(1, 2) Quadratic Form g (x1, x2) 9 = 3x,2 + 4x, x2 -1x2 $X, \in \mathbb{R}$ ExI X2 ER $\frac{1}{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$ Symmetrie $\frac{7}{7} = x_1^2 + 2x_2^2 + 7x_3^2 - 2x_1x_2 + 4x_1x_3 - 2x_2x_3$ Ex2.a

$$\begin{bmatrix} X_1 & X_2 & X_3 \end{bmatrix} \begin{bmatrix} 1 & -1 & 2 \\ -1 & 2 & -1 \\ 2 & -1 & 7 \end{bmatrix} \begin{bmatrix} X_1 \\ X_2 \\ X_3 \end{bmatrix}$$

" General form $q = \sum_{i=1}^{n} \sum_{j=1}^{n} a_{ij} \times_{i} \times_{j}$ x= x1 x2 : Xn A = [aij] $= \underbrace{\times^{\top}}_{\text{N=17}} \underbrace{\wedge}_{\text{M=17}}$ $A = A^{T}$ is the definite if 9>0 for all x ≠0 Z = XTAX is - Ve definite if q<0 for all x ≠0 is - Ve Semi-definite if 9 =0 is - Ve Semi-definite if 9 =0 indefinite if it can be the and negative values.

9 = X1 + 2X2 + 7X3 - 2X1X2 + 4X1X3 - 2X2X3 $= (X_1 - X_2 + 2X_3)^2 + 2X_2^2 + 7X_3^2 - 2X_2X_3 - X_2^2)$ $= (X_1 - X_2 + 2X_3)^2 + 2X_2^2 + 7X_3^2 - 2X_2X_3 - X_2^2)$ $= (x_1 - x_2 + 2x_3)^{2} + x_2^{2} + 3x_3^{2} + 2x_2x_3$ $= \left(\frac{x_1 - x_2 + z x_3}{+ \sqrt{2}} + \frac{z x_3}{+ \sqrt{2}} + \frac{z x_3}{+ \sqrt{2}} + \frac{z x_3}{+ \sqrt{2}} \right)$ for any choice of X1+X2 X3 $\frac{2}{3}$ and $A = \begin{bmatrix} 1 & -7 & 2 \\ -1 & 2 & -1 \\ 2 & -1 & 7 \end{bmatrix}$ are the definite (How do we associate) (with eigenvalues?) q = XTAX >0 for any choice of x check all >i>o, Example

$$= 3 \left(\frac{\chi_{1}^{2} + 2(\frac{2}{3})\chi_{1}\chi_{2} + (\frac{2}{3}\chi_{2})^{2} - (\frac{2}{3})^{2}\chi_{2}^{2} - \frac{1}{3}\chi_{2}^{2}}{3} \right)$$

$$= 3 \left(\left(\frac{\chi_{1} + (\frac{2}{3}\chi_{2})^{2}}{3} - (\frac{2}{3})^{2}\chi_{2}^{2} - \frac{1}{3}\chi_{2}^{2}} \right)$$

$$= 3 \left(\left(\frac{\chi_{1} + \frac{2}{3}\chi_{2}}{3} \right)^{2} - \frac{7}{9}\chi_{2}^{2} \right)$$

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$$= 3 \left(\frac{\chi_{1} + \frac{2}{3}\chi_{2}}{3} \right)$$

$$= 3 \left(\frac{\chi_{$$

9 = 3x12 + 4x1x2 - x2

 $= 3(x_1^2 + \frac{4}{3}x_1x_2 - \frac{1}{3}x_2^2)$

. "A" is a real symmetric matrix, it is possible to find a linearly independent eigenvectors, x1, x2, ..., xn · If $\lambda_1, \lambda_2, \dots \lambda_n$ are distinct, then these eigenvectors xi, xz, ... xn will also be orthogonal. xix;=0 ixj • [Of course, if they are not distinct, it is in fact still possible to obtain n orthogonal eigenvectors via "Gran-Schmidt process"]
(We did not cover this process in our course.) $\Sigma_1^T \times_1 = 1$, $\Sigma_2^T \times_2 = 1$, ..., $\Sigma_N^T \times_N = 1$ · If $X_1, X_2, ..., X_n$ are normalized, i.e. P=[x1,x2,...,xn]; $P^TP = I \Leftrightarrow P^T = P^{-1}$ P is Orthogonal Matrix

