Raspberry Pi Based Mainframe Simulator

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September 29, 2021

Contents

List of Figures

Chapter 1

Introduction

A rather simplistic view is that this provides a way to get a Raspberry Pi to blink some LEDs and read some switches. However, this hardware could be modified for a number of other applications that require lots of discrete I/O, such as burglar alarms or sprinkler controls.

1.1 Parts

1.1.1 3D Printing

A fair bit of 3D printing is required, so having lots of filament is a good idea. Labels on the panels are done by (on my printer with a 0.15mm layer height) printing 2 layers of the panel color, then 3 layers of a contrasting color for the text, and then the rest in the panel color. The panels are printed with the text faced down. You may wish to tinker with this for your printer. The actual parts are:

- Four or six racks depending on whether you want a 16 or 32 bit system.
- One processor tray.
- Two or three discrete I/O trays.
- One control panel
- One modes panel
- Two or four address/data panels (starting a 9, 8, 16, and 24).

1.1.2 Electronic Parts

Note that soldering will be required so a soldering station with appropriate tools and solder will be required in addition to the following.

- One Raspberry Pi 3B computer (available from many places).

- Four or six half-size perma-proto breadboards (p/n 1609 for qty 1 or p/n 571 for qty 3 from Adafruit)[1].
- One quarter-size perma-proto breadboard (p/n 1608 from Adafruit).
- At least four or up to eight MCP23017 I2C 16 bit input/output port expander chips (p/n 732 from Adafruit).
- One 28-pin DIP socket per MCP23017. (eg p/n A120353-ND from Digi-Key)
- Recommended one LTC4311 I2C Extender/Active Terminator (p/n 4756 from Adafruit).
- One set of Female/Male jumper wires (p/n 1954 from Adafruit). These are used to connect from the Raspberry Pi to the rest of the circuitry since female connectors are needed on the Raspberry Pi end).
- Hookup wire, preferably multi-colored (available from many places).
- 36 pin 0.1" female header (5 pack p/n 598 at Adafruit). You may need a couple packs.
- 23 to 39 Mini panel mount SPDT toggle switches (p/n 3221 from Adafruit). Feel free to use other switches if you like, though you may need to adjust the hole sizes in the panels.
- 11 or 16 female and male DB-9 connectors (eg p/n AE10972-ND (male) and p/n AE11063-ND (female) from Digi-Key (buy a pack of 25 for a price discount)).
- Lots of 5mm oval LEDs (I used red, but you can use other colors) (eg p/n C5SMF-RJF-CT0W0BB1-ND from Digi-Key (buy a pack of 100 for a price discount, you can always use the excess in other projects)).
- Lots of 120Ω resistors (eg p/n CF14JT120RCT-ND (lots of other options) from Digi-Key). These are used for current limiting the LEDs from 3.3V drive. If you're driving the LEDs with 5V, you'll need a bit more resistance. Since the Raspberry Pi uses 3.3V, these will work for this project.
- A couple meters of CAT-5 cable. This is for the cables to connect the various assemblies (available from many places).

1.1.3 Mechanical Hardware

I have a Phillips Panhead Electronic Hardware Kit from Digi-Key (p/n 1602-KIT-ND) that has an assortment of machine screws and nuts. I used these because they were handy.

You will need many cable ties. I have a container of assorted cable ties from Costco. These can be obtained from many other sources.

[1] Adafruit generally throws one of these in with your order if your order is over $100

Chapter 2

Hardware

2.1 Electronics

2.1.1 Processor

I had a Raspberry Pi 3 board laying around so I figured that I would use it. Interestingly, this is a more powerful computer than many of the processors it might be used to simulate.

2.1.2 Discrete I/O

Each of these boards in built on a 1/2 size perma-proto board from Adafruit. It has one MCP23017 16 bit I/O expander chip with I2C interface in a socket. Three pins are provided to configure the address, so the system can have up to 8 of these chips or 128 discrete I/O pins. There is space on the board for 8 current limiting resistors for LED drive.

