

the
Pothole Patrol

6.S062 3/22/2017
Based on Slides from
Jakob Eriksson

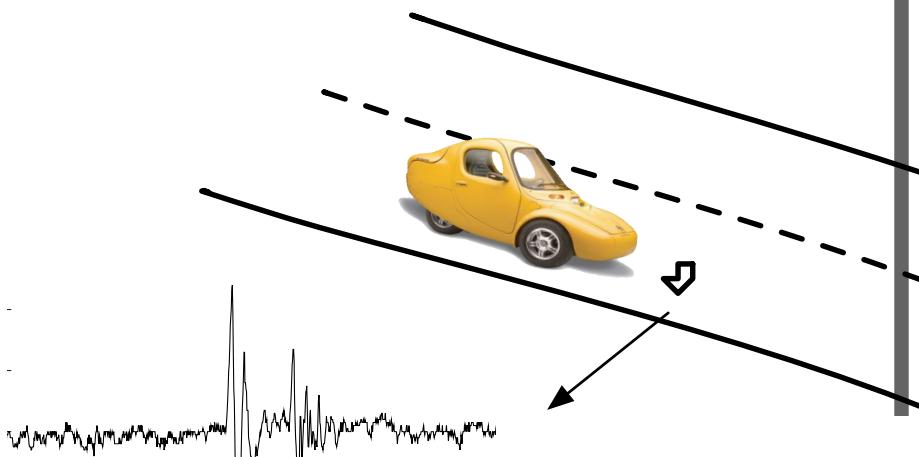


- road decay unavoidable, hard to predict
- current monitoring methods costly/ineffective

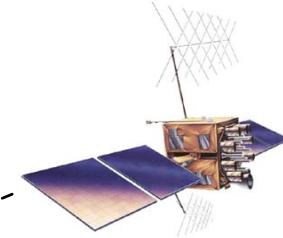
the Pothole Patrol

GPS localization

opportunistic accelerometer sensing



GPS
localization



opportunistic data upload

central aggregation
and reporting



P2 Central
Server

'Pothole
detected at ...'



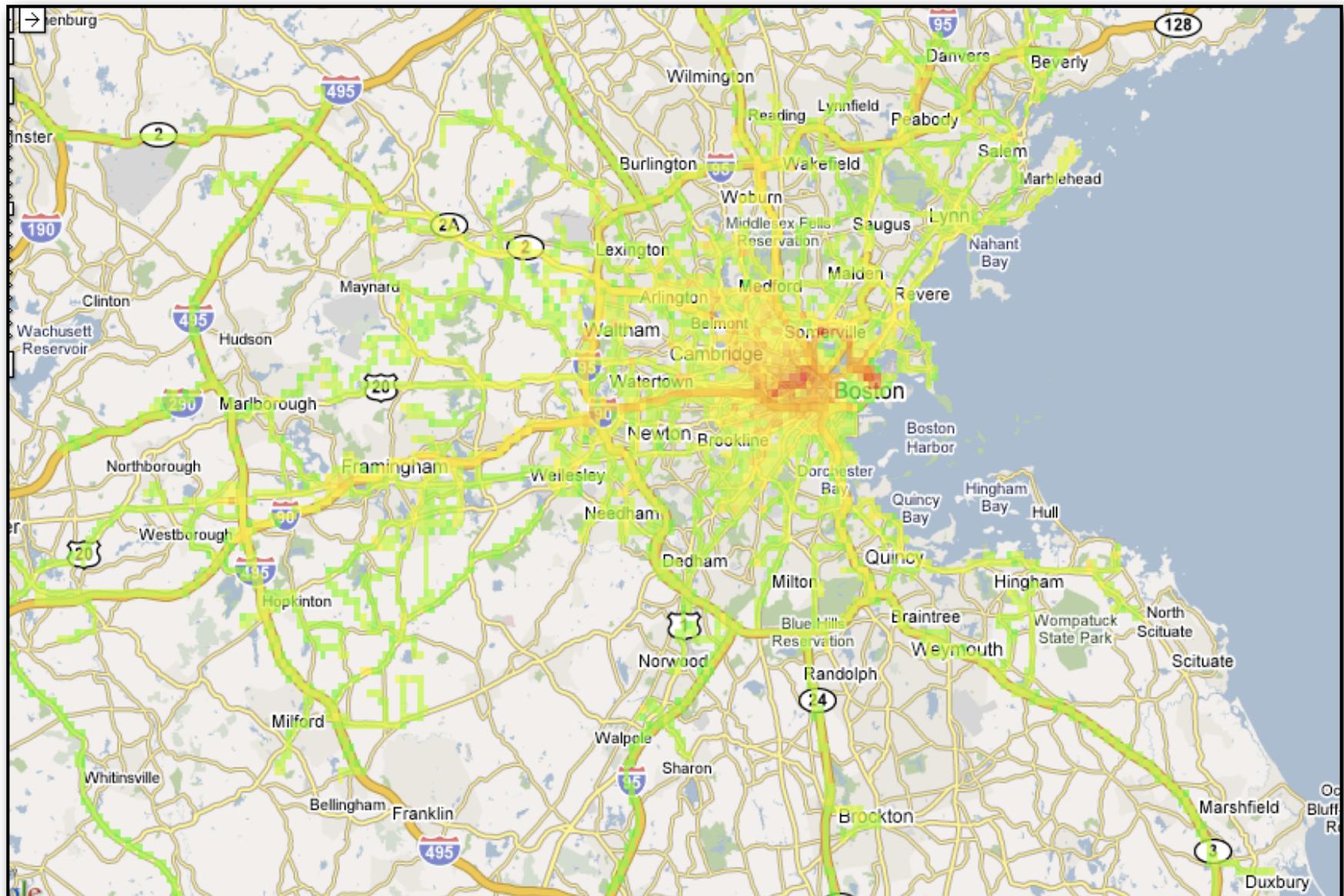
Open WiFi
Access Point

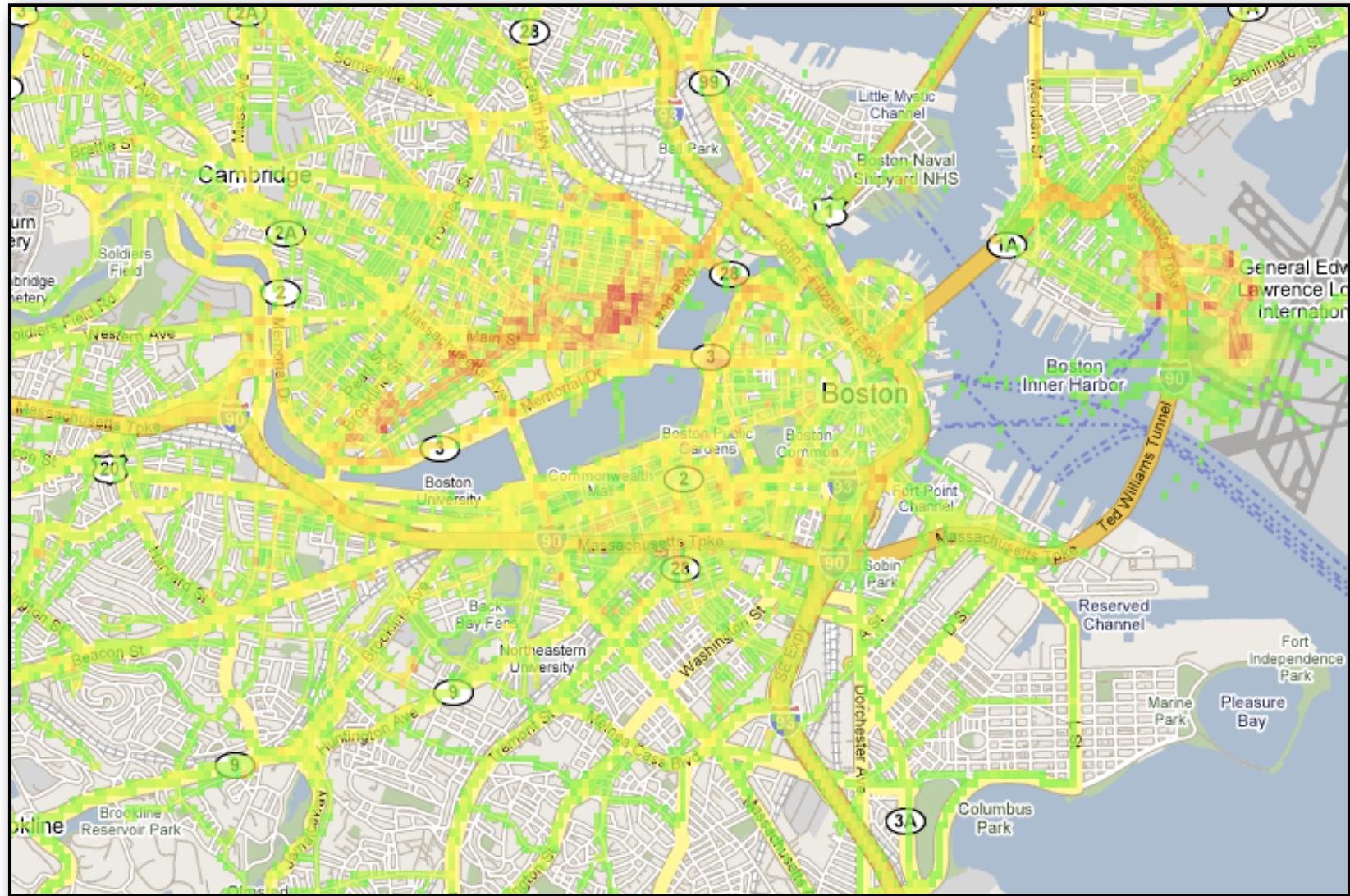
experimental platform

- 7 Boston/Cambridge taxis
- small computer in glove box
- 400 Hz 3-axis accelerometer
- 802.11a/b/g wireless interface
- GPS receiver on roof

