

COURS (M2) RdFIA

Matthieu Cord LIP6 / SU
Thanks to N. Thome for sharing slides on NN

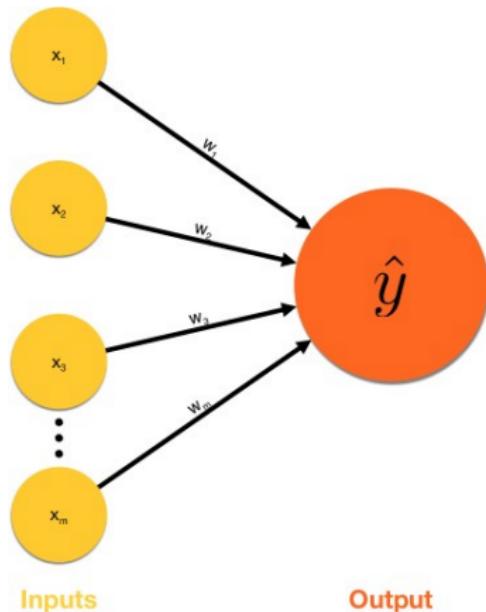
Outline

ConvNets as Deep Neural Networks for Vision

- 1. Neural Nets**
2. Deep Convolutional Neural Networks

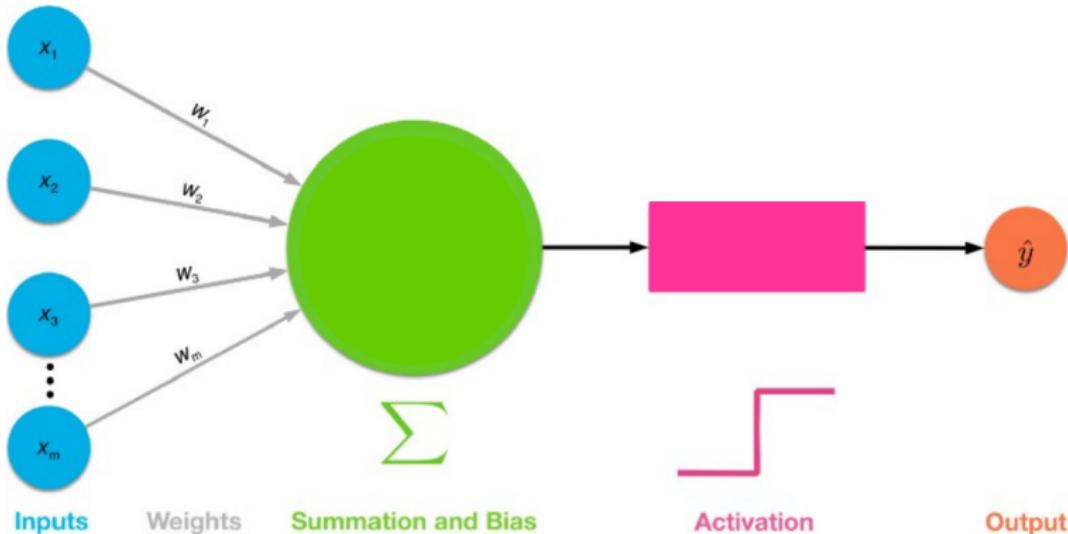
The Formal Neuron: 1943 [MP43]

- ▶ Basis of Neural Networks
- ▶ Input: vector $\mathbf{x} \in \mathbb{R}^m$, i.e. $\mathbf{x} = \{x_i\}_{i \in \{1, 2, \dots, m\}}$
- ▶ Neuron output $\hat{y} \in \mathbb{R}$: scalar



The Formal Neuron: 1943 [MP43]

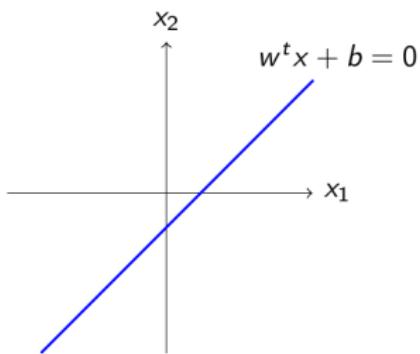
- ▶ Mapping from x to \hat{y} :
 1. Linear (affine) mapping: $s = \mathbf{w}^T \mathbf{x} + b$
 2. Non-linear activation function: f : $\hat{y} = f(s)$



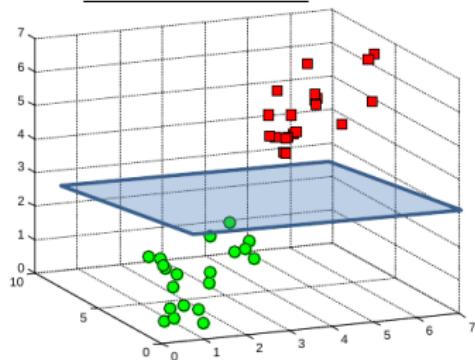
The Formal Neuron: Linear Mapping

- ▶ Linear (affine) mapping: $s = \mathbf{w}^T \mathbf{x} + b = \sum_{i=1}^m w_i x_i + b$
 - ▶ \mathbf{w} : normal vector to an hyperplane in $\mathbb{R}^m \Rightarrow$ **linear boundary**
 - ▶ b bias, shift the hyperplane position

2D hyperplane: line

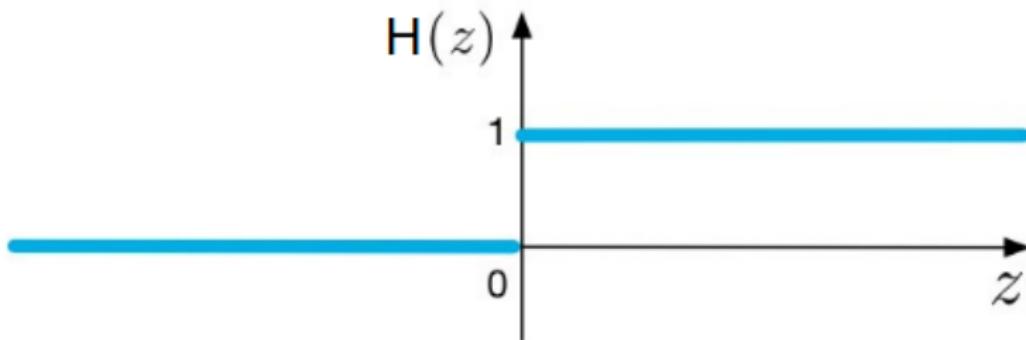


3D hyperplane: plane

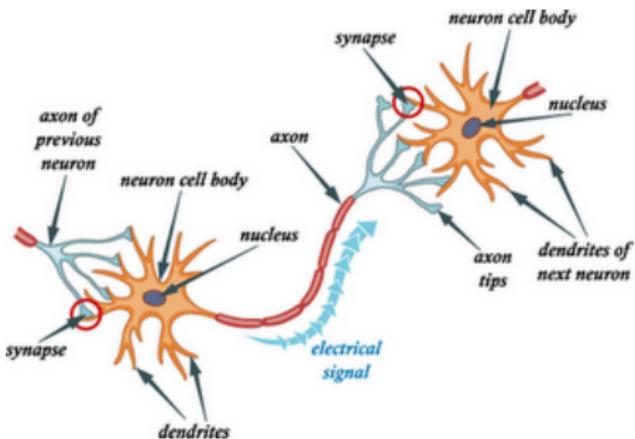
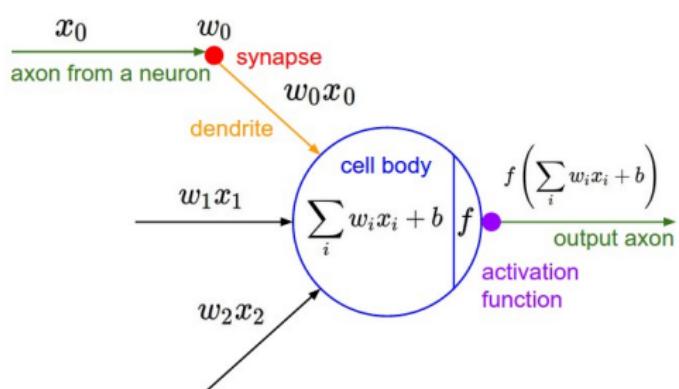


The Formal Neuron: Activation Function

- ▶ $\hat{y} = f(\mathbf{w}^T \mathbf{x} + b)$, f activation function
 - ▶ Popular f choices: step, sigmoid, tanh
- ▶ Step (Heaviside) function: $H(z) = \begin{cases} 1 & \text{if } z \geq 0 \\ 0 & \text{otherwise} \end{cases}$



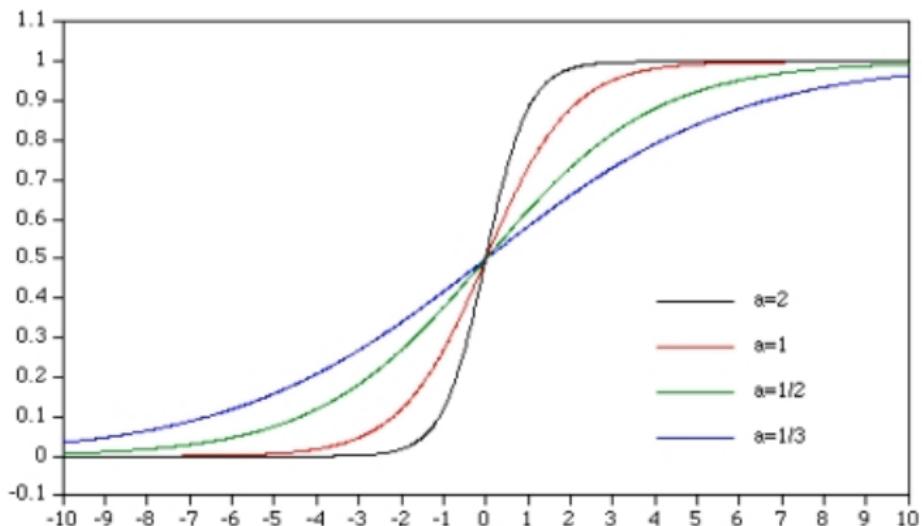
Step function: Connection to Biological Neurons



