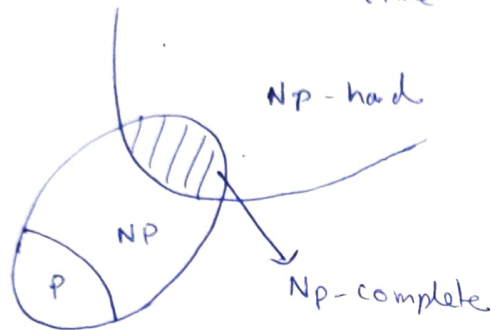


1.
a) NP-completeness

A given problem π is NP complete if

i) $\pi \in NP$

ii) π is NP-hard (i.e. if every problem in NP is ~~reducible~~ polynomial time reducible to π)

i) Showing a problem is NP

This can be achieved simply using a certificate verification strategy, where a certificate is an answer to our problem & verifier is a polynomial algorithm that can tell us whether the answer to the problem is "yes" or "No".

ii) Showing a problem is NP-hard

The theory of reduction is used to prove this. Let H be an NP-hard problem and X be our target problem. We have to reduce H to X . This means that given a polynomial Θ time Θ subroutine for X , we can use it to solve H in polynomial time.

SATISFIABILITY (SAT) problem was the first problem to be proved as NP-hard by Stephen-Cook. All proofs ultimately follow reduction from the NP-completeness of CIRCUIT-SAT

Example:- SAT problem or satisfiability problem. (Md. Sahid, 001710501024) ②

i) $SAT \in NP$

- A proof (proposed solution) is an assignment to the variables.
- The proposed solution can be verified in polynomial time.

ii) SAT is NP-hard

Proof If there exists a polynomial time algorithm for SAT, then there is one for all problems in NP.

b) In order to prove that ~~an~~ an NP-hard problem is not necessarily in NP, we take an example of such a problem:-

given some ~~time~~ n , find all cliques in all graphs with n vertices. Clearly this problem is harder than the general clique problem (i.e. find the largest clique given a graph of n vertices & m edges).

Since, we can solve this ~~problem~~ problem, we can solve the previous clique problem. The answer to this problem is actually all subsets of n vertices which form cliques.

But also note that to verify that we have the ~~correct~~ correct answer, we have to check that we have all subsets which form cliques.

So this problem is NP-hard, but not NP.

1. c) Answer (ii) R is NP-complete.

Because an NP-complete problem, S, is polynomial time reducible to R.
Thus R is NP-hard.

Option (i) is incorrect because R is not NP.

An NP complete problem has to be both NP-hard & NP.

Option (iii) is incorrect because Q is not NP. (same reason as in (i))

Option (iv) is incorrect. as there is not NP-complete problem that is polynomial time reducible to Q.

1.2) P denotes polynomial time solvable problem, i.e. a problem such that there is a solution that solves it in $O(n^k)$ time when k is a constant & n is input size.

A problem is said to be NP if.

→ The solution can be verified in polynomial time.

→ solution always have length polynomial in input size.

To show $P \subseteq NP$,

Let problem X be in P.

We need to show X is also in NP.

For a given instance i of X , and a candidate ~~a~~ solution S_i , the given steps will decide if S_i is correct solution or not.

1. As X is ~~a~~ in P , we have a polynomial solvable problem.
~~step~~ algorithm that can determine the solution of X_i .
2. Let the answer of X be S , then it will ~~of~~ have length polynomial in input size.
3. Now, S can be matched with S_i , ~~then~~ the candidate solution, and tell that if solution is correct or not, Have verification of solution S is ~~not~~ done in polynomial time.

So the problem can be said to be in NP too as both the criteria are fulfilled.

$$\text{Hence } X \in P \Rightarrow X \in NP$$

$$\therefore P \subset NP.$$

⑤

Using recursion :-

Let $D[i]$ be the length of the longest increasing subsequence for the subarray (a_1, \dots, a_i) such that the subsequence ends with $a[i]$.

Our longest increasing subsequence will be $= \text{Max}(D(i))$ for $0 \leq i \leq n$.

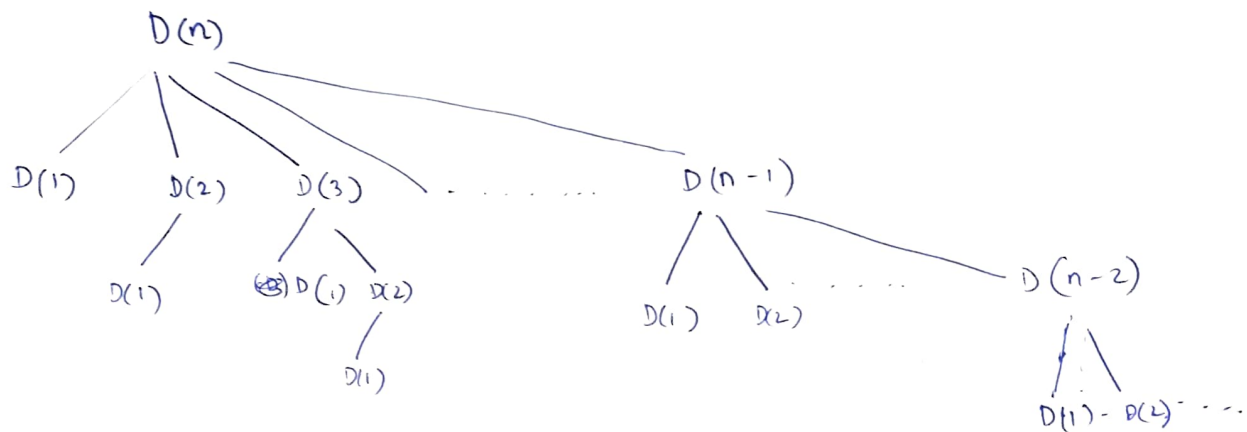
$\therefore D(i)$ can be recursively evaluated as follows:-

$$D[i] = \max(D[j]) + 1; \text{ where } 0 \leq j < i \text{ and } a[i] > a[j]$$

if no such j exists.

then $D(i) = 1$.

