0.1 Model

0.2 Optimisation with non-linear constraints
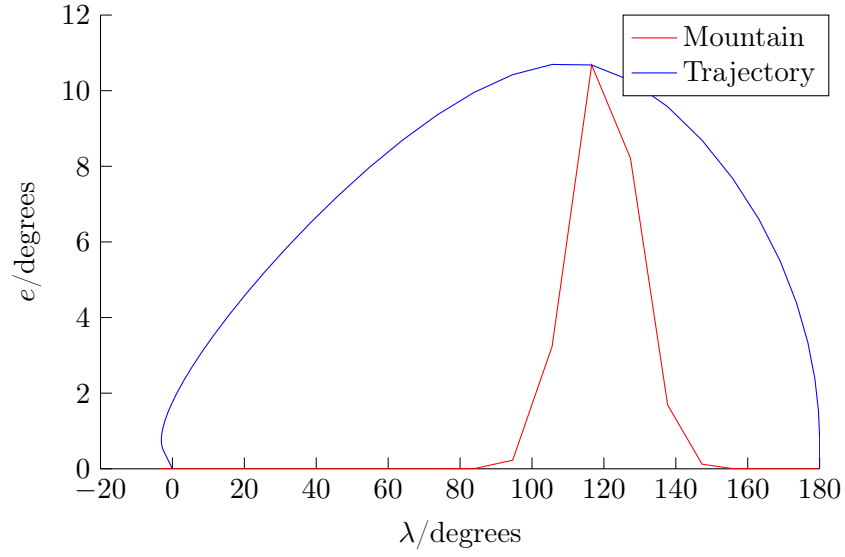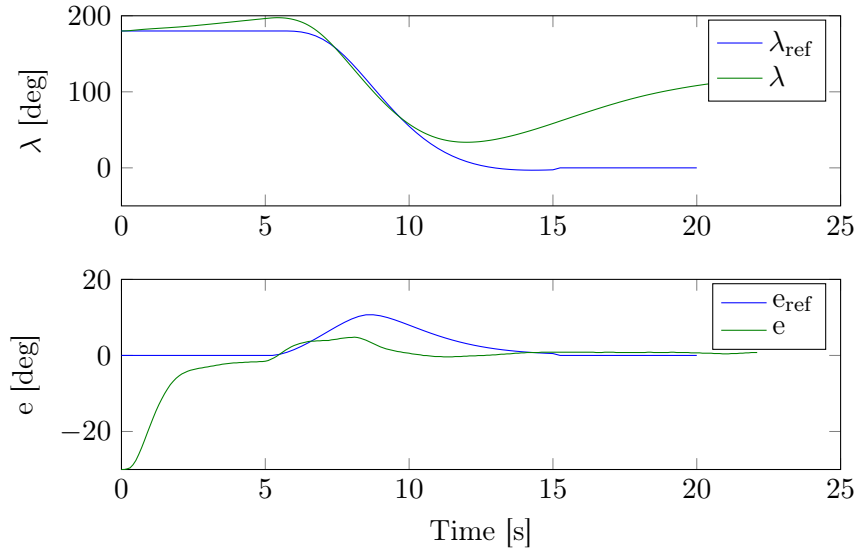

