

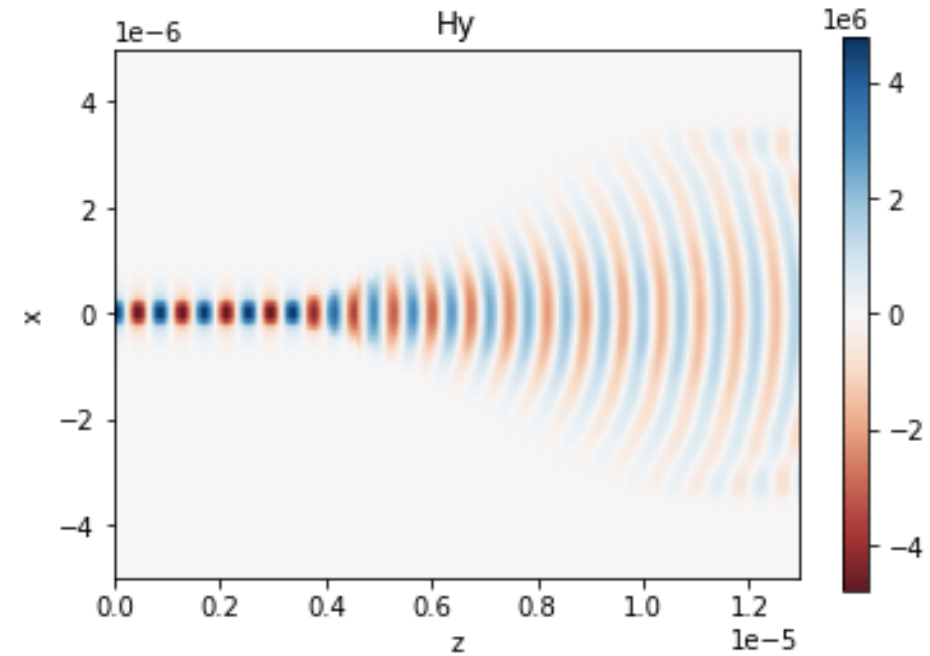
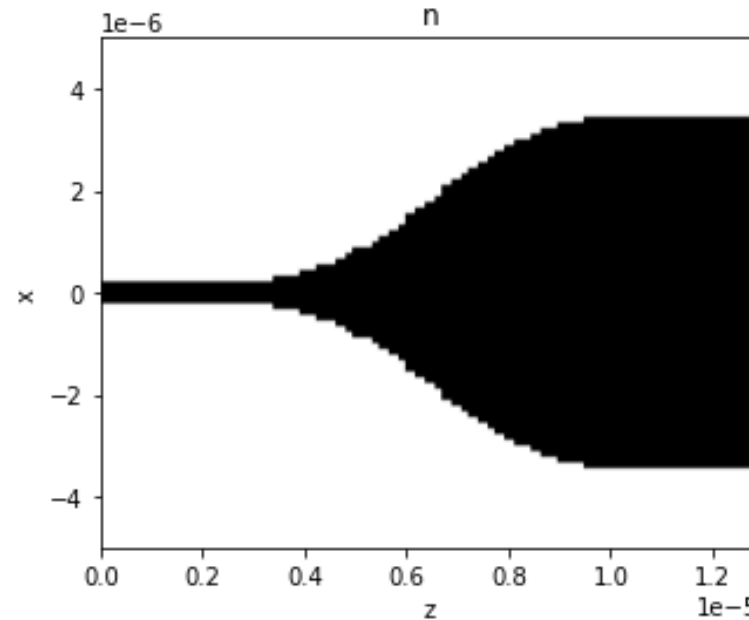
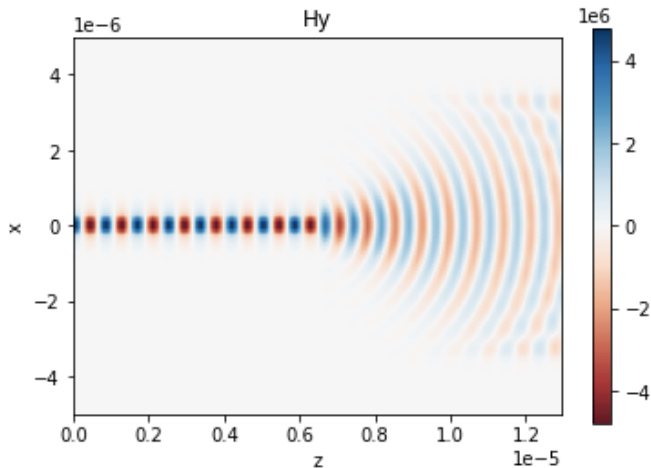
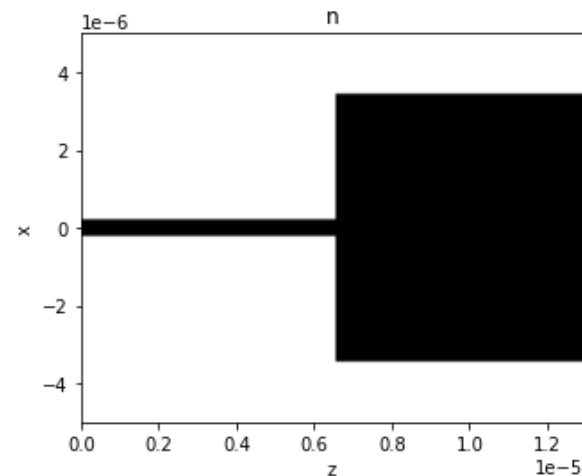
Machine Learning in Photonics:



