Automatic Test Grading Using Image Processing And Machine Learning Techniques



Andries Petrus Smit 18183085

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STUDY LEADER: JA du Preez

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I would like to acknowledge my skripsie leader, JA du Preez, parents and the engineering class of 2017 for their kind contributing to this thesis.

Declaration

the work contained in this final year
I have not previously in its entirety
for a degree.
Date

Abstract

The aim of this research project is to develop software that can automatically grade tests, written by students. These tests are written on a special template. This template allows the software to extract the students intended answers, after it has been scanned into a digital form. The standard method used in these Optical Mark Recognition (OMR) software, is to allow a learner to specify answers by colouring in bubble grids. To correct a mistake, the previous answer bubbles must first be erased and new ones coloured in. This takes time and increases the probability that a learner might colour in bubbles incorrectly.

This research project tries to solve this problem by implementing additional software that eases the use of such a template. Using computer vision and two machine learning techniques, namely Artificial Neural Networks (ANN) and Probabilistic Graphical Models (PGM), a student can now answer questions using characters and bubbles. In the case of a student number the student does not need to colour in the bubbles at all. The software implemented in this project allows for a decreased time in filling in these templates and thus decreases the number of mistakes made. New methods like these thus allows OMR templates to more easily be incorporated into the traditional educational systems.

Uittreksel

Die doel van hierdie navorsings projek is om sagteware te ontwikkel wat automaties toetse, wat deur studente geskryf is, na te kan sien. Hierdie toetse word elkeen op 'n spesiale templaat geskryf. Die templaat laat die sagteware toe om die student se antwoord te vind nadat dit digitaal gekopieer is. Die standaard metode wat gebruik word in hierdie Optiesemerk-leser sagteware is om van inkleur rooster borrels gebruik te maak. Om 'n fout wat die student gemaak het regtemaak, moet die ou borrels eers uitgevee word and nuwe borrels ingekleur word. Hierdie prosses vat baie tyd en vermeeder die kanse dat 'n student die borrels verkeerd in kan vul. Die navorsingsprojek poog om hierdie probleem op te los deur addisionele sagteware te implementeer wat die gebruik van so 'n templaat vergemaklik. Met behulp van rekenaarvisie en twee masjienleertegnieke, naamlik Kunsmatige Neurale Netwerke en Probabilistiese Grafiese Modelle (PGM), kan 'n student nou vrae beantwoord deur karakters en borrels te gebruik. In die geval van 'n studentenommer hoef die student glad nie die borrels eers in te kleur nie. Die sagteware wat in hierdie projek gemplementeer word, veroorsaak 'n verminderde tyd in antwoorde inskryf en verminder dus die aantal foute wat gemaak word. Nuwe metodes soos hierdie kan dus help dat meer OMR sagteware in die tradisionele onderwysstelsels ingebring kan word.

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Nomenclature

Acronyms

ANN Artificial neural network

DCNN Deep convolutional neural network

DCNN Deep convolutional neural network

OCR Optical character recognition

OMR Optical mark recognition

PGM Probabilistic graphical model

Symbols

 w_i Weight value at index i.

 x_i Input value at index i.

Chapter 1

Introduction

As modern technology and machine learning techniques advances, it is important for the educational sector to also continuously advance their learning environment. This allows for an ever improving learning experience in and outside the classroom.

1.1 Problem background

In the recent years the Applied Mathematics Department of Stellenbosch Engineering, started observing a decrease of accuracy in grading of tutorial tests, done by a teaching assistants and demies. Students complain on a regular basis about correct answers being marked wrong or even that their answers were totally ignored. Further the assistants also takes a long time to grade these tests. To address this problem the Applied Mathematics department proposes to automate the process of grading these tutorial tests.

The head of the department wants a system that can analyse and grade tests written on a specific template. These answer sheets are handed out to the students to fill in their respective answers. The answer sheets are then scanned-in to create a digital copy. The system is tasked with automatically grading all these digital copies and transferring the graded results to a database.

The department has tried to use a basic version of this type of system in the past. Such a system only really becomes useful to the department if it can grade decimal values instead of only being able to grade multiple choice answers. Thus a template needs to be designed that allows students to answer with decimal valued answers. Another factor to consider is filling in those values must still be relatively easy. Thus students need to

have the freedom of quickly crossing out an answer instead of erasing it each time. In this research project the department sends weekly scanned in answer sheets, which needs to be graded and the results returned to them. The feedback from these weekly tutorial tests then acts as validation tests for the system. These tests are done in parallel with the development and expansion of the test grading software. For these reasons an agile development methodology is used to develop this software.

1.2 Problem statement

Given the problem background and stakeholders discussed in the previous section the problem to be solved can be formulated as

Develop and **implement** a automatic test grading system that will increase marking accuracy and decrease marking time on the grading of Applied Mathematics tutorial tests, written by students.

1.3 Project scope and assumptions

Initial discussions with the department revealed that a specific template can be used. This template allows the image processing software to more accurately determine what the student's intended answer is. The template consists of bubbles that can be filled in as well as blocks for handwritten digits, as seen in Figure 1.1. The focus of this project lies on processing the scanned in answer sheet written on the specific template. To use the template the student must fill in his/her student number and question answers in the designated character blocks. They are also required to fill in the bubble underneath each digit, corresponding to that specific digit. Additionally a bubble next to each question is provided if a negative sign is required. (Gebriuk dalk template wat nie scrubble of het nie?)

Any additional assumptions are specified at the appropriate times throughout this project. In the next section the project objectives is laid out.

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Figure 1.1: Automatic grading template 1.

