

6.S062: Mobile and Sensor Computing

Class 1

<http://6s062.github.io/6MOB>

Lecturers

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The Lunchbox Reimagined

An intelligently designed, beautifully crafted lunchbox and smart lunch recipe app. Prepd Pack redefines the whole experience of taking lunch, from planning and preparing, to tracking the nutritional value of your lunches.

EVERYTHING YOU'VE EVER WANTED IN A PERSONAL ROBOT!



Expressions and gestures

Professor Einstein looks like the real Einstein and can smile, frown, and even stick his tongue out--to name a few of his 50+ gestures.



Built-in Wi-Fi

Download new interactive apps from the cloud whenever you're ready for more learning and fun! Includes one-year of free cloud service.



Fancy some brain-teasing fun?

Lend him your iPad™ and Android tablet, and he can play hours of interactive games with you to teach you science and math.



Just want to talk?

He recognizes speech and loves to chat! He can talk about the weather, famous people, food, or math problems.



Stay organized

He will manage your calendar and to-do list. You just need to

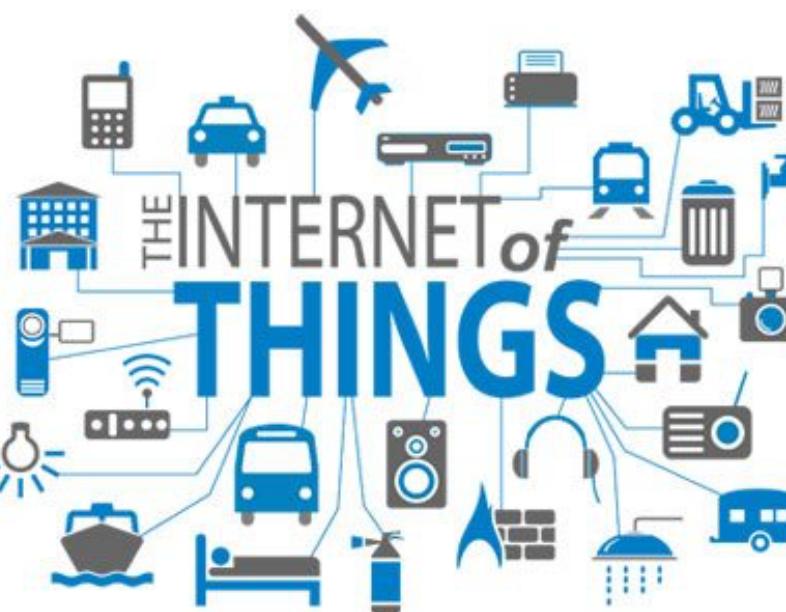
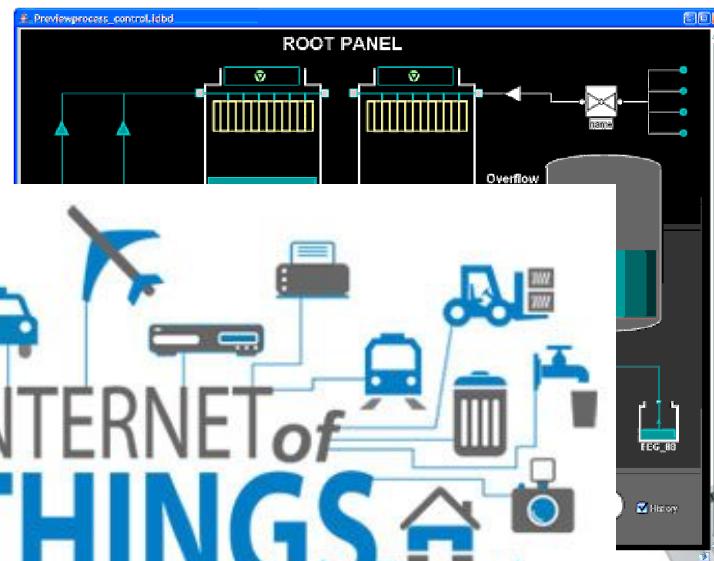
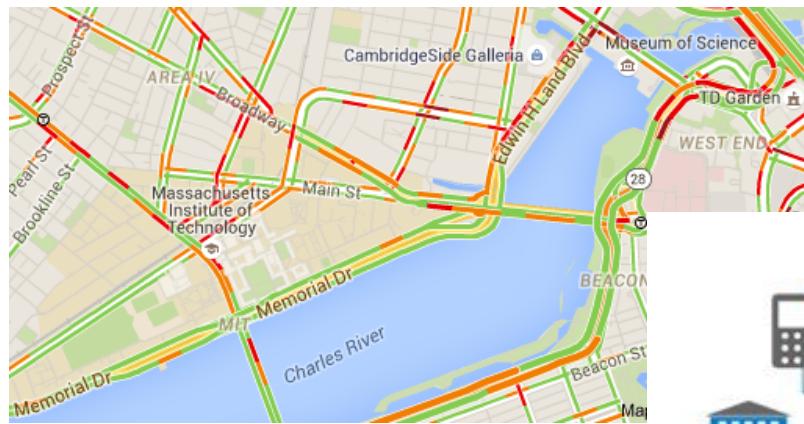


