### 6.829: Computer Networks and Mobile Systems

Lecture 6: Device-Free Localization

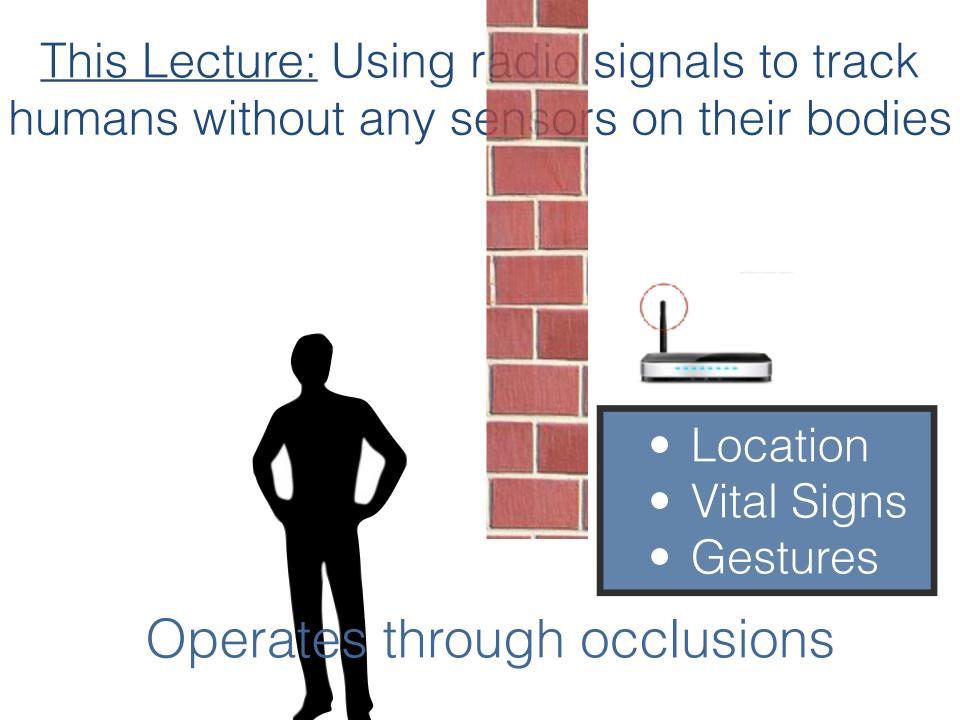


# Previous Lecture: Device-based Localization

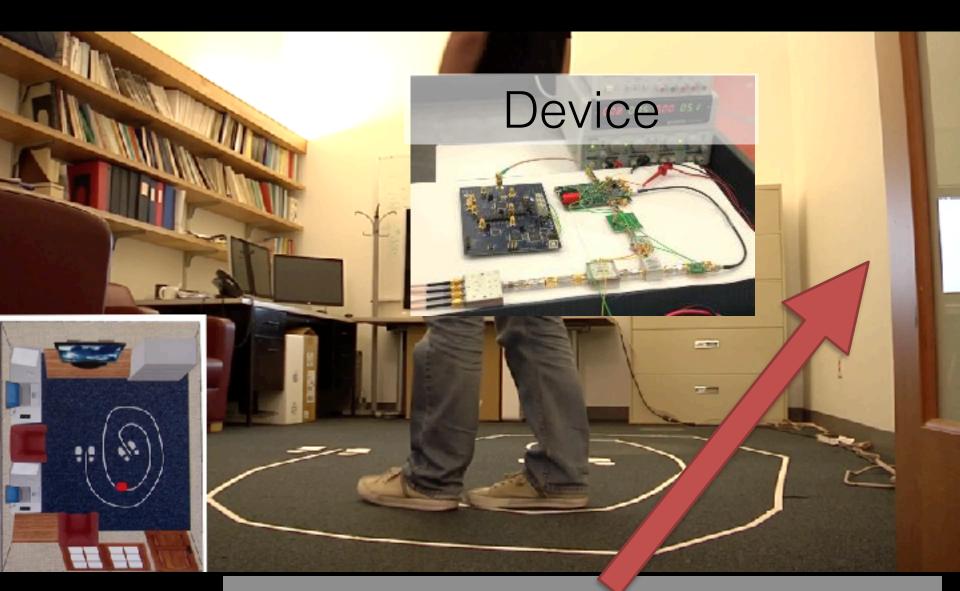




# This Lecture: Using radio signals to track humans without any sensors on their bodies

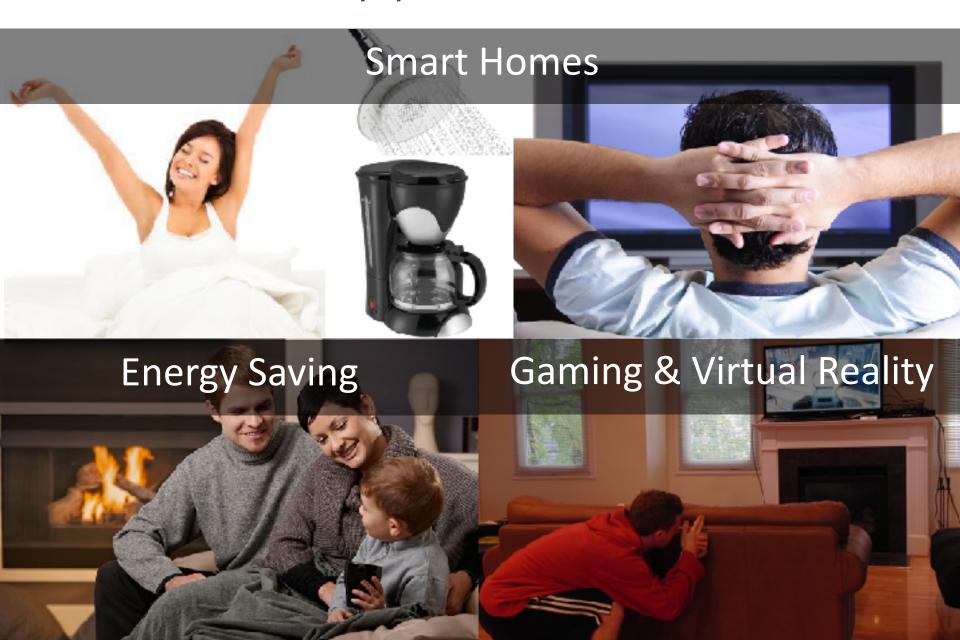


### Example: WiTrack

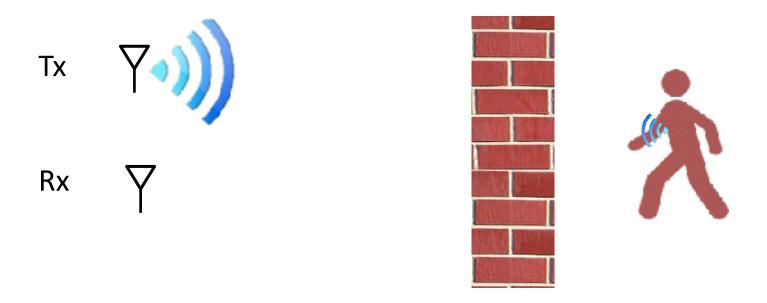


Device in another room

### Applications



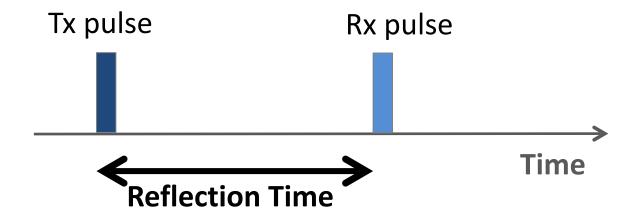
### Measuring Distances



Distance = Reflection time x speed of light

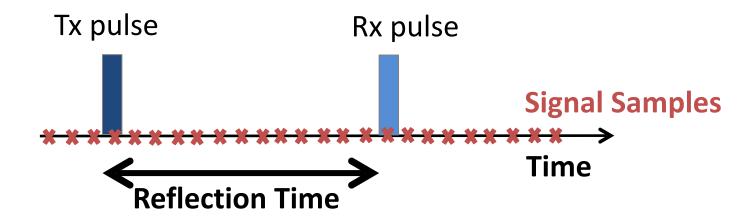
