with threshold (|lhs - rhs| < threshold)
00212
         * @return false otherwise
00213
         * @note Threshold defined by threshold_ static member
00214
00215
00216
        static bool isNumEq(T lhs, T rhs);
00217
00218
00219
         * @brief Set new threshold value
00220
00221
        * @param[in] thres value to set
00222
00223
        static void setThreshold(T thres);
00224
00225
00226
        * @brief Get current threshold value
00227
00228
       static void getThreshold();
00230
00231
        * @brief Set threshold to default value
00232
        * @note default value equals float point epsilon
00233
00234
        static void setDefThreshold();
00235 };
00236
00237 /**
00238 * @brief Overloaded + operator
00239 *
00240 * @tparam T vector template parameter
00241 * @param[in] lhs first vector
00242 * @param[in] rhs second vector
00243 * @return Vector<T> sum of two vectors
00244 */
00245 template <std::floating_point T> 00246 Vector<T> operator+(const Vector<T> &lhs, const Vector<T> &rhs)
00247 {
00248
       Vector<T> res{lhs};
00249
       res += rhs;
00250
       return res;
00251 }
00252
00253 /**
00254 * @brief Overloaded - operator
00255 *
00256 \star @tparam T vector template parameter
00257 \star @param[in] lhs first vector
00258 * @param[in] rhs second vector
00259 * @return Vector<T> res of two vectors
```

6.8 vector.hh 57

```
00261 template <std::floating_point T>
00262 Vector<T> operator-(const Vector<T> &lhs, const Vector<T> &rhs)
00263 {
00264
        Vector<T> res{lhs};
00265
        res -= rhs;
       return res;
00266
00267 }
00268
00269 /**
00270 \,\,\star\, @brief Overloaded multiple by value operator
00271 *
00272 * @tparam nT type of value to multiply by 00273 * @tparam T vector template parameter
00274 * @param[in] val value to multiply by
00275 \star @param[in] rhs vector to multiply by value
00276 * @return Vector<T> result vector
00277 */
00278 template <Number nT, std::floating_point T>
00279 Vector<T> operator*(const nT &val, const Vector<T> &rhs)
00280 {
00281
        Vector<T> res{rhs};
00282 res *= val;
00283
        return res;
00284 }
00285
00286 /**
00287 \star @brief Overloaded multiple by value operator
00288 *
00289 \star @tparam nT type of value to multiply by
00290 * @tparam T vector template parameter
00290 * (Param[in] val value to multiply by 00292 * (Param[in] lhs vector to multiply by value
00293 * @return Vector<T> result vector
00294 */
00295 template <Number nT, std::floating_point T>
00296 Vector<T> operator*(const Vector<T> &lhs, const nT &val)
00297 {
00298
        Vector<T> res{lhs};
00299 res *= val;
00300
        return res;
00301 }
00302
00303 /**
00304 \star @brief Overloaded divide by value operator
00305 *
00306 \star @tparam nT type of value to divide by
00307 * @tparam T vector template parameter
00308 * @param[in] val value to divide by
00309 * @param[in] lhs vector to divide by value
00310 * @return Vector<T> result vector
00311 */
00312 template <Number nT, std::floating_point T>
00313 Vector<T> operator/(const Vector<T> &lhs, const nT &val)
00314 {
00315
        Vector<T> res{lhs};
      res /= val;
00316
00317
        return res;
00318 }
00319
00320 /**
00321 * @brief Dot product operator
00322 *
00323 * @tparam T vector template parameter
00324 * @param[in] lhs first vector
00325 * @param[in] rhs second vector
00326 * @return T dot production 00327 */
00328 template <std::floating_point T>
00329 T operator&(const Vector<T> &lhs, const Vector<T> &rhs)
00330 {
00331
        return lhs.dot(rhs);
00332 }
00333
00334 /**
00335 * @brief Cross product operator
00336 *
00337 * @tparam T vector template parameter
00338 * @param[in] lhs first vector
00339 * @param[in] rhs second vector
00340 * @return T cross production
00341
00342 template <std::floating_point T>
00343 Vector<T> operator%(const Vector<T> &lhs, const Vector<T> &rhs)
00344 {
00345
         return lhs.cross(rhs);
00346 }
```

```
00347
00348 /**
00349 * @brief Vector equality operator
00350 *
00351 \star @tparam T vector template parameter
00352 * @param[in] lhs first vector
00353 * @param[in] rhs second vector
00354 * @return true if vectors are equal
00355 \star @return false otherwise
00356 */
00357 template <std::floating_point T>
00358 bool operator == (const Vector < T > &lhs, const Vector < T > &rhs)
00359 {
        return lhs.isEqual(rhs);
00360
00361 }
00362
00363 /**
00364 * @brief Vector inequality operator
00366 * @tparam T vector template parameter
00367 * @param[in] lhs first vector
00368 * @param[in] rhs second vector
00369 * @return true if vectors are not equal
00370 * @return false otherwise 00371 */
00372 template <std::floating_point T>
00373 bool operator!=(const Vector<T> &lhs, const Vector<T> &rhs)
00374 {
00375
        return !(lhs == rhs);
00376 }
00377
00378 /**
00379 * @brief Vector print operator
00380 *
00381 * @tparam T vector template parameter
00382 * @param[in, out] ost output stream
00383 * @param[in] vec vector to print
00384 * @return std::ostream& modified stream instance
00385 */
00386 template <std::floating_point T>
00387 std::ostream &operator«(std::ostream &ost, const Vector<T> &vec)
00388 {
       ost « "(" « vec.x « ", " « vec.y « ", " « vec.z « ")";
00389
00390
       return ost;
00391 }
00392
00393 using VectorD = Vector<double>;
00394 using VectorF = Vector<float>;
00395
00396 template <std::floating_point T>
00397 Vector<T> &Vector<T>::operator+=(const Vector &vec)
00398 {
00399
       x += vec.x;
       y += vec.y;
00400
       z += vec.z;
00401
00402
00403
        return *this;
00404 }
00405
00406 template <std::floating_point T>
00407 Vector<T> &Vector<T>::operator == (const Vector &vec)
00408 {
00409
       x \rightarrow vec.x;
00410
       y -= vec.y;
00411
        z -= vec.z;
00412
00413
        return *this;
00414 }
00415
00416 template <std::floating_point T>
00417 Vector<T> Vector<T>::operator-() const
00418 {
00419
        return Vector{-x, -y, -z};
00420 }
00421
00422 template <std::floating_point T>
00423 template <Number nType>
00424 Vector<T> &Vector<T>::operator*=(nType val)
00425 {
00426 x \star = val;
       y *= val;
00427
00428
       z *= val;
00429
00430
        return *this;
00431 }
00432
00433 template <std::floating point T>
```

6.8 vector.hh 59