Py

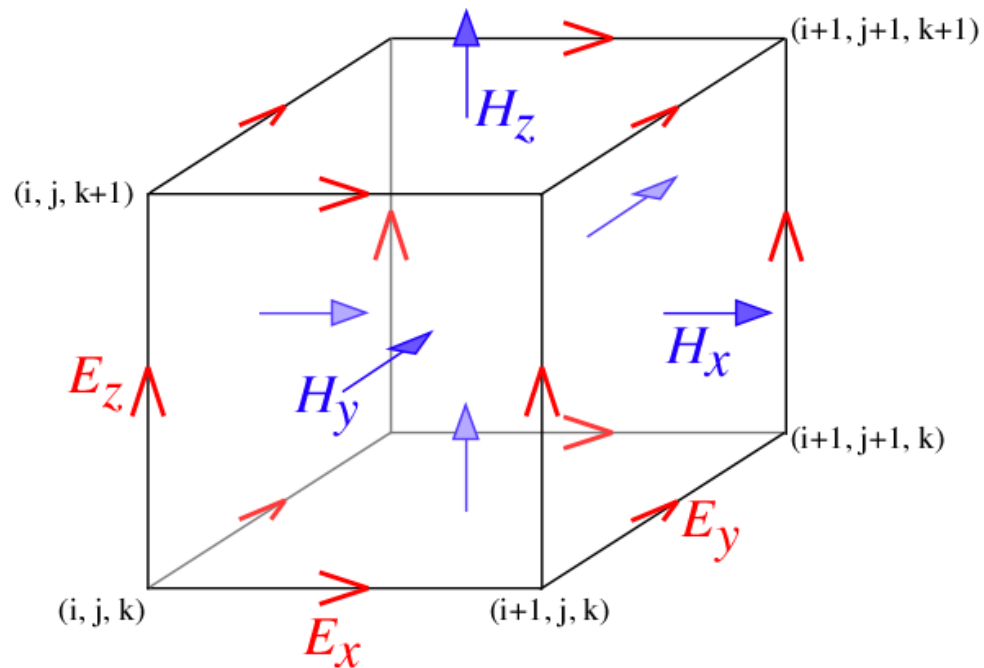
Ian Hammond, Alec Hammond

EME Overview



[Photonic Crystal EME with PML](#)
[Dielectric Waveguide EME](#)
[EME Advanced Boundary Conditions](#)

Finite Difference Overview



[MEEP Yee Lattice](#)
[MEEP FDTD Paper](#)
[EMpy FD Modesolver Paper](#)