- ▶ Formal neuron, step activation H : $\hat{y} = H(\mathbf{w}^T \mathbf{x} + b)$
 - ▶ $\hat{y} = 1$ (activated) $\Leftrightarrow \mathbf{w}^T \mathbf{x} \geq -b$
 - ▶ $\hat{y} = 0$ (unactivated) $\Leftrightarrow \mathbf{w}^T \mathbf{x} < -b$
- ▶ **Biological Neurons:** output activated
 \Leftrightarrow input weighted by synaptic weight \geq threshold

Sigmoid Activation Function

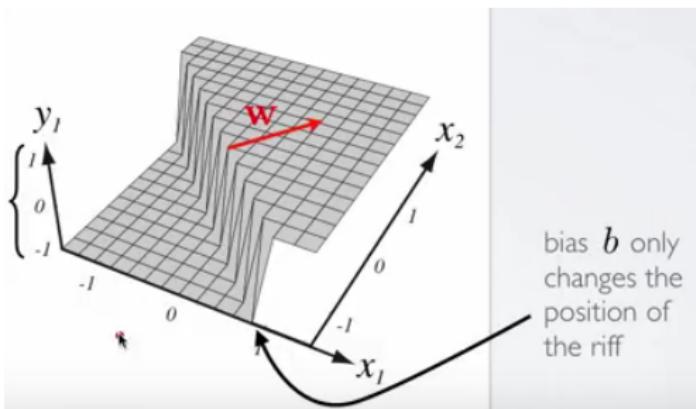
- ▶ Neuron output $\hat{y} = f(\mathbf{w}^T \mathbf{x} + b)$, f activation function
- ▶ Sigmoid: $\sigma(z) = (1 + e^{-az})^{-1}$



- ▶ $a \uparrow$: more similar to step function (step: $a \rightarrow \infty$)
- ▶ Sigmoid: linear and saturating regimes

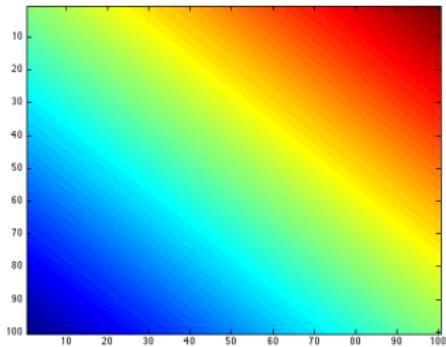
The Formal neuron: Application to Binary Classification

- ▶ Binary Classification: label input x as belonging to class 1 or 0
- ▶ Neuron output with sigmoid: $\hat{y} = \frac{1}{1+e^{-a(w^T x + b)}}$
- ▶ Sigmoid: probabilistic interpretation $\Rightarrow \hat{y} \sim P(1/x)$
 - ▶ Input x classified as 1 if $P(1/x) > 0.5 \Leftrightarrow w^T x + b > 0$
 - ▶ Input x classified as 0 if $P(1/x) < 0.5 \Leftrightarrow w^T x + b < 0$
 $\Rightarrow \text{sign}(w^T x + b)$: linear boundary decision in input space !



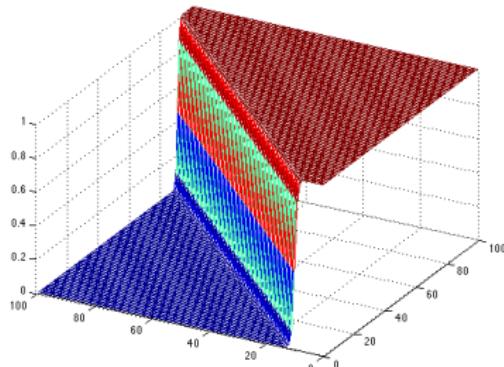
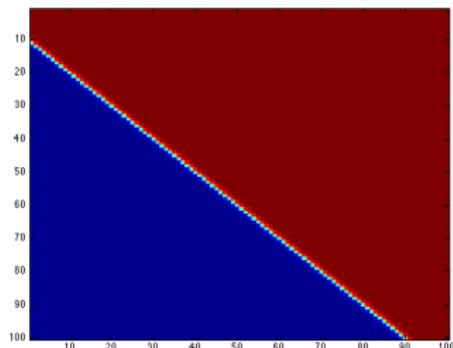
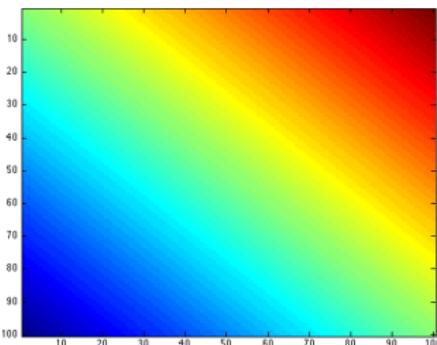
The Formal neuron: Toy Example for Binary Classification

- ▶ 2d example: $m = 2$, $\mathbf{x} = \{x_1, x_2\} \in [-5; 5] \times [-5; 5]$
- ▶ Linear mapping: $\mathbf{w} = [1; 1]$ and $b = -2$
- ▶ Result of linear mapping : $s = \mathbf{w}^T \mathbf{x} + b$



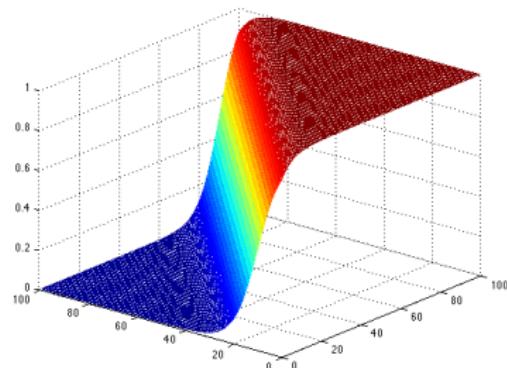
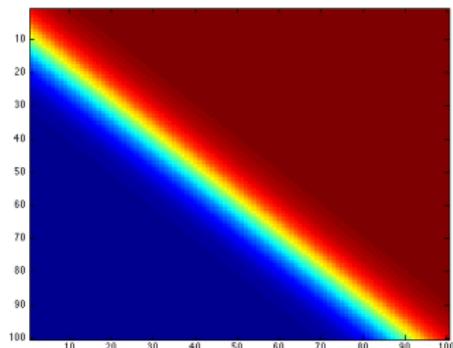
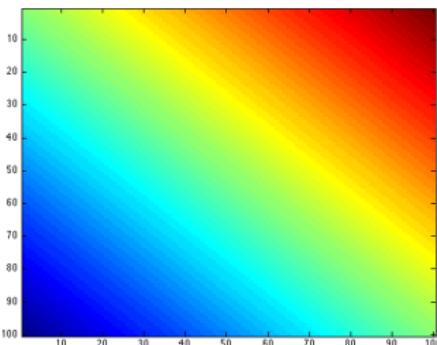
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- ▶ Result of linear mapping : $s = \mathbf{w}^\top \mathbf{x} + b$
- ▶ Sigmoid activation function: $\hat{y} = \left(1 + e^{-a(\mathbf{w}^\top \mathbf{x} + b)}\right)^{-1}$,
 $a = 10$



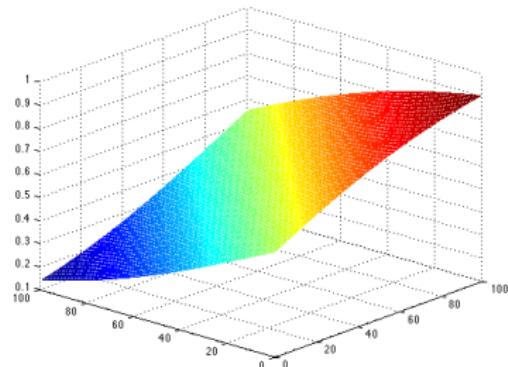
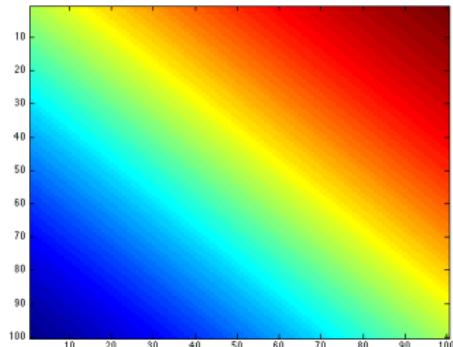
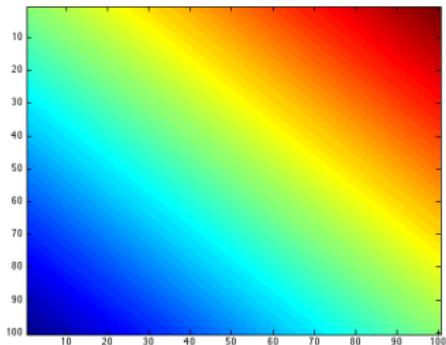
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 $a = 1$