He can be recharged

Enjoy up to three hours of interaction with him every time

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12:45

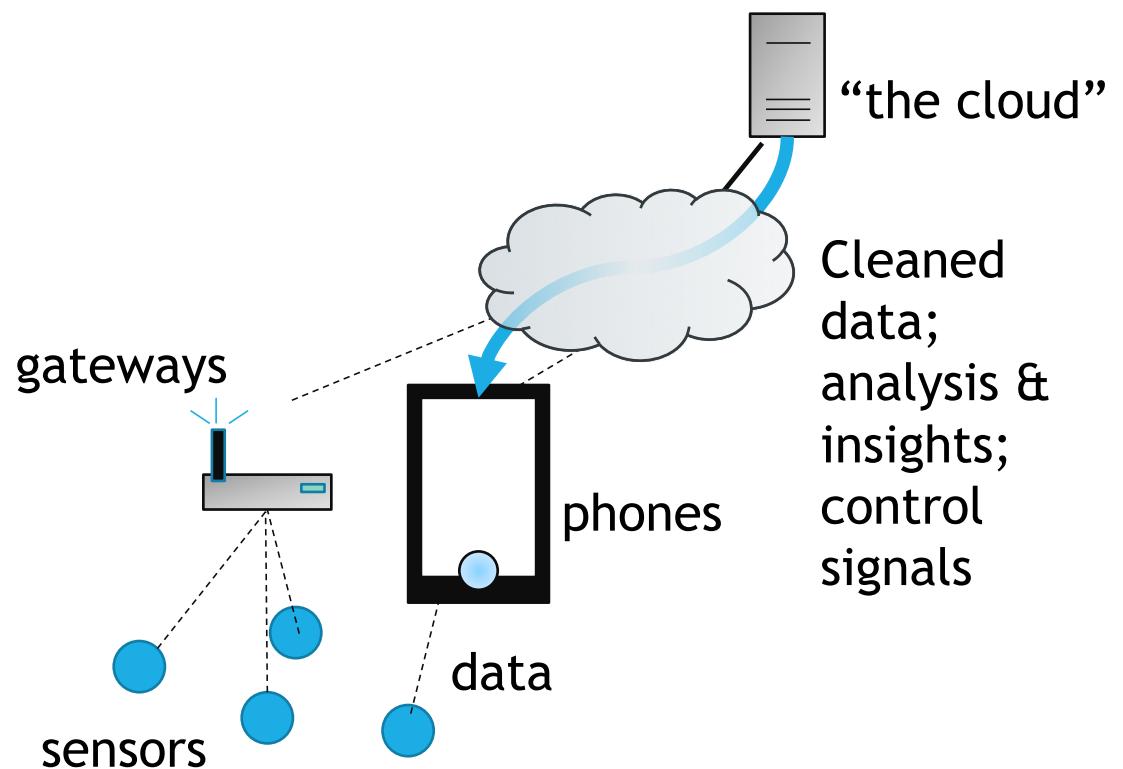
PROTOTYPICAL SENSOR SYSTEM ARCHITECTURE

Data path: sensors → phones/basestations → cloud

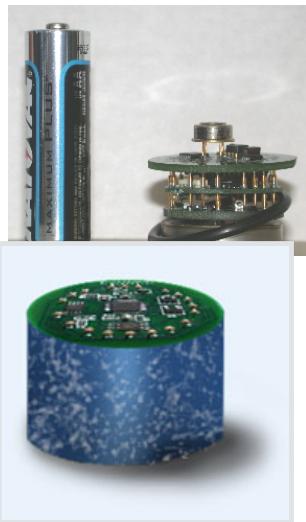
Sensors use low-power (BTLE, Zigbee) wireless

Phones and gateways use WiFi, cellular, or wired Internet links

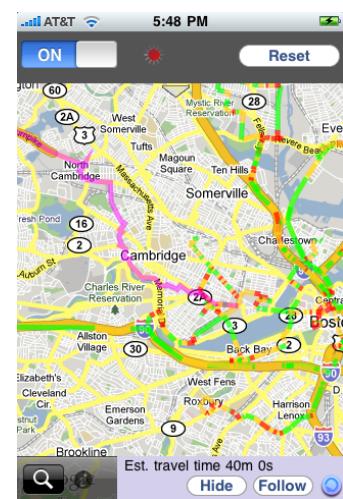
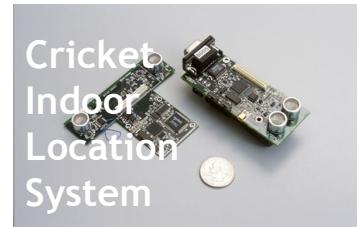
Processing happens on sensors, basestations, phones, and cloud



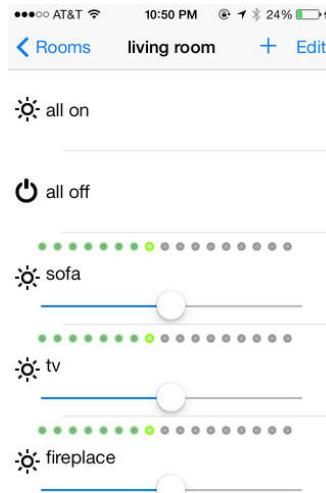
OUR IOT EXPERIENCE



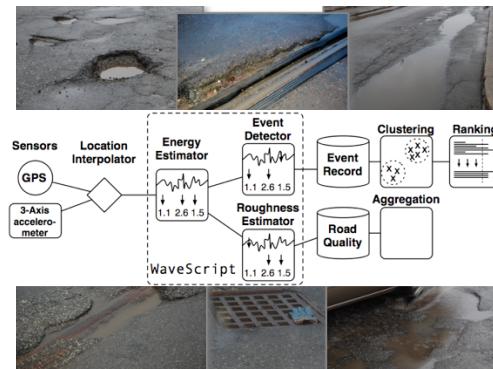
TinyDB: The
Sensornet is
the Database



iCarTel crowdsourced
traffic aware routing
app



Lutron Light Control
app for controlling
lutron lighting
systems from iPhone



Pothole Patrol



Pipenet



DriveWell
safe driving
app and BTLE
accident-
detection
device

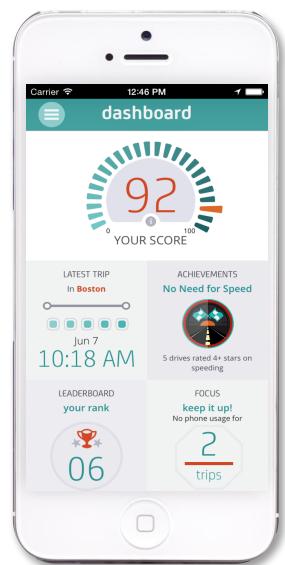
CASE STUDY: DRIVEWELL + TAG

Key capabilities: “safety score”, end-to-end collision alerting facility

Requirement 1:
3+ years battery life

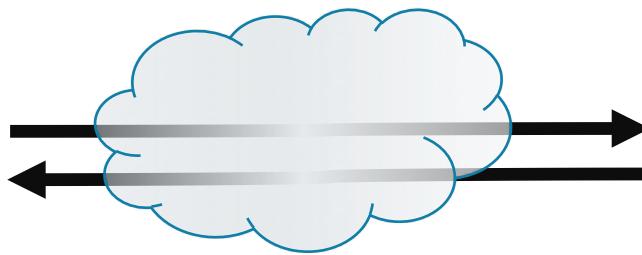


Acceleration Data
Impacts
Trip starts (triggered)
(Over BLE)



