

# Deep Learning Homework 1

1-) For every ML problem we should define

- 1-) Hypothesis = Linear hypothesis with non linear parameters.
- 2-) Loss = Hinge loss which can not be differentiable at some point
- 3-) Optimize the loss

Since differentiation of hinge loss has discontinuity therefore there is no closed form solution. We should use sub gradient.

$$\text{Hypothesis} = h_{\theta}(x) = w^T \cdot x \quad \text{where } X = \begin{bmatrix} x_1^{(i)} \\ x_2^{(i)} \\ \vdots \\ x_6^{(i)} \\ 1 \end{bmatrix}$$

Note:  $x^{(i)}$  is the  $i$ 'th instance of data points

$$\text{loss } \ell(\theta) = \max(1 - y h_{\theta}(x), 0)$$

Our optimization  $\min_{w \in \mathbb{R}^d} \sum_{i=1}^n \max(1 - y^{(i)} w^T x^{(i)}) \rightarrow J(w) = \frac{1}{n} \sum_{i=1}^n \max(1 - y^{(i)} w^T x^{(i)}, 0)$

$$\begin{aligned} \nabla_w \ell(y^{(i)} w^T x^{(i)}) &= \ell'(y^{(i)} w^T x^{(i)}) y^{(i)} x^{(i)} = \begin{pmatrix} \begin{cases} 0 & , y^{(i)} w^T x^{(i)} > 1 \\ -1 & , y^{(i)} w^T x^{(i)} < 1 \\ \text{undefined} & , y^{(i)} w^T x^{(i)} = 1 \end{cases} \end{pmatrix} y^{(i)} x^{(i)} \\ &= \begin{cases} 0 & , y^{(i)} w^T x^{(i)} > 1 \\ -y^{(i)} x^{(i)} & , y^{(i)} w^T x^{(i)} < 1 \\ \text{undefined} & , y^{(i)} w^T x^{(i)} = 1 \end{cases} = \nabla_w \ell(y^{(i)} w^T x^{(i)}) \end{aligned}$$

$$\nabla_w J(w) = \nabla_w \left( \frac{1}{n} \sum_{i=1}^n \ell(y^{(i)} w^T x^{(i)}) \right) = \frac{1}{n} \sum_{i=1}^n \nabla_w \ell(y_i w^T x_i)$$

Pseudo code:

```
w ← <0, 0, ..., 0> ← weights
b ← 0 ← bias
for iter = 1 ... epochs do
    g ← <0, 0, ..., 0> ← gradients
    g_b ← 0
    for all (x, y) do
        if y(w·x + b) ≤ 1
            g ← g + y·x
            g_b ← g_b + y
    end for
    w ← w + λg ← step size
    b ← b + λg_b
```

$$= \begin{cases} \frac{1}{n} \left( \sum_{i: y^{(i)} w^T x^{(i)} < 1} -y^{(i)} x^{(i)} \right), & \text{all } y^{(i)} w^T x^{(i)} \neq 1 \\ \text{undefined}, & \text{otherwise} \end{cases}$$

2-)

Output of the  $z_u = \sigma(z_u) = \frac{1}{1+e^{-z_u}}$ 

$$2.1-) L = -y \log(\hat{y}) - (1-y) \log(1-\hat{y}) \quad \frac{\partial L}{\partial \hat{y}} = \frac{-y}{\hat{y}} + \frac{y-1}{1-\hat{y}} = \frac{\hat{y}-y}{\hat{y}(1-\hat{y})}$$

$$\hat{y} = \sigma(z_u) = \frac{1}{1+e^{-z_u}} \quad \frac{\partial \hat{y}}{\partial z_u} = \sigma(z_u) \cdot (1-\sigma(z_u))$$

$$\text{So } \frac{\partial L}{\partial \sigma(z_u)} = \frac{\sigma(z_u)(1-\sigma(z_u)) - y}{\sigma(z_u)(1-\sigma(z_u))(1-\sigma(z_u)(1-\sigma(z_u)))}$$

$$2.2-) \frac{\partial L}{\partial w_{1u}} = \frac{\partial L}{\partial \hat{y}} \cdot \frac{\partial \hat{y}}{\partial z_u} \cdot \frac{\partial z_u}{\partial w_{1u}} = \delta_{z_u} \cdot \frac{\partial z_u}{\partial w_{1u}} = \delta_{z_u} \cdot a_1 = \frac{\partial L}{\partial w_{1u}}$$