```
00434 template <Number nType>
00435 Vector<T> &Vector<T>::operator/=(nType val)
00436 {
00437
       x /= val;
       y /= val;
00438
       z /= val;
00439
00441
        return *this;
00442 }
00443
00444 template <std::floating_point T>
00445 T Vector<T>::dot(const Vector &rhs) const
00446 {
00447
       return x * rhs.x + y * rhs.y + z * rhs.z;
00448 }
00449
00450 template <std::floating_point T>
00451 Vector<T> Vector<T>::cross(const Vector &rhs) const
00453
       return Vector{y * rhs.z - z * rhs.y, z * rhs.x - x * rhs.z, x * rhs.y - y * rhs.x};
00454 }
00455
00456 template <std::floating_point T>
00457 T Vector<T>::length2() const
00458 {
00459
       return dot(*this);
00460 }
00461
00462 template <std::floating_point T>
00463 T Vector<T>::length() const
00464 {
00465
        return std::sqrt(length2());
00466 }
00467
00468 template <std::floating_point T>
00469 Vector<T> Vector<T>::normalized() const
00470 {
       Vector res{*this};
00472 res.normalize();
00473 return res;
00474 }
00475
00476 template <std::floating_point T>
00477 Vector<T> &Vector<T>::normalize()
00478 {
00479
       T len2 = length2();
00480 if (isNumEq(len2, 0) || isNumEq(len2, 1))
00481
         return *this;
       return *this /= std::sqrt(len2);
00482
00483 }
00484
00485 template <std::floating_point T>
00486 T &Vector<T>::operator[](size_t i)
00487 {
       switch (i % 3)
00488
00489
00490
       case 0:
00491
         return x;
00492
        case 1:
         return y;
00493
00494
        case 2:
00495
         return z;
00496
       default:
00497
         throw std::logic_error{"Impossible case in operator[]\n"};
00498
00499 }
00500
00501 template <std::floating_point T>
00502 T Vector<T>::operator[](size_t i) const
00503 {
00504
       switch (i % 3)
00505
00506
       case 0:
00507
         return x;
00508
        case 1:
00509
         return y;
00510
        case 2:
00511
00512
        default:
00513
         throw std::logic error{"Impossible case in operator[]\n"};
00514
00515 }
00516
00517 template <std::floating_point T>
00518 bool Vector<T>::isPar(const Vector &rhs) const
00519 {
00520
        return cross(rhs).isEqual(Vector<T>{0});
```

```
00521 }
00523 template <std::floating_point T>
00524 bool Vector<T>::isPerp(const Vector &rhs) const
00525 {
00526
       return isNumEq(dot(rhs), 0);
00528
00529 template <std::floating_point T>
00530 bool Vector<T>::isEqual(const Vector &rhs) const
00531 {
00532
        return isNumEq(x, rhs.x) && isNumEq(y, rhs.y) && isNumEq(z, rhs.z);
00533 }
00534
00535 template <std::floating_point T>
00536 bool Vector<T>::isNumEq(T lhs, T rhs)
00537 {
       return std::abs(rhs - lhs) < threshold_;</pre>
00538
00539 }
00541 template <std::floating_point T>
00542 void Vector<T>::setThreshold(T thres)
00543 {
       threshold_ = thres;
00544
00545 }
00547 template <std::floating_point T>
00548 void Vector<T>::getThreshold()
00549 {
00550
       return threshold_;
00551 }
00552
00553 template <std::floating_point T>
00554 void Vector<T>::setDefThreshold()
00555 {
00556
       threshold_ = std::numeric_limits<T>::epsilon();
00557 }
00559 } // namespace geom
00560
00561 #endif // __INCLUDE_PRIMITIVES_VECTOR_HH__
```

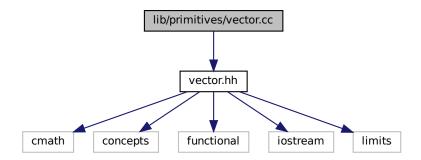
## 6.9 lib/primitives/line.cc File Reference

- 6.10 line.cc
- 6.11 lib/primitives/plane.cc File Reference
- 6.12 plane.cc
- 6.13 lib/primitives/triangle.cc File Reference
- 6.14 triangle.cc
- 6.15 lib/primitives/vector.cc File Reference

#include "vector.hh"

6.16 vector.cc 61

Include dependency graph for vector.cc:



## **Namespaces**

• geom

line.hh Line class implementation

## 6.16 vector.cc

```
00001 #include "vector.hh"
00002
00003 namespace geom
00004 {
00005
00006 // template <std::floating_point T>
00007 // T Vector<T>::threshold_ = std::numeric_limits<T>::epsilon();
00008
00009 } // namespace geom
```