### Measuring Reflection Time

Option1: Transmit short pulse and listen for echo



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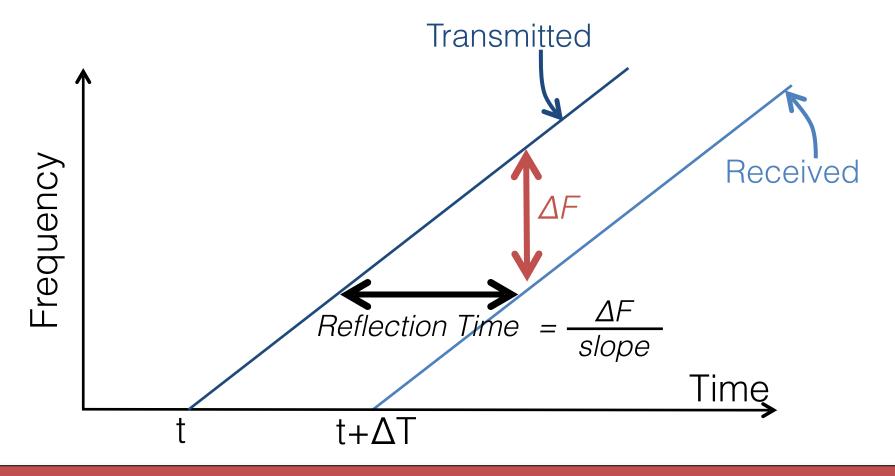


Capturing the pulse needs sub-nanosecond sampling

Multi-GHz samplers are expensive, have high noise, and create large I/O problem

# What is the resolution direct time sampling?

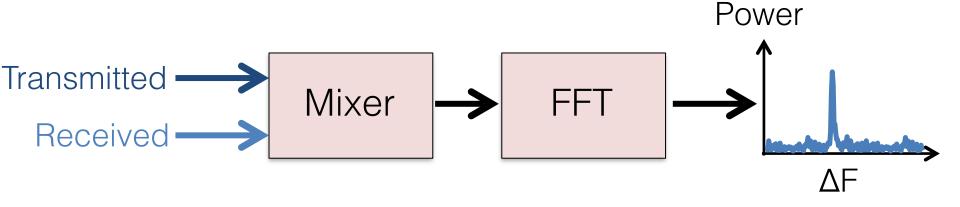
### FMCW: Measure time by measuring frequency



How do we measure  $\Delta F$ ?

### Measuring ΔF

- Subtracting frequencies is easy (e.g., removing carrier in WiFi)
- Done using a mixer (low-power; cheap)

