



A graph interpreter for DSP/ML stream-based processing

IoT-SW
4Q24

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Summary : DSP/ML is complex and it slows time-to-market

Complexity from the “physical domains” and the “software computation domains”

⇒ Split the problem in smaller pieces (“computing nodes”), let them have the same prototype

⇒ Create a framework to ease integration of DSP pre-processing coupled with classifiers using AI-Tile



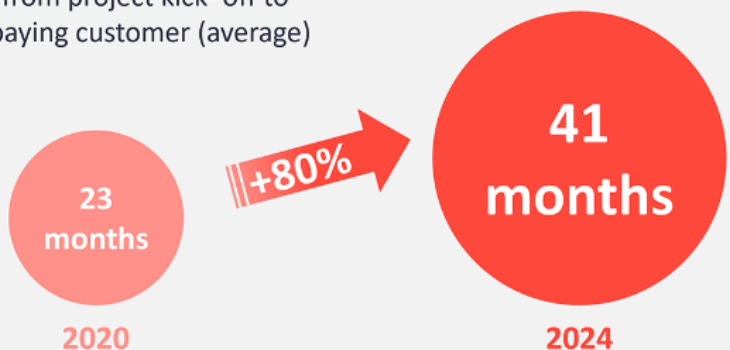
April 2024

Your Global IoT Market Research Partner

Time to market for IoT-connected products

Time-to-market* has increased by 80%

Time from project kick-off to first paying customer (average)



4 key reasons

- 1 Increased product complexity
- 2 Regulatory hurdles
- 3 Higher security scrutiny
- 4 More advanced use cases

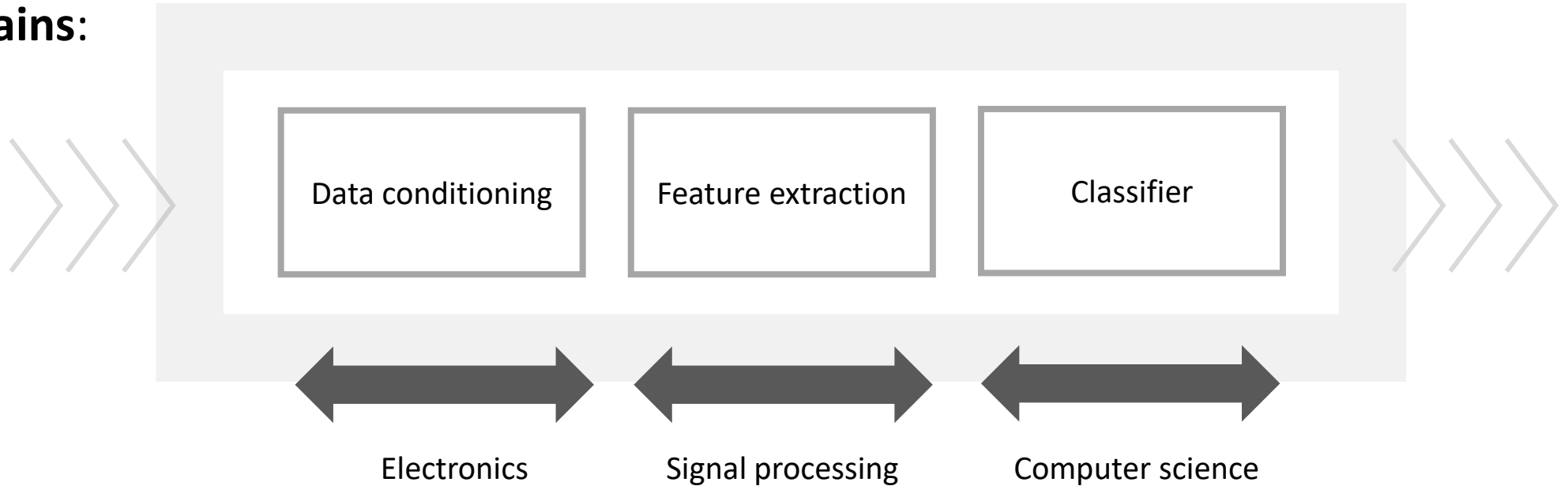
Note: *Time to market = time needed (in months) to get from project kick-off to first paying customer.

Source: IoT Analytics Research 2024 – IoT Commercialization & Business Model Adoption Report 2024. We welcome republishing of images but ask for source citation with a link to the original post and company website.

Stream-based processing - different domains of expertise

Different **data**
physical domains:

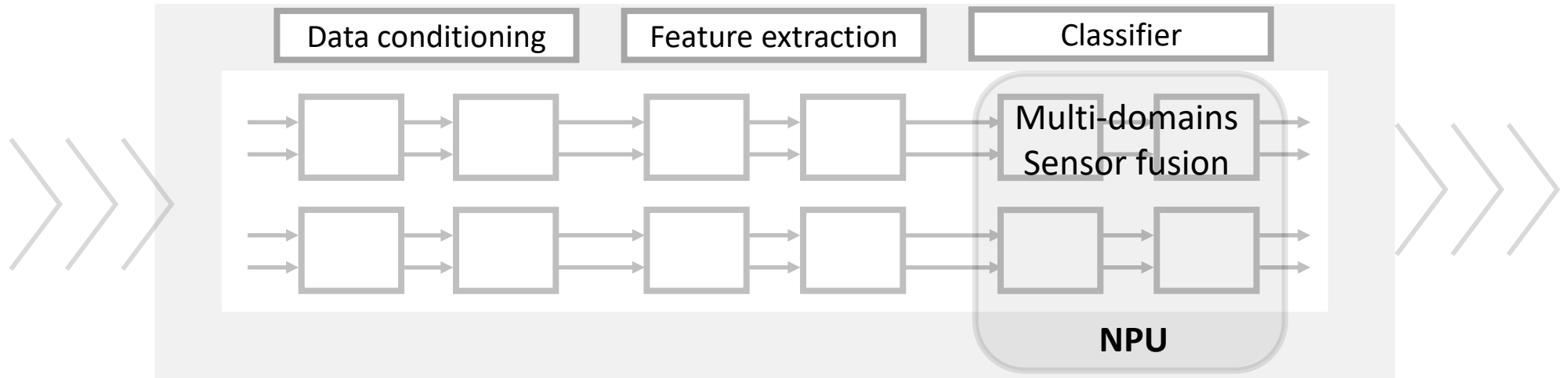
- Acoustics
- Electrical
- Chemical
- Mechanical
- ...



