

Lecture September 25

Lanczos algorithm and
wrapping up Eigen value
discussions-

$A \in \mathbb{R}^{n \times n}$ ($\mathbb{C}^{n \times n}$), symmetric
 $x \in \mathbb{R}^n$ (\mathbb{C}^n)

$$\underline{Ax = \lambda x}$$

Direct methods-

+ Jacobi'

+ Householder

÷ QR transform

÷ SVD $A = U \Sigma V^\top$

$$UU^\top = U^\top U = \mathbb{I}$$

$$VV^\top = V^\top V = \mathbb{I}$$

$A \in \mathbb{R}^{n \times m}$

$U \in \mathbb{R}^{n \times n}$

$\Sigma \in \mathbb{R}^{n \times m}$

$V \in \mathbb{R}^{m \times m}$

$$[x \ x \ x \ x] = \begin{pmatrix} \cdot & \cdot & \cdot & \cdot \end{pmatrix}$$

$$A = \begin{bmatrix} * & * & * & * \\ * & * & * & * \\ * & * & * & * \\ * & * & * & * \end{bmatrix} \xrightarrow{SAS'} T = \begin{bmatrix} * & * & * & * \\ * & * & * & * \\ 0 & * & * & * \\ 0 & 0 & * & * \end{bmatrix}$$

Bisection

$$\rightarrow D = \text{diag}(\lambda_1, \lambda_2, \dots, \lambda_n)$$

$$n = 10^5 \Rightarrow A \sim 8 \text{ bytes} \times 10^{10} \sim 10^{11} \text{ bytes} \sim 100 \text{ Gb.}$$

Iterative methods:

$$T = Q^T A Q \quad Q^T Q = \mathbb{I}$$

$$= \begin{bmatrix} \alpha_1 \beta_1 & & & 0 \\ \beta_1 \alpha_2 \beta_2 & & & \\ 0 & \ddots & \ddots & \beta_{n-1} \\ & & \ddots & \beta_n \alpha_n \end{bmatrix}$$

$$Q = [q_1 \ q_2 \ \dots \ q_m]$$

column vector of Q

$$\langle q_i, q_j \rangle = q_i^T q_j = \delta_{ij}$$

$$Q^T Q^T A Q = \tilde{Q}^T \Rightarrow$$

$$AQ = QT$$

$$A [q_1 \ q_2 \ q_k \ q_n]$$

$$A q_k = \underline{\beta_{k-1}} q_{k-1} + \underline{\alpha_k} q_k + \underline{\beta_k} q_{k+1}$$

$$\beta_0 \cdot q_0 = 0$$

$$q_k^T A q_k = \alpha_k q_k^T q_k = \alpha_k$$

Define

$$r_k = (A - \alpha_k I) q_k - \beta_{k-1} q_{k-1}$$

$$q_k^2 = 1 \rightarrow q_{k+1} = r_k / \beta_k$$

$$\beta_k = \pm \|r_k\|_2 = \sqrt{\sum_i r_i^2}$$

$r_k = 0$, iteration meets down

Algorithm

Guesses: $\beta_0 = 1$ $q_0 = 0$ $k = 0$

while ($\beta_k \neq 0$) $r_0 = \text{random values}$

$$q_{k+1} = r_k / \beta_k$$

$$k = k + 1$$

$$\alpha_k = \frac{q_k^T A q_k}{(A q_k)} \quad (\underline{A q_k})$$

$$r_k = (A - \alpha_k I) \underline{q_k} - \beta_{k-1} q_{k-1}$$

$B_K = \|u_K\|_2$
end while

After ($A \in \mathbb{R}^{n \times n}$) n -
iterations we have the
full Tridiagonal matrix.
Lanczos' method converges
to the extreme values

λ_{\min} and λ_{\max}

why is this of interest for
Project 2? 2d+2e

- approx one: $A \in \mathbb{R}^{n \times n}$

$$= \begin{bmatrix} T & & \\ & T & \\ & & T \end{bmatrix}$$

λ_i depends on - n -

- approx two: $u(\infty) = 0$
replaced by
 $u(\underline{1}) = 0$

with Lanczos' method and
in short?

$\Gamma - \sigma \dots$
 suppose $n = 1000$
 use Lanczos' method
 iteratively and stop at
 $m = 100$

$$\begin{bmatrix} \alpha_1 & \beta_1 & & \\ \beta_1 & \alpha_2 & & \\ & \ddots & \ddots & \\ & & & \beta_{99} \\ & & & \alpha_{100} \end{bmatrix}$$

and diagonalize (Lanczos or
 Eigen/Arnoldi)
 look λ_{\min} (is lowest)

