# CS:APP2e Web Aside ARCH:HCL: HCL Descriptions of Y86 Processors\*

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# **Notice**

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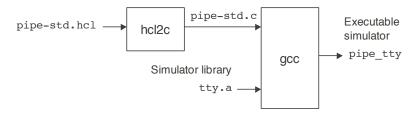
This document describes the Hardware Control Language, HCL, devised to provide a simple, yet systematic way to describe the control logic for Y86 processors. It also includes copies of the HCL descriptions of Y86 processors SEQ and PIPE. Electronic versions of these HCL files are available at www.csapp.cs.cmu.edu.

## 1 HCL Reference Manual

HCL has some of the features of a hardware description language (HDL), allowing users to describe Boolean functions and word-level selection operations. On the other hand, it lacks many features found in true HDLs, such as ways to declare registers and other storage elements; looping and conditional constructs; module definition and instantiation capabilities; and bit extraction and insertion operations.

In its implementation, HCL is really just a language for generating a very stylized form of C code. All of the block definitions in an HCL file get converted to C functions by a program HCL2C These functions are then compiled and linked with library code implementing the other simulator functions to generate an executable simulation program, as diagrammed below:

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This diagram shows the files used to generate the text version of the pipeline simulator.

It would be possible to describe the behavior of the control logic directly in C, rather than writing HCL and translating this to C. The advantage of the HCL route is that we more clearly separate the functionality of the hardware from the inner workings of the simulator.

HCL supports just two data types: bool (for "Boolean") signals are either 0 or 1, while int (for "integer") signals are equivalent to int values in C. Data type int is used for all types of multi-bit signals, such as words, register IDs, and instruction codes. When converted to C, both data types are represented as int data, but a value of type bool will only equal 0 or 1.

# 1.1 Signal Declarations

Expressions in HCL can reference named *signals* of type integer or Boolean. The signal names must start with a letter (a-z or A-z), followed by any number of letters, digits, or underscores (\_). Signal names are case sensitive. The Boolean and integer signal names used in HCL Boolean and integer expressions are really just aliases for C expressions. The declaration of a signal also defines the associated C expression. A signal declaration has one of the following forms:

where *C-expr* can be an arbitrary C expression, except that it cannot contain a single quote (') or a newline character (\n). When generating C code, HCL2C will replace any signal name with the corresponding C expression.

#### 1.2 Quoted Text

Quoted text provides a mechanism to pass text directly through HCL2C into the generated C file. This can be used to insert variable declarations, include statements, and other things generally found in C files. The general form is:

where string can be any string that does not contain single quotes (') or newline characters (\n).

Syntax	Meaning
0	Logic value 0
1	Logic value 1
name	Named Boolean signal
$int$ - $expr$ in $\{int$ - $expr_1$ , $int$ - $expr_2$ , $\dots$ , $int$ - $expr_k\}$	Set membership test
$int$ - $expr_1 == int$ - $expr_2$	Equality test
$int$ - $expr_1$ != $int$ - $expr_2$	Not equal test
$int$ - $expr_1 < int$ - $expr_2$	Less than test
$int$ - $expr_1 \le int$ - $expr_2$	Less than or equal test
$int$ - $expr_1 > int$ - $expr_2$	Greater than test
$int$ - $expr_1 >= int$ - $expr_2$	Greater than or equal test
! bool-expr	Not
$bool$ - $expr_1$ && $bool$ - $expr_2$	And
$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	OR

Figure 1: **HCL Boolean expressions.** These expressions evaluate to 0 or 1. The operations are listed in descending order of precedence, where those within each group have equal precedence.

# 1.3 Expressions and Blocks

There are two types of expressions: Boolean and integer, which we refer to in our syntax descriptions as *bool-expr* and *int-expr*, respectively. Figure 1 lists the different types of Boolean expressions. They are listed in descending order of precedence, with the operations within each group (groups are separated by horizontal lines) having equal precedence. Parentheses can be used to override the normal operator precedence.

