Review: Bilinear Model

Bilinear model,

$$\hat{\mathbf{y}} = f((\mathbf{x}^0 \mathbf{W}^0) \mathbf{W}^1 + \mathbf{b})$$

- $\mathbf{x}^0 \in \mathbb{R}^{1 imes d_0}$ start with one-hot.
- $ightharpoonup \mathbf{W}^0 \in \mathbb{R}^{d_0 imes d_{\mathrm{in}}}, \ d_0 = |\mathcal{F}|$
- $lackbox{W}^1 \in \mathbb{R}^{d_{
 m in} imes d_{
 m out}}$, $\mathbf{b} \in \mathbb{R}^{1 imes d_{
 m out}}$; model parameters

Notes:

- Bilinear parameter interaction.
- $ightharpoonup d_0 >> d_{
 m in}$, e.g. $d_0 = 10000$, $d_{
 m in} = 50$

Review: Bilinear Model: Intuition

$$(\mathbf{x}^0\mathbf{W}^0)\mathbf{W}^1 + \mathbf{b}$$

$$\begin{bmatrix} w_{1,1}^1 & \cdots & w_{0,d_{\mathrm{out}}}^1 \\ \cdots & \cdots & \cdots \\ w_{d_{\mathrm{in}},0}^1 & \cdots & w_{d_{\mathrm{in}},d_{\mathrm{out}}}^1 \end{bmatrix}$$

Review: Window Model

Goal: predict t_5 .

Windowed word model.

$$w_1 \ w_2 \ [w_3 \ w_4 \ w_5 \ w_6 \ w_7] \ w_8$$

- ► w₃, w₄; left context
- ▶ *w*₅; Word of interest
- \triangleright w_6 , w_7 ; right context
- d_{win} ; size of window ($d_{\text{win}} = 5$)

Review: Dense Windowed BoW Features

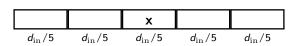
- $ightharpoonup f_1, \ldots, f_{d_{win}}$ are words in window
- ▶ Input representation is the concatenation of embeddings

$$\boldsymbol{x} = [v(f_1) \ v(f_2) \ \dots \ v(f_{d_{\min}})]$$

Example: Tagging

$$w_1 \ w_2 \ [w_3 \ w_4 \ w_5 \ w_6 \ w_7] \ w_8$$

$$\mathbf{x} = [v(w_3) \ v(w_4) \ v(w_5) \ v(w_6) \ v(w_7)]$$



Rows of W^1 encode position specific weights.

Quiz

We are doing tagging with a windowed bilinear model with hinge-loss and no capitalization features. The model has $d_{\rm win}=5$, $d_{\rm in}=50$, $d_{\rm out}=40$, and vocabulary size 10000.

We are given the input window:

The dog walked to the

Unfortunately we incorrectly classify walked as NN as opposed to VP, in a bilinear model with a hinge-loss .

What is the maximum number of parameters that receive a non-zero gradient?

Answer:

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Neural Network

One-layer multi-layer perceptron architecture,

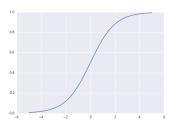
$$NN_{MLP1}(\mathbf{x}) = g(\mathbf{x}\mathbf{W}^1 + \mathbf{b}^1)W^2 + \mathbf{b}^2$$

- **xW** + **b**; perceptron
- **x** is the dense representation in $\mathbb{R}^{1 \times d_{\mathrm{in}}}$
- ullet $\mathbf{W}^1 \in \mathbb{R}^{d_{ ext{in}} imes d_{ ext{hid}}}$, $\mathbf{b}^1 \in \mathbb{R}^{1 imes d_{ ext{hid}}}$; first affine transformation
- $m{W}^2 \in \mathbb{R}^{d_{ ext{hid}} imes d_{ ext{out}}}$, $m{b}^2 \in \mathbb{R}^{1 imes d_{ ext{out}}}$; second affine transformation
- $ightharpoonup g: \mathbb{R}^{d_{ ext{hid}} imes d_{ ext{hid}}}$ is an activation non-linearity (often pointwise)
- $g(\mathbf{xW}^1 + \mathbf{b}^1)$ is the hidden layer

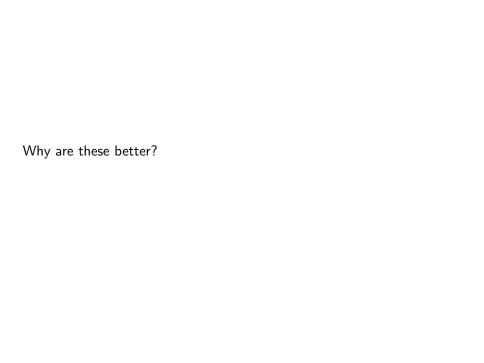
Non-Linear Functions

Logistic sigmoid function:

$$\sigma(t) = \frac{1}{1 + \exp(-t)}$$



Intuition: Each dimension of hidden-layer is the prob. under a logistic regression model.



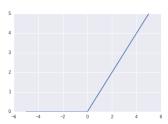
Function Approximator

 $\mathsf{MLP1} \ \mathsf{is} \ \mathsf{a} \ \mathsf{universal} \ \mathsf{approximator}$

Other Non-Linearities: ReLU

Rectified Linear Unit:

$$\mathsf{ReLU}(t) = \max\{0,t\}$$





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