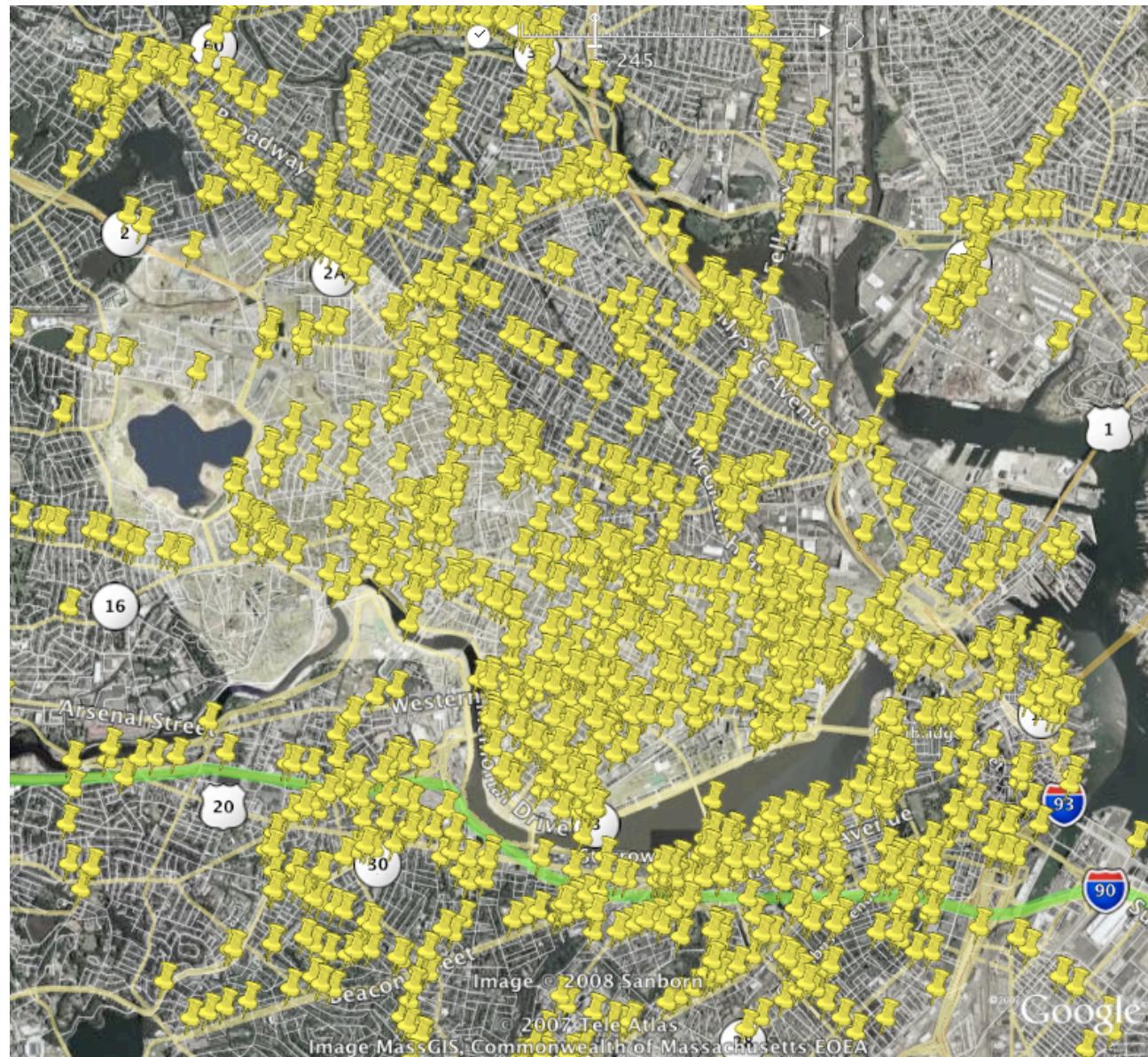


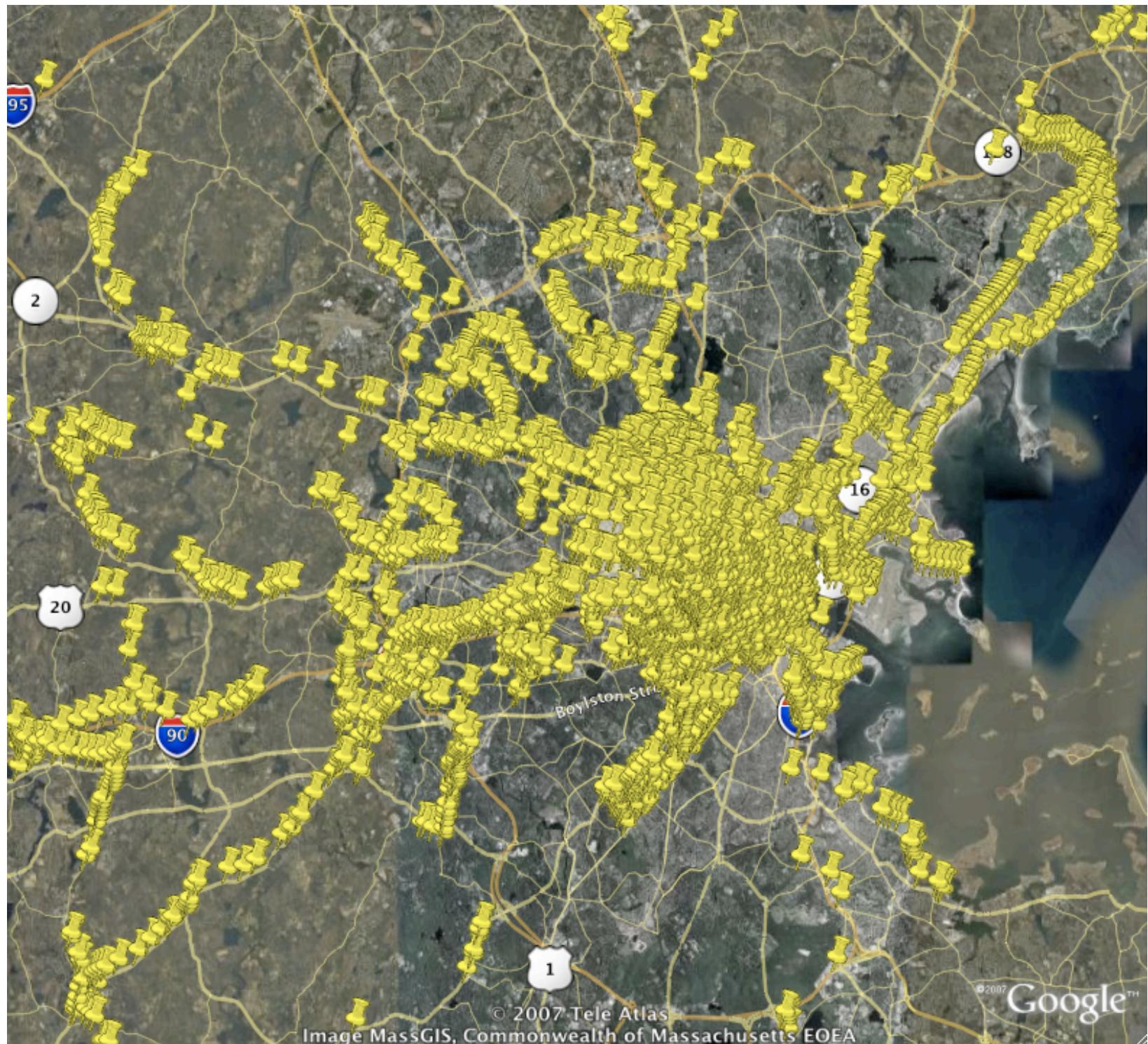
wide-area sensing



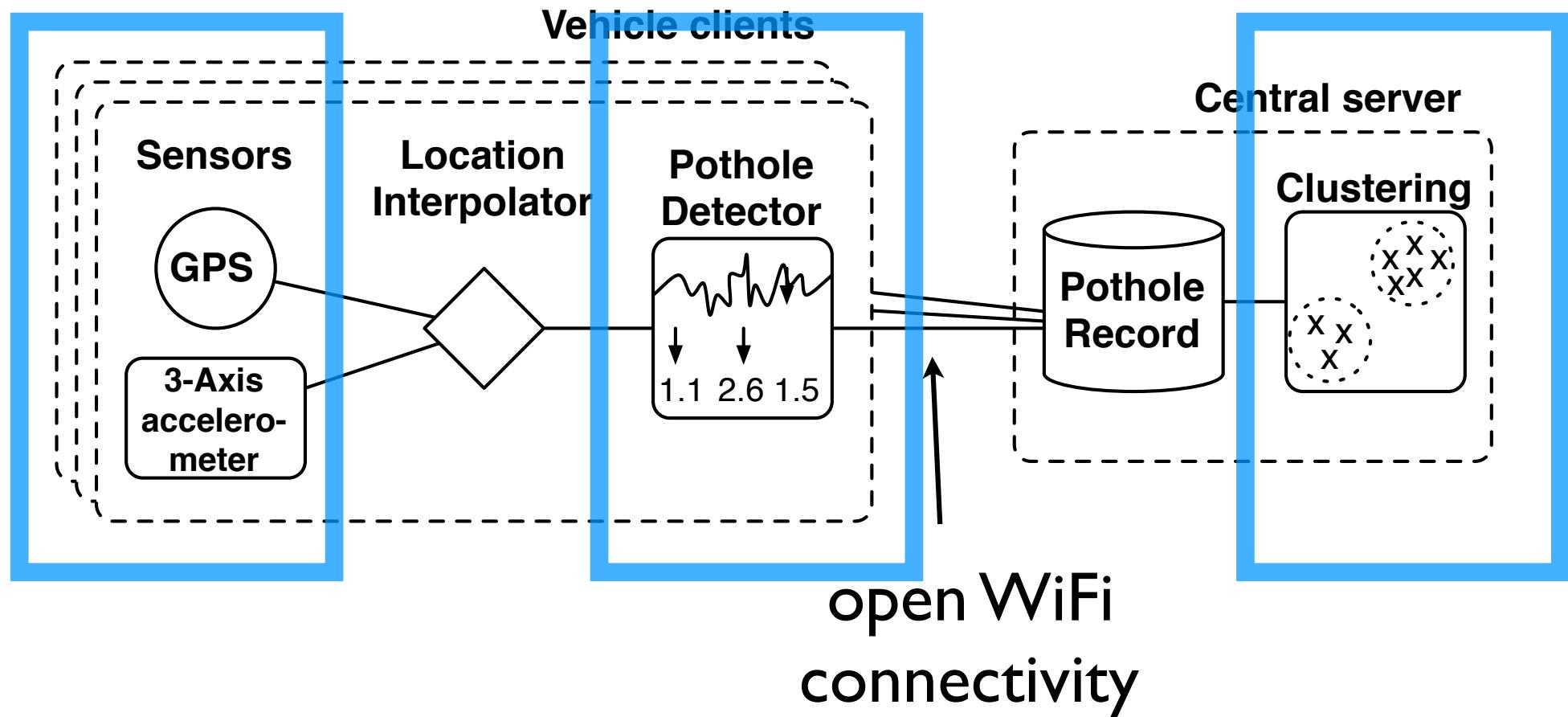


open WiFi connectivity





P² architecture



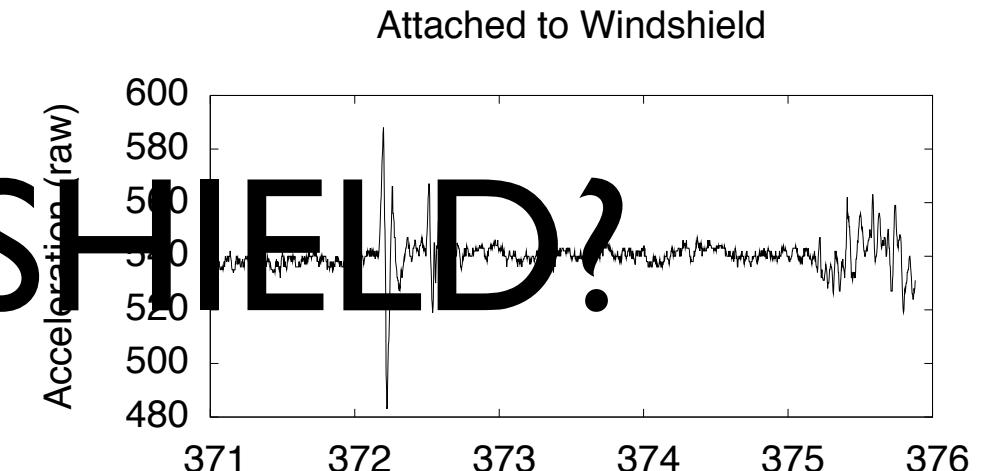
sensor placement