1.4 Project objectives

The problem as stated in section 1.2, is addressed by pursuing the following objectives:

- 1. Do a literature study on the topics of Image Processing, Computer Vision and Character Recognition. Further a literature study on Neural Networks and Probabilistic Graphical models is also done.
- 2. Develop a software application to allow a user to grade a large number (approximately 1000) scanned in student tests automatically.
- 3. The software should providing precise and useful feedback. To do this every graded result will also include feedback on what questions the student answered incorrectly.
- 4. Upgrade the software to allow students to cross out answers over having to erase them.
- 5. Do a weekly validation experiment with the software, by grading tutorial test for the department. The results are then used as the student's grade for that test.
- 6. Use an agile development methodology to improving the software in parallel with the grading of weekly tests.
- 7. Add additional software using machine learning to improve the accuracy of the system in grading these test.
- 8. Add additional software that allows students to specify their student number only using characters, which makes the template easier to use.

The objectives are covered in different chapters in the report. Note that each objective (1–8) build on the objective(s) previously listed.

1.5 Research methodology

To complete the objectives listed in Section 1.4, a agile development methodology is used. The methodology consists of six different phases:

- 1. Identify a new feature or update that needs to be implemented into the software package.
- 2. Do a study on the existing methods to implement this new software.
- 3. Implement and integrate the new software with the current knowledge of the solution.
- 4. Test the software and observe if it is working as planned.
- 5. If the software is not working as planned, revisit steps 2-4 until the new software is working.
- 6. Use version control, in this case Git, to save the latest version of the software.

Next the structure and graphical overview of the software is presented.

1.6 Graphical overview of system

When thinking about the template, from a philosophical sense, it can be represented using 6 information nodes. These nodes are illustrated in Figure 1.2. The unnamed blocks indicate that information processing happens in these steps. The student has certain information he/she wants to portray on the paper. This includes the 4 answers and student number he/she wants to write down. Thus those 5 nodes gives rise to the image, representing the last node. These nodes have to be represented in a probabilistic way. The reason for this is, because the process of writing answers down and scanning the test sheet in is going to produce a different image every time a test is written, even though the same answers are intended. Thus the system is fundamentally tasked with inferring the probability of each answer and the student's number given that image as evidence. This is done by processing the image evidence to produce and estimate of the intended answers. These processes are described in later sections. In the next section a literature study on current systems is discussed.

For a more detailed mathematical overview of the system, refer to Appendix C.

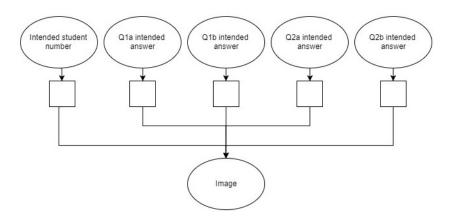


Figure 1.2: Graphical overview of the system as a whole.

Chapter 2

Literature Study

In the previous chapter the problem statement and objectives of this project was laid out. Further a brief system overview is also provided. This chapter will provide information about already existing Optical Mark Recognition(OMR) systems and the techniques they use in doing image processing on images. Research on additional machine learning approaches used in character recognition and probabilistic modelling is also described.

2.1 Existing OMR techniques

A OMR system is a piece of software that is used to extracted hand written information from a filled in form. Each system normally has a specific template that it can extract information from. An example template is shown in Figure 2.1. These systems are generally used when fast and accurate grading of tests are needed. The biggest drawback of these systems are that information can only be portrayed in a very limited manner, due to the bubbles. On OMR templates there are a grid of bubbles that allows a user to cohose between different options to answer. OMR systems are thus excellent for the grading multiple choice type questions.

2.1.1 Standard OMR systems

As can be seen in Figure 2.1, there is normally specific reference blocks on a OMR template. These blocks are included to allow the computer vision and image processing

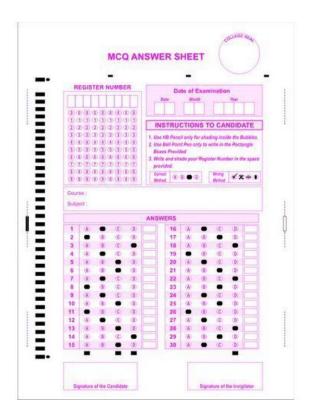


Figure 2.1: Standard OMR template with reference blocks on the left, from VijayaForm (2017)

algorithms find the orientation of the image more easily. Other templates include lines that can be used to locate the template.

In an OMR system there are normally two phases in the grading of an test, as stated in Ivetic & Dragan (2003). The first step is to determine the grid within where the answers are located in the image. In this process the system finds the orientation of the template in the image and thus can approximate the location of the use of colour in bubbles. Normally some preprocessing on a blank template is done beforehand too aid in locating the bubbles. Once the bubbles are found their estimated locations gets stored. The second step is then to estimate the value each bubble and use these values as the estimated answers. These steps is described in more detail next.

2.1.2 Finding the template

The first process performed by OMR software is to locate a template grid inside the test image. This step is necessary for the software to know which bubble corresponds with each answer. One method of locating the template is looking for lines in the template. This border normally contains long lines that can be extracted using a Hough transform, as stated in Patel & Prajapati (2003). A Hough transform is used to locate instances of an imperfect object within a certain shape range. A specific form of a Hough transform can be implemented to detect lines. This form is called a Radon transform, as described in MathWorks. A Radon transform provides a way of representing a image as a summation of different line integrations, as is discussed again in Section 3.1.2.

Once a atleast two line references on a page has been found the template orientation can be determined. This is done by using those lines two find two reference points on a page. These points allows the system to estimate the locations of every bubble on the template sheet. In the next section a method to process these bubble is described.

