M.TECH. INTELLIGENT AUTOMATION AND ROBOTICS

MULTIMEDIA SYSTEMS		TIMEDIA SYSTEMS	Time: 3 hours	Full Marks: 100)
		Ans	swer any five questions		
1.	a) b)	Explain the encoding and decodi Write short note on 1D DPCM, 2	ng process of Pixel-to- Pixel DPCM. 2D DPCM, 3D DPCM.		2 8
2.	a) b)	Write short notes on the followin Special Redundancy and Ter Give a brief idea about Uniform	mporal Redundancy.	10	0
	c)	Explain the μ law and A law			5
3.	Ex	plain the sequential DCT based me	ethod for JPEG.	2	0
4.	a) b) c)	What is linear transform? Descri Explain different types of maskin Give an example of Huffman coo	-	•	0 5 5
5.			block matching for motion estimation and conjugate direction sea		4 6
	c) d)		n strategy can improve the perfor	mance of a basic	5 5
6.		Differentiate between a motion	ic flow is mathematically represent field and an optic flow field with low vectors following the Horn and	proper examples. I Schunk	4 7
	d)	Discuss a correlation based app	proach of determining optic flow.		5
7.	a)	Discuss the basic principle of and one disadvantage of this m	Smotion-compensated coding. Statethod.	ite one advantage 5+	2
	b)	Explain the principle of PEL re			3
	c)		nique based on steepest descent ap	proach.	7
	ď)		ique which uses Newton-Raphson		3

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8.	a)	Mathematically express image sampling for an image sequence. State the sampling	2+2	
		Alegoram	3	
	b)	Briefly explain how different types of redundancies can be exploited to achieve the goal	J	
		of a video coding system.	5	
	c)	Describe the layered structure of the MPEG-1 video.	1+3	
	d)	Explain the importance and principle of detelecine processing.		
	e)	What is AVO in a MPEG-4 system? Briefly discuss the sprite coding aspect of		
		MPFG-4		