Different **software engineering domains**

Stream-based processing with graph of computing nodes

- Acoustics
- Electrical
- Chemical
- Mechanical
- ...

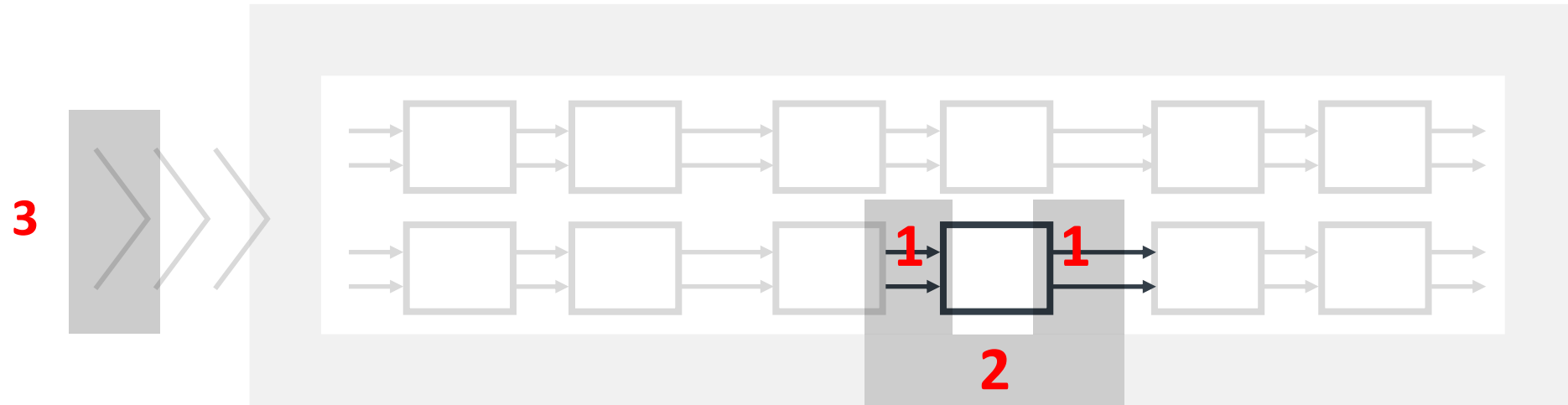


Stream-processing implemented with a graph of computing nodes **designed independently** (different providers)

The proof of concept is in production with the graph of [EEMBC audiomark](#) using a [classifier node](#) (Key Word Spotting) running with or without Ethos-U55 with the same interface.

Manifests of interfaces for Nodes, Graph-I/O, Processor

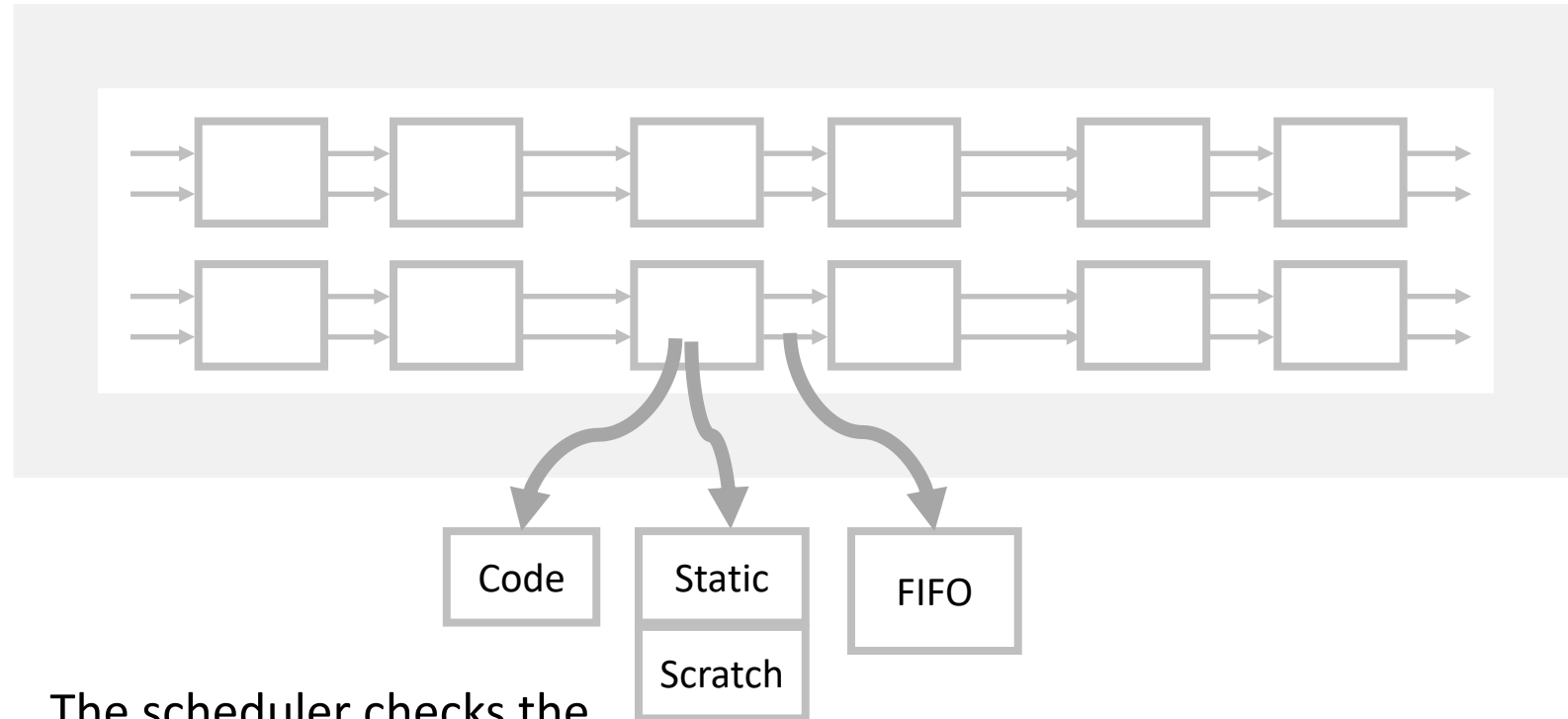
Stream-processing implemented with a graph of computing nodes