2.1.3 Processing a bubble

Now that a estimated location for each bubble is known, the next step for a OMR system is to process this bubble. As stated in Patel & Prajapati (2003), a basic image processing method to clasify bubbles is to simple count up the number of coloured in pixels. If this value is above a threshold value the bubble is classfied as filled in, otherwise not. A better algorithm is needed if there needs to be detected if a bubble is crossed out.

To determine if an answer in a bubble is truly coloured in and not just crossed out, contour detection is needed. This means that the contour around the bubble needs to be detected and used in analysis. In python(or C) this can be implemented using the freely available OpenCV library, as described in Rosebrock (2016). OpenCV is an image processing library that has highly optimized techniques to find contours in a given image. An example of this can be seen in Figure 2.2 Give contour information the bubbles can be assessed by the pixels inside it, as well as its shape. Thus by looking at the shape of a contour it can be determined if a bubble is crossed out or not. (Verander die image dalk na een wat 'n contour om het)

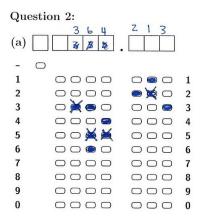


Figure 2.2: Corrected answer by crossing out bubbles.

2.2 Optical character recognition

To further increase the accuracy of the system, Optical Character Recognition (OCR) software will also be need and applied on the characters blocks, present on the templates. It is found that one preferred way of doing OCR is using TensorFlow. This method is described in Google (2017). TensorFlow is also a python library, but allows the build of instructions to be implemented in efficient c++ code. For this test grader, TensorFlow is used to construct a deep convolutional neural network(DCNN). DCNN is a powerful machine learning technique used to process images. One effective application of DCNN are that they are excellent at processing an image with a digit in and estimating that digit.

2.2.1 Probabilistic approach

A last piece of information that needs to be investigate is how the bubble and character evidence can be brought together in a effective way to produced the best estimate of the intended student entries. Once an bubble and character is analysed an probabilistic value is assigned it that it. Each bubble has a probability of being filled in, while each character has a probability of representing each of 10 digits. Top predict a final answer a probabilistic model is needed. In Ankan & Panda (2015), a machine learning approach is used to infer a probability a random variable being in a certain state given evidence. This method is known as a Probabilistic Graphical Model(PGM). A PGM is a probabilistic

framework that consist of a graph that specifies the probabilistic relationship between a number of random variables. These type of models works well in some aspects of a medical field. If a patient has certain simptomes a PGM can be used to predict what the underlining illness behind the decease is. Applying this method to this project a PGM can be used to estimate the underling student entries given the evidence presented. The library used in Ankan & Panda (2015) is called pgmPy. This library allows for a PGM to be constructed in python.

2.3 Conclusion: System requirements

In conclusion it is seen that a combination of image processing and machine learning techniques is needed to successfully grade a student test paper. A good method in locating a template is using a Radon transform to find reference lines in an image. Once this is done the bubbles can be estimate in the image. Too classified the digits it is found that a DCNN can be implemented in the TensorFlow library space. Once all these evidence are acquired a it was found that Probabilistic Graphical Model can be a good way to predict the final entry answer of the student. In Chapter 3 a more detailed overview on the image processing techniques used in this project is given.

Chapter 3

Image Processing

The previous chapter focused on existing methods of grading tests automatically. It was found that most systems only use image processing, without a machine learning component, to grade these test. In this chapter the core techniques behind processing these answer sheets, using image processing, is described. By using only these image processing techniques a reasonably accurate system can already be constructed.

For further improvements in accuracy we will investigate and implement two machine learning approaches. These approaches are discussed in Chapter 4.

3.1 Orientation Detection

As mentioned in Section 2.1.1 there are two main steps in OMR grading. The first challenge with grading a scanned in answer sheet, is finding the orientation of the template in the image. To do this there 2 or more references points must be found on the page. These reference points then allows for the calculation of the template's rotation, offset and size inside the image. In Chapter 2 it was determined that the traditional way to to find this reference points was to include them on the page, in forms of black blocks. This is an effective method of finding the template, but might look a bit less attractive, due to the black blocks on the page.

For this project the markers, reference points, that the software uses are already present on the template paper. These are the two longest horizontal lines as well as the two vertical lines on the comment box, as can be seen in Figure 3.1. Together these lines have enough information to determine 4 reference points, shown in red in the figure.

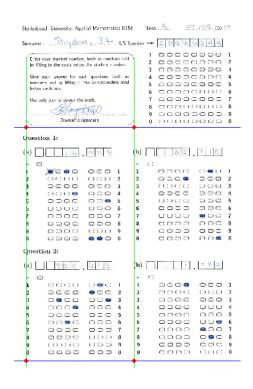


Figure 3.1: Four markers found from applying Radon transforms.

The reason these lines are chosen as references, are due to the fact that a Radon transform can easily be applied to find them, as seen in Section 3.1.2. Thus the software can successfully find the template even though one of the 4 lines are identified incorrectly. Using the reference points the rotation, offset and size of the template is calculated. But before the orientation of the image can be determined it is a good idea to quickly check if the image might be upside down. This is done to make it easier to find the orientation afterwards. To do this some initial image filtering is firstly required and is discussed in the next section.