Recall (A is nxn matrix)

Thus, it is possible to diagonalize a symmetric matrix using an orthogonal matrix P PTAP=D

Suppose à quadratic form 9=2cTAz

Make the change of variable

$$X = Py$$

The property of the p

7 = XTAX = (Pg)TA Py = yTPTAPY

of is written as a = 9 D 9 = Sum of squares with $= \lambda_1 y_1^2 + \lambda_2 y_2^2 + \dots + \lambda_n y_n^2$ the coefficients of the = アカレタン

$$[y_1, y_2, \dots, y_n] \begin{bmatrix} x_1 \\ y_2 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ y_n \end{bmatrix}$$

A quadratic form and its associated motivix are positive definite all eigenvalues of the associated symmetric matrix are positive !a N; of A >0 for all i

Example
$$q = 2x_1^2 - 2x_1x_2 + 2x_2^2 = [x_1 x_2] \begin{bmatrix} 2 & -1 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_3 \end{bmatrix} = x^T A x$$

The eigenvalues and sigenvectors of A are

$$\lambda_1 = 1 \qquad \lambda_2 = 3$$

 $x_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ $x_2 = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$ $\chi_{2} = \begin{bmatrix} -1/2 \\ 1/2 \end{bmatrix} \implies P = \begin{bmatrix} 1/2 \\ 1/2 \end{bmatrix} \begin{bmatrix} 1/2 \\ 1/2 \end{bmatrix}$ normalized vectors $x_1 = \begin{bmatrix} 1/\sqrt{2} \\ 1/\sqrt{2} \end{bmatrix}$

$$P^{-1} = P^{T} = \begin{bmatrix} \frac{1}{3}z & \frac{1}{3}z \\ -\frac{1}{3}z & \frac{1}{3}z \end{bmatrix}; \qquad P^{T}AP = \begin{bmatrix} 1 & 0 \\ 0 & 3 \end{bmatrix} = D$$
If we make the change of variable
$$X = PY \qquad or \qquad P^{-1}X = Y \qquad or \qquad P^{T}X = Y$$