Thus the recursion tree will look like this:-



Calculating time complexity:-

In order to calculate $D(n)$, $D(1) \dots D(n-1)$ needs to be calculated.

$$T(n) = T(n-1) + T(n-2) + \dots + T(1) + k. \quad \text{--- (1)}$$

$$\Rightarrow T(n-1) = T(n-2) + T(n-3) \dots T(L) + k \quad \text{--- (11)}$$

①-② $T(n) - T(n-1) = T(n-1)$

$$\Rightarrow T(n) = 2T(n-1)$$
$$= 2 \times [2T(n-2)]$$
$$= 2 \times 2 \times 2 \times T(n-3)$$

$2^{n-1}T(1)$ \therefore The time complexity is of order $O(2^n)$

Using Dynamic Programming :-

Here, instead of recalculating the values of $D[j]$ (of $0 < j < i$) at each call, we use the concept of memorization so that each $D[i]$ is calculated only once.

Let dp be an array such that $dp[i] = D(i)$

$$\therefore dp[i] = \begin{cases} 1 + \max(dp[j]) & \text{where } 0 < j < i \text{ \& } a[j] < a[i] \\ 1 & \text{if no such } j \text{ exists.} \end{cases}$$

$$i = 1, \dots, n.$$

$$LIS = \max(dp[i]) \text{ where } 0 < i \leq n$$

we calculate $dp[i]$ starting from $i=1$ with increasing value of i for each iteration.

$$\therefore T(1) = k$$

$$T(2) = T(1) + k$$

$$T(3) = T(2) + 2k$$

⋮

$$T(n) = T(n-1) + (n-1)k$$

•

$$\therefore T(n) = T(n-1) + (n-1)k$$

$$= T(n-2) + (n-2)k + (n-1)k$$

$$= T(n-3) + (n-3)k + (n-2)k + (n-1)k$$

⋮

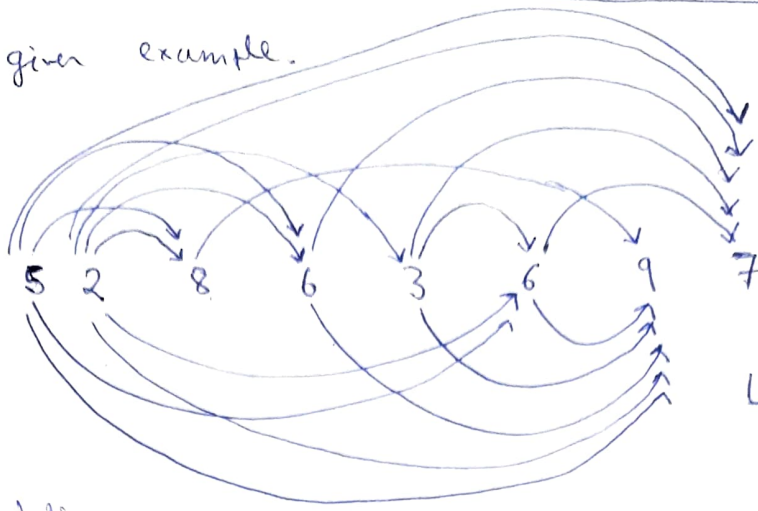
$$= k + 2k + \dots + (n-1)k$$

$$T(n) = \frac{(n-1)(n+1)}{2} k.$$

\therefore Time complexity will be of order $O(n^2)$.

DAG for the given example.

a =



LIS: $2 \rightarrow 3 \rightarrow 6 \rightarrow 7$
or
 $2 \rightarrow 3 \rightarrow 6 \rightarrow 9$

Table of computation.

X	X	A	L	T	R	U	I	S	T	H	C
X	0	1	2	3	4	5	6	7	8	9	10
A	1	0	1	2	3	4	5	6	7	8	9
L	2	1	0	1	2	3	4	5	6	7	8
T	3	2	1	0	1	2	3	4	5	6	7
R	4	3	2	1	0	1	2	3	4	5	6
U	5	4	3	2	1	0	1	2	3	4	5
I	6	5	4	3	2	1	0	1	2	3	4
S	7	6	5	4	3	2	1	0	1	2	3
T	8	7	6	5	4	3	2	1	0	1	2
H	9	8	7	6	5	4	3	2	1	0	1
C	10	9	8	7	6	5	4	3	2	1	0

\therefore Minimum edit distance = $E(9, 10) = 6$.

The path to reach goal is marked in the table.

Other possible paths are marked with dotted paths.

~~Align~~

Optimal solution Alignment:-

A	L	G	O	R	-	I	-	T	H	M
A	L	-	T	R	U	I	S	T	I	C
		1	2		3		4		5	6

Other solutions possible optimal solutions:-

A	L	G	O	R	-	I	-	T	H	M
A	L	T	-	R	U	I	S	T	I	C
		1	2		3		4		5	6

A	L	G	O	R	I	-	T	H	M
A	L	T	R	U	I	S	T	I	C
		1	2	3		4		5	6