Trip data:
Acceleration
Gyroscope
Position

Requirement 2:
< 5% battery drain /
hour when driving



Requirement 3: 10
second end-to-end
notification of
accidents

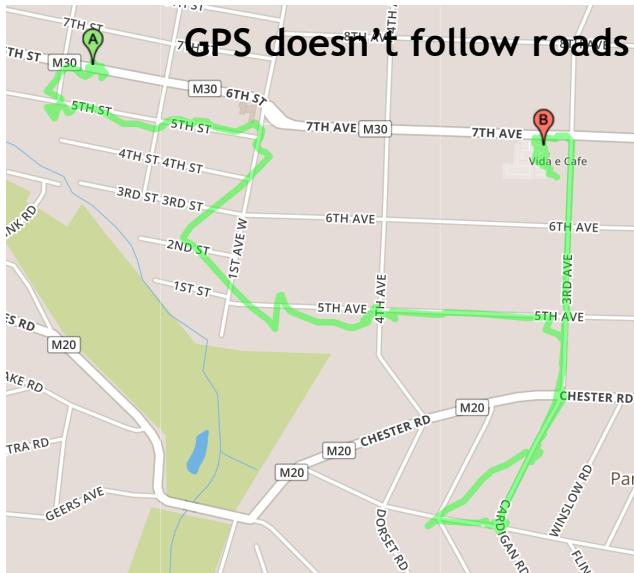
Requirement 5:
Accurately measure
mileage and detect
various harsh events



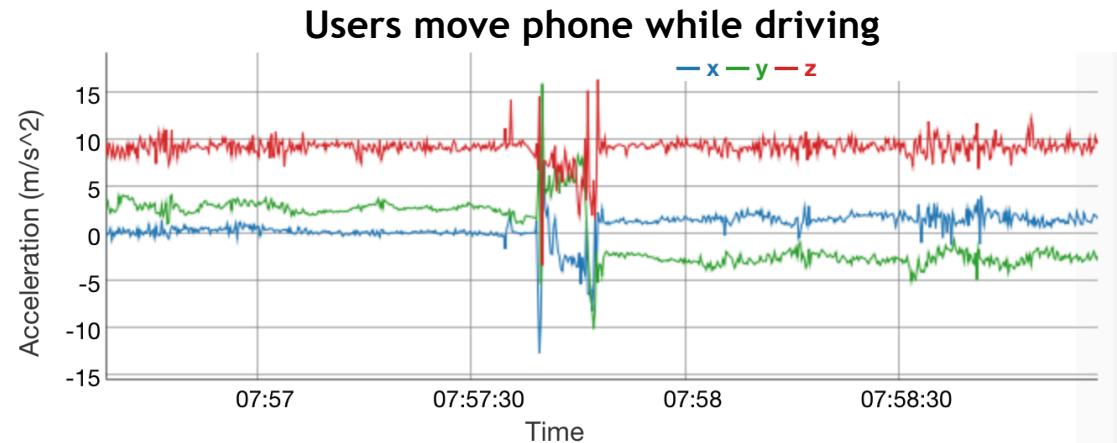
Requirement 4:
Real time trip
feedback in a few
minutes