2.2 3D Printed Parts

2.2.1 Racks

Each rack is a bbs_rack2(10, 6, 4). The size is basically constrained by what my 3D printer can do. Each of these requires about 15 hours to print on my printer. Two of these can be bolted together side-by-side and fit in a 19 inch rack. This is the approximate size of the classic computer equipment. Multiple racks can be bolted together vertically as needed to provide panel space. Each rack has slots for two vertically oriented trays.

2.2.2 Processor Tray

The processor tray has mounting holes for the Raspberry Pi processor boad. It also has a 1/4 size perma-proto board from Adafruit (this may get changed to a half sized board) to provide space for miscellaneous wiring. Also on the tray is a LTC4311 I2C Extender/Active Terminator (p/n 4756 from Adafruit). This may not strictly be necessary, but since the I2C bus will be running off to

several other boards, I thought that it might be a good idea. There is also a DB-9 connector that carries power and the I2C bus to the other trays.

2.2.3 Discrete I/O Tray

Each of these trays has one or two MCP23017 16 bit I/O expander chips with I2C interface. These trays would typically be mounted in the slot next to the panel. The tray has 4 DB-9 connections and can interface with up to 16 LEDs and 16 switches. One additional DB-9 connection is provided to connect the the power and I2C bus from the processor.

2.2.4 Address/Data Panels

The address/data panels provide 8 switches and LEDs numbered consecutively from right to left. The starting number is selectable in the model. Each panel has two cables (one for LEDs and one for switches) that attach to connectors on the discrete I/O boards. Enough of these need to be provided to account for all the address and data lines in the simulated processor. A system would typically have two or four of these panels for 16 or 32 bit systems. Note that there are many cases where the number of address lines does not match the number of data lines. In these cases panels would need to be provided for whichever number is greater.

2.2.5 Control Panel

At this point, without an actual CPU simulation, this is mostly a way to organize what needs to be in a relatively generic control panel. The following functions are needed:

- Read from a memory location.
- Write to a memory location.
- Stop/pause processor execution.
- Start processor execution at a specified address.
- Continue processor execution.
- Reset the processor.

The following switches are defined on the panel:

- “Run”/“Pause” - The “Run” position allows program execution. The “Pause” position temporarily suspends execution. Moving the switch back to the “Run” position will continue where the program left off.
- “Start”/“Stop” - Moving the switch to the “Start” position loads a starting address to begin program execution. The “Stop” position halts a program and a new starting address will need to be provided.
- “Auto”/“Man” - The “Auto” position allows for remote control of the simulator via a web interface. The “Man” position disables remote control.
- “Addr”/“Data” - Selects display and entry of memory addresses or data.

- "Dep" deposits the switch value. If the "Addr"/"Data" switch is in the "Addr" position, a memory address is loaded. If the "Addr"/"Data" switch is in the "Data" position, the switch value is deposited in memory and the address incremented.
- "Exam" is used to examine memory at the current address. The address is incremented each time the switch is moved to the "Exam" position.
- Spare - an empty position reserved for future expansion.
- "Power"/"Off" - This will eventually be wired up to control power to the Raspberry Pi computer.

To Specify an Address

Note that if the word size is greater than 8 bits, some of the lower order address bits may be ignored.

- Toggle the desired address using the address/data switches.
- Move the "Addr"/"Data" switch to the "Addr" position.
- Move the "Dep" (deposit) switch to the "Dep" position.
- Once the LED for the "Dep" switch illuminates, move the switch to the unlabeled position.

To Read Memory

- Specify the starting address as described above.
- Move the "Addr"/"Data" switch to the "Data" position.
- Move the "Exam" switch to the "Exam" position.
- The contents of memory at the specified address will be displayed in the Address/Data LEDs.
- The "Addr"/"Data" switch can be used to toggle between display of the address and the data.
- Move the "Exam" switch to the unlabeled position. This increments the internal address pointer so that by toggling this switch a block of memory can be modified.