- project 2

$$\gamma = \frac{\alpha_{kk} - \alpha_{kk}}{2\alpha_{kk}} \quad \leftarrow \text{Jacobi Rotation}$$

$$\tan \theta = t \quad \alpha_{kk} \rightarrow 0$$

$$t^2 + 2\gamma t + 1 = 0$$

$$t = \frac{-\gamma \pm \sqrt{1 + \gamma^2}}{2} \quad \Leftarrow$$

$$\text{choose } t = -\gamma + \sqrt{1 + \gamma^2}$$

γ becomes large, $t \rightarrow 0$

$$t = \frac{(-\tau + \sqrt{1+\tau^2})(\tau + \sqrt{1+\tau^2})}{\tau + \sqrt{1+\tau^2}}$$

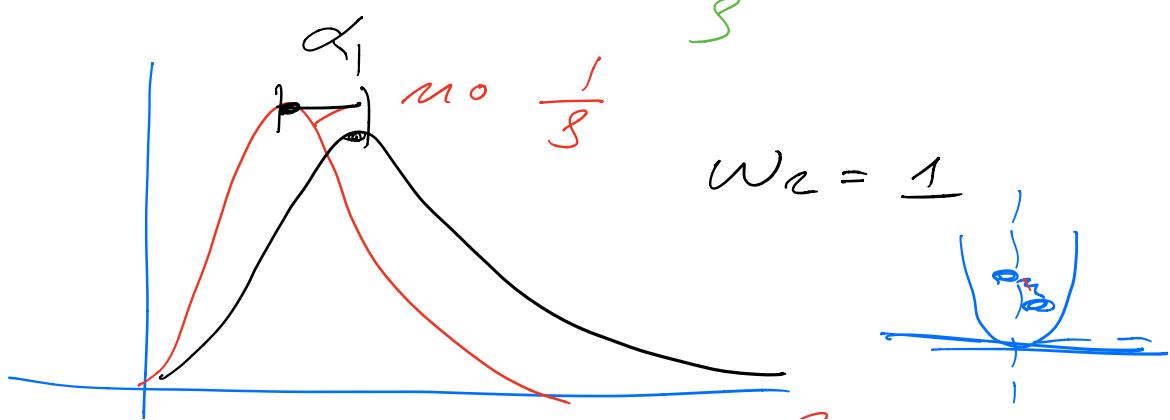
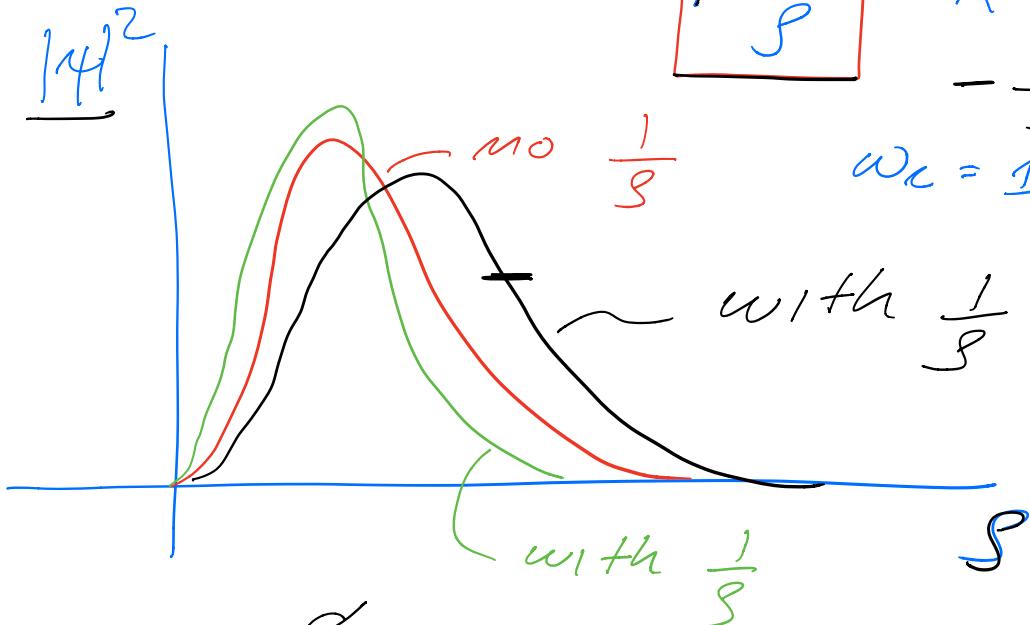
$$= \boxed{\frac{1}{\tau + \sqrt{1+\tau^2}}} \quad \leftarrow$$