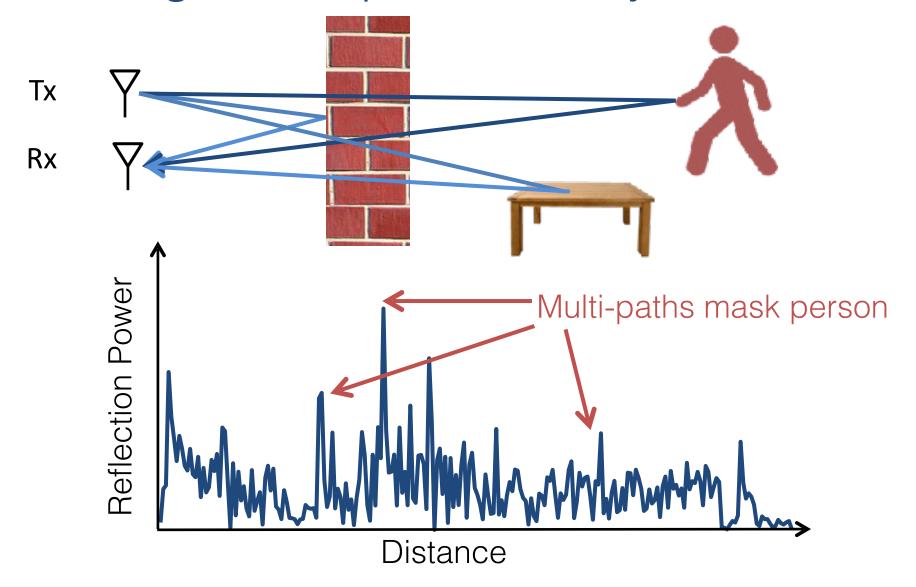


Signal whose frequency is  $\Delta F$ 

 $\Delta F \rightarrow Reflection Time \rightarrow Distance$ 

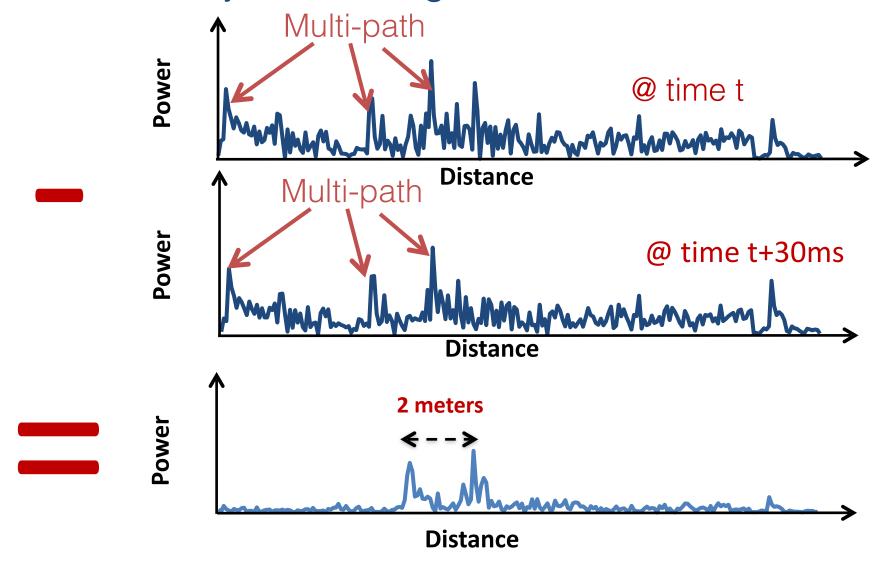
### What is the resolution of FMCW?