To Write Memory

- Specify the starting address as described above.
- Move the "Addr"/"Data" switch to the "Data" position.
- Toggle the desired data using the address/data switches.
- Move the "Dep" switch to the "Dep" position.
- The contents of memory at the specified address will be updated and displayed in the Address/Data LEDs.

- The "Addr"/"Data" switch can be used to toggle between display of the address and the data.
- Move the "Dep" switch to the unlabeled position. This increments the internal address pointer so that by toggling this switch a block of memory can be examined.

To Start Execution at a Specific Address

- Move the "Start"/"Stop" switch to the "Stop" position.
- Move the "Addr"/"Data" switch to the "Addr" position.
- Toggle the address using the address/data switches.
- Move the "Start"/"Stop" switch to the "Start" position.
- If the "Run"/"Pause" switch is in the "Pause" position, move it to the "Run" position.

2.2.6 Mode Panel

This is a display only panel to show the processor and memory access modes. It has seven labeled positions in two groups separated by a spare. The first group is the processor mode. This indicates which of four possible modes (User, Supervisor, Executive, or Kernel) the processor is in. The second group indicates the type of memory access. There are three possibilities: Instruction (read-only), Data (read/write), and Interrupt (read-only).

2.3 Assembly

2.3.1 Discrete I/O Boards

- First, solder the resistors and socket. See Figure 2.1.
- Then add some fixed wires. See Figure 2.2.

2.3.2 Panel I/O Tray

- Attach the connectors to the tray (see Figure 2.3)..

2.3.3 I2C Bus Cable

The I2C bus cable is probably the most difficult bit of soldering as you will have to add two wires to each contact in a connector. Multiple times. Which pairs are used for which pins isn't particularly important, but I wire pins 2 & 6, 2 & 7, 4 & 8, and 5 & 9 as pairs. Pin 3 is left unconnected. It is obviously important to have the same wire go to the same pin on each connector on the bus. Figure 2.4 shows an example cable. Figure 2.5 is a close-up of one of the connectors. It is a little easier to decide ahead of time how many connectors you want on the bus. Soldering a cable segment to an existing connector can be done, but is more difficult.

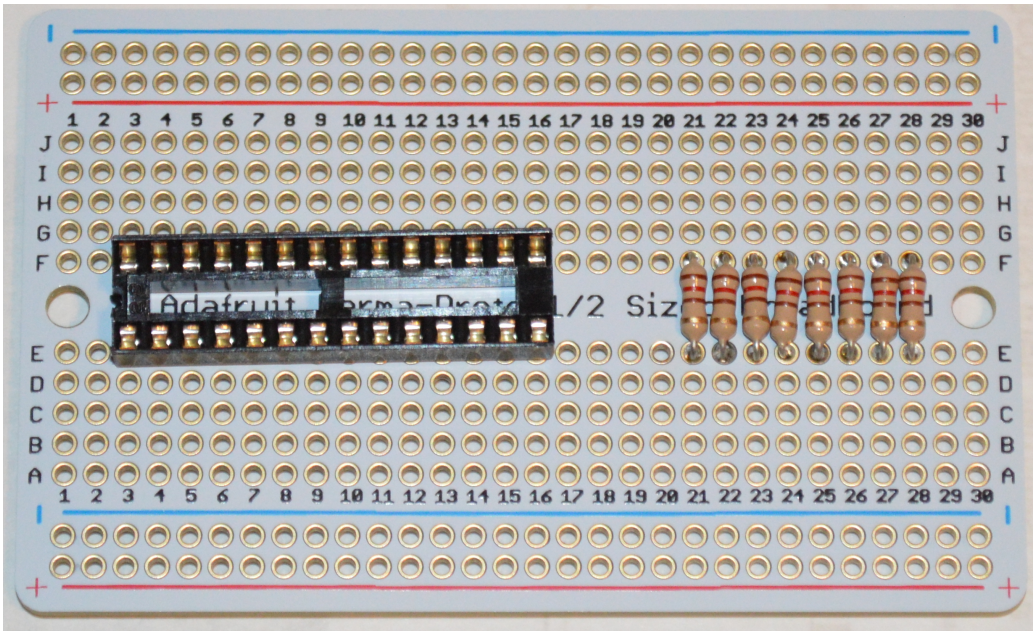

Figure 2.1: GPIO Board with Socket and Resistors

2.3.4 Panel LEDs

The wiring for the panel LEDs is similar for all panels. The Modes Panel is shown as an example. The LEDs on the other panels would be wired the same way. Note the cable ties used to attach the wiring to the panel. This also helps to keep the LEDs in place so that they don't push out.

