

Parallel Computing for Machine Learning

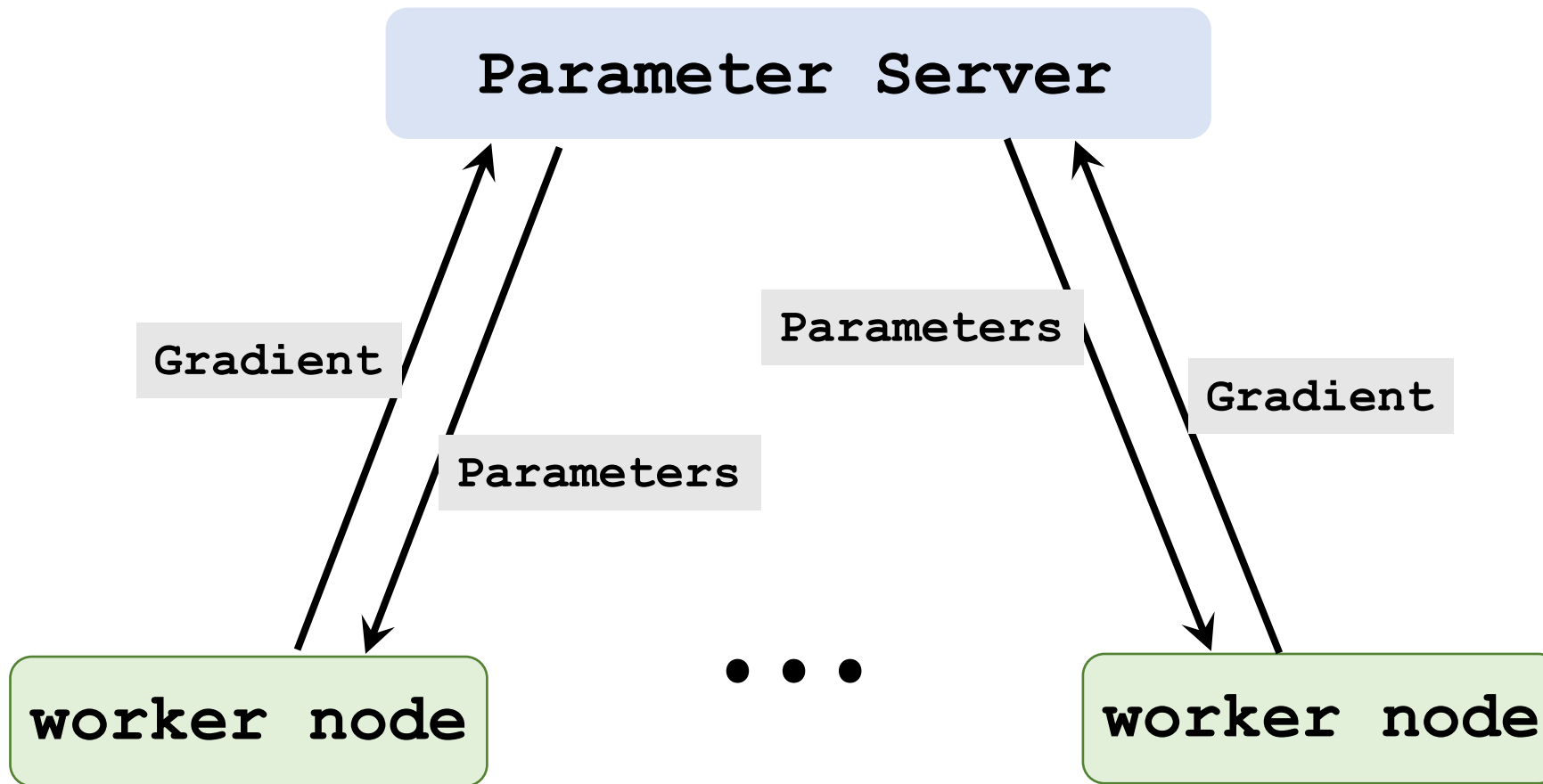
(Part 2)

Shusen Wang

Synchronous Parallel Gradient Descent

Using Parameter Server

Parameter Server's Architecture



The Parameter Server

- The parameter server was proposed by [1] for scalable machine learning.
- **Characters:** client-server architecture, message-passing communication, and **asynchronous**.
- (Note that MapReduce is **bulk synchronous**.)