- 1 Inter-node interface** : data format (sampling rate, interleaving, raw format, frame size)
- 2 Processor interface** with nodes : memory allocation and TCM, compute libraries and AI-Tile
- 3 Graph-I/O interfaces** : buffering and polling scheme, mixed-signal configuration of the domains

Graph interpreter and scheduler

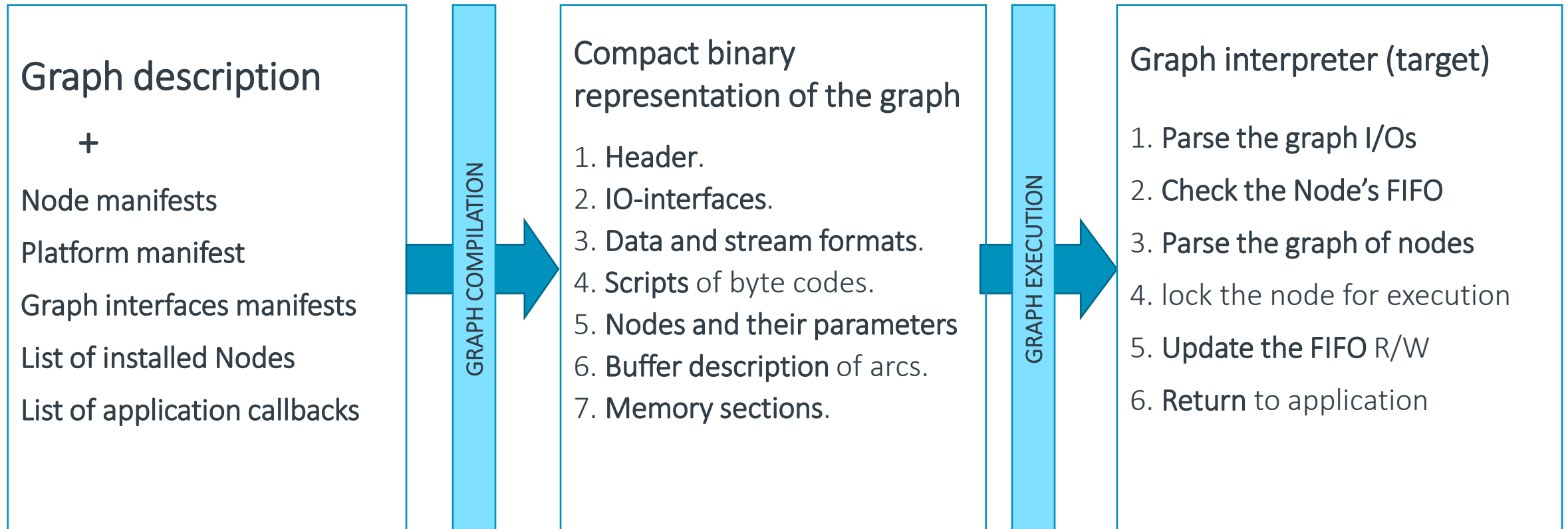
The compiled graph is a linked-list with references to memory buffers and node addresses