The Formal neuron: Toy Example for Binary Classification

- ▶ 2d example: $m = 2$, $\mathbf{x} = \{x_1, x_2\} \in [-5; 5] \times [-5; 5]$
- ▶ Linear mapping: $\mathbf{w} = [1; 1]$ and $b = -2$
- ▶ Result of linear mapping : $s = \mathbf{w}^T \mathbf{x} + b$
- ▶ Sigmoid activation function: $\hat{y} = \left(1 + e^{-a(\mathbf{w}^T \mathbf{x} + b)}\right)^{-1}$,
 $a = 0.1$



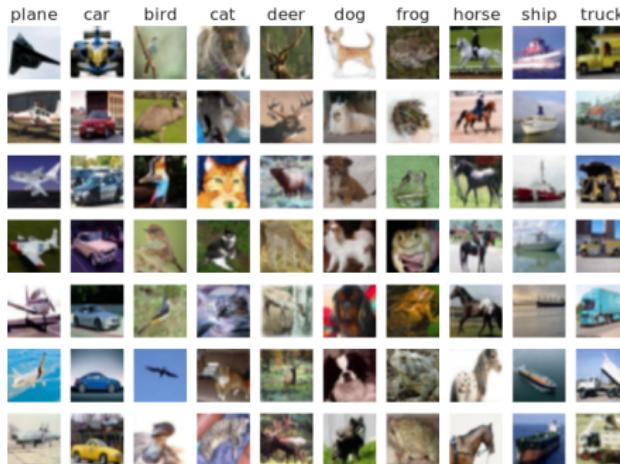
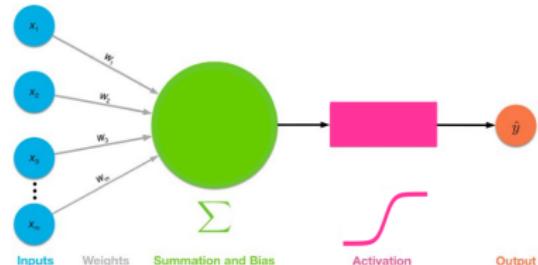
From Formal Neuron to Neural Networks

► Formal Neuron:

1. A single scalar output
2. Linear decision boundary for binary classification

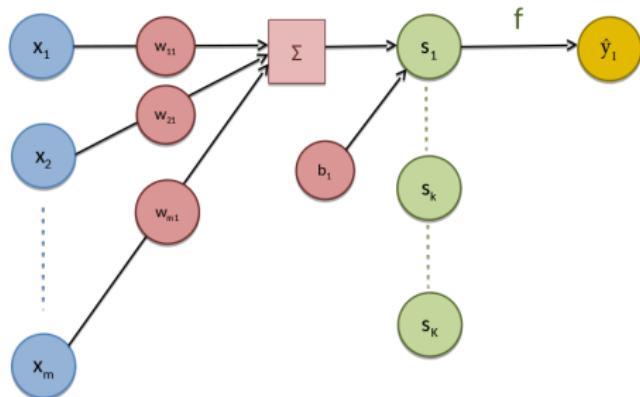
► Single scalar output: limited for several tasks

- Ex: multi-class classification, e.g. MNIST or CIFAR



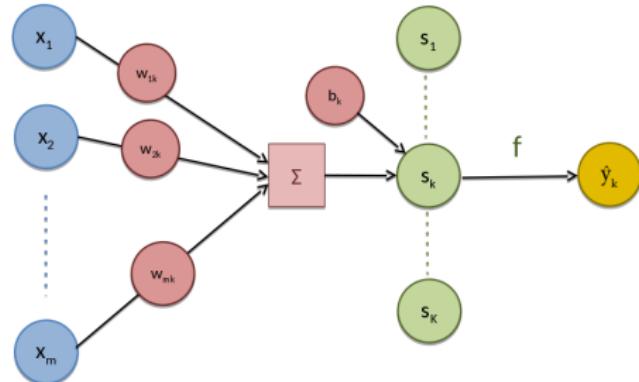
Perceptron and Multi-Class Classification

- ▶ Formal Neuron: limited to binary classification
- ▶ **Multi-Class Classification:** use several output neurons instead of a single one !
⇒ **Perceptron**
- ▶ Input x in \mathbb{R}^m
- ▶ Output neuron \hat{y}_1 is a formal neuron:
 - ▶ Linear (affine) mapping: $s_1 = \mathbf{w}_1^\top \mathbf{x} + b_1$
 - ▶ Non-linear activation function: f :
 $\hat{y}_1 = f(s_1)$
- ▶ Linear mapping parameters:
 - ▶ $\mathbf{w}_1 = \{w_{11}, \dots, w_{m1}\} \in \mathbb{R}^m$
 - ▶ $b_1 \in \mathbb{R}$



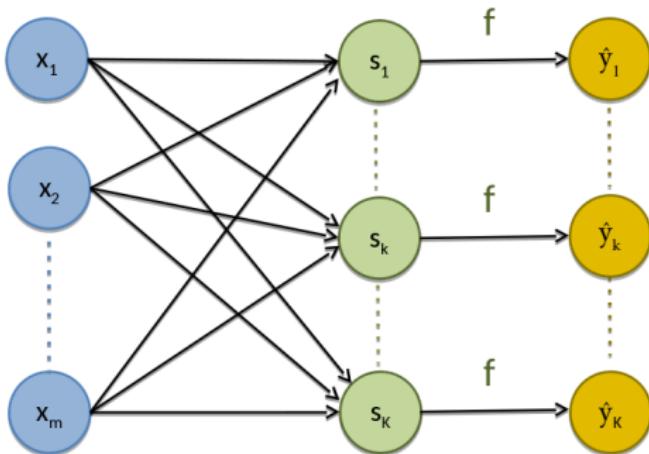
Perceptron and Multi-Class Classification

- ▶ Input x in \mathbb{R}^m
- ▶ Output neuron \hat{y}_k is a formal neuron:
 - ▶ Linear (affine) mapping: $s_k = \mathbf{w}_k^\top x + b_k$
 - ▶ Non-linear activation function: f :
$$\hat{y}_k = f(s_k)$$
- ▶ Linear mapping parameters:
 - ▶ $\mathbf{w}_k = \{w_{1k}, \dots, w_{mk}\} \in \mathbb{R}^m$
 - ▶ $b_k \in \mathbb{R}$



Perceptron and Multi-Class Classification

- ▶ Input $x \in \mathbb{R}^m$ ($1 \times m$), output \hat{y} : concatenation of K formal neurons
- ▶ Linear (affine) mapping \sim matrix multiplication: $s = xW + b$
 - ▶ W matrix of size $m \times K$ - columns are w_k
 - ▶ b : bias vector - size $1 \times K$
- ▶ Element-wise non-linear activation: $\hat{y} = f(s)$



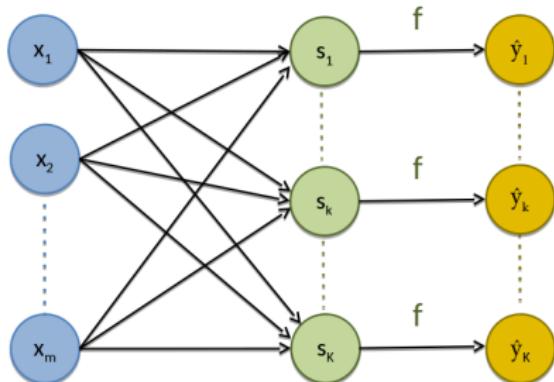
Perceptron and Multi-Class Classification

- ▶ Soft-max Activation:

$$\hat{y}_k = f(s_k) = \frac{e^{s_k}}{\sum_{k'=1}^K e^{s_{k'}}}$$

- ▶ Probabilistic interpretation for multi-class classification:

- ▶ Each output neuron \Leftrightarrow class
- ▶ $\hat{y}_k \sim P(k|\mathbf{x}, \mathbf{w})$

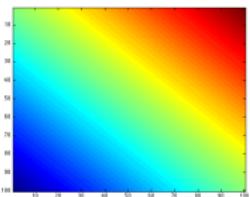


⇒ Logistic Regression (LR) Model !

