

# 6.S062: Mobile and Sensor Computing

aka IoT Systems

<http://6s062.github.io/6MOB>

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Sign up on Piazza for announcements

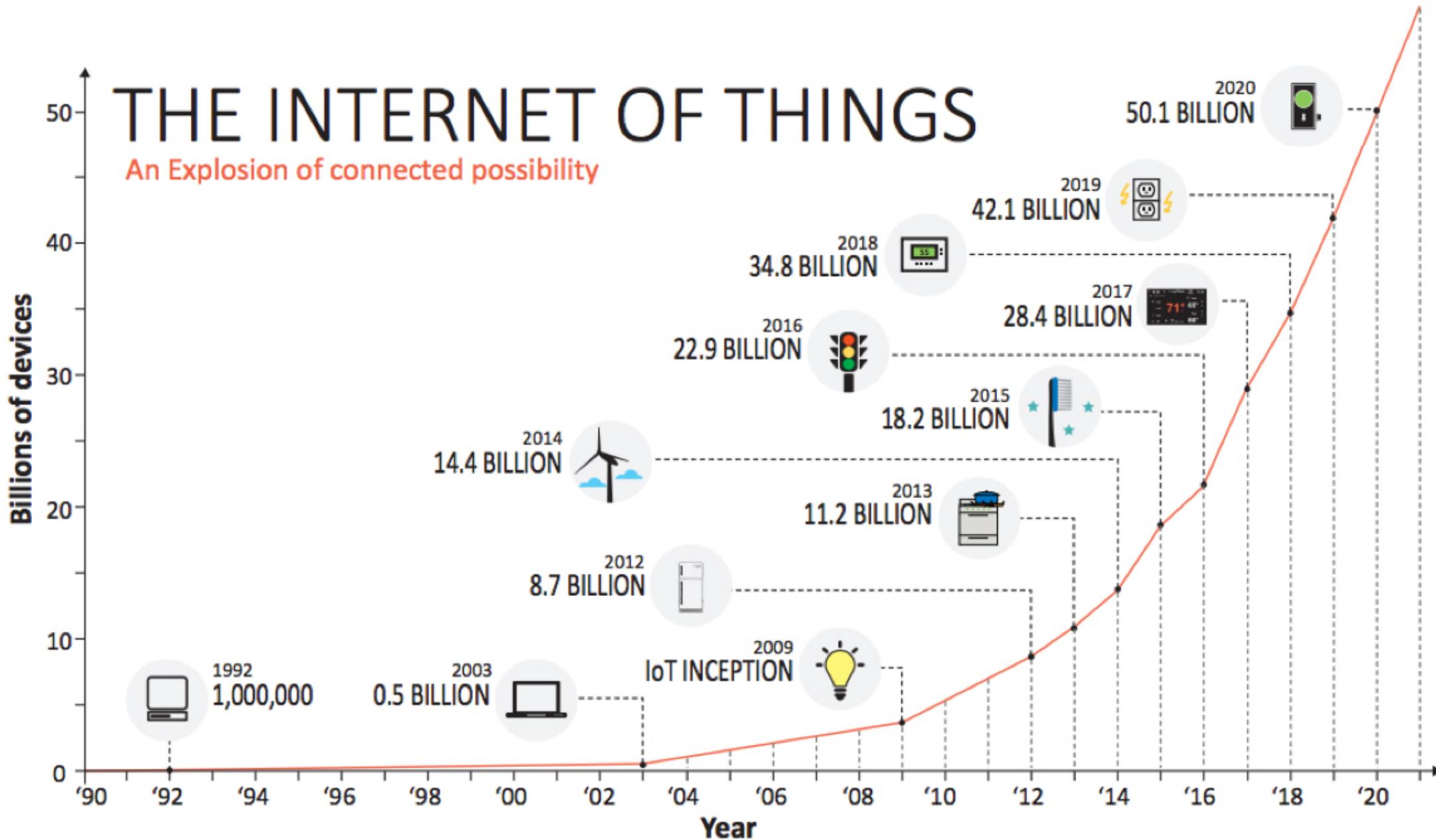
# Internet-of-Things

Convergence of micro-sensing, computation, and communication that allows us to:

- *Acquire (sense)* data from the environment
- *Pre-process* data locally
- *Deliver* data to servers
- *Draw inferences* and *provide insights* about the world from the data using computational techniques
  - Sensor fusion, data integration
  - Signal processing
  - Machine learning
- *Control* actions in the environment