The scheduler checks the FIFO buffers before calling a node instance

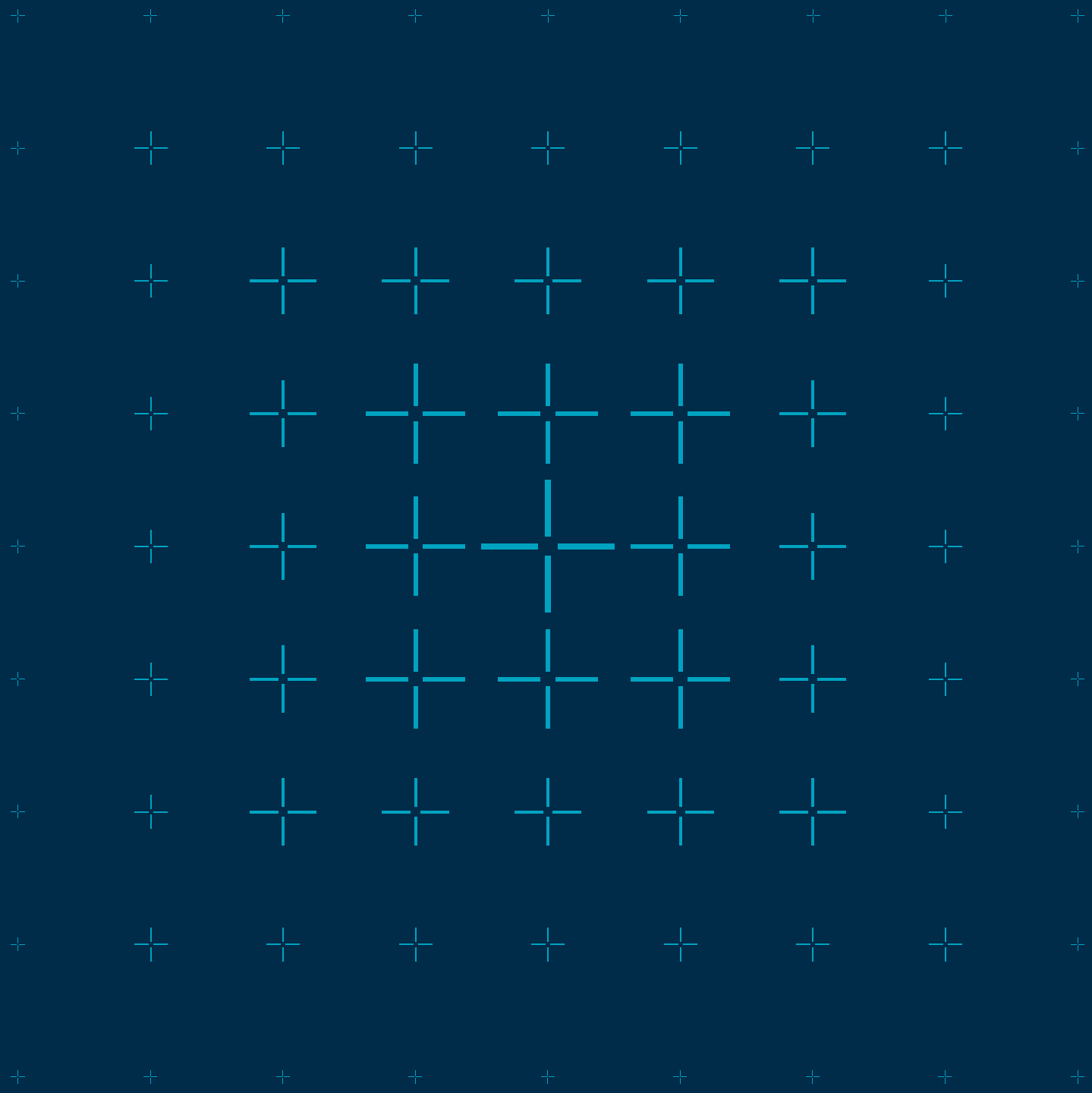
Process

“manifests” are helping the “graph compiler” to prepare the memory map and the data flow between Nodes

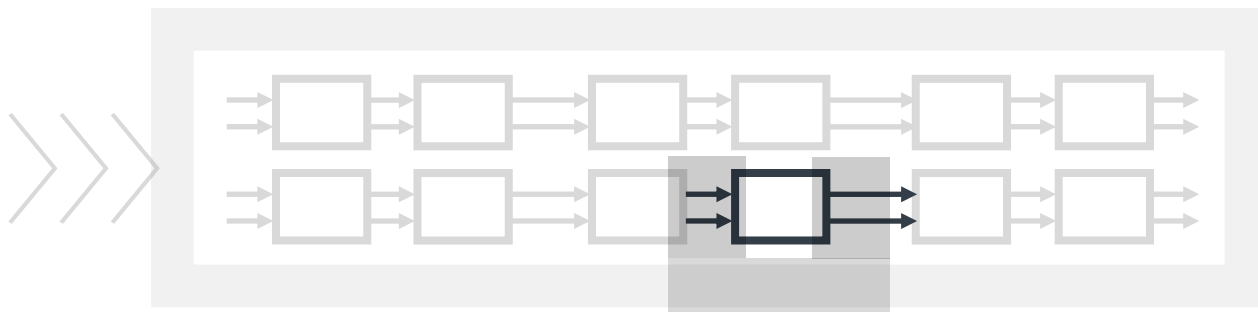


arm

Graph design



Manifests of Nodes



1 Inter-node interface and interface with the platform :

a text file (readable syntax)

done once at node delivery

```
-----  
; SOFTWARE COMPONENT MANIFEST - "arm_stream_filter"  
-----  
;  
node_developer_name    ARM          ; developer name  
node_name              arm_stream_filter ; node name  
  
node_using_arc_format  1            ; to let filter manage q15 and fp32  
node_mask_library      64          ; dependency with DSP services  
  
-----  
; MEMORY ALLOCATIONS  
-----  
  
node_mem               0            ; first memory bank (node instance)  
node_mem_alloc         76          ; amount of bytes  
  
node_mem               1            ; second memory bank (node fast working area)  
node_mem_alloc         52          ;  
node_mem_type          1            ; working memory  
node_mem_speed         2            ; critical fast  
  
-----  
; ARCS CONFIGURATION  
node_arc               0  
node_arc_nb_channels   {1 1 2}    ; arc interleaved, options for the number of channels  
node_arc_raw_format    {1 17 27}  ; options for the raw format STREAM_S16, STREAM_FP32  
  
node_arc               1  
node_arc_nb_channels   {1 1 2}    ; options for the number of channels  
node_arc_raw_format    {1 17 27}  ; options for the raw format STREAM_S16, STREAM_FP32  
  
end
```

