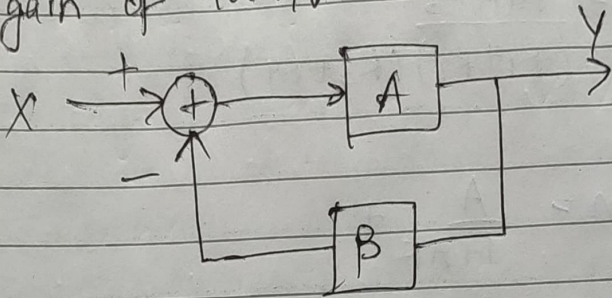


Assignment-5

Ques)

Consider a general feedback network with open loop gain of 1000 V/V and close loop gain of 100 V/V



- ① Find the tolerance in close loop gain if tolerance in open loop gain is 30%.

$$\therefore \Delta A \approx \Delta A_{OL} \quad \text{for } +30\%$$

$$A \approx 1300$$

$$\frac{A}{1+AB} = \frac{1300}{1+1300 \times B} \quad \text{--- (1)}$$

$$\frac{A}{1+AB} \approx 100$$

$$\frac{1000}{1+AB} \approx 100$$

$$1+AB \approx 10$$

$$AB \approx 9$$

$$\boxed{B \approx 9/1000}$$

② ~~the if 1.5% from ①~~

$$\frac{A'}{1+A'R} = \frac{1300}{1 + \frac{1300 \times 9}{1000}}$$

$$\frac{A'}{1+A'R} = 78.74$$

for -30%

$$\frac{700}{1 + \frac{9}{1000} \times 700} = 95.89\%$$

\therefore Tolerance of closed loop $= 21.28\%$

(ii)

$$\text{if } \frac{A}{1+A'R} = 10$$

$$\frac{1000}{1+1000R} = 10$$

$$1+1000R > 100$$

$$1000R = 99$$

$$R = \frac{99}{1000}$$

$$\frac{1300}{1 + \frac{1300 \times 99}{1000}} = \frac{13000}{13.15}$$

$$= 10.02\%$$

for $A = 700$

$$\frac{700}{1 + \frac{700 \times 99}{1000}} = 9.95$$

$$\text{Tolerance} = \frac{10 - 9.95}{10}$$

$$= 0.005 \%$$

(iii) when 2 stages are cascaded

$$\text{gain} = 10 \times 10 = 100 \text{ V/V} \quad \text{--- (1)}$$

Tolerance

$$= 0.005 \times 0.005$$

$$= \boxed{25 \times 10^{-5}} \text{ V/V} \quad \text{--- (2)}$$

Q.2

Problems 7.2 and 7.6 of Razavi's book

Problem 7.2

$$\overline{v_{in}^2} = 4kT \left[\frac{2}{3} \frac{1}{g_{m1}} + \frac{2}{3} \frac{(g_{m2})^2}{g_{m1}^2} \right]$$

$$\overline{v_{in}^2} = \sqrt{4kT \frac{2}{3}} \sqrt{\frac{1}{g_{m1}} + \frac{g_{m2}}{g_{m1}^2}}$$

$$\frac{g_{m2}}{g_{m1}^2} = \left(\frac{1}{5} \right)^2 \frac{1}{g_{m1}} \Rightarrow g_{m2} = \left(\frac{1}{5} \right)^2 g_{m1}$$

$$g_m = \frac{2I_D}{V_{GS} - V_T} \Rightarrow V_{GS} - V_T = \frac{2I_D}{g_m}$$

$$\begin{aligned} \text{Output swing} &= V_{DD} - (V_{GS1} - V_T) - |V_{GS2} - V_T| \\ &= V_{DD} - 2I_D \left[\frac{1}{g_{m1}} + \frac{1}{g_{m2}} \right] \end{aligned}$$

$$V_{DD} = 2.8V \left(\frac{1}{g_{m1}} \right) (1+s^2)$$

$$g_{m1} = \sqrt{2 I_D \mu_n C_{ox} \left(\frac{W}{L} \right)}$$

$$= \sqrt{2 (1 \text{ mA}) \left(134.28 \frac{\mu\text{A}}{\text{V}^2} \right) \left(\frac{50 \mu\text{m}}{0.54 \mu\text{m}} \right)}$$

$$\approx 1.906 \text{ mA/V}$$

$$\therefore \text{Output swing} = 3V - 2 (1 \text{ mA}) \left(\frac{1}{1.906 \text{ mA/V}} \right) \times (28) = \boxed{0.30V}$$