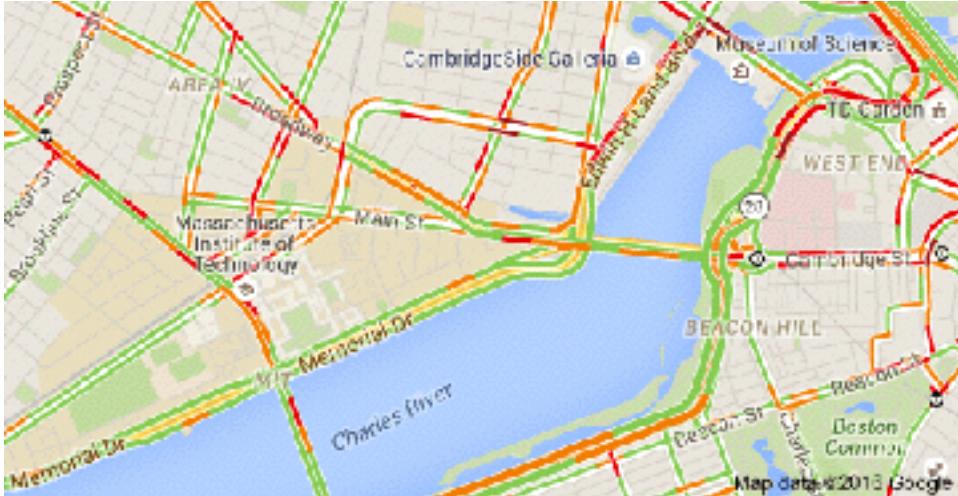
# THE INTERNET OF THINGS

An Explosion of connected possibility



# IoT is Transforming Industries

Transportation & Smart Cities



Medicine



Smart Homes



Health & Wellness

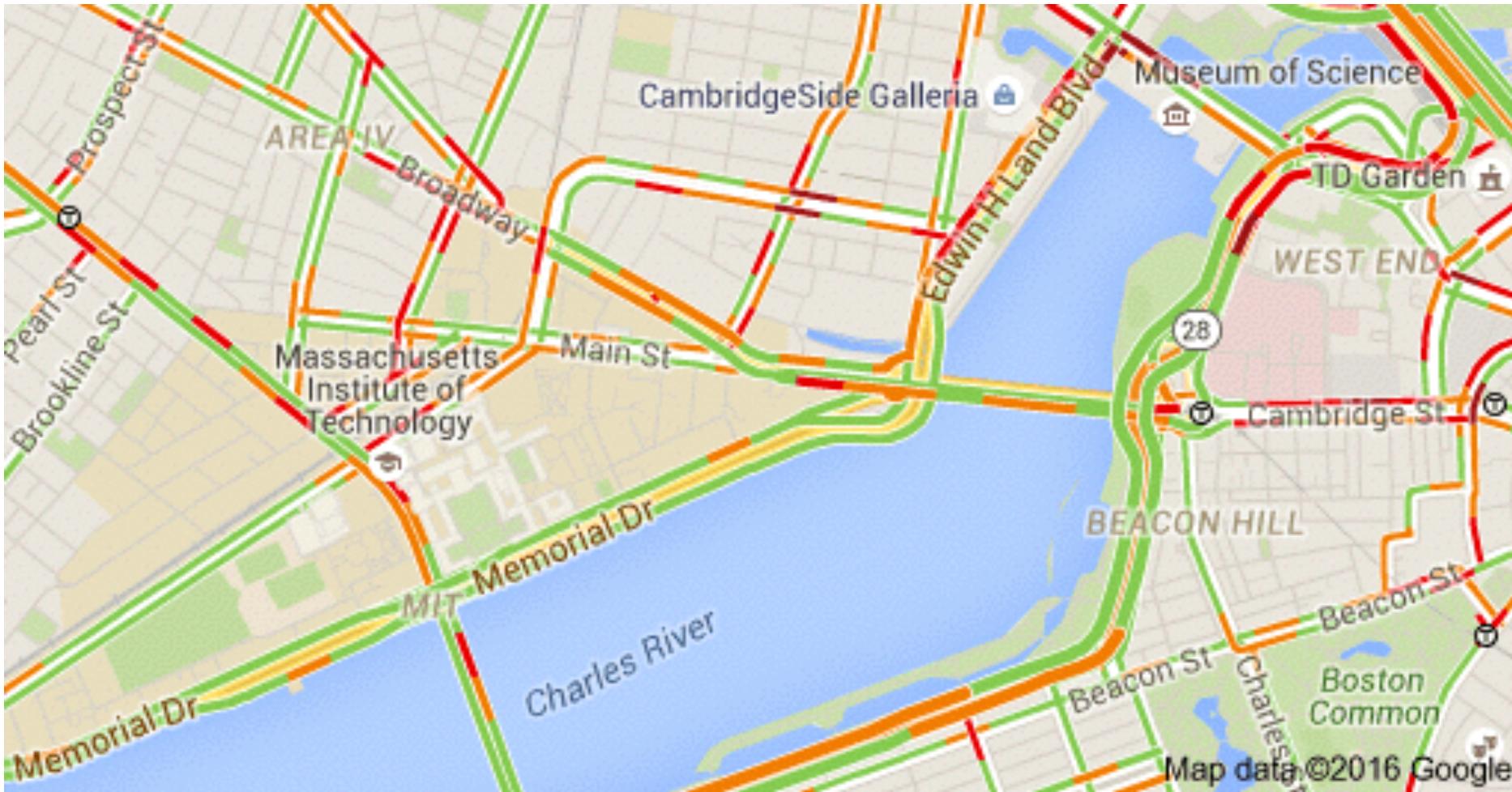


Connected vehicles

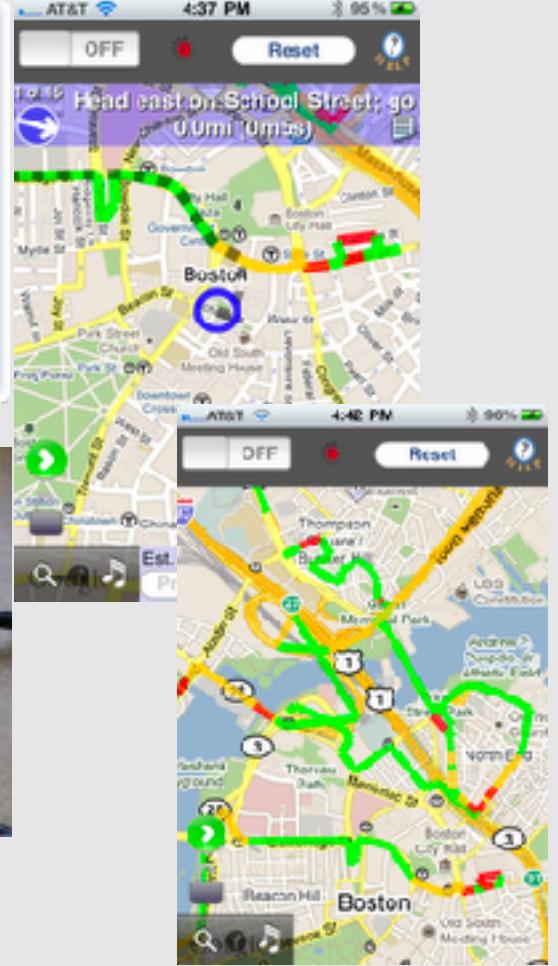
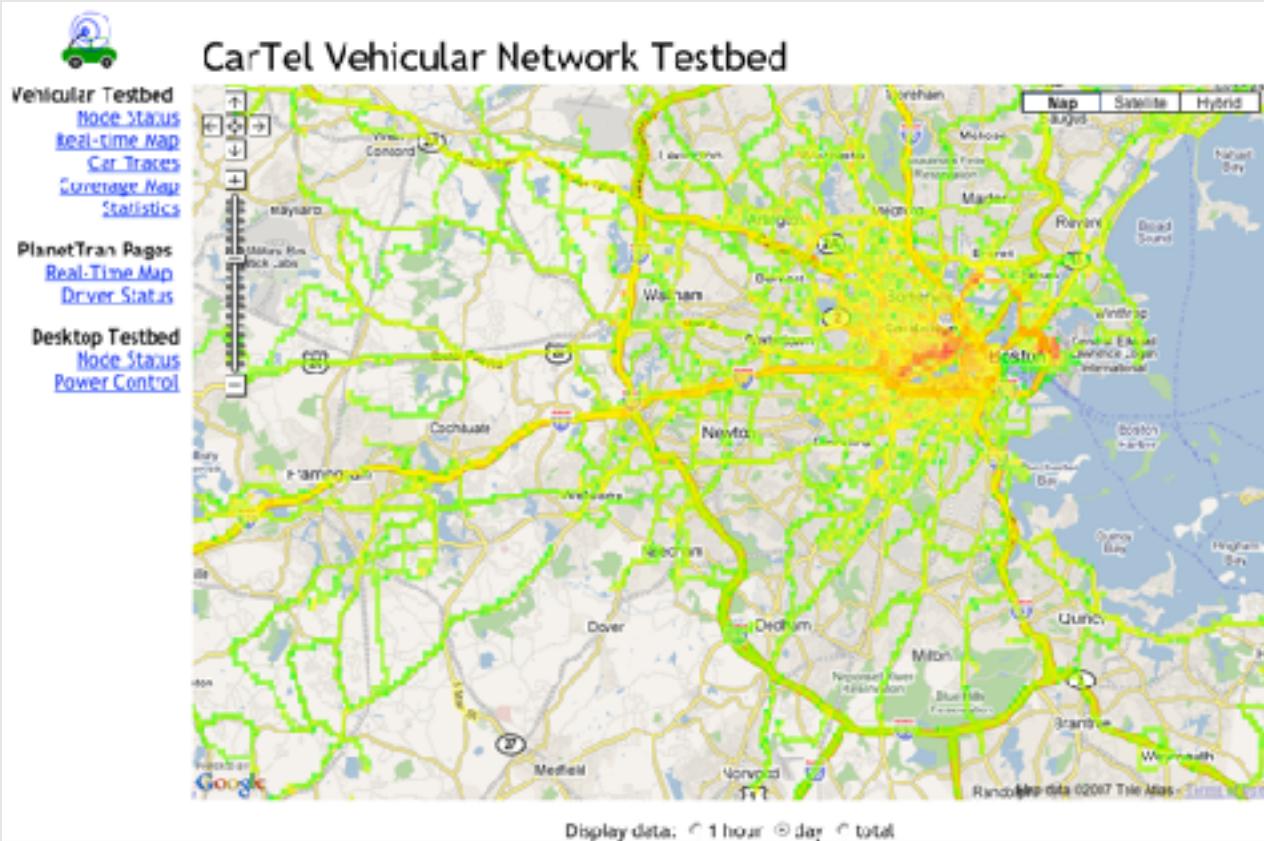
Precision Agriculture