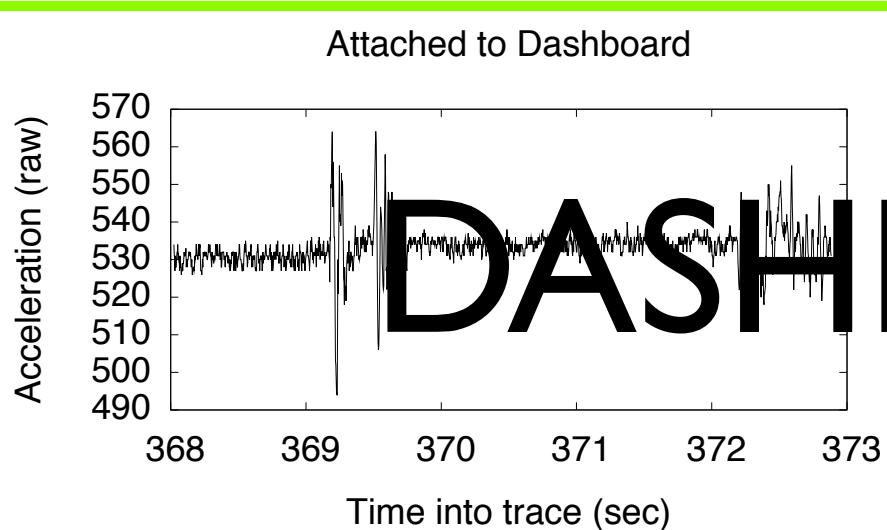
try to stay
inside vehicle

- highly accurate
- difficult mounting
- extreme exposure

- very clean signal
- ‘gold standard’
- difficult to mount



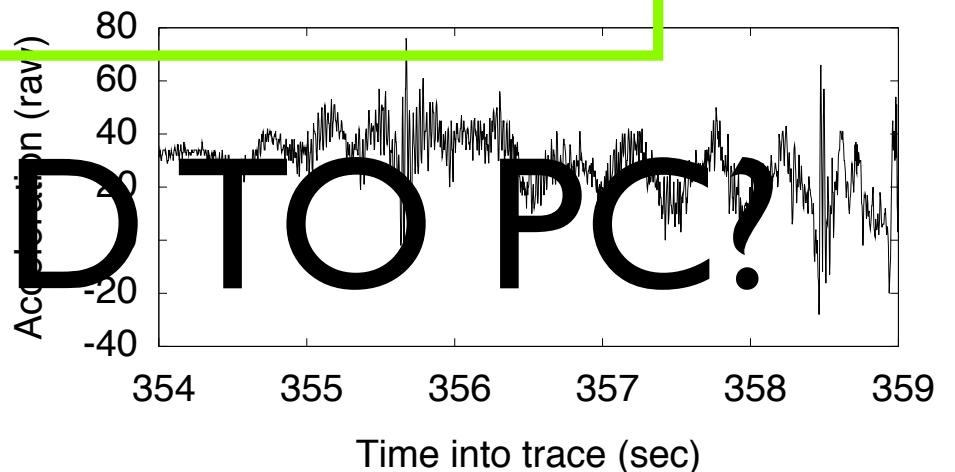
Attached to Dashboard



Time into trace (sec)

