# FUNCTIONAL SAFETY IN EMBEDDED SYSTEMS

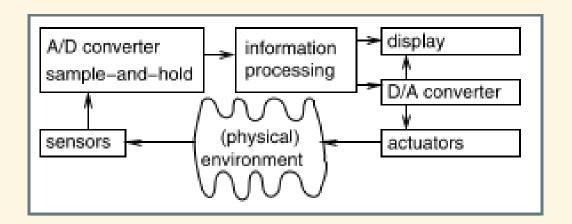
Part III
Embedded Systems Hardware
STEPHAN HEIDINGER

### OUTLINE

- Introduction
- Input
- Processing Units
- Reconfigurable Logic
- Memory
- Communication
- Output
- Secure Hardware

### INTRODUCTION

- System consists of Software and Hardware.
- Hardware for Embedded Systems is much less standardized than PC hardware is.



### **INPUT**

- Sensors
- Discretization of time
- Discretization of values

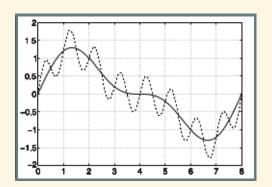
### **INPUT - SENSORS**

Sensors for any given quantity.

- Acceleration
- Rain
- Image CCD
- Image CMOS
- Biometric Sensors
- RFID
- ...

### INPUT - DISCRETIZATION OF TIME

- Computers only work in discrete time domain.
  - => Need to take samples at fixed points in time.
  - => Only those samples can be used by the computer.
- Reconstruction of unsampled data generaly not possible.
  - => Can be possible in some cases.
  - => Nyquist sampling criterion:
  - "Restrict the frequencies of the incoming signal to less than half of the sampling frequency."
- Sample-and-Hold circuits: value is sampled and held, until next value is sampled (sampling takes some time).



### INPUT - DISCRETIZATION OF VALUES

- Computers only work in discrete data domain.
- large variety of converters
- Flash A/D converter
  - + very fast
  - complex hardware (n-1 comparators)
- Successive Approximation:
  - + hardware efficient
  - slow (log(n) steps)
- SNR => "how much good signal" (dB, dimensionless)
- Automatic techniques for selecting most approriate converter exist.

### **PROCESSING UNITS**

- Overview
- ASIC
- Processors

### **PROCESSING UNITS - OVERVIEW**

- "consumed" energy
- power and energy efficiency important=> "green IT"
- energy efficient => not flexible
- flexible => not energy efficient
- high power consumption => may be more energy efficient, if also faster

### PROCESSING UNITS - ASIC APPLICATION SPECIFIC INTEGRATED CIRCUITS

- Cost of design and manufacture very high.
   => only feasible for large quantities
- Design is time consuming.
  => Correcting faults is expensive.
- Very small energy consumption.

### PROCESSING UNITS - PROCESSORS

- Processors are programmable.
  - => very flexible
- Embedded processors
  - => no need for instruction set compatibility.

### PROCESSING UNITS - PROCESSORS ENERGY EFFICIENCY

- gate clocking
  - => parts of processor are disconnected from clock if idle
- Dynamic Power Management (DPM)
  - => more power saving states (e.g. run, idle, sleep)
- Dynamic Voltage Scaling (DVS)
  - => power changes quadratically with voltage
  - => runtime changes linearly

## PROCESSING UNITS - PROCESSORS CODE-SIZE EFFICIENCY

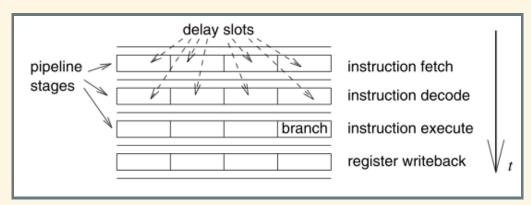
- Memory very limited => want to take as little space as possible for code
- RISC => designed for speed
- CISC ("old processors") => designed for code-efficiency
- Compression Techniques => hardware decoder
- second instruction set (ARM)
- dictionaries