3.1.1 Initial filtering and orientation detection

To check if and image is upside down the software first needs to find relevant contours on the page. The contours are then filtered out if it does not loosely match the characteristics of a bubble or character block. This is done in 5 steps:

- 1. Threshold the image by making all the pixel values either white (lower that the mean) or black (higher that the mean)
- 2. Do contour analysis on the image to find all the contours, using the python library OpenCV.
- 3. Filter through the contour array to filter out all contours that are not approximately the size and aspect ratios desired.
- 4. Save these contours for later use.
- 5. Determine if more contours lie above the middle of the image. This is true if the image is the right way around. Rotate the image by 180° otherwise.

It is important to note that there are still unwanted contours in the list, but for now this reduced list is sufficient. Once the list is found the software counts the number of contour centrepoints below and above the image center. Figure 3.2 shows the resulting contours found in the image. As can be seen in the figure more bubbles should be below the horizontal center line, for the image to be the right side up. The next step will now be to determine the coordinates of the answers the student wrote down. To do this the template is first located in the image. This process is described in Section 3.1.2.

3.1.2 Radon Transform

(Maak 'n symbols page) The Radon transform is an integral transform that can be represented by a series of line integrals over a function f(x, y). These transforms are commonly used in CT scans. Mathematically this transform is defined as

$$G(r,\theta) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x,y)\delta(x\cos(\theta) + y\sin(\theta) - r)dxdy.$$

Where r represents the perpendicular offset of the line and θ the angle of the line. x and y represents a 2D space within which the function f(x, y) is defined. A visual interpretation of this transform can be seen in Figure 3.3.

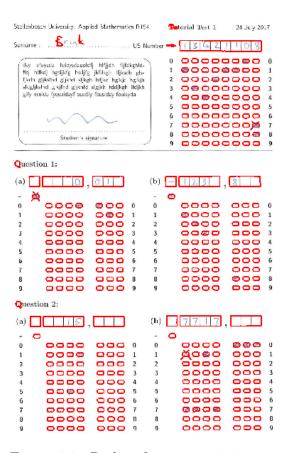


Figure 3.2: Reduced contours in image.

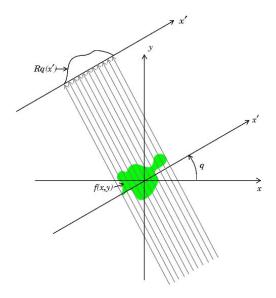


Figure 3.3: Radon transform applied on a 2 dimensional area, from Edoras (2017)

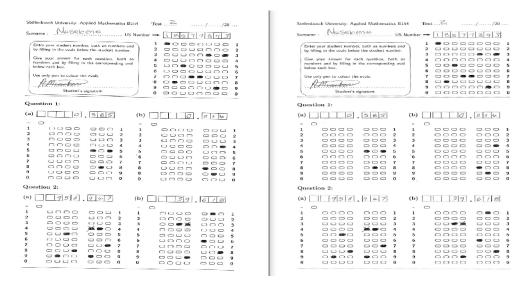


Figure 3.4: Result in rotation after applying radon transform.

3.1.3 Finding the template

In this project a Radon transform is calculated at specific intervals of the gradient. Each gradient interval will thus generate a 1 dimensional array of values corresponding with the pixel intensities along the lines that are being summed, as seen in Figure 3.3. This method is used determine where the 2 horizontal and 2 vertical lines are located, as mentioned in Section 3.1.

To find the first two horizontal lines the Radon transform is applied at a angle of 90° and then incremented by a small amounts for the next transform. Black lines will cause a spike to appear on the Radon transform when it is summing parallel with that black line. Thus by finding the transform angle value that present this maximum value. The rotation of the template can be found. The two maximum values that is recorded at this angle is can then be interpreted as the locations of the two horizontal lines. After the correct angle is found the two vertical lines can be found by applying a Radon transform at a angle 90° clockwise from the previously calculated angle. Those two values then provides the relative locations of the two vertical lines. Now the four reference point shown in Figure 3.1 can be calculated. Once the reference points are found the image is rescaled and orientated to the original template size and orientation for further processing. In Figure 3.4 the corrected image is shown, before it gets processed.

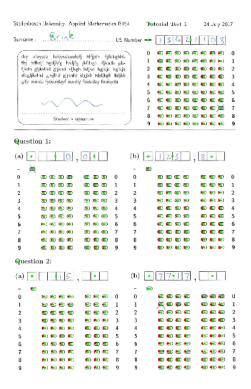


Figure 3.5: Detection of template in image and estimation of bubble locations.

Once the template is found the bubble values and digit blocks can be determined, using reference location. These reference locations were calculated in preprocessing done on an empty template. Figure 3.5 illustrates the final estimation of all the bubbles in the template. The estimated bubble centres are coloured red, while the green points represent the centres of all the remaining contours.

Now that all a list of possible bubble contours are found, the next challenge is to find one contour for each bubble. This is discussed in the next section.

3.2 Bubble detection and processing

To find the location of each bubble in the image, the system simply takes the contour closest to the estimated bubble location. This can be done in an efficient manner by sorting the contours by their locations. Searching through the contours now becomes linear and of complexity O(n), where n is the number of bubbles. This means that the processing time to find these bubbles is linearly related to the number of bubbles in the

template image.

Next the data in each contour needs to be processed and stored. The first type of evidence is calculating the average pixel intensity inside the contours. If this value is high the bubble is most likely coloured in or crossed out. The advantage of using the closest contour as the bubble's estimated location, over conventional methods now becomes apparent. In conventional methods an estimated area is calculated where the bubble is most likely to be located. This becomes problematic if the system needs to know if the bubble has been crossed out, as only data about pixel intensities are present.

Using contour analysis, information about the shape of the bubble entry is also provided. Thus by drawing the smallest possible block around the contour, that still covers every value inside the contour, an area can be calculated. This area becomes large when a answer is crossed out, due to the lines stretching outside the initial bubble. By inspecting the area value, the system can successfully determine if the bubble is filled in and crossed out.

