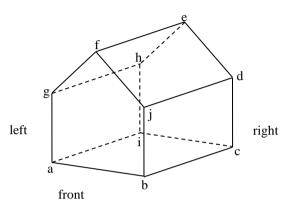
Tut 1

Qn 1

The three dimensional coordinates of the house-shaped object below are as follows:

$$\begin{array}{lll} a=(0,\,0,\,0) & b=(10,\,0,\,0) & c=(10,\,0,\,-20) \\ d=(10,\,10,\,-20) & e=(5,\,15,\,-20) & f=(5,\,15,\,0) \\ g=(0,\,10,\,0) & h=(0,\,10,\,-20) & i=(0,\,0,\,-20) & j=(10,\,10,\,0) \end{array}$$



The front face is denoted by F_1 , the right face F_2 , the left face F_3 , the back face F_4 , the right roof F_5 , the left roof F_6 , and the ground face F_7 .

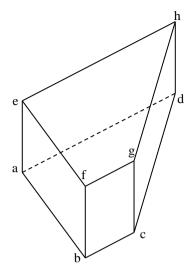
- a) Construct the vertex, edge, face, and attribute table of a polygonal model of the object.
- b) Determine the outward unit surface normal of the left roof face.
- c) Derive the equation of the face d e f j in the form

$$A x + B y + C z + D = 0$$

such that if the (LHS > 0) \Leftrightarrow (Outside) and vice versa.

- d) Suggest a method for determining whether a point is inside or outside the house.
- e) Suggest a general method for determining whether a point is inside or outside any volumetric object.
- f) Suggest an application for the function in e).

<u>Qn 2</u>



a (0, 0, 0) e (0, 0, 5) b (10, 0, 0) f (10, 0, 5) c (10, 4, 0) g (10, 4, 5) d (0, 25, 0) h (0, 25, 5)

Two popular object representation methods are tables and quadrilateral mesh.

- a) Using tables, write C code to represent the face \Box bcgf in the form of vertex table, edge table and face table. Use vertices to form the face table.
- b) Represent the object above, except the top and bottom face, as a quadrilateral mesh. To save time, you are only required to draw a 2D array and put the alphabet (e.g. a) to each of the vertex of the array to show your idea.
- c) Derive the plane equation of □cdhg.
- d) Give an advantage of using the mesh representation compared to using the table representation.

Qn 3

- a) In CG, the *parametric form* is used instead of the *non-parametric form*. What is the reason(s)?
- b) The non-parametric form of a superellipsoid is given by

$$\left[\left(\frac{x}{r_x} \right)^{\frac{2}{s_2}} + \left(\frac{y}{r_y} \right)^{\frac{2}{s_2}} \right]^{\frac{s_2}{s_1}} + \left(\frac{z}{r_z} \right)^{\frac{2}{s_1}} = 1$$

Derive its equivalent parametric form. Give the physical meaning of any additional variables you introduce.

<u>Qn 4</u>

Consider the following program fragment:

```
\begin{tabular}{ll} void calculate\_mesh (void) \\ \{ & for (int i=0; i < GRIDSIZE; i++) \\ & for (int j=0; j < GRIDSIZE; j++) \\ \{ & mesh[i][j].x = ... \\ & mesh[i][j].y = ... \\ & mesh[i][j].z = ... \\ \} \\ \end{tabular}
```

Complete the above program to model a super-ellipsoid mesh with the following requirement:

```
Center : (50, 100, 200)
Bounding Box volume : 100 \times 200 \times 400
s_1 and s_2 : user input parameters
```

Qn 5

State the i) non-parametric and ii) parametric form of

- a) elliptic paraboloid
- b) hyperboloid of two sheets (Hint: use $\cosh^2 x \sinh^2 x = 1$)

They are 3D forms of the 2D quadric, parabola and hyerbola respectively.

Consult MathWorld: http://mathworld.wolfram.com/ for definitions.

OpenGL Mini-project Progress

At this point, you should be doing OpenGL Ex 1. After finishing the exercise, try replacing the quadrilateral mesh with

```
glutSolidCube (0.5);
```

What do you observe?