

Problem Definition:

- Given a **directed** graph $G=(V, E, W)$, where each edge has a weight (length, cost),
- Find a shortest path from s to v .
 - s —source
 - v —destination.

Dijkstra's algorithm

$d[s] \leftarrow 0$

for each $v \in V \setminus \{s\}$

do $d[v] \leftarrow \infty, \pi[v] \leftarrow NIL.$

$S \leftarrow \emptyset$

$Q \leftarrow V$ % $Q = V \setminus S$ is a priority queue

while $Q \neq \emptyset$

do $u \leftarrow \text{EXTRACT-MIN}(Q)$

$S \leftarrow S \cup \{u\}$

relaxation step



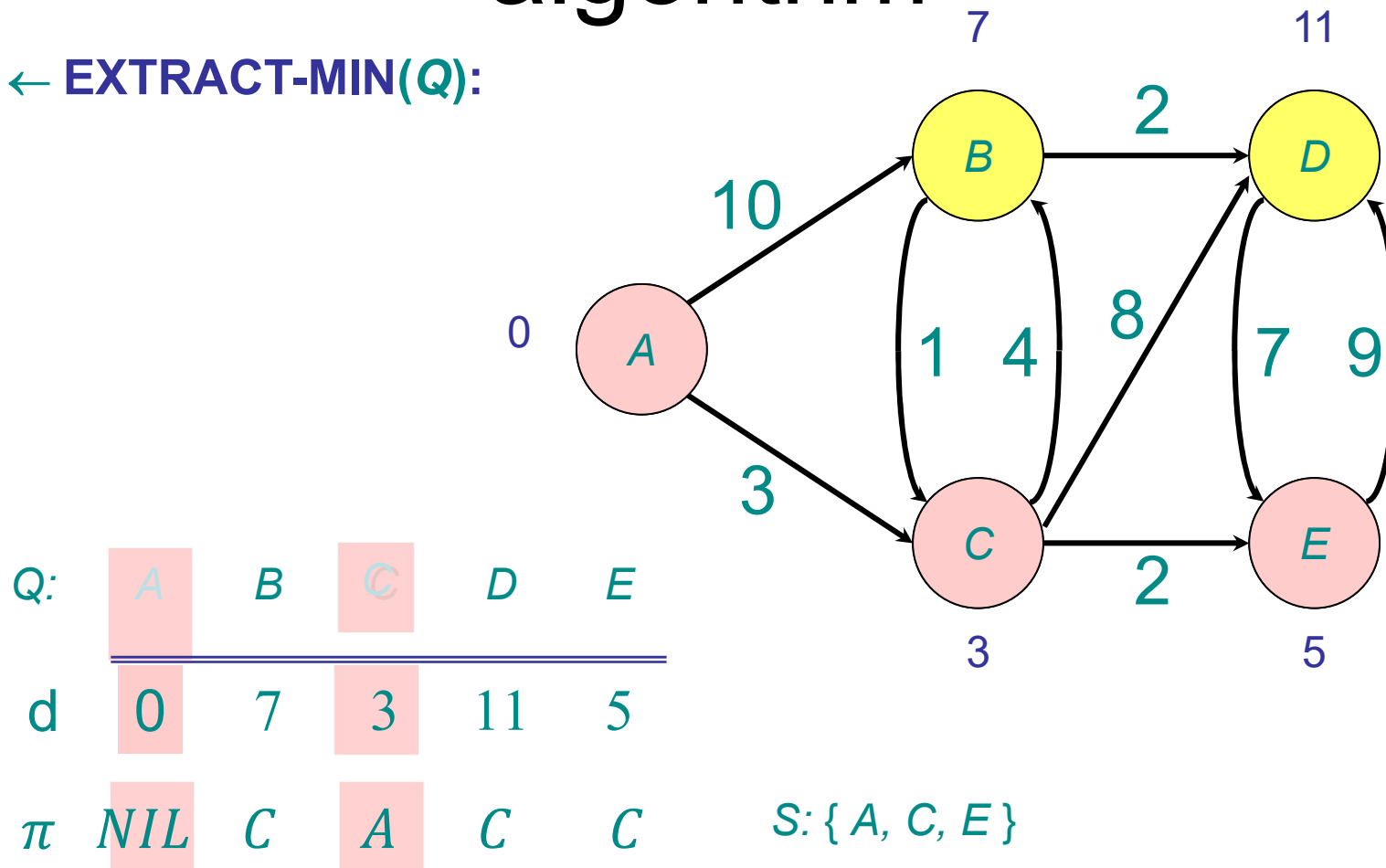
for each $v \in \text{Adj}[u] \ \& \ v \in V \setminus S$

do if $d[v] > d[u] + w(u, v)$

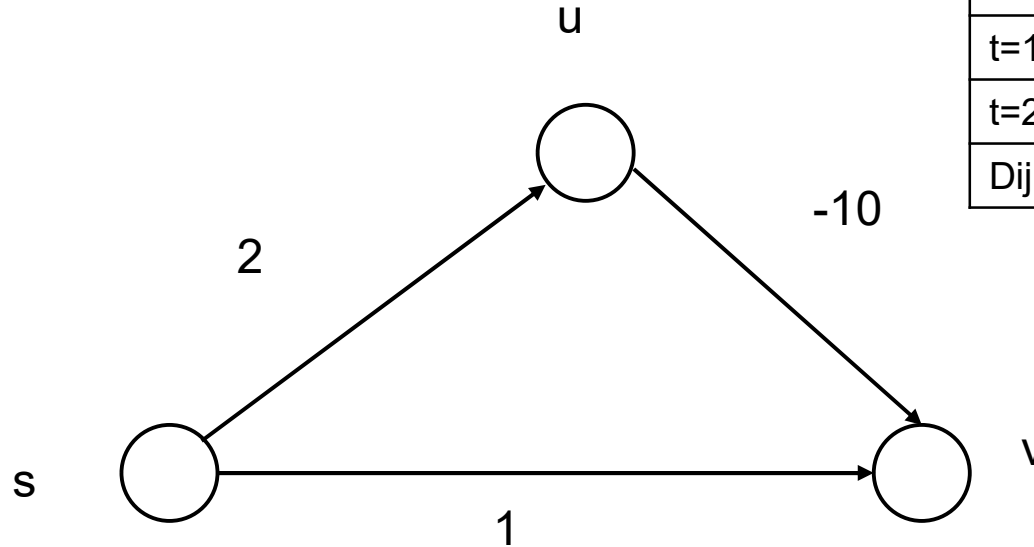
then $d[v] \leftarrow d[u] + w(u, v), \pi[v] \leftarrow u,$

Example of Dijkstra's algorithm

"E" \leftarrow EXTRACT-MIN(Q):



The algorithm does not work if there are negative weight edges in the graph



	s	v	u
t=0	0/Nil	Inf/Nil	Inf/Nil
t=1		1/s	2/s
t=2			2/s
Dijkstra doesn't work			

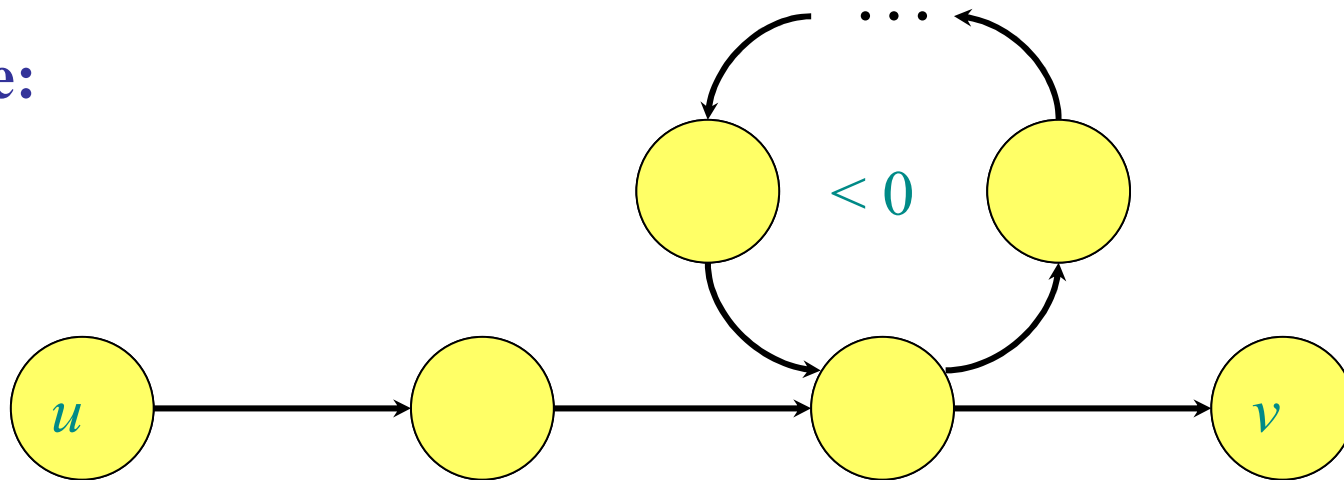
$s \rightarrow v$ is shorter than $s \rightarrow u$, but it is longer than $s \rightarrow u \rightarrow v$.