Reference

1. Li and others: [Scaling distributed machine learning with the parameter server](#). In *OSDI*, 2014.

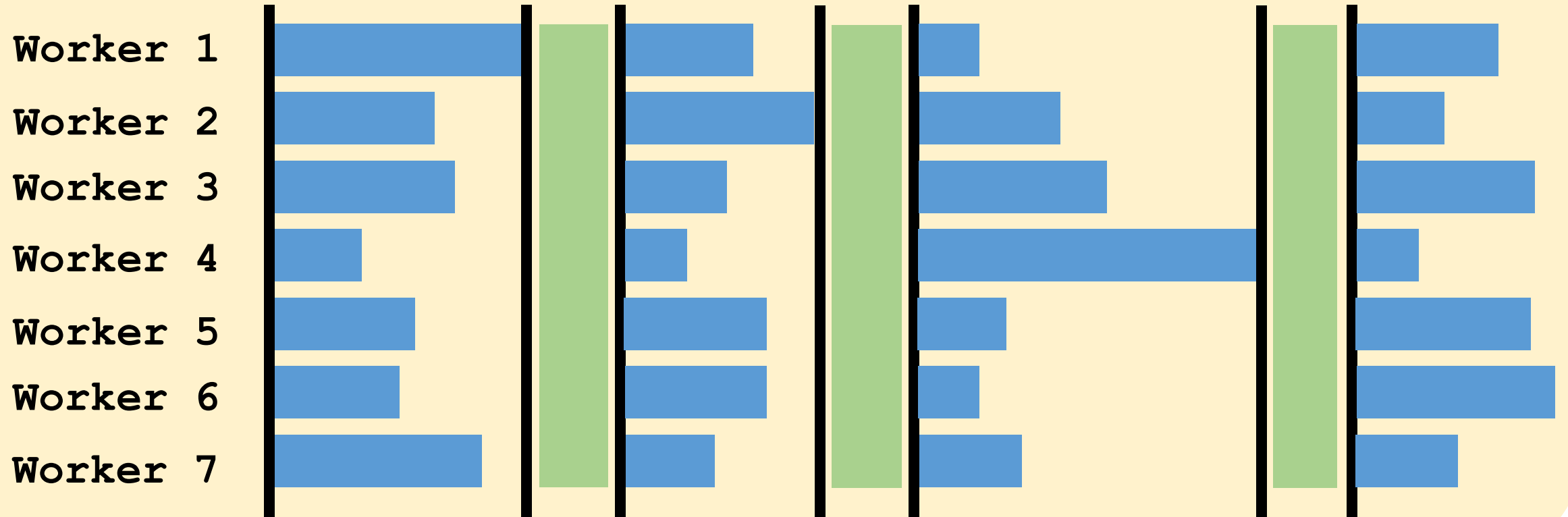
The Parameter Server

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- **Characters:** client-server architecture, message-passing communication, and **asynchronous**.
- (Note that MapReduce is **bulk synchronous**.)
- Ray [2], an open-source software system, supports parameter server.

Reference

1. Li and others: [Scaling distributed machine learning with the parameter server](#). In *OSDI*, 2014.
2. Moritz and others: [Ray: A distributed framework for emerging AI applications](#). In *OSDI*, 2018.

