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/*****
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package de.dakror.wseminar.graph.algorithm;

import static de.dakror.wseminar.util.Benchmark.Type.*;

import java.util.ArrayList;
import java.util.Collections;

import de.dakror.wseminar.Const.State;
import de.dakror.wseminar.graph.Edge;
import de.dakror.wseminar.graph.Graph;
import de.dakror.wseminar.graph.Path;
import de.dakror.wseminar.graph.Vertex;
import de.dakror.wseminar.graph.VertexData.InfPath;
import de.dakror.wseminar.graph.WeightedEdge;
import de.dakror.wseminar.graph.algorithm.base.PathFinder;
import de.dakror.wseminar.util.Benchmark.Type;
import de.dakror.wseminar.util.Visualizer;

/**
 * @author Maximilian Stark | Dakror
 */
public class Dijkstra<V> extends PathFinder<V> {
    ArrayList<Vertex<V>> list;

    public Dijkstra(Graph<Vertex<V>> graph, boolean animate) {
        super(graph, animate);

        list = new ArrayList<>();
        metaClasses = new Class<?>[] { InfPath.class };
    }

    @SuppressWarnings("unchecked")
    @Override
    public Path<Vertex<V>> findPath(Vertex<V> from, Vertex<V> to) {
        Visualizer.resetAll(graph, true, false);
        BM.time();

        for (Vertex<V> v : graph.getVertices()) {
            v.add(new InfPath<>());
            if (v.equals(from)) v.get(InfPath.class).d = 0;
            list.add(v);
        }
    }

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    BM.add(v);
    BM.add(OPEN_LIST_SIZE);
    Visualizer.setVertexState(v, State.OPENLIST, true);
};

boolean found = false;

Vertex<V> v = null;

while (!list.isEmpty()) {
    Collections.sort(list, (a, b) -> {
        int c = Float.compare(a.get(InfPath.class).d, b.get(InfPath.class).d);
        if (c == 0) return a.data().toString().compareTo(b.data().toString());
        return c;
    });
    BM.add(SORTS);
    v = list.remove(0);
    BM.sub(OPEN_LIST_SIZE);
    BM.add(CLOSED_LIST_SIZE);
    Visualizer.setVertexState(v, State.CLOSEDLIST, true);

    if (v.equals(to)) {
        found = true;
        break;
    }

    takeStep(null, v, to);
}

if (!found) return null;

Path<Vertex<V>> p = new Path<Vertex<V>>();
p.setUserData("Dijkstra" + (animate ? " anim" : "") + " " + from.data() + "->" +
to.data());

for (Edge<Vertex<V>> e : graph.getEdges()) {
    Visualizer.setEdgePath(e, false, false, false);
}

while (v != null) {
    p.add(0, v);

    if (v.get(InfPath.class).parent != null) {
        Visualizer.setEdgePath(graph.getEdge(v, v.get(InfPath.class).parent), true, true);
    }
    Visualizer.setVertexState(v, State.BACKTRACK, false);
    v = v.get(InfPath.class).parent;

    BM.add(PATH_CREATION);
}
p.calculateCost(graph);

p.setBenchmark(BM);

BM.time();
cleanup();

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Visualizer.resetAll(graph, true, false);

return p;
}

@SuppressWarnings("unchecked")
@Override
protected boolean takeStep(Vertex<V> parent, Vertex<V> node, Vertex<V> to) {
    for (Edge<Vertex<V>> e : graph.getEdges(node)) {
        Vertex<V> oe = e.getOtherEnd(node);
        BM.add(oe);
        if (list.contains(oe)) {
            float alt = node.get(InfPath.class).d + (e instanceof WeightedEdge ?
                ((WeightedEdge<Vertex<V>>) e).getWeight() : 1);
            if (alt < oe.get(InfPath.class).d) {
                oe.get(InfPath.class).d = alt;
                oe.get(InfPath.class).parent = node;
                Visualizer.setEdgePath(e, true, true);
                BM.add(Type.OVERRIDES);
            }
        }
    }
}

return false;
}
}
```