- good signal
- easy to mount
- out of the way

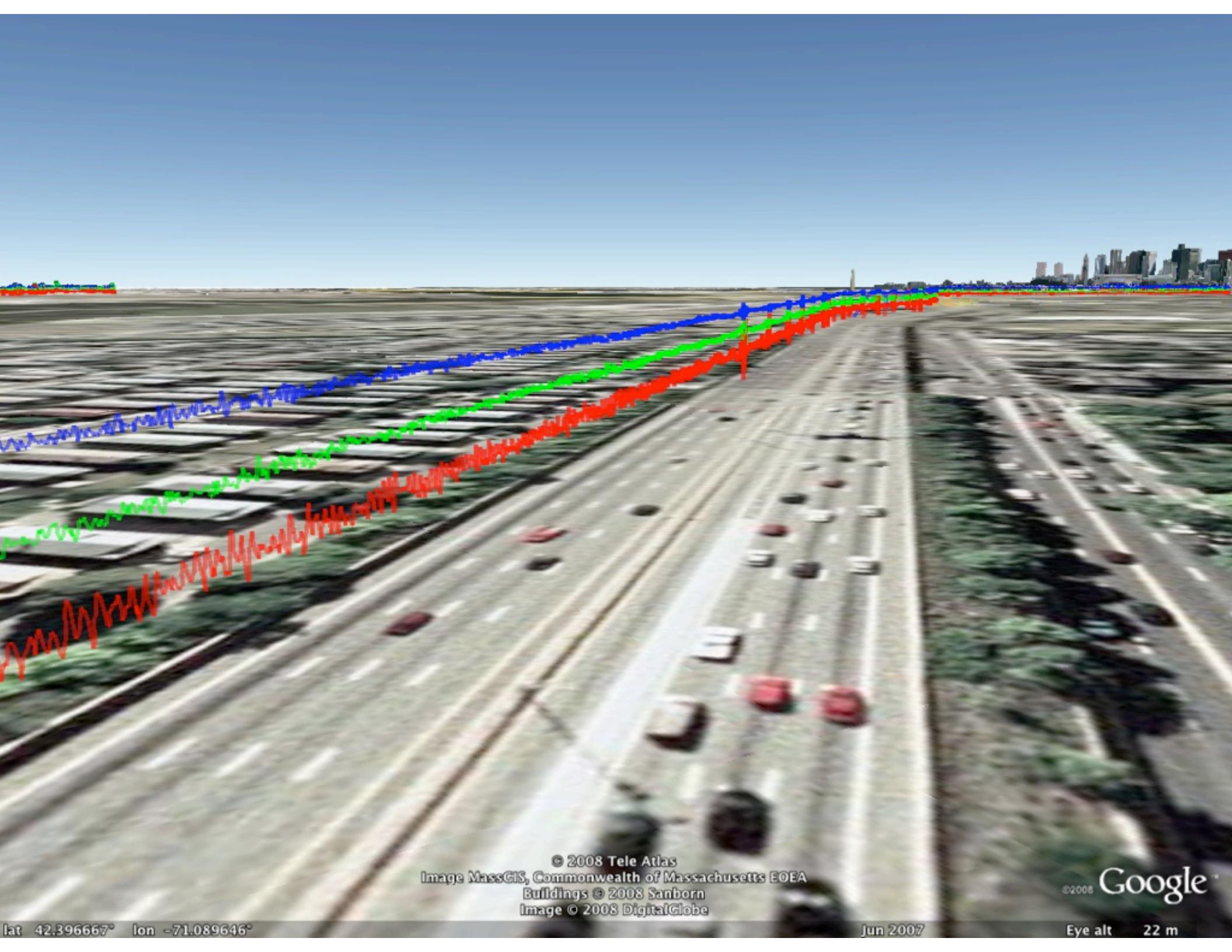
Attached to Embedded PC



- very poor signal
- no mounting necessary

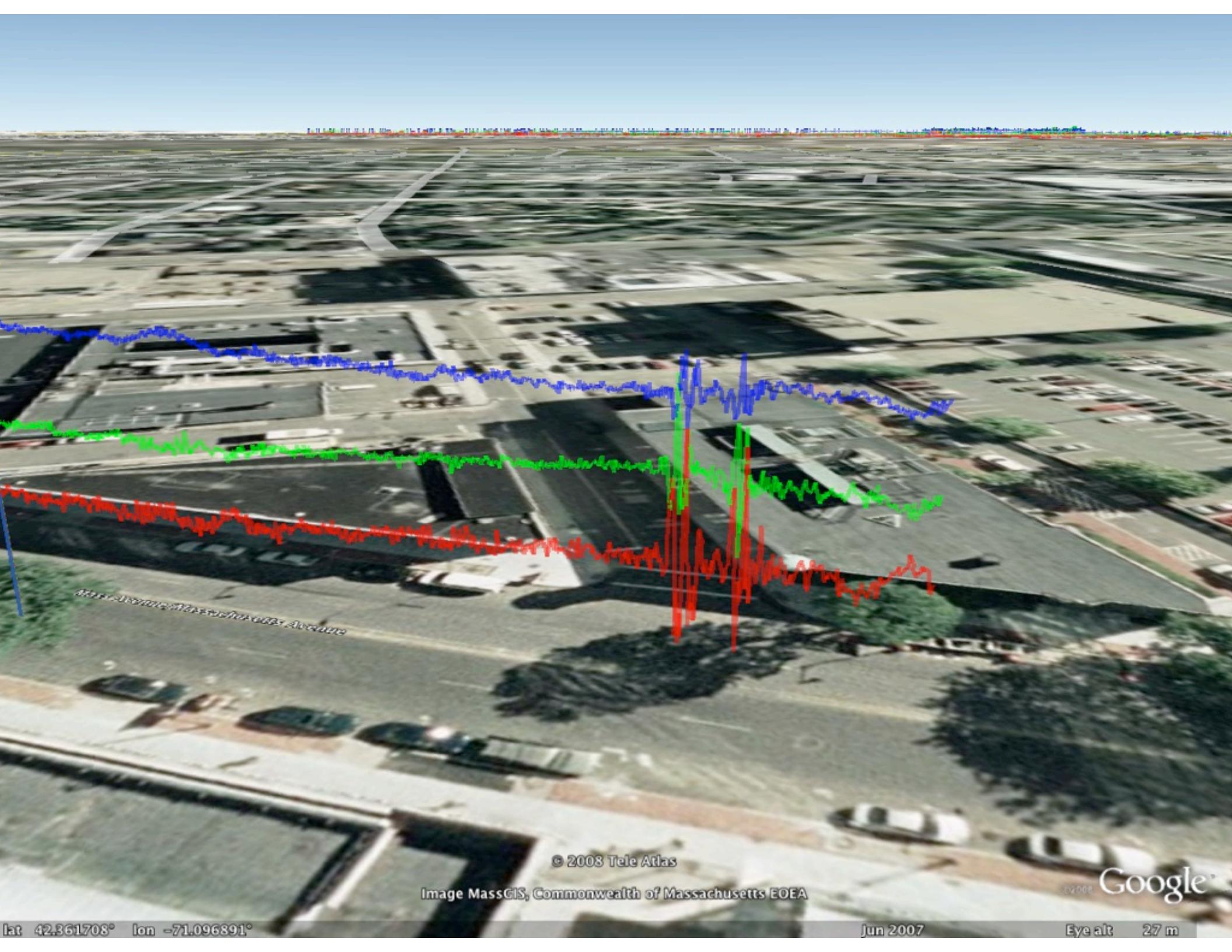
crowd-pleasing
graphics

CONTINUE



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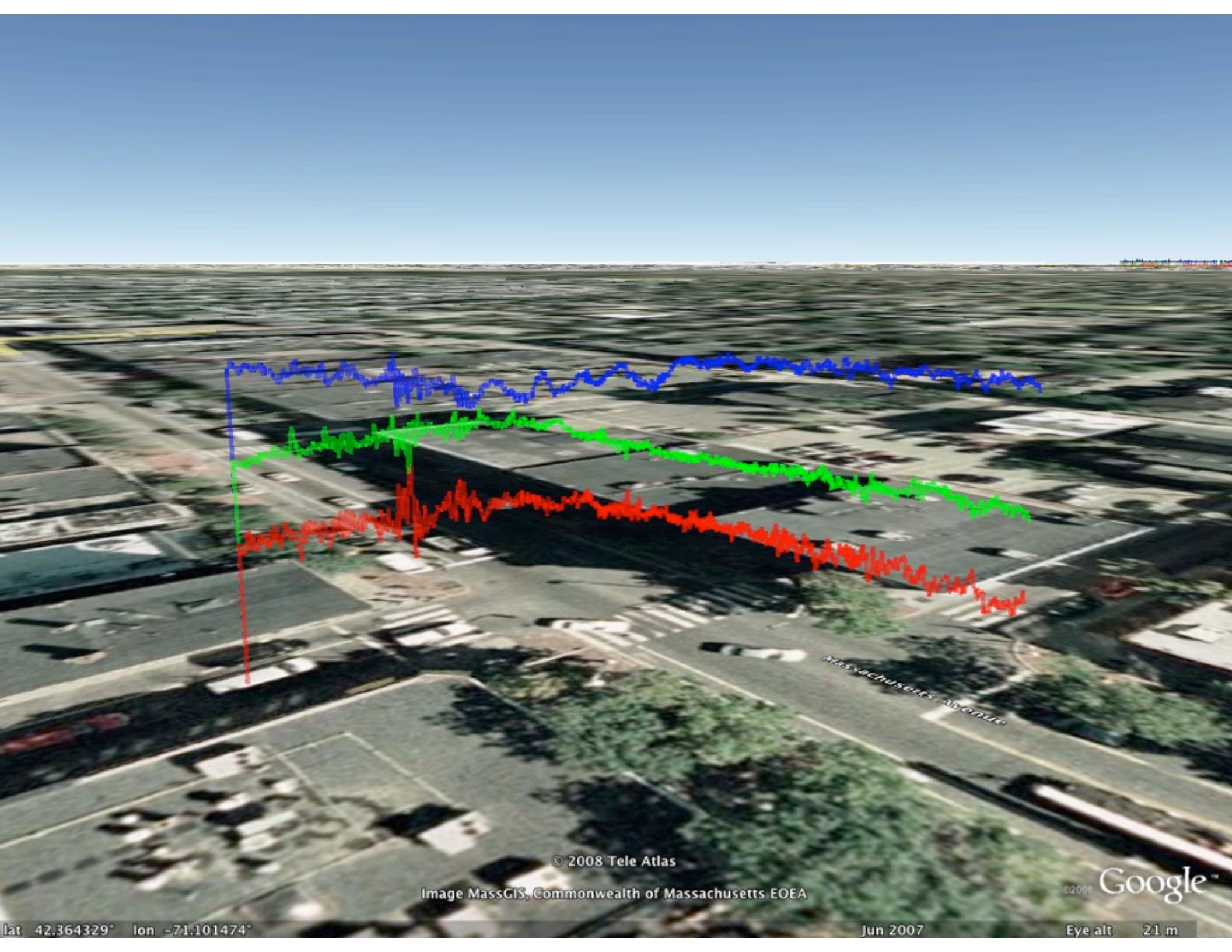
Image MassGIS, Commonwealth of Massachusetts EOEA

