

Indian Association for the Cultivation of Science

(Deemed to be University under *de novo* Category) Master's/Integrated Master's-PhD Program/Integrated Bachelor's-Master's Program/PhD Course

End-Semester (Sem-II/IV) Examination-Spring 2021

Subject: Introduction to Machine Learning Subject Code(s): COM-4203/PHD-226 Full Marks: 50 Time Allotted: 3 h

Answer all questions. Marks for each question are indicated in [].

- 1. **(a)** Consider an unthreshold perceptron. Suppose you use gradient descent to train it. Will the algorithm always converge to a weight vector with minimum error on the training examples? Explain.
 - **(b)** State the differences between perceptron rule and delta rule for training a [2] perceptron.
 - **(c)** Consider the k-means algorithm. At the end of the current iteration, [2] suppose we have 3 centroids (0, 1), (2, 1), (-1, 2) corresponding to 3 clusters C_1 , C_2 , C_3 , respectively. In the next iteration, to which cluster(s) will the points (1.5, 3) and (2, 0.6) be assigned? Explain.
 - **(d)** Suppose you have 2 decision trees: *D*1 and *D*2. You trained *D*1 and *D*2 on the same training sets. *D*1 is grown to full depth while *D*2 is post-pruned to reduce the size of the tree. Which of the two trees is likely to have larger bias and which one larger variance?
 - **(e)** Consider the instance space corresponding to all points in the *x*, *y* plane. [2] Let *H* be the set of all circles in the *x*, *y* plane. Points inside the circle are classified as positive examples. Then, is the following statement TRUE or FALSE? Justify your answer.

"VC-dimension of *H* is at least 3."

- 2. **(a)** Which of the following 3 statements is/are TRUE for *k*-NN algorithm? [6] Justify your answer.
 - (I) For very large *k*, points from classes other than the true class may also get included in the neighborhood.
 - (II) For very small *k*, the algorithm is not sensitive to noise.
 - (III) It takes a small training time but large inference time.

(b) Consider 3 data points in the 2D space: (-2, -3), (0,0), (2,3). What is the first principal component (write down the actual vector)?

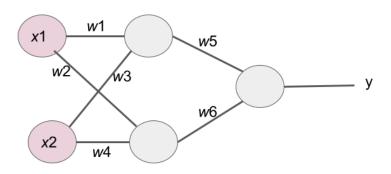
- 3. **(a)** The following four training instances are provided: [4]
 - (i) $x_1 = -1$, $y_1 = 0.03$
 - (ii) $x_2 = 0$, $y_2 = 0.80$
 - (iii) $x_3 = 1$, $y_3 = 1.90$
 - (iv) $x_4 = 2$, $y_4 = 3.05$

Suppose you model this data using the ordinary least squares regression form of

$$y = f(x) = a_0 + a_1 x$$

Which of the following parameters (a_0 , a_1) would you use to best model this data? Justify your answer.

- (I) (1,2)
- (II) (1,1)
- (III)(2,1)
- (IV) (2,2)
- **(b)** Why do we allow misclassifications in support vector classifier? [3]
- (c) Briefly explain the principle behind SVM. [3]
- 4. Consider a neural network, consisting of two inputs (shown as x1, x2), a single hidden layer containing two units, and one output unit. The weights are w1 through w6. The activation function used by the hidden and output units is specified in each sub-question.



- (a) Suppose each input is binary-valued. The activation function used by each [4] unit is the threshold function f(x) given by:
- f(x) = 1 if x > t, and
- f(x) = 0 otherwise.

Assume t is the threshold which can be different for different units and must be set properly. How will you implement the equivalence gate (defined as Q=A.B+A'.B' where A, B are the input boolean variables, A' denotes the complement of A, '+' denotes the OR operator and '.' denotes the AND operator) with this neural network? Explain with a diagram.

(b) Assume each input is a real number. (There is no bias term for the units.) [3] Consider 2 cases:

Case-I: each unit uses sigmoid activation function, i.e., $f(x) = 1/(1 + \exp(-x))$,

Case-II: each unit uses linear activation function, i.e., f(x) = Cx where C is a constant.

Write down the expression for the output *y* in each case.

(c) Consider **Case-II** from part (b) above. Can you draw an equivalent neural [3] network (with linear activation function) that produces the same output but without any hidden layer?

(You have to express the weights of the new network in terms of the old weights *w*1 through *w*6.)

5. **(a)** In the PAC learning model, the sample complexity for a consistent learner [4] with finite hypothesis space is given by

 $m >= (1/\epsilon) (\ln |H| + \ln (1/\delta))$

where the symbols have their usual significance.

Suppose the concept class C = set of boolean conjunctions based on n boolean variables. Show that the class C is PAC-learnable by a consistent learner with hypothesis space H = C.

(Assume we are only concerned with the number of training examples required and not with the computational resources when defining PAC-learnability.)

- **(b)** Why is it unrealistic to expect a classifier to give zero test error even when [3] trained on examples that are very representative of the underlying data distribution?
- **(c)** Briefly explain the significance of VC-dimension in computational [3] learning theory.

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