

# EE3220 System-on-Chip Design

## Tutorial Note 4 – Operating System Scheduling Algorithms

# I. Introduction

## Why do we need scheduling?

A typical process involves both I/O time and CPU time. In a programming system like MS-DOS, time spent waiting for I/O is wasted and CPU is free during this time. In multi-programming systems, one process can use CPU while another is waiting for I/O. This is possible only with process scheduling.

Generally, scheduling algorithms can be divided into non-preemptive and preemptive algorithms:

- **Non-preemptive** algorithms are designed so that once a process enters the running state, it cannot be preempted until it completes its allotted time,
- **Preemptive** scheduling is based on priority where a scheduler may preempt a low priority running process anytime when a high priority process enters a ready state.
- Both have advantage and disadvantage, we need to select according to our applications

# I. Introduction

Before introducing the algorithms. There are some important concepts in this tutorial.

- **Arrival time:** Time at which the process arrives in the ready queue.
- **Completion Time:** Time at which process completes its execution.
- **Burst Time:** Time required by a process for CPU execution. (Or named as execute time)
- **Turn Around Time:** Time Difference between completion time and arrival time. (equals to Completion Time – Arrival Time)
- **Service time:** Time at which the queue begins the process
- **Wait time:** equals to Turn Around Time – Burst time. (Or named as wait time)

# I. Introduction

For the objectives of selecting process scheduling algorithms:

- Max CPU utilization [Keep CPU as busy as possible]
- Fair allocation of CPU.
- Min turn around time [Time taken by a process to finish execution]
- Min waiting time [Time a process waits in ready queue]
- Max throughput [Number of processes that complete their execution per time unit]

# I. Introduction

Based on the objectives, in this tutorial, we mainly introduce 6 popular process scheduling algorithms to be assigned to the CPU.

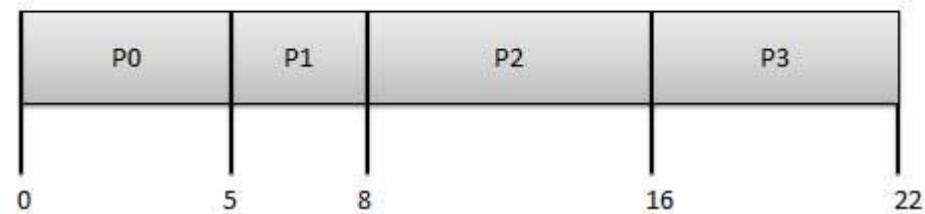
- First-Come, First-Served (FCFS) Scheduling
- Shortest-Job-First (SJF) Scheduling
- Shortest Remaining Time
- Fixed Priority Scheduling
- Round Robin(RR) Scheduling
- Multiple-Level Queues Scheduling

## 2.1 First-Come, First-Served (FCFS) Scheduling

For this algorithm,

- Jobs are executed on first come, first serve basis.
- It is a **non-preemptive** algorithm.
- Easy to understand and implement.
- Poor in performance as average wait time is high

Process	Arrival Time	Burst Time	Service Time	Wait Time
P0	0	5	0	0
P1	1	3	5	4
P2	2	8	8	6
P3	3	6	16	13



Average Wait Time:  $(0+4+6+13) / 4 = 5.75$

## 2.2 Shortest-Job-First (SJF) Scheduling

- This is a **non-preemptive** scheduling algorithm.
- Best approach to minimize waiting time.
- Easy to implement in Batch systems where required CPU time is known in advance.
- Impossible to implement in interactive systems where required CPU time is not known.
- The processor should know in advance how much time process will take.