At the top level are the constant values 0 and 1 and named Boolean signals. Next in precedence are expressions that have integer arguments but yield Boolean results. The set membership test compares the value of the first integer expression int-expr to the values of each of the integer expressions comprising the set  $\{int$ - $expr_1, \dots int$ - $expr_k\}$ , yielding 1 if any matching value is found. The relational operators compare two integer expressions, generating 1 when the relation holds and 0 when it does not.

The remaining expressions in Figure 1 consist of formulas using Boolean connectives (! for NOT, && for AND. and | | for OR).

There are just three types of integer expressions: numbers, named integer signals, and case expressions. Numbers are written in decimal notation and can be negative. Named integer signals use the naming rules described earlier. Case expressions have the following general form:

The expression contains a series of cases, where each case i consists of a Boolean expression  $bool-expr_i$ , indicating whether this case should be selected, and an integer expression  $int-expr_i$ , indicating the value resulting for this case. In evaluating a case expression, the Boolean expressions are conceptually evaluated in sequence. When one of them yields 1, the value of the corresponding integer expression is returned as the case expression value. If no Boolean expression evaluates to 1, then the value of the case expression is 0. One good programming practice is to have the last Boolean expression be 1, guaranteeing at least one matching case.

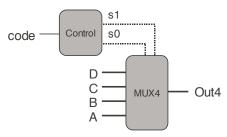
HCL expressions are used to define the behavior of a block of combinational logic. A block definition has one of the following forms:

```
bool name = bool-expr;
int name = int-expr;
```

where the first form defines a Boolean block, while the second defines a word-level block. For a block declared with *name* as its name, HCL2C generates a function gen\_name. This function has no arguments, and it returns a result of type int.

# 1.4 HCL Example

The following example shows a complete HCL file. The C code generated by processing it with HCL2C is completely self-contained. It can be compiled and run using command line arguments for the input signals. More typically, HCL files define just the control part of a simulation model. The generated C code is then compiled and linked with other code to form the executable simulator. We show this example just to give a concrete example of HCL. The circuit is based on the MUX4 circuit shown in CS:APP2e Figure 4.14 and reproduced here:



```
1 ## Simple example of an HCL file.
2 ## This file can be converted to C using hcl2c, and then compiled.
3
4 ## In this example, we will generate the MUX4 circuit shown in
5 ## Section 4.2.4. It consists of a control block that generates
6 ## bit-level signals s1 and s0 from the input signal code,
7 ## and then uses these signals to control a 4-way multiplexor
8 ## with data inputs A, B, C, and D.
9
10 ## This code is embedded in a C program that reads
```

```
11 ## the values of code, A, B, C, and D from the command line
12 ## and then prints the circuit output
13
14 ## Information that is inserted verbatim into the C file
15 quote '#include <stdio.h>'
16 quote '#include <stdlib.h>'
17 quote 'int code_val, s0_val, s1_val;'
18 quote 'char **data names;'
20 ## Declarations of signals used in the HCL description and
21 ## the corresponding C expressions.
22 boolsig s0 's0 val'
23 boolsig s1 's1 val'
24 intsig code 'code val'
25 intsig A 'atoi(data names[0])'
26 intsig B 'atoi(data names[1])'
27 intsig C 'atoi(data names[2])'
28 intsig D 'atoi(data_names[3])'
29
30 ## HCL descriptions of the logic blocks
31 bool s1 = code in { 2, 3 };
32
33 bool s0 = code in { 1, 3 };
34
35 int Out4 = [
          !s1 && !s0 : A; # 00
          !s1
                 : B; # 01
37
                     : C; # 10
          !s0
38
                     : D; # 11
39
          1
40 ];
41
42 ## More information inserted verbatim into the C code to
43 ## compute the values and print the output
44 quote 'int main(int argc, char *argv[]) {'
45 quote ' data names = argv+2;'
46 quote ' code_val = atoi(argv[1]);'
47 quote ' s1 val = gen s1();'
48 quote ' s0 val = gen s0();'
49 quote ' printf("Out = %d\n", gen_Out4());'
50 quote ' return 0;'
51 quote '}'
```

This file defines Boolean signals s0 and s1 and integer signal code to be aliases for references to global variables s0\_val, s1\_val, and code\_val. It declares integer signals A, B, C, and D, where the corresponding C expressions apply the standard library function atoi to strings passed as command line arguments.