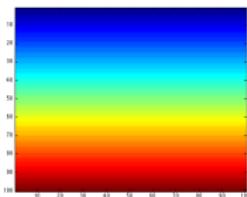
2d Toy Example for Multi-Class Classification

- ▶ $\mathbf{x} = \{x_1, x_2\} \in [-5; 5] \times [-5; 5]$, \hat{y} : 3 outputs (classes)

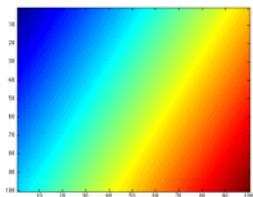
$$\mathbf{w}_1 = [1; 1], b_1 = -2$$



$$\mathbf{w}_2 = [0; -1], b_2 = 1$$



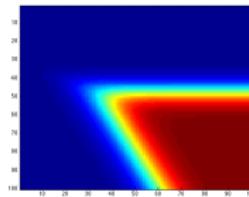
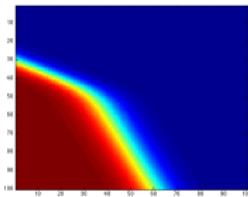
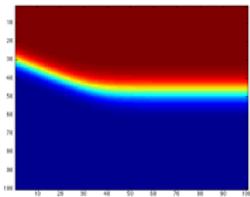
$$\mathbf{w}_3 = [1; -0.5], b_3 = 10$$



Linear mapping for each class:

$$\mathbf{s}_k = \mathbf{w}_k^\top \mathbf{x} + b_k$$

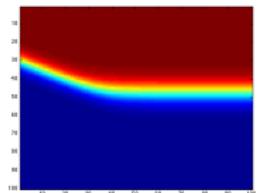
Soft-max output:
 $P(k|\mathbf{x}, \mathbf{W})$



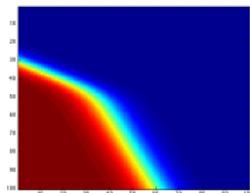
2d Toy Example for Multi-Class Classification

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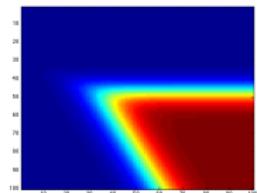
$$\mathbf{w}_1 = [\mathbf{1}; \mathbf{1}], b_1 = -2$$



$$\mathbf{w}_2 = [\mathbf{0}; -\mathbf{1}], b_2 = 1$$

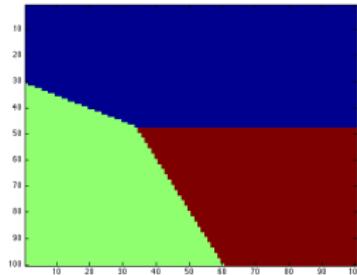


$$\mathbf{w}_3 = [\mathbf{1}; -\mathbf{0.5}], b_3 = 10$$



Soft-max output:
 $P(k/x, \mathbf{W})$

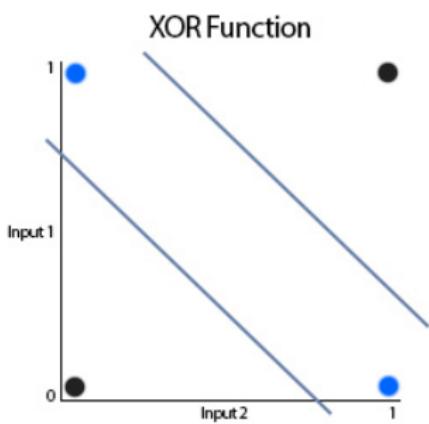
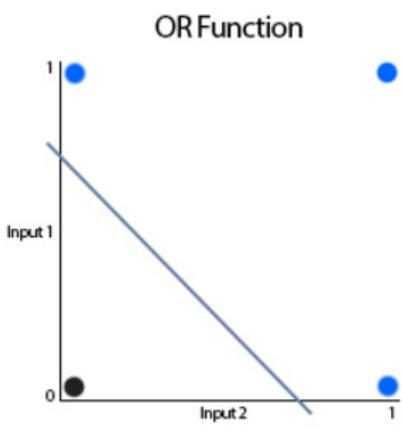
Class Prediction:
 $k^* = \arg \max_k P(k/x, \mathbf{W})$



Beyond Linear Classification

X-OR Problem

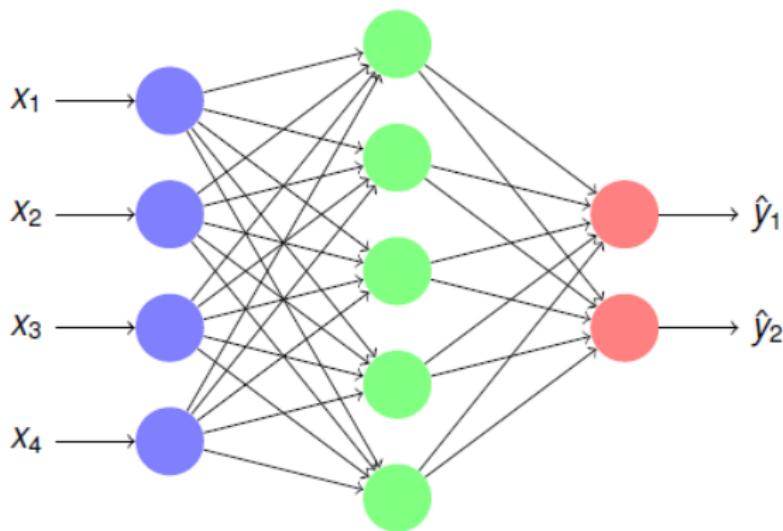
- ▶ Logistic Regression (LR): NN with 1 input layer & 1 output layer
- ▶ LR: limited to linear decision boundaries
- ▶ **X-OR: NOT 1 and 2 OR NOT 2 AND 1**
 - ▶ X-OR: Non linear decision function



Beyond Linear Classification

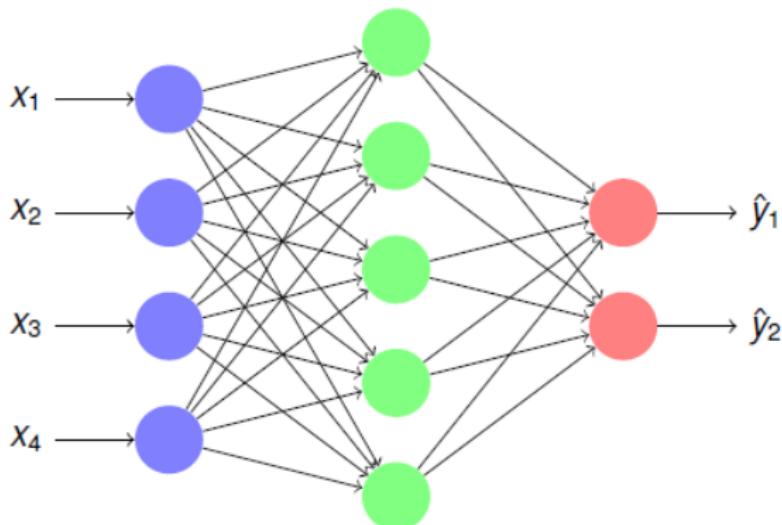
- ▶ LR: limited to linear boundaries
- ▶ Solution: add a layer !

- ▶ Input \mathbf{x} in \mathbb{R}^m , e.g. $m = 4$
- ▶ Output $\hat{\mathbf{y}}$ in \mathbb{R}^K ($K \#$ classes),
e.g. $K = 2$
- ▶ **Hidden layer \mathbf{h} in \mathbb{R}^L**



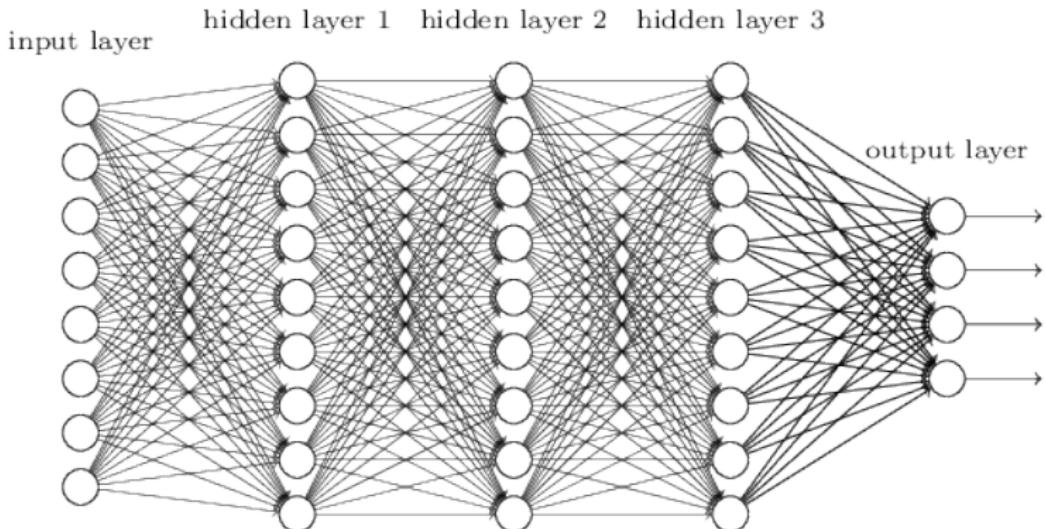
Multi-Layer Perceptron

- ▶ **Hidden layer h :** x projection to a new space \mathbb{R}^L
- ▶ Neural Net with ≥ 1 hidden layer:
Multi-Layer Perceptron (MLP)
- ▶ h : intermediate representations of x for classification \hat{y} : $h = f(xW + b)$
- ▶ **Mapping from x to \hat{y} :** non-linear boundary ! \Rightarrow activation f crucial!