Let us recall synchronous algorithm



 : computation

 : communication

 : synchronization

Asynchronous algorithm

Worker 1

Worker 2

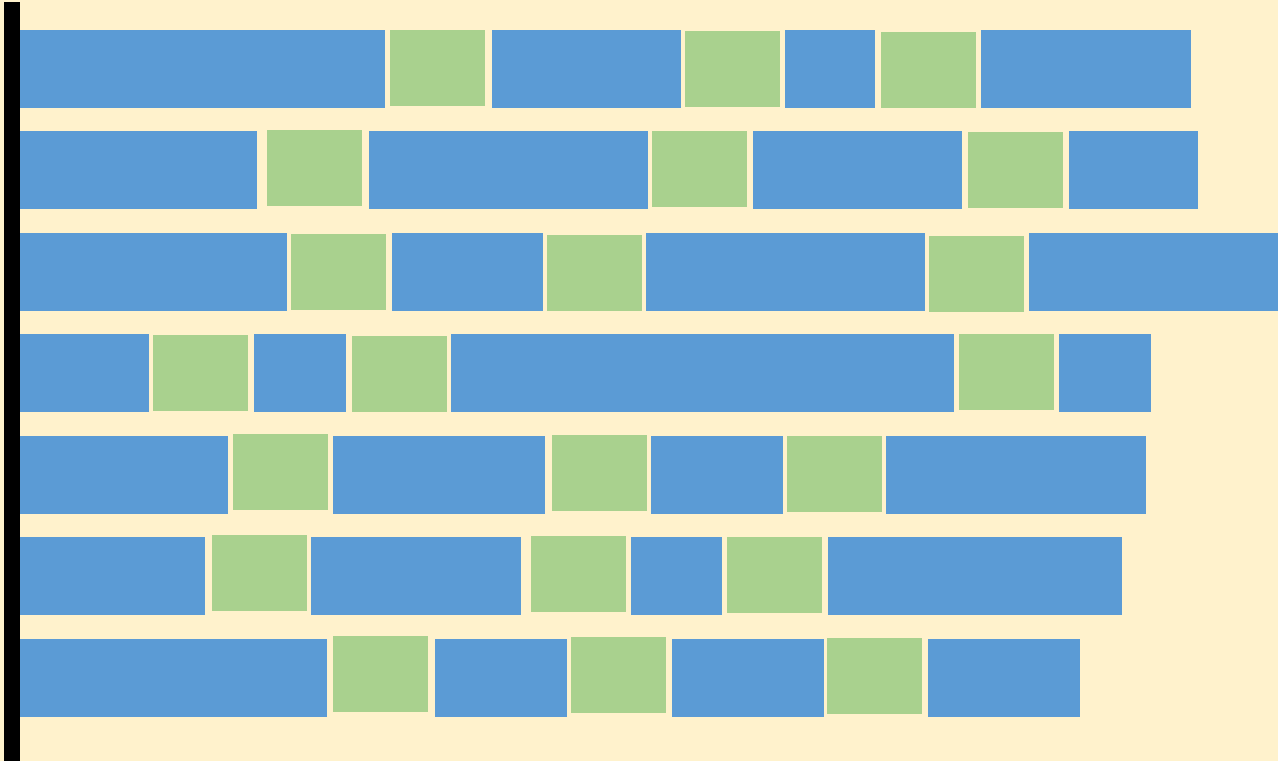
Worker 3

Worker 4

Worker 5

Worker 6

Worker 7



: computation



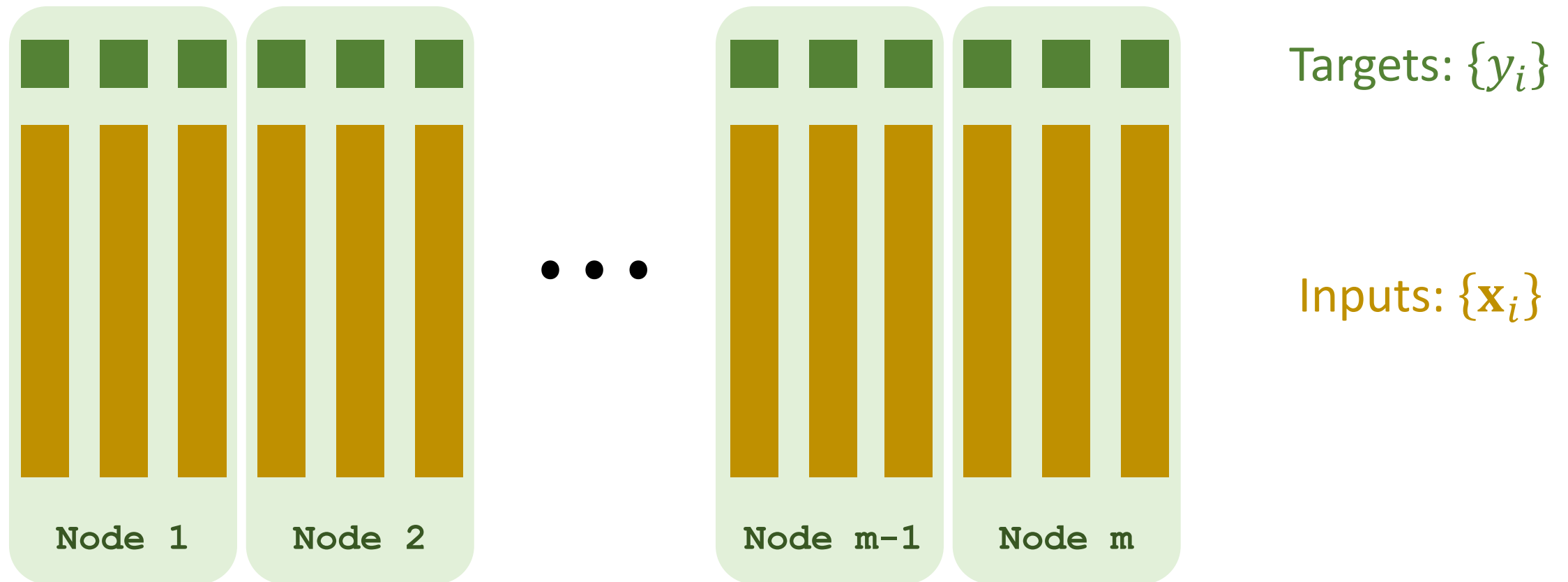
: communication



: synchronization

Asynchronous Gradient Descent

- Partition the data among worker nodes. (A node has a subset of data.)



Asynchronous Gradient Descent

The i -th worker repeats:

1. Pull the up-to-date model parameters \mathbf{w} from the server.
2. Compute gradient $\tilde{\mathbf{g}}_i$ using its local data and \mathbf{w} .
3. Push $\tilde{\mathbf{g}}_i$ to the server.

The server performs:

1. Receive gradient $\tilde{\mathbf{g}}_i$ from a worker.
2. Update the parameters by:

$$\mathbf{w} \leftarrow \mathbf{w} - \alpha \cdot \tilde{\mathbf{g}}_i.$$

Reference

1. Niu and others: [Hogwild: A lock-free approach to parallelizing stochastic gradient descent](#). In *NIPS*, 2011.

Asynchronous Gradient Descent

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3. Push $\tilde{\mathbf{g}}_i$ to the server.

The server performs:

1. Receive gradient $\tilde{\mathbf{g}}_i$ from a worker.
2. Update the parameters by:

$$\mathbf{w} \leftarrow \mathbf{w} - \alpha \cdot \tilde{\mathbf{g}}_i.$$

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Pro and Con of Asynchronous Algorithms

- In practice, asynchronous algorithms are faster than the synchronous.
- In theory, asynchronous algorithms has slower convergence rate.
- Asynchronous algorithms have restrictions, e.g., a worker cannot be much slower than the others. (Why?)

Pro and Con of Asynchronous Algorithms

Question: What if a worker is too slow?