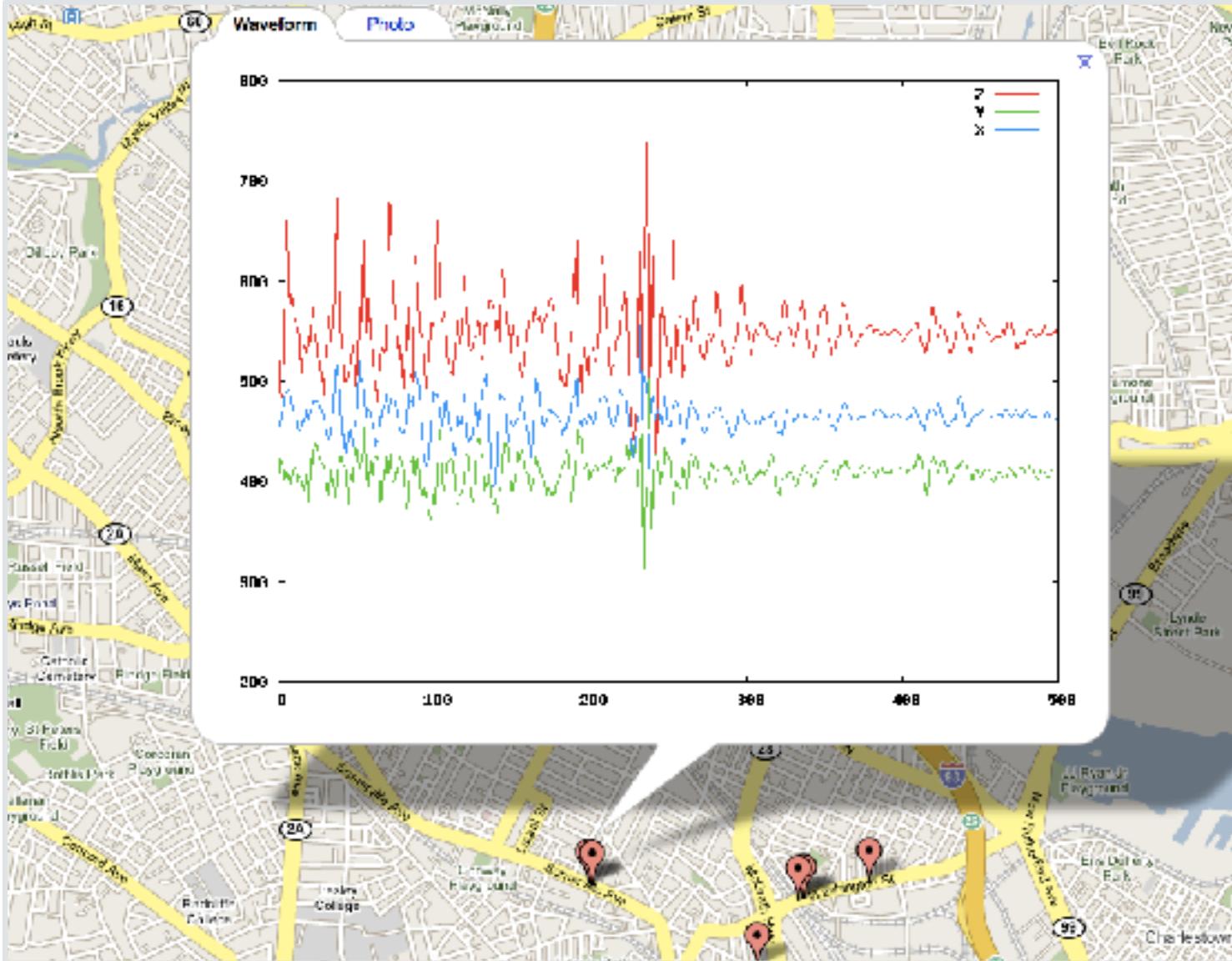
# Transportation & Smart Cities



# CarTel Project at MIT (2005-2011)



# Pothole Patrol



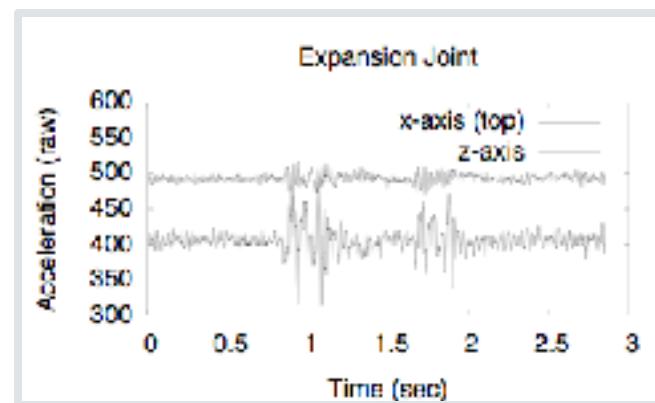
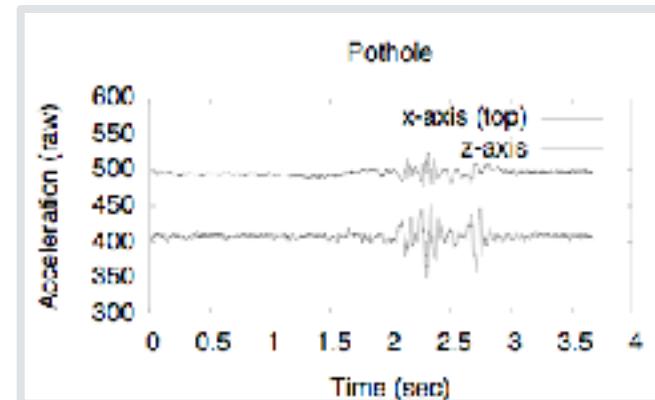
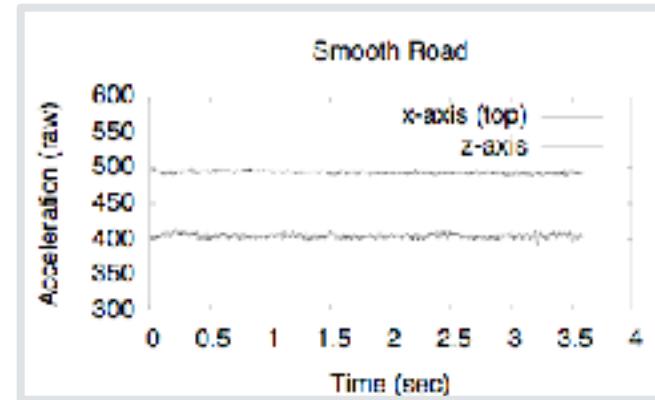
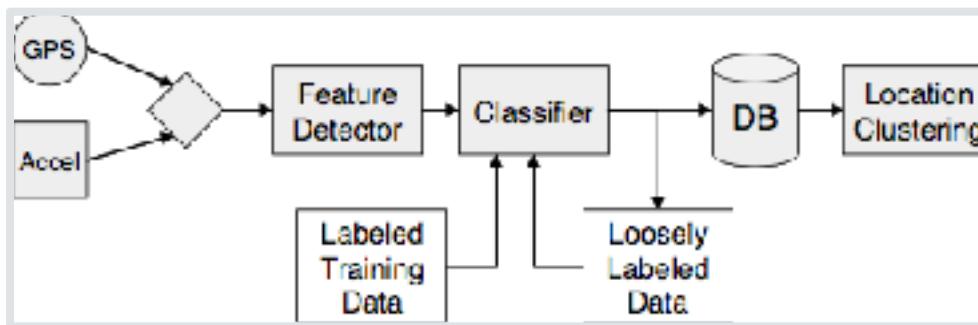
# Classification-based Approach

Classifier differentiates between several types of anomalies

Window data, compute features per window

Variety of features:

- Range of X,Y,Z accel
- Energy in certain frequency bands
- Car speed
- ...



# DriveWell: Safe Driving

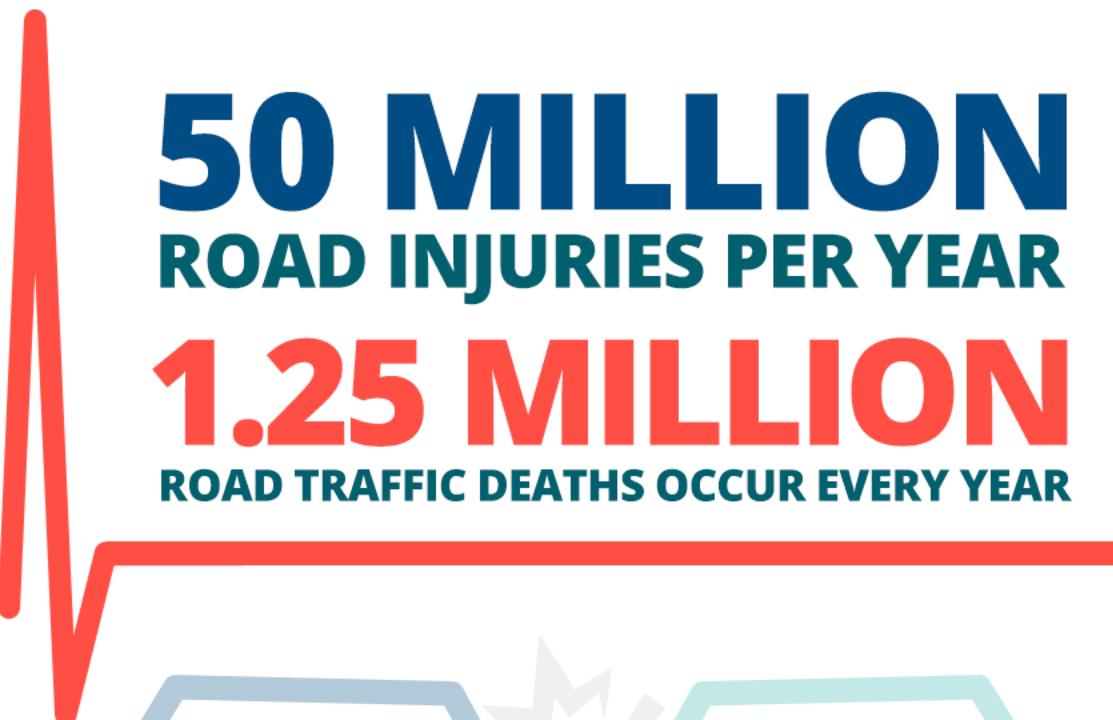
*Make roads safer by making drivers better*

**50 MILLION**  
ROAD INJURIES PER YEAR

**1.25 MILLION**  
ROAD TRAFFIC DEATHS OCCUR EVERY YEAR

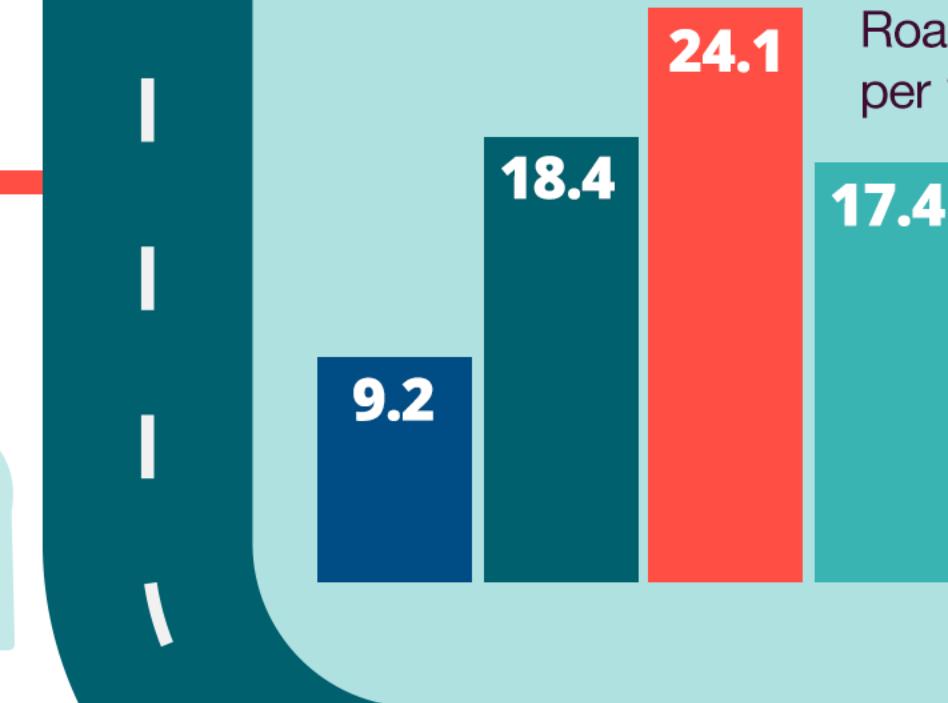


**INCREASE IN U.S. ROAD FATALITIES  
BETWEEN 2014 AND 2016**



## A GLOBAL PROBLEM.

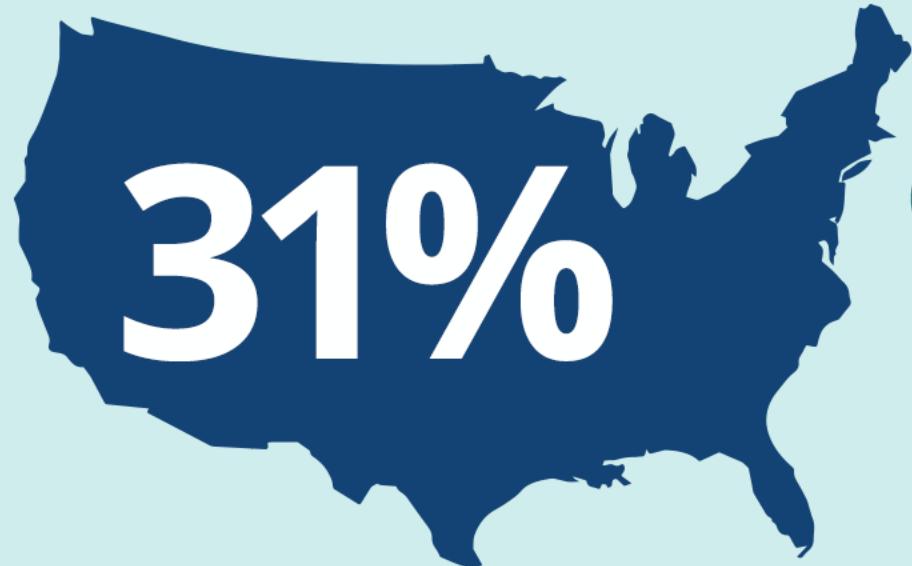
Road traffic fatalities per 100,000 population.