### <u>Challenge:</u> Multipath→ Many Reflections



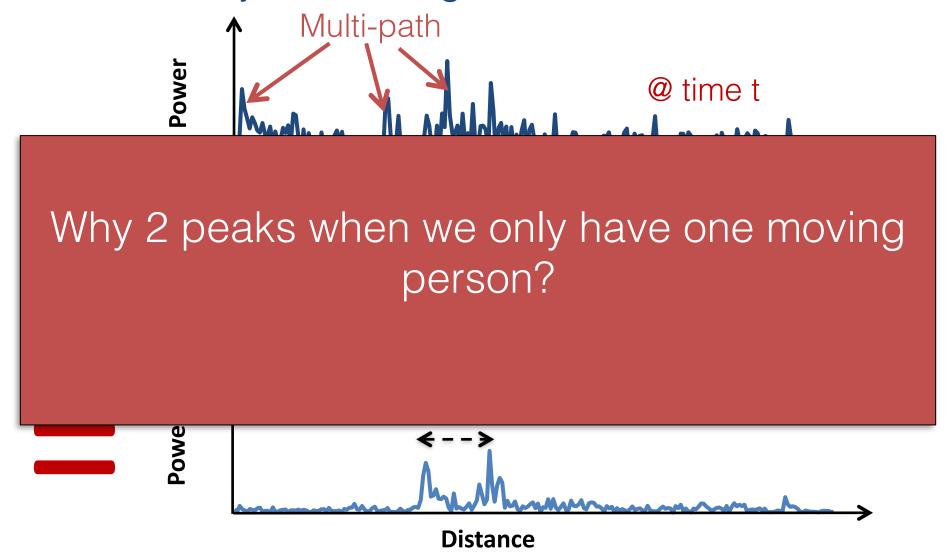
### Static objects don't move

→ Eliminate by subtracting consecutive measurements

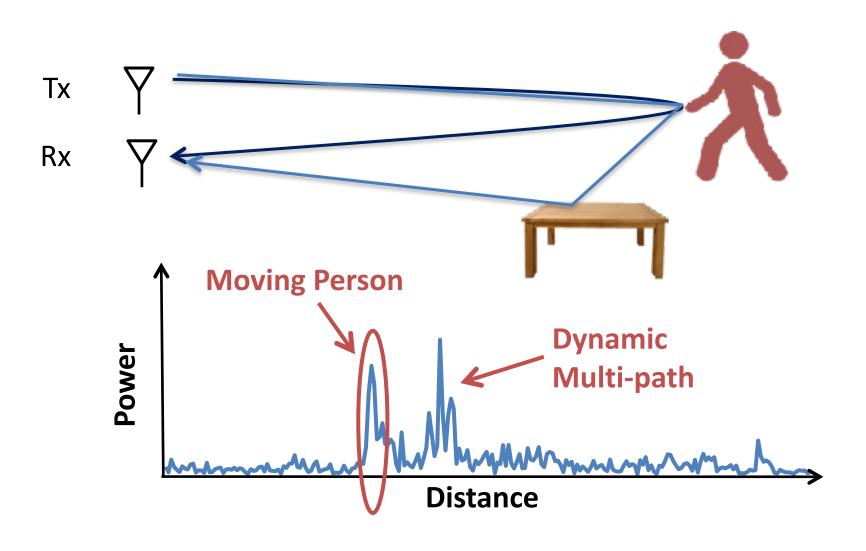


### Static objects don't move

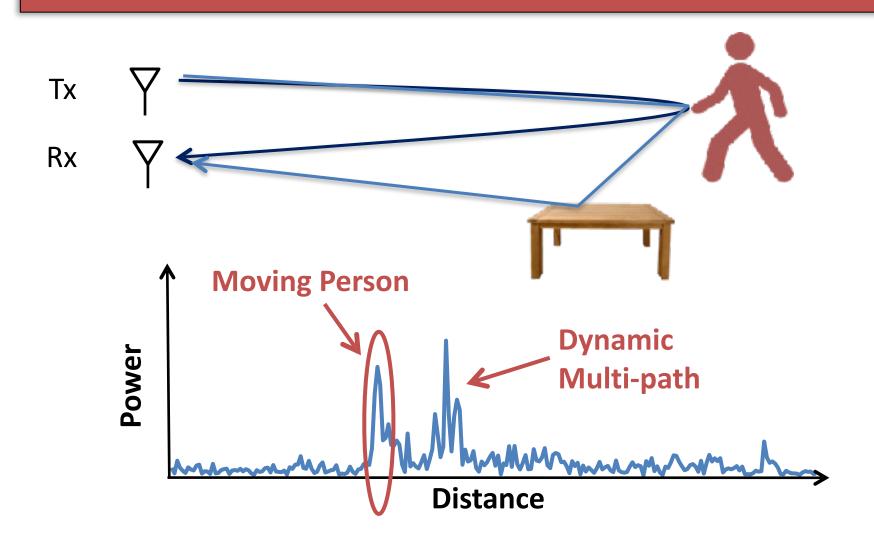
→ Eliminate by subtracting consecutive measurements



### Challenge: Dynamic Multipath

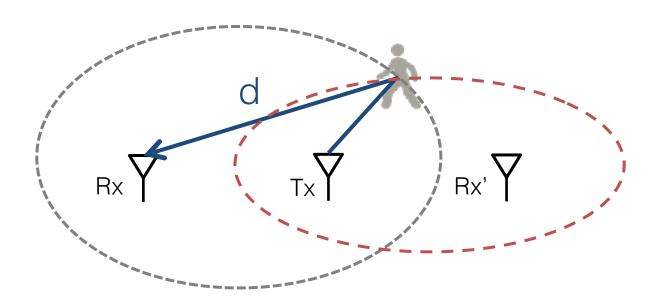


