

## EXPERIMENT 7

**Experiment No:** 7

**Date:** 10/04/2021

**Aim:** Implementation of Single Source Shortest Path Algo (Dijkstra's Algo) and estimate its step count

**Theory:**

### Dijkstra's Shortest Path Algorithm

- Given a graph and a source vertex in the graph, find shortest paths from source to all vertices in the given graph.
- Dijkstra's algorithm is very similar to Prim's algorithm for minimum spanning tree.
- Like Prim's MST, we generate a SPT (shortest path tree) with given source as root.
- We maintain two sets, one set contains vertices included in shortest path tree, other set includes vertices not yet included in shortest path tree.
- At every step of the algorithm, we find a vertex which is in the other set (set of not yet included) and has a minimum distance from the source.

### Time Complexity

- The time complexity of the above code/algorithm looks  $O(V^2)$  as there are two nested while loops.
- If we take a closer look, we can observe that the statements in inner loop are executed  $O(V+E)$  times (similar to BFS).
- The inner loop has decreaseKey() operation which takes  $O(\log V)$  time.

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- So overall time complexity is  $O(E+V)*O(\log V)$  which is

$$O((E+V)*\log V) = O(E\log V)$$

- Note that the above code uses Binary Heap for Priority Queue implementation.
- Time complexity can be reduced to  $O(E + V\log V)$  using Fibonacci Heap.
- The reason is, Fibonacci Heap takes  $O(1)$  time for decrease-key operation while Binary Heap takes  $O(\log n)$  time.

```
Begin Algorithm Dijkstra (G, s)
1  For each vertex  $v \in V$ 
2     $d[v] \leftarrow \infty$  // an estimate of the min-weight path from s to v
3  End For
4   $d[s] \leftarrow 0$ 
5   $S \leftarrow \emptyset$  // set of nodes for which we know the min-weight path from s
6   $Q \leftarrow V$  // set of nodes for which we know estimate of min-weight path from s
7  While  $Q \neq \emptyset$ 
8     $u \leftarrow \text{EXTRACT-MIN}(Q)$ 
9     $S \leftarrow S \cup \{u\}$ 
10   For each vertex  $v$  such that  $(u, v) \in E$ 
11     If  $v \in Q$  and  $d[v] > d[u] + w(u, v)$  then
12        $d[v] \leftarrow d[u] + w(u, v)$ 
13       Predecessor( $v$ ) =  $u$ 
14   End For
15 End While
16 End Dijkstra
```

**Annotations:**

- Lines 1-3:  $O(V)$  time
- Line 4:  $O(V)$  time to Construct a Min-heap
- Line 7: done  $|V|$  times =  $O(V)$  time
- Line 8: Each extraction takes  $O(\log V)$  time
- Line 10: done  $O(E)$  times totally
- Line 11: It takes  $O(\log V)$  time when done once

**Overall Complexity:**  $O(V) + O(V) + O(V\log V) + O(E\log V)$   
Since  $|V| = \Omega(|E|)$ , the  $V\log V$  term is dominated by the  $E\log V$  term. Hence, overall complexity =  $O(|E| \log |V|)$

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### Algorithm

```
Algorithm ShortestPaths(v, cost, dist, n)

// dist[j],  $1 \leq j \leq n$ , is set to the length of the shortest
// path from vertex v to vertex j in a digraph G with n
// vertices. dist[v] is set to zero. G is represented by its
// cost adjacency matrix cost[1: n, 1:n].

{
    for i:=1 to n do
    { // Initialize S.
        S[i]:= false; dist[i]:= cost[v, i];
    }

    S[v]:= true; dist[v] := 0.0; // Put v in S.

    for num=2 to n - 1 do
    {
        // Determine n - 1 paths from v.
        Choose u from among those vertices not
        in S such that dist[u] is minimum;

        S[u]:= true; // Put u in S.

        for (each w adjacent to u with S[w] = false) do
```