Lecture 10: Shortest Paths
with **Negative weighted** edges
Bellman-Ford algorithm

Negative-weight cycles

Recall: If a graph $G = (V, E)$ contains a negative-weight cycle, then some shortest paths may not exist.

Example:



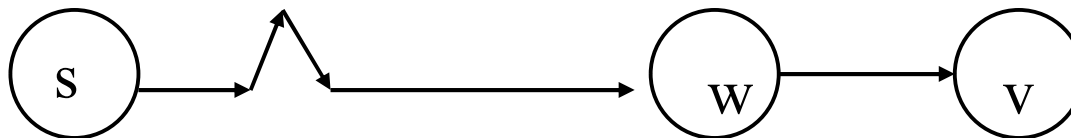
Bellman-Ford algorithm: Finds all shortest-path lengths from a *source* $s \in V$ to all $v \in V$ or **determines that a negative-weight cycle exists.**

Shortest Paths: Dynamic Programming

Def. $OPT(i, v)$ = length of shortest s-v path P using at most i edges.

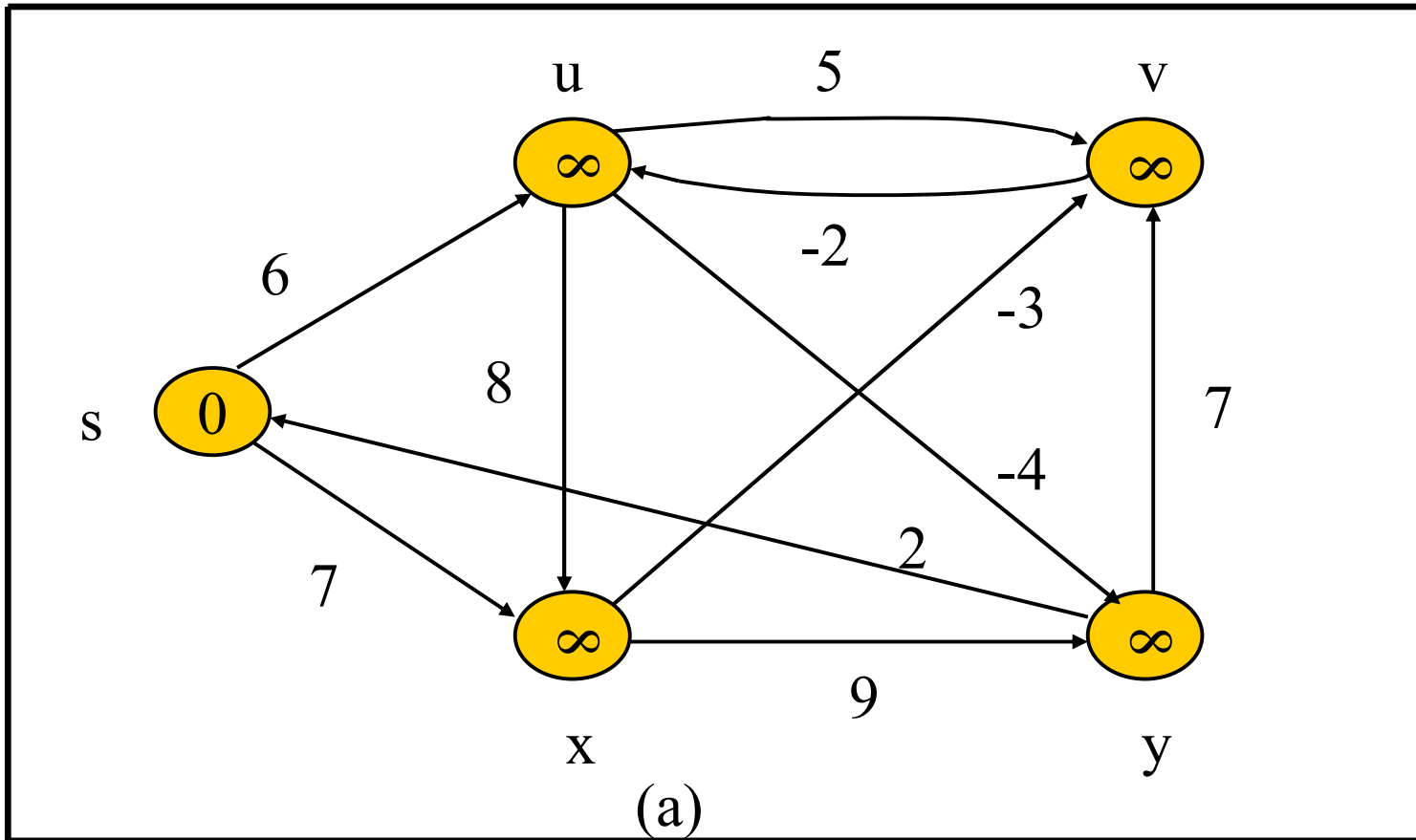
- Case 1: P uses at most $i-1$ edges.
 - $OPT(i, v) = OPT(i-1, v)$
- Case 2: P uses exactly i edges.
 - If (w, v) is the last edge, then OPT use the best s-w path using at most $i-1$ edges and edge (w, v) .

$$OPT(i, v) = \begin{cases} 0 & \text{if } i = 0 \text{ and } v = s \\ \infty & \text{if } i = 0, \text{ and } v \neq s \\ \min\{OPT(i-1, v), \min_{(w,v) \in E} \{OPT(i-1, w) + C_{wv}\}\} & \text{otherwise} \end{cases}$$



Remark: if no negative cycles, then $OPT(n-1, v)$ = length of shortest s-v path.
 n : the number of nodes.

- Using this recursive equation, You can design a DP algorithm. $\text{Opt}(v, i)$ is a subproblem (exercise).