3.3 Data processing and grading

The previous section now allows each bubble to be classified into 3 categories namely, empty, completely filled in and crossed out. An additional category of partially filled in will also be introduced, as it aids grading of tests where students write lightly. An algorithm to determine what bubble was chosen can now be described as follows:

- 1. Count the number of completely filled in answers in each column. Store the position of that entry for later use.
- 2. If there are no completely filled in answers, count the amount of partially filled in answers and override the previous values.
- 3. If the previous result is 0, set the output value for that column to 0.
- 4. If step 2 or 3 presents a value greater that 1, save the answer sheet to a clashlist to be evaluated manually once the automatic grading of the test are completed.

3.4 Conclusion

This chapter provided an overview of a basic automatic test grading system using image processing and computer vision. The system can achieve acceptable results using only these techniques.

The following chapter will focus on applying additional machine learning techniques to further improve the accuracy of grading these test. Two new test templates will also be introduced. (maak seker jy het daaroor gepraat).

Chapter 4

Machine learning approach

The previous chapter briefly described the basic workings of the optical mark recognition (OCR) system inside the automatic test grader. There is still one critical piece of evidence that has not been used with the basic system. This information is the characters that the student writes in the designated boxes.

This next chapter will provide two machine learning approaches to significantly improve the accuracy in identifying digits over the previous standalone basic system, discussed in Chapter 3. An approach to locate and classify hand written characters, provided by the students, using a deep convolutional neural network (DCNN), is firstly described. Next a more accurate method in determining the true digit, student answers and student number, using probabilistic graphical models (PGM), is discussed. This PGM method is found to be accurate enough to determine the student number by only using the character recognition information provided.

4.1 Character recognition using a neural network

4.1.1 Summary

In Chapter 3 only the bubble evidence is considered when estimating what digits the student wrote down. In this section another piece of information is going to be processed to further increase the accuracy of this system. This information is the characters that the students write down in the designated boxes, as shown in Figure 4.1. To process these digits a machine learning approach, called a neural network, is implemented. Once

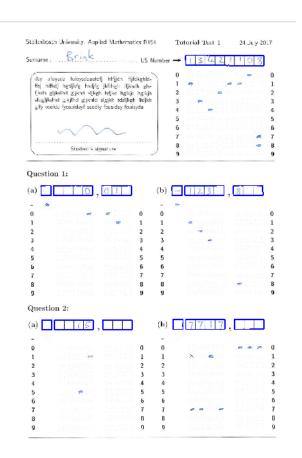


Figure 4.1: Image showing found contours for boxes used for character recognition.

the test sheet is processed all the character digits can be found. A 28 by 28 digit image is then created for each character found on the page. An example of this is shown in Figure 4.2.

A neural network then processes these digit images and produces an estimate to what digits are most likely to be present in each image.

4.1.2 Preprocessing to find individual digit image

Before each digit can be classified using a neural network, the individual 28 by 28 pixel digits must first be found inside the test sheet. To do this image processing is required. This is done in 6 steps as seen below:

1. Find the contour closest to the expected location of the block, calculated in Section



Figure 4.2: Example image found by doing image processing in main test sheet.

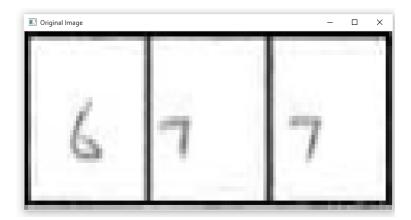


Figure 4.3: The box contour found is normalized to form a rectangular shape.

- 3.1.3. This is illustrated in Figure 4.1. The bubbles was already extracted out of the image where they were processed.
- 2. Transform the image to become fully rectangular using OpenCv's four_point_transform method. This method applies a four point perspective transform on the image to reshape it into a rectangular form. An example of the final product can be seen in Figure 4.3.
- 3. Do a horizontal and vertical Radon transform to find and remove the dark box lines on the image, as seen in Figure 4.4. The mathematics behind a Radon transform is described in Section 3.1.2.
- 4. Use the values received from the Radon transform to segment the image into the different boxes.

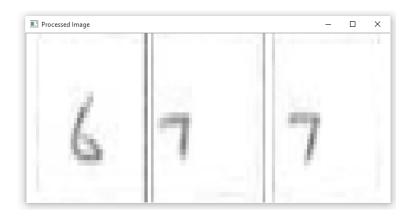


Figure 4.4: Box after black lines gets filtered out, found using a Radon transform.



Figure 4.5: Custom segmentation algorithm used to find the main cluster in the remaining image.

- 5. Using a custom segmentation algorithm to find the pixels most likely to belong to the digit. This algorithm is developed and implemented using breath first search technique to cluster the image into different segments. The algorithm works by first searching the image for pixels higher that a threshold value. This value specifies if an pixel is background or belongs to an image segment. Then all the pixels higher that the threshold value gets assigned to a segment. A segment is thus classified as a local region that does not connect to any other segment through pixels higher that a threshold. The segment that most likely represents the digit is then extracted, as seen in Figure 4.5.
- 6. The area that the segment occupies then gets calculated, as seen in Figure 4.6
- 7. Next the image is centred and normalized using the image area as reference. This



Figure 4.6: Area block drawn around segment most probable to belong to the digit.



Figure 4.7: Image after final translation and normalization is applied.

is seen in Figure 4.7

8. The image is then reshaped into a 28 by 28 greyscalled image to be processed by the neural network.

Each digit on the test sheet is now separated and can be used as input to an neural network. An overview of this neural network will be given next.

