

0.1 Jacobian

Definition 0.1.1: Jacobian

Let $\mathbf{f}: U(\subseteq \mathbb{R}^m) \rightarrow \mathbb{R}^n$ be differentiable. The function $J_{\mathbf{f}}: U \rightarrow \mathbb{R}$ defined by

$$J_{\mathbf{f}}(\mathbf{x}) = \det \begin{bmatrix} \partial_1 f_1(\mathbf{x}) & \cdots & \partial_n f_1(\mathbf{x}) \\ \vdots & \ddots & \vdots \\ \partial_1 f_n(\mathbf{x}) & \cdots & \partial_n f_n(\mathbf{x}) \end{bmatrix}$$

is called the *Jacobian* of \mathbf{f} at \mathbf{x} .

Lemma 0.1.1

If $f: V(\subseteq \mathbb{R}^n) \rightarrow \mathbb{R}$ and $\mathbf{g}: U \rightarrow V$ are differentiable, then

$$J_{f \circ \mathbf{g}}(\mathbf{x}) = J_f(\mathbf{g}(\mathbf{x})) \cdot J_{\mathbf{g}}(\mathbf{x}).$$

Note:-

The linear mapping $df(c)$ is invertible if and only if $J_{\mathbf{f}}(c)$ is nonzero.

0.2 The Inverse Function Theorem

Lemma 0.2.1 Contraction Mapping Principle

Let (X, d) be a complete metric space. Let $\varphi: X \rightarrow X$. Suppose that there exists $M \in [0, 1)$ such that $d(\varphi(x_1), \varphi(x_2)) \leq Md(x_1, x_2)$. (We call it a *contraction mapping*.) Then, there uniquely exists $x_* \in X$ such that $\varphi(x_*) = x_*$.

Proof. Fix any $x_0 \in X$. Since $\{x_j\}_{j \in \mathbb{Z}_+}$, where $x_j = \varphi(x_{j-1})$ for each $j \in \mathbb{Z}_+$, is continuous. It converges to some x_* . As φ is continuous, we have $\varphi(x_*) = x_*$. The uniqueness follows trivially. \square

Note:-

- For each $v \in \mathbb{R}^n \setminus \{0\}$, $|Av| = |v| \cdot |A \frac{v}{|v|}| \leq \|A\|_L \cdot |v|$. The result is trivial when $v = 0$.
- For each $u \in \mathbb{R}^n$ with $|u| = 1$, $|ABu| \leq \|A\|_L |Bu| \leq \|A\|_L \|B\|_L$. Hence, $\|AB\|_L = \|A\|_L \|B\|_L$.
- Given invertible $A \in L(\mathbb{R}^n, \mathbb{R}^n)$, $A^{-1}: \mathbb{R}^n \rightarrow \mathbb{R}^n$ is linear. Moreover, $\|A\|_L > 0$.

Lemma 0.2.2

Given two linear mappings $A, B: \mathbb{R}^n \rightarrow \mathbb{R}^n$ with invertibility of A ,

$$\|A - B\|_L \|A^{-1}\|_L < 1 \implies B \text{ is invertible.}$$

Proof. (Hint: show that $Bx = 0$ has only the trivial solution, i.e., if $x \neq 0$, then $Bx \neq 0$.) \square

Theorem 0.2.1 Inverse Function Theorem

Let $\mathbf{f}: E(\subseteq \mathbb{R}^n) \rightarrow \mathbb{R}^n$ be C^1 in U , $\mathbf{a} \in E$, and $\mathbf{b} = \mathbf{f}(\mathbf{a})$. Suppose that $J_{\mathbf{f}}(\mathbf{a}) \neq 0$. Then,

$$\exists \delta \in \mathbb{R}_+, \mathbf{f}|_{B_\delta(\mathbf{a})}: B_\delta(\mathbf{a}) \rightarrow \mathbf{f}(B_\delta(\mathbf{a})) \text{ is invertible.}$$

Moreover, $\mathbf{f}(B_\delta(a))$ is an open set, and $(\mathbf{f}|_{B_\delta(a)})^{-1}$ is C^1 .

Proof. Let $A \triangleq \mathbf{df}(\mathbf{c})$. Define λ by $\lambda \triangleq \frac{1}{2\|A^{-1}\|_L} > 0$ so $2\lambda\|A^{-1}\|_L = 1$. Since \mathbf{df} is continuous, there exists $\delta \in \mathbb{R}_+$ such that $\|\mathbf{df}(\mathbf{x}) - \mathbf{df}(\mathbf{c})\|_L < \lambda$ for each $B_\delta(\mathbf{c})$.

Given a point $\mathbf{y} \in \mathbb{R}^n$, we define $\varphi(\cdot; \mathbf{y})$ by

$$\begin{aligned}\varphi(\cdot; \mathbf{y}) : B_\delta(\mathbf{c}) &\longrightarrow \mathbb{R}^n \\ \mathbf{x} &\longmapsto \varphi(\mathbf{x}; \mathbf{y}) = \mathbf{x} + A^{-1}(\mathbf{y} - \mathbf{f}(\mathbf{x}))\end{aligned}$$

Note that \mathbf{x} is a fixed point of $\varphi(\cdot; \mathbf{y})$ if and only if $A^{-1}(\mathbf{y} - \mathbf{f}(\mathbf{x})) = 0$, i.e., $\mathbf{y} = \mathbf{f}(\mathbf{x})$. Note also that φ is differentiable and $\mathbf{d}\varphi(\mathbf{x}; \mathbf{y}) = \text{Id} - A^{-1}\mathbf{df}(\mathbf{x}) = A^{-1}(A - \mathbf{df}(\mathbf{x}))$ for each $\mathbf{x} \in B_\delta(\mathbf{c})$. Let $U \triangleq B_\delta(\mathbf{c})$ and $V \triangleq \mathbf{f}(U)$.