Problem 7.6

① $|A_v| = \frac{g_m R_D}{1 + g_m R_S}$

$$\overline{V_{n\text{out}}}^2 = 4kTR_D + 4kT \frac{2}{3} \left(\frac{1}{g_m} \right) \left(\frac{g_m R_D}{1 + g_m R_S} \right)^2 + 4kT \frac{1}{R_S} \left(\frac{R_S}{\frac{1}{g_m} + R_S} \right)^2 R_D^2$$

$$= 4kTR_D + 4kT \frac{2}{3} \frac{1}{g_m} \left(\frac{g_m R_D}{1 + g_m R_S} \right)^2 + 4kT R_S \left(\frac{g_m R_D}{1 + g_m R_S} \right)^2$$

$$\overline{V_{n\text{in}}}^2 = \frac{\overline{V_{n\text{out}}}^2}{|A_v|^2} = 4kT \frac{2}{3} \frac{1}{g_m} + 4kT R_S + 4kTR_D \left(\frac{1 + g_m R_S}{g_m R_D} \right)^2$$

② $|A_v| = g_m (g_m || R_S)$

$$\overline{V_{n,out}^2} = \left(4kT \frac{2}{3} g_m + 4kT \frac{1}{R_s} \right) \left(\frac{1}{g_m || R_s} \right)$$

$$\overline{V_{n,in}^2} = \frac{\overline{V_{n,out}^2}}{|A_v|^2} = 4kT \frac{2}{3} \frac{1}{g_m} + 4kT \frac{1}{g_m R_s}$$

① $|A_v| = \frac{g_m}{(g_m + 1/R_p) R_s} \cdot R_{out}$

$$R_{out} = R_s + (1 + g_m R_s) R_p$$

$$\overline{V_{n,out}^2} = \left(\frac{4kT \frac{2}{3} g_m}{\left((1 + g_m \frac{1}{R_p}) R_s \right)^2} + \frac{4kT \frac{1}{R_p}}{\left((1 + g_m \frac{1}{R_p}) R_s \right)^2} \right) R_{out}^2$$

$$\left(\frac{4kT \frac{1}{R_s} \times R_s^2}{R_s + \frac{1}{g_m || R_p}} \right) R_{out}^2$$

$$\overline{V_{n,in}^2} = \frac{\overline{V_{n,out}^2}}{|A_v|^2} = 4kT \left(\frac{2}{3} \frac{1}{g_m} + \frac{1}{g_m^2 R_p} + R_s \right) \left(1 + \frac{1}{g_m R_p} \right)^2$$

② $|A_v| = \frac{g_{m1}}{1 + g_{m1} R_s} \cdot R_{out}$

$$R_{out} = \frac{1}{g_{m2}}$$

$$\overline{V_{n,out}^2} = 4kT \frac{2}{3} g_{m1} R_{out}^2 + 4kT \frac{1}{3} g_{m1} R_{out}^2$$

$$+ 4kT \frac{1}{R_s} \left(\frac{R_s}{1 + \frac{R_s}{g_{m1} R_s}} \right)^2 R_{out}^2$$

$$\overline{V_{in}^2} = \frac{\overline{V_{out}^2}}{|A_v|^2} = 4kT \left[\frac{2}{3} \frac{1}{g_{m1}} + R_s + \frac{2}{3} g_{m2} \left(\frac{1+g_{m1}R_s}{g_{m1}} \right)^2 \right]$$

② $|A_v| = g_{m1} R_D$

$$\overline{V_{out}^2} = \left(4kT \frac{2}{3} g_{m1} + 4kT \frac{1}{R_D} \right) R_D^2$$

$$\overline{V_{in}^2} = \frac{\overline{V_{out}^2}}{|A_v|^2} = 4kT \left[\frac{2}{3} \frac{1}{g_{m1}} + \frac{1}{g_{m1}^2 R_D} \right]$$