DRIVEWELL DATA CHALLENGES



GPS doesn't follow roads

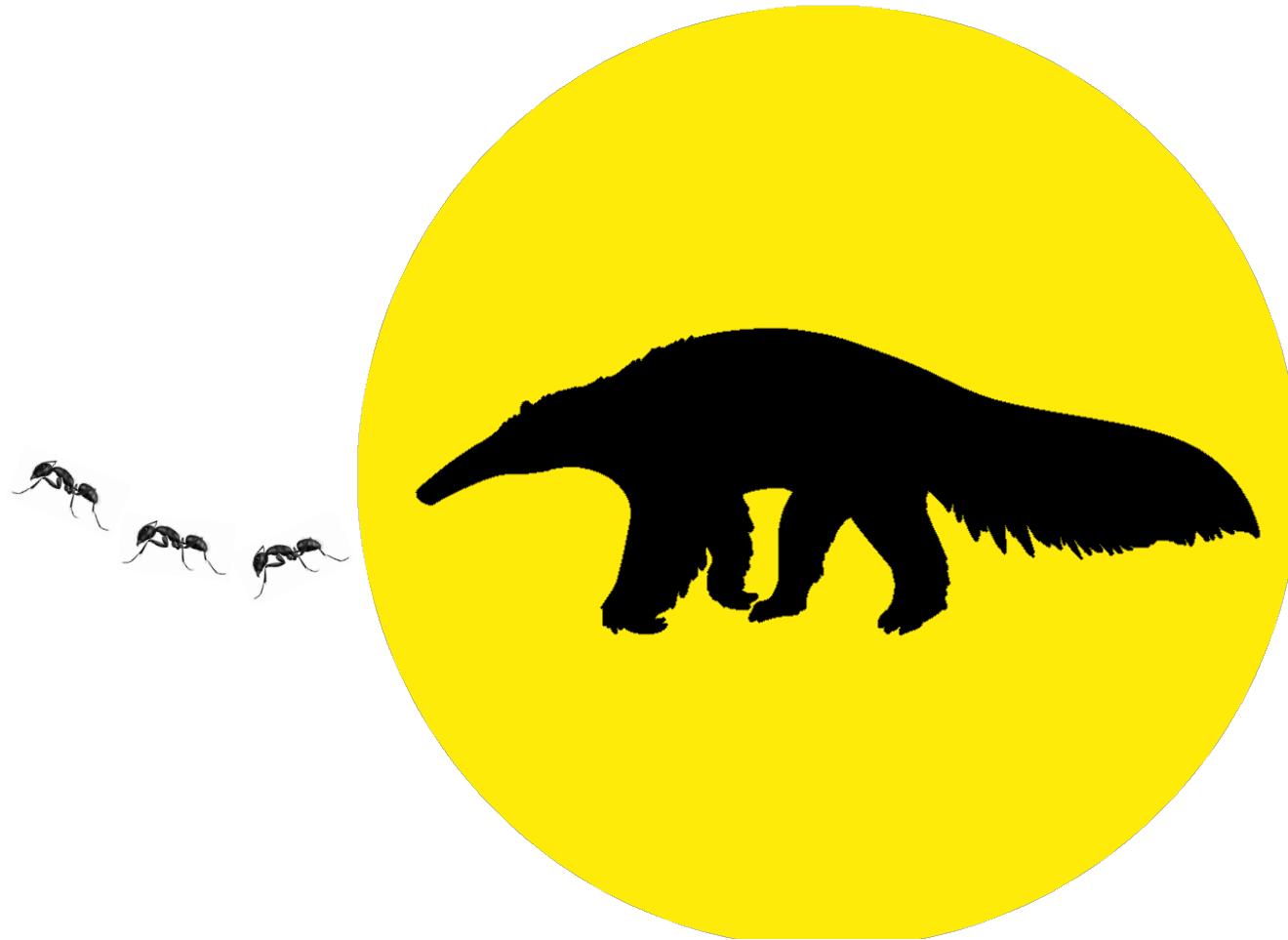


Certain classes of devices experience failures

Discover CBCharacteristic for CBSERVICE misses a few characteristics

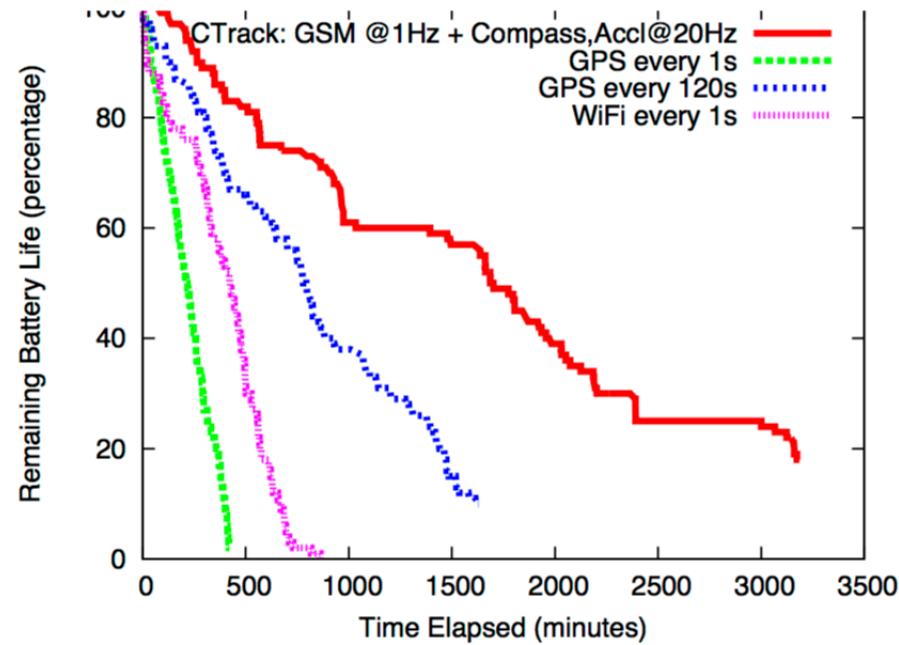
442 Views 15 Replies [Latest reply](#): Sep 29, 2015 2:05 AM by masakazu

AN ANTERNET OF THINGS



VTRACK/CTRACK

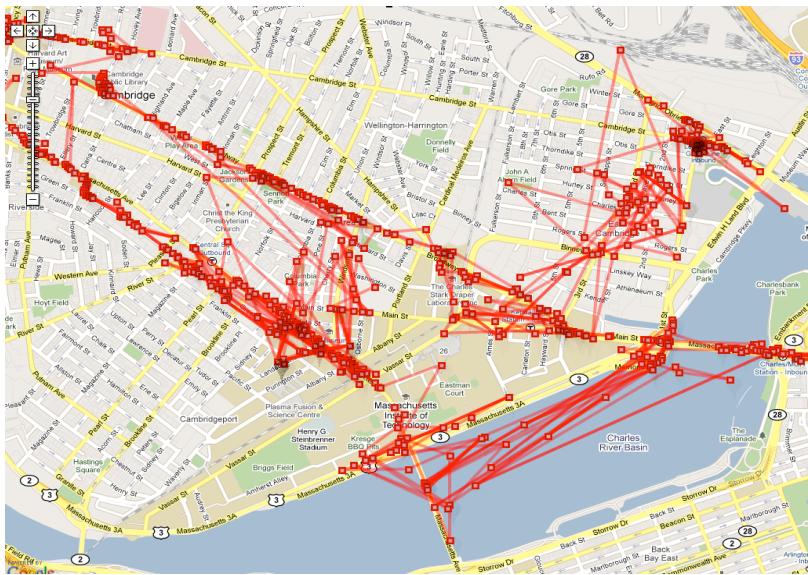
Tradeoff between accuracy and cost



VTRACK/CTRACK

Tradeoff between accuracy and cost

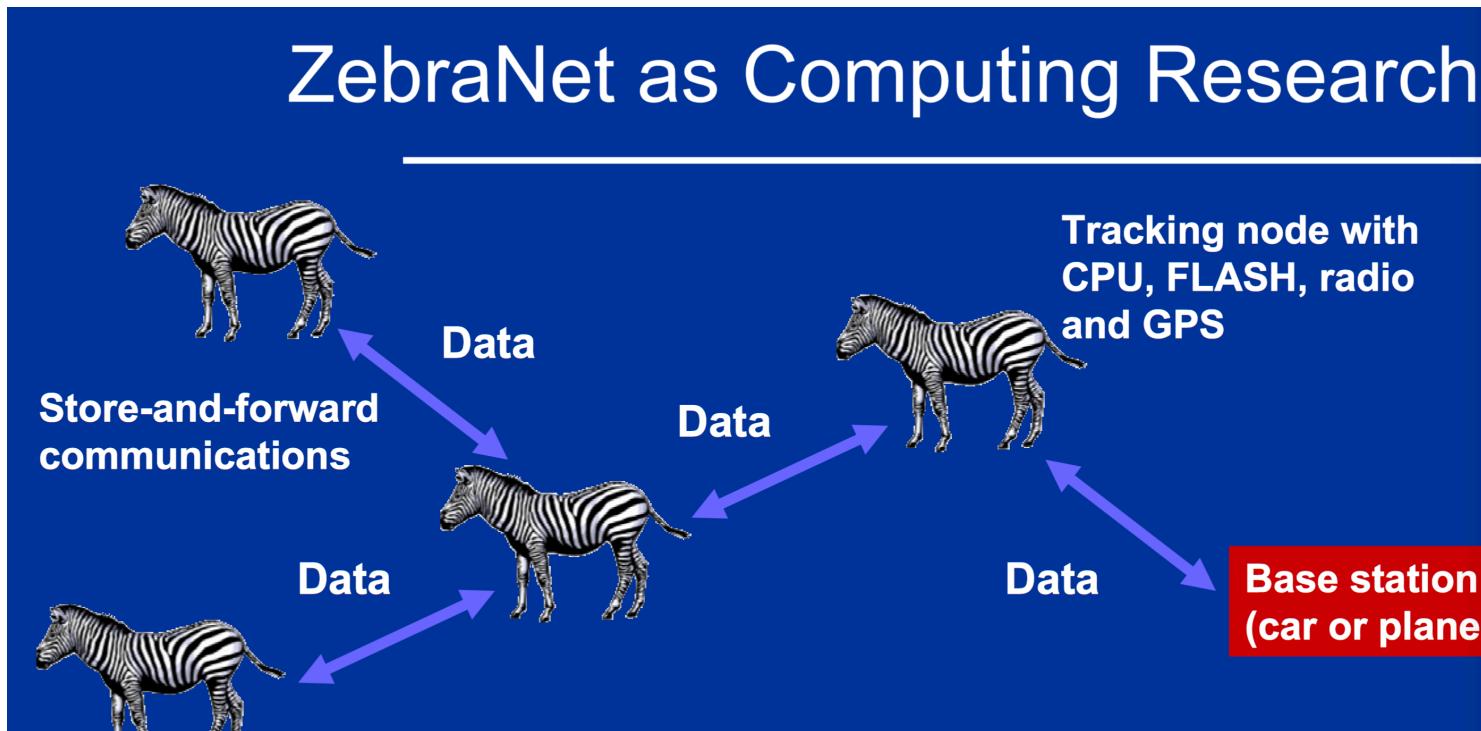
To this...