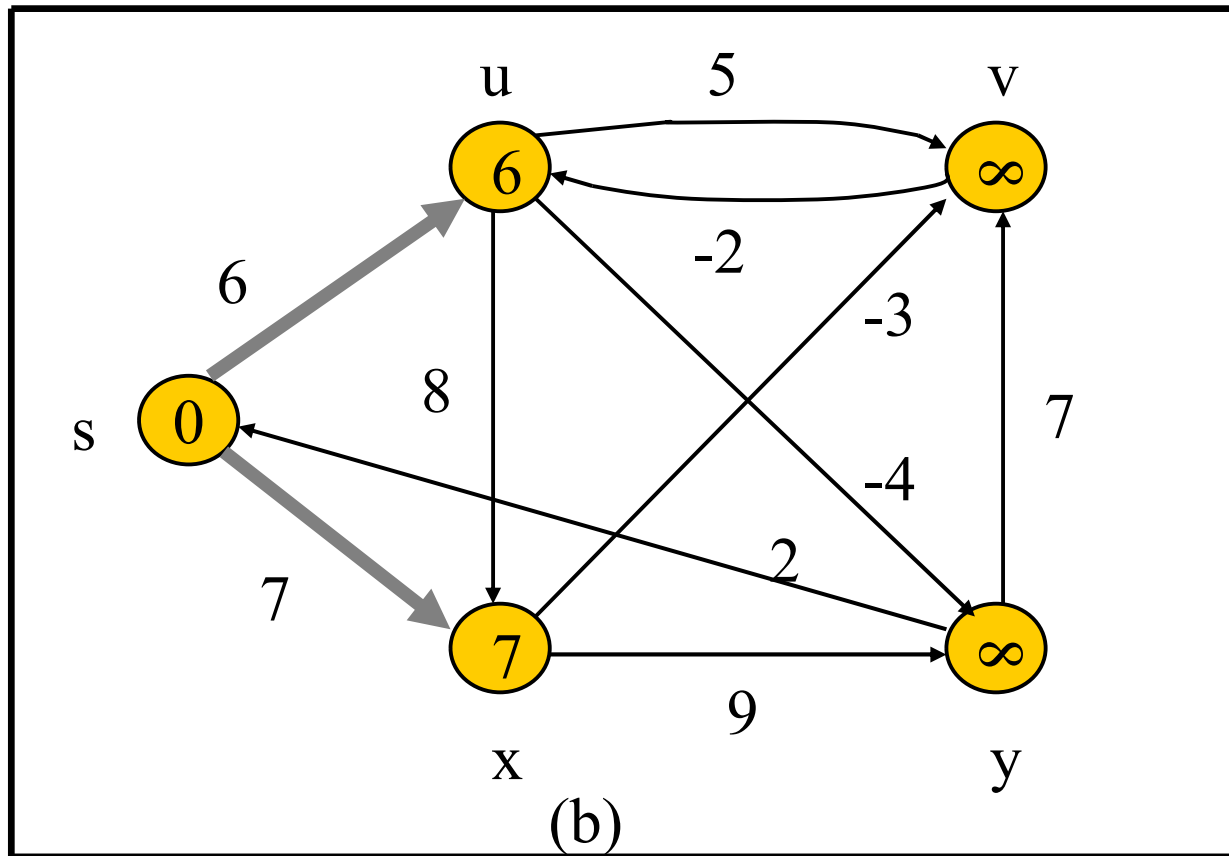


$$OPT(i, v) = \begin{cases} 0 & \text{if } i = 0 \text{ and } v = s \\ \infty & \text{if } i = 0, \text{ and } v \neq s \\ \min\{OPT(i-1, v), \min_{(w,v) \in E} \{OPT(i-1, w) + C_{wv}\}\} & \text{otherwise} \end{cases}$$

vertex: s u v x y i=0

d: 0 ∞ ∞ ∞ ∞

π : s - - - -

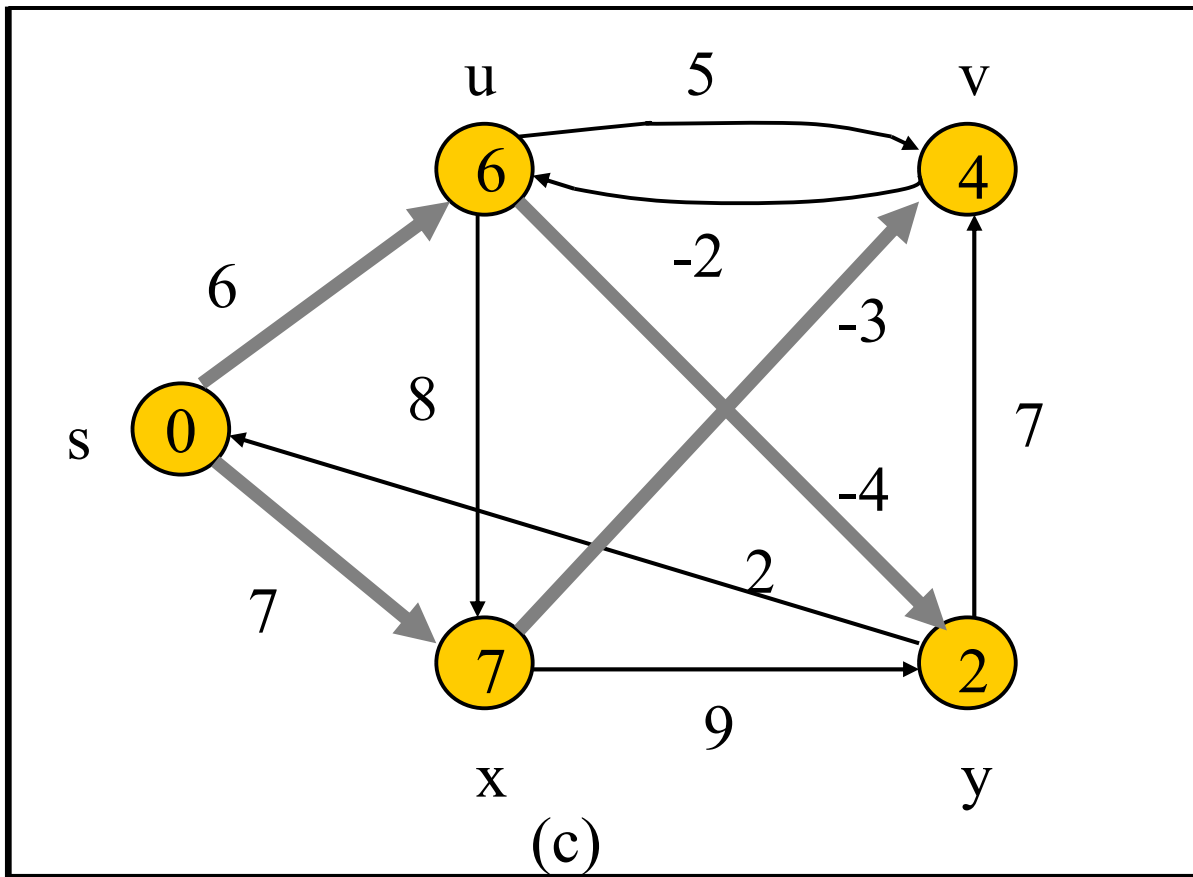


$$OPT(i, v) = \begin{cases} 0 & \text{if } i = 0 \text{ and } v = s \\ \infty & \text{if } i = 0, \text{ and } v \neq s \\ \min\{OPT(i-1, v), \min_{(w,v) \in E} \{OPT(i-1, w) + C_{wv}\}\} & \text{otherwise} \end{cases}$$