The definition of the block named s1 generates the following C code:

```
int gen_s1()
```

```
{
    return ((code_val) == 2 || (code_val) == 3);
}
```

As can be seen here, set membership testing is implemented as a series of comparisons, and that every reference to signal code is replaced by the C expression code\_val.

Note that there is no direct relation between the signal s1 declared on line 23 of the HCL file, and the block named s1 declared on line 31. One is an alias for a C expression, while the other generates a function named gen\_s1.

The quoted text at the end generates the following main function:

```
int main(int argc, char *argv[]) {
  data_names = argv+2;
  code_val = atoi(argv[1]);
  s1_val = gen_s1();
  s0_val = gen_s0();
  printf("Out = %d\n", gen_Out4());
  return 0;
}
```

The main function calls the functions gen\_s1, gen\_s0, and gen\_Out4 that were generated from the block definitions. We can also see how the C code must define the sequencing of block evaluations and the setting of the values used in the C expressions representing the different signal values.

# 2 SEQ

```
1 #/* $begin seq-all-hcl */
3 # HCL Description of Control for Single Cycle Y86 Processor SEQ
   Copyright (C) Randal E. Bryant, David R. O'Hallaron, 2010
C Include's. Don't alter these
10
11 quote '#include <stdio.h>'
12 quote '#include "isa.h"'
13 quote '#include "sim.h"'
14 quote 'int sim_main(int argc, char *argv[]);'
15 quote 'int gen pc(){return 0;}'
16 quote 'int main(int argc, char *argv[])'
17 quote ' {plusmode=0;return sim_main(argc,argv);}'
18
```

```
Declarations. Do not change/remove/delete any of these
22
23 ##### Symbolic representation of Y86 Instruction Codes ############
24 intsig INOP
                'I NOP'
25 intsig IHALT
                 'I HALT'
26 intsig IRRMOVL 'I RRMOVL'
27 intsig IIRMOVL 'I IRMOVL'
28 intsig IRMMOVL 'I RMMOVL'
29 intsig IMRMOVL 'I MRMOVL'
30 intsig IOPL
                 'I ALU'
31 intsig IJXX
                 'I JMP'
32 intsig ICALL
                 'I CALL'
33 intsig IRET
                 'I RET'
34 intsig IPUSHL
                 'I PUSHL'
35 intsig IPOPL 'I POPL'
36
                                                                   #####
37 ##### Symbolic represenations of Y86 function codes
38 intsig FNONE 'F NONE' # Default function code
40 ##### Symbolic representation of Y86 Registers referenced explicitly #####
                             # Stack Pointer
41 intsig RESP
               'REG ESP'
42 intsig RNONE
                 'REG NONE'
                                # Special value indicating "no register"
43
44 ##### ALU Functions referenced explicitly
                                                                   #####
45 intsig ALUADD 'A ADD' # ALU should add its arguments
                                                                   #####
47 ##### Possible instruction status values
48 intsig SAOK 'STAT_AOK'
                                       # Normal execution
49 intsig SADR
                 'STAT_ADR'
                                # Invalid memory address
50 intsig SINS
                 'STAT INS'
                              # Invalid instruction
                 'STAT HLT' # Halt instruction encountered
51 intsig SHLT
52
55 ##### Fetch stage inputs
                                       #####
56 intsig pc 'pc'
                                       # Program counter
57 ##### Fetch stage computations
                                      #####
58 intsig imem icode 'imem icode'
                                      # icode field from instruction memory
59 intsig imem_ifun 'imem_ifun'
                                      # ifun field from instruction memory
60 intsig icode
                   'icode'
                                      # Instruction control code
61 intsig ifun
                   'ifun'
                                      # Instruction function
                  'ra'
                                      # rA field from instruction
62 intsig rA
                                      # rB field from instruction
63 intsig rB
                   'rb'
64 intsig valC
                   'valc'
                                      # Constant from instruction
65 intsig valP
                   'valp'
                                      # Address of following instruction
66 boolsig imem_error 'imem_error'  # Error signal from instruction memory
67 boolsig instr_valid 'instr_valid'  # Is fetched instruction valid?
68
69 #### Decode stage computations
                                      #####
```

```
70 intsig valA
               'vala'
                                    # Value from register A port
71 intsig valB 'valb'
                                    # Value from register B port
72