③ $|A_v| = g_{m1} \left(\frac{g_{m2} R_s}{1+g_{m2} R_s} \right) R_D$

note: $\frac{R_s}{1/g_{m1} + R_s} = \frac{g_{m2} R_s}{1+g_{m2} R_s}$

$$\overline{V_{in}^2} = \frac{\overline{V_{out}^2}}{|A_v|^2} = 4kT \left[\frac{2}{3} \frac{1}{g_{m1}} + \frac{2}{3} \frac{1}{g_{m1}} \left(\frac{1}{g_{m1} R_s} + \frac{1}{g_{m1}^2 R_s} + \frac{1}{g_{m1}^2 R_D} \right) \left(\frac{1+g_{m2} R_s}{g_{m2} R_s} \right)^2 \right]$$

Ques 3 Short note on non-linearity in differential circuit

Ans 3 Non linearity

It is used to measure performance in Digital to analog converter (DAC) Analog to Digital converter (ADC).

It refers to constant relation between the change in output & input

$$DNL(i) = \frac{V_{out}(i+1) - V_{out}(i)}{\text{Ideal LSB step width}}$$

Ques 4 Problem 1.4 of Razavi's book

$$\left(\frac{W}{L}\right)_{1,0} = \frac{100}{0.5}$$

$$I_{D0} = 1 \text{ mA}$$

$$V_{D0} = 1.2 \text{ V}$$

$$r = 0$$

$$\begin{aligned} \textcircled{a} \quad V_{in,cmmin} &= V_{iss} + V_{th1} \\ &= V_{iss} + V_{thn} + V_{op1} \end{aligned}$$

$$V_{in,cmmax} = V_r + V_{th1}$$

$$V_r = V_{b1} - V_{DS3}$$

$$= V_{b1} - V_{th3} - V_{OD3}$$

$$V_{r, \text{cm max}} = V_{b1} - V_{OD3}$$

$$V_{r, \text{cm max}} = 1.7 - 0.159$$

$$= \boxed{1.541 \text{ V}}$$

(b) $V_{x2}?$

$$V_{GS2} = V_{thp} = \left[\frac{2 \rho_{D2}}{\mu_{p10X} \left(\frac{W}{L} \right)_2} \right]^{1/2}$$

$$= \left[\frac{2 (0.5 \text{ mA})}{100 \text{ A} (1 \times 3.6 \times 10^9) \left(\frac{100}{0.52} \right)} \right]^{1/2} = 0.209$$

$$V_{GS2} = 0.209 + V_{thp} = 1.009 \text{ V}$$

$$V_{x2} = V_{OD} - V_{GS2} = 3 - 1.009 \text{ V}$$

$$\boxed{V_{x2} = 1.911 \text{ V}}$$

(c) $V_{GS3} = V_{th3}$

$$V_{GS4} = 0.7 + 0.159 = 0.859 \text{ V}$$

$$\text{max o/p swing} = 0.7 - (0.859 - 0.7)$$

$$\boxed{\text{max o/p swing} = 0.541 \text{ V}}$$

(d) we know $V_x = 1.911V$
 $V_{GS} = V_{GS2} = 1.089V$
 $V_t < V_x + V_{thp}$ M4 is sat.
 $V_{b2} = V_t - |V_{GS}|$

$$V_{b2} < V_x + V_{thp} - |V_{GS}|$$

$$= 1.911V + 0.8 - 1.089$$

$$V_{b2} < 1.622V$$

$$V_{b2} > V_x - V_{th5} = 1.911 - 0.8$$

$$= V_{b2} > 1.111V$$

$$\boxed{1.111V < V_{b2} < 1.622V}$$

(e) $\overline{V_n^2}_{input} = 4kTR \frac{1}{g_{m12}}$
 $\overline{V_n^2}_{input} Mo = 4kTR \frac{g_{m10}}{g_{m12}}$

$$= \left[4kTR \left(\frac{1}{g_{m12}} + \frac{g_{m10}}{g_{m12}^2} \right) \right] \times 2$$

$$g_{m10} = \left(2(100)(3.03 \times 10^{-9}) \left(\frac{100}{0.32} \right) \right)$$

$$(0.5mA)$$

$$= 3.46 m\Omega^{-1}$$

input refer noise voltage $= 5.45 \times 10^{-6} V/\sqrt{Hz}$
 or $\boxed{2.34 \times 10^{-9} V/\sqrt{Hz}}$