Graph (a text file : manual input or generated by a GUI)

Nodes

```
arm_stream_filter 0

parameters
  1 u8; 0
  2 u8; 2 0
  5 h16; 1231 1D28 1231 63E8 D475
  5 h16; 1231 0B34 1231 2470 9821
_end_
```

Node name instance index Boot preset,
Options : Memory allocation, pre/post processing script,
Dedicated architecture, processor (or any), priority, trace verbose level
Memory mapping of each segment

Arcs

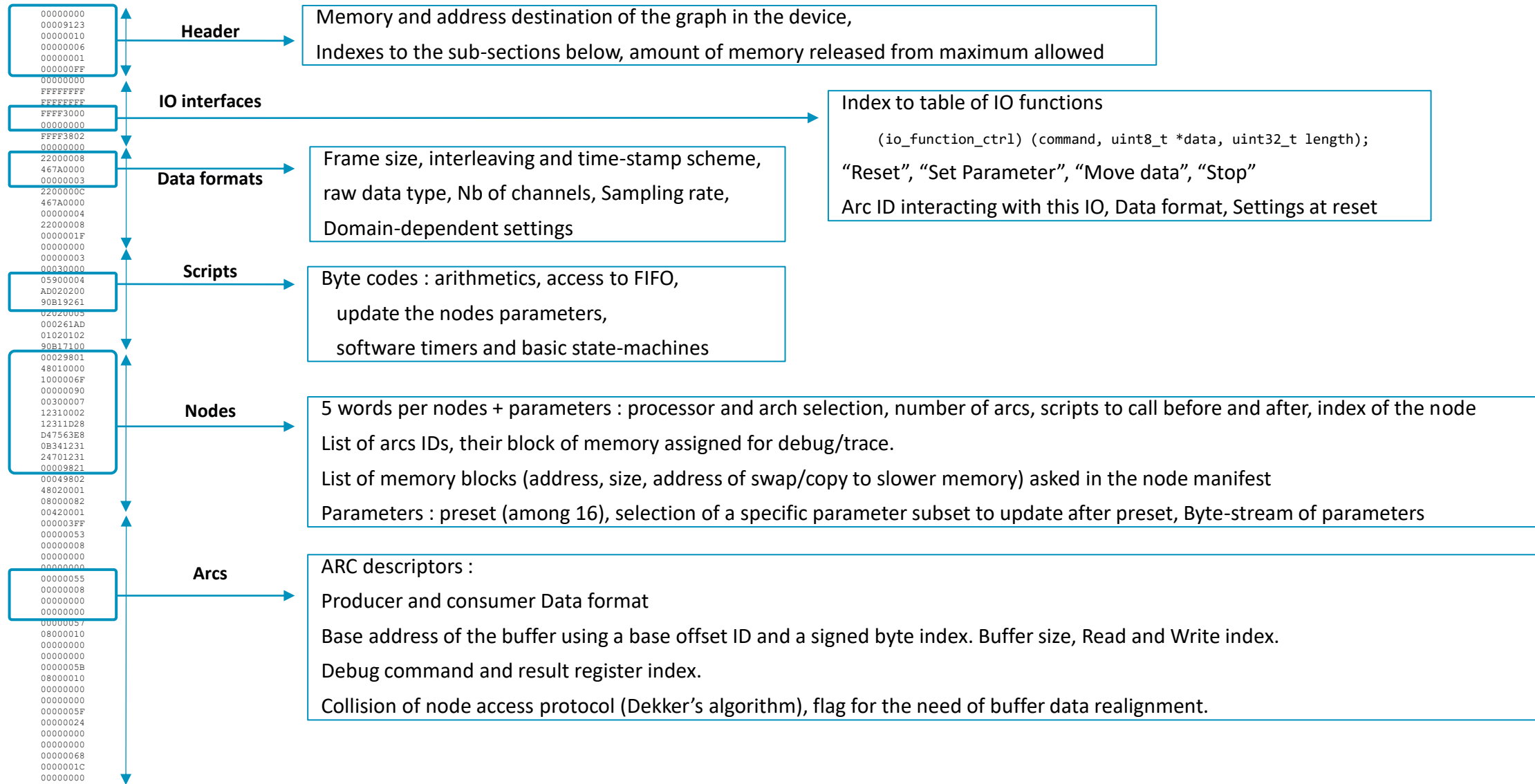
```
arm_stream_filter      0 1
arm_stream_detector    0 0
```

Node name instance index arc output index
Node name instance index arc input index

```
_graph_interface      4 1
arm_stream_filter      0 0
```

BOUNDARY ARCS
Index of the IO

“Compiled” Graph (used by the scheduler)