### The direct reflection arrives before dynamic multipath!



### Mapping Distance to Location

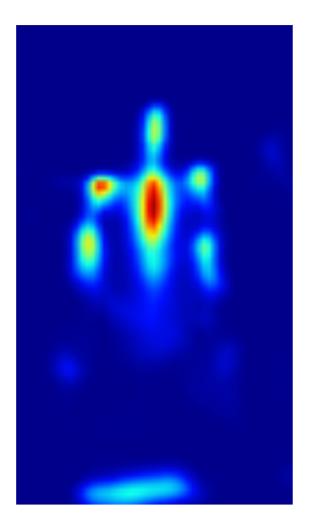
Person can be anywhere on an ellipse whose foci are (Tx,Rx)



By adding another antenna and intersecting the ellipses, we can localize the person

# People are points

### Want a silhouette



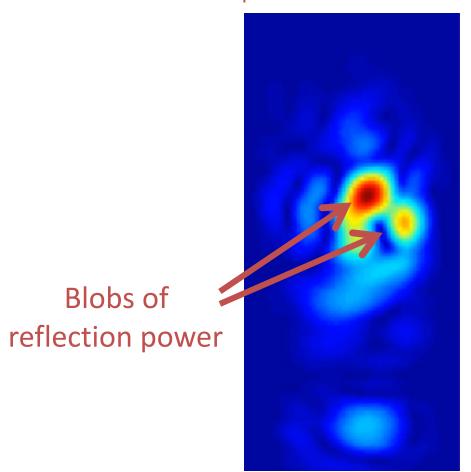
# Approach: Combine antenna arrays with FMCW to get 3D image

- 2D Antenna array gives 2 angles
- FMCW gives depth (1D)