vertex: s u v x y i=1

d: 0 6 ∞ 7 ∞

π : s s - s -

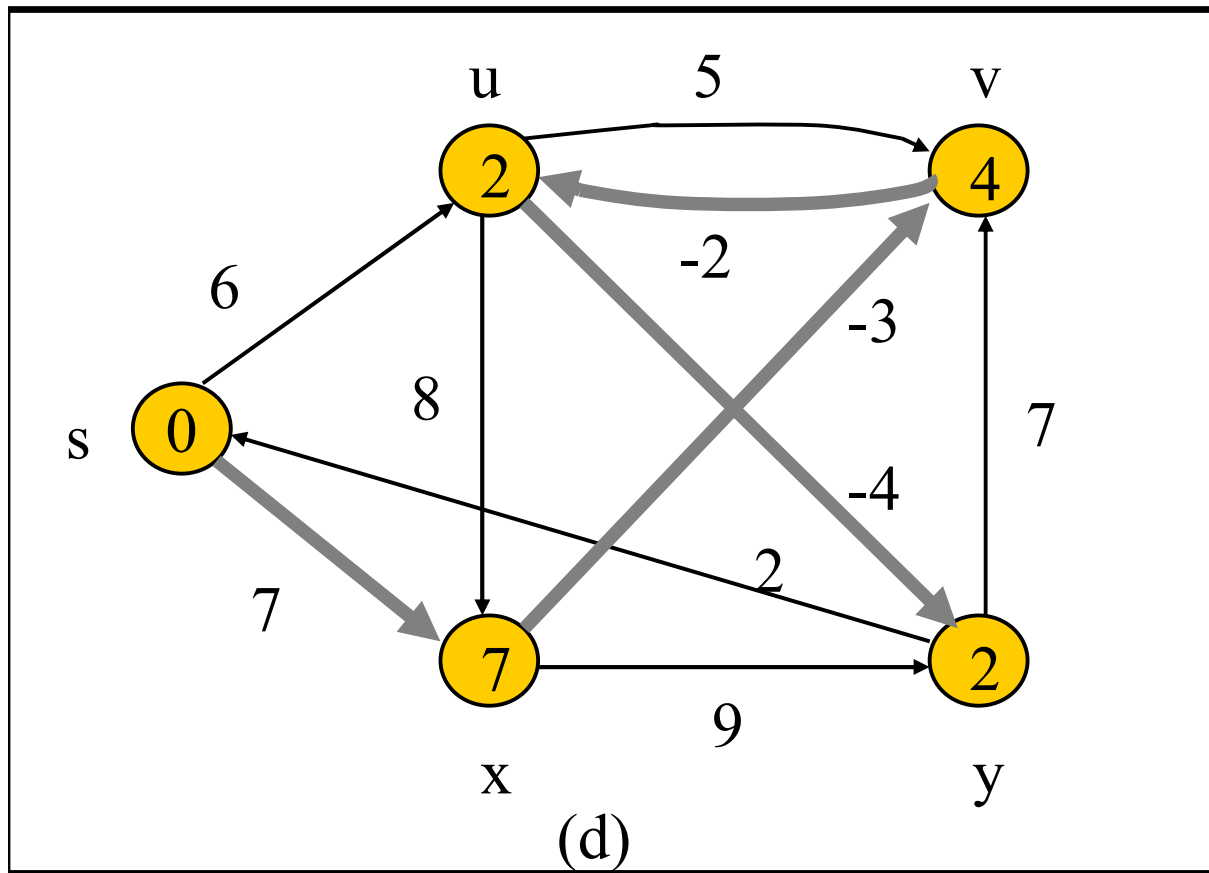


$$OPT(i, v) = \begin{cases} 0 & \text{if } i = 0 \text{ and } v = s \\ \infty & \text{if } i = 0, \text{ and } v \neq s \\ \min\{OPT(i-1, v), \min_{(w,v) \in E} \{OPT(i-1, w) + C_{wv}\}\} & \text{otherwise} \end{cases}$$

vertex: s u v x y i=2

d: 0 6 4 7 2

π s s x s u

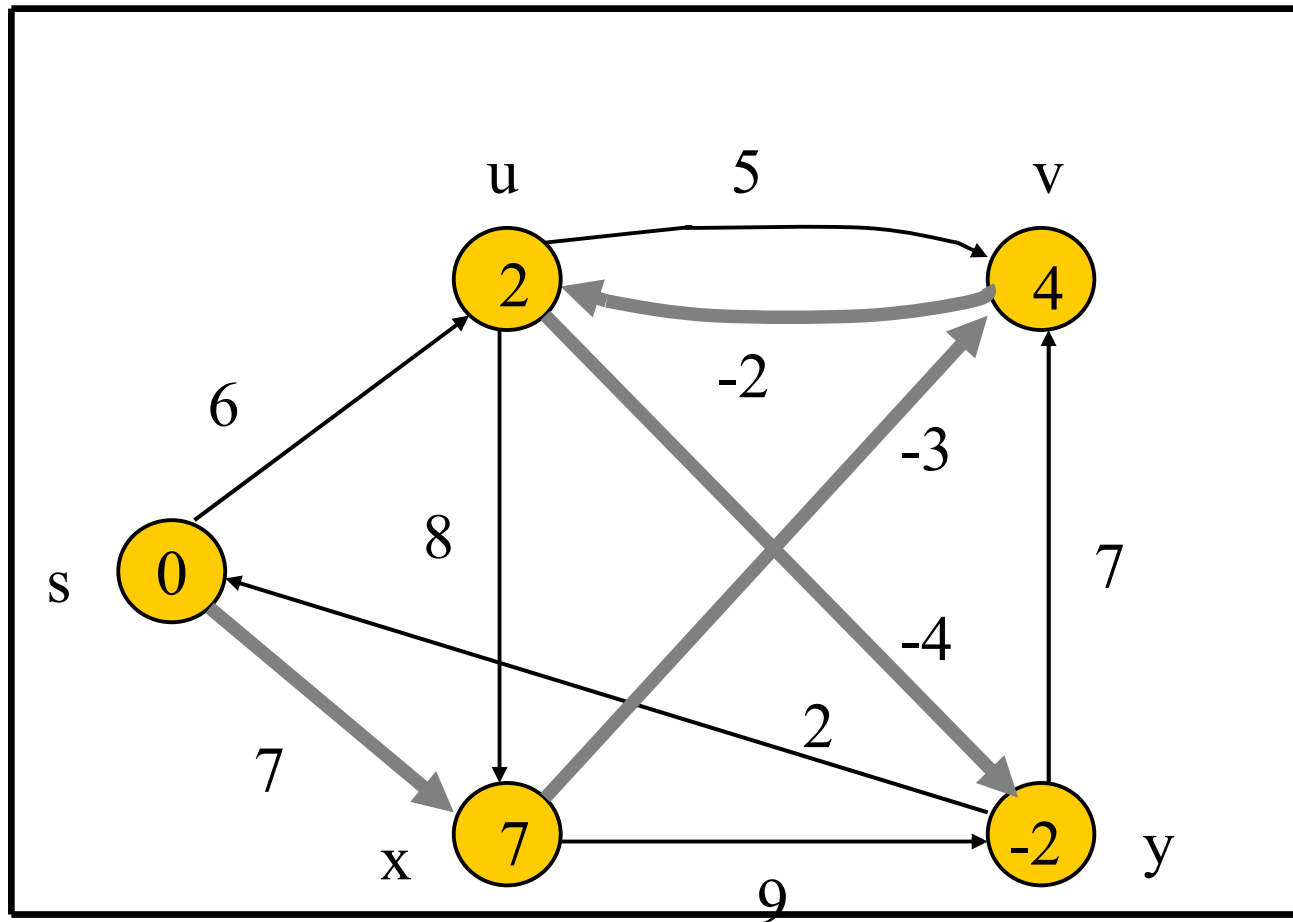


$$OPT(i, v) = \begin{cases} 0 & \text{if } i = 0 \text{ and } v = s \\ \infty & \text{if } i = 0, \text{ and } v \neq s \\ \min\{OPT(i-1, v), \min_{(w,v) \in E} \{OPT(i-1, w) + C_{wv}\}\} & \text{otherwise} \end{cases}$$