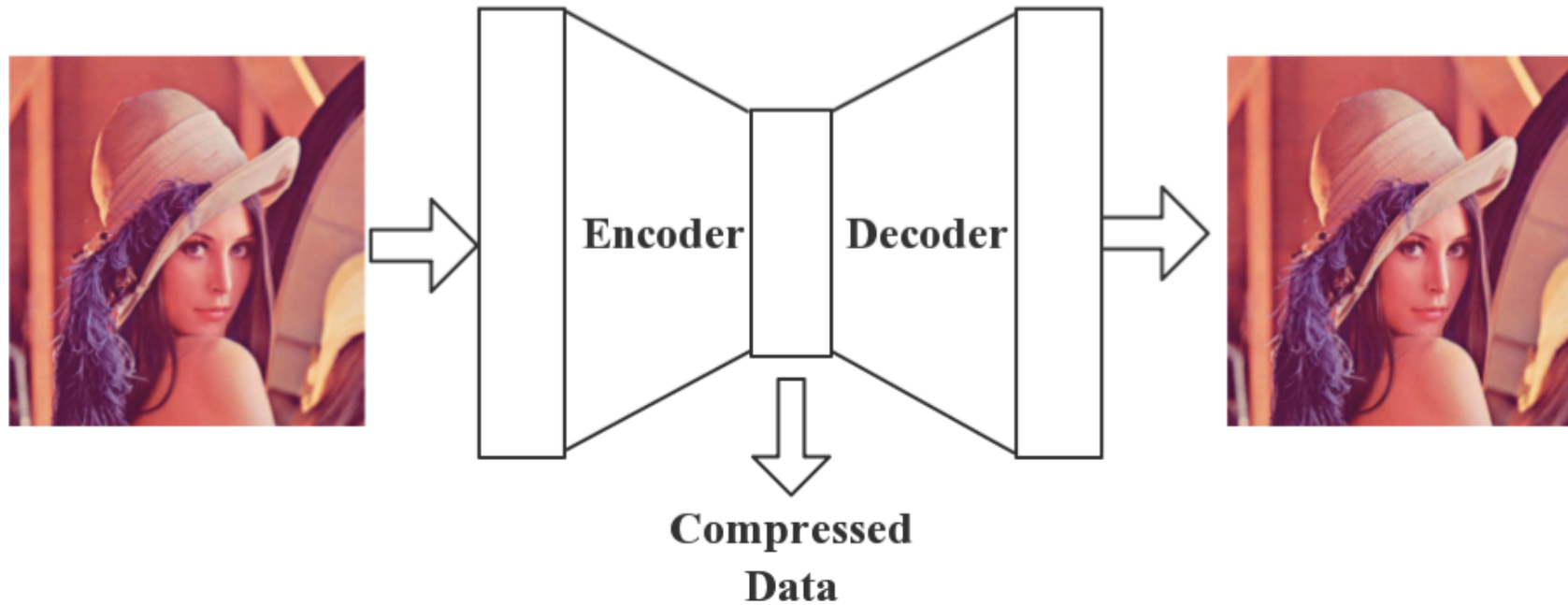
$$\nabla \cdot \mathbf{E} = \frac{\rho}{\epsilon_0}$$

$$\nabla \cdot \mathbf{B} = 0$$

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$$

$$\nabla \times \mathbf{B} = \mu_0 \mathbf{j} + \frac{1}{c^2} \frac{\partial \mathbf{E}}{\partial t}$$

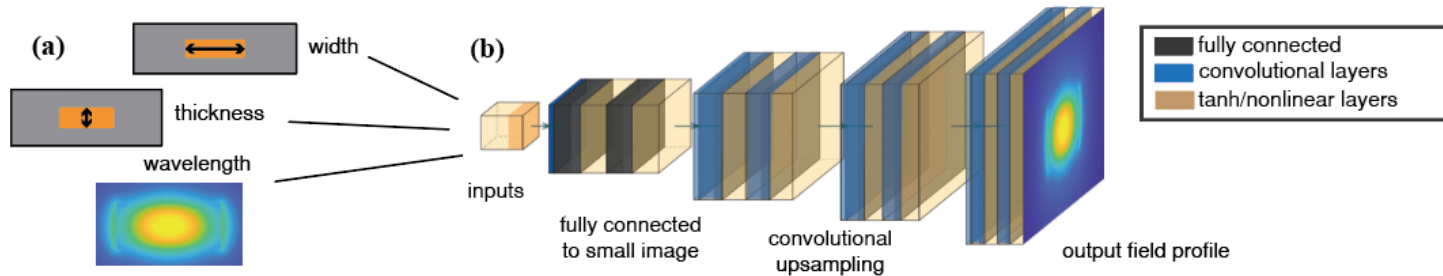
Neural Network (Convolutional Autoencoder)