73 ##### Execute stage computations
                                    #####
74 intsig valE 'vale'
                                    # Value computed by ALU
               'cond'
75 boolsig Cnd
                                     # Branch test
76
                                    #####
77 ##### Memory stage computations
78 intsig valM
               'valm'
                                    # Value read from memory
79 boolsig dmem_error 'dmem_error'
                                 # Error signal from data memory
80
81
83 # Control Signal Definitions.
85
86 ########### Fetch Stage
                            87
88 # Determine instruction code
89 int icode = [
       imem error: INOP;
         1: imem icode;
                             # Default: get from instruction memory
91
92 ];
93
94 # Determine instruction function
95 int ifun = [
         imem error: FNONE;
         1: imem ifun;
                              # Default: get from instruction memory
97
98 ];
99
100 bool instr valid = icode in
         { INOP, IHALT, IRRMOVL, IIRMOVL, IRMMOVL, IMRMOVL,
101
                IOPL, IJXX, ICALL, IRET, IPUSHL, IPOPL };
102
103
104 # Does fetched instruction require a regid byte?
105 bool need regids =
         icode in { IRRMOVL, IOPL, IPUSHL, IPOPL,
106
                     IIRMOVL, IRMMOVL, IMRMOVL );
107
108
109 # Does fetched instruction require a constant word?
110 bool need valC =
         icode in { IIRMOVL, IRMMOVL, IMRMOVL, IJXX, ICALL };
112
113 ########### Decode Stage
                               114
115 ## What register should be used as the A source?
116 int srcA = [
         icode in { IRRMOVL, IRMMOVL, IOPL, IPUSHL } : rA;
117
         icode in { IPOPL, IRET } : RESP;
118
         1 : RNONE; # Don't need register
119
```

```
120 ];
121
122 ## What register should be used as the B source?
123 int srcB = [
           icode in { IOPL, IRMMOVL, IMRMOVL } : rB;
           icode in { IPUSHL, IPOPL, ICALL, IRET } : RESP;
           1 : RNONE; # Don't need register
126
127 ];
128
129 ## What register should be used as the E destination?
130 int dstE = [
           icode in { IRRMOVL } && Cnd : rB;
131
           icode in { IIRMOVL, IOPL} : rB;
132
133
           icode in { IPUSHL, IPOPL, ICALL, IRET } : RESP;
           1 : RNONE; # Don't write any register
134
135 ];
136
137 ## What register should be used as the M destination?
138 int dstM = [
           icode in { IMRMOVL, IPOPL } : rA;
139
           1 : RNONE; # Don't write any register
140
141 ];
142
143 ########### Execute Stage
                                   145 ## Select input A to ALU
146 int aluA = [
           icode in { IRRMOVL, IOPL } : valA;
147
           icode in { IIRMOVL, IRMMOVL, IMRMOVL } : valC;
148
           icode in { ICALL, IPUSHL } : -4;
149
           icode in { IRET, IPOPL } : 4;
150
           # Other instructions don't need ALU
151
152 ];
153
154 ## Select input B to ALU
155 int aluB = [
           icode in { IRMMOVL, IMRMOVL, IOPL, ICALL,
156
                         IPUSHL, IRET, IPOPL } : valB;
157
           icode in { IRRMOVL, IIRMOVL } : 0;
158
           # Other instructions don't need ALU
160 ];
161
162 ## Set the ALU function
163 int alufun = [
164
           icode == IOPL : ifun;
165
           1 : ALUADD;
166 ];
168 ## Should the condition codes be updated?
169 bool set cc = icode in { IOPL };
```

```
170
171 ########### Memory Stage
                                 172
173 ## Set read control signal
174 bool mem_read = icode in { IMRMOVL, IPOPL, IRET };
176 ## Set write control signal
177 bool mem write = icode in { IRMMOVL, IPUSHL, ICALL };
179 ## Select memory address
180 int mem_addr = [
          icode in { IRMMOVL, IPUSHL, ICALL, IMRMOVL } : valE;
          icode in { IPOPL, IRET } : valA;
182
183
          # Other instructions don't need address
184 ];
185
186 ## Select memory input data
187 int mem_data = [
188 # Value from register
          icode in { IRMMOVL, IPUSHL } : valA;
189
          # Return PC
190
          icode == ICALL : valP;
191
          # Default: Don't write anything
192
193 ];
195 ## Determine instruction status
196 int Stat = [
          imem_error || dmem_error : SADR;
197
          !instr_valid: SINS;
198
          icode == IHALT : SHLT;
199
200
          1 : SAOK;
201 ];
202
205 ## What address should instruction be fetched at
206
207 int new pc = [
          # Call. Use instruction constant
208
          icode == ICALL : valC;
          # Taken branch. Use instruction constant
210
          icode == IJXX && Cnd : valC;
211
          # Completion of RET instruction. Use value from stack
212
          icode == IRET : valM;
213
          # Default: Use incremented PC
214
215
          1 : valP;
216 ];
217 #/* $end seq-all-hcl */
```