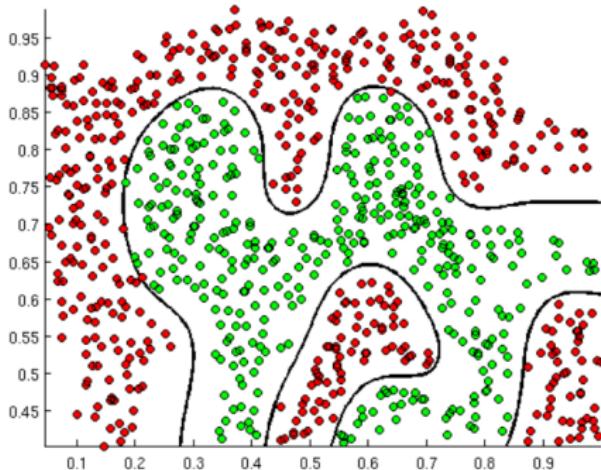
Deep Neural Networks

- ▶ Adding more hidden layers: Deep Neural Networks (DNN) \Rightarrow **Basis of Deep Learning**
- ▶ Each layer \mathbf{h}^l projects layer \mathbf{h}^{l-1} into a new space
- ▶ Gradually learning intermediate representations useful for the task



Conclusion

- ▶ Deep Neural Networks: applicable to classification problems with non-linear decision boundaries



- ▶ Visualize prediction from fixed model parameters
- ▶ Reverse problem: **Supervised Learning**

Outline

Neural Networks

Training Deep Neural Networks

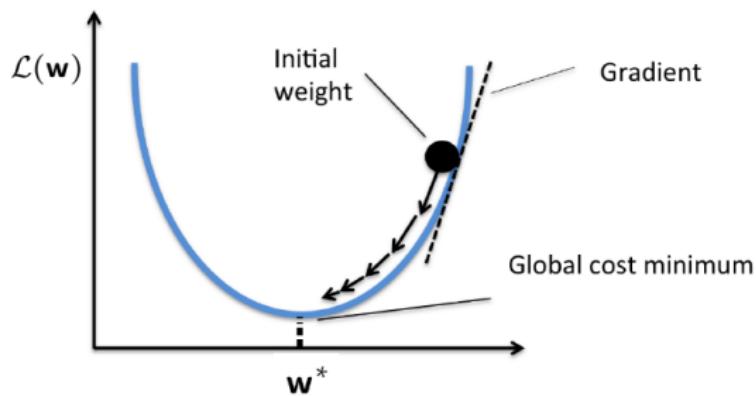
Training Multi-Layer Perceptron (MLP)

- ▶ Input \mathbf{x} , output \mathbf{y}
- ▶ A parametrized (w) model $\mathbf{x} \Rightarrow \mathbf{y}$: $f_w(\mathbf{x}_i) = \hat{\mathbf{y}}_i$
- ▶ Supervised context:
 - ▶ Training set $\mathcal{A} = \{(\mathbf{x}_i, \mathbf{y}_i^*)\}_{i \in \{1, 2, \dots, N\}}$
 - ▶ Loss function $\ell(\hat{\mathbf{y}}_i, \mathbf{y}_i^*)$ for each annotated pair $(\mathbf{x}_i, \mathbf{y}_i^*)$
 - ▶ Goal: Minimizing average loss \mathcal{L} over training set: $\mathcal{L}(w) = \frac{1}{N} \sum_{i=1}^N \ell(\hat{\mathbf{y}}_i, \mathbf{y}_i^*)$
- ▶ Assumptions: parameters $w \in \mathbb{R}^d$ continuous, \mathcal{L} differentiable
- ▶ Gradient $\nabla_w = \frac{\partial \mathcal{L}}{\partial w}$: steepest direction to decrease loss $\mathcal{L}(w)$



MLP Training

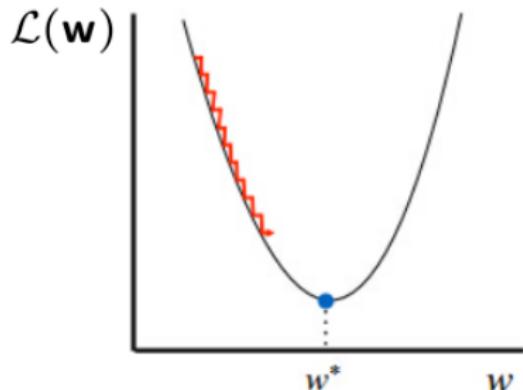
- ▶ Gradient descent algorithm:
 - ▶ Initialize parameters w
 - ▶ Update: $w^{(t+1)} = w^{(t)} - \eta \frac{\partial \mathcal{L}}{\partial w}$
 - ▶ Until convergence, e.g. $\|\nabla_w\|^2 \approx 0$



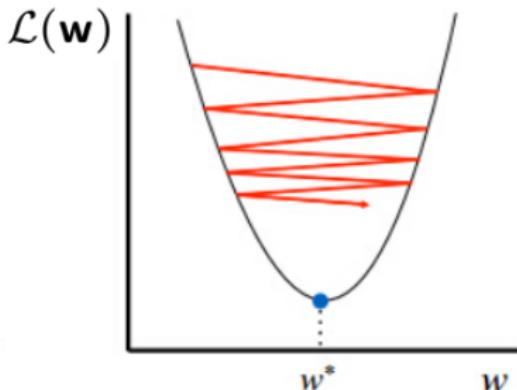
Gradient Descent

Update rule: $\mathbf{w}^{(t+1)} = \mathbf{w}^{(t)} - \eta \frac{\partial \mathcal{L}}{\partial \mathbf{w}}$ η learning rate

- ▶ Convergence ensured ? \Rightarrow provided a "well chosen" learning rate η



Too small: converge
very slowly



Too big: overshoot and
even diverge

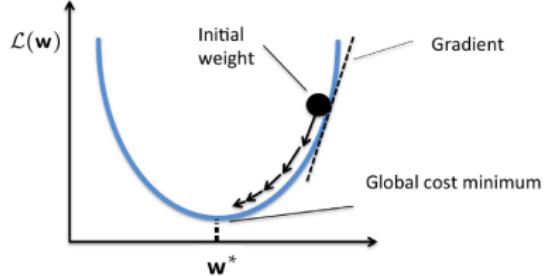
Gradient Descent

Update rule:

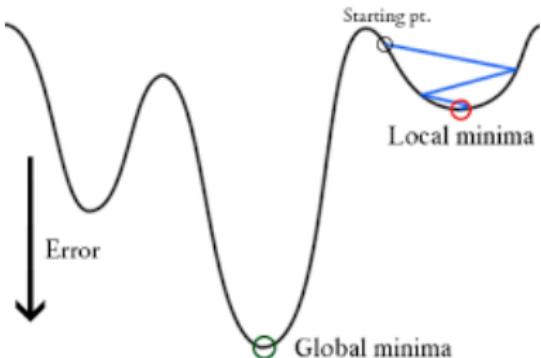
$$\mathbf{w}^{(t+1)} = \mathbf{w}^{(t)} - \eta \frac{\partial \mathcal{L}}{\partial \mathbf{w}}$$

- ▶ **Global minimum ?**

⇒ convex a) vs non convex b) loss $\mathcal{L}(\mathbf{w})$



a) Convex function



a) Non convex function

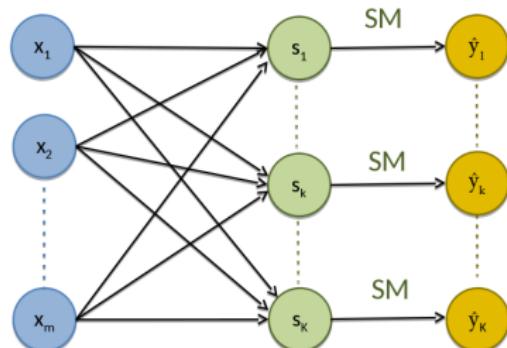
Supervised Learning: Multi-Class Classification

- ▶ Logistic Regression for multi-class classification
- ▶ $s_i = \mathbf{x}_i \mathbf{W} + \mathbf{b}$
- ▶ Soft-Max (SM): $\hat{y}_k \sim P(k/x_i, \mathbf{W}, \mathbf{b}) = \frac{e^{s_k}}{\sum_{k'=1}^K e^{s_{k'}}}$
- ▶ Supervised loss function: $\mathcal{L}(\mathbf{W}, \mathbf{b}) = \frac{1}{N} \sum_{i=1}^N \ell(\hat{y}_i, y_i^*)$

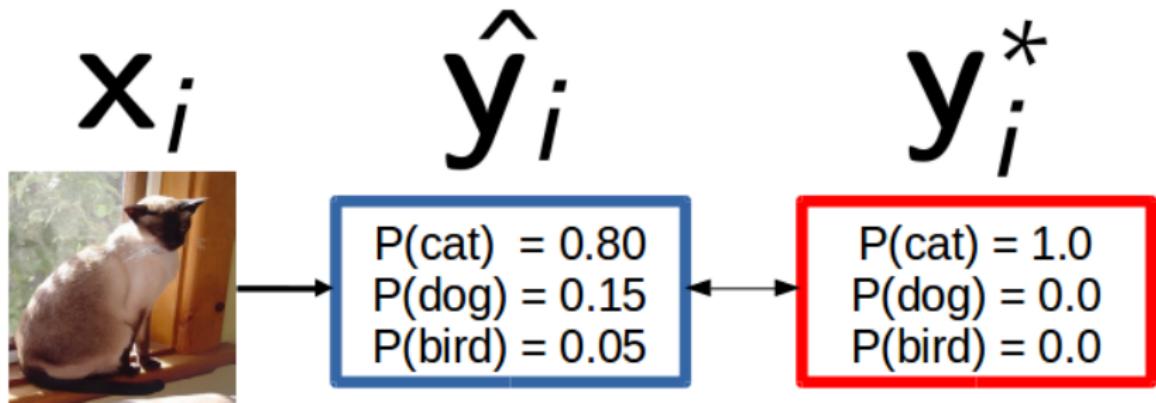
1. $\mathbf{y} \in \{1; 2; \dots; K\}$

2. $\hat{y}_i = \arg \max_k P(k/x_i, \mathbf{W}, \mathbf{b})$

3. $\ell_{0/1}(\hat{y}_i, y_i^*) = \begin{cases} 1 & \text{if } \hat{y}_i \neq y_i^* \\ 0 & \text{otherwise} \end{cases} : \text{0/1 loss}$



