Property 1 Iwo important properties x is orthogonal to y X-4=0 [-1,0,0] [0]=0 XT 4 = 0 万中子

x, y, + x2 y2 + ... Xnyn=0 => [xiyi =0 Se is normalized vector (=> (2 is a cun't vector) 完·至= 1 ← 至至=1

 $\begin{pmatrix} -1 \\ 0 \\ 0 \end{pmatrix} \bullet \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = 0$

These two proporties will be used later

A hes Ai- >2, Az 3×1 3×1 3×3 (i) Suppose $\lambda_1 \neq \lambda_2 \neq \lambda_3$ $P = \begin{bmatrix} \hat{x}_1, \hat{x}_2, \hat{x}_3 \end{bmatrix}$ (ii) $\hat{x}_1, \hat{x}_2, \hat{x}_3$ are unit vectors i=1,2,3 || \(\hat{\pi}\) || =1 (\implies \(\hat{\pi}\) := | √ from (i), it implies $\{\hat{x}_1 \cdot x_2 = 0, \hat{x}_2 \cdot \hat{x}_3 = 0, \hat{x}_3 \cdot \hat{x}_1 = 0\}$ "orthogonal" $\{\hat{x}_1 - \hat{x}_3 = 0, \hat{x}_2 \cdot \hat{x}_3 = 0, \hat{x}_3 \cdot \hat{x}_1 = 0\}$ $\hat{x}_{1}^{-}, \hat{x}_{2}, \hat{x}_{3})$ $\hat{x}_{1}^{-}, \hat{x}_{2}, \hat{x}_{3}$ orthogonal Matrix

Thm If A is a real symmetric matrix (:eA=AT) (i) $\lambda_1, \lambda_2, \lambda_3, \dots, \lambda_n$ are real numbers. (ii) XI, XI, XI, , Xn corresponding to distinct eigenblug are orthogonal. troof: Read Notes (page 8) &g; 并入, 丰入之

少 2、 五 22

XXX AX=XX If A is a Symmetric Matrix A is real symmatric matrix (1) Light, Az ... In are distinct ~ each eigenvector is normalized \ We can find a P $P = \begin{bmatrix} \hat{x}_1 & \hat{x}_2 \\ \vdots & \hat{x}_n \end{bmatrix} \Leftrightarrow \begin{pmatrix} P^T = P^T \end{pmatrix}$ 1 Unit -P-IAP = D Diagonalization @ eigenvector PTAP = D

Example ***

$$A = \begin{bmatrix} 1 & 3 & 3 \\ -3 & -5 & -3 \end{bmatrix}$$

$$A = \begin{bmatrix} |A - \lambda I| = \begin{bmatrix} |-\lambda| & 3 & 3 \\ |-\lambda| & -3| & -5 - \lambda| & -3 \\ 3 & 3 & (-\lambda) \end{bmatrix}$$

$$A = \begin{bmatrix} |A - \lambda I| = \begin{bmatrix} |-\lambda| & 3 & 3 \\ |-\lambda| & -3| & -3 \\ |-\lambda| & -2| & -2| & (repeated) \end{bmatrix}$$

$$\lambda = \begin{bmatrix} |A - \lambda I| & -2| & -2| & (repeated) \end{bmatrix}$$
When $\lambda = 1$

When
$$\lambda = -2$$
 (repeated) ***

(A-NI) $\times = 0$ (repeated) **

(A-NI) $\times = 0$ (repeated) ***

(A-NI) $\times = 0$ (repeated) ***

(A-NI) $\times = 0$ (repeated) **

(A-N

$$A = \begin{bmatrix} 1 & -2 & 0 \\ -2 & 0 & 2 \end{bmatrix}$$

$$= \det \left(A - \begin{bmatrix} 1 & 0 \\ 0 & \lambda \end{bmatrix} \right) = \dots$$

$$= (-1)^{3} + 9\lambda = -\lambda (1)^{2} - 2 = -\lambda (1)^{3} + 3\lambda = -\lambda (1)^{3}$$

Example : Symmetric Case

 $\begin{bmatrix} 1 & -2 & 0 \\ -2 & 0 & 2 \\ 0 & 2 & -1 \end{bmatrix} \begin{bmatrix} \chi_1 \\ \chi_2 \\ \chi_3 \end{bmatrix} = 0 \qquad \cdots > \begin{bmatrix} 1 & -2 & 0 \\ 0 & 1 & -\frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} \chi_1 \\ \chi_2 \\ \chi_3 \end{bmatrix} = 0$ $\frac{1}{3} - 2 \frac{\pi}{3} = 0$ $\frac{1}{3} - 2 \frac{\pi}{3} = 0$ $\frac{1}{3} - 2 \frac{\pi}{3} = 0$

$$\begin{bmatrix} -2 & 0 & 2 \\ 0 & 2 & -1 \end{bmatrix} \begin{bmatrix} x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix}$$

I apareter

eigenvector = [1]

$$2g: \begin{cases} y_2 \\ y_3 \end{cases}$$
 $1^2 + \frac{1}{2^2 + 1^2}$
 $t=1$
 1