vertex: s u v x y i=3

d: 0 2 4 7 2

π : s v x s u

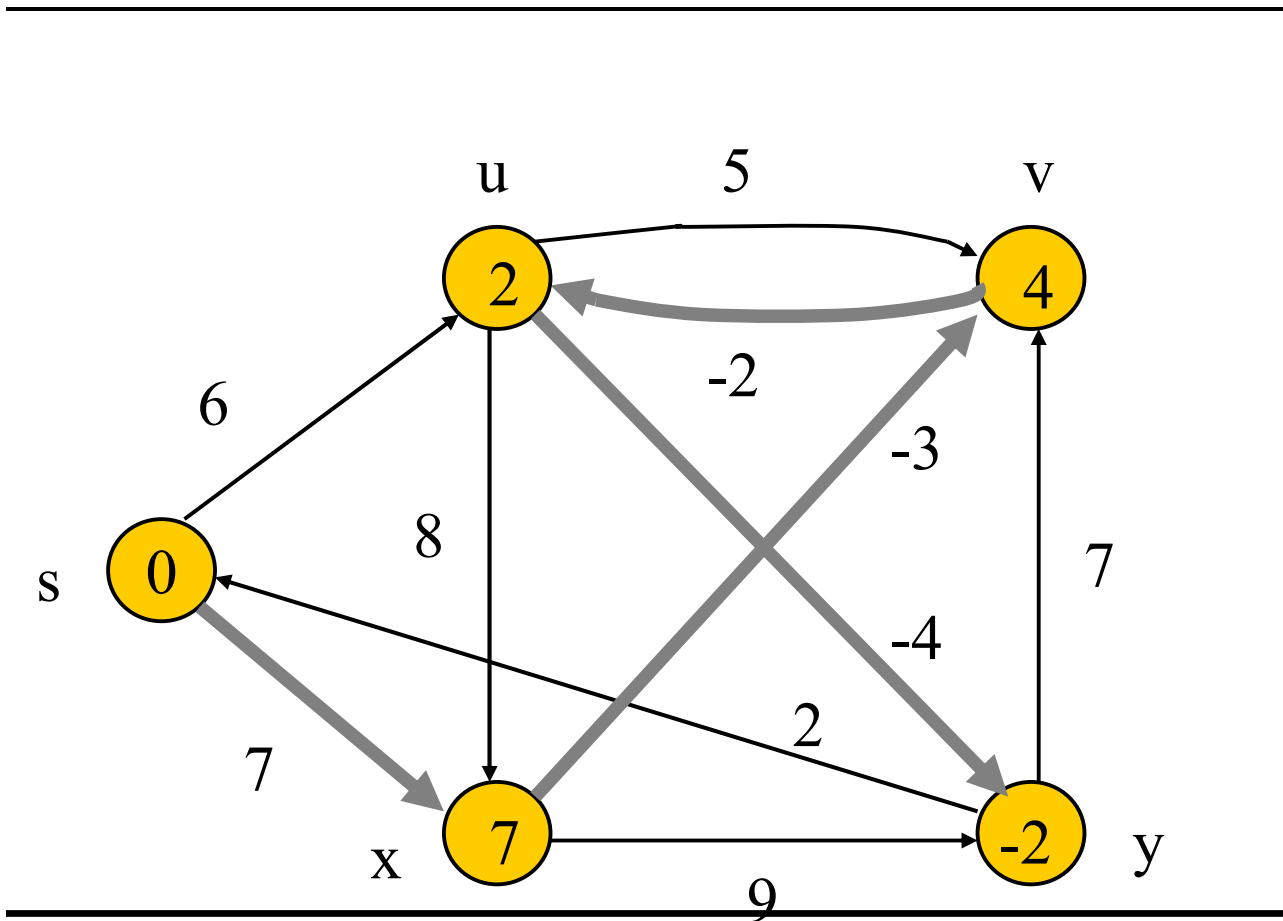


(e)

vertex: s u v x y i=4

d: 0 2 4 7 -2

π : s v x s u



(e)

$$OPT(i, v) = \begin{cases} 0 & \text{if } i = 0 \text{ and } v = s \\ \infty & \text{if } i = 0, \text{ and } v \neq s \\ \min\{OPT(i-1, v), \min_{(w,v) \in E} \{OPT(i-1, w) + C_{wv}\}\} & \text{otherwise} \end{cases}$$

vertex: s u v x y i=5

d: 0 2 4 7 -2

π : s v x s u

$$OPT(i, v) = \begin{cases} 0 & \text{if } i = 0 \text{ and } v = s \\ \infty & \text{if } i = 0, \text{ and } v \neq s \\ \min\{OPT(i-1, v), \min_{(w,v) \in E} \{OPT(i-1, w) + C_{wv}\}\} & \text{otherwise} \end{cases}$$

vertex:	s	u	v	x	y	
d:	∞	∞	∞	∞	∞	i=0
π :	s	-	-	-	-	
d:	0	6	∞	7	∞	i=1
π :	s	s	-	s	-	
d:	0	6	4	7	2	i=2
π :	s	s	x	s	u	
d:	0	2	4	7	2	i=3
π :	s	v	x	s	u	
d:	0	2	4	7	-2	i=4
π :	s	v	x	s	u	
d:	0	2	4	7	-2	i=5
π :	s	v	x	s	u	

So, no negative cycle.

- Bellman-Ford algorithm is more efficient.

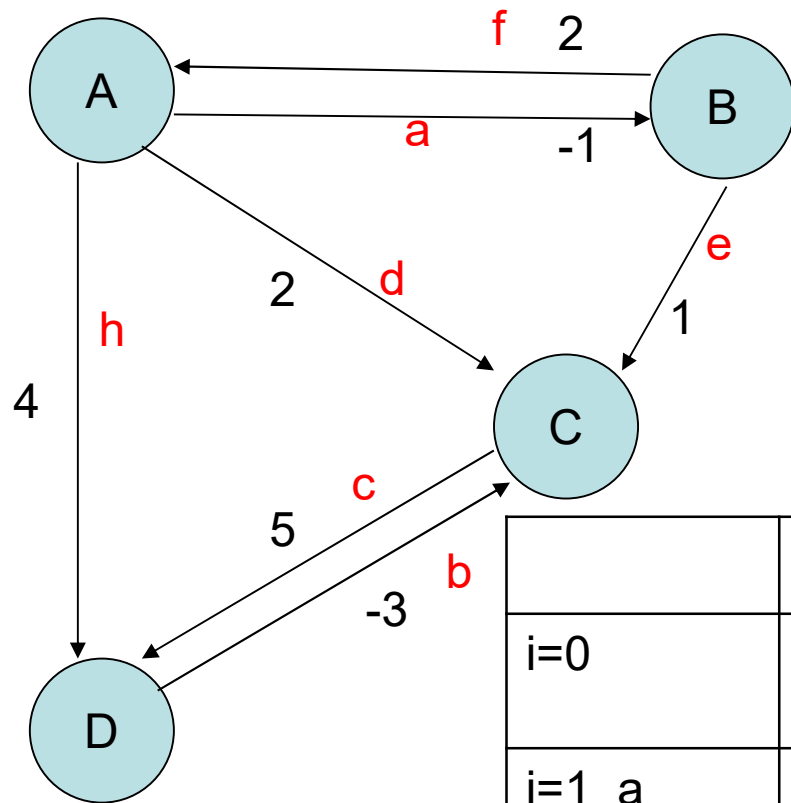
Bellman-Ford algorithm

$d[s] \leftarrow 0$
for each $v \in V - \{s\}$
 do $d[v] \leftarrow \infty$ } initialization

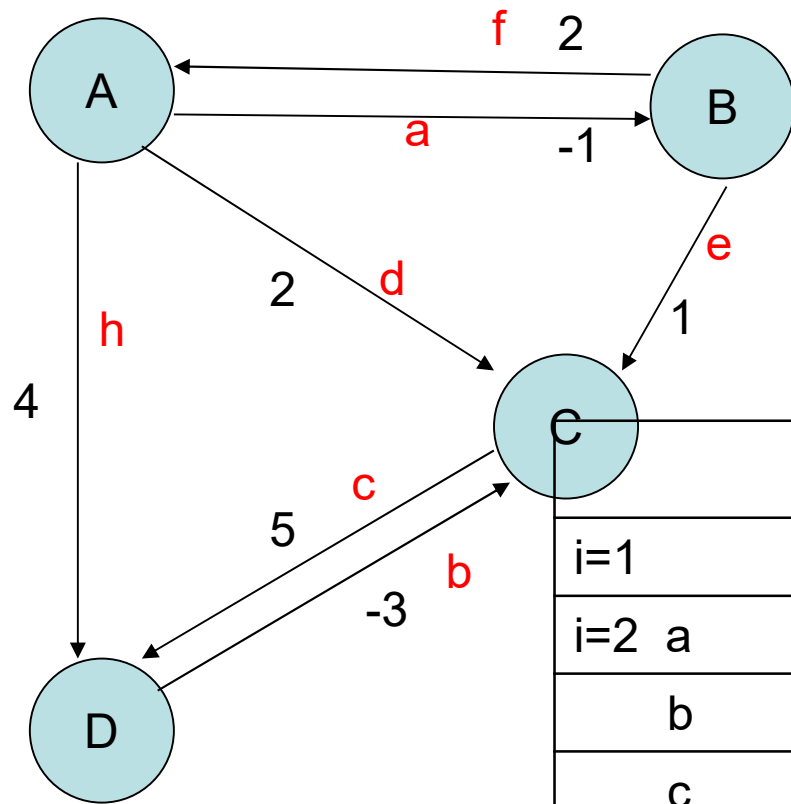
for $i \leftarrow 1$ **to** $|V| - 1$
 do for **each edge** $(u, v) \in E$
 do if $d[v] > d[u] + w(u, v)$
 then $d[v] \leftarrow d[u] + w(u, v)$ } *relaxation step*

for each edge $(u, v) \in E$
 do if $d[v] > d[u] + w(u, v)$
 then report that a negative-weight cycle exists

At the end, $d[v] = \delta(s, v)$. Time = $O(|V| |E|)$.