Logistic Regression Training Formulation



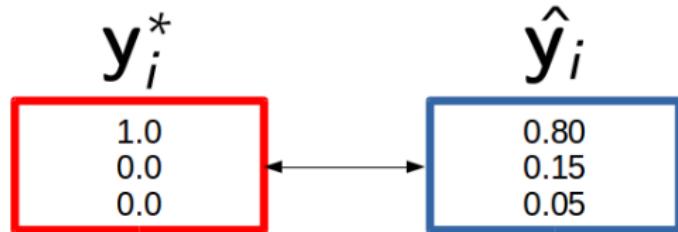
- ▶ **Input x_i , ground truth output supervision y_i^***
- ▶ One hot-encoding for y_i^* :
$$y_{c,i}^* = \begin{cases} 1 & \text{if } c \text{ is the ground truth class for } x_i \\ 0 & \text{otherwise} \end{cases}$$

Logistic Regression Training Formulation

- ▶ Loss function: multi-class Cross-Entropy (CE) ℓ_{CE}
- ▶ ℓ_{CE} : Kullback-Leiber divergence between \mathbf{y}_i^* and $\hat{\mathbf{y}}_i$

$$\ell_{CE}(\hat{\mathbf{y}}_i, \mathbf{y}_i^*) = KL(\mathbf{y}_i^*, \hat{\mathbf{y}}_i) = - \sum_{c=1}^K y_{c,i}^* \log(\hat{y}_{c,i}) = -\log(\hat{y}_{c^*,i})$$

- ▶ \triangle KL asymmetric: $KL(\hat{\mathbf{y}}_i, \mathbf{y}_i^*) \neq KL(\mathbf{y}_i^*, \hat{\mathbf{y}}_i)$ \triangle

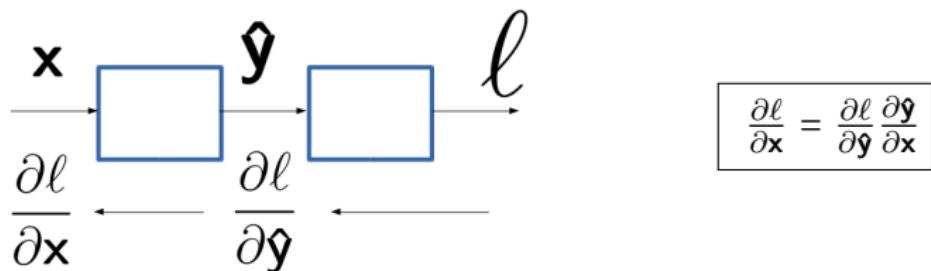


$$KL(\mathbf{y}_i^*, \hat{\mathbf{y}}_i) = -\log(\hat{y}_{c^*,i}) = -\log(0.8) \approx 0.22$$

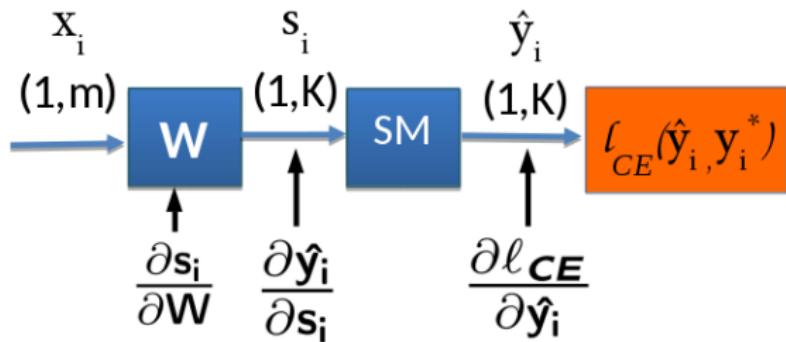
Logistic Regression Training

- ▶ $\mathcal{L}_{CE}(\mathbf{W}, \mathbf{b}) = \frac{1}{N} \sum_{i=1}^N \ell_{CE}(\hat{\mathbf{y}}_i, \mathbf{y}_i^*) = -\frac{1}{N} \sum_{i=1}^N \log(\hat{y}_{c^*, i})$
- ▶ ℓ_{CE} smooth convex upper bound of $\ell_{0/1}$
⇒ **gradient descent optimization**
- ▶ Gradient descent: $\mathbf{W}^{(t+1)} = \mathbf{W}^{(t)} - \eta \frac{\partial \mathcal{L}_{CE}}{\partial \mathbf{W}}$ ($\mathbf{b}^{(t+1)} = \mathbf{b}^{(t)} - \eta \frac{\partial \mathcal{L}_{CE}}{\partial \mathbf{b}}$)
- ▶ **MAIN CHALLENGE:** computing $\frac{\partial \mathcal{L}_{CE}}{\partial \mathbf{W}} = \frac{1}{N} \sum_{i=1}^N \frac{\partial \ell_{CE}}{\partial \mathbf{W}}$?
⇒ Key Property: chain rule $\frac{\partial \mathbf{x}}{\partial z} = \frac{\partial \mathbf{x}}{\partial \mathbf{y}} \frac{\partial \mathbf{y}}{\partial z}$
⇒ **Backpropagation of gradient error!**

Chain Rule



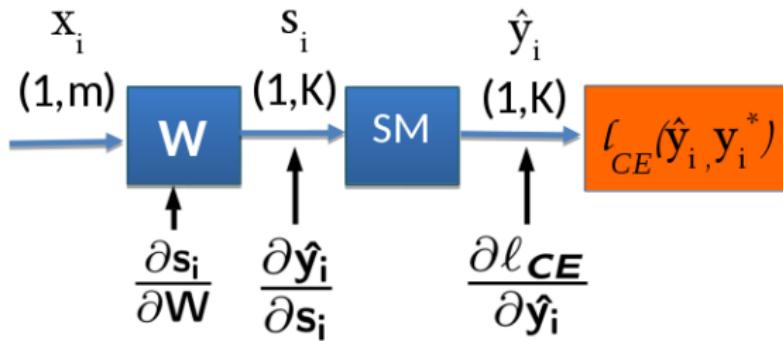
- Logistic regression:
$$\frac{\partial \ell_{CE}}{\partial \mathbf{W}} = \frac{\partial \ell_{CE}}{\partial \hat{\mathbf{y}}_i} \frac{\partial \hat{\mathbf{y}}_i}{\partial \mathbf{s}_i} \frac{\partial \mathbf{s}_i}{\partial \mathbf{W}}$$



Logistic Regression Training: Backpropagation

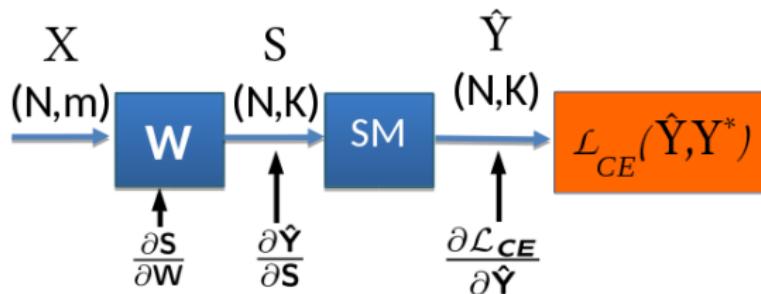
$$\frac{\partial \ell_{CE}}{\partial \mathbf{W}} = \frac{\partial \ell_{CE}}{\partial \hat{\mathbf{y}}_i} \frac{\partial \hat{\mathbf{y}}_i}{\partial \mathbf{s}_i} \frac{\partial \mathbf{s}_i}{\partial \mathbf{W}}, \quad \ell_{CE}(\hat{\mathbf{y}}_i, \mathbf{y}_i^*) = -\log(\hat{y}_{c^*, i}) \Rightarrow \text{Update for 1 example:}$$

- ▶ $\frac{\partial \ell_{CE}}{\partial \hat{\mathbf{y}}_i} = \frac{-1}{\hat{y}_{c^*, i}} = \frac{-1}{\hat{y}_i} \odot \delta_{\mathbf{c}, \mathbf{c}^*}$
- ▶ $\frac{\partial \ell_{CE}}{\partial \mathbf{s}_i} = \hat{\mathbf{y}}_i - \mathbf{y}_i^* = \delta_i^y$
- ▶ $\frac{\partial \ell_{CE}}{\partial \mathbf{W}} = \mathbf{x}_i^T \delta_i^y$



Logistic Regression Training: Backpropagation

- Whole dataset: data matrix \mathbf{X} ($N \times m$), label matrix $\hat{\mathbf{Y}}$, \mathbf{Y}^* ($N \times K$)
- $\mathcal{L}_{CE}(\mathbf{W}, \mathbf{b}) = -\frac{1}{N} \sum_{i=1}^N \log(\hat{y}_{c^*, i})$, $\frac{\partial \mathcal{L}_{CE}}{\partial \mathbf{W}} = \frac{\partial \mathcal{L}_{CE}}{\partial \hat{\mathbf{Y}}} \frac{\partial \hat{\mathbf{Y}}}{\partial \mathbf{S}} \frac{\partial \mathbf{S}}{\partial \mathbf{W}}$

