

## Standard Motorshield Assignments: Channel A:

D12 - Direction D3 - PWM (work duty) D9 - Brake AO - current sensing.

### Channel B:

D13 - Direction D11 - PWM (work duty) D8 - Brake A1 - current sensing

DRV8874 Mode Select

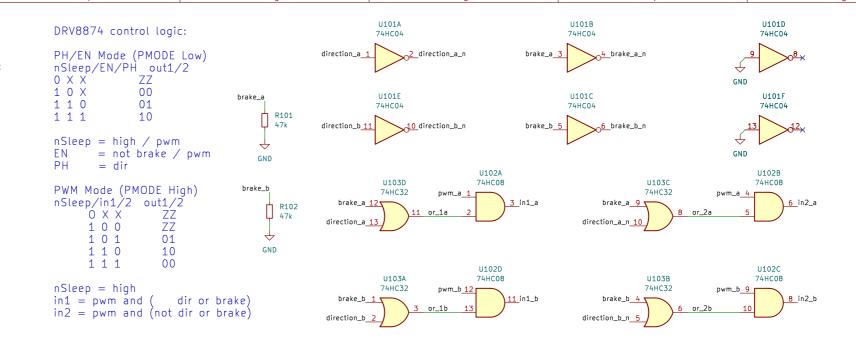
Jumper\_3

GND

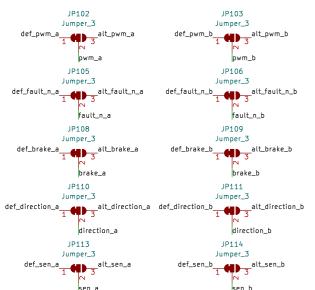
nmode

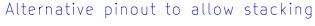
Low: EN/PH

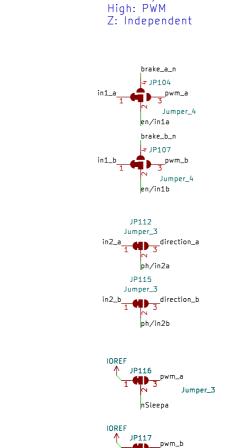
IOREF JP101



GND

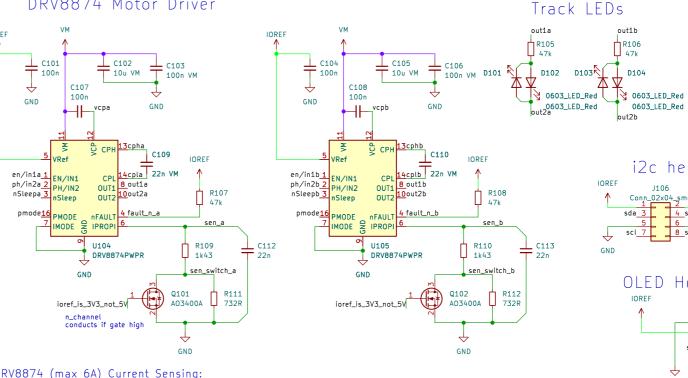


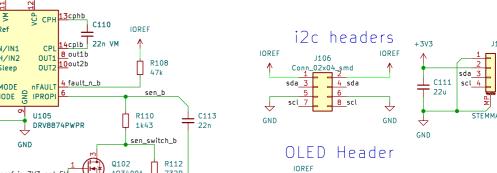




nSleepb

# DRV8874 Motor Driver



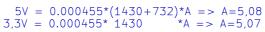


R106

D104

0603\_LED\_Red





if subbed with DRV8876 (max 3.5A): 5V = 0.001\*(x+y)\*A => A= 3.3V = 0.001\* x \*A => A \*A => A=

#### O FID101 Toolinghole\_jlc O FID102 Toolinghole\_jlc candidate values: 3.63/1.65 1% 2k+1k1k8+(680+220) 4.0/1.83 1% O FID103 Toolinghole\_jlc 1k5+(680+100) 4.8/2.2 0.2% O FID104 Fiducial

1k43+732(extend.) 5.08 0.1% <-- USED HERE (1k2+120)+680 5.5/2.5 0.0% 1k2+(470+180) 5.9/2.7 2% 1k2+620(extend.) 5.9/2.7 0.1% 1k1+560 (0603) 6.6/3.0 0.4%

# Power Sheet

GND

File: power.kicad\_sch

1 2 scl 3 sda 4 J107 Conn\_01x04\_f

Track Connector

out1a 1 J101 out2a 2 MC 1,5/ 2-G-3,5

out1b 1 J103 out2b 2 MC 1,5/ 2-G-3,5

out1a out2a J102

Licensed under CERN-OHL-W v2 or later

Engineer: Erwin Peterlin DCC-EX semify-eda.com

Sheet: / File: motor-shield.kicad\_sch

O FID105 Fiducial

O FID106 Fiducial

Title: EX-Motorshield8874 Size: A3 Date: 2023-02-23 KiCad E.D.A. kicad 7.0.1

# OpAmp as IORef Comparator

