

Derivatives Pricing Course

Lecture 5 – Monte Carlo methods

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Agenda

- Fundamentals.
- Generation of random samples.
- Digital options.
- C++ implementation.
- QuantLib results.



Previously discussed

• First way to price a derivative security is to find a closed-form solution of a parabolic PDE or to explicitly evaluate an expectation of a random variable.

• Second way is to find solutions numerically, and we have discovered how to find solutions to PDEs using finite-difference methods.



Following steps

- While the finite difference method is flexible and powerful, it has a number of limitations.
- First, its usage is restricted to problems where the state variable dynamics are Markovian.
- Second, for strongly path-dependent problems, the method often does not apply.
- And third, it is unsuited for problems where the dimension of the underlying is high (exponential growth in p, where p the number of dimensions).



Previously discussed

- We will study the Monte Carlo method, a numerical technique where the computational effort grows only linearly in the problem dimension p.
- While the convergence of the Monte Carlo method is relatively slow, it is nearly always the method of choice for high-dimensional pricing problems.
- On the other hand, as Monte Carlo inherently run forward in time, pricing of American/Bermudan options becomes tedious.



Fundamentals

• Consider a European-style derivative V with time T payout V(T) = g(T). Where finite-difference methods start with a PDE representation of the price of a contingent claim at times t < T, the starting point for the Monte Carlo method is the basic martingale relation:

$$V(t) = D(t)E_t^{Q}(g(T)/D(T))$$

• To evaluate this expression numerically, we need a numerical technique to compute expectations of a random variable.



Fundamentals

• Theorem 5.1(Strong Law of Large Numbers) Let $Y_1, Y_2, ...$ be a sequence of i.i.d. random variables with expectation $\mu < \infty$. Define the sample mean:

$$\overline{Y}_n = \frac{1}{n} \sum_{i=1}^n Y_i$$
 then $\lim_{n \to \infty} \overline{Y}_n = \mu$, a.s.

- This result forms the basis for Monte Carlo method, which computes the expectation by simply
 - i. generation independent realization of g(T)/D(T)
 - ii. forming their average
- Consider the expected convergence rate of the Monte Carlo method as *n* is increased.



Fundamentals

• Theorem 5.2(Central Limit Theorem) Let $Y_1, Y_2, ...$ be a sequence of i.i.d. random variables with expectation μ and standard deviation $\sigma < \infty$. Then, for $n \to \infty$:

$$\frac{\overline{Y}_n - \mu}{\sigma/\sqrt{n}} \to \mathcal{N}(0,1).$$

Let's define a sample standard deviation:

$$s_n \triangleq \sqrt{\frac{1}{n-1} \sum_{i=1}^n \left(\frac{g_i D(t)}{D_i} - \overline{V}(t) \right)^2}$$

- The quantity s_n/\sqrt{n} is known as the *standard error*.
- For a given level of percentile we can build a confidence interval for V(t).



Fundamentals

- The rate at which the confidence interval contracts is $O(n^{-\frac{1}{2}})$.
- This is relatively slow: to reduce the width of the interval by a factor of 2, *n* must increase by a factor of 4.
- On the other hand, we notice that the convergence rate only depends on n, not on the specifics of g_i .



Generation of random samples

- At the most basic level, the Monte Carlo method requires the ability to draw independent realizations of a scalar random variable Z with a specified cumulative distribution function $F(z) = P(Z \le z)$, where P is a probability measure.
- On a computer, the starting point for this exercise is a *pseudo-random number generator*, a software program that will generate a sequence of numbers uniformly distributed on [0,1].
- The externally specified starting point is the *seed* of a generator.
- Also one should pay attention to the *period* length of the generator.
- Now we need to convert uniformly distributed numbers into draws from the distribution F of Z.



Inverse Transform Method

• Let *U* be a random variable uniformly distributed on [0,1], and consider setting:

$$Z = F^{-1}(U)$$

as desired it has the needed distribution.

- Many distributions allow for closed-form inversion, however method depends on being able to compute F^{-1} fast.
- For the Gaussian distribution, no closed-form expression for the inverse distribution exists.



Acceptance-Rejection

- In cases where F^{-1} is cumbersome to compute, this method may be preferable.
- Suppose that we want to sample from a density

$$f(z) = dF(z)/dz$$

• And also suppose that we have a good method to sample from a density e(z), where

$$e(z)c \ge f(z), z \in \mathbb{R}$$

for some positive constant c.

- Steps:
 - 1. Draw a sample Z from e(z).
 - 2. Draw an independent uniform variable U.
 - 3. Accept the sample Z if $U \le f(Z)/(ce(Z))$; otherwise discard it.



Correlated Gaussian samples

- In applications one may face the task of generating vectors of random variables, drawn from a joint multi-variate distribution.
- Recall that a *p*-dimensional Gaussian distribution $\mathcal{N}(\mu, \Sigma)$ is characterized by a density: $\varphi_p(z; \mu, \Sigma) = \frac{1}{(2\pi)^{p/2} (\det \Sigma)^{1/2}} \exp\left(-\frac{1}{2}(z-\mu)^T \Sigma^{-1}(z-\mu)\right)$
- Lemma 3.3. Let $Z \sim \mathcal{N}(\mu, \Sigma)$ be a p-dimensional. Given a $d \times p$ matrix A and a d-dimensional vector B, then

$$AZ + B \sim \mathcal{N}(A\mu + B, A\Sigma A^T)$$

- We can use this lemma as follows. Suppose that we generate p independent standard Gaussian samples X vector. Define a $(p \times p)$ dimensional matrix C satisfying $CC^T = \Sigma$.
- Then $Z = \mu + CX$ is distributed $\mathcal{N}(\mu, \Sigma)$.
- We need to determine a matrix C.