Nector $2x_1 = \begin{bmatrix} 2/3 \\ 1/3 \\ 2/3 \end{bmatrix}$

$$x_{3} = t , x_{1} = x_{2} = -2t , x_{2} = 2t$$

$$x_{2} = \begin{bmatrix} -2t \\ 2t \\ t \end{bmatrix} = t \begin{bmatrix} -2 \\ 2 \\ 1 \end{bmatrix}, t = 1 \begin{bmatrix} -2 \\ 2 \\ 1 \end{bmatrix}$$

$$x_{2} = \begin{bmatrix} -2/3 \\ 2/3 \end{bmatrix}$$

$$x_{3} = t , x_{2} = -2t , x_{2} = 2t$$

$$x_{4} = \begin{bmatrix} -2/3 \\ 2/3 \end{bmatrix}$$

$$x_{5} = t$$

$$x_{1} = x_{2} = -2t , x_{2} = 2t$$

$$x_{2} = \begin{bmatrix} -2/3 \\ 2/3 \end{bmatrix}$$

$$x_{3} = t$$

$$x_{4} = t$$

$$x_{2} = \begin{bmatrix} -2/3 \\ 2/3 \end{bmatrix}$$

$$x_{4} = t$$

$$x_{5} = t$$

$$x_{1} = x_{2} = -2t$$

$$x_{2} = t$$

$$x_{3} = t$$

$$x_{4} = t$$

$$x_{2} = t$$

$$x_{3} = t$$

$$x_{4} = t$$

$$x_{4} = t$$

$$x_{4} = t$$

$$x_{4} = t$$

$$x_{5} = t$$

$$P = \begin{bmatrix} 2/3 & -1/3 \\ 1/3 & 2/3 & -1/3 \\ 2/3 & 1/3 & 2/3 \\ 1/3 & 1/3 & 2/3 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/4 & 1/4 \\ 1/$$

If A (nxn) has $\lambda_1, \lambda_2, \dots \lambda_n$ eigenvalues. Find the eigenvalues and their Corresponding eigenvectors (1) A^{R} (3) A^{-1} k is a constant (iii) kA (iv) AT k is a socaler. (V) (A+kI)If. A. has eigenvalues, [10, 15,22] What about the eigenvalues B= A + 2A + A = 10I? 1:=10,15,22

Ans. (> + 2/2 + /2 - 10)

industion (1) A X; = N; Xi i=1,2,..., n k=1 A (NUXL) = $A^{(2)}$ $x_i =$ $\lambda_1 A = \lambda_1 (\lambda_1 x_1) = \lambda_2^2 x_1$ $AA^2 \times i = A(\lambda \tilde{i} \times i) = \lambda \tilde{i} A \times i = \tilde{\lambda} \tilde{j} \times i$ R= 3 (20) = X (20) R=n R= N+1 And = A An XI = Nin AXI = Ninti XR, XR, ..., Xn Matrix AR has aigenvalues sigenlectors (same as those of eigenvector

Oil) A' ?

$$A = X = X \times X$$
 $A' A = A' (X \times X)$
 $X = X = A' \times X$
 $X =$

(iii)
$$(kA)$$

$$A \leq i = \lambda i \leq i$$

$$kA \leq i = k(\lambda i \leq i)$$

$$(kA) \leq i = k(\lambda i \leq i)$$

$$(kA) \leq i = k(\lambda i \leq i)$$

$$kA \text{ has eigenvalues}$$

$$(k\lambda_i, k\lambda_2, \dots, k\lambda_n)$$

$$k \leq i \leq i$$

$$(k\lambda_i, k\lambda_2, \dots, k\lambda_n)$$

det(B) = det(BT) (iv) Hints. B XT carrot be eigenvector of AT Yz=Yz $\underline{x}^T A^T = \lambda \underline{x}^T$ $(A - \lambda I) = 0$ $\det (A - \lambda I) = 0 \qquad (\lambda - \lambda_1)(\lambda - \lambda_2) \cdot \cdot \cdot \cdot (\lambda - \lambda_n) = 0$ $\det (A - \lambda I)^T = 0 \longrightarrow \det (A - \lambda I) = 0$ (>(1-11)(1-12) --- (1-11)=0 A has the same set of eigenvalues as that of AT in general (unless AT = A), Xi will be, the same for AT)

— eigenvector

(V) (A+ RI) k is a scalar. $(A + kI)x_i = Ax_i + kx_i$ = Note + kxi (L+k) xi (A+kI) has eigenvalues (hitk, hatk, ..., hutk)

EX/ Q: If. A. has sigenvalues, .10. 15,22 What about the eigenvalues. of B= A+2A3+ A-10I? Ans (10 + 2 12 + 1 -10). Ex Book page 20-21 * 1,5,9,11,12,15,29,30.* Book: Maths for Engineering and Sciences City U, Prentice Hall. or other Engineering Mathe book.

Ex.2.

Q 1 A= (-5 = 0)
0 0-1

a). Find the eigenvalues and the corresponding eigenvectors of A.

b). Is the natrix X. diagonalizable, briefly explain.

B=PDP, Dis a diagonal watris Let B be a square matrix, if Show that $B^3 = PD^3 P^{-1}$.

Toly of As Howall