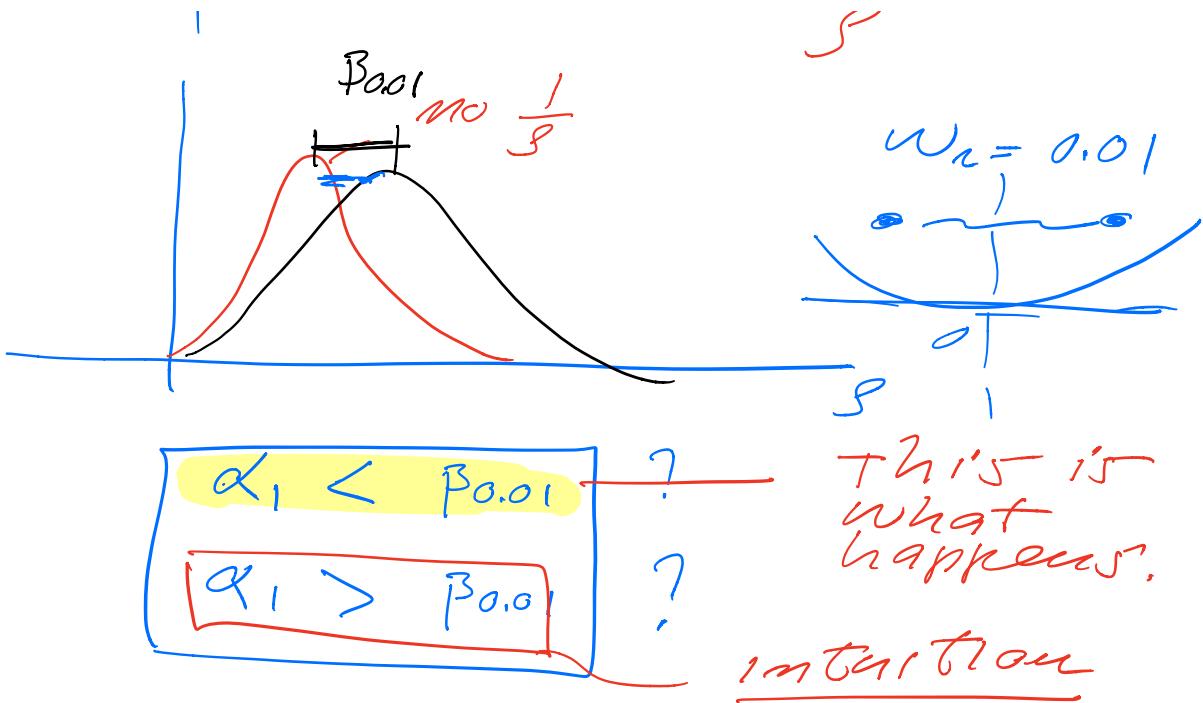
project 2e

$$-\frac{d^2}{ds^2} \psi(s) + \omega_n^2 s^2 \psi(s)$$

$$\boxed{+ \frac{1}{s}} = \lambda \psi(s)$$

$$-\frac{1}{s}$$





$\frac{1}{s}$ what is its range?
 s infinite range.

Harmonic oscillator:

$$E_0 = \hbar\omega \cdot 3/2 \quad \omega \rightarrow 0$$

$$E_0 \rightarrow 0$$

Term to the energy from the Coulomb interaction

$1/s$ becomes smaller at a slower pace than the harmonic oscillator, due the infinite range of

$1/s$.

$$\frac{e^{-\beta y}}{\beta}$$

Differential equations (ODE)

our most common type
of equations

$$\frac{d^2y(t)}{dt^2} = f(y, t, \frac{dy}{dt})$$

Redefine in terms of two
coupled first-order equations

$$v(t) = \frac{dy}{dt}$$

$$\begin{aligned} \frac{d^2y}{dt^2} &= \frac{d}{dt} v = f(y, t, \frac{dy}{dt}) \\ &= f(y, t, v(t)) \end{aligned}$$

$$\frac{dy}{dt} = v(t)$$

$$\frac{dv}{dt} = f(y, t, v)$$

to defines initial conditions
 $y(0) = \dots$

$$v(0) = v_0 \quad y(t_0) = y_0$$

Discretize: Define $t_{final} = t_m$
 $t_{initial} = t_0$

$$h = \frac{t_m - t_0}{n} = \text{step size}$$

$$t_i = t_0 + i \cdot h$$

Taylor-expand (derivatives
in p1 and p2)

Euler's forward formula for
derivative

$$\left. \frac{dy}{dt} \right|_{t_i} = \frac{y(t_{i+1}) - y(t_i)}{h} + o(h)$$

$$= \frac{y_{i+1} - y_i}{h} + o(h)$$

$$\left. \frac{dy}{dt} \right|_{t_i} = v(t_i) = v_i \approx \frac{y_{i+1} - y_i}{h}$$

$$y_{i+1} = y_i + h \cdot v_i$$

$$\left. \frac{dv}{dt} \right|_{t_i} \approx \frac{v_{i+1} - v_i}{h}$$

-

\Rightarrow

Define y_0 and v_0 (initialization)

for $i = 1 : n$

$$y_{i+1} = y_i + h \cdot v_i$$

$$v_{i+1} = v_i + h \cdot f(y_i, t_i, v_i)$$

$$= v_i + h \cdot f_i$$

end for,

Euler's forward method,
Explicit (all previous values
known)
scheme,

Euler's Backward method.
Implicit scheme (later),