# 2D array

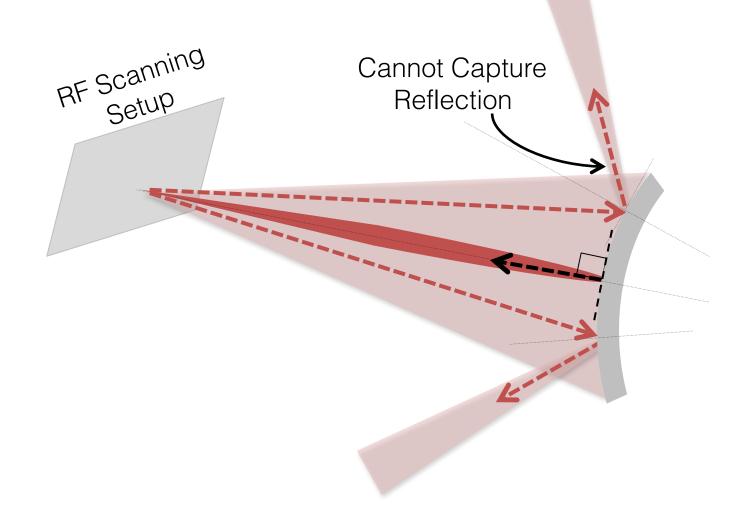
## Challenge: We only obtain blobs in space

Output of 3D RF Scan

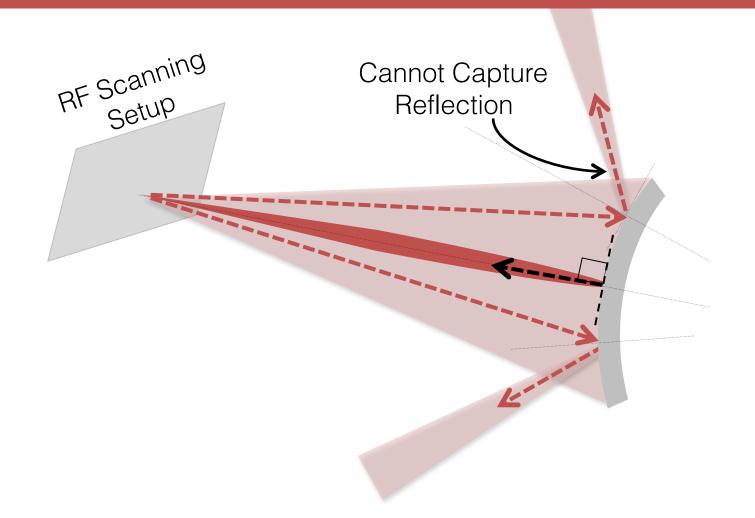


### Challenge: We only obtain blob in space

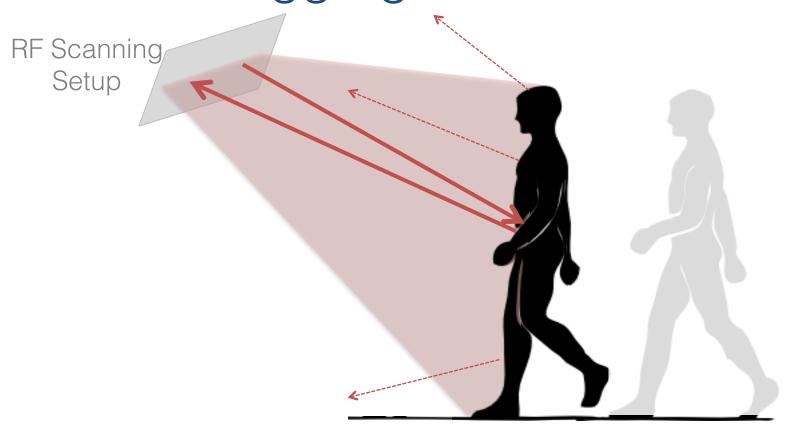
At frequencies that traverse walls, human body parts are specular (pure mirror)



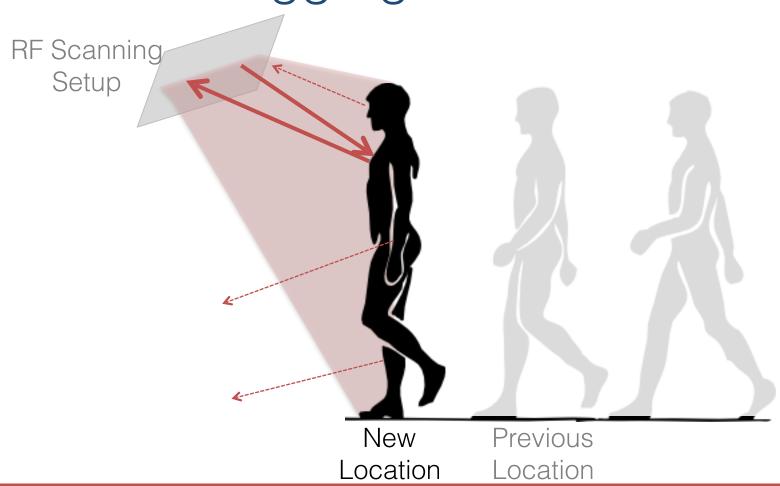
# At every point in time, we get reflections from only a subset of body parts.