Given  $\delta_{z_u} = \frac{\partial L}{\partial z_u}$   $a_1$

$$2.3-) \frac{\partial L}{\partial w_{11}} = \frac{\partial L}{\partial \hat{y}} \cdot \frac{\partial \hat{y}}{\partial z_u} \cdot \frac{\partial z_u}{\partial a_1} \cdot \frac{\partial a_1}{\partial z_1} \cdot \frac{\partial z_1}{\partial w_{11}} = \delta_{a_1} \cdot \frac{\partial a_1}{\partial z_1} \cdot \frac{\partial z_1}{\partial w_{11}}$$

Given  $\delta_{a_1} = \frac{\partial L}{\partial a_1}$

$$= \delta_{a_1} \cdot \begin{cases} 0 & \text{if } z_1 < 0 \\ 1 & \text{if } z_1 > 0 \end{cases} \cdot x_1$$

$$a_1 = \text{ReLU}(z_1) = \max(0, z_1) = \begin{cases} 0 & \text{if } z_1 < 0 \\ z_1 & \text{if } z_1 > 0 \end{cases}$$

$$= \begin{cases} 0 & \text{if } z_1 < 0 \\ \delta_{a_1} \cdot x_1 & \text{if } z_1 > 0 \end{cases}$$

$$\frac{\partial a_1}{\partial z_1} = \begin{cases} 0 & \text{if } z_1 < 0 \\ 1 & \text{if } z_1 > 0 \end{cases}$$

$$z_1 = w_{11} \cdot x_1 + b_1$$

$$\frac{\partial z_1}{\partial w_{11}} = x_1$$

2.4-) L2 regularization is only applied on weights in general. Biases are omitted.  
We add L2 norm on cost function with  $\lambda$  regularization parameter.

First gradient: Our new cost  $L = -y \log(\hat{y}) - (1-y) \log(1-\hat{y}) + \frac{\lambda}{2} \sum w^2$

So for every partial derivate on weight becomes  $\frac{\partial L}{\partial w_{ij}} = \frac{\partial L}{\partial w_{ij}} + \lambda \cdot w$

Since we don't use any  $w$  in  $\frac{\partial L}{\partial \sigma(z_4)}$  there is no change.

Note: I assume same upstream gradients for the following gradients.

Second gradient:  $\frac{\partial L}{\partial w_{14}} = \left( \frac{\partial L}{\partial \hat{y}} \cdot \frac{\partial \hat{y}}{\partial z_4} \right) \cdot \frac{\partial z_4}{\partial w_{14}} = \delta z_4 \cdot (a_1 + \lambda \cdot w_{14}) = \delta z_4 \cdot a_1 + \delta z_4 \cdot \lambda \cdot w_{14}$   
 $\delta z_4 = \frac{\partial L}{\partial z_4}$

Third gradient: We have found that  $\frac{\partial L}{\partial w_{11}} = \delta a_1 \cdot \frac{\partial a_1}{\partial z_1} \cdot \frac{\partial z_1}{\partial w_{11}}$

$$\frac{\partial a_1}{\partial z_1} = \begin{cases} 0 & \text{if } z_1 < 0 \\ 1 & \text{if } z_1 > 0 \end{cases} = \delta a_1 \cdot \begin{cases} 0 & \text{if } z_1 < 0 \\ 1 & \text{if } z_1 > 0 \end{cases} \cdot (x_1 + \lambda w_{11})$$

$$z_1 = w_{11} \cdot x_1 + b$$

$$\frac{\partial z_1}{\partial w_{11}} = x_1 + \lambda \cdot w_{11}$$

$$= \begin{cases} 0 & \text{if } z_1 < 0 \\ \delta a_1 (x_1 + \lambda w_{11}) & \text{if } z_1 > 0 \end{cases}$$

So in general regularization term regularize the derivatives with  $w_{ij}$  weights

So it changes when  $w$  is involved in the gradient.