# 3 PIPE

```
1 #/* $begin pipe-all-hcl */
HCL Description of Control for Pipelined Y86 Processor
     Copyright (C) Randal E. Bryant, David R. O'Hallaron, 2010
8 # C Include's. Don't alter these
10
11 quote '#include <stdio.h>'
12 quote '#include "isa.h"'
13 quote '#include "pipeline.h"'
14 quote '#include "stages.h"'
15 quote '#include "sim.h"'
16 quote 'int sim main(int argc, char *argv[]);'
17 quote 'int main(int argc, char *argv[]){return sim_main(argc,argv);}'
Declarations. Do not change/remove/delete any of these
23 ##### Symbolic representation of Y86 Instruction Codes #############
24 intsig INOP
             'I NOP'
25 intsig IHALT
             'I HALT'
26 intsig IRRMOVL 'I RRMOVL'
27 intsig IIRMOVL 'I IRMOVL'
28 intsig IRMMOVL
             'I RMMOVL'
29 intsig IMRMOVL 'I MRMOVL'
30 intsig IOPL
             'I ALU'
31 intsig IJXX
             'I JMP'
32 intsig ICALL
             'I CALL'
33 intsig IRET
             'I RET'
34 intsig IPUSHL
             'I PUSHL'
             'I POPL'
35 intsig IPOPL
36
37 ##### Symbolic represenations of Y86 function codes
                                               #####
                       # Default function code
38 intsig FNONE
           'F NONE'
40 ##### Symbolic representation of Y86 Registers referenced
                                               #####
41 intsig RESP
            'REG ESP'
                            # Stack Pointer
             'REG_NONE'
                            # Special value indicating "no register"
42 intsig RNONE
43
'A_ADD'
45 intsig ALUADD
                            # ALU should add its arguments
46
47 ##### Possible instruction status values
                                               #####
```

```
'STAT_BUB' # Bubble in stage
'STAT_AOK' # Normal execution
'STAT_ADR' # Invalid memory address
'STAT_INS' # Invalid instruction
48 intsig SBUB
49 intsig SAOK
50 intsig SADR
51 intsig SINS
                                # Halt instruction encountered
52 intsig SHLT
                  'STAT_HLT'
54 ##### Signals that can be referenced by control logic ##############
57
58 intsig F predPC 'pc curr->pc' # Predicted value of PC
61
62 intsig imem icode 'imem icode'
                                      # icode field from instruction memory
63 intsig imem ifun 'imem ifun'
                                      # ifun field from instruction memory
64 intsig f icode 'if id next->icode' # (Possibly modified) instruction code
65 intsig f_ifun 'if_id_next->ifun' # Fetched instruction function
                                     # Constant data of fetched instruction
66 intsig f valC 'if id next->valc'
67 intsig f_valP 'if_id_next->valp' # Address of following instruction
                                     # Error signal from instruction memory
68 boolsig imem error 'imem error'
69 boolsig instr_valid 'instr_valid' # Is fetched instruction valid?
72 intsig D icode 'if id curr->icode' # Instruction code
73 intsig D_rA 'if_id_curr->ra'  # rA field from instruction
74 intsig D_rB 'if_id_curr->rb'  # rB field from instruction
75 intsig D_valP 'if_id_curr->valp' # Incremented PC
76
78
79 intsig d srcA 'id ex next->srca' # srcA from decoded instruction
80 intsig d_srcB 'id_ex_next->srcb' # srcB from decoded instruction
81 intsig d_rvalA 'd_regvala'  # valA read from register file
82 intsig d rvalB 'd regvalb'
                                      # valB read from register file
85 intsig E icode 'id ex curr->icode' # Instruction code