Figure 1: Mountain

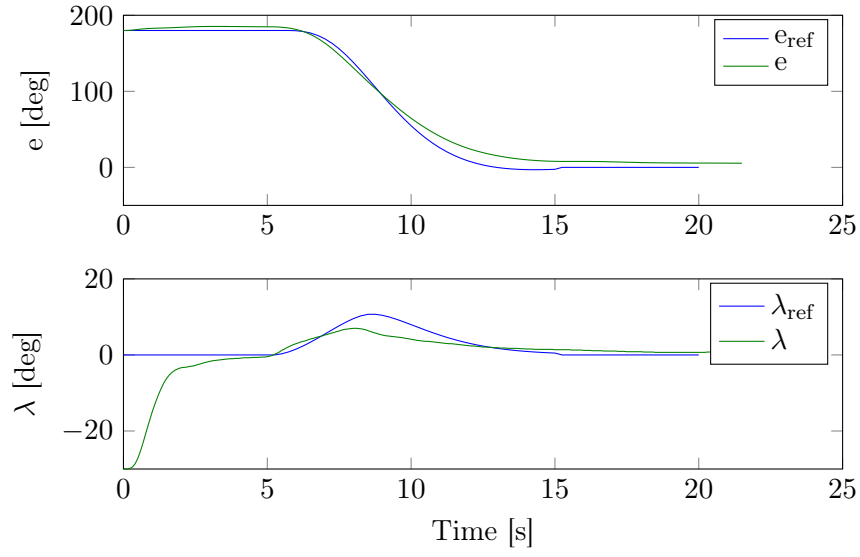## 0.3 Implementation

Figure 2: Open loop
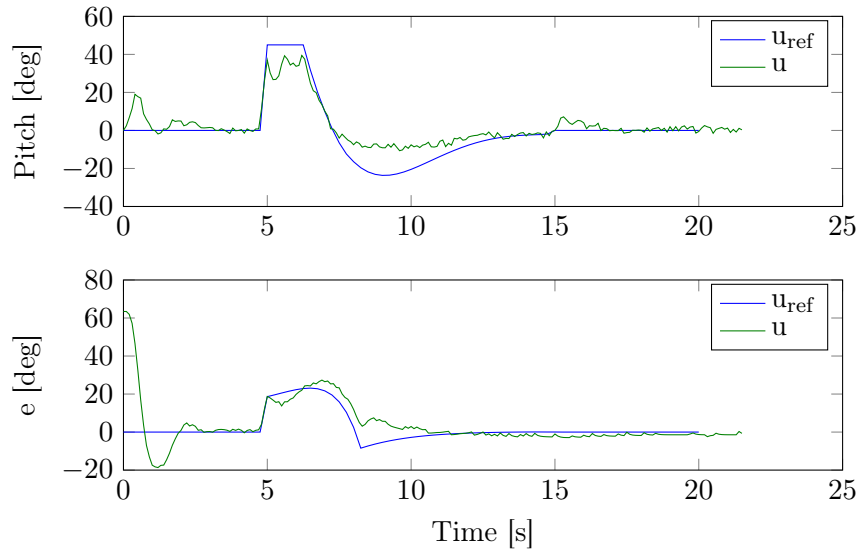
1

Figure 3: Closed loop

Figure 4: Closed loop inputs
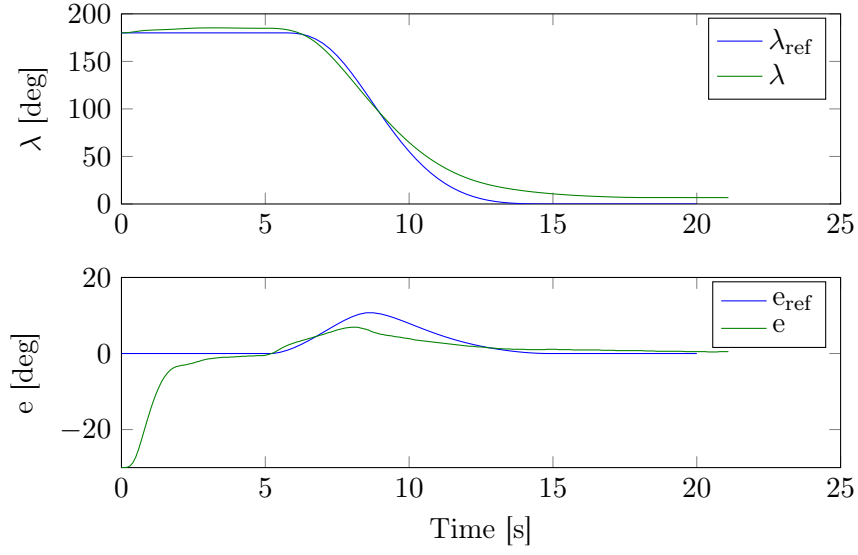
Figure 5:

0.3.1 Additional constraints

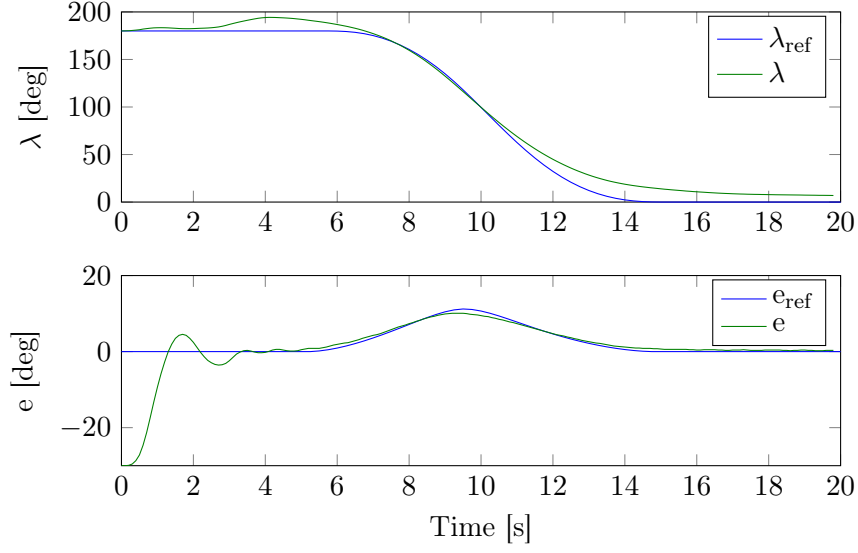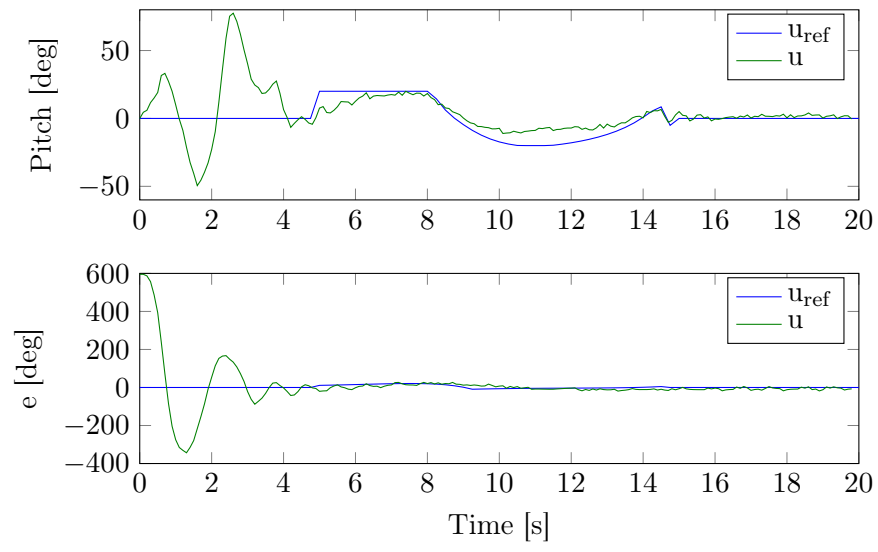Figure 6: Closed loop with end constraints

Figure 7: Constrain to only 20 degrees pitch

Figure 8: High feedback gain