Matrix decomposition

- Cholesky decomposition we impose the constraint that the matrix C is lower triangular.
- For instance, if $\Sigma = \begin{pmatrix} \sigma_1^2 & \rho \sigma_1 \sigma_2 \\ \rho \sigma_1 \sigma_2 & \sigma_2^2 \end{pmatrix}$

• Then
$$C = \begin{pmatrix} \sigma_1 & 0 \\ \sigma_2 \rho & \sigma_2 \sqrt{1 - \rho^2} \end{pmatrix}$$

• If the matrix Σ is only positive semi-definite (but not positive definite), the Cholesky decomposition will fail.



Matrix decomposition

• As an alternative to Cholesky decomposition, we can also consider diagonalizing Σ through an eigenvalue decomposition.

$$\Sigma = E\Lambda E^T$$

where Λ is a diagonal matrix of eigenvalues.

• Implies that one choice of *C* is

$$C = E\sqrt{\Lambda}$$



Double No-Touch option

- Double No-Touch option pays the nominal value N if the spot price of the underlying asset is between two numbers, the lower K_1 and upper K_2 strikes of the option.
- The payoff:

$$g(T) = N \cdot \mathbb{I}_{\{K_1 \le S(T) \le K_2\}}$$



Double One-Touch option

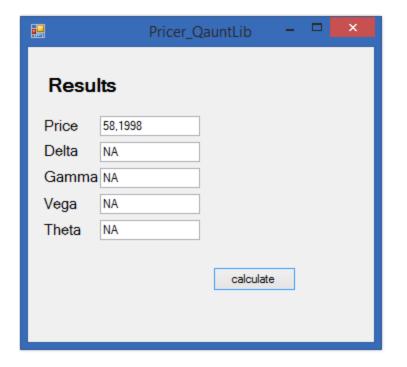
- Double One-Touch option pays the nominal value N if the spot price of the underlying asset reaches any of two numbers, the lower K_1 and upper K_2 strikes of the option.
- The payoff:

$$g(T) = N \cdot \mathbb{I}_{\{K_1 \le S(T)\} \cup \{S(T) \ge K_2\}\}}$$



What is the price of one-touch with the same parameters?

- No-Touch option
 - -S = 100
 - r = 0
 - $-\sigma = 20\%$
 - $-K_1 = 70$
 - $-K_2 = 120$
 - -N = 100



• Closed-form formula as an infinite series exists.



C++ code Payoff(.h)

```
#ifndef PAYOFF_H
#define PAYOFF H
//Abstract class to define the interface
class Payoff
public:
            Payoff(){};
            virtual ~Payoff(){}
            virtual double operator()(double Spot) const = 0;
            virtual Payoff* clone() const = 0;
};
class PayoffCall : public Payoff
public:
            PayoffCall(double Strike_);
            double operator()(double Spot) const;
            ~PayoffCall(){}
            Payoff* clone() const;
private:
            double Strike;
};
#endif
```



C++ code Payoff(.cpp)



C++ code OptionClass(.h)

```
#ifndef OPTIONCLASS_H
#define OPTIONCLASS_H
#include "Bridge.h"
//Abstract class for Option - defined interface, overload payoff function in inherited classes
//to return payoff at expiry
class SimpleOptionMC
public:
            SimpleOptionMC(const Bridge& thePayoff , double Time );
            double optionPayoff(double Spot) const;
            double getTime() const;
private:
            double Time;
            //Bridge to separate Option class from Payoff class realization
            Bridge thePayoff;
};
#endif
```



C++ code OptionClass(.cpp)

```
#include "OptionClass.h"
SimpleOptionMC::SimpleOptionMC(const Bridge& thePayoff_, double Time_) :
            thePayoff(thePayoff_), Time(Time_)
double SimpleOptionMC::optionPayoff(double Spot) const
           return thePayoff(Spot);
double SimpleOptionMC::getTime() const
            return Time;
```



C++ code Bridge(.h)

```
#ifndef BRIDGE_H
#define BRIDGE_H
#include "Payoff.h"
//New class created for memory handling and copying
class Bridge
public:
            //For type conversion Payoff <-> Bridge
            Bridge(const Payoff& initialPayoff);
            //Copy constructor for Bridge
            Bridge(const Bridge& initial);
            double operator()(double Spot) const;
            //Class stores a pointer, memory was allocated with new
            ~Bridge();
private:
            Payoff* thePayoff;
};
#endif
```



C++ code DoubleNoTouch(.h)



C++ code DoubleNoTouch(.cpp)

```
#include "DoubleNoTouch.h"
PayOffDoubleNoTouch::PayOffDoubleNoTouch(double LowerBarrier_, double UpperBarrier_)
            : LowerBarrier(LowerBarrier_), UpperBarrier(UpperBarrier_)
double PayOffDoubleNoTouch::operator()(double Spot) const
            if (Spot <= LowerBarrier)</pre>
                        return 0.0;
            if (Spot >= UpperBarrier)
                        return 0.0;
            return 100.0;
Payoff* PayOffDoubleNoTouch::clone() const{
            //Copy constructor is called, ok since no dynamic objects
            return new PayOffDoubleNoTouch(*this);
```



C++ code MonteCarloRoutine(.h)



Homework assignment 4

- Modify program to price one-touch option.
- Suggest alternative Normal random variables generating algorithm.
- Convergence plot
 - Fix any spot level
 - X-axis number of simulations, Y-axis value of an option
- **Deadline** 6th May EOD