$$X = PY \qquad or \qquad P^{-1}X = Y \qquad or \qquad P^{-1}X = Y$$

$$X = Y = \begin{bmatrix} \frac{1}{3}z & -\frac{1}{3}z \\ \frac{1}{3}z & \frac{1}{3}z \end{bmatrix} \begin{bmatrix} \frac{1}{3}z & -\frac{1}{3}z \\ \frac{1}{3}z & \frac{1}{3}z \end{bmatrix} \begin{bmatrix} \frac{1}{3}z & -\frac{1}{3}z \\ \frac{1}{3}z & \frac{1}{3}z \end{bmatrix} = \begin{bmatrix} \frac{1}{3}z & -\frac{1}{3}z \\ \frac{1}{3}z & \frac{1}{3}z \end{bmatrix} \begin{bmatrix} \frac{1}{3}z & -\frac{1}{3}z \\ \frac{1}{3}z & \frac{1}{3}z \end{bmatrix} = \begin{bmatrix} \frac{1}{3}z & -\frac{1}{3}z \\ \frac{1}{3}z & \frac{1}{3}z \end{bmatrix}$$
ficiation (i) $Y = P^{T}X = \begin{bmatrix} \frac{1}{3}z & \frac{1}{3}z \\ -\frac{1}{3}z & \frac{1}{3}z \end{bmatrix} \begin{bmatrix} \frac{1}{3}z & -\frac{1}{3}z \\ \frac{1}{3}z & \frac{1}{3}z \end{bmatrix} = \begin{bmatrix} \frac{1}{3}z & \frac{1}{3}z \\ -\frac{1}{3}z & \frac{1}{3}z \end{bmatrix} = \begin{bmatrix} \frac{1}{3}z & \frac{1}{3}z \\ -\frac{1}{3}z & \frac{1}{3}z \end{bmatrix} = \begin{bmatrix} \frac{1}{3}z & \frac{1}{3}z \\ -\frac{1}{3}z & \frac{1}{3}z \end{bmatrix} = \begin{bmatrix} \frac{1}{3}z & \frac{1}{3}z \\ -\frac{1}{3}z & \frac{1}{3}z \end{bmatrix} = \begin{bmatrix} \frac{1}{3}z & \frac{1}{3}z \\ -\frac{1}{3}z & \frac{1}{3}z \end{bmatrix} = \begin{bmatrix} \frac{1}{3}z & \frac{1}{3}z \\ -\frac{1}{3}z & \frac{1}{3}z \end{bmatrix} = \begin{bmatrix} \frac{1}{3}z & \frac{1}{3}z \\ -\frac{1}{3}z & \frac{1}{3}z \end{bmatrix} = \begin{bmatrix} \frac{1}{3}z & \frac{1}{3}z \\ -\frac{1}{3}z & \frac{1}{3}z \end{bmatrix} = \begin{bmatrix} \frac{1}{3}z & \frac{1}{3}z \\ -\frac{1}{3}z & \frac{1}{3}z \end{bmatrix} = \begin{bmatrix} \frac{1}{3}z & \frac{1}{3}z \\ -\frac{1}{3}z & \frac{1}{3}z \end{bmatrix} = \begin{bmatrix} \frac{1}{3}z & \frac{1}{3}z \\ -\frac{1}{3}z & \frac{1}{3}z \end{bmatrix} = \begin{bmatrix} \frac{1}{3}z & \frac{1}{3}z \\ -\frac{1}{3}z & \frac{1}{3}z \end{bmatrix} = \begin{bmatrix} \frac{1}{3}z & \frac{1}{3}z \\ -\frac{1}{3}z & \frac{1}{3}z \end{bmatrix} = \begin{bmatrix} \frac{1}{3}z & \frac{1}{3}z \\ -\frac{1}{3}z & \frac{1}{3}z \end{bmatrix} = \begin{bmatrix} \frac{1}{3}z & \frac{1}{3}z \\ -\frac{1}{3}z & \frac{1}{3}z \end{bmatrix} = \begin{bmatrix} \frac{1}{3}z & \frac{1}{3}z \\ -\frac{1}{3}z & \frac{1}{3}z \end{bmatrix} = \begin{bmatrix} \frac{1}{3}z & \frac{1}{3}z \\ -\frac{1}{3}z & \frac{1}{3}z \end{bmatrix} = \begin{bmatrix} \frac{1}{3}z & \frac{1}{3}z \\ -\frac{1}{3}z & \frac{1}{3}z \end{bmatrix} = \begin{bmatrix} \frac{1}{3}z & \frac{1}{3}z \\ -\frac{1}{3}z & \frac{1}{3}z \end{bmatrix} = \begin{bmatrix} \frac{1}{3}z & \frac{1}{3}z \\ -\frac{1}{3}z & \frac{1}{3}z \end{bmatrix} = \begin{bmatrix} \frac{1}{3}z & \frac{1}{3}z \\ -\frac{1}{3}z & \frac{1}{3}z \end{bmatrix} = \begin{bmatrix} \frac{1}{3}z & \frac{1}{3}z \\ -\frac{1}{3}z & \frac{1}{3}z \end{bmatrix} = \begin{bmatrix} \frac{1}{3}z & \frac{1}{3}z \\ -\frac{1}{3}z & \frac{1}{3}z \end{bmatrix} = \begin{bmatrix} \frac{1}{3}z & \frac{1}{3}z \\ -\frac{1}{3}z & \frac{1}{3}z \end{bmatrix} = \begin{bmatrix} \frac{1}{3}z & \frac{1}{3}z \\ -\frac{1}{3}z & \frac{1}{3}z \end{bmatrix} = \begin{bmatrix} \frac{1}{3}z & \frac{1}{3}z \\ -\frac{1}{3}z & \frac{1}{3}z \end{bmatrix} = \begin{bmatrix} \frac{1}{3}z & \frac{1}{3}z \\ -\frac{1}{3}z \end{bmatrix} = \begin{bmatrix} \frac{1}{3}z & \frac{1}{3}z \\ -\frac{1}{3}z \end{bmatrix} = \begin{bmatrix} \frac{1}{3}z & \frac{1}{3}z \\ -\frac{1}{3}z \end{bmatrix} = \begin{bmatrix} \frac{1}{3}$