Process	Arrival Time	Burst Time	Service Time	Wait Time
P0	0	5	0	0
P1	1	3	5	4
P2	2	8	14	12
P3	3	6	8	5



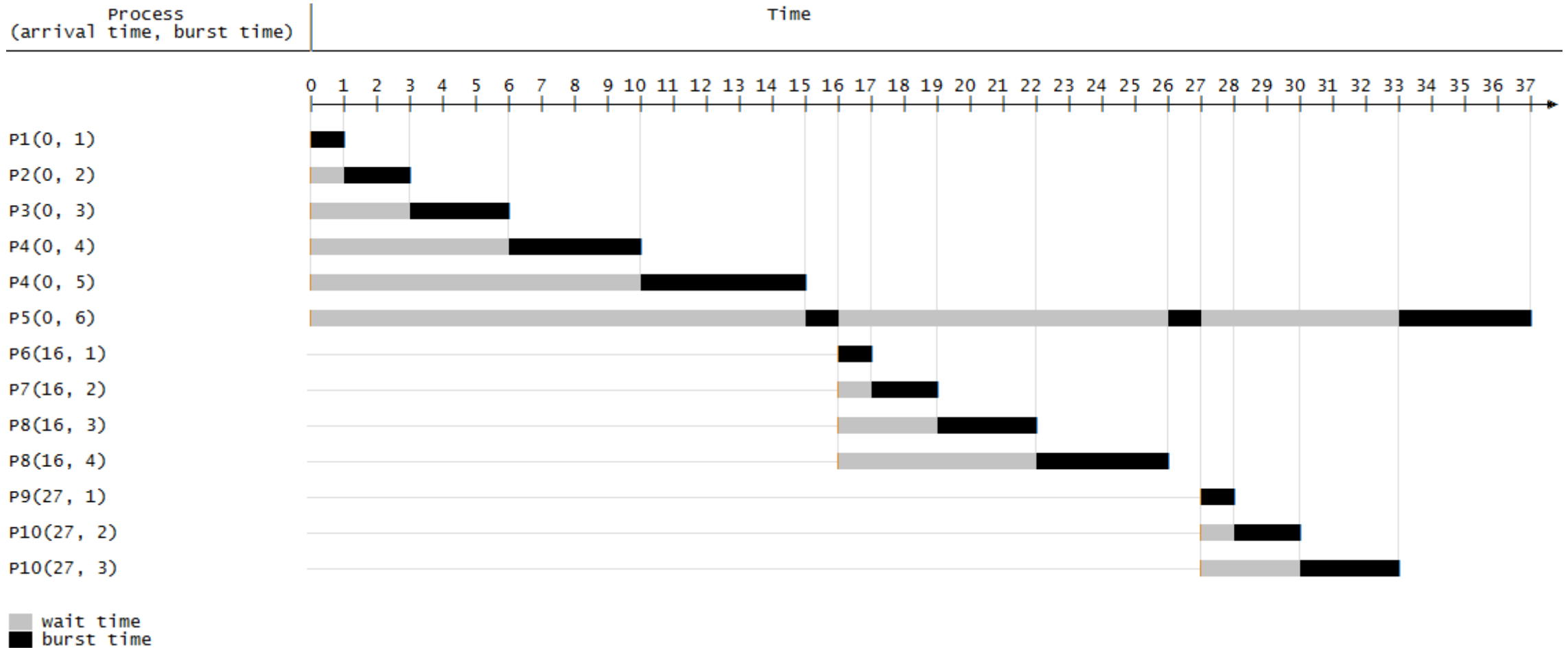
Average Wait Time:  $(0 + 4 + 12 + 5)/4 = 21 / 4 = 5.25$

## 2.3 Shortest Remaining Time (SRT) Algorithm

- Shortest remaining time (SRT) is the **preemptive** version of the SJF algorithm.
- The processor is allocated to the job closest to completion but it can be preempted by a newer arrived job with shorter time to completion.
- Impossible to implement in interactive systems where required CPU time is not known.
- It is rarely used outside of specialized environments
- It is often used in batch environments where short jobs need to give preference.



## 2.3 Shortest Remaining Time (SRT) Algorithm



## 2.3 Shortest Remaining Time (SRT) Algorithm

- **Questions:** Please finish the table, draw the process figure following the format in page 9 and calculate average waiting time based on following data.