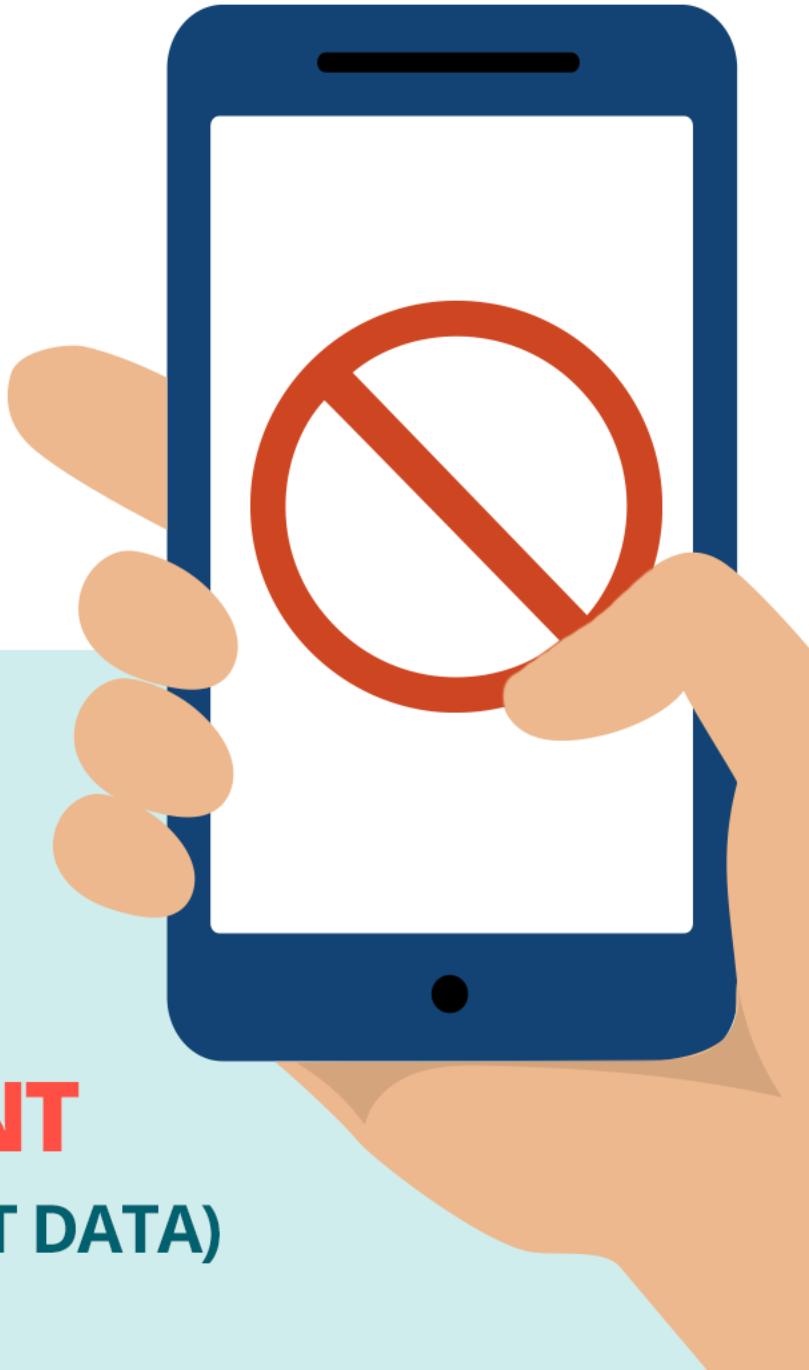
- HIGH-INCOME COUNTRIES
- MIDDLE-INCOME COUNTRIES
- LOW-INCOME COUNTRIES
- WORLD



IN 2014, **431,000**  
WERE INJURED IN CRASHES  
INVOLVING DISTRACTED  
DRIVERS



**OF DRIVES  
IN THE U.S.  
HAVE SIGNIFICANT  
DISTRACTION (CMT DATA)**



# Example: Safe Driving (Drivewell)

Key capabilities: “safety score”, incentives, end-to-end impact alerts

## Smartphone sensors:

Acceleration  
Gyroscope  
Position  
Barometer  
Compass



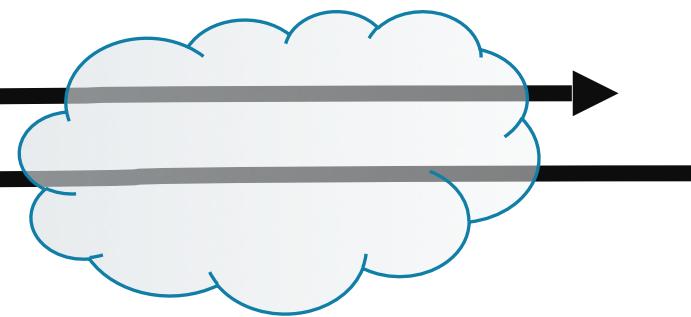
Requirement:  
< 5% battery drain /  
hour when driving, 0  
at other times

Bluetooth Low  
Energy (BLE)

Requirement:  
4+ years battery life

Tag

Sense: Acceleration  
Infer: Events, Impacts,  
trips start/end, mileage,  
duration



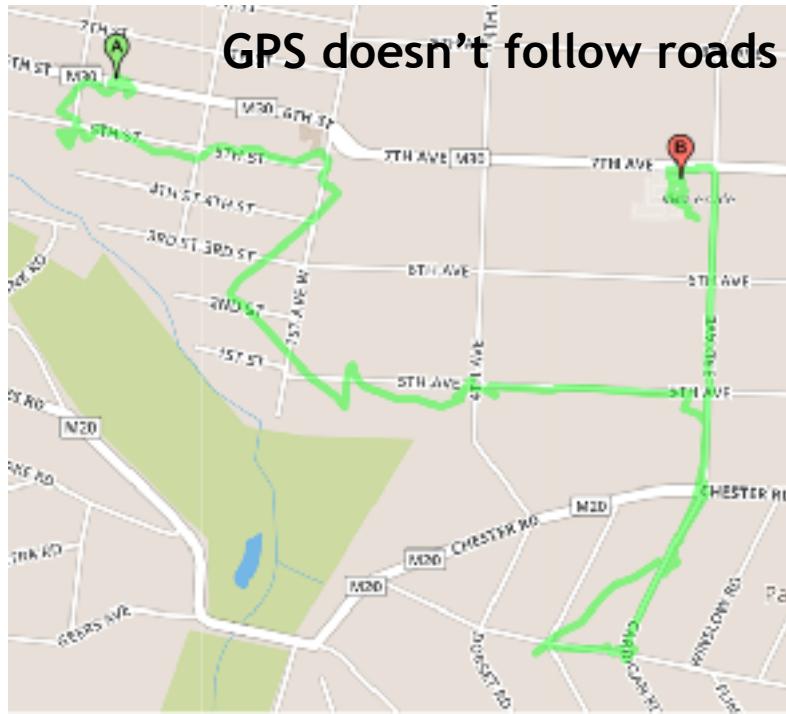
Requirement: 10  
second end-to-end  
notification of  
accidents

Requirement: Accurately  
measure distracted  
driving, unsafe speeding,  
hard braking, mileage etc.