	A	B	C	D
i=0	0/NIL	∞ /NIL	∞ /NIL	∞ /NIL
i=1 a		-1/A		
b			X	
c				X
d			2/A	
e			0/B	
f	X			
h				4/A
	0/NIL	-1/A	0/B	4/A

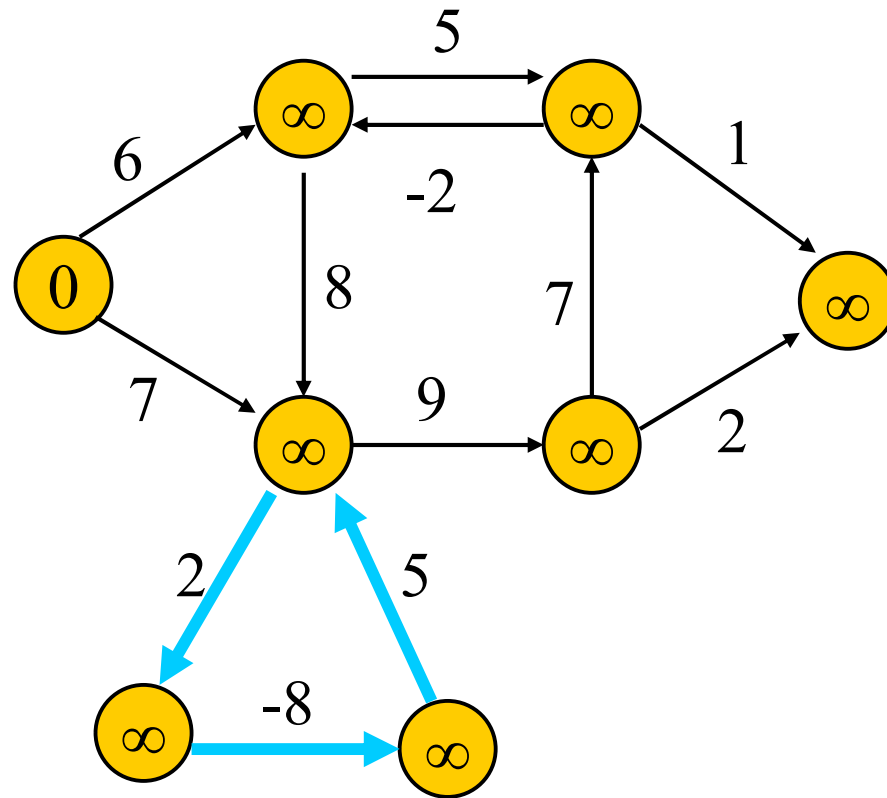


	A	B	C	D
i=1	0/NIL	-1/A	0/B	4/A
i=2 a		-1/A		
b			X	
c				X
d			X	
e			X	
f	X			
h				X
	0/NIL	-1/A	0/B	4/A

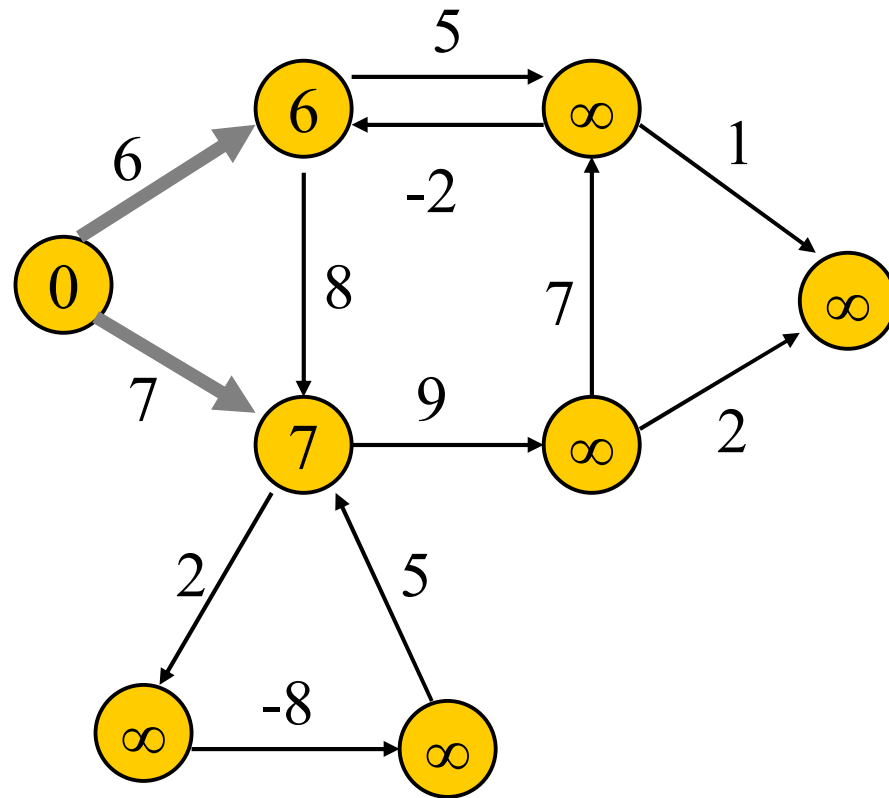
The result for i=2 is the same as i=1, so are i=3, 4.
Conclusion: no negative cycle.

Corollary: If negative-weight circuit exists in the given graph, in the n -th iteration, the cost of a shortest path from s to *some* node v will be further reduced.

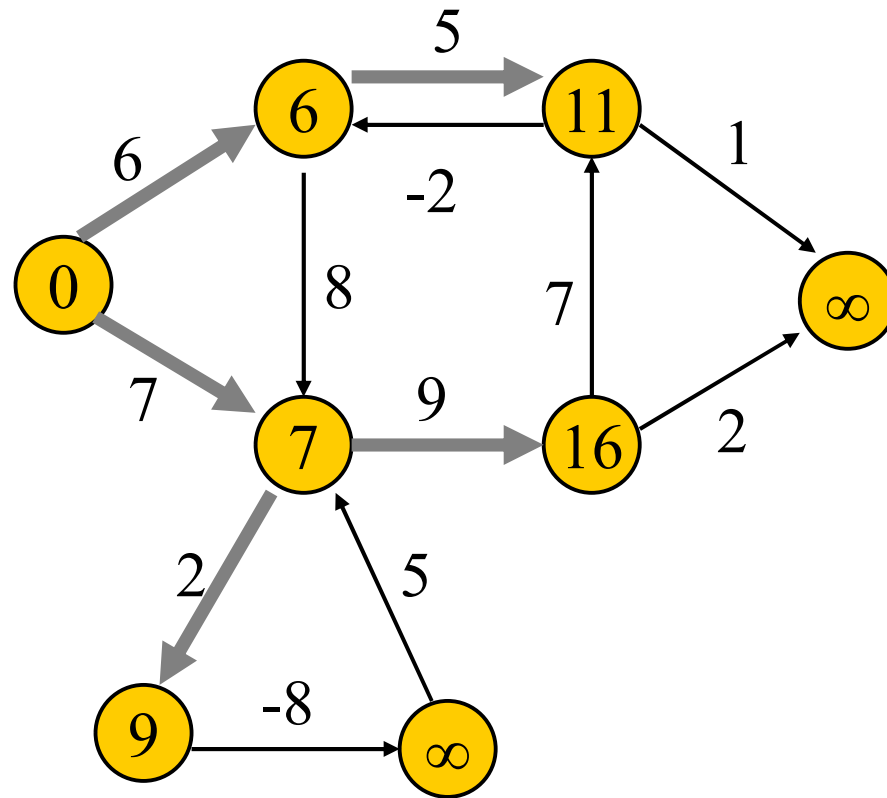
Demonstrated by the following examples.