[Convolutional Autoencoder](#)
[MIT OpenCourseWare Neural Networks](#)

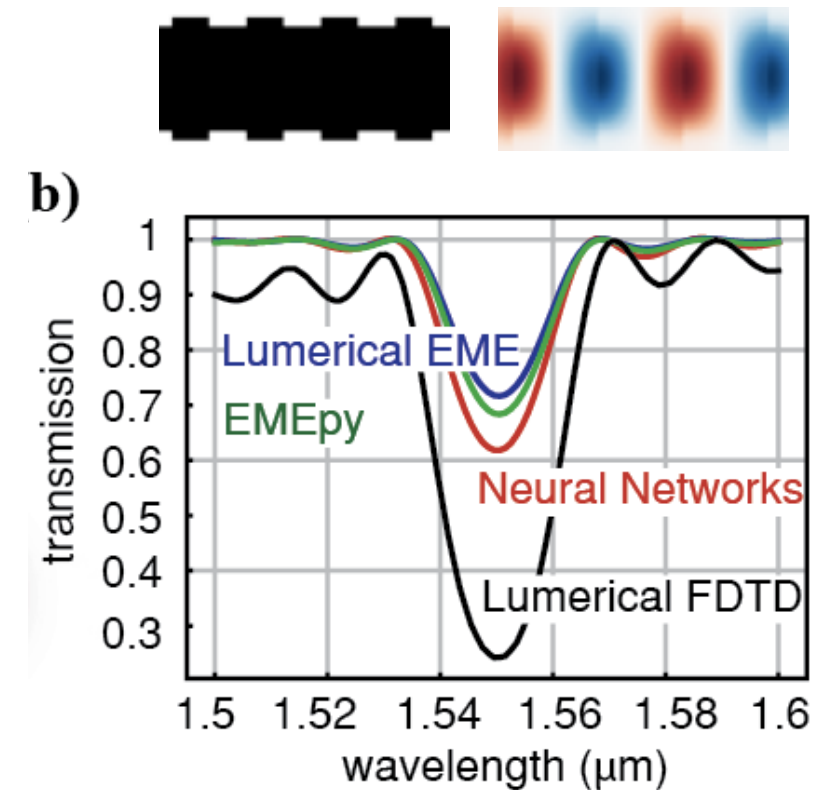
EMEPy Overview

- Convolutional Neural Networks (CNN) replace Finite Difference (FD) solver