86 intsig E_ifun 'id_ex_curr->ifun' # Instruction function
87 intsig E_valC 'id_ex_curr->valc' # Constant data
88 intsig E_srcA 'id_ex_curr->srca' # Source A register ID
89 intsig E_valA 'id_ex_curr->vala' # Source A value
90 intsig E_srcB 'id_ex_curr->srcb'  # Source B register ID
91 intsig E_valB 'id_ex_curr->valb'  # Source B value
92 intsig E_dstE 'id_ex_curr->deste'  # Destination E register ID
93 intsig E_dstM 'id_ex_curr->destm'  # Destination M register ID
94
96 intsig e valE 'ex mem next->vale' # valE generated by ALU
97 boolsig e Cnd 'ex mem next->takebranch' # Does condition hold?
```

```
98 intsig e dstE 'ex mem next->deste'
                                    # dstE (possibly modified to be RNONE)
100 ##### Pipeline Register M
                                        ##############################
101 intsiq M stat 'ex mem curr->status'
                                    # Instruction status
102 intsig M_icode 'ex_mem_curr->icode'
                                    # Instruction code
103 intsig M_ifun 'ex_mem_curr->ifun'
                                     # Instruction function
                                    # Source A value
104 intsig M_valA 'ex_mem_curr->vala'
105 intsig M dstE 'ex mem curr->deste'
                                    # Destination E register ID
106 intsig M valE 'ex mem curr->vale'
                                    # ALU E value
                                 # Destination M register ID
107 intsig M_dstM 'ex_mem_curr->destm'
108 boolsig M Cnd 'ex mem curr->takebranch' # Condition flag
109 boolsig dmem_error 'dmem_error'
                                     # Error signal from instruction memory
110
112 intsig m valM 'mem_wb_next->valm'
                                     # valM generated by memory
113 intsig m stat 'mem_wb_next->status'
                                     # stat (possibly modified to be SADR)
114
116 intsig W stat 'mem wb curr->status' # Instruction status
117 intsig W icode 'mem_wb_curr->icode'
                                    # Instruction code
118 intsig W_dstE 'mem_wb_curr->deste'
                                    # Destination E register ID
                                    # ALU E value
intsig W_valE 'mem_wb_curr->vale'
120 intsig W dstM 'mem wb curr->destm'
                                    # Destination M register ID
121 intsig W_valM 'mem_wb_curr->valm'
                                    # Memory M value
Control Signal Definitions.
126
                               ######################################
127 ########### Fetch Stage
128
129 ## What address should instruction be fetched at
130 int f pc = [
131
          # Mispredicted branch. Fetch at incremented PC
132
         M icode == IJXX && !M Cnd : M valA;
         # Completion of RET instruction.
133
         W icode == IRET : W valM;
          # Default: Use predicted value of PC
          1 : F predPC;
136
137 ];
139 ## Determine icode of fetched instruction
140 int f icode = [
         imem error : INOP;
141
142
          1: imem icode;
143 ];
144
145 # Determine ifun
146 int f ifun = [
         imem error : FNONE;
147
```

```
1: imem ifun;
148
149 ];
150
151 # Is instruction valid?
152 bool instr_valid = f_icode in
           { INOP, IHALT, IRRMOVL, IIRMOVL, IRMMOVL, IMRMOVL,
             IOPL, IJXX, ICALL, IRET, IPUSHL, IPOPL };
154
155
156 # Determine status code for fetched instruction
157 int f_stat = [
           imem error: SADR;
158
           !instr valid : SINS;
159
           f icode == IHALT : SHLT;