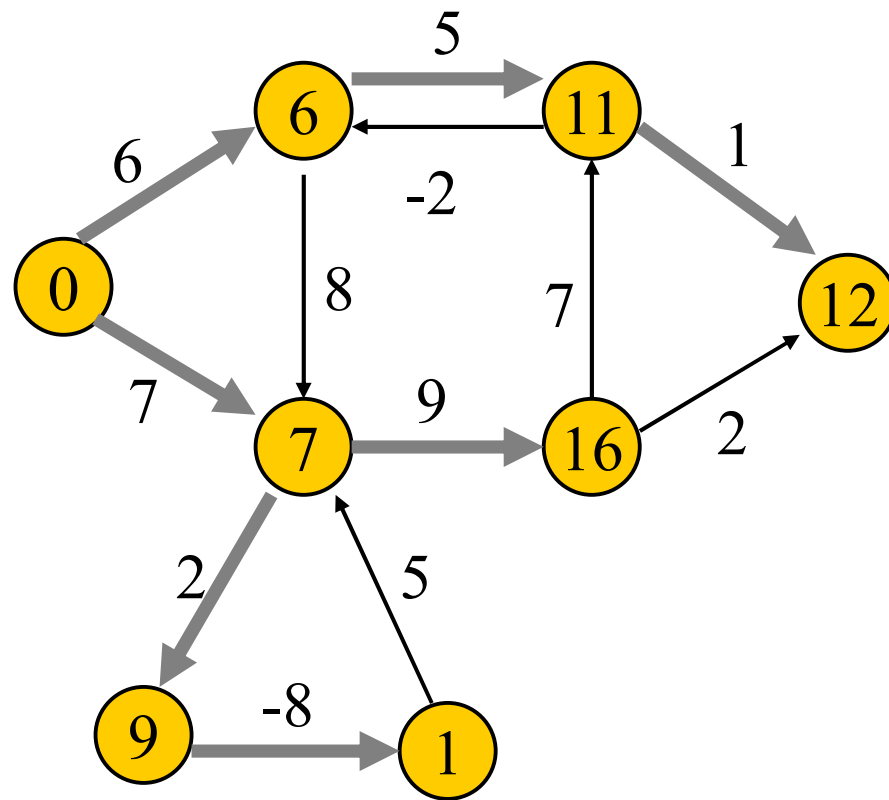
An example with negative-weight cycle



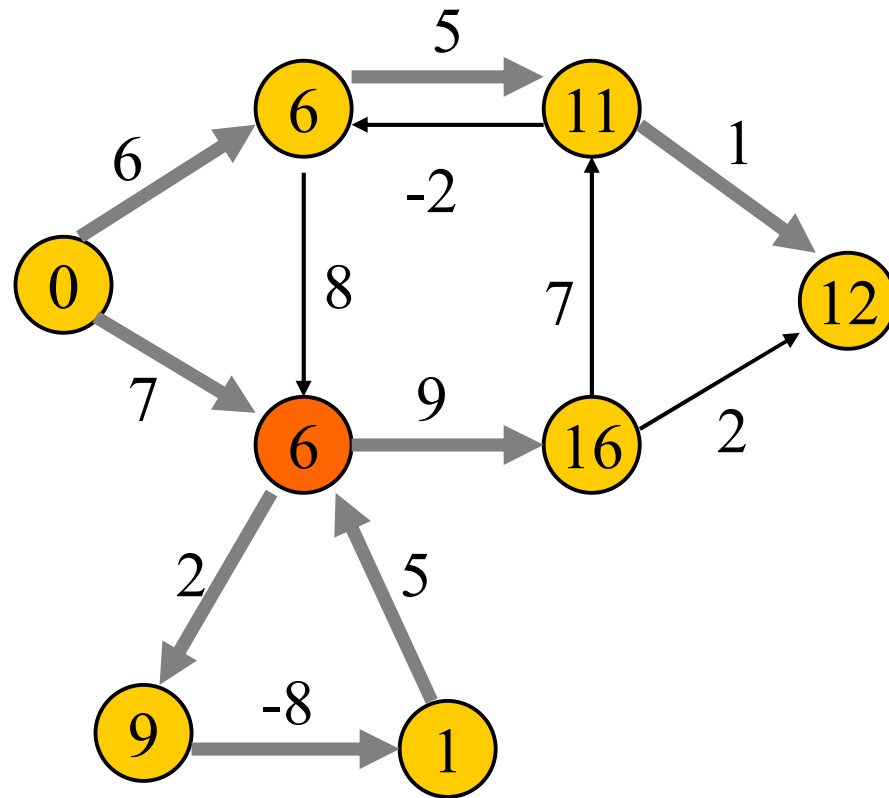
i=1



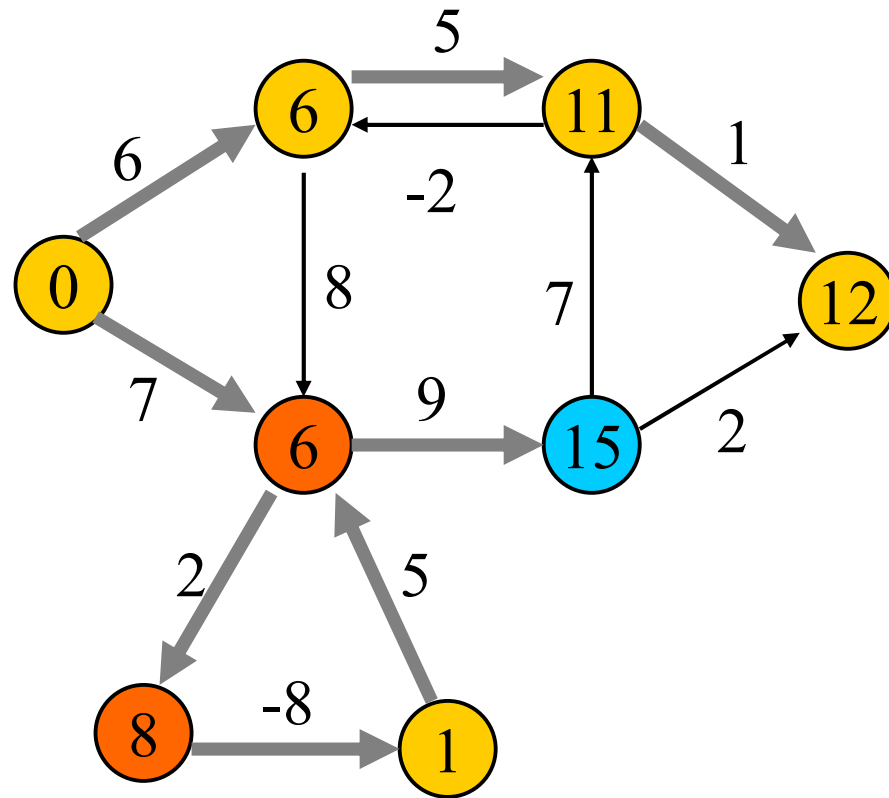
i=2



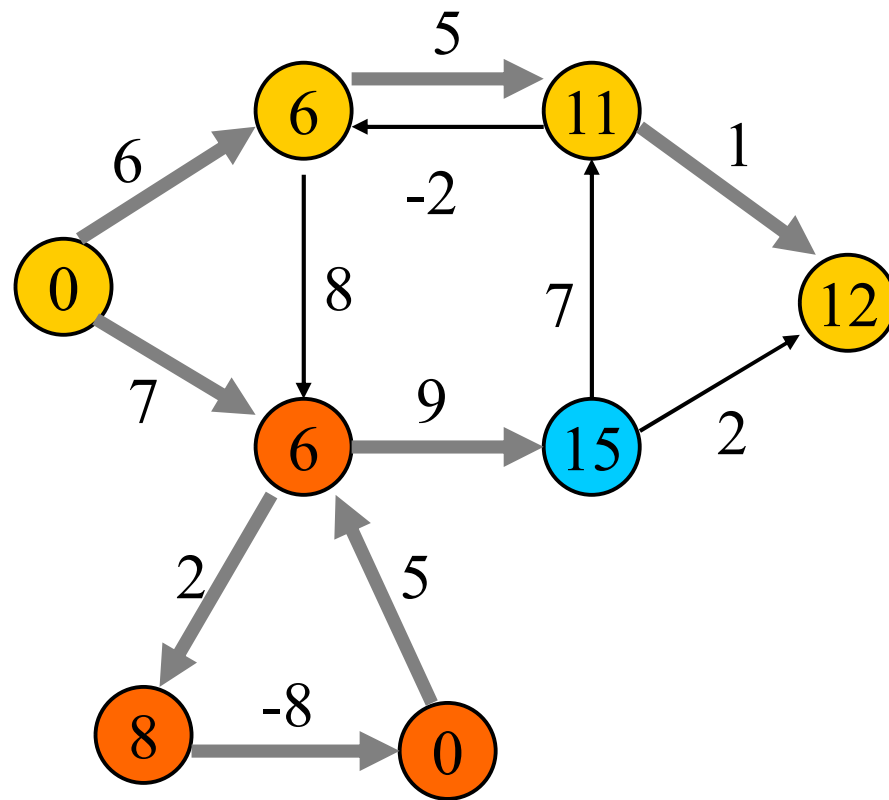
$i=3$



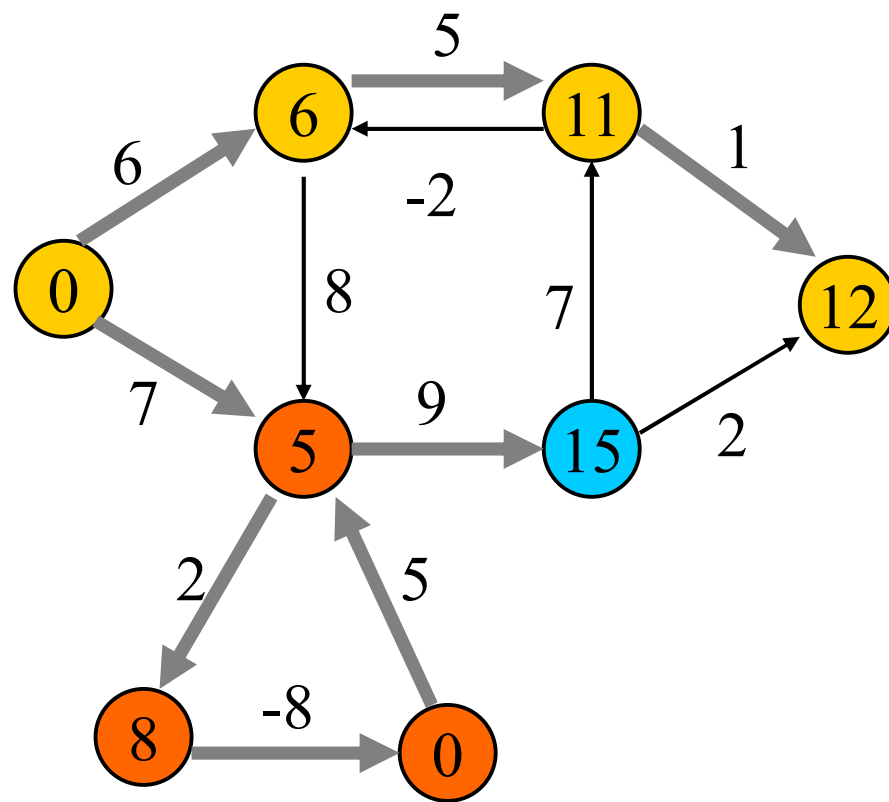
i=4



$i=5$

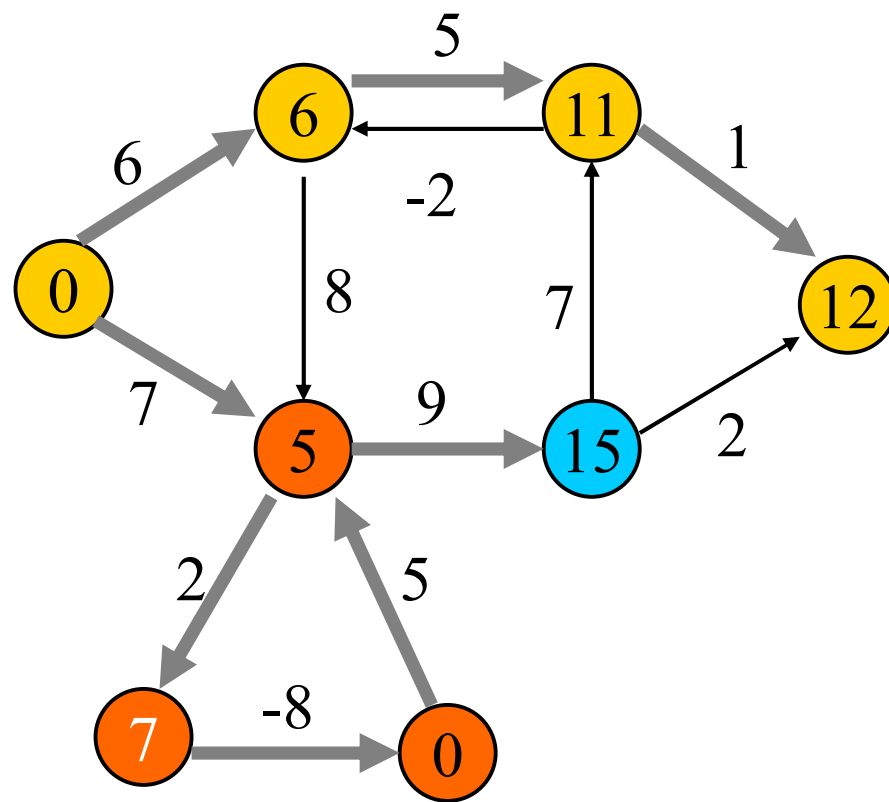


i=6



x

i=7



x

i=8

0-1 Knapsack Problem

Knapsack Problem 0-1 version

Knapsack problem.

- Given n objects and a "knapsack."
- Item i weighs $w_i > 0$ kilograms and has value $v_i > 0$.
- Knapsack has capacity of W kilograms.
- Goal: fill knapsack so as to maximize total value.

Ex: { 3, 4 } has value 40.

$W = 11$

Item	Value	Weight
1	1	1
2	6	2
3	18	5
4	22	6
5	28	7

Greedy: repeatedly add item with maximum ratio v_i / w_i .

Ex: { 5, 2, 1 } achieves only value = 35 \Rightarrow greedy not optimal.

Dynamic Programming: Adding a New Variable

Def. $OPT(i, w)$ = max profit subset of items 1, ..., i with weight limit w.

- Case 1: OPT does not select item i.
 - OPT selects best of { 1, 2, ..., i-1 } using weight limit w
- Case 2: OPT selects item i.
 - new weight limit = $w - w_i$
 - OPT selects best of { 1, 2, ..., i-1 } using this new weight limit

$$OPT(i, w) = \begin{cases} 0 & \text{if } i = 0 \\ OPT(i-1, w) & \text{if } w_i > w \\ \max \{ OPT(i-1, w), v_i + OPT(i-1, w - w_i) \} & \text{otherwise} \end{cases}$$