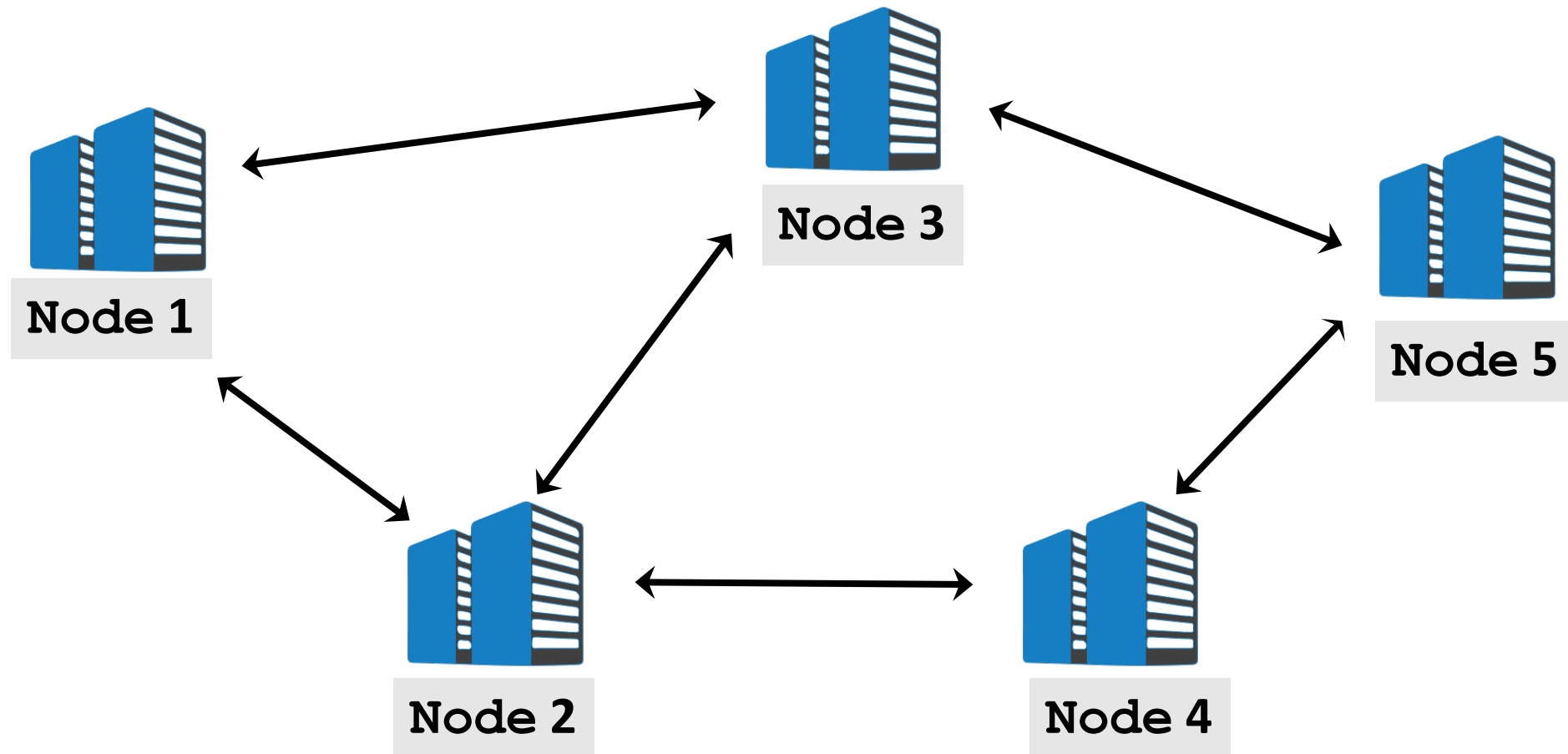


- At $\text{time } t_1$, the parameters in the server have been updated many times.
- Worker 3's gradient is based on very old parameters (at $\text{time } t_0$)
- ➔ Worker 3's gradient is harmful!

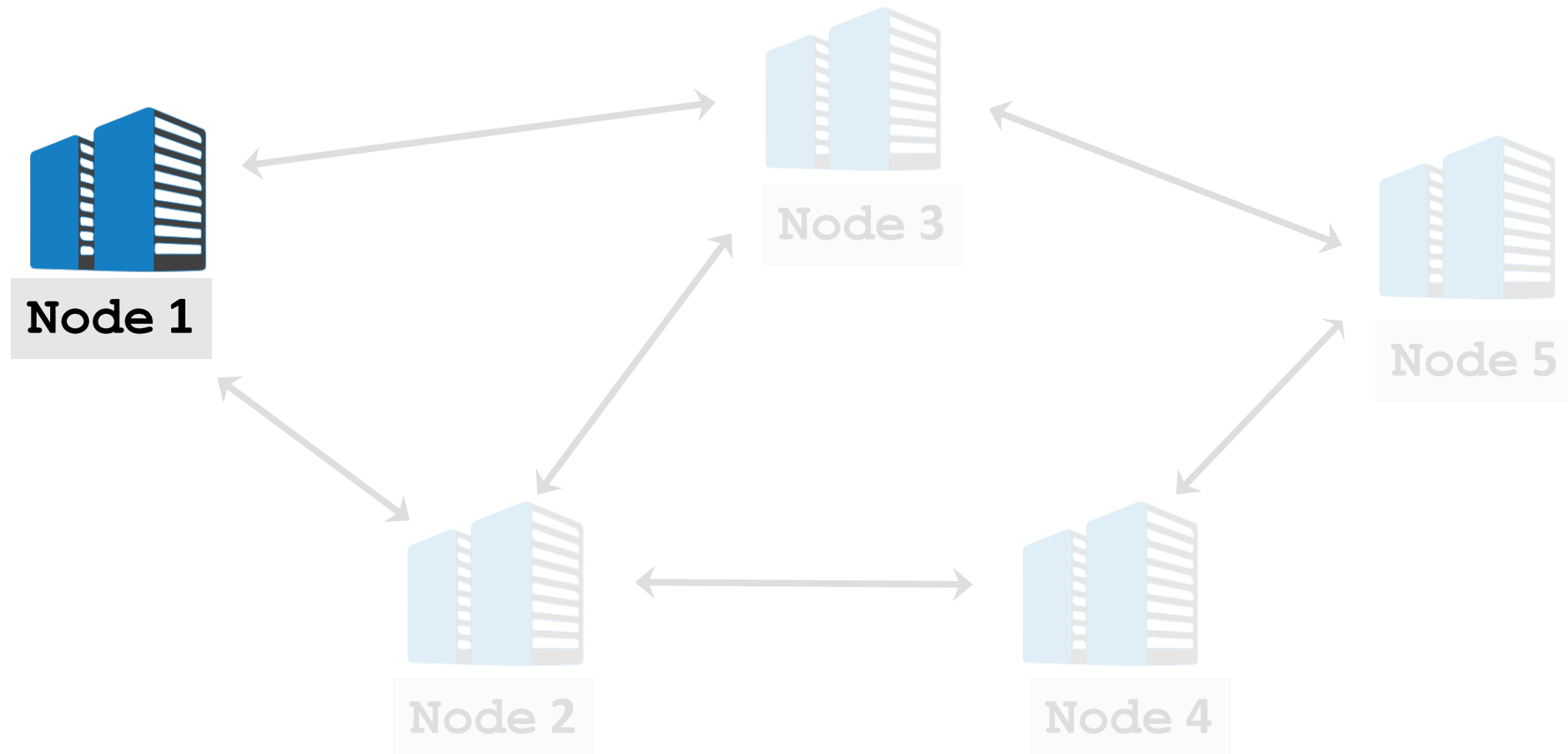
Parallel Gradient Descent in Decentralized Network