- Since CAT-5 cables are only 8 conductor, a separate ground/return wire needs to be added. As a note of caution, I find that the orange and brown pairs are difficult to distinguish. Be careful, otherwise you may wind up having to resolder the connector. See Figure 2.6.
- First using a cable tie, attach the cable to the panel. This helps to keep the cable from moving around while the LEDs are soldered. There is also a bare copper wire used as a ground/return wire for the LEDs. See Figure 2.7.
- Solder the first LED to one side of the cable. This one is the hardest as there is only a short length of wire to work with. See Figure 2.8.
- Solder the next LED and add a cable tie between them. See Figure 2.9.
- Solder the remaining LEDs on that side and add cable ties between them. See Figure 2.10.
- Find a place to solder the ground/return wire from the connector to the bare LED ground/return wire. See Figure 2.11.
- Complete the other side of the panel. See Figure 2.11.

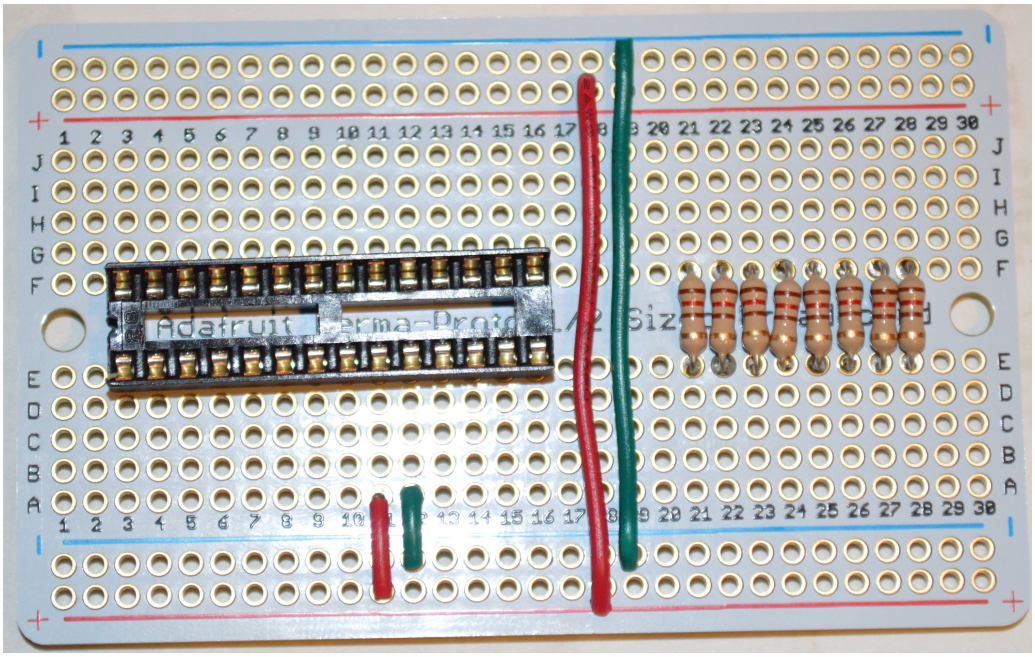

Figure 2.2: GPIO Board with Socket, Resistors, and Fixed Wires

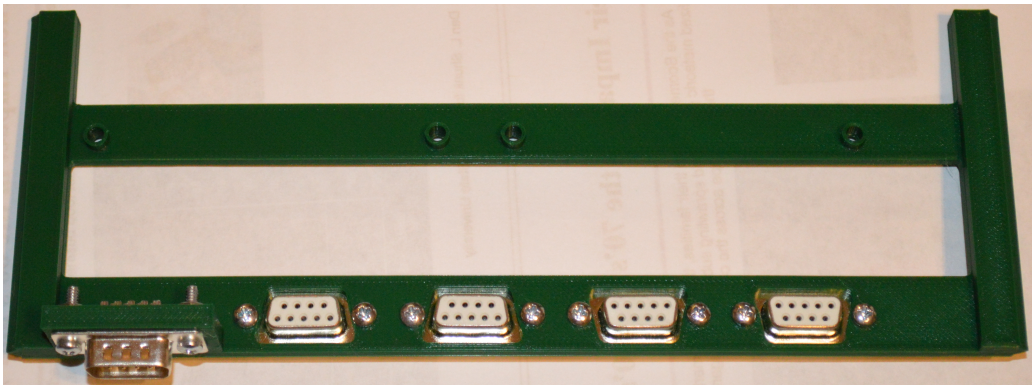

Figure 2.3: Panel I/O Tray with Connectors