Google

lat 42.361708° lon -71.096891°

Jun 2007

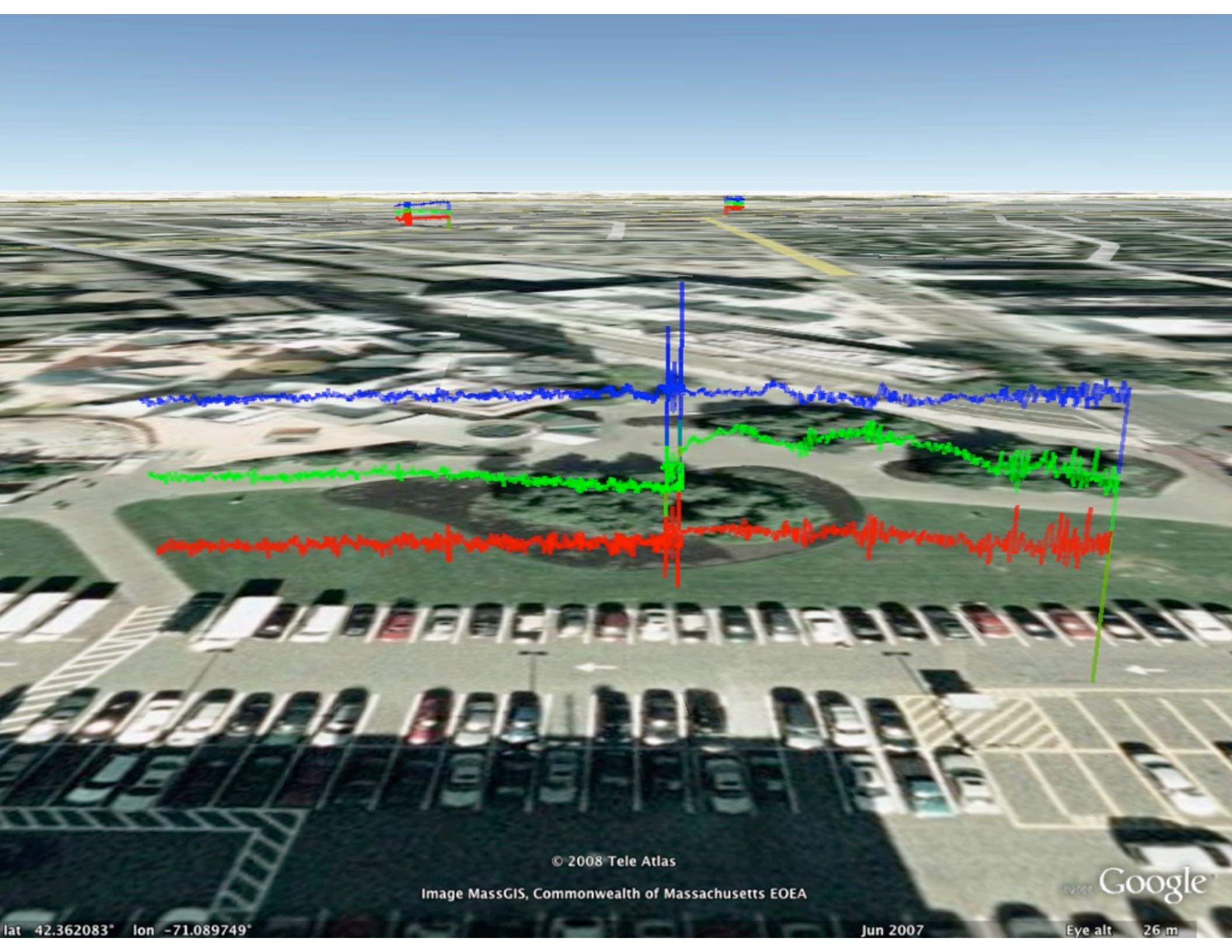
Eye alt 27 m



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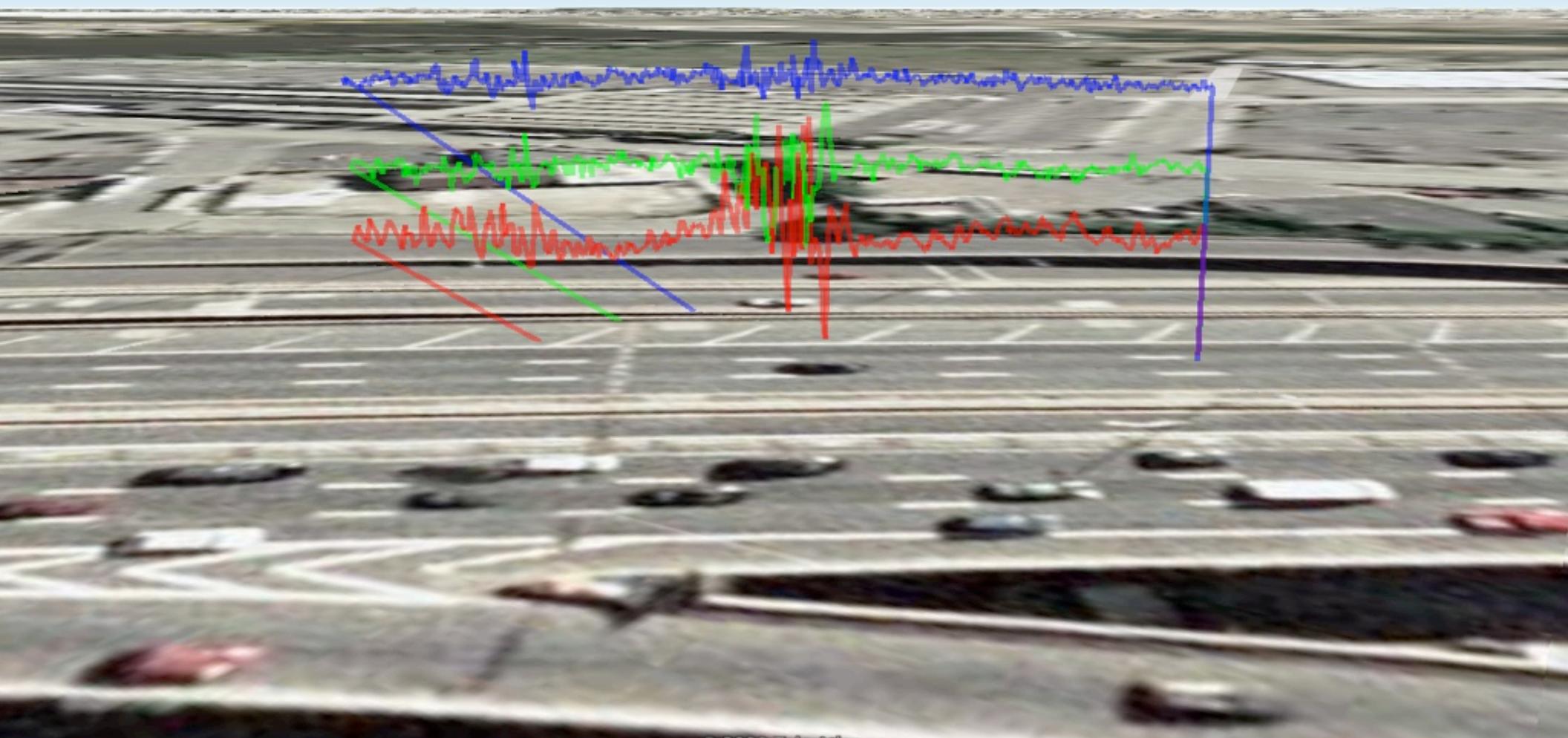
Image MassGIS, Commonwealth of Massachusetts EOEA

Google

lat 42.362083° lon -71.089749°

Jun 2007

Eye alt 26 m



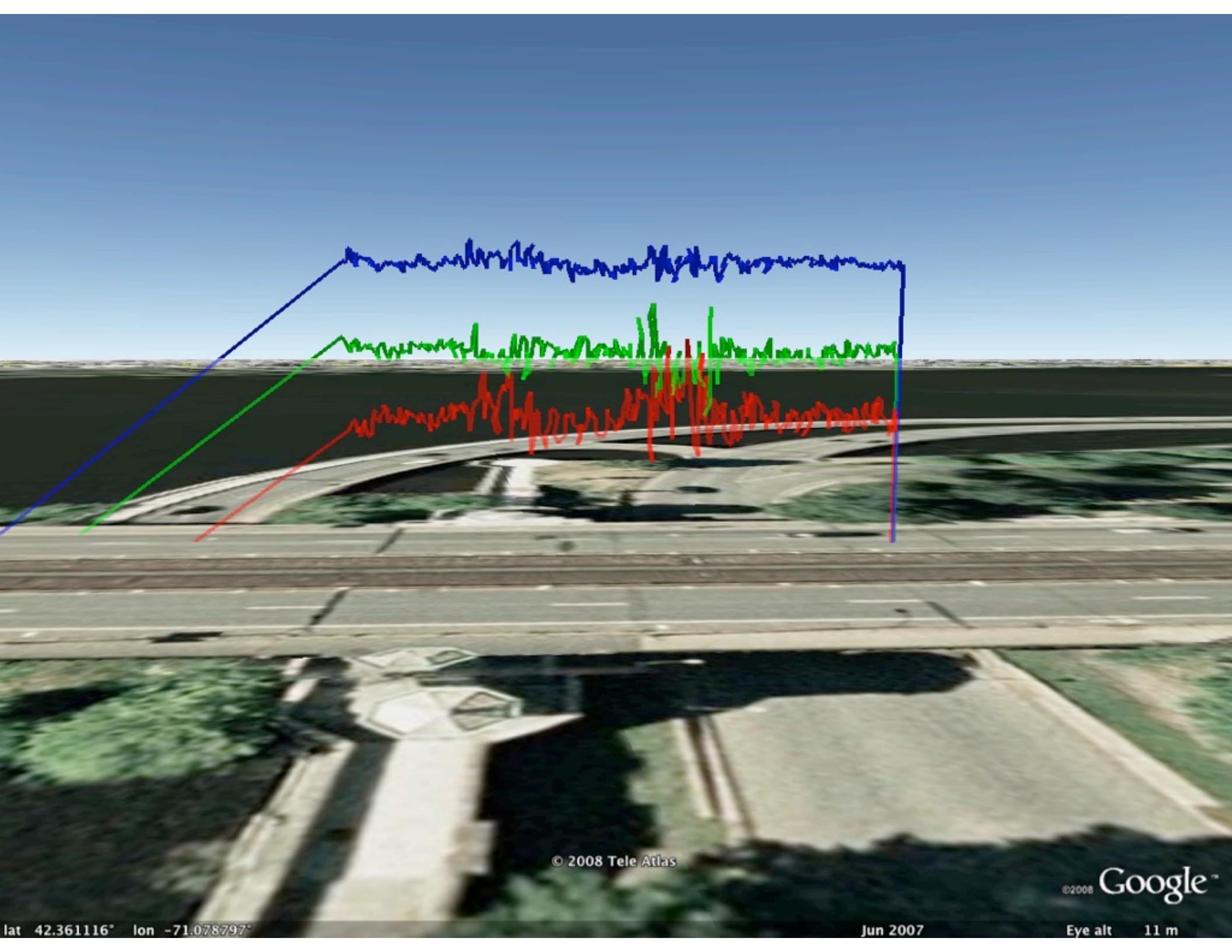
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lat 42.392652° lon -71.084025°