Varification (i) $y = P^T x = \begin{bmatrix} \frac{1}{12} & \frac{1}{12} \\ -\frac{1}{12} & \frac{1}{12} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} \frac{1}{12} & \frac{1}{12} & \frac{1}{12} \\ \frac{1}{12} & \frac{1}{12} & \frac{1}{12} & \frac{1}{12} \end{bmatrix}$ $\begin{cases} \frac{1}{12} & \frac{1}{12} &$

Varification (ii)
$$g = 2x_1^2 - 2x_1x_2 + 2x_2^2$$

$$= 2(y_1 - y_2)^2/2 - 2(y_1 - y_2) \cdot (y_1 + y_2) + 2(y_1 + y_2)^2$$

$$= y_1^2 + 3y_2^2$$

"Completing the Square" does not necessarily give the same factorization.

Example

- For any constant c>o, the points (x1, x2) satisfying

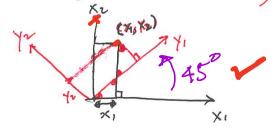
form a conie in the plane.

· change of Variable, we have

 $y_1^2 + 3y_2^2 = C$ This is an equation of an ellepsie

X = PY, where P = [Yz - Yz]

represents a totation of the axes through 45°,



Equivalent definitions

A) If $A_1 = a_{11}$, $A_2 = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}$, $A_3^2 = \begin{bmatrix} a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$... An = det(A), then A is the iff A, Az, a. An are all positive.

B) A is the iff A -> inchalon form, all the diagonal elements are positive.

A eg odzz *

o odzz

$$A = \begin{bmatrix} 2 & -1 & -3 \\ -1 & 2 & 4 \\ -3 & 4 & 9 \end{bmatrix}$$
 is +ve desfine to

$$det[z] = z$$
; $det\begin{bmatrix} z & -1 \\ -1 & z \end{bmatrix} = 3$; $det\begin{bmatrix} z & -1 & -3 \\ -1 & z & 4 \end{bmatrix} = 1$

Ihm: A quadratic form XTAX on a symmetric matrix A is 2= x7Ax 2:>0 some 2 is the definite iff · > (A) >0 入してのす人いでの q is semidefinite iff 2 (A) >0 g is - ve definite if \nearrow (A) < 0 んくっ λ (A) ≤ 0 of is semidefuite iff 1200 4 ALSO some $\chi(A)>0$ and q is indefinite iff 7 (A) <0

Eg: Check if $A = \begin{bmatrix} 4 & 2 & 2 \\ 2 & 4 & 2 \end{bmatrix}$ is positive definite.

(Hints: $\lambda = 2, 8$)

Fo: Find a change of variables that reduces the

Eg: Find a change of variables that reduces the guadratic form $X_1^2 - X_3^2 - 4X_1X_2 + 4X_2X_3$ to a sum of squares and express the quadratic form in terms of the new variables.

Ans: -3 /2 + 3 /3