From this...

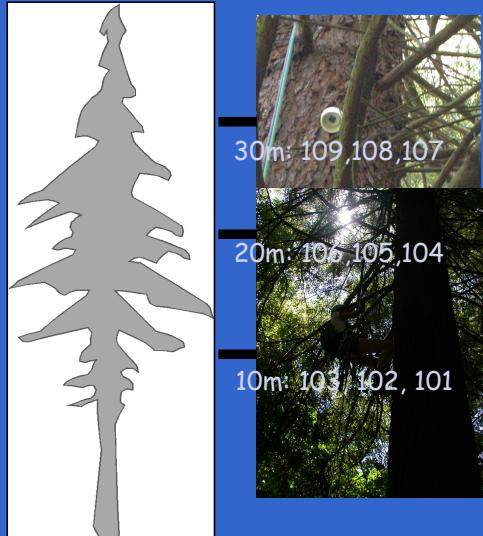


EXAMPLE: ZEBRANET



My PhD – Sensor Networks & TinyDB

Habitat Monitoring: Storm petrels on Great Duck Island, microclimates on James Reserve.



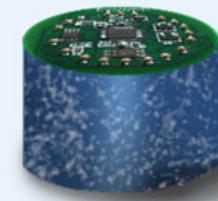
Redwood Forest Monitoring

Earthquake monitoring in shake-test sites.



Traditional monitoring apparatus.

TinyDB: The Network is the Database



- Users specify the data they want
 - Simple, SQL-like queries
 - Using predicates, not specific addresses
- Challenge is to provide:
 - Expressive & easy-to-use interface
 - Power efficient execution framework
 - » Efficiently fetches data from network
 - » While capturing as much data as possible

The Power of
Declarative
Thinking!

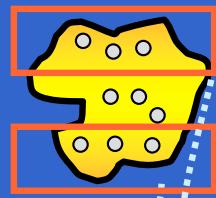
Many research groups became excited about related set of ideas in early 2000's

Aggregation Queries

② `SELECT AVG(sound)
FROM sensors
EPOCH DURATION 10s`

“Count the number occupied nests in each loud region of the island.”

③ `SELECT region,
CNT(occupied)
AVG(sound)
FROM sensors
GROUP BY region
HAVING AVG(sound) > 200
EPOCH DURATION 10s`



Epoch	region	CNT(...)	AVG(...)
0	North	3	360
0	South	3	520
1	North	3	370
1	South	3	520

Regions w/ $AVG(sound) > 200$

ILLUSTRATION: IN-NETWORK DATA PROCESSING IN TINYDB

Multihop data collection

- Divide sample period into short time *intervals*
- Assign each node to an interval according to its depth in the tree