### PROCESSING UNITS - PROCESSORS RUN-TIME EFFICIENCY

- Optimize architecture for specific domain.
   => more efficient without higher clock frequency
- Example: Digital Signal Processing
  - Specialized Addressing Modes
  - Seperate Address Generation Units
  - Saturation Arithmetic
  - Fixed-Point Arithmetic
  - Multiple Memory Banks
  - Multiply/Accumulate Instructions

### PROCESSING UNITS - PROCESSORS VERY LONG INSTRUCTION WORD PROCESSORS

- no instruction set compatibility
  - => explicit identification of parallelism
  - => EPIC (explicitly parallel instruction computing)
- several operations in one instructions
  - => execution in parallel
- possible delay penalty (due to branch instructions):



### PROCESSING UNITS - PROCESSORS MICRO-CONTROLLERS

- not complex
- easy usage

#### MULTIPROCESSOR SYSTEM-ON-A-CHIP (MPSOC)

- increased clock speed => higher energy consumption
- in PC
  - => homogenous *multi-core* systems
- in embedded systems
  - => highly specialised processors
  - => energy efficiency close to ASICs

### RECONFIGURABLE LOGIC

- ASIC often too expensive, processor too slow
   => field programmable gate Arrays (FPGAs)
- timing of FPGA precisely predictable
- reconfigurable hardware
  - => ROM is non-volatile
  - => RAM is volatile
- processors may be included in FPGA:
  - hard core: physical processor (efficient)
  - *soft core*: synthesize processor from CLB

### **MEMORY**

- efficient storage
  - => run-time memory hierarchy
  - => code-size compiler, compression
  - => energy memory hierarchy
- Moore's Law
  - => speed of processors doubles every 18-36 months
  - => speed of memory only increases by 1.07
- Use small, fast memory between processor and main memory.
- Scratch Pad Memory (SPM)

### **COMMUNICATION**

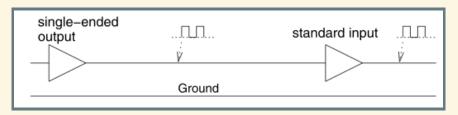
- Common Communication Requirements
- Electrical Robustness
- Real-Time Behavior
- Examples

### **COMMUNICATION - REQUIREMENTS**

- real-time behavior
- efficiency
- bandwidth, communication delay
- event-driven communication
- robustness
- fault tolerance
- maintainability
- privacy

## COMMUNICATION - EL. ROBUSTNESS SINGLE-ENDED SIGNALING

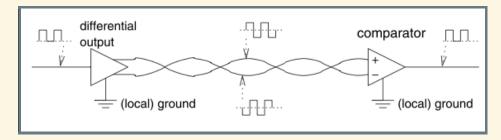
- voltage over commong ground
- succeptible to noise
- common ground may be hard to achieve



### **COMMUNICATION - EL. ROBUSTNESS**

#### **DIFFERENTIAL SIGNALING**

- first -> second = positive voltage => '1'
- noise added to both wires => no effect
- magnitude of voltage => irrelevant
- no common ground
- large throughput



### **COMMUNICATION - REAL TIME**

- point-to-point
  - => many wires needed
  - => shared buses very common
- priority based arbitration
  - => poor timing, can lead to starvation
- TDMA (timed division multiple access)
  - => real time behavior may be to slow
- CSMA/CD: upon collision: stop, wait, restart
- CSMA/CA: priority based arbitration phase
  - => starvation possible

### **COMMUNICATION - EXAMPLES**

- Sensor/Actuator Bus
- Field Bus
  - => controller area network
  - => time-triggered Protocol
- Wired Multimedia Communication
  - => MOST (media oriented system transport)
  - => IEEE 1394 "FireWire"
- Wireless Communication
  - => HSPA, LTE
  - => Bluetooth
  - => IEEE 802.11

### OUTPUT

- Displays
- Electro-Mechanical Devices (motors, gauges, ...)
- D/A Converter
  - => generate current proportional to signal x
  - => convert current into voltage y
- If Nyquist Theorem holds => interpolation is possible
  - => Shannon-Whittaker interpolation
  - => possible via low-pass filter
- Actuators: very wide range
  - => relatively new: Microsystem Technology

### **SECURE HARDWARE**

Embedded Systems may need special security elements:

- cryptography, en-/decryption
- side-channel attacks

Different levels of security and enemy need to be taken into account.