4.1.3 Neural Network Classification

4.1.3.1 Introduction

A neural network is a powerful machine learning tool for approximating complex functions. The basic architecture of a neural network can be seen in Figure 4.8. A artificial neural network (ANN) consist of an input, hidden and output layer, as described in Nielsen (2015). A neural network is a simplified approximation of how neurons in the brain works. Each neuron in the network acts as a small processing unit. With a initial

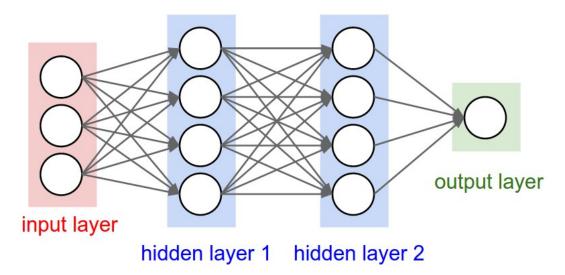


Figure 4.8: Basic structure of a neural network, from Karpathy (2017)

input, an output is determined by measuring the last output node, as seen in the Figure. The output can only be determined once each layer have been calculated one after the other.

For this project, a neural network is trained to estimate the probability of which of the 10 digits, from 0 to 9, are most likely present in the input image. The neural network will take a 2 dimensional array, representing a greyscaled image, as input to the network. Figure 4.9 illustrates an example input of a neural network using and 14 by 14 example image.

For this project a 28 by 28 greyscalled image is used as input. Thus if each pixel represents one value, ranging from 0.0 to 1.0, there is total of 748 input values. The basic workings of a neural network is described in the next section.

4.1.3.2 The artificial neuron

The neuron unit is the small processing unit used to build a neural network. The first step in calculating the output of a neural network is to find the weighted sum of the inputs. All the variables in this network are floating point values. A bias variable is added to allow a neuron to have an offset in its output. The weighted sum of these

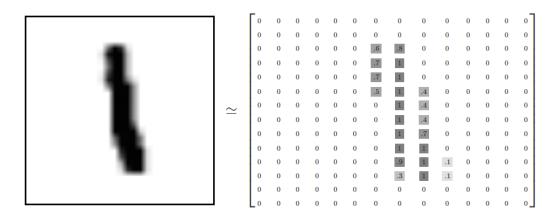


Figure 4.9: Example image used as input to the neural network, from Tensorflow (2017)

inputs are added with a bias variable to give,

$$z = \sum_{i=0}^{c} x_i * w_i + b. \tag{4.1}$$

Where c is the number of inputs. x_i and w_i respectively are the input and weight values at index i. b is the biased that enables and offset in the output(z) of the neuron.

The summed value then gets normalize using an sigmoid function, seen in Equation 4.2.

$$\sigma(z) = \frac{1}{1 + e^{-z}} \tag{4.2}$$

This artificial neuron thus basically takes in a weighted input with a bais and produces a normalized output sigma(z). By adjusting the weights and bais variable, each neuron can learn to exhibit certain characteristics. This process thus allows different functions to be approximated by changing these weights. If a network of these neurons is used together, as shown in Figure 4.8, complex functions can be trained onto the network. In the case of this project these weights and biases needs to be set to specific values, to allow the network to best categorize digits from an image. To do this these weights and biases will be trained form training data, as seen in Section 4.1.3.4.

4.1.3.3 Generating output from an neural network

After the 748 input values have been assigned to the network inputs, each of the network's layers can be calculated consecutively one after another. The first coulomb in the hidden layer will thus use the 748 input values and produce a normalize output for each of the neurons in that coulomb. This is done using using the previously mentioned equations 4.1 and 4.2. Once the first layers's outputs are calculated the next layer can be calculated. This process is repeated until all the layers are calculated in the hidden section. The output layer is then calculated using the same method. For the character recognition in the test grader, 10 output neurons are used, corresponding to the probability of the 10 digits being present. The values observed on the output neurons, gets normalized and used as the probability of each digit being present, using

$$p(i) = \frac{\sigma(z_i)}{\sum_{k=0}^{10} \sigma(z_k)}.$$
 (4.3)

Where p(i) is the probability of digit i being the character in the image. The value $\sigma(z_i)$ is the output of the output neuron at index i.

For a more detailed explanation on the DCNN used in this project, refer to Appendix D.1. (Maak dit dalk dat die neural network in overview hier beskryf word. Soos hoe dit werk as a black box. En dan Verder word die wiskunde agter NN and DCNN agter in die appedix beskryf)

By: For a mathematical description on neural networks and DCNN, refere to Appendix D.1.

4.1.3.4 Training of neural network

To train a neural network the MNIST dataset is used. This is a database that has a labelled training set of 60,000 images, and a labelled test set of 10,000 images. Each image has an accompanied label that specifies what digit is in the picture. The neural network is trained by using this training set, to adjust its internal weights and bias variables to more closely represent the labelled training data. The basic idea behind the training method used in a neural network is described in the following steps. For a more detailed description refer to Appendix D.

1. Calculate the network's output for each of the training images used in this training round.

- 2. Get the error margin of the network, using a formula that compares the true label of the training image, with the estimated label of the network.
- 3. Calculate the value with which each weight should be changed to reduce the error margin. One method of doing this is using the gradient decent with back propagation algorithms.
- 4. Repeat steps 1-3 until a time or accuracy criteria is met.

classified by the neural network. The new character recognition evidence can now be used in combination with the bubble evidence to make a significantly more accurate estimate for the intended answers from the student. The next step is thus to combine all these individual evidence, in a intelligence way, to make a accurate prediction. A method to achieve this result is described the next section.