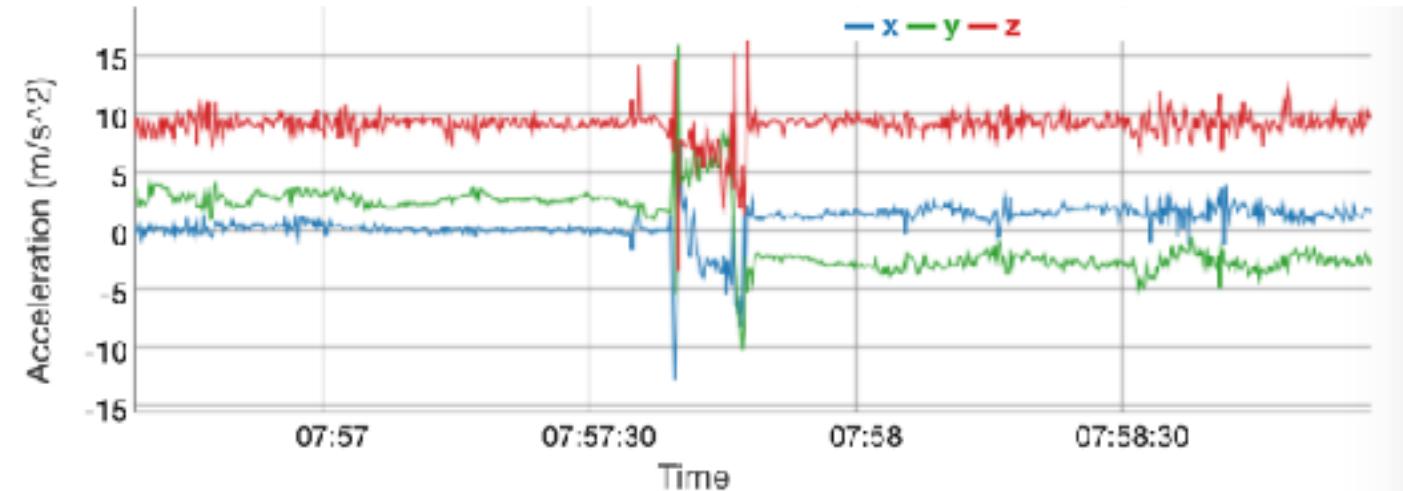


Requirement:  
Prompt trip  
feedback within  
seconds-minutes

# Drivewell Data Challenges



Users move phone while driving



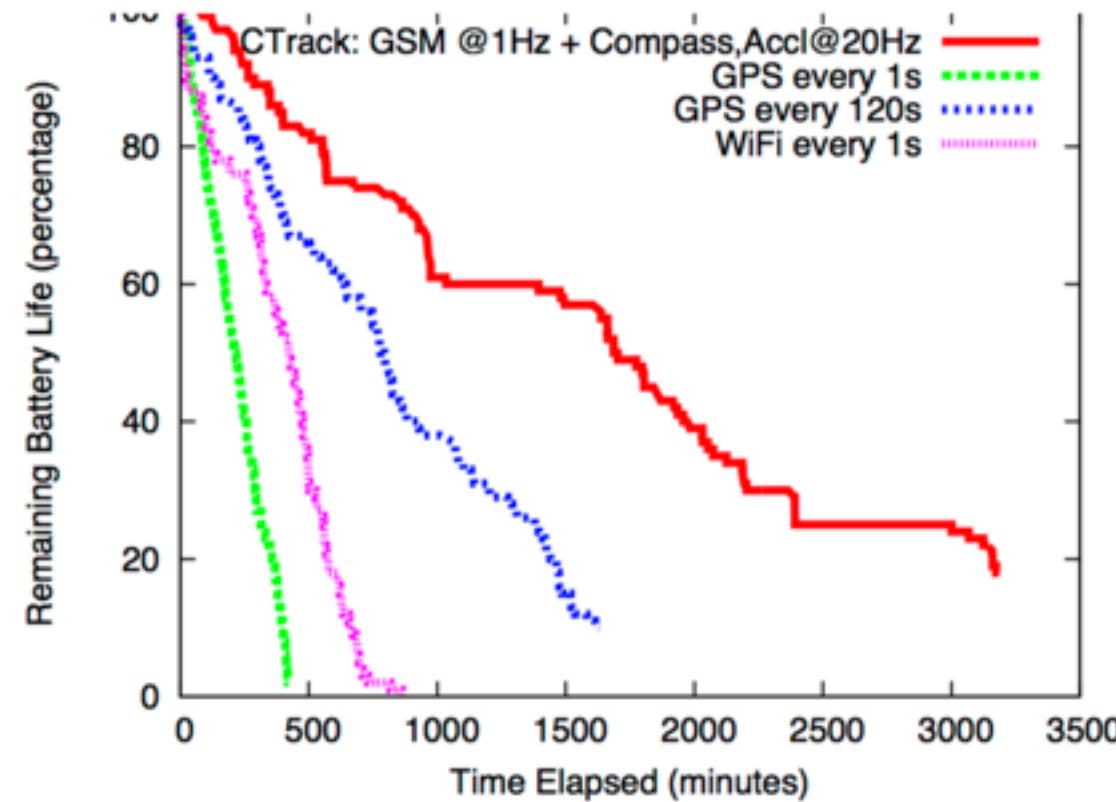
Certain classes of devices experience failures