# Solution Idea: Exploit Human Motion and Aggregate over Time

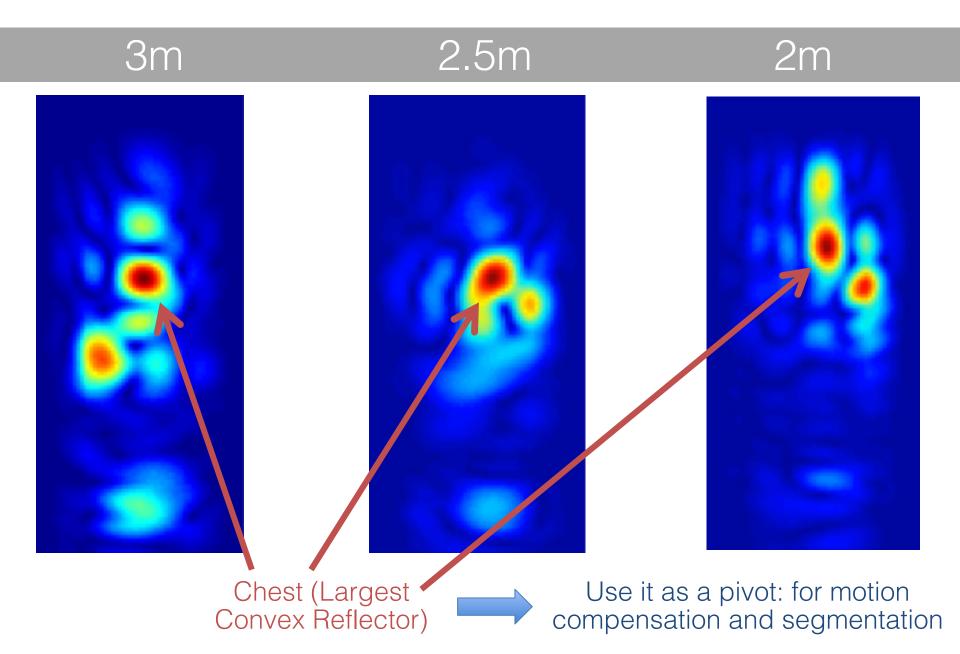


# Solution Idea: Exploit Human Motion and Aggregate over Time

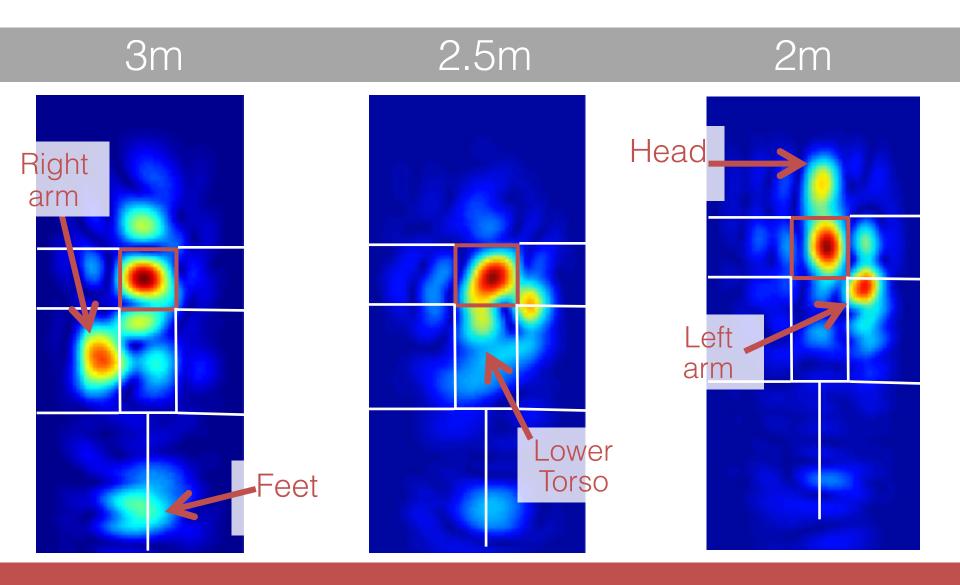


Combine the various snapshots

### Human Walks toward Sensor

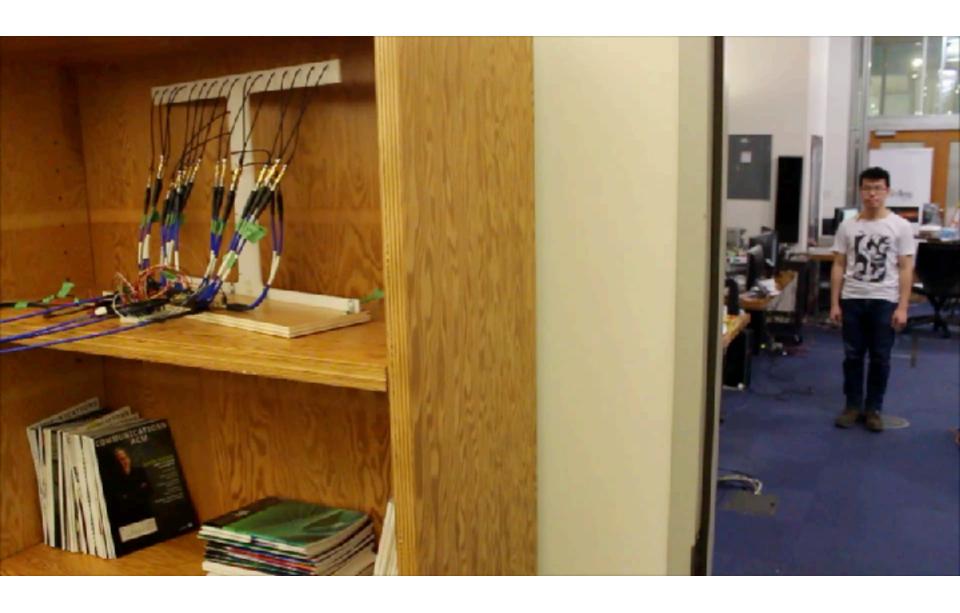


### Human Walks toward Sensor



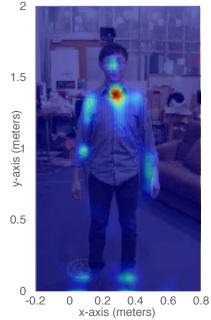