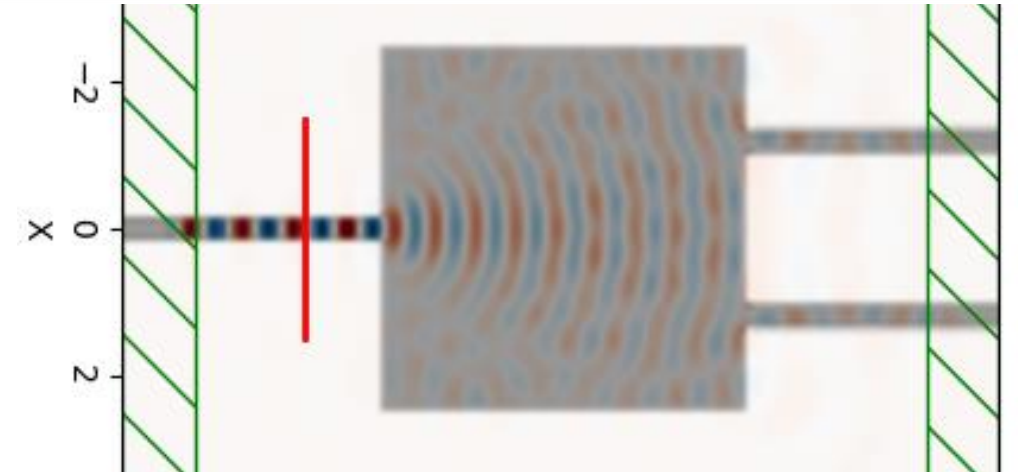
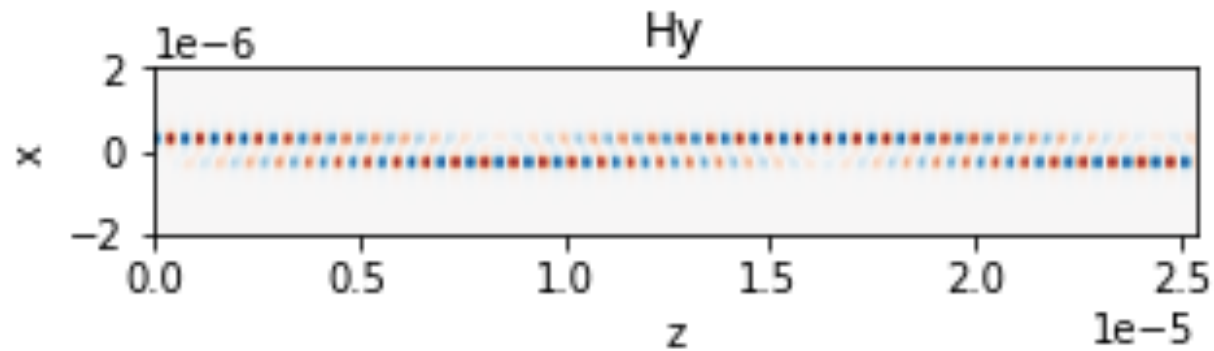
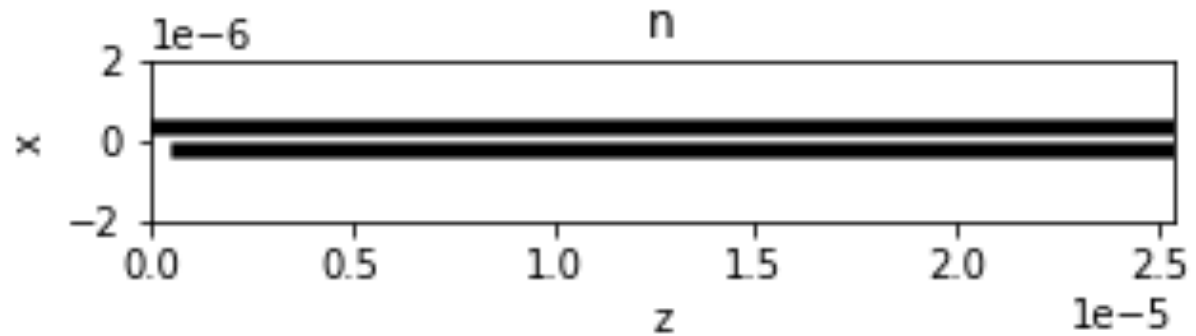
[EMEPy Docs](#)
[CLEO EMEPy Paper](#)