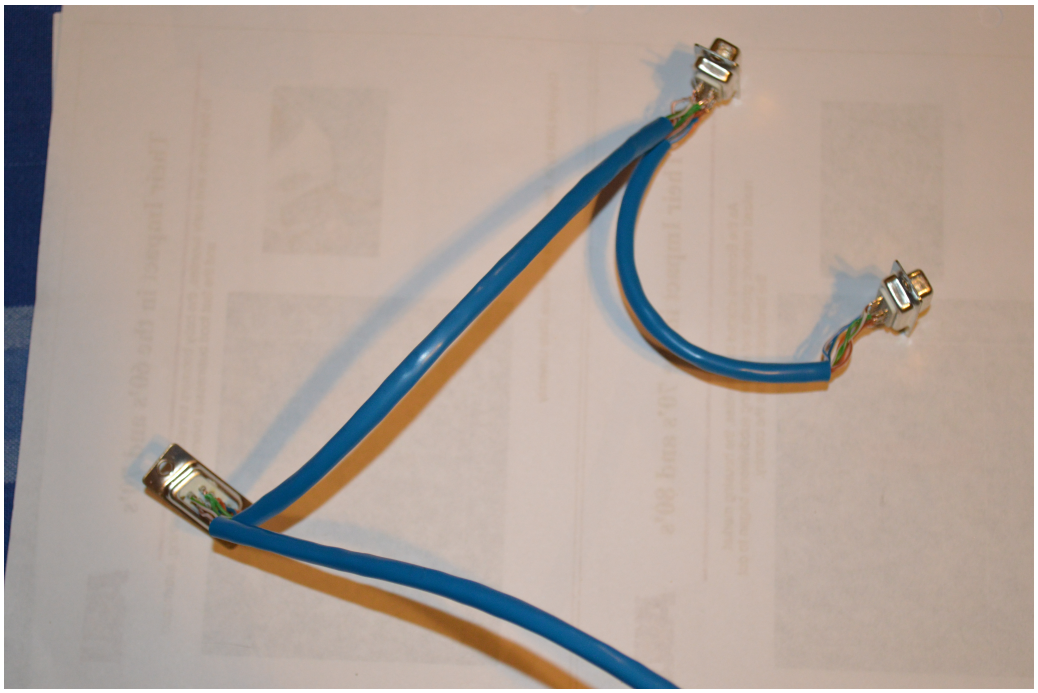

Figure 2.4: The I2C Bus Cable

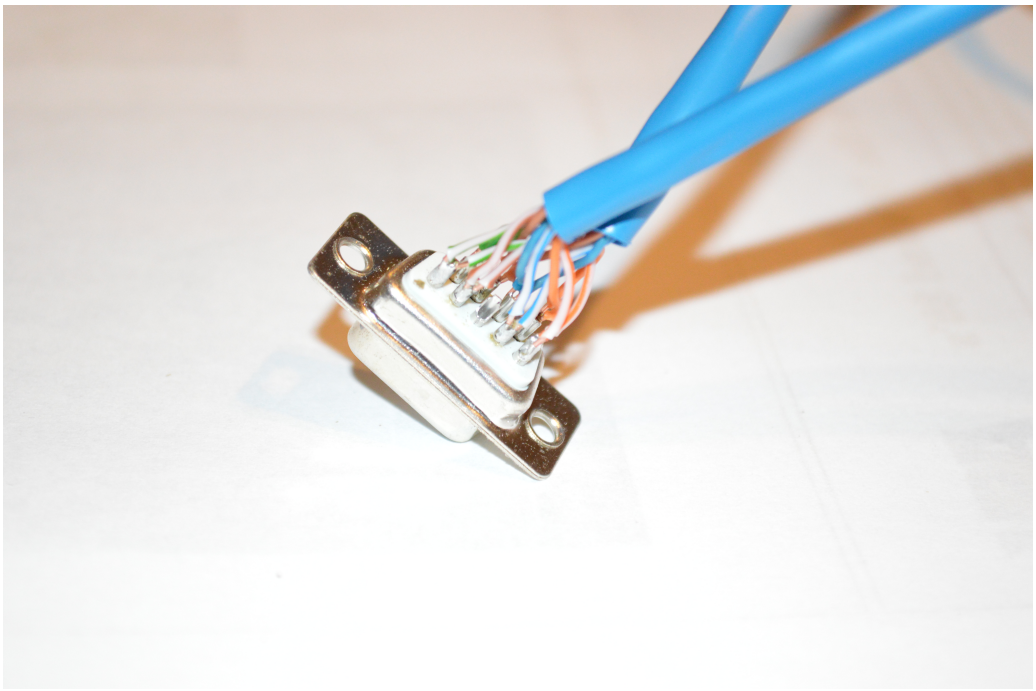

Figure 2.5: An I2C Bus Cable Connector

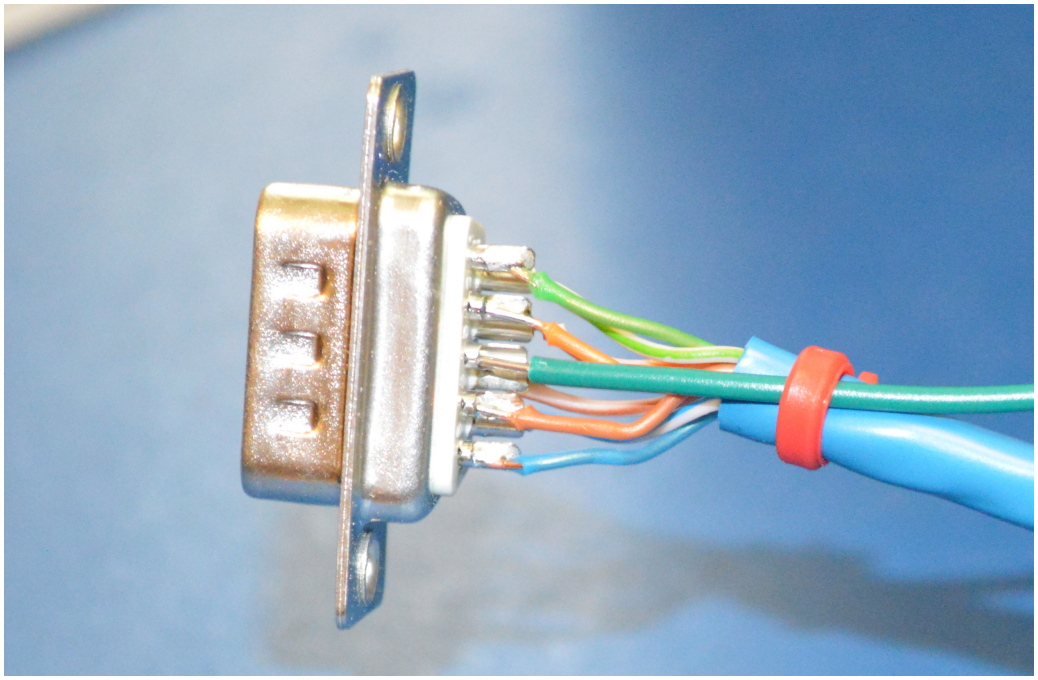

Figure 2.6: The Connector with Ground Wire

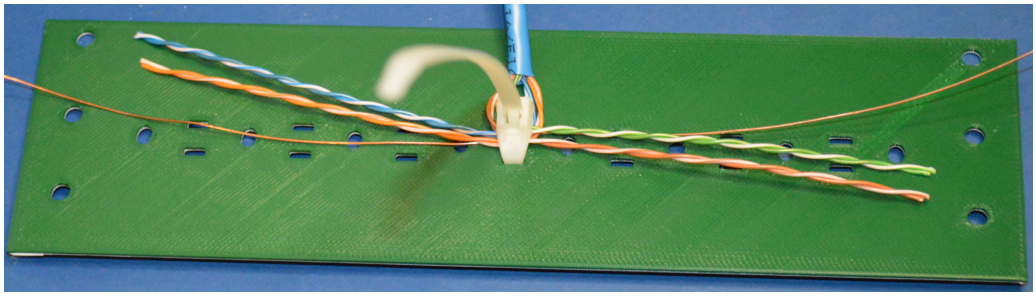

Figure 2.7: Attach the Cable to the Panel

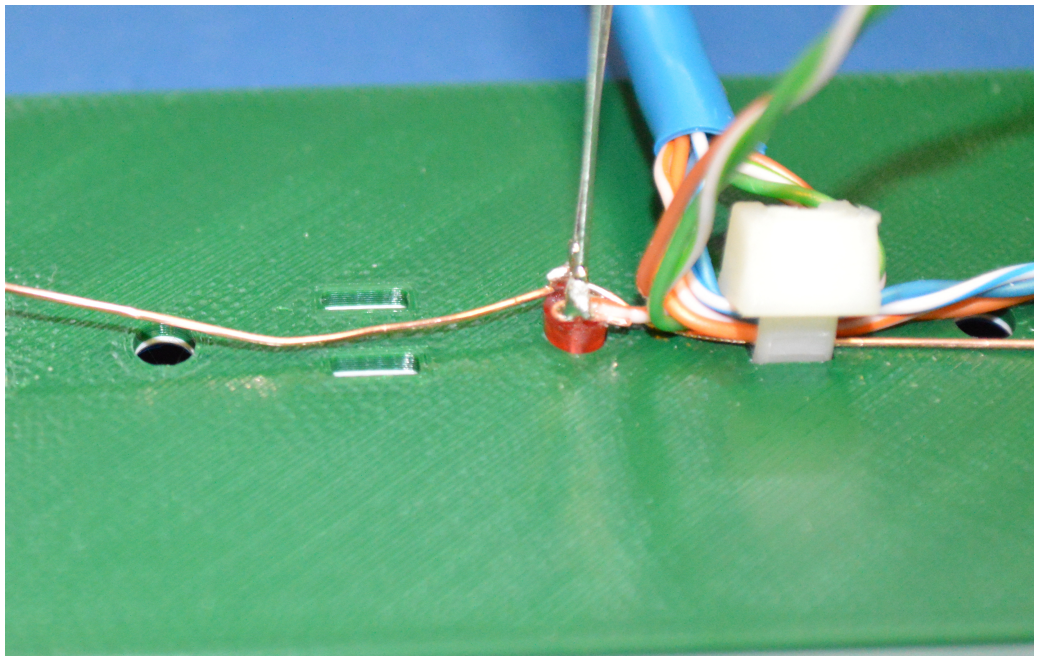