Google

Eye alt 21 m



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lat 42.361116° lon -71.078797°

Jun 2007

Eye alt 11 m

P² detector

256-sample
windows →

need
threshold
parameters



training the detector

- manually label training samples

Type	Count	Percentage
Smooth road (SM)	64	23%
Potholes (PH)	63	23%
Manholes (MH)	59	21%
Railroad Crossing (RC)	18	6%
Crosswalk/Exp. Joint (CWEJ)	76	27%

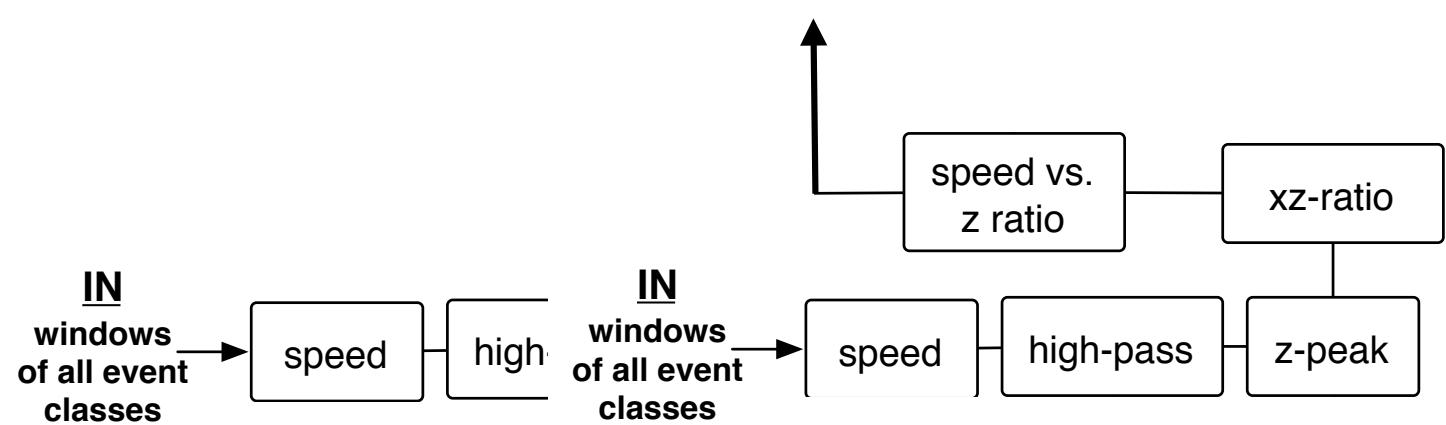
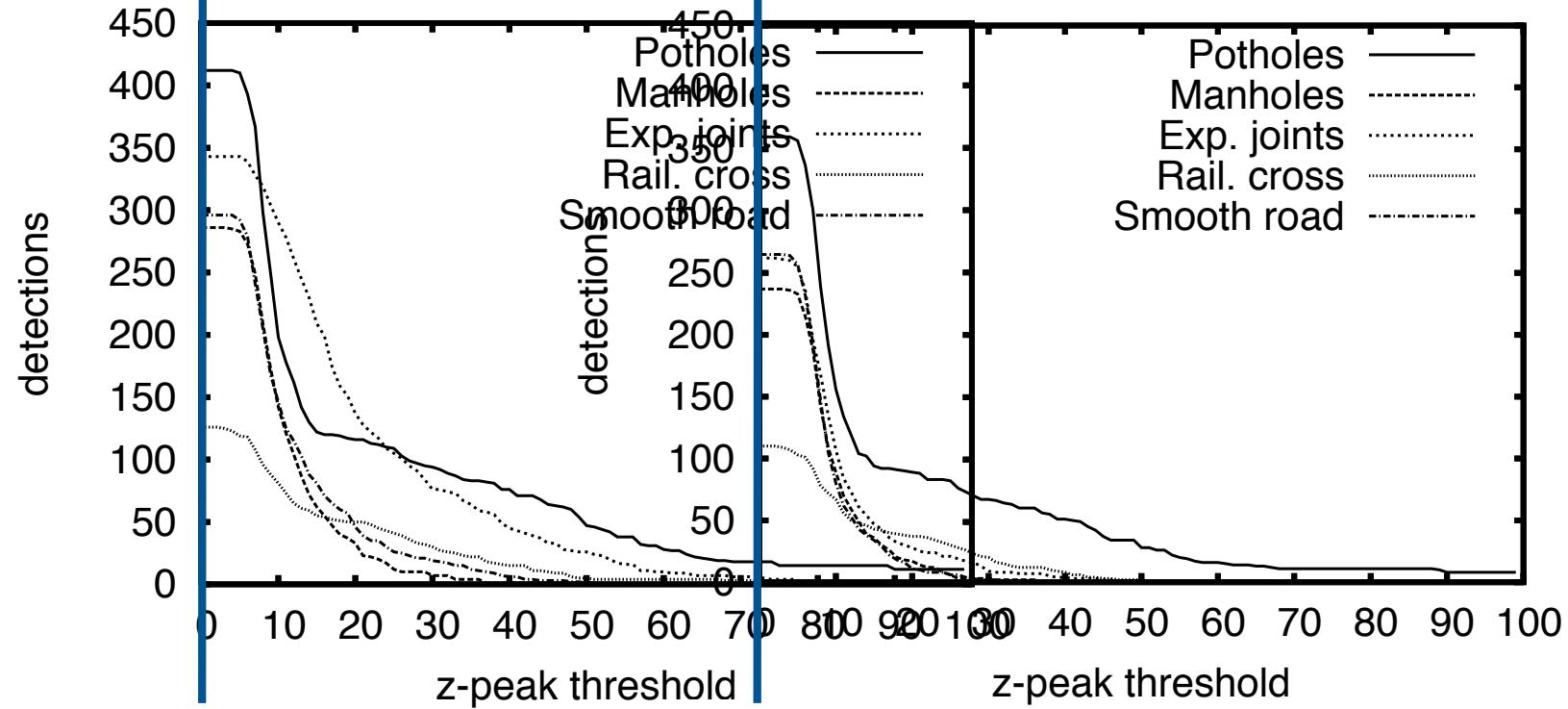
training the detector