4.2 Probabilistic Graphical Models

The final step in determining the students answers is to probabilistically determining the most likely answers, given the bubble and character evidence presented. To do this 3 probabilistic graphical models (PGM) are implemented.

4.2.1 Overview

For this project a graphical approach is followed in representing the software developed. A graphical model in essence allows software to be represented as information (nodes or circles) and relationships (directed arrows). The directions of the arrows represents what information causes other information to be created, thus given a parent to offspring interpretation). An example of such a graph can again be seen in Figure 4.10. These graphs allows for intuitive reasoning about how the system should operate. For this project an observation is made in the form of an image which is used as evidence. The system is then tasked with predicting what the written entries are given this information. Due to the probabilistic nature of the system a probabilistic component is also needed in this graphical models. Thus a probabilistic graphical model (PGM) is used.

A probabilistic graphical model (PGM) is a probabilistic graph containing random variables, where the graph expresses the conditional independence structure between

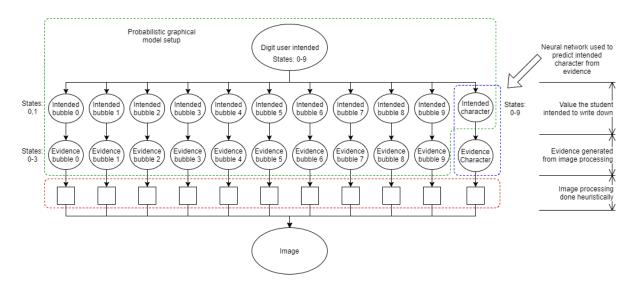


Figure 4.10: Graphical setup for determining the intended digit written by a student.

these variables. The type of PGM used for this project is a Bayesian network. A Bayesian network models a set of random variables and their conditional dependencies via a directed acyclic graph (DAG). As seen in Figure 4.10, arrows are used to indicate which variables are conditionally dependent on others.

4.2.2 Intended digit model

4.2.2.1 Structure of the graph

The figure should be interpreted in the direction which information flows. Originally a student has a certain digit that he/she wants to portray on the page. This is given by the 'Digit user intended bubble'. There are 10 possible digits to consider and thus the bubble has 10 possible states. The intended digit gives rise to the intended bubbles and character that the student wants to write down. The student might sometimes mistakenly think that the first bubble represents 0 and thus even if the intended digit is 0 the intended bubble might be 1. Thus, this must also be done in a probabilistic manner to compensate for this uncertainty. The intended bubbles and character then produces evidence, as seen in Figure 4.10.

When looking at Figure 4.11, it is observed that there are 11 evidence areas to consider. They are the 10 bubbles and the character block. The process of writing down



Figure 4.11: Column with the evidence that gets considered for the calculation of an intended digit.

this digit introduces so noise into the system, due to the fact the student is not always going to write down the digit in exactly the same way. Thus the evidence is also probabilistically linked to the 'intended bubble' and 'intended character' parent distribution. This evidence then gets written down on the paper and is what ultimately influences how the image looks. Each of the bubbles can take one of 4 states as evidence. These states are blank, crossed-out, partially coloured in and fully coloured in. The character block evidence is a 28 by 28 greyscale image. Thus it can have 28*28*256 possible states, where 256 is the possible pixel intensities of each pixel. This value with true range 0 to 256, gets converted into a normalized value between 0.0 and 1.0 before it gets assigned as inputs to the neural network.

4.2.2.2 Estimating the intended digit

After the model is constructed the intended digit needs to be estimated, with the image as evidence. This can be done by reasoning from the bottom (image evidence) upwards to the intended digit. The first step is to process the image, using of image processing, to produce more tractable evidence. Producing the bubble evidence from the image is described in Chapter 3. In Section 4.1.2, the process to extract the character evidence from the image is also described. Using the neural network the probability of intended character, given the character box, can be determined. After these steps is completed the intended digit can be estimated using the PGM. This is done by first setting the evidence node to the values calculated when image processing were done on them. The 'intended character' node then gets set to prior calculated through the use of the neural

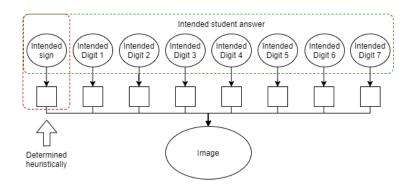


Figure 4.12: Graphical setup of determining student answer.

network. After this is done inference is done on the PGM and the resulting probability of each digit is calculated for the 'intended digit node'. The PGM structure can again be seen in Figure 4.10.

4.2.3 Intended answer model

4.2.3.1 Structure of the graph

There are 8 possible columns to use for an answer. The first column represents the sign of an answer. Thus two signs are possible. For each of the remaining 7 columns a number from 0 - 9 can be represented. Thus there are ten possible values for each column. This gives a possible number of values that a answer can take to be $2*10^7 = 20000000$. Each of these states needs to be calculated and becomes computationally intractable. Thus a assumption is needed to reduce the number of possible states. A fair assumption to make, is that all 20000000 possible values are equally likely to be written down. Thus each column digit becomes independent of the another columns values. This means that if a value in one column is known, it does not influence the probabilities of the other columns being a certain value. Thus the number of states to calculate now becomes 2+10*7=72, because each column's states can now be calculated independently. Thus knowing this independent property the answer model can be described as a combination of 7 digit models with a heuristic calculation of the intended sign. This model is illustrated in Figure 4.12.