Figure 2.8: Solder the First LED

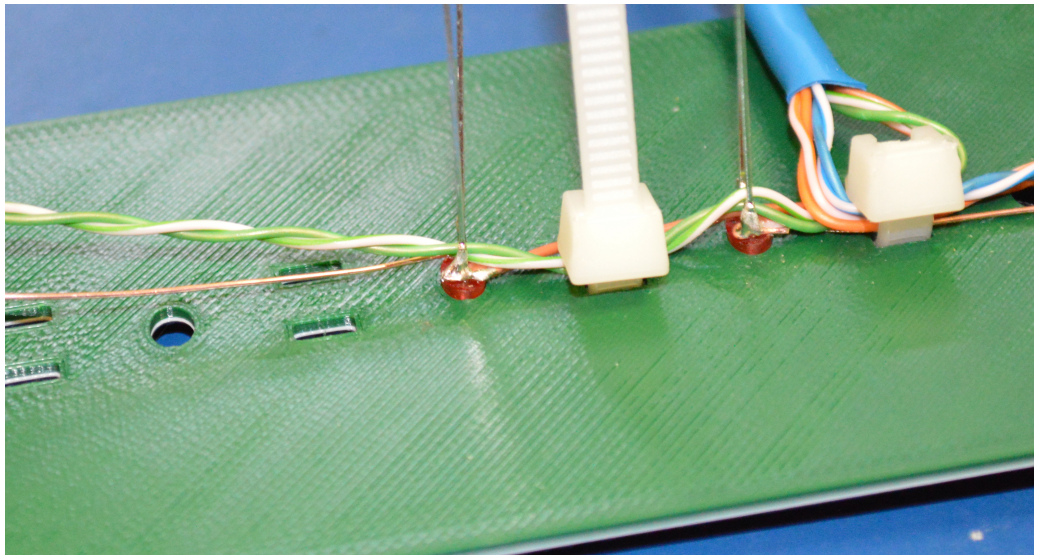

Figure 2.9: Solder the Second LED and Add a Cable Tie

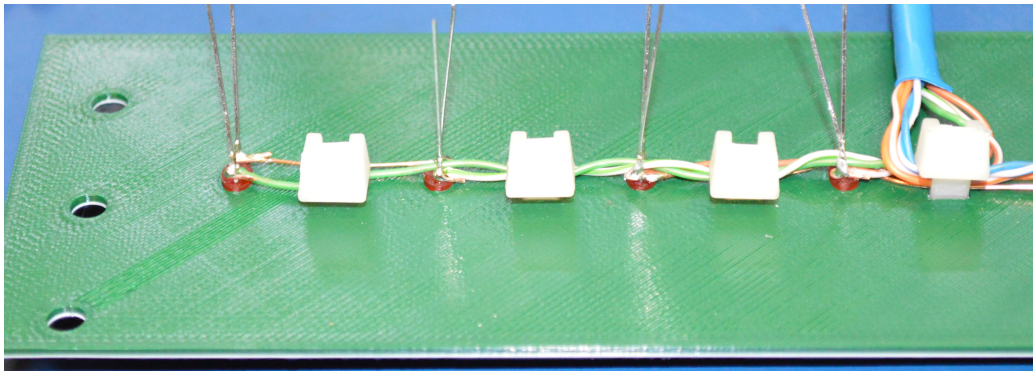

Figure 2.10: Solder the Remaining LEDs on That Side and Add Cable Ties

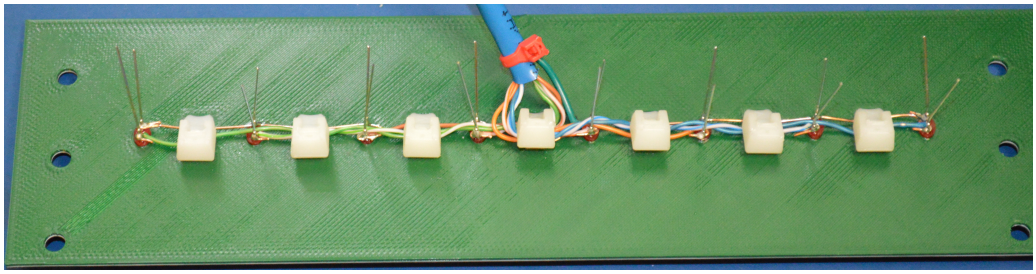

Figure 2.11: The Completed Panel

Chapter 3

Software

3.1 Overview

3.2 Simulation

3.3 Web Server