- pick an objective function

$$s(\mathbf{t}) = corr - incorr^2$$

- optimize over 3 threshold parameters
 - z-peak
 - xy-ratio
 - speed vs. z-ratio

training the detector

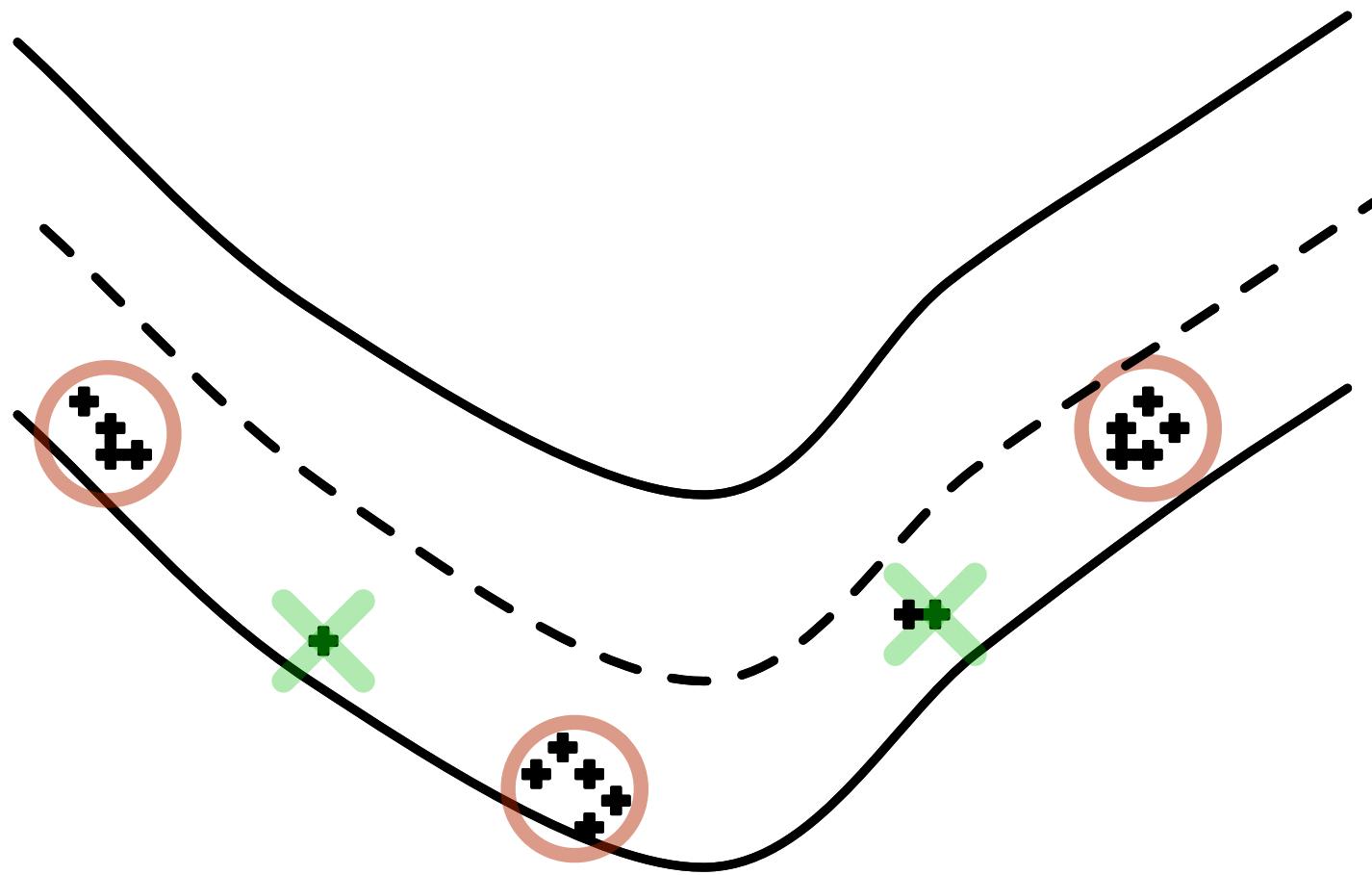


detector performance

Road	# potholes	#win	#det.	rate
Storrow Dr.	few	1865	3	0.16%
Memorial Dr.	few	1781	2	0.12%
Hwy I-93	few	2877	5	0.17%

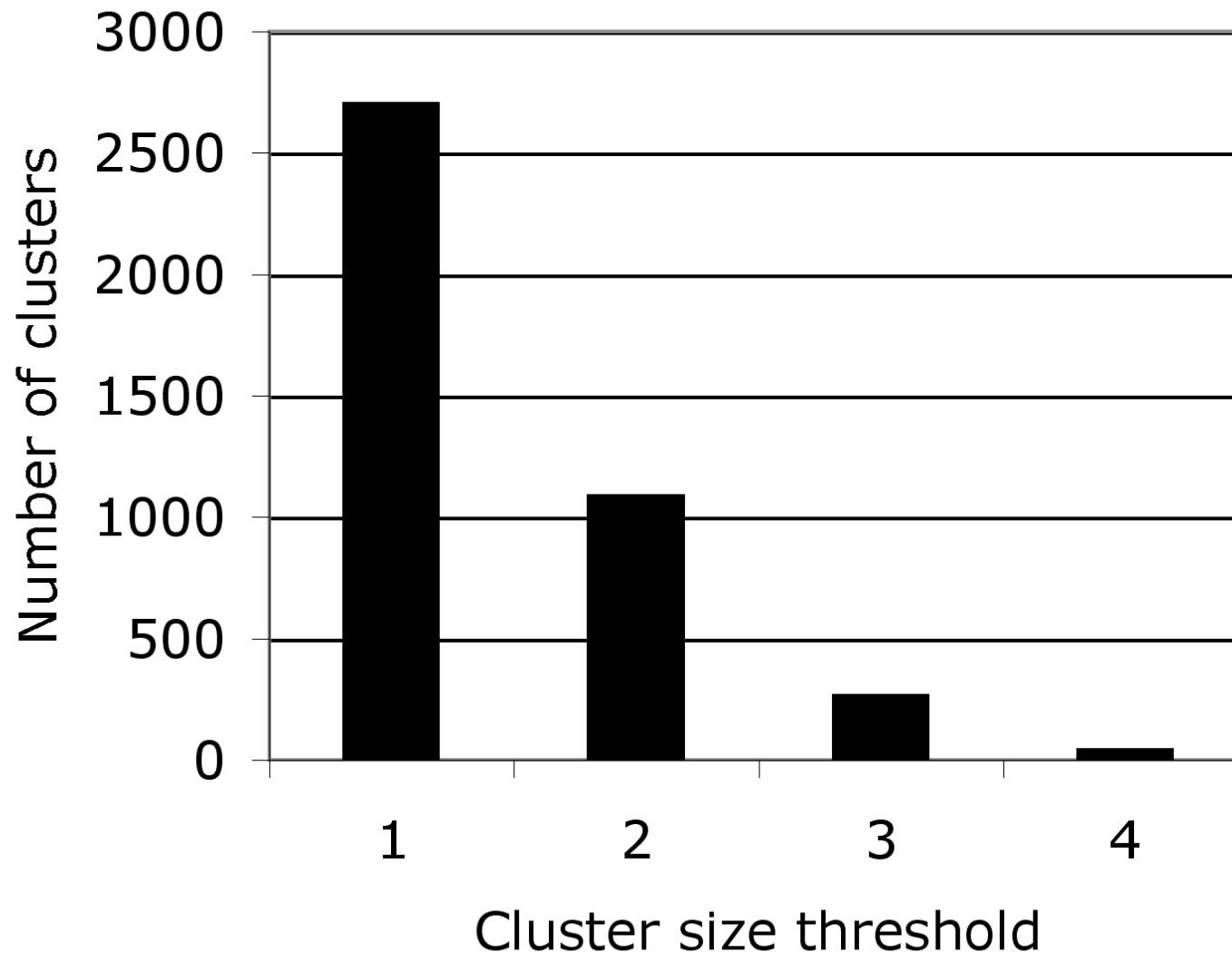


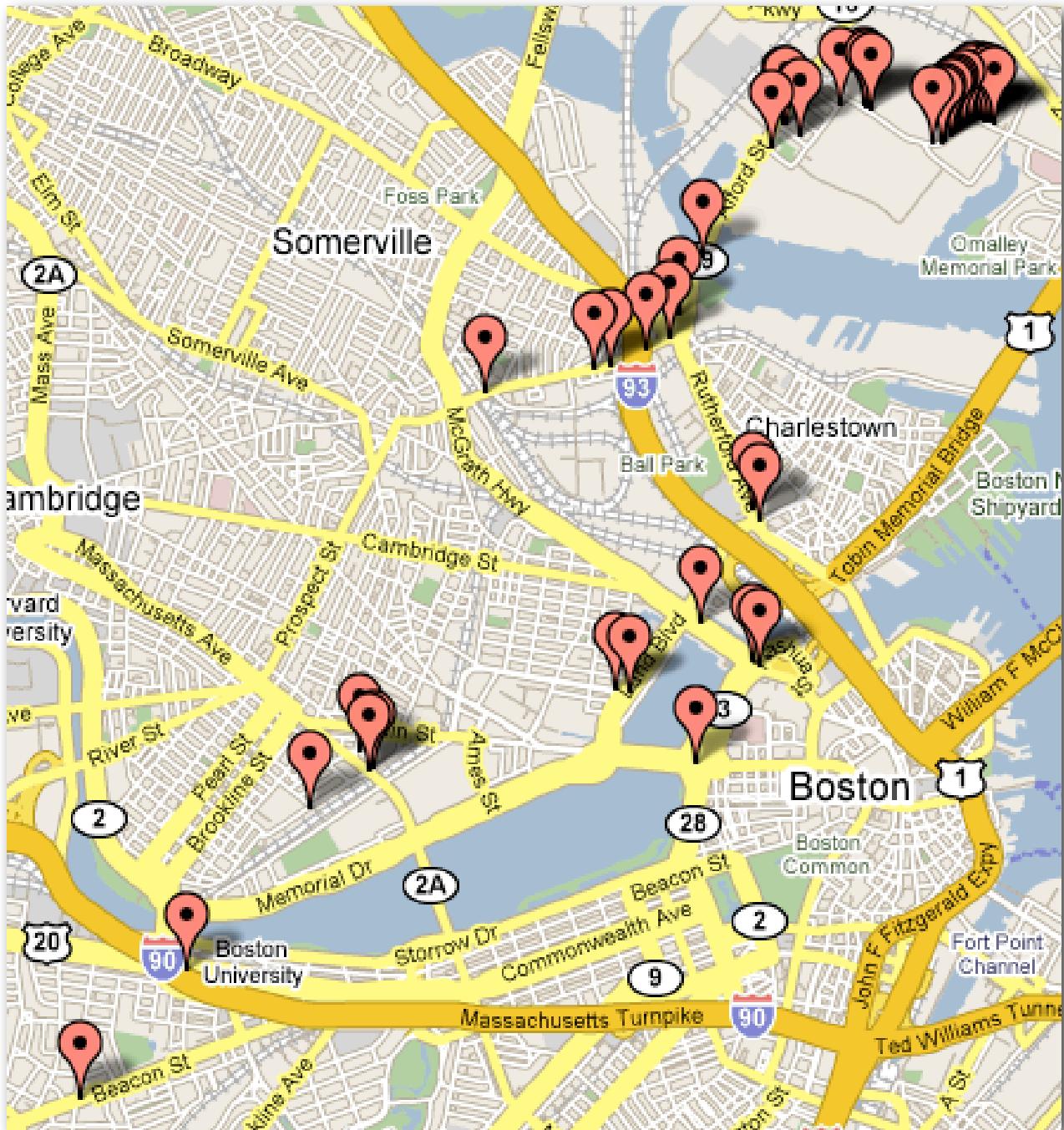
clustering



- 1.4 million sample windows
- 2500 unique km of road covered
- 4131 detections in 2709 locations

