view_frames Result Recorded at time: 947.085 odom Broadcaster: /gazebo Average rate: 10.267 Hz Most recent transform: 947.045 (0.040 sec old) Buffer length: 3.701 sec robot_footprint Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (947.085 sec old) Buffer length: 0.000 sec chassis Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10.287 Hz Average rate: 10.287 Hz Most recent transform: 0.000 (947.085 sec old) Most recent transform: 0.000 (947.085 sec old) Most recent transform: 947.045 (0.040 sec old) Most recent transform: 947.045 (0.040 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 3.694 sec Buffer length: 3.694 sec hokuyo left_wheel right_wheel camera