Process	Arrival Time	Burst Time	Service Time	Wait Time
P0	0	8		
P1	1	3		
P2	2	6		
P3	3	5		

## 2.4 Fixed Priority Based Scheduling Algorithm

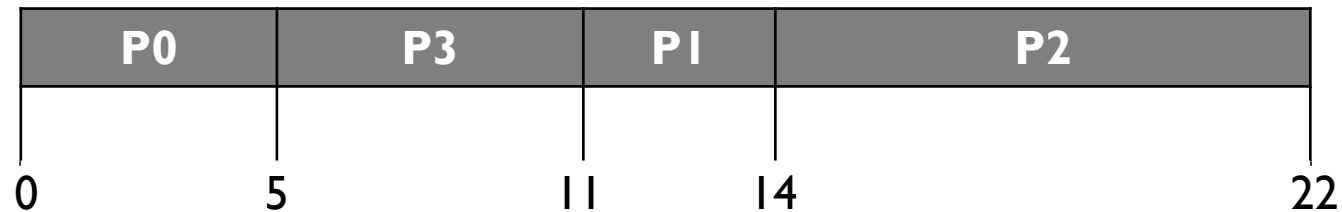
- Priority scheduling is a **non-preemptive** algorithm and one of the most common scheduling algorithms in batch systems.
- Each process is assigned a fixed priority. Process with highest priority is to be executed first and so on.
- Processes with same priority are executed on **first come first served** basis.
- Priority can be decided based on memory requirements, time requirements or any other resource requirement

Process	Arrival Time	Burst Time	Priority	Service Time	Wait Time
P0	0	5	1	0	0
P1	1	3	2	11	10
P2	2	8	1	14	12
P3	3	6	3	5	2

Given: Table of processes, and their Arrival time, Execution time, and priority. Here we are considering 1 is the lowest priority

## 2.4 Fixed Priority Based Scheduling Algorithm

Process	Arrival Time	Burst Time	Priority	Service Time	Wait Time
P0	0	5	1	0	0
P1	1	3	2	11	10
P2	2	8	1	14	12
P3	3	6	3	5	2



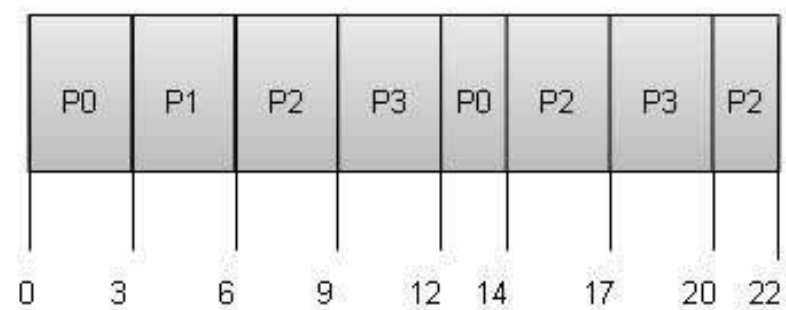
Average Wait Time:  $(0 + 10 + 12 + 2)/4 = 24 / 4 = 6$

# 2.5 Round Robin Scheduling Algorithm

- Round Robin is the **preemptive** process scheduling algorithm.
- Each process is provided a fix time to execute, it is called a **quantum**.
- Once a process is executed for a given time period, it is **preempted** and other process executes for a given time period.
- Context switching is used to save states of preempted processes.

Process	Arrival Time	Burst Time	Completion Time	Turn Around Time	Wait Time
P0	0	5	14	14	9
P1	1	3	6	5	2
P2	2	8	22	20	12
P3	3	6	20	17	11