Discover CBCharacteristic for CBService misses a few characteristics

412 Views 15 Replies Latest reply: Sep 29, 2015 2:05 AM by masakazu

# Map-matching

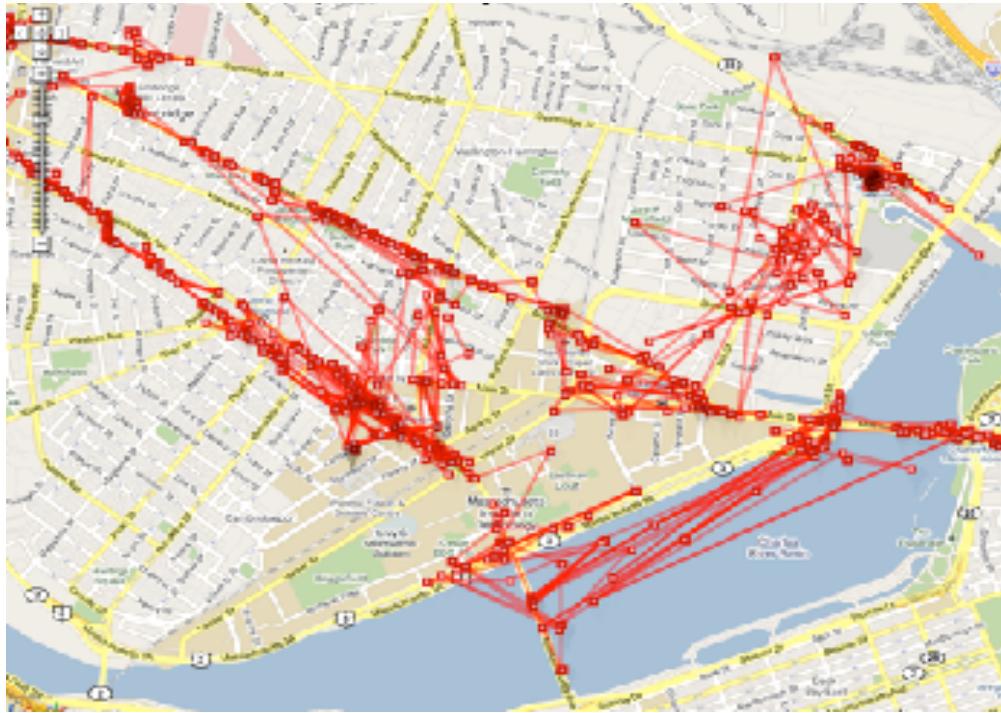
Tradeoff between accuracy and energy



# VTrack & CTrack Map-Matching Methods

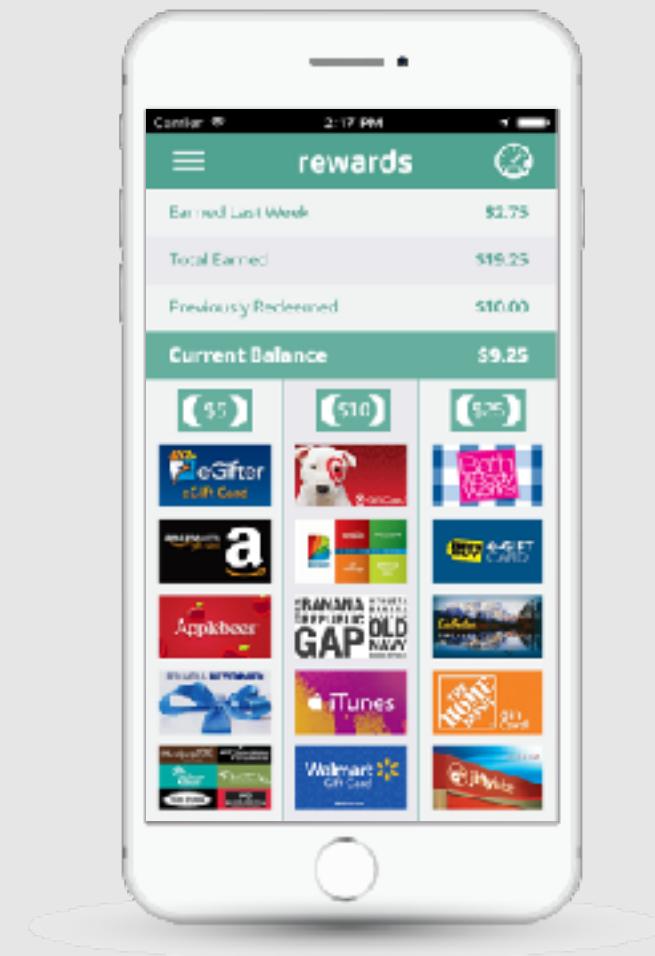
Tradeoff between accuracy and cost

*To this...*



*From this...*





## Rewards

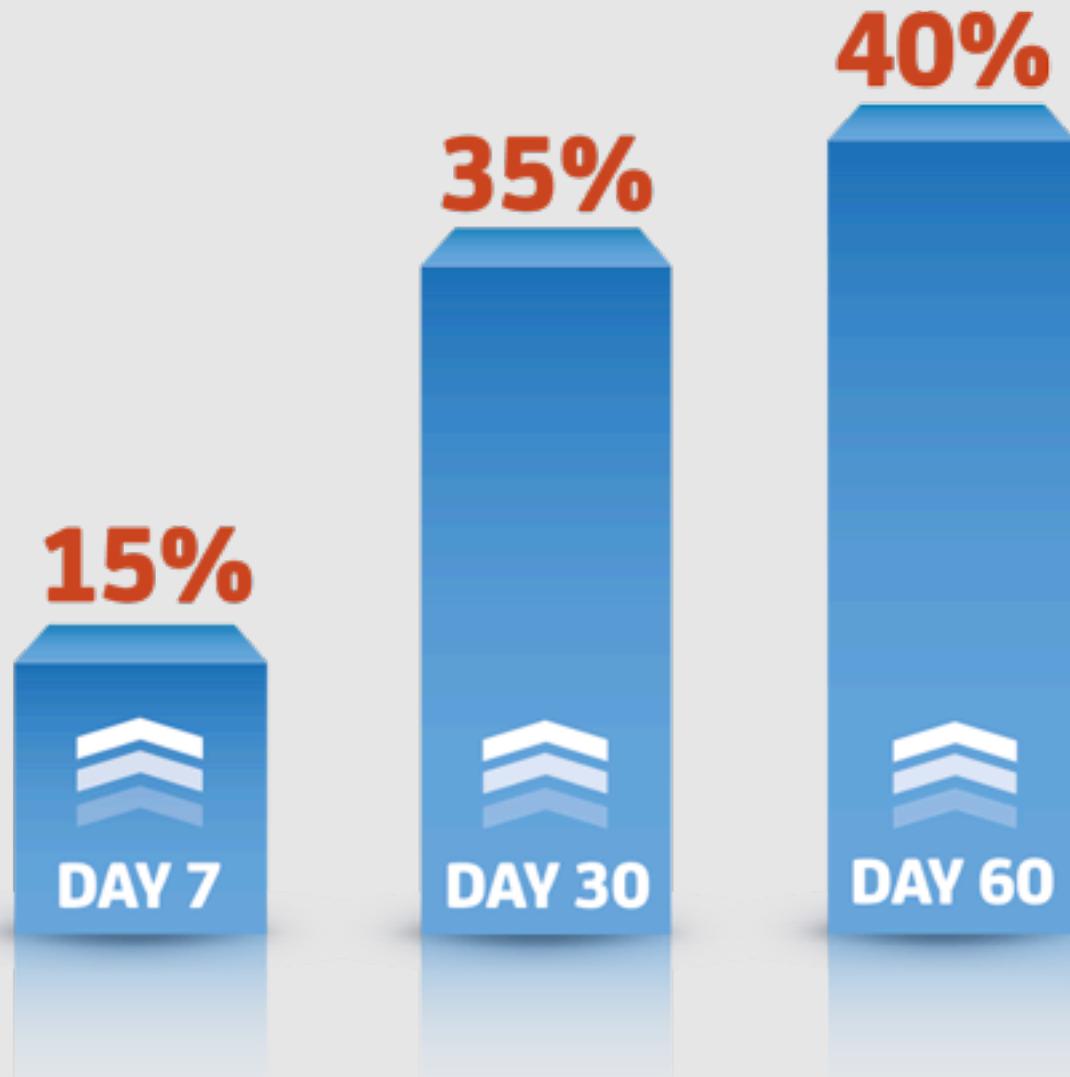
A white smartphone is shown from a slightly elevated angle, displaying a mobile application's contests section. The top part of the screen shows a banner for 'SINGAPORE'S BEST DRIVER CHALLENGE'. Below the banner, there is a section titled 'DO YOU THINK YOU'RE A GOOD DRIVER?' with a list of challenges. The bottom part of the screen shows a banner for 'BOSTON'S SAFEST DRIVER COMPETITION'.

## Contests

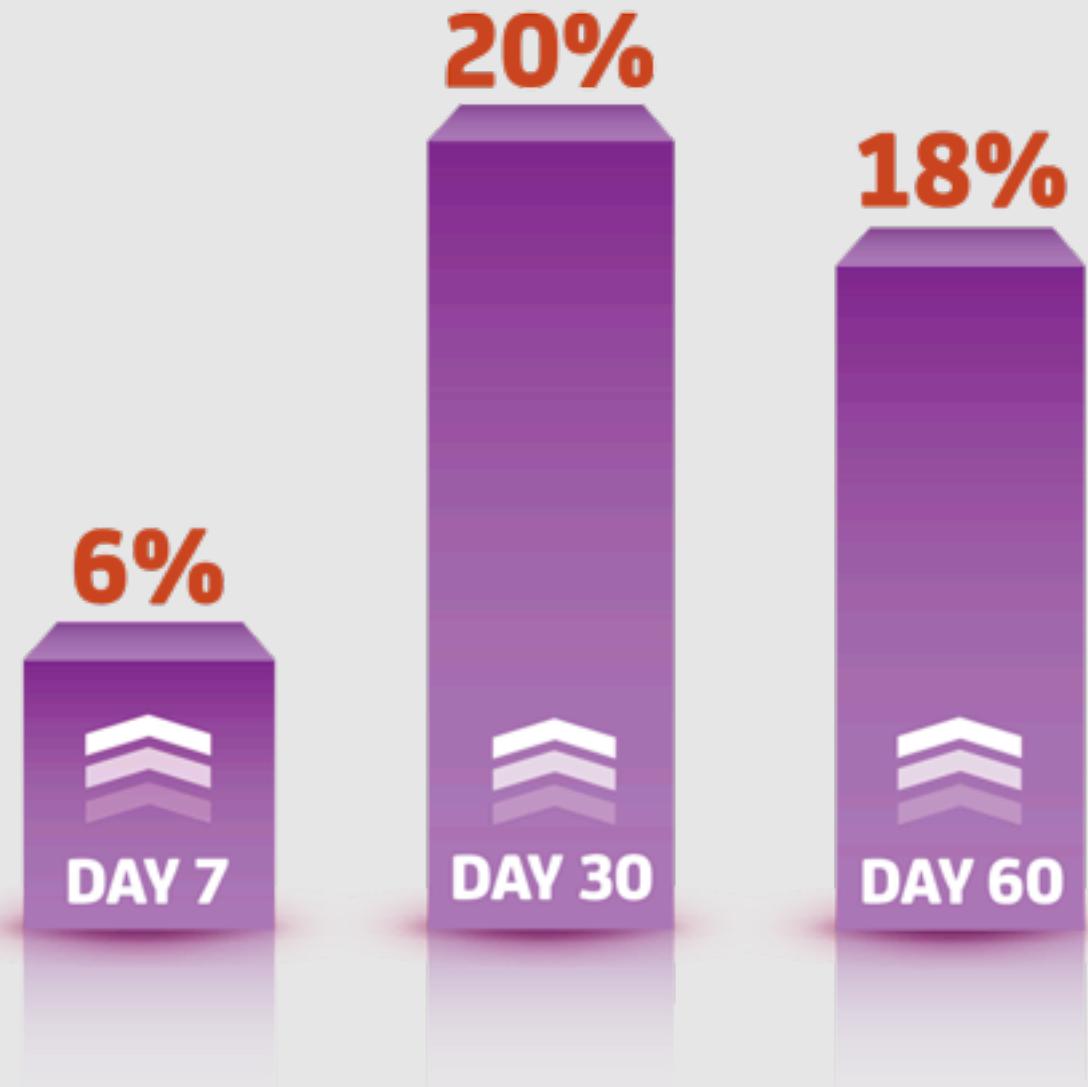
Two white smartphones are shown side-by-side, both displaying mobile application leaderboards. The left phone shows a 'leaderboards' screen for 'State Ranking' with a table of top drivers and their scores. The right phone shows an 'Achievements' screen with a grid of shield icons, each representing a different achievement like 'SAFEST DRIVER' or 'LONGEST TRIP'.

## Leaderboards & Social Features

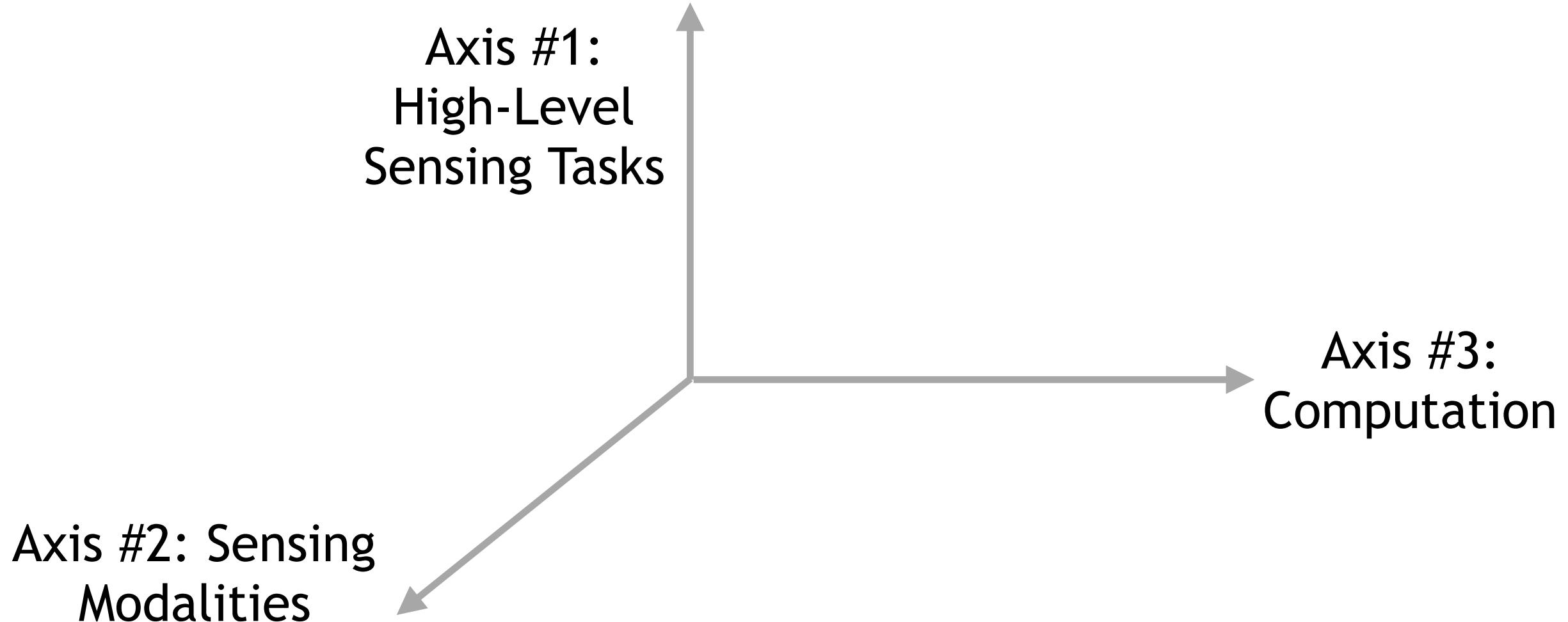
## Reduction in Phone Distraction after Enrolling in DriveWell



## Reduction in Hard Braking after Enrolling in DriveWell



# IoT Systems are designed along 3 main axes



# Axis #1: High-Level Sensing Tasks

WHAT do we want to sense?