Root file of the platform details (all the manifests used by the translation tool)

```
; -----  
; list of paths for the included files  
  
3                                     three file paths  
../../../../stream_platform/        "" path index 0 is local  
../../../../stream_platform/windows/manifest/ "" path index 1  
../../../../stream_nodes/           "" path index 2  
  
; -----  
; PLATFORM DIGITAL, MIXED-SIGNAL AND IO MANIFESTS - max 32 IOs => iomask  
  
1 platform_manifest_computer.txt    path index + file name  
; path + manifests file + index used in the graph + processor affinity bit-field +  
  
10 number of IO streams available    aligned with struct platform_io_control plat  
;Path Manifest fw io idx ProcCtrl clock-domain definition (c  
1 io_platform_data_in_0.txt 0 1 0 application processor #c  
1 io_platform_data_in_1.txt 1 1 0 application processor #c  
1 io_platform_analog_sensor_0.txt 2 1 0 ADC #c  
1 io_platform_motion_in_0.txt 3 1 0 accelero=gyro #c  
1 io_platform_audio_in_0.txt 4 1 0 microphone #c  
1 io_platform_2d_in_0.txt 5 1 0 camera #c  
1 io_platform_line_out_0.txt 6 1 0 audio out stereo #c  
1 io_platform_gpio_out_0.txt 7 1 0 GPIO/LED #c  
1 io_platform_gpio_out_1.txt 8 1 0 GPIO/PWM #c  
1 io_platform_data_out_0.txt 9 1 0 application processor #c  
  
; -----  
; SOFTWARE COMPONENTS MANIFESTS  
  
19 nodes path index + file name, in the same order of p_stream_node node_entry_  
  
; p_stream_node node_entry_point_table[NB_NODE_ENTRY_POINTS] =  
; /* 0 node disabled */  
2 Basic/arm/script/swc_manifest_script.txt /* 1 arm_script  
2 Basic/arm/router/swc_manifest_router.txt /* 2 arm_stream_router  
2 Basic/arm/converter/swc_manifest_converter.txt /* 3 arm_stream_convert  
2 Basic/arm/amplifier/swc_manifest_amplifier.txt /* 4 arm_stream_amplifi  
2 Basic/arm/mixer/swc_manifest_mixer.txt /* 5 arm_stream_mixer  
2 Audio/arm/filter/swc_manifest_filter.txt /* 6 arm_stream_filter  
2 Audio/arm/detector/swc_manifest_detector.txt /* 7 arm_stream_detectc  
2 Basic/arm/rescaler/swc_manifest_rescaler.txt /* 8 arm_stream_rescale  
2 Audio/arm/compressor/swc_manifest_compressor.txt /* 9 arm_stream_compres  
2 Audio/arm/decompressor/swc_manifest_decompressor.txt /* 10 arm_stream_decompr  
2 Basic/arm/modulator/swc_manifest_modulator.txt /* 11 arm_stream_modulat  
2 Basic/arm/demodulator/swc_manifest_demodulator.txt /* 12 arm_stream_demodul  
2 Basic/arm/interpolator/swc_manifest_interpolator.txt /* 13 arm_stream_interpc  
2 Basic/arm/qos/swc_manifest_qos.txt /* 14 arm_stream_qos  
2 Basic/arm/split/swc_manifest_split.txt /* 15 arm_stream_split  
2 image/arm/detector2D/swc_manifest_detector2D.txt /* 16 arm_stream_detectc  
2 image/arm/filter2D/swc_manifest_filter2D.txt /* 17 arm_stream_filter2  
2 image/arm/interpolator2D/swc_manifest_interpolator2D.txt /* 18 arm_stream_interpc  
2 Basic/arm/synchro/swc_manifest_synchro.txt /* 19 arm_stream_synchrc
```

Processor manifest

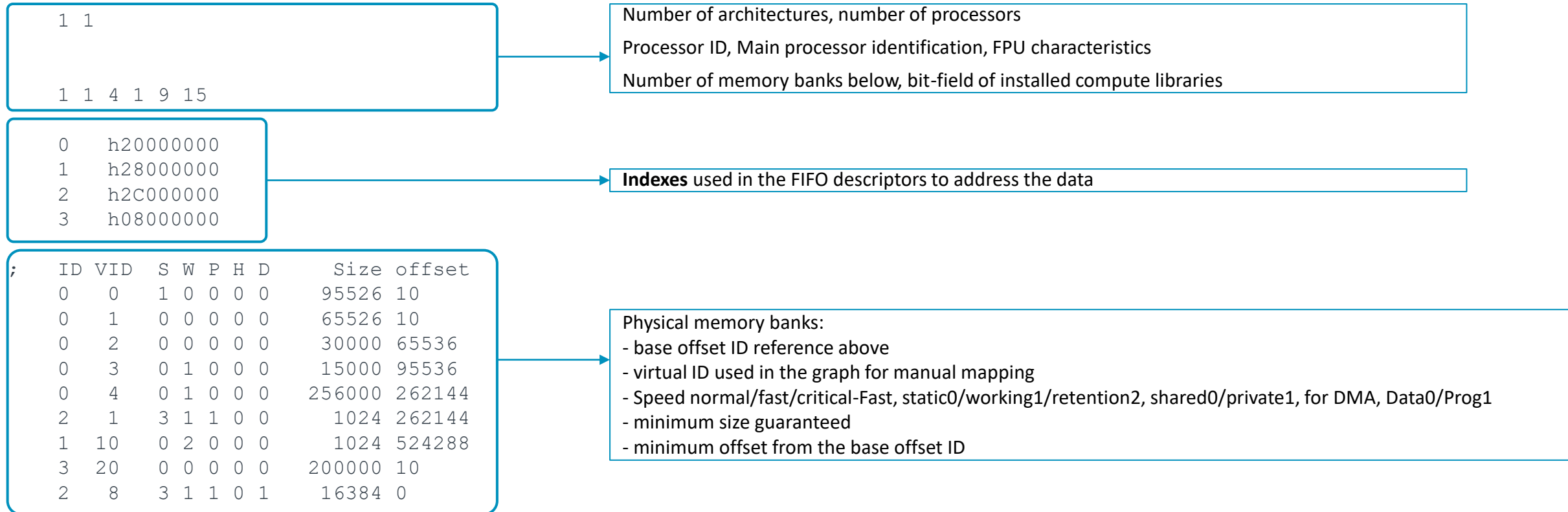
List of available IO for stream processing