Quantum = 3



Average Wait Time:  $(9+2+12+11) / 4 = 8.5$

## 2.6 Multiple-Level Queues Scheduling

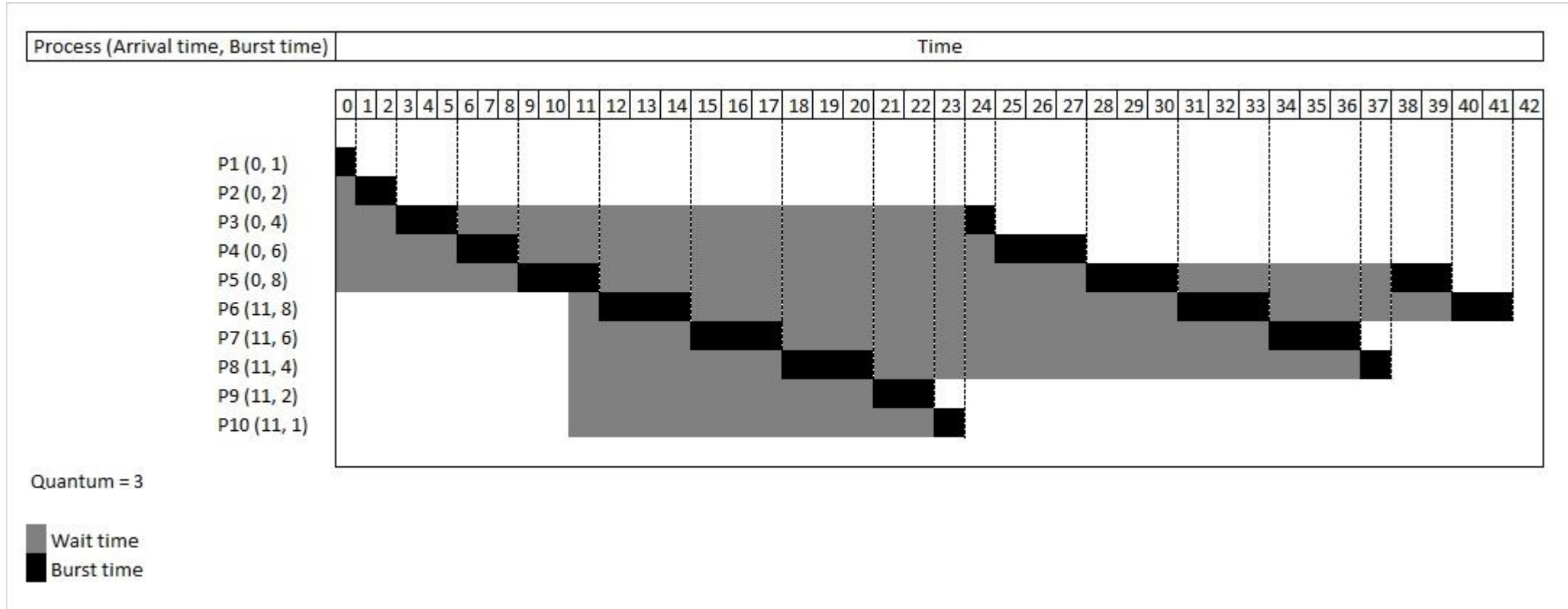
Multiple-level queues are not an independent scheduling algorithm. They make use of other existing algorithms to group and schedule jobs with common characteristics.

- Multiple queues are maintained for processes with common characteristics.
- Each queue can have its own scheduling algorithms.
- Priorities are assigned to each queue.
- For example, CPU-bound jobs can be scheduled in one queue and all I/O-bound jobs in another queue. The Process Scheduler then alternately selects jobs from each queue and assigns them to the CPU based on the algorithm assigned to the queue

### 3. Conclusion

- Some features of algorithms:
  - FCFS can cause long waiting times, especially when the first job takes too much CPU time.
  - Both SJF and Shortest Remaining time first algorithms may cause starvation. Consider a situation when the long process is there in the ready queue and shorter processes keep coming.
  - If time quantum for Round Robin scheduling is very large, then it behaves same as FCFS scheduling.
  - SJF is optimal in terms of average waiting time for a given set of processes, i.e., average waiting time is minimum with this scheduling, but problems are, how to know/predict the time of next job.
- Besides, these are also other useful algorithms can be used according to our applications. Please learn the features of each algorithm and find the most suitable algorithm for your application.

# 4. Exercise



Calculate the average waiting time according to the figure of process and distinguish what kind of algorithm it is.



# 5. Reference

- [https://www.tutorialspoint.com/operating\\_system/os\\_process\\_scheduling\\_algorithms.htm](https://www.tutorialspoint.com/operating_system/os_process_scheduling_algorithms.htm)
- <https://www.geeksforgeeks.org/cpu-scheduling-in-operating-systems/>
- [https://en.wikipedia.org/wiki/Scheduling\\_\(computing\)](https://en.wikipedia.org/wiki/Scheduling_(computing))