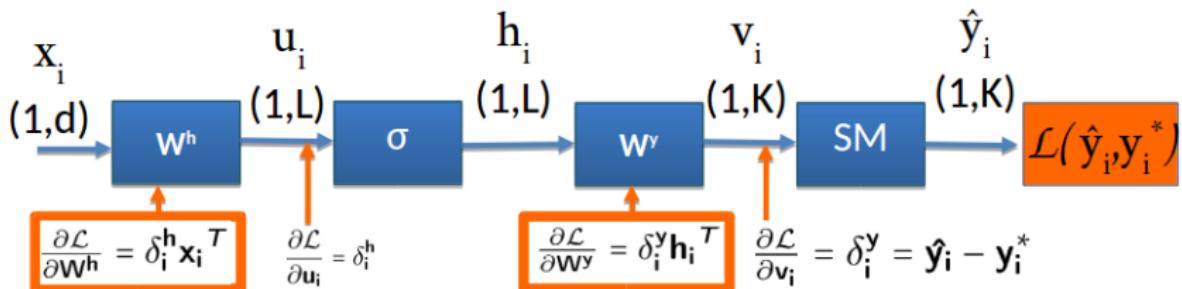


- $$\frac{\partial \mathcal{L}_{CE}}{\partial \mathbf{s}} = \hat{\mathbf{Y}} - \mathbf{Y}^* = \Delta^y$$
- $$\frac{\partial \mathcal{L}_{CE}}{\partial \mathbf{W}} = \mathbf{X}^T \Delta^y$$

Perceptron Training: Backpropagation

- Perceptron vs Logistic Regression: adding hidden layer (sigmoid)
- Goal:** Train parameters \mathbf{W}^y and \mathbf{W}^h (+bias) with Backpropagation

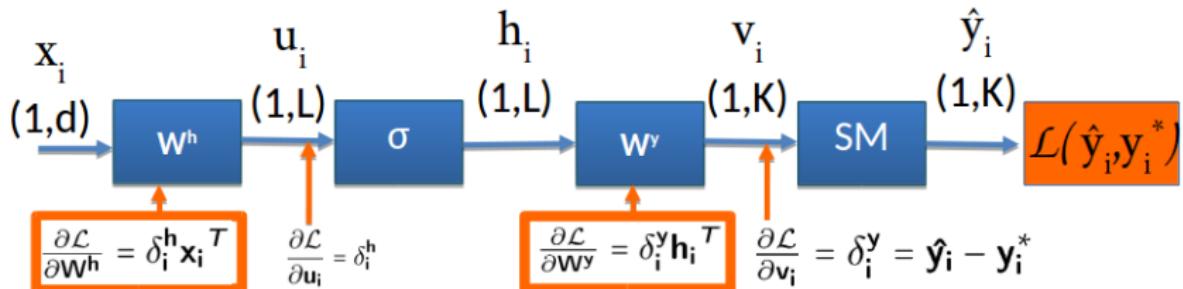
⇒ computing $\frac{\partial \mathcal{L}_{CE}}{\partial \mathbf{W}^y} = \frac{1}{N} \sum_{i=1}^N \frac{\partial \ell_{CE}}{\partial \mathbf{W}^y}$ and $\frac{\partial \mathcal{L}_{CE}}{\partial \mathbf{W}^h} = \frac{1}{N} \sum_{i=1}^N \frac{\partial \ell_{CE}}{\partial \mathbf{W}^h}$



- Last hidden layer ~ Logistic Regression
- First hidden layer: $\frac{\partial \mathcal{L}_{CE}}{\partial \mathbf{W}^h} = \mathbf{x}_i^T \frac{\partial \ell_{CE}}{\partial \mathbf{u}_i} \Rightarrow$ **computing** $\frac{\partial \ell_{CE}}{\partial \mathbf{u}_i} = \delta_i^h$

Perceptron Training: Backpropagation

- ▶ Computing $\frac{\partial \ell_{CE}}{\partial u_i} = \delta_i^h \Rightarrow$ use chain rule: $\frac{\partial \ell_{CE}}{\partial u_i} = \frac{\partial \ell_{CE}}{\partial v_i} \frac{\partial v_i}{\partial h_i} \frac{\partial h_i}{\partial u_i}$
- ▶ ... Leading to: $\frac{\partial \ell_{CE}}{\partial u_i} = \delta_i^h = \delta_i^y {}^T W^y \odot \sigma' (h_i) = \delta_i^y {}^T W^y \odot (h_i \odot (1 - h_i))$



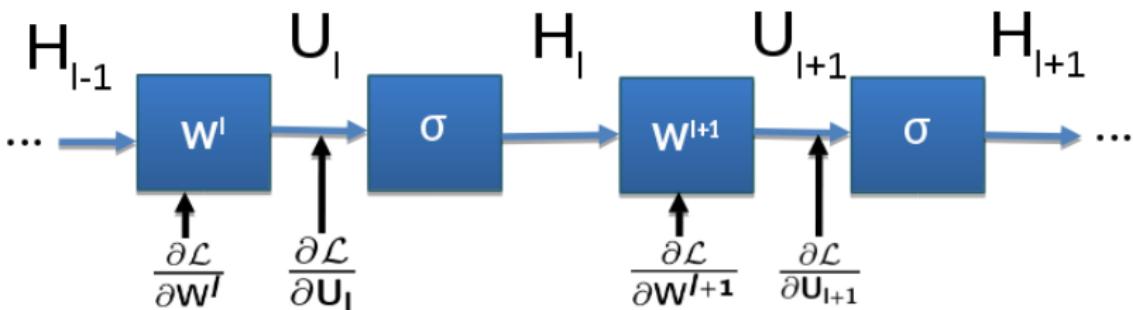
Deep Neural Network Training: Backpropagation

- ▶ Multi-Layer Perceptron (MLP): adding more hidden layers
- ▶ Backpropagation update \sim Perceptron: **assuming** $\frac{\partial \mathcal{L}}{\partial \mathbf{U}_{l+1}} = \Delta^{l+1}$ known

$$\frac{\partial \mathcal{L}}{\partial \mathbf{W}^{l+1}} = \mathbf{H}_l^T \Delta^{l+1}$$

▶ Computing $\frac{\partial \mathcal{L}}{\partial \mathbf{U}_l} = \Delta^l$ ($= \Delta^{l+1 T} \mathbf{W}^{l+1} \odot \mathbf{H}_l \odot (1 - \mathbf{H}_l)$ sigmoid)

$$\frac{\partial \mathcal{L}}{\partial \mathbf{W}^l} = \mathbf{H}_{l-1}^T \Delta^{h_l}$$



Neural Network Training: Optimization Issues

- ▶ Classification loss over training set (vectorized \mathbf{w} , \mathbf{b} ignored):

$$\mathcal{L}_{CE}(\mathbf{w}) = \frac{1}{N} \sum_{i=1}^N \ell_{CE}(\hat{\mathbf{y}}_i, \mathbf{y}_i^*) = -\frac{1}{N} \sum_{i=1}^N \log(\hat{y}_{c^*, i})$$

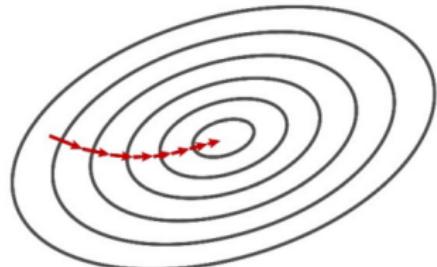
- ▶ Gradient descent optimization:

$$\mathbf{w}^{(t+1)} = \mathbf{w}^{(t)} - \eta \frac{\partial \mathcal{L}_{CE}}{\partial \mathbf{w}} (\mathbf{w}^{(t)}) = \mathbf{w}^{(t)} - \eta \nabla_{\mathbf{w}}^{(t)}$$

- ▶ Gradient $\nabla_{\mathbf{w}}^{(t)} = \frac{1}{N} \sum_{i=1}^N \frac{\partial \ell_{CE}(\hat{\mathbf{y}}_i, \mathbf{y}_i^*)}{\partial \mathbf{w}} (\mathbf{w}^{(t)})$ linearly scales

wrt:

- ▶ \mathbf{w} dimension
- ▶ Training set size



⇒ Too slow even for moderate
dimensionality & dataset size!

Stochastic Gradient Descent

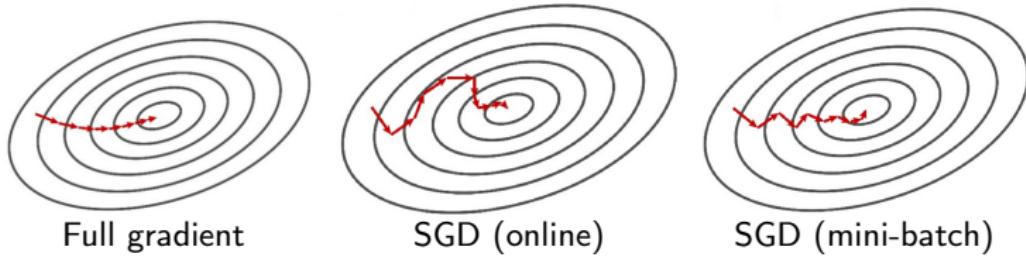
- ▶ **Solution:** approximate $\nabla_{\mathbf{w}}^{(t)} = \frac{1}{N} \sum_{i=1}^N \frac{\partial \ell_{CE}(\hat{\mathbf{y}}_i, \mathbf{y}_i^*)}{\partial \mathbf{w}} (\mathbf{w}^{(t)})$ with subset of examples
⇒ **Stochastic Gradient Descent (SGD)**

- ▶ Use a single example (online):

$$\nabla_{\mathbf{w}}^{(t)} \approx \frac{\partial \ell_{CE}(\hat{\mathbf{y}}_i, \mathbf{y}_i^*)}{\partial \mathbf{w}} (\mathbf{w}^{(t)})$$