Hence, for all $\mathbf{x} \in U$,

$$\|\mathbf{d}\varphi(\mathbf{x}; \mathbf{y})\|_L = \|A^{-1}(A - \mathbf{df}(\mathbf{x}))\|_L \leq \|A^{-1}\|_L \cdot \|A - \mathbf{df}(\mathbf{x})\|_L < 1/(2\lambda) \cdot \lambda = 1/2.$$

Now, fix any $\mathbf{y} \in V$. Fix $\mathbf{x}_1, \mathbf{x}_2 \in U$. Define $\Psi : [0, 1] \rightarrow \mathbb{R}$ by $t \mapsto \varphi(t\mathbf{x}_1 + (1-t)\mathbf{x}_2; \mathbf{y})$. $\Psi(0) = \varphi(\mathbf{x}_2; \mathbf{y})$ and $\Psi(1) = \varphi(\mathbf{x}_1; \mathbf{y})$. Note that Ψ is differentiable on $(0, 1)$. By MVT, there exists $t_* \in (0, 1)$ such that $\Psi(1) - \Psi(0) = \Psi'(t_*)$. The chain rule gives

$$\Psi'(t_*) = \mathbf{d}\varphi(t_*\mathbf{x}_1 + (1-t_*)\mathbf{x}_2)(\mathbf{x}_1 - \mathbf{x}_2).$$

Hence,

$$|\varphi(\mathbf{x}_1) - \varphi(\mathbf{x}_2)| = |\mathbf{d}\varphi(t_*\mathbf{x}_1 + (1-t_*)\mathbf{x}_2)| \cdot |\mathbf{x}_1 - \mathbf{x}_2| \leq |\mathbf{x}_1 - \mathbf{x}_2|/2.$$

We want to show that \mathbf{f} is locally invertible. It suffices to show that it is injective. Hence, φ has at most one fixed point, i.e., there exists at most one \mathbf{x} such that $\mathbf{y} = \mathbf{f}(\mathbf{x})$; thus \mathbf{f} is injective on U .

Let $\mathbf{x}_0 \in U$ and $\mathbf{y}_0 = \mathbf{f}(\mathbf{x}_0)$. Fix any $r \in \mathbb{R}_+$ such that $\overline{B_r(\mathbf{x}_0)} \subseteq U$. Let $B = B_r(\mathbf{x}_0)$. Take any $\mathbf{y} \in B_{\lambda r}(\mathbf{y}_0)$. Then,

$$|\varphi(\mathbf{x}_0; \mathbf{y}) - \mathbf{x}_0| = |A^{-1}(\mathbf{y} - \mathbf{y}_0)| < \|A^{-1}\|_L \lambda r = \frac{r}{2}.$$

Moreover, for any $\mathbf{x} \in \overline{B}$,

$$|\varphi(\mathbf{x}; \mathbf{y}) - \mathbf{x}_0| \leq |\varphi(\mathbf{x}; \mathbf{y}) - \varphi(\mathbf{x}_0; \mathbf{y})| + |\varphi(\mathbf{x}_0; \mathbf{y}) - \mathbf{x}_0| \leq \frac{1}{2}|\mathbf{x} - \mathbf{x}_0| + \frac{r}{2} < r.$$

This directly implies that $\varphi(\overline{B}) \subseteq B \subseteq \overline{B}$. Hence, φ is a contraction mapping on a complete metric space \overline{B} . By ??, there exists a fixed point $\mathbf{x} \in \overline{B}$, which satisfies $\mathbf{y} = \mathbf{f}(\mathbf{x})$. Thus, $\mathbf{y} \in \mathbf{f}(\overline{B}) \subseteq \mathbf{f}(U) = V$. Hence, $B_{\lambda r}(\mathbf{y}_0) \subseteq V$, V is open.

Now, let $\mathbf{g} : V \rightarrow U$ be the local inverse of \mathbf{f} . Take any $\mathbf{y} \in V$ and $\mathbf{y} + \mathbf{k} \in V$. There are unique $\mathbf{x} \in U$ and $\mathbf{x} + \mathbf{h} \in U$ such that $\mathbf{y} = \mathbf{f}(\mathbf{x})$ and $\mathbf{y} + \mathbf{k} = \mathbf{f}(\mathbf{x} + \mathbf{h})$. □

Example 0.2.1 (Level Sets)

Define $\Omega \triangleq \{(x_1, x_2) \in \mathbb{R}^2 \mid |x_2| \leq 1\}$. Given two constants, $a, b \in \mathbb{R}$ with $a < b$, define $\overline{\varphi}(x_1, x_2) = ax_1$ and $\overline{\psi}(x_1, x_2) = bx_1$. Then, $\Gamma_0 = \{\mathbf{x} \in \Omega \mid \overline{\varphi}(\mathbf{x}) - \overline{\psi}(\mathbf{x}) = 0\} = \{\mathbf{x} \in \Omega \mid x_1 = 0\}$.