160
161
           1 : SAOK;
162 ];
163
164 # Does fetched instruction require a regid byte?
165 bool need regids =
           f icode in { IRRMOVL, IOPL, IPUSHL, IPOPL,
                        IIRMOVL, IRMMOVL, IMRMOVL };
167
168
169 # Does fetched instruction require a constant word?
170 bool need valC =
           f_icode in { IIRMOVL, IRMMOVL, IMRMOVL, IJXX, ICALL };
171
173 # Predict next value of PC
174 int f predPC = [
           f_icode in { IJXX, ICALL } : f_valC;
175
           1 : f_valP;
176
177 ];
178
180
181
182 ## What register should be used as the A source?
183 int d srcA = [
           D icode in { IRRMOVL, IRMMOVL, IOPL, IPUSHL } : D rA;
           D icode in { IPOPL, IRET } : RESP;
           1 : RNONE; # Don't need register
186
187 ];
188
189 ## What register should be used as the B source?
190 int d srcB = [
           D_icode in { IOPL, IRMMOVL, IMRMOVL } : D_rB;
191
192
           D_icode in { IPUSHL, IPOPL, ICALL, IRET } : RESP;
           1 : RNONE; # Don't need register
193
194 ];
196 ## What register should be used as the E destination?
197 int d dstE = [
```

```
D icode in { IRRMOVL, IIRMOVL, IOPL} : D rB;
198
           D icode in { IPUSHL, IPOPL, ICALL, IRET } : RESP;
199
200
           1 : RNONE; # Don't write any register
201 ];
202
203 ## What register should be used as the M destination?
204 int d_dstM = [
           D icode in { IMRMOVL, IPOPL } : D rA;
           1 : RNONE; # Don't write any register
206
207 ];
208
209 ## What should be the A value?
210 ## Forward into decode stage for valA
211 int d valA = [
           D icode in { ICALL, IJXX } : D valP; # Use incremented PC
212
           d srcA == e dstE : e valE;  # Forward valE from execute
213
           d srcA == M dstM : m valM;
                                       # Forward valM from memory
214
                                      # Forward valE from memory
           d srcA == M dstE : M valE;
215
216
           d srcA == W dstM : W valM;
                                      # Forward valM from write back
           d srcA == W dstE : W valE;
                                      # Forward valE from write back
217
           1 : d rvalA; # Use value read from register file
218
219 ];
220
221 int d_valB = [
           d srcB == e dstE : e valE;
                                        # Forward valE from execute
222
           d srcB == M dstM : m valM;
                                        # Forward valM from memory
223
           d srcB == M dstE : M valE;
                                      # Forward valE from memory
224
           d srcB == W dstM : W valM;
                                       # Forward valM from write back
225
           d srcB == W dstE : W valE;
226
                                        # Forward valE from write back
           1 : d rvalB; # Use value read from register file
227
228 ];
229
231
232 ## Select input A to ALU
233 int aluA = [
           E icode in { IRRMOVL, IOPL } : E valA;
           E icode in { IIRMOVL, IRMMOVL, IMRMOVL } : E valC;
           E icode in { ICALL, IPUSHL } : -4;
236
           E_icode in { IRET, IPOPL } : 4;
           # Other instructions don't need ALU
238
239 ];
240
241 ## Select input B to ALU
242 int aluB = [
243
           E_icode in { IRMMOVL, IMRMOVL, IOPL, ICALL,
                        IPUSHL, IRET, IPOPL } : E_valB;
244
           E icode in { IRRMOVL, IIRMOVL } : 0;
245
           # Other instructions don't need ALU
246
247 ];
```

```
248