Decentralized Network

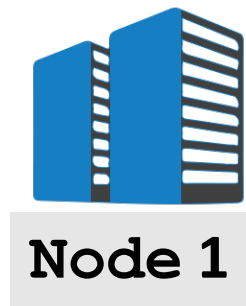
- Characters: peer-to-peer architecture (no central server), message-passing communication, a node communicate with its neighbors.



Decentralized Gradient Descent



Decentralized Gradient Descent



The i -th node repeats:

1. Compute gradient $\tilde{\mathbf{g}}_i$ using its local data and current parameters $\tilde{\mathbf{w}}_i$.
2. Pull the parameters from its neighbors, denote $\{\tilde{\mathbf{w}}_k\}$.
3. $\tilde{\mathbf{w}}_i \leftarrow$ weighted average of $\tilde{\mathbf{w}}_i$ and $\{\tilde{\mathbf{w}}_k\}$.
4. $\tilde{\mathbf{w}}_i \leftarrow \tilde{\mathbf{w}}_i - \alpha \cdot \tilde{\mathbf{g}}_i$.

Node 2

Node 4

Theories of Decentralized Algorithms

- Decentralized GD and SGD are guaranteed to converge, e.g., [1].

Reference

1. Lian and others: [Can decentralized algorithms outperform centralized algorithms?](#) In *NIPS*, 2017.

Theories of Decentralized Algorithms

- Decentralized GD and SGD are guaranteed to converge, e.g., [1].
- Convergence rate depends on how well the nodes are connected.
 - If the nodes forms a complete graph, then it has very fast convergence.
 - If the graph is not strongly connected, then it does not converge.

Reference

1. Lian and others: [Can decentralized algorithms outperform centralized algorithms?](#) In *NIPS*, 2017.

Summary

Parallel Computing

- **Why?** To make the wall-clock runtime shorter.
- **How?** Use multiple processors and/or multiple nodes.

Important Concepts

- **Communication:** sharing memory **V.S.** message passing.
- **Architecture:** client-server **V.S.** peer-to-peer.

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- **Synchronization:** bulk synchronous **V.S.** asynchronous.

Important Concepts

- **Communication:** sharing memory **V.S.** message passing.
- **Architecture:** client-server **V.S.** peer-to-peer.
- **Synchronization:** bulk synchronous **V.S.** asynchronous.
- **Parallelism:** data parallelism (more popular) **V.S.** model parallelism.

Parallel Programming Models

- **MapReduce:** Message passing, client-server, and synchronous.
- **Parameter Server:** Message passing, client-server, and asynchronous.
- **Decentralized:** Message passing, peer-to-peer, synchronous or asynchronous.

Parallel Computing v.s. Distributed Computing

Distributed computing is a kind of parallel computing.

Question: What is the difference?

- It is not black and white. No consensus in the academia.

Parallel Computing v.s. Distributed Computing

Distributed computing is a kind of parallel computing.

Question: What is the difference?

- It is not black and white. No consensus in the academia.
- **HPC people's opinion:**
 - When the compute nodes are not in the physical locations, parallel computing is called distributed computing.
- **ML people's opinion:**
 - When the data or model are partitioned among multiple nodes, parallel computing is called distributed computing.
 - In contrast, computation in one node (which has many processors) is not distributed computing.

Thank you!