## (1) Location



- Outdoors, indoors
- Humans, objects

## (2) Dynamics



- Velocity, Acceleration
- Activities, Monitoring

## (3) Properties



- Identify, Characterize
- Environment, Humans

# Axis #2: Sensing Modalities

HOW will we perform this sensing?

(1) Radio



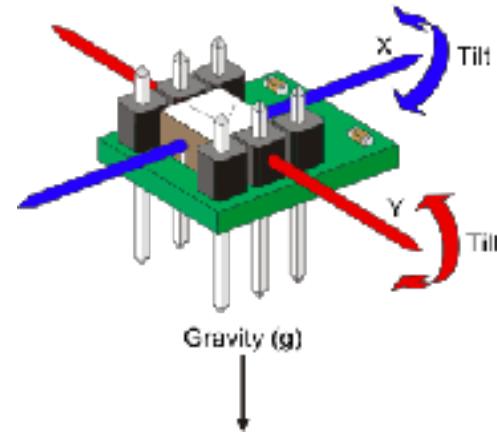
- Wi-Fi
- Cellular
- Bluetooth

(2) Acoustic/  
Ultrasonic



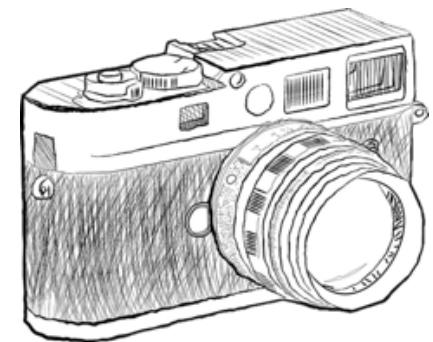
- Voices
- Engines
- Animals

(3) Inertial



- Gyroscope
- Accelerometer

(4) Visual



- Camera
- Infrared
- LIDAR

And many others: pressure, temperature, etc.

# Axis #3: Computation

HOW can we use the sensing modalities to achieve the sensing task?

## (1) Networking



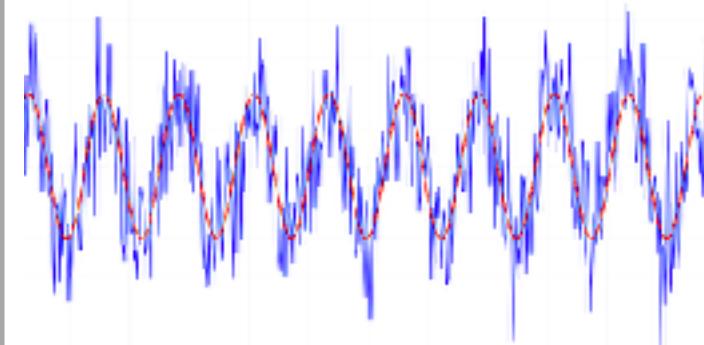
- Connectivity
- Communication

## (2) Data Management



- Storage
- Queries

## (3) Signal Processing & Inference



- Digitization
- Inference & Machine Learning

## (4) Security



- Digital, Analog
- Trust, Privacy

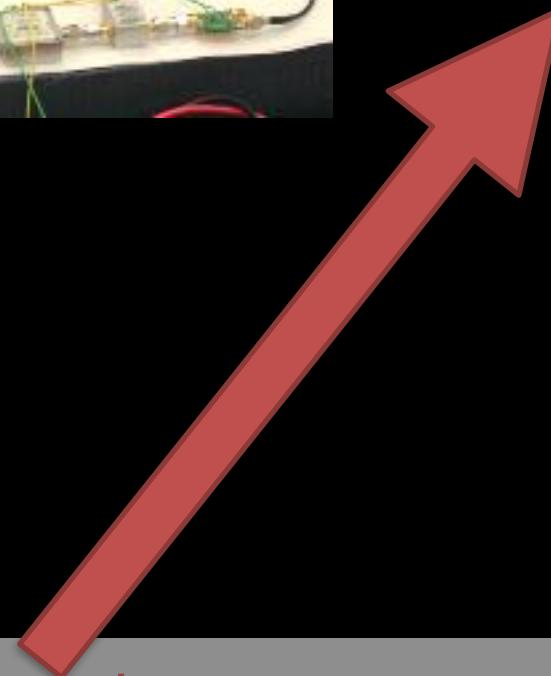
# IoT System Architecture

Axis #1: Sensing Tasks	(1) Location	(2) Dynamics	(3) Properties
Axis #3: Computation	(1) Networking	(2) Data Management	(3) Signal Processing & Inference  (4) Security
Axis #2: Sensing Modalities	(1) Radio	(2) Acoustic/Ultrasonic	(3) Inertial  (4) Visual

# Indoor Positioning (Cricket, 2001)

# Accurate Localization (Cricket, 2003)

# Device-Free Localization (WiTrack, 2014)

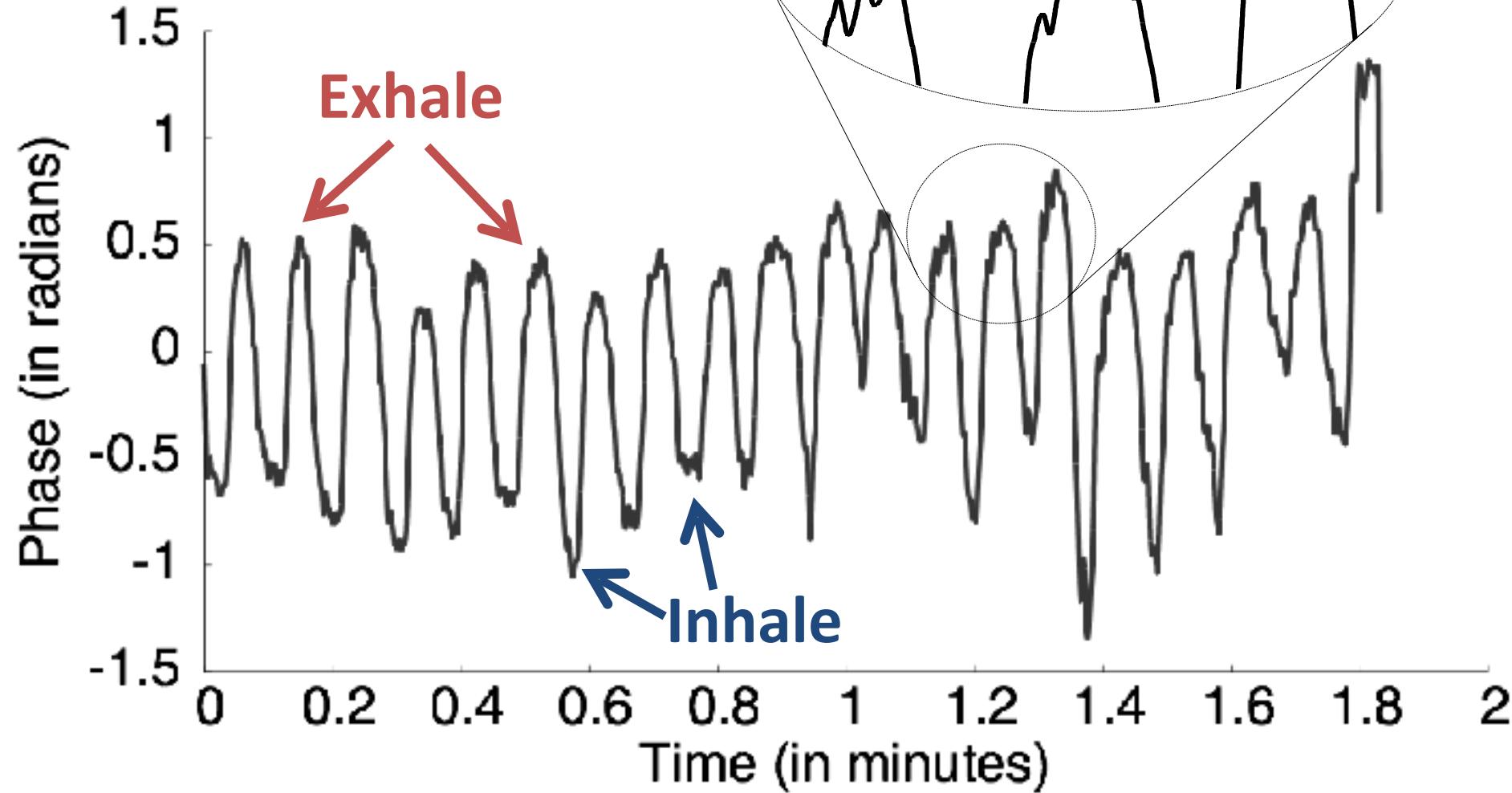


Device in another room

# Seeing Through Walls (RF-Capture, 2015)

# Breath Monitoring using Wireless (Vital-Radio, 2015)

Let's zoom in on these signals



# Baby Monitoring

# Mobile Security

## Case Study: Inaudible Voice Commands

# Fundamental Constraints

- Noise
- Faults
- Energy (battery, power)
- Communication bandwidth
- Processing on “leaf” nodes (sensors)
- Security is harder than with datacenter servers
  - In uncontrolled areas, act as “servers” providing data, resource-constrained nodes, physical attacks, ...

