1 Optimal Control of Pitch/Travel with Feedback (LQ)
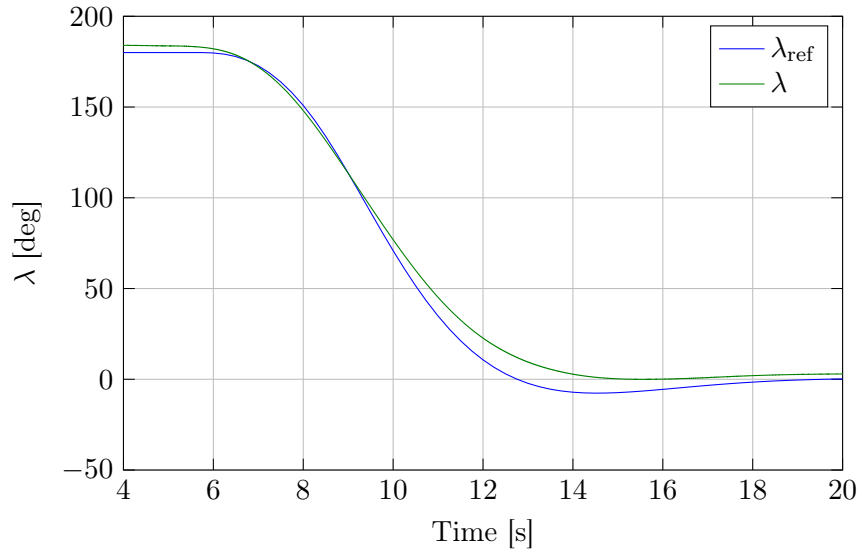

Figure 1: Travel, λ and Optimal reference Q = diag[50,0,0,0]
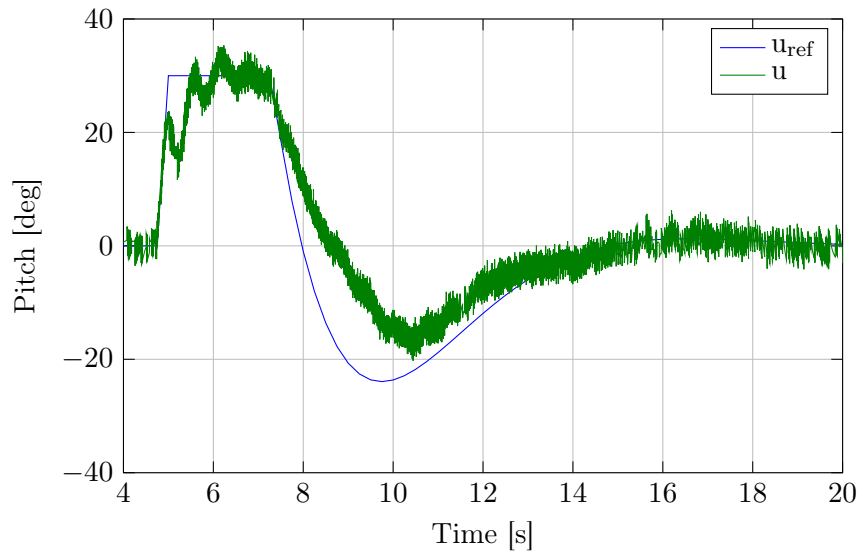

Figure 2: U, p_{ref} and Optimal U, Q = diag[50,0,0,0]