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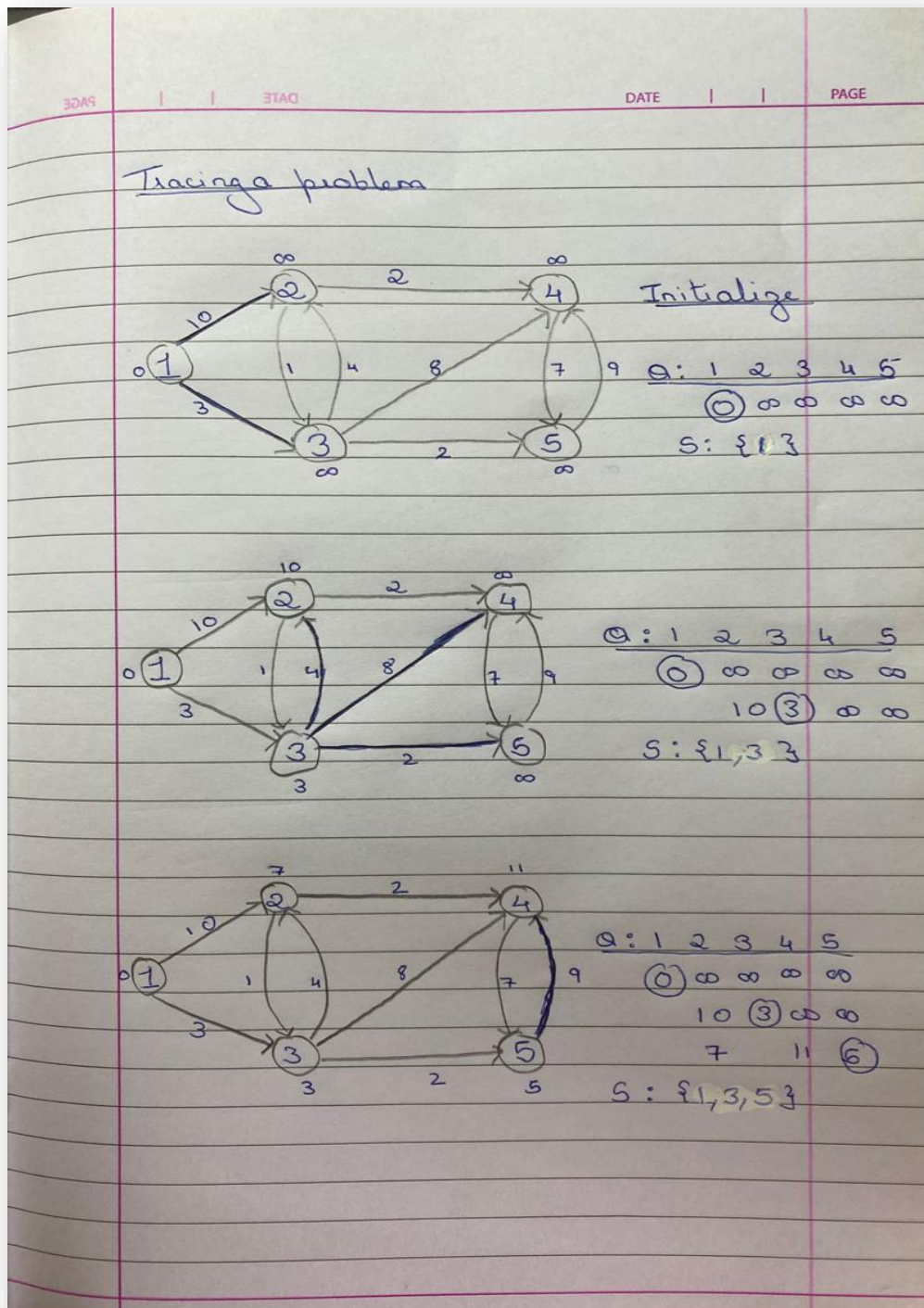
```
// Update distances.  
  
if (dist[w]> dist[u] + cost[u, w])) then  
  
    dist[w]: dist[u] + cost[u, w];  
  
}  
  
}
```