Abstraction layer = data move, set buffer, set parameter, stop

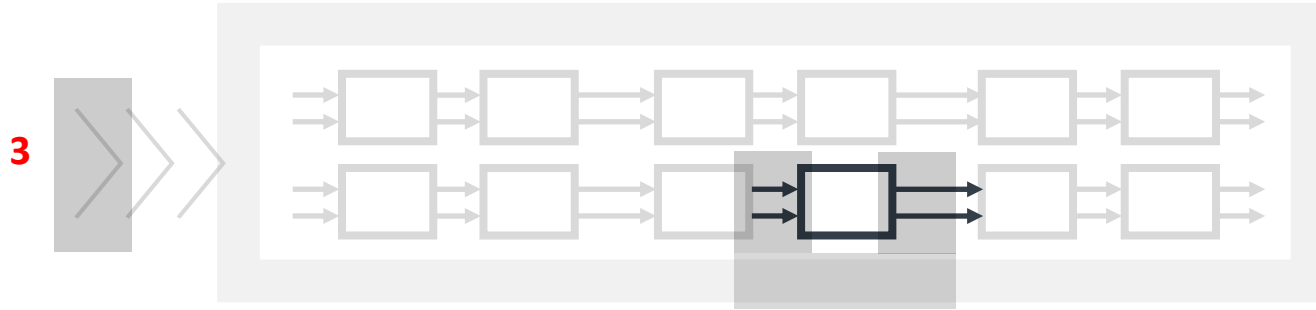
Stream physical domains: generic data_stream, audio, gpio, motion, 2D, analog_sensor, analog_transducer, rtc

List of available Nodes

Processor manifest : memory mapping



Manifests of interfaces for Graph-I/Os



3 Graph-I/O interfaces :

a text file (readable syntax)

done once at platform manufacturing

```
io_platform_sensor_in_0      ; name for the tools
analog_in                    ; domain name, unit: dB, Vrms, mV/Gauss, dps, kWh, ...

io_commander0_servant1 1     ; commander=0 servant=1 (default is servant)
io_buffer_allocation 2.0 1    ; default is 0, which means the buffer is declared outside of the graph, VID 1
io_direction_rx0tx1 1        ; direction of the stream 0:input 1:output from graph point of view
io_raw_format {1 17}         ; options for the raw arithmetics computation format here STREAM_S16
io_nb_channels {1 1 2}       ; multichannel interleaved (0), deinterleaved by frame-size (1) + options for the number of channels
io_frame_length {1 2 16}     ; [ms]0/[samp]1 + options of possible frame_size
io_subtype_units 104         ; depending on the domain. Here Units_Vrms of the "general" domain (0 = any or underfined)
io_analogscale 0.55          ; 0.55V is corresponding to full-scale (0x7FFF or 1.0f) with the default setting
io_sampling_rate {1 16000 44100 48000} ; sampling rate options (enumeration in Hz)
io_rescale_factor 12.24 -44.3 ; [1/a off] analog_input = invinterpa x ((samples/Full_Scale_Digital) - interpooff)
end
```

Graph API (one entry-point to the scheduler)

1) Graph interpreter interface for the application :

```
void arm_graph_interpreter (uint32_t command, arm_stream_instance_t *S, uint8_t *data, uint32_t size)
```

Commands : reset the graph, execute, check boundary FIFO filling state and move data in/out, update the use-case

Instance : structure of pointers to the graph, to the installed nodes and application callbacks, to the data stream interfaces functions (below), control fields and static memory of the scheduler instance.

2) Stream interfaces used by the scheduler to initiate data moves (abstraction layer of the BSP):

```
void (io_function_ctrl) (uint32_t command, uint8_t *data, uint32_t length);
```

Commands : set buffer, set parameters, data move, stop

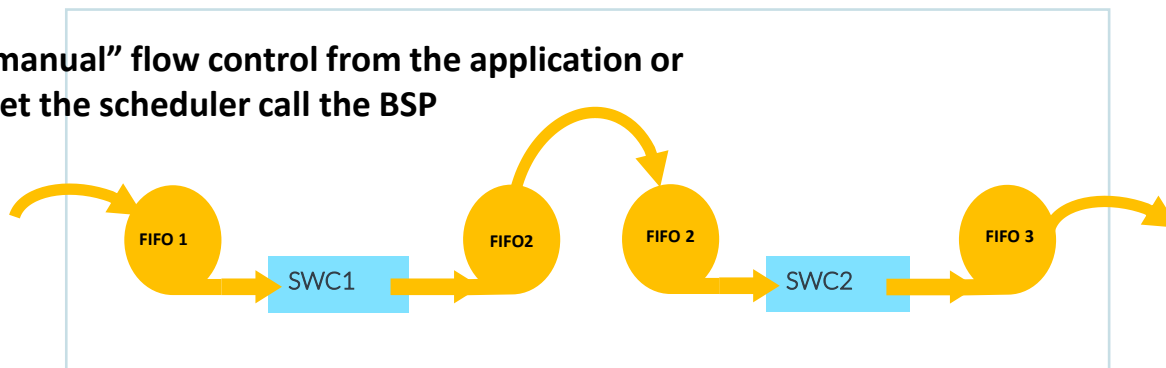
3) One callback, after data moves (to update the FIFO descriptors) :

```
void arm_graph_interpreter_io_ack (uint8_t fw_io_idx, uint8_t *data, uint32_t data_size)
```