impact of cluster size

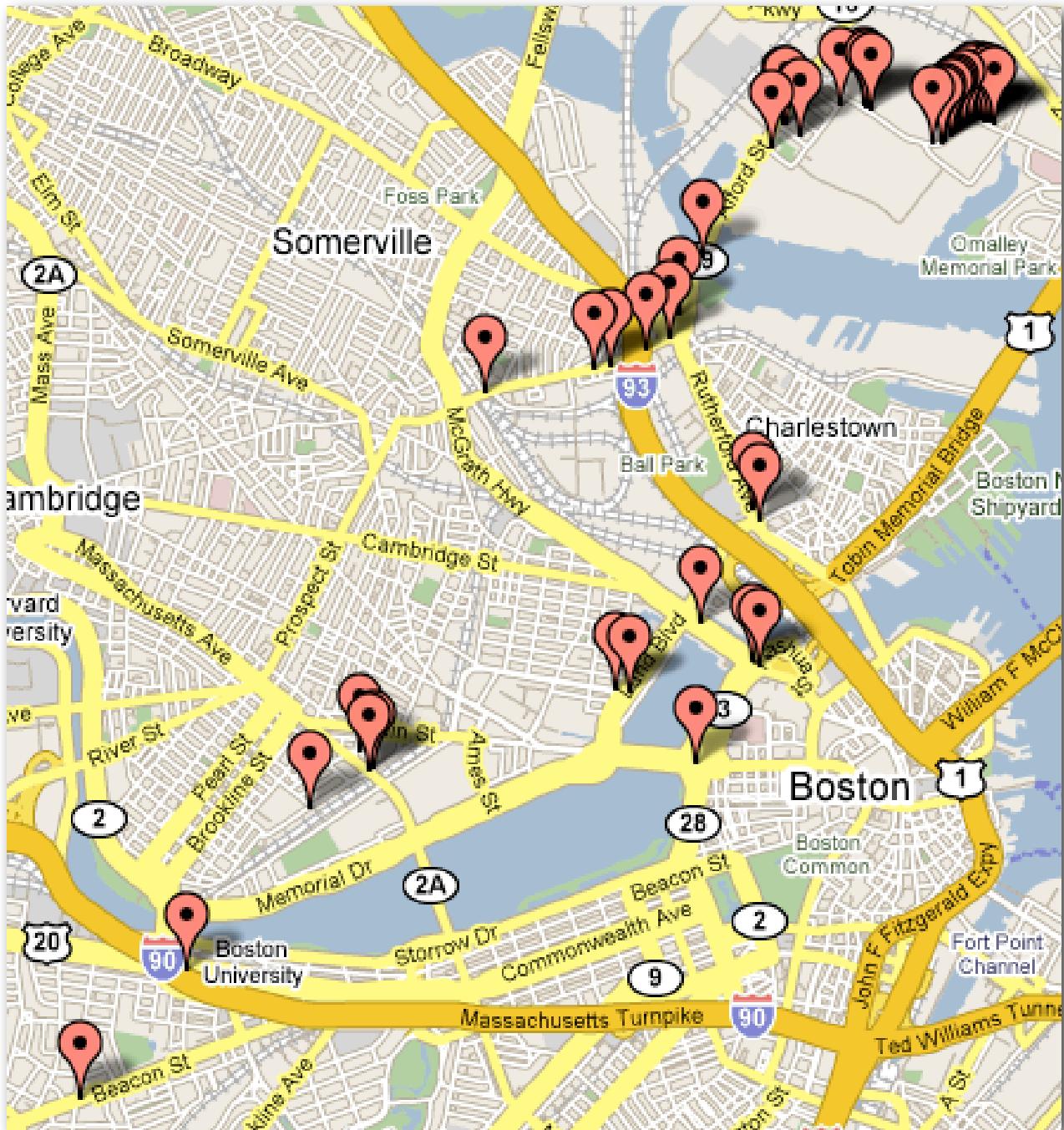


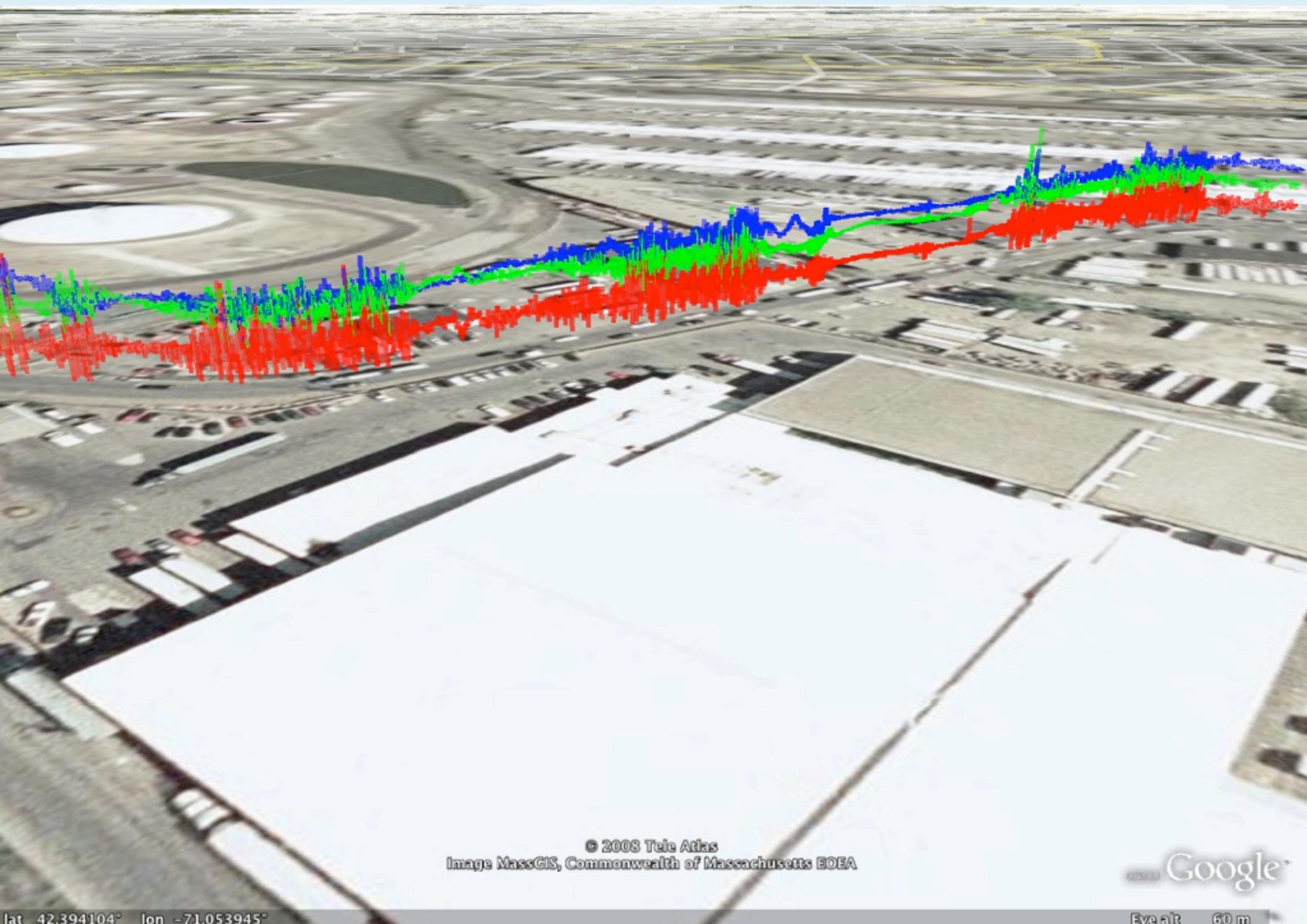


48 spot-checks

potholes	39
sunk-in manholes	3
railways and exp. joints	4
undetermined	2







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lat 42.394104° lon -71.053945°

Eye alt 60 m

Google

P²: the Pothole Patrol

- automatic wide-area road quality monitoring
- use of opportunistic mobility
 - mobile sensing
 - delay-tolerant communication
- low-cost approach to help solve a costly problem