Combine the various snapshots

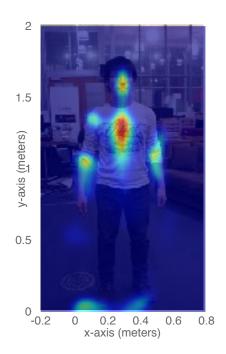
### Human Walks toward Sensor

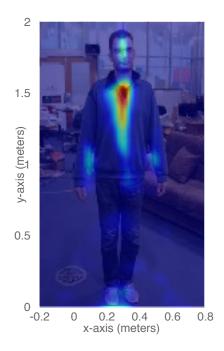


### Sample Captured Figures through Walls

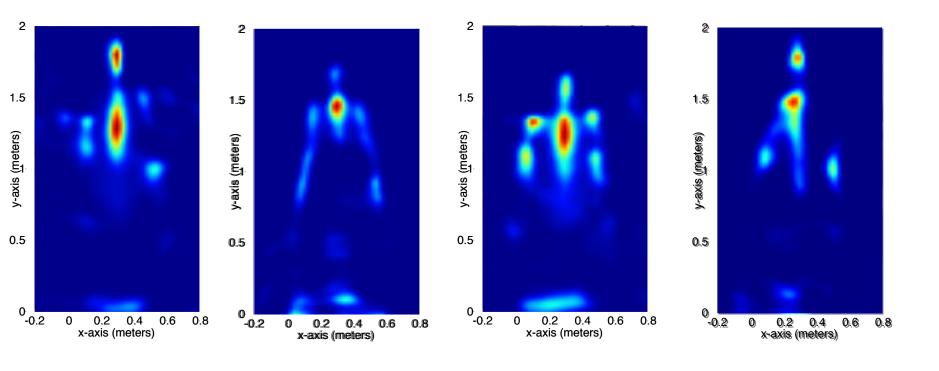








### Through-wall classification accuracy of 90% among 13 users



### Wireless Comm (Cont'd)

Packet Detection (sliding window)

Wireless Channel

Carrier Frequency Offset (CFO)