249 ## Set the ALU function
250 int alufun = [
           E icode == IOPL : E ifun;
           1 : ALUADD;
252
253 ];
254
255 ## Should the condition codes be updated?
256 bool set cc = E icode == IOPL &&
           # State changes only during normal operation
258
           !m_stat in { SADR, SINS, SHLT } && !W_stat in { SADR, SINS, SHLT };
259
260 ## Generate valA in execute stage
261 int e valA = E valA;  # Pass valA through stage
262
263 ## Set dstE to RNONE in event of not-taken conditional move
264 int e dstE = [
265
           E icode == IRRMOVL && !e Cnd : RNONE;
266
           1 : E dstE;
267 ];
268
271 ## Select memory address
272 int mem_addr = [
           M_icode in { IRMMOVL, IPUSHL, ICALL, IMRMOVL } : M valE;
273
           M icode in { IPOPL, IRET } : M valA;
274
           # Other instructions don't need address
275
276 ];
277
278 ## Set read control signal
279 bool mem read = M icode in { IMRMOVL, IPOPL, IRET };
280
281 ## Set write control signal
282 bool mem_write = M_icode in { IRMMOVL, IPUSHL, ICALL };
283
284 #/* $begin pipe-m stat-hcl */
285 ## Update the status
286 int m stat = [
287
           dmem error : SADR;
           1 : M_stat;
288
289 ];
290 #/* $end pipe-m_stat-hcl */
292 ## Set E port register ID
293 int w_dstE = W_dstE;
294
295 ## Set E port value
296 int w valE = W valE;
297
```

```
298 ## Set M port register ID
299 int w dstM = W dstM;
300
301 ## Set M port value
302 int w_valM = W_valM;
304 ## Update processor status
305 int Stat = [
           W stat == SBUB : SAOK;
306
           1 : W stat;
307
308 ];
309
312 # Should I stall or inject a bubble into Pipeline Register F?
313 # At most one of these can be true.
314 bool F bubble = 0;
315 bool F_stall =
316
           # Conditions for a load/use hazard
           E icode in { IMRMOVL, IPOPL } &&
317
           E dstM in { d_srcA, d_srcB } ||
318
           # Stalling at fetch while ret passes through pipeline
319
           IRET in { D_icode, E_icode, M_icode };
320
321
322 # Should I stall or inject a bubble into Pipeline Register D?
323 # At most one of these can be true.
324 bool D stall =
           # Conditions for a load/use hazard
325
           E_icode in { IMRMOVL, IPOPL } &&
326
            E_dstM in { d_srcA, d_srcB };
327
328
329 bool D bubble =
           # Mispredicted branch
330
331
           (E icode == IJXX && !e Cnd)
332
           # Stalling at fetch while ret passes through pipeline
           # but not condition for a load/use hazard
333
           !(E icode in { IMRMOVL, IPOPL } && E dstM in { d srcA, d srcB }) &&
334
335
             IRET in { D icode, E icode, M icode };
337 # Should I stall or inject a bubble into Pipeline Register E?
338 # At most one of these can be true.
339 bool E stall = 0;
340 bool E bubble =
           # Mispredicted branch
341
342
           (E icode == IJXX && !e Cnd) ||
343
           # Conditions for a load/use hazard
           E_icode in { IMRMOVL, IPOPL } &&
344
            E dstM in { d srcA, d srcB};
345
346
347 # Should I stall or inject a bubble into Pipeline Register M?
```

```
348 # At most one of these can be true.
349 bool M_stall = 0;
350 # Start injecting bubbles as soon as exception passes through memory stage
351 bool M_bubble = m_stat in { SADR, SINS, SHLT } || W_stat in { SADR, SINS, SHLT };
352
353 # Should I stall or inject a bubble into Pipeline Register W?
354 bool W_stall = W_stat in { SADR, SINS, SHLT };
355 bool W_bubble = 0;
356 #/* $end pipe-all-hcl */
```