Key idea: combine data as it is transmitted in the network

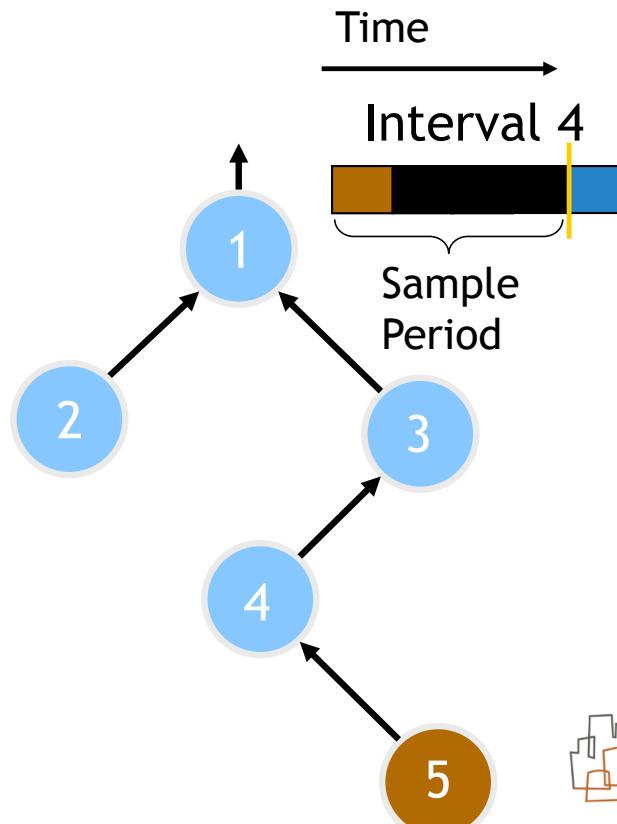


ILLUSTRATION: IN-NETWORK DATA PROCESSING

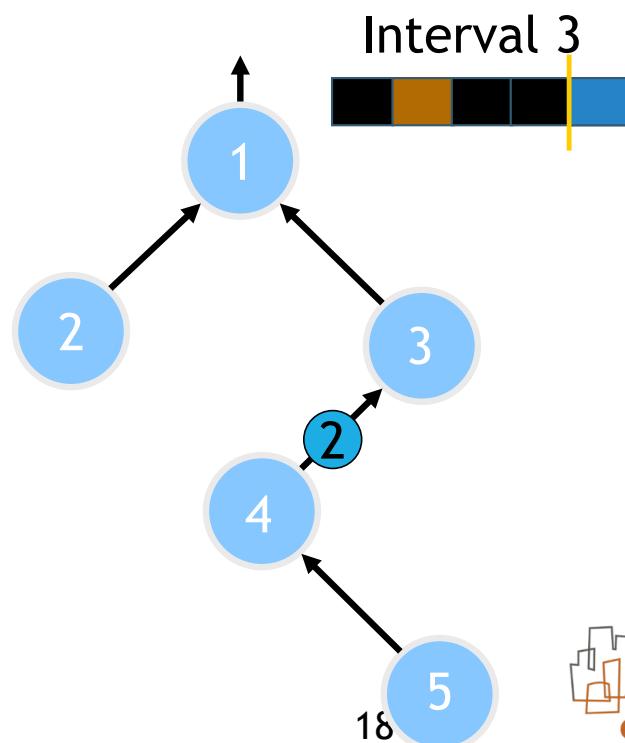
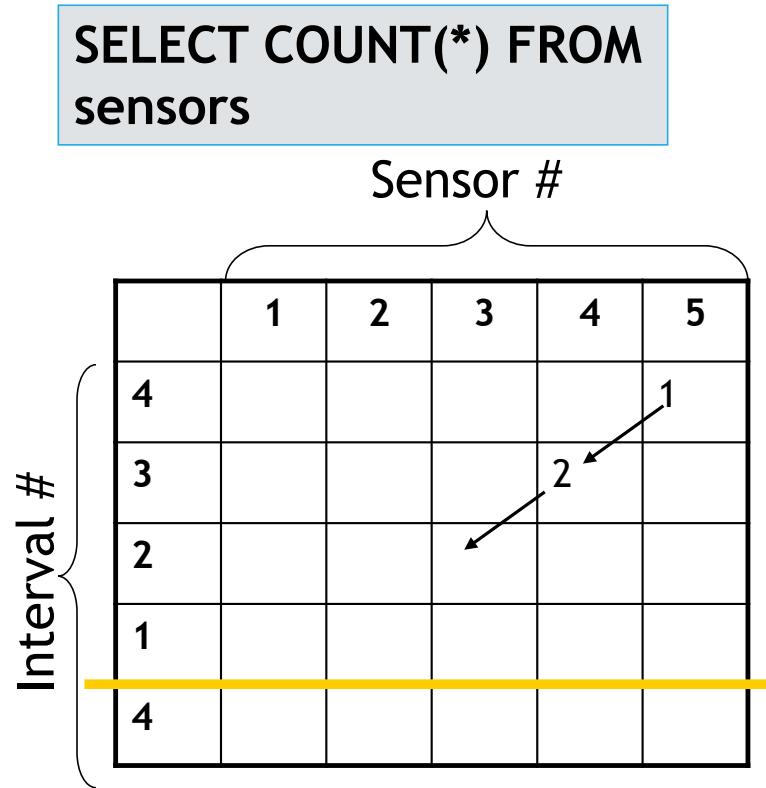


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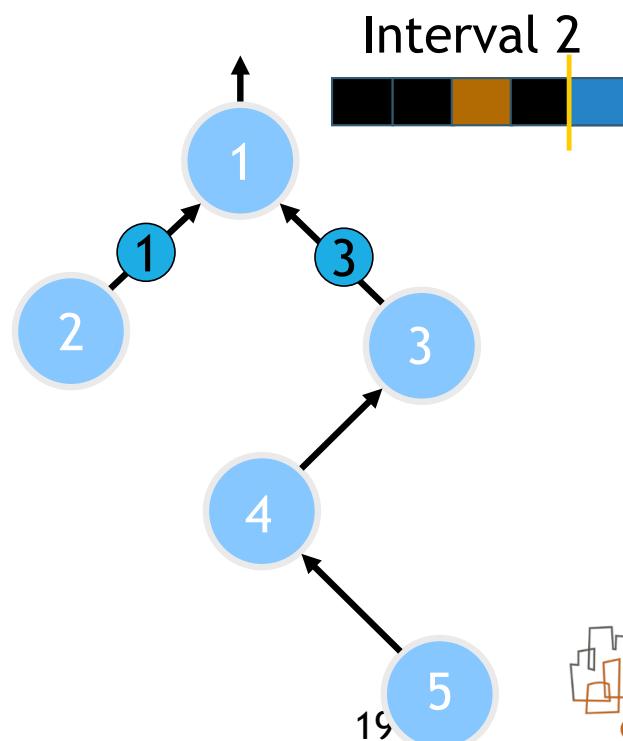
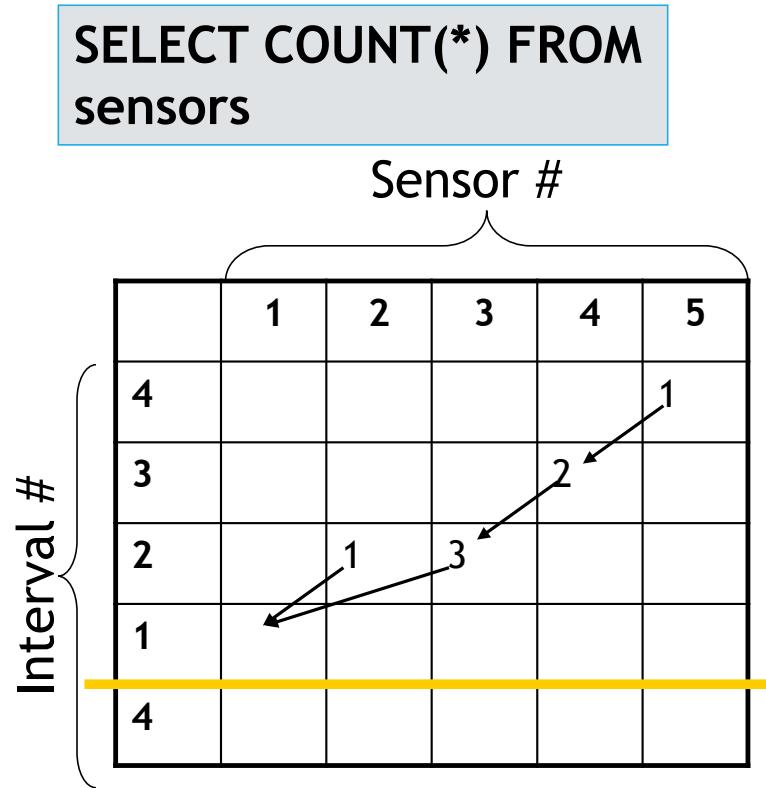