### **Algorithm writing**

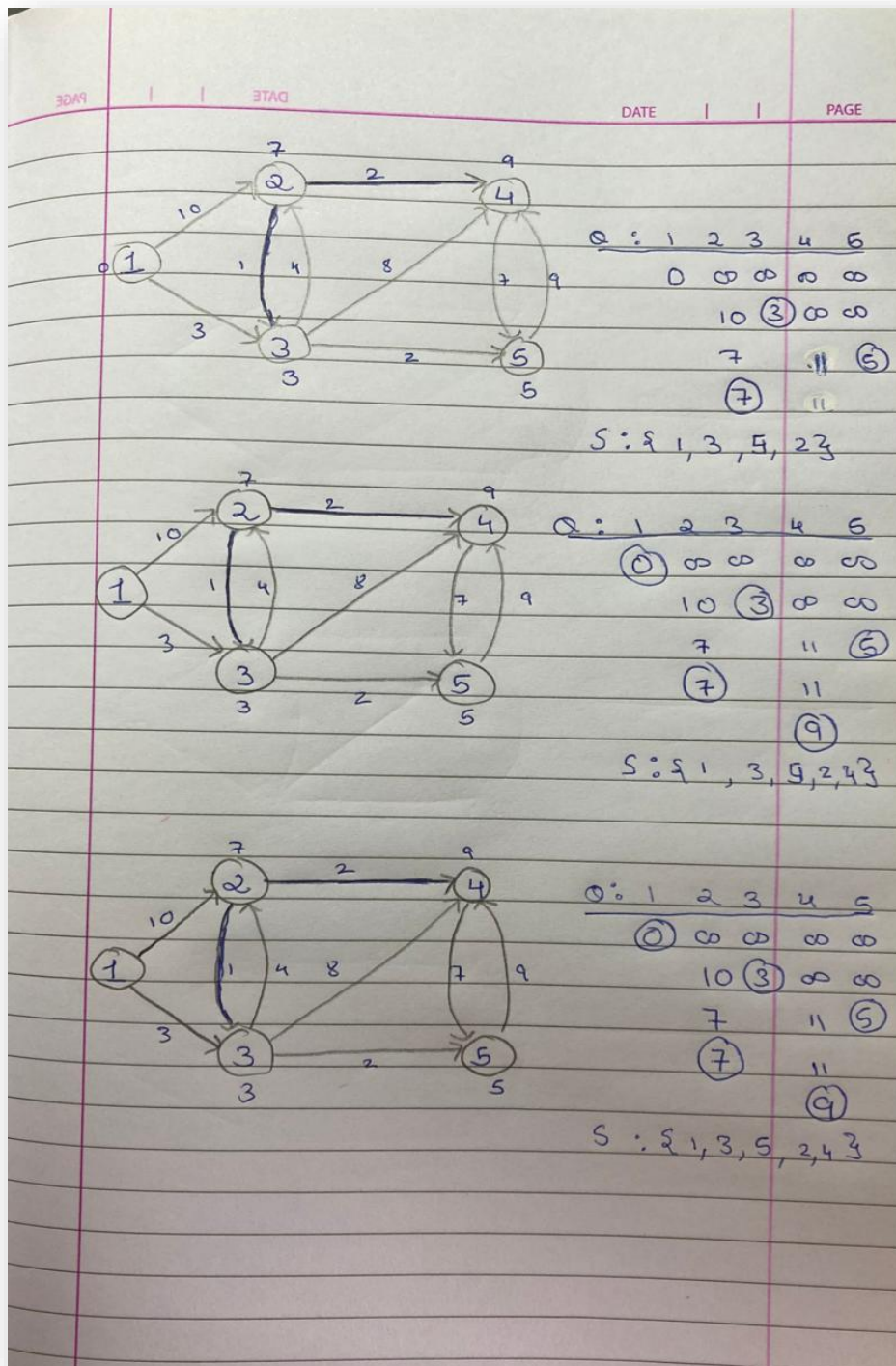
1. Mark your selected initial node with a current distance of 0 and the rest with infinity.
2. Set the non-visited node with the smallest current distance as the current node C.
3. For each neighbour N of your current node C:
  - add the current distance of C with the weight of the edge connecting C-N.
  - If it's smaller than the current distance of N, set it as the new current distance of N.
4. Mark the current node C as visited.
5. If there are non-visited nodes, go to step 2.