4) One prototype for all nodes :

```
void node_XXXX (uint32_t command, void *instance, void *data, uint32_t *status)
```

“manual” flow control from the application or
let the scheduler call the BSP



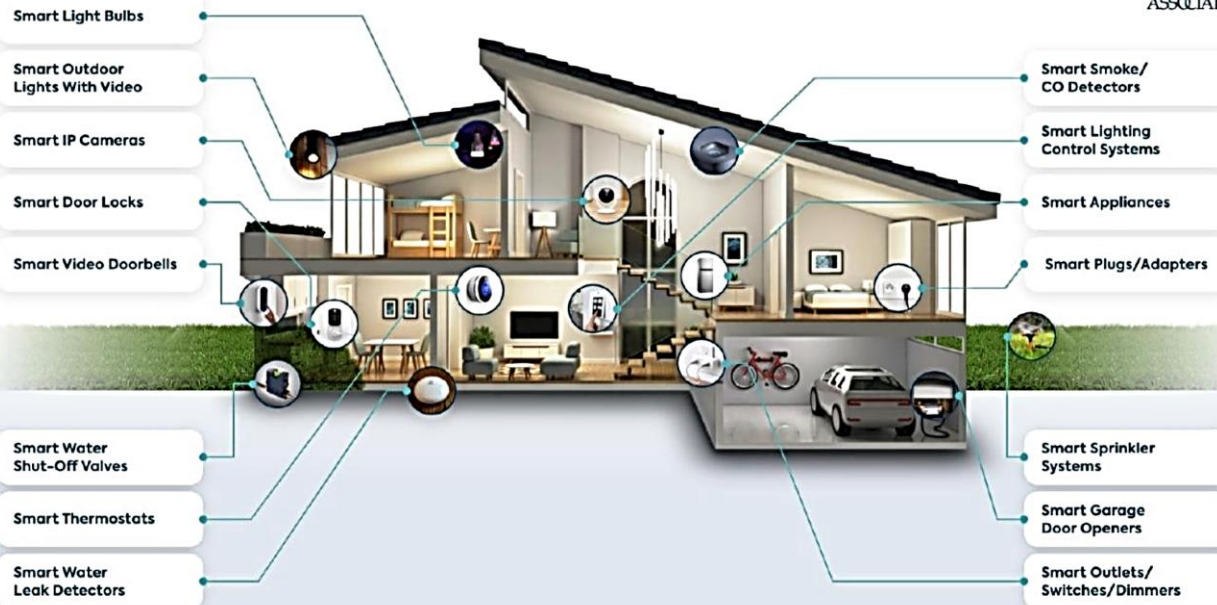
Abstraction layer of IOs : data-move and settings + callback to set the FIFO
or
Data move from the application with same functions for FIFO setting

Next steps : low-code for smart-home sensors

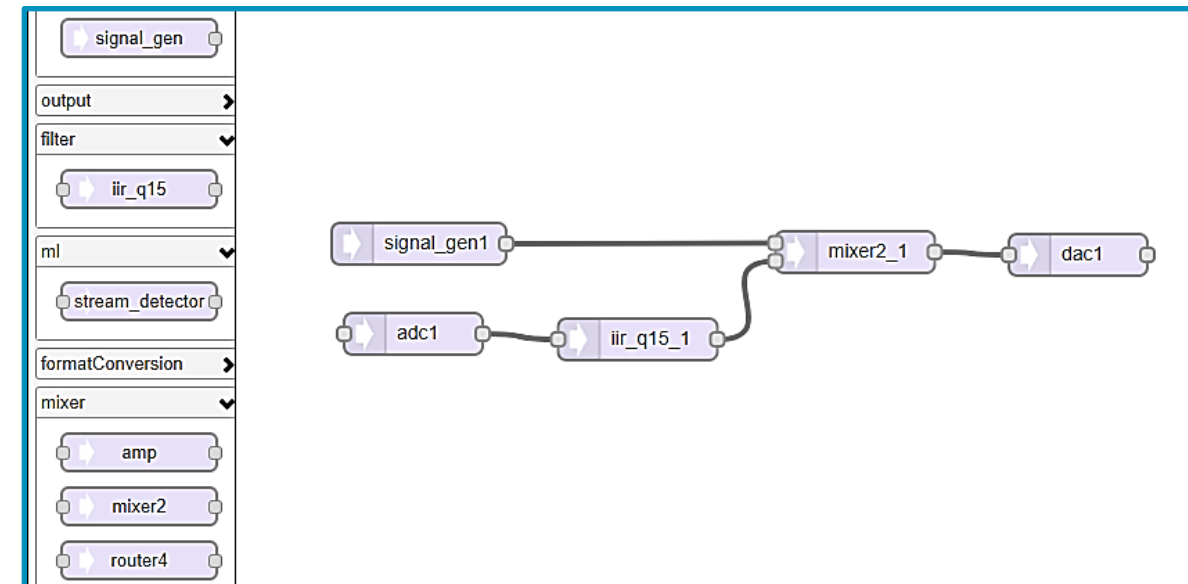
Do we need a complex programming environment to drag and drop software components from a Store ?

Smart Home Devices

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arm

Thank You

Danke

Gracias

Grazie

谢谢

ありがとう

Asante

Merci

감사합니다

धन्यवाद

Kiitos

شكراً

ধন্যবাদ

תודה

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