Knapsack Problem: Bottom-Up

Knapsack. Fill up an n -by- W array.

```
Input:  $n, w_1, \dots, w_N, v_1, \dots, v_N$ 

for  $w = 0$  to  $W$ 
     $M[0, w] = 0$ 

for  $i = 1$  to  $n$ 
    for  $w = 1$  to  $W$ 
        if  $(w_i > w)$ 
             $M[i, w] = M[i-1, w]$ 
        else
             $M[i, w] = \max \{M[i-1, w], v_i + M[i-1, w-w_i]\}$ 

return  $M[n, W]$ 
```

Knapsack Problem: Running Time

Running time. $\Theta(n W)$.

- Not polynomial in input size!
- "Pseudo-polynomial."
- Decision version of Knapsack is NP-complete. [Chapter 8]

$$OPT(i, w) = \begin{cases} 0 & \text{if } i = 0 \\ OPT(i - 1, w) & \text{if } w_i > w \\ \max\{OPT(i - 1, w), v_i + OPT(i - 1, w - w_i)\} & \text{otherwise} \end{cases}$$

Knapsack Algorithm

		W + 1											
		0	1	2	3	4	5	6	7	8	9	10	11
n + 1	ϕ	0	0	0	0	0	0	0	0	0	0	0	0
	{1}	0	1	1	1	1	1	1	1	1	1	1	1
	{1, 2}	0	1	6	7	7	7	7	7	7	7	7	7
	{1, 2, 3}	0	1	6	7	7	18	19	24	25	25	25	25
	{1, 2, 3, 4}	0	1	6	7	7	18	22	24	28	29	29	40
	{1, 2, 3, 4, 5}	0	1	6	7	7	18	22	28	29	34	34	40

OPT: { 4, 3 }
value = 22 + 18 = 40

W = 11

Item	Value	Weight
1	1	1
2	6	2
3	18	5
4	22	6
5	28	7

Summary

- Bellman-ford algorithm
 - Comparison with Dijkstra Algorithm.
- Knapsack Problem.