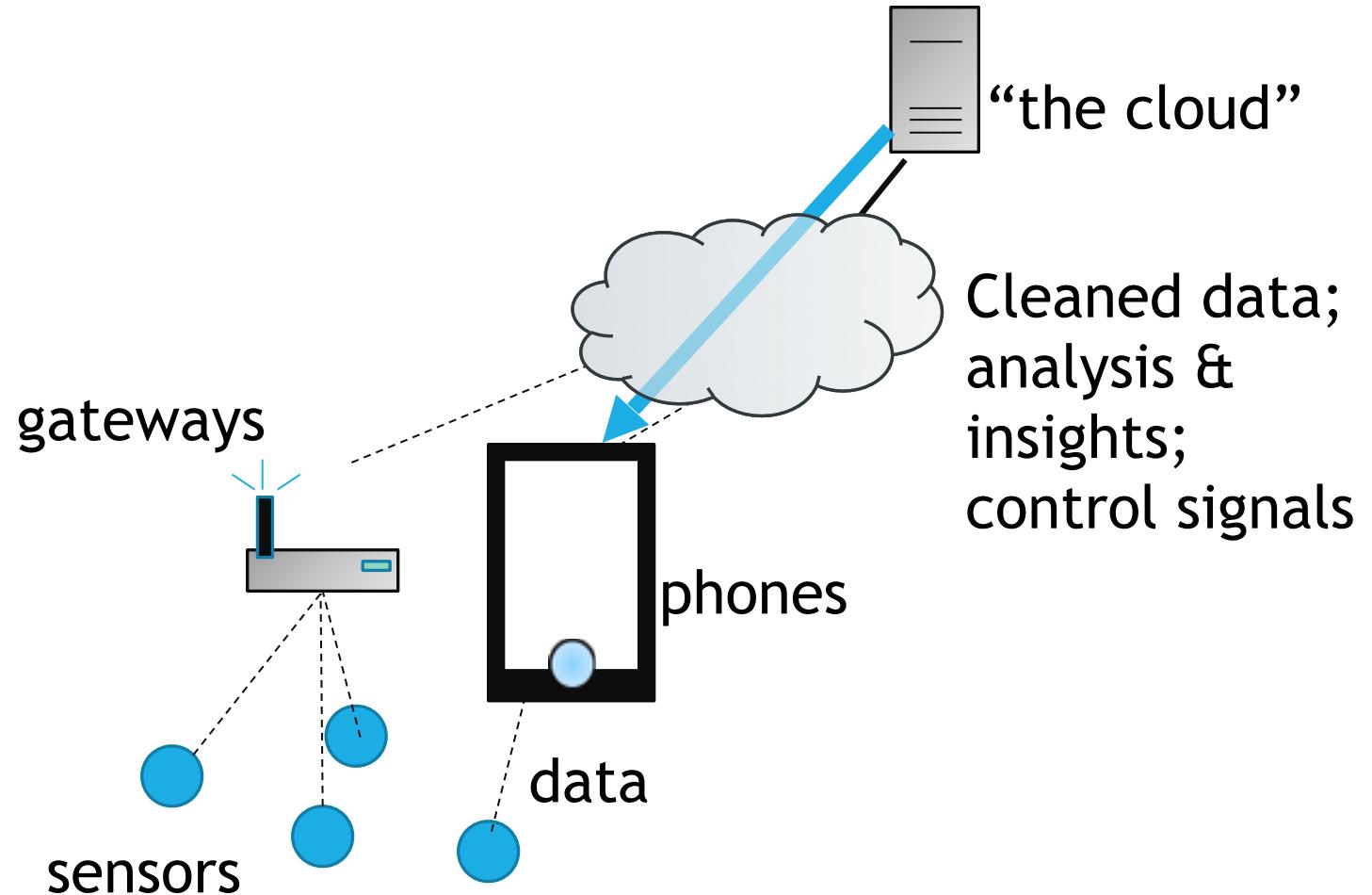
# Canonical IoT System Architecture

Data path: sensors → phones/  
basestations → cloud

Sensors use low-power (BLE,  
Zigbee) wireless

Phones and gateways use WiFi,  
cellular, or wired Internet links

Processing happens on sensors,  
basestations, phones, and cloud



# Power used by some common components

Component	Approximate Power Consumption
LTE Radio (transmit @ 1 Mb/s)	1700 mW
3G Radio (transmit @ 1 Mb/s)	1700 mW
WiFi (transmit @ 1Mb / s)	400 mW
ARM+RAM uProc (100% cpu)	2000 mW
ARM+RAM uProc (idle)	70 mW
Smartphone Screen (full brightness)	850 mW
GPS (once lock is acquired)	100-150 mW
Accelerometer (@10 Hz)	75 uW
Image sensor (@1080p/30Hz)	270 mW (Sony IMX206CQC)

# Split Processing

Case Study: Continuous Object Recognition

# Continuous Object Recognition (Glimpse, 2015)

All processing done on server

With Glimpse with on-phone object tracking

# End-to-end IoT System

## Case Study: Precision Agriculture

# Course Logistics

Grading:

- 1 Course Project (40%)
- 1 Quiz: April 24, during lecture (25%)
- 4+1 Labs (25%)
- Participation (10%)
  - Includes answering questions before every lecture

Website: <https://6s062.github.io/6MOB/index.html>

Piazza: Ask questions about lectures, labs, etc.

Late lab policy: 72 hours

This Friday: iOS Tutorial (2.30-4PM in 26-168)

Monday	Tuesday	Wednesday	Thursday	Friday
Feb 6 Reg day	Feb 6 <b>LEC 1:</b> Introduction and Course Overview First day of classes	Feb 7	Feb 8 <b>LEC 2:</b> Intro to Positioning and Indoor Location Systems <b>Preparation:</b> Read Cricket, Location-based Services, Chapter 6 <b>Assigned:</b> Lab 0	Feb 9
Feb 12	Feb 13 <b>LEC 3:</b> GPS; Outdoor Location <b>Preparation:</b> Read GPS <b>Assigned:</b> Lab 1 <b>DUE:</b> Lab 0	Feb 14	Feb 15 <b>LEC 4:</b> Indoor Location with RF <b>Preparation:</b> Read RADAR, WiTrack	Feb 16
Feb 19 President's day	Feb 20 Monday schedule	Feb 21	Feb 22 <b>LEC 5:</b> Connectivity Overview and BLE	Feb 23
Feb 26	Feb 27 <b>LEC 6:</b> Mesh and Multi-Hop Wireless Networks <b>Preparation:</b> Read ETX <b>Assigned:</b> Lab 2 <b>DUE:</b> Lab 1	Feb 28	Mar 1 <b>LEC 7:</b> Intro to Inertial Sensing and Activity Recognition <b>Preparation:</b> Read Developments of Inertial Sensing, Principles of Inertial Sensing, Activity Recognition	Mar 2
Mar 5	Mar 6 <b>LEC 8:</b> Pothole detection <b>Preparation:</b> Read Pothole Patrol	Mar 6	Mar 8 <b>LEC 9:</b> Wireless sensing <b>Preparation:</b> Read Vital-Radio	Mar 9
Mar 12	Mar 13 <b>LEC 10:</b> In-network Aggregation <b>Preparation:</b> Read TAG <b>DUE:</b> Project Proposals	Mar 14	Mar 15 <b>LEC 11:</b> Agriculture IoT <b>Preparation:</b> Read FarmBeats	Mar 16
Mar 19	Mar 20 Project meetings <b>Assigned:</b> Lab 3 <b>DUE:</b> Lab 2	Mar 21	Mar 22 <b>LEC 12:</b> Map-matching with cellular data <b>Preparation:</b> Read CTrack	Mar 23
Mar 26 Spring break	Mar 27 Spring break	Mar 28 Spring break	Mar 29 Spring break	Mar 30 Spring break
Apr 2	Apr 3 <b>LEC 13:</b> Map Inference <b>Preparation:</b> Read Map Inference	Apr 4	Apr 5 <b>LEC 14:</b> Shooter localization <b>Preparation:</b> Read Sensor Network-Based Countersniper System <b>Assigned:</b> Lab 4 <b>DUE:</b> Lab 3	Apr 6
Apr 9	Apr 10 <b>LEC 15:</b> Attacks on acoustic sensing <b>Preparation:</b> Read BackDoor	Apr 11	Apr 12 <b>LEC 16:</b> Habitat monitoring with acoustic sensors <b>Preparation:</b> Read VoxNet	Apr 13
Apr 16 Patriots' day	Apr 17 Patriots' day	Apr 18	Apr 19 <b>LEC 17:</b> Continuous object recognition <b>Preparation:</b> Read Glimpse <b>DUE:</b> Lab 4	Apr 20
Apr 23	Apr 24 Quiz during lecture time	Apr 25	Apr 26 Project meetings <b>DROP DATE</b>	Apr 27
Apr 30	May 1 Project meetings	May 2	May 3 Project meetings	May 4
May 7	May 8 Project meetings	May 9	May 10 Project meetings <b>DUE:</b> Project Titles and Abstracts	May 11
May 14	May 15 Project meetings	May 16	May 17 Project presentations <b>DUE:</b> Posters, Presentations, and Demos <b>Last day of classes</b>	May 18