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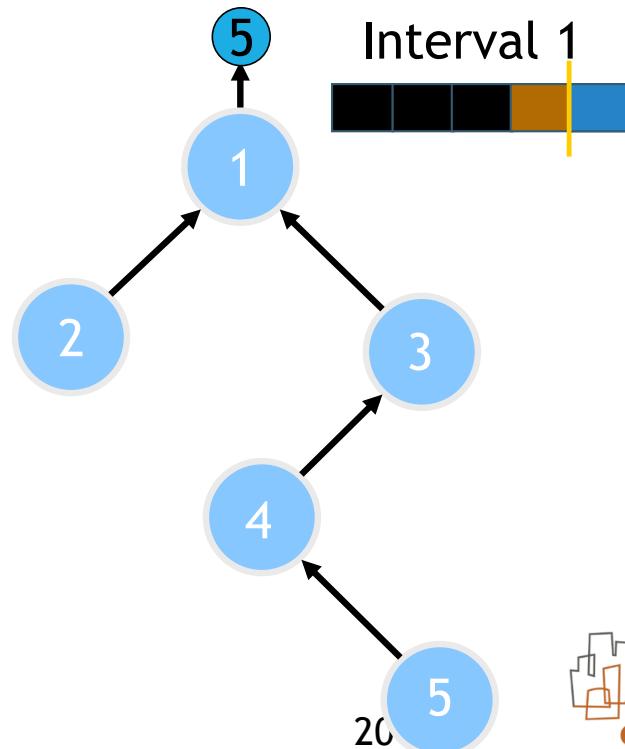
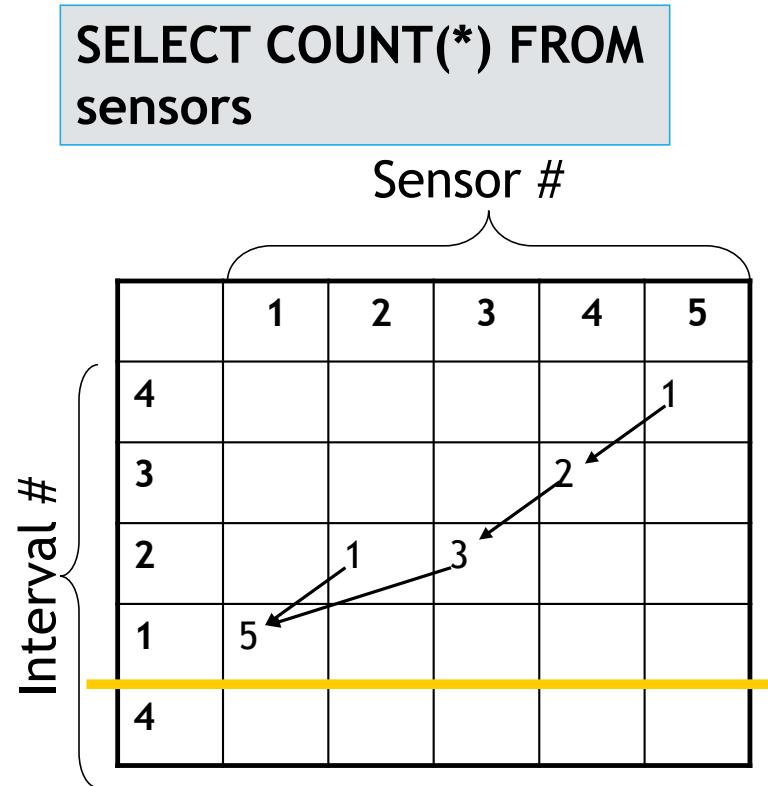


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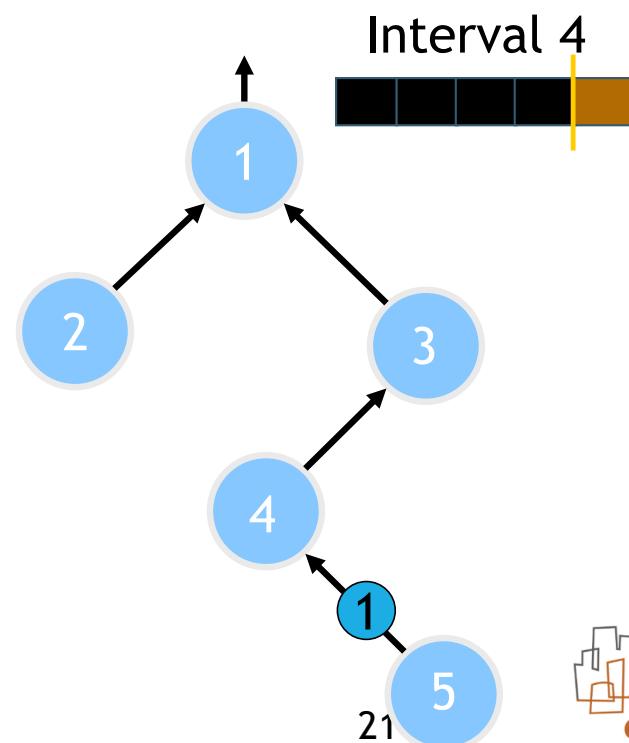
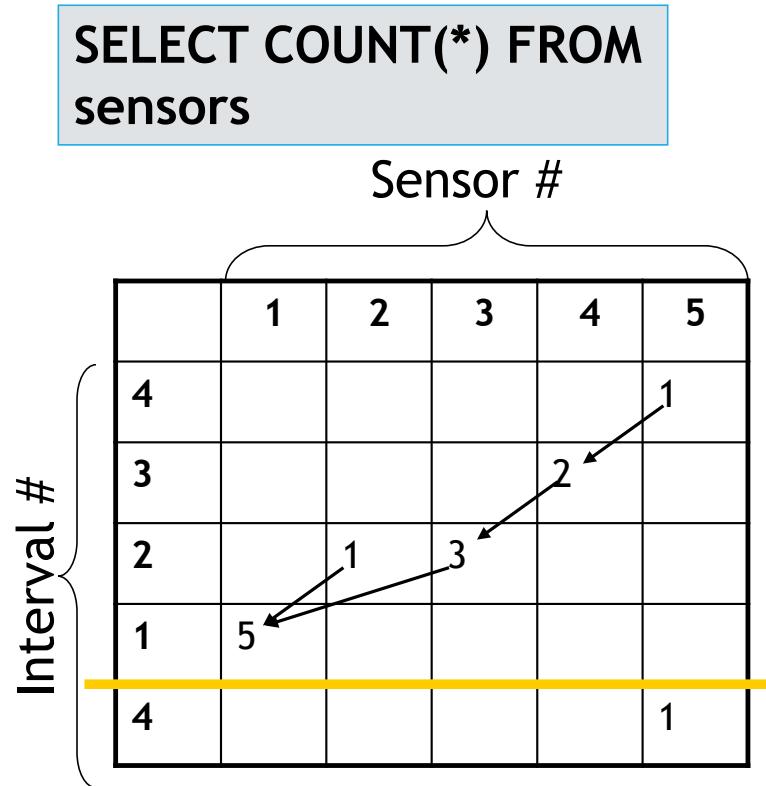