Optics Letters EMEPy Paper



EMEPy Recent Updates

- MultiMode Field Propagation
- Recently discovered critical error!*



EMEPy Inverse Design



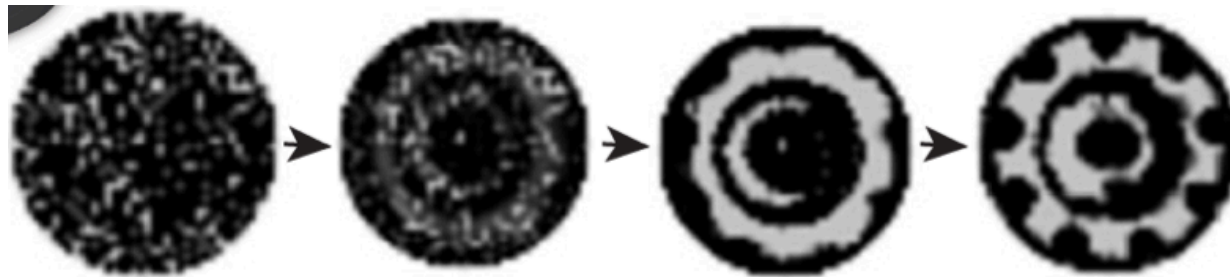
1) Overlap Integrals



2) Phase Propagation

Density Based Inverse Design

- Pixel Based
- Binary material at each pixel

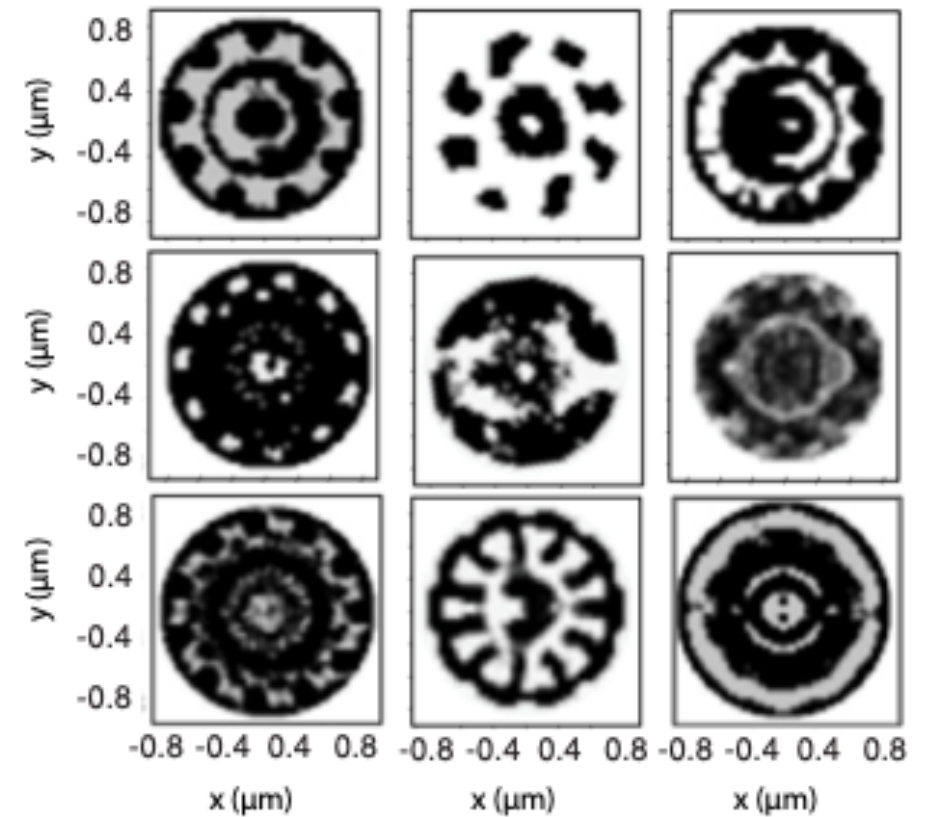


MEEP Topology Optimization

[Quantum Emitter Topology Optimization \(FiO\)](#)

[Photonic TopOpt for Foundry Design](#)

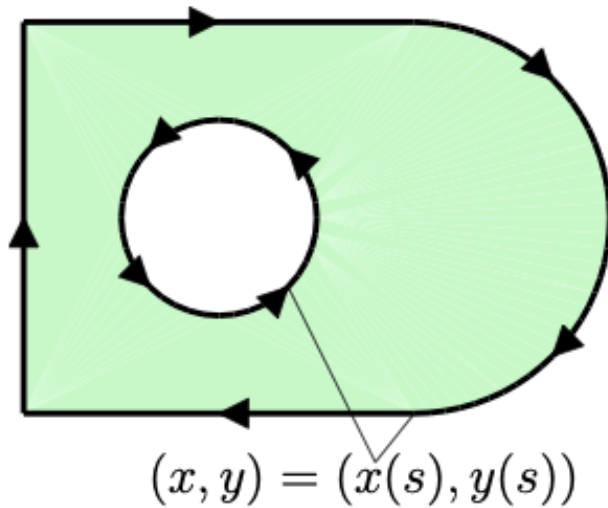
[Hybrid Time/Frequency-Domain TopOpt](#)