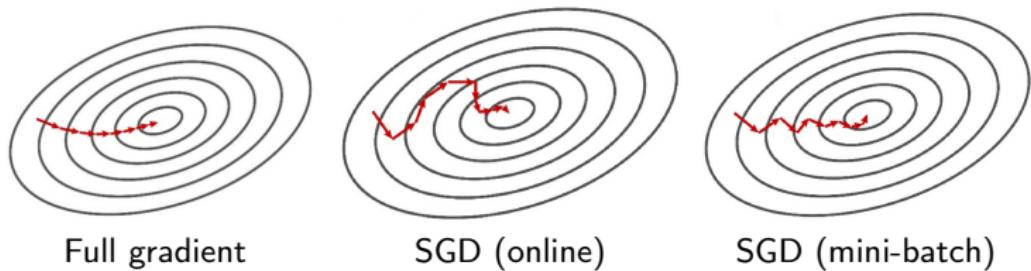
- ▶ Mini-batch: use $B < N$ examples:

$$\nabla_{\mathbf{w}}^{(t)} \approx \frac{1}{B} \sum_{i=1}^B \frac{\partial \ell_{CE}(\hat{\mathbf{y}}_i, \mathbf{y}_i^*)}{\partial \mathbf{w}} (\mathbf{w}^{(t)})$$



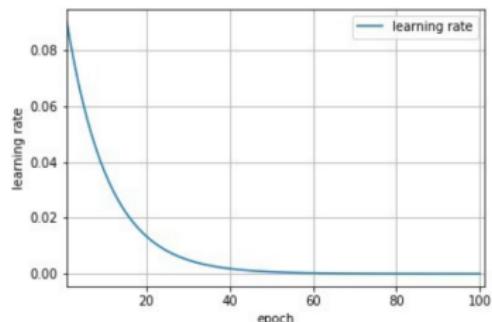
Stochastic Gradient Descent

- ▶ SGD: approximation of the true Gradient ∇_w !
 - ▶ Noisy gradient can lead to bad direction, increase loss
 - ▶ **BUT:** much more parameter updates: online $\times N$, mini-batch $\times \frac{N}{B}$
 - ▶ **Faster convergence**, at the core of Deep Learning for large scale datasets

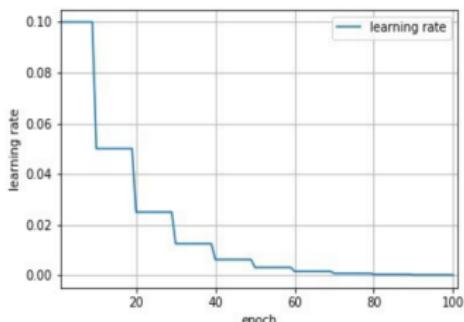


Optimization: Learning Rate Decay

- ▶ Gradient descent optimization: $\mathbf{w}^{(t+1)} = \mathbf{w}^{(t)} - \eta \nabla_{\mathbf{w}}^{(t)}$
- ▶ η setup ? \Rightarrow open question
- ▶ Learning Rate Decay: decrease η during training progress
 - ▶ Inverse (time-based) decay: $\eta_t = \frac{\eta_0}{1+r \cdot t}$, r decay rate
 - ▶ Exponential decay: $\eta_t = \eta_0 \cdot e^{-\lambda t}$
 - ▶ Step Decay $\eta_t = \eta_0 \cdot r^{\frac{t}{t_u}} \dots$



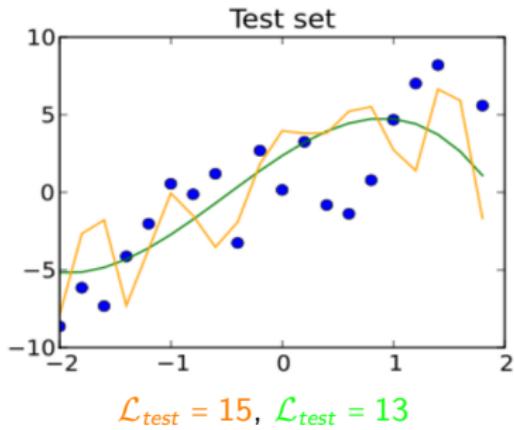
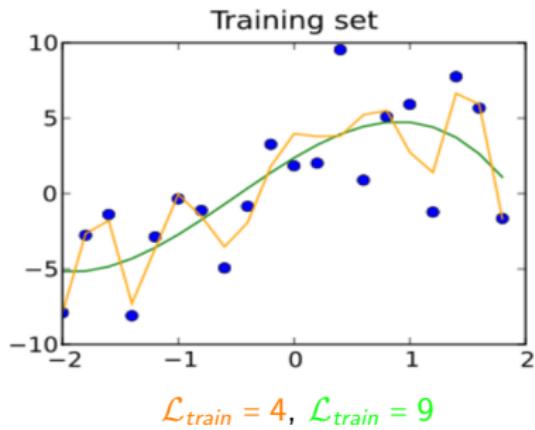
Exponential Decay ($\eta_0 = 0.1$, $\lambda = 0.1s$)



Step Decay ($\eta_0 = 0.1$, $r = 0.5$, $t_U = 10$)

Generalization and Overfitting

- ▶ **Learning:** minimizing classification loss \mathcal{L}_{CE} over training set
 - ▶ Training set: sample representing data vs labels distributions
 - ▶ Ultimate goal: train a prediction function with low prediction error on the **true (unknown) data distribution**



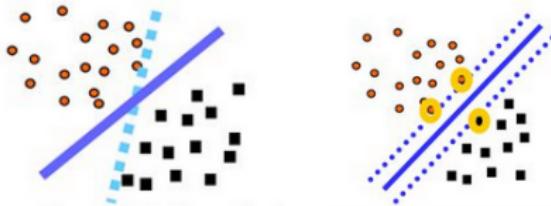
⇒ Optimization ≠ Machine Learning!
⇒ Generalization / Overfitting!

Regularization

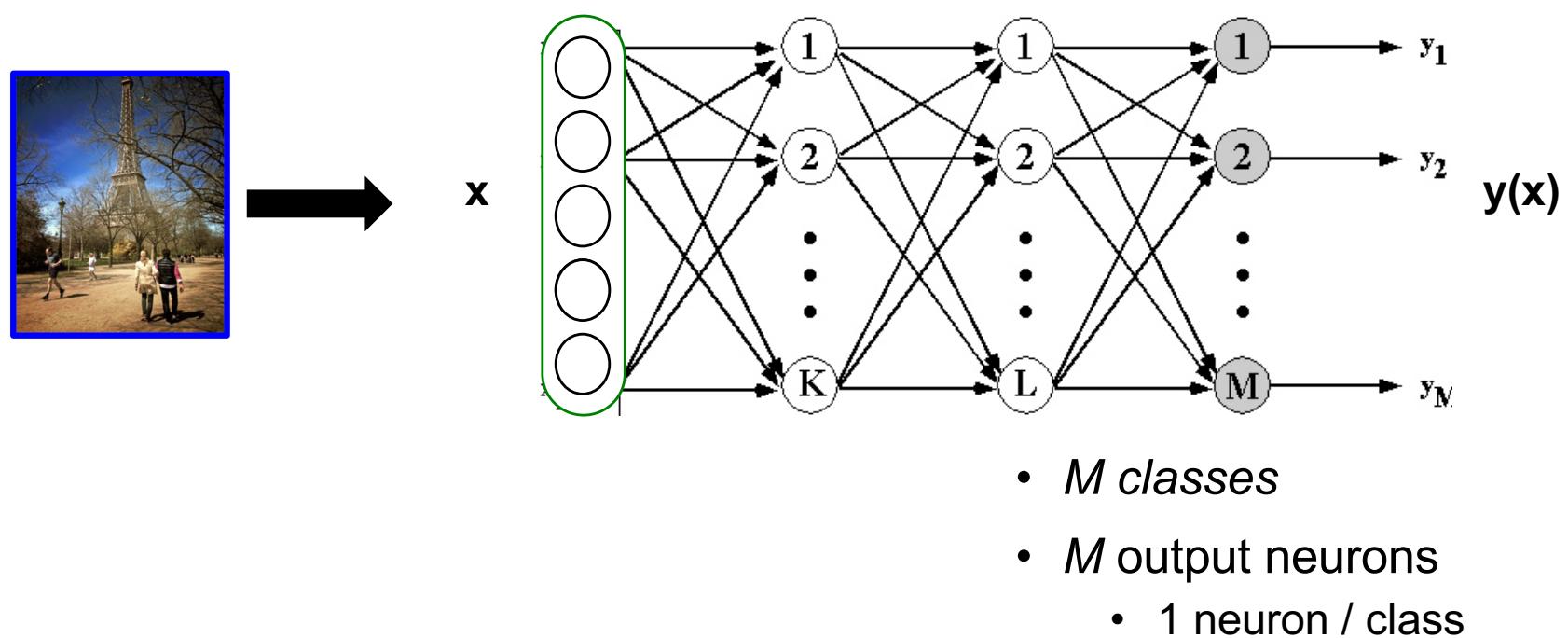
- ▶ **Regularization:** improving generalization, i.e. test (\neq train) performances
- ▶ Structural regularization: add **Prior** $R(\mathbf{w})$ in training objective:

$$\mathcal{L}(\mathbf{w}) = \mathcal{L}_{CE}(\mathbf{w}) + \alpha R(\mathbf{w})$$

- ▶ **L^2 regularization: weight decay,** $R(\mathbf{w}) = \|\mathbf{w}\|^2$
 - ▶ Commonly used in neural networks
 - ▶ Theoretical justifications, generalization bounds (SVM)
- ▶ Other possible $R(\mathbf{w})$: L^1 regularization, dropout, etc



Deep for image classification



Question: how to connect the image to the MLP?

Outline

ConvNets as Deep Neural Networks for Vision

1. Neural Nets
2. **Deep Convolutional Neural Networks**