Recurrent Neural Networks 2

CS 287

(Based on Yoav Goldberg's notes)

Review: Representation of Sequence

Many tasks in NLP involve sequences

$$w_1, \ldots, w_n$$

Representations as matrix dense vectors X
 (Following YG, slight abuse of notation)

$$\mathbf{x}_1 = \mathbf{x}_1^0 \mathbf{W}^0, \dots, \mathbf{x}_n = \mathbf{x}_n^0 \mathbf{W}^0$$

Would like fixed-dimensional representation.

Review: Sequence Recurrence

- ► Can map from dense sequence to dense representation.
- $ightharpoonup x_1, \ldots, x_n \mapsto s_1, \ldots, s_n$
- ▶ For all $i \in \{1, ..., n\}$

$$\mathbf{s}_i = R(\mathbf{s}_{i-1}, \mathbf{x}_i; \theta)$$

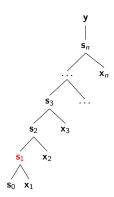
 \triangleright θ is shared by all R

Example:

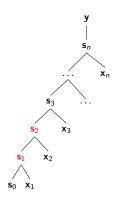
$$\mathbf{s}_4 = R(\mathbf{s}_3, \mathbf{x}_4)$$

= $R(R(\mathbf{s}_2, \mathbf{x}_3), \mathbf{x}_4)$
= $R(R(R(R(\mathbf{s}_0, \mathbf{x}_1), \mathbf{x}_2), \mathbf{x}_3), \mathbf{x}_4)$

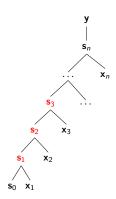
- Run forward propagation.
- ► Run backward propagation.
- ▶ Update all weights (shared)



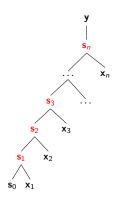
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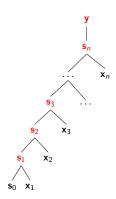
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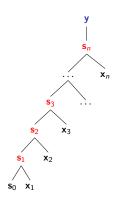
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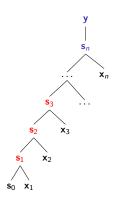
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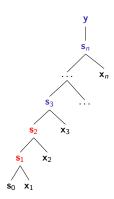
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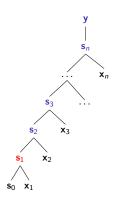
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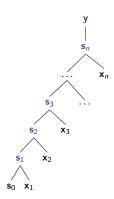
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Issues

- ► Can be inefficient, but batch/GPUs help.
- ▶ Model is much deeper than previous approaches.
 - ▶ This matters a lot, focus of next class.
- ▶ Variable-size model for each sentence.
 - Have to be a bit more clever in Torch.

Quiz

Consider a ReLU version of the Elman RNN with function R defined as

$$NN(\mathbf{x}, \mathbf{s}) = ReLU(\mathbf{s}\mathbf{W}^{\mathbf{s}} + \mathbf{x}\mathbf{W}^{\mathbf{x}} + \mathbf{b}).$$

We use this RNN with an acceptor architecture over the sequence $\mathbf{x}_1, \ldots, \mathbf{x}_5$. Assume we have computed the gradient for the final layer

$$\frac{\partial \mathbf{z}}{\partial \mathbf{s}}$$

What is the symbolic gradient of the previous state $\frac{\partial L}{\partial s_4}$?

What is the symbolic gradient of the first state $\frac{\partial L}{\partial s_1}$?

Answer

Chain rule, then relu cases, then to indicator notation

$$\frac{\partial L}{\partial s_{4,i}} = \sum_{j} \frac{\partial s_{5,j}}{\partial s_{4,i}} \frac{\partial L}{\partial s_{5,j}}$$

$$= \sum_{j} \begin{cases} W_{i,j}^{s} \frac{\partial L}{\partial s_{5,j}} & s_{5,j} > 0 \\ 0 & o.w. \end{cases}$$

$$= \sum_{j} \mathbf{1}(s_{5,j} > 0) W_{i,j}^{s} \frac{\partial L}{\partial s_{5,j}}$$

Answer

Multiple applications of Chain rule, combine relu cases.

$$\frac{\partial L}{\partial s_{1,i}} = \sum_{j_2} \dots \sum_{j_5} \frac{\partial s_{5,j_5}}{\partial s_{4,j_4}} \frac{\partial L}{\partial s_{5,j_5}}$$

$$= \sum_{j_2} \dots \sum_{j_5} \mathbf{1}(s_{2,j_2} > 0 \wedge \dots \wedge s_{5,j} > 0) W_{i,j_2}^s \dots W_{j_4,j_5}^s \dots \frac{\partial L}{\partial s_{5,j}}$$

The Promise of RNNs

- ▶ We hope to learn a model with memory.
- For acceptors this means long-range interaction.

How can you not see this movie?

You should not see this movie.

▶ Memory interaction here is at s_1 , but gradient signal is at s_n

Vanishing Gradients

- ► Gradients at early layers go through many squashing layers.
- For instance consider quiz with hardtanh

$$\sum_{j_2} \dots \sum_{j_5} \mathbf{1}((0 < s_{2,j_2} < 1) \wedge \dots \wedge (0 < s_{5,j} < 1)) W_{i,j_2}^s \dots W_{j_4,j_5}^s \frac{\partial L}{\partial s_{5,j}}$$

► The indicator term causes a tendency towards *vanishing gradients*.

LSTMs