Level Set Based Inverse Design

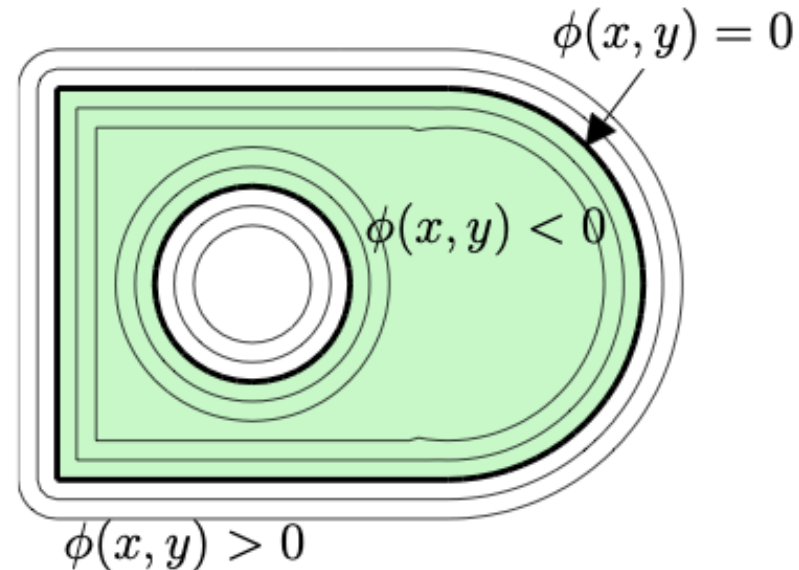
Explicit Geometry

- Parameterized boundaries



Implicit Geometry

- Boundaries given by zero level set



[Implicit vs Explicit Level Set](#)

Adjoint Formulation

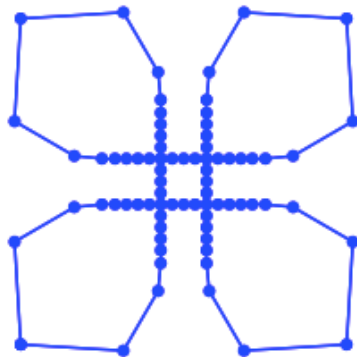
$$\nabla f(x, y) = \lambda \nabla g(x, y) \quad \text{Lagrange Multiplier}$$

$$\frac{\partial f_n}{\partial \rho} = -\widehat{\mathbf{E}}_a^T(\rho, \widehat{\omega}) \frac{\partial \epsilon_r(\rho, \widehat{\omega})}{\partial \rho} \widehat{\mathbf{E}}_f(\rho, \widehat{\omega}) \quad \text{FDTD/FDFD Adjoint}$$

Proposed Algorithm

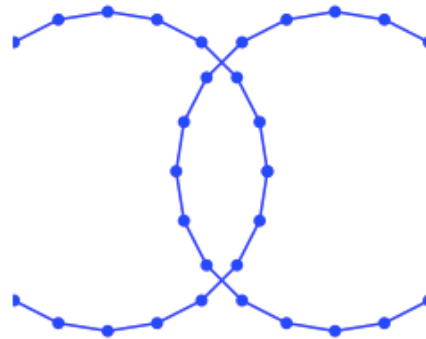
1. Use **explicit** level set (discretization then differentiation)
2. Utilize **implicit** level set method of sub pixel smoothing
3. Forward simulation -> Store steady state fields (E)
4. Adjoint simulation -> Store steady state fields (λ)
5. $\nabla_{\phi} f = -\lambda A_{\phi} E$ A = Maxwell Operator

Sharp corners



Subpixel Smoothing Eliminates

Topology changes



Explicit Level Set Allows

Fast Gradients



Adjoint Routine