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### Tracing with Example



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### Program

```
#include<iostream>

using namespace std;

#define V 6

int stepcount=0;

int minDistance(int dist[], bool sptSet[])
{
    int min = INT_MAX;stepcount++;

    int min_index;

    for (int v = 0; v < V; v++)
    {
        stepcount++;

        stepcount++;

        if (sptSet[v] == false && dist[v] <= min)
        {
            min = dist[v], min_index = v;stepcount++;
        }
    }
}
```

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```
        stepcount++;

        return min_index;
    }

    void printSolution(int dist[])
    {
        cout<<"Vertex \t\t Distance from Source"<<endl;stepcount++;

        for (int i = 0; i < V; i++)
        {
            stepcount++;

            cout<<i<<"\t\t"<<dist[i]<<endl;stepcount++;
        }

    }

    void dijkstra(int graph[V][V], int src)
    {
        int dist[V];

        bool sptSet[V];
```



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```
for (int i = 0; i < V; i++)  
{  
    stepcount++;  
    dist[i] = INT_MAX, sptSet[i] = false; stepcount++;  
}  
  
dist[src] = 0; stepcount++;  
  
for (int count = 0; count < V - 1; count++)  
{  
    stepcount++;  
    int u = minDistance(dist, sptSet); stepcount++;  
    sptSet[u] = true; stepcount++;  
    for (int v = 0; v < V; v++)  
    {  
        stepcount++;  
        stepcount++;  
        if (!sptSet[v] && graph[u][v] && dist[u] !=  
INT_MAX
```

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```
                && dist[u] + graph[u][v] < dist[v])  
                {  
                    dist[v] = dist[u] +  
graph[u][v];stepcount++;  
                }  
            }  
        }  
        stepcount++;  
        printSolution(dist);  
    }  
  
int main()  
{  
    int graph[V][V];  
    cout<<"Enter the vertices for a graph with 6  
vetices:";stepcount++;  
    for (int i=0;i<V;i++)  
    {  
        stepcount++;  
        for(int j=0;j<V;j++)
```

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```
{  
  
    stepcount++;  
  
        cin>>graph[i][j];stepcount++;  
  
    }  
  
}  
  
stepcount++;  
  
    dijkstra(graph, 0);  
  
    cout<<"*****"<<endl;  
  
    cout<<"Stepcount:"<<stepcount<<endl;  
  
    cout<<"*****"<<endl;  
  
    return 0;  
  
}
```

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### Output

```
C:\Users\Vedant\OneDrive\Desktop\GEC\MADF\PRA...
Enter the vertices for a graph with 6 vetices:
8 4 6 2 5 7
7 5 8 4 2 1
3 5 7 6 1 4
8 5 1 3 4 9
7 8 5 2 1 7
9 4 7 2 5 6
Vertex          Distance from Source
0                0
1                4
2                3
3                2
4                4
5                5
*****
Stepcount:268
*****

-----
Process exited after 36.81 seconds with return value 0
Press any key to continue . . .
```

### Conclusion

- Detailed concept of Single Source Shortest Path Algo (Dijkstra's Algo) was studied successfully.
- Program using Dijkstra's Algorithm was executed successfully.
- The step count for the Dijkstra's Algorithm was obtained.