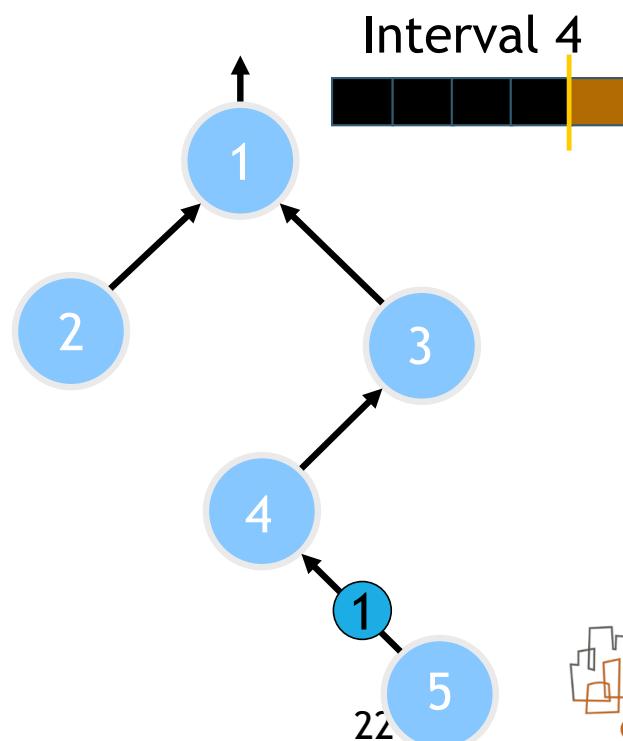
ILLUSTRATION: IN-NETWORK DATA PROCESSING

SELECT COUNT(*) FROM sensors

	Sensor #				
	1	2	3	4	5
4	zzz	zzz	zzz		1
3	zzz	zzz		2	zzz
2		1	3	zzz	zzz
1	5	zzz	zzz	zzz	zzz
4	zzz	zzz	zzz		1

Interval #

*Nodes can sleep most of the time
Each node transmits only one COUNT*



POTHOLE PATROL



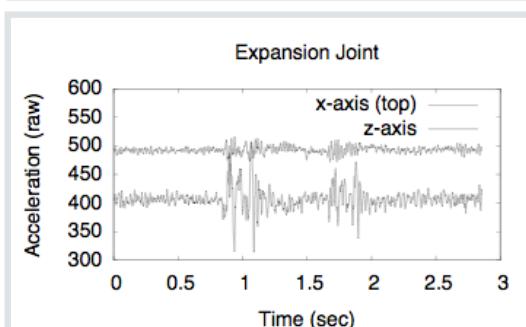
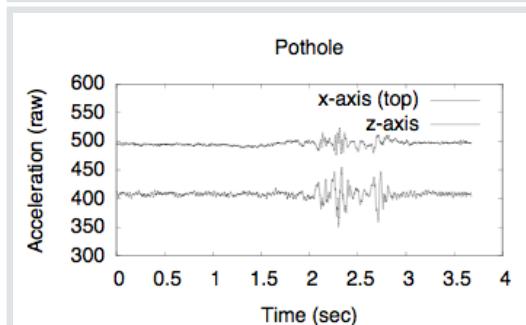
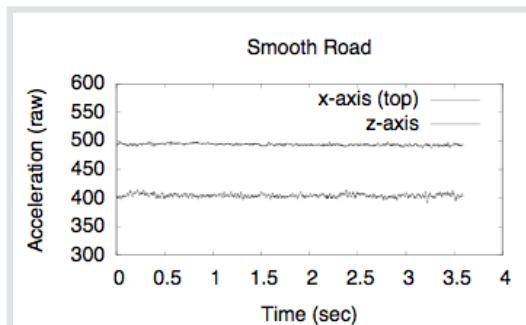
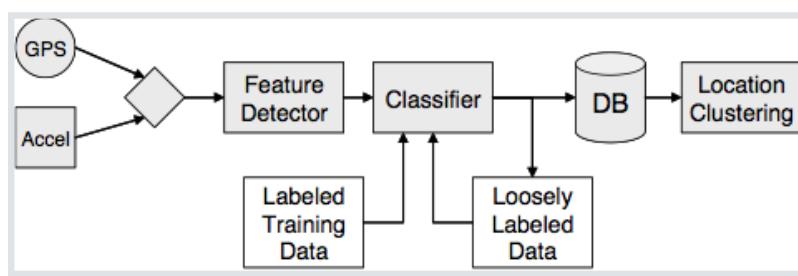
CLASSIFICATION-BASED APPROACH

Classifier differentiates between several types of anomalies

Window data, compute features per window

Variety of features:

- Range of X,Y,Z accel
- Energy in certain frequency bands
- Car speed
- ...



POWER USED BY SOME COMMON COMPONENTS

Component	Approximate Power Consumption	
LTE Radio (transmit @ 1 Mb/s)	1700 mW	
3G Radio (transmit @ 1 Mb/s)	1700 mW	
WiFi (transmit @ 1Mb / s)	400 mW	
ARM+RAM uProc (100% cpu)	2000 mW	
ARM+RAM uProc (idle)	70 mW	
Smartphone Screen (full brightness)	850 mW	
GPS (once lock is acquired)	100-150 mW	
Accelerometer (@10 Hz)	75 uW	
Image sensor (@1080p/30Hz)	270 mW (Sony IMX206CQC)	<i>Collecting the data is cheap; displays & radios & processing are expensive</i>



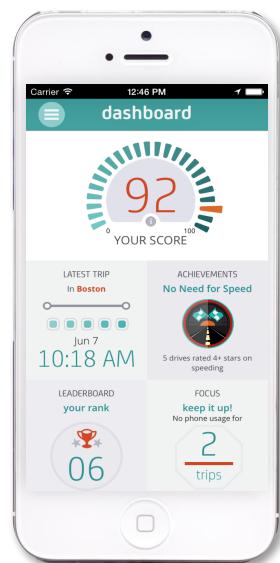
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3+ years battery life

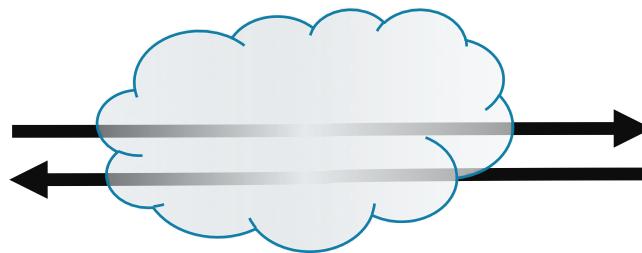


Acceleration Data
Impacts
Trip starts (triggered)
(Over BLE)



Trip data:
Acceleration
Gyroscope
Position

Requirement 2:
< 5% battery drain /
hour when driving



Requirement 5:
Accurately measure
mileage and detect
various harsh events

Amazon AWS Cloud

Requirement 3: 10
second end-to-end
notification of
accidents

Requirement 4:
Real time trip
feedback in a few
minutes



TOPICS

- Positioning technologies, including GPS, WiFi and cellular localization
- Wireless networking, including BLE, WiFi, Zigbee, as well as multi-hop and store-and-forward ("muling")
- Resource constraints, including power, bandwidth, and storage
- Inertial sensing, including accelerometers, gyroscopes, IMUs, dead-reckoning
- Other types of sensors, e.g., microphones and cameras
- Application studies
- Embedded hardware and software architecture
- Embedded system security
- iOS APIs for accessing various sensing and wireless networking technologies