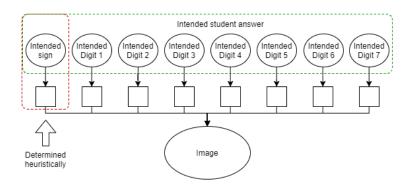


Figure 4.13: Graphical setup of determining a student answer.

4.2.3.2 Estimating the intended answer

In the previous section it was found that determining the intended sign and digit for each column the intended answer can be found. Thus the intended digit for each column is calculated separately using the digit model, as described in Section 4.2.3.2. The intended sign is determined heuristically by using the image processing methods described in Chapter 3 to find if the bubble underneath the sign is coloured in. Once this is done the intended answer is determined by combining the estimated sign and digits in the order seen in Figure 4.12.

4.2.4 Student number model

4.2.4.1 Structure of the graph

For a student number additional information is present. Knowing the digit value of one column changes the probability of each other column taking a certain value. The reason for this is, because there is only a limit number of student numbers to consider. Thus if the first digit is a 2, only student numbers starting with 2 still have to be considered. To account for this fact an additional node is added above the individual digit probabilities. This node represents the probability of each student number being present in the image and is related to the intended digits. The student number thus produces the intended digits. This node will have +-900 states, depending on the number of student numbers. The student number graph can be seen in Figure C.3.

4.2.4.2 Estimating the student number

Now that the graph has been setup the model can be used to infer the most probable student number. By setting all the bubble evidence and character priors the student number probabilities can be inferred. This model allows for a accurate result, because most student numbers are quite different to one another. It is found that if the student provides only character information and no bubbles are coloured in, the student number can still be estimated reliably. These results is states in Section 5.

4.2.5 Training the model

For this project the conditional probabilities for the intended digit model was found by using training data. From these distributions the answer model can also be constructed due to it only consisting of independent digit models. The probability of a student number given the intended digits was estimated manually.

As seen in Figure 4.10, the digit PGM will include the bubble evidence as well as a prior probability which the neural network provides. Once these values are assigned, the PGM model will infer the intended digit using the conditional probability distributions specified. To do this the conditional probabilities of the PGM, must first be determined from data.

The process of training a PGM is a simple process once enough training set is present. This was done by allowing the initial software, without the PGM model, classify the digits. Thus the training set contains the bubble and neural network outputs as evidence. The training set then also includes the intended bubbles and intended digit, as estimated by the image processing unit. Once all these test data are gathered, the conditional probabilities can be calculated. These probabilities then gets stored and used as prior probabilities in the PGM.

4.3 Conclusion

This chapter looked at two machine learning techniques to improve the accuracy with with the system infers the answers written on each scanned test sheet. A method was shown, using a neural network, to estimate the probability of each digit given only the character box as input. Additionally a approach was discussed, using a PGM, to allow

the system to make a final prediction of what the student intended to write down given the bubble and character boxes as evidence.

The following chapter will cover the validation and results of the system from weekly grading done for the Applied mathematics department.

Chapter 5

Analysis of results

In the following chapter a study is described on the accuracy of the test grading system. In the first two sections of this chapter a basic system and complete system is tested using the same datasets. This allows for a accurate interpretation and comparison between the two systems. The first test grading system is implemented using only the image processing techniques, described in Chapter ??. The second system is the final complete system implemented in this project and includes all the machine learning techniques described in Chapter 4. In the last section a description of 3 additional validation tests is given. These tests are done on tutorials written by Applied Mathematics students as is described in the agreement with the department.

Each systems is assessed in the next section under 3 categories. Firstly some marking statistics will be given on the tests grade. The second category describes all the tests, the system appointed to be marked manually, because it was not sure what the correct answer is. In this catagory the tests gets sent to a clashlist. After all the test is graded the systems displays a interface with values it thinks the student wrote down. An additional image is also displayed. The user is then tasked with scanning through each of the clashed tests, using the interface, to see if any tests is graded incorrectly by the system. This process is normally fast, because the system has a high accuracy in guessing the answers correctly. Lastly, all the answers that the system did not assign for manual marking, but identified incorrectly will be described.

5.1 Results of 25 test cases

In this section the results of grading 25 hand picked tests is compared between the two systems. Among the 25 tests there are different categories that tests different aspects and limitations of the systems. The categories and the number of case included can be seen in the list below:

- 1. Test with crossed out answers(7).
- 2. Test with lightly coloured entries or partially coloured in entries(4).
- 3. Test with negative signed answers(1, but also included under other categories as well).
- 4. Test with no bubbles and only characters filled in for a specific entry field (5)
- 5. Test with no characters filled in and only bubbles for a specific entry field(2)
- 6. Test with data filled in correctly(2).
- 7. Random page with no template on them(2).
- 8. Page with tilted template inside image(2).

These test is specifically chosen, because in combination it approximates all the types of tests the system has to asses. Most of the tests are slightly extreme cases of what students has filled in on tutorial tests.

5.1.1 Basic system

5.1.1.1 Marking statistics

Using this basic system an average time for each test is calculated to be 0.305 seconds.



Figure 5.1: Image showing answer with crossed out answers that the system misinterpreted.

5.1.1.2 Clashlist

A total of 6 out of the 25 test where reported as clashes. The two random images were both reported in the clash list. Further the one test which only has the student number written in with no bubbles filled in is also reported to the list. The other 3 clashes were reported due to the crossed out bubbles interpreted as still filled in, causing the system to think that two answer were filled in. An example of this can be seen in Figure 5.1.

5.1.1.3 Incorrect automatic graded results

There where 4 tests in total that where graded automatically, but wrongly. All of these test were tests that had only character information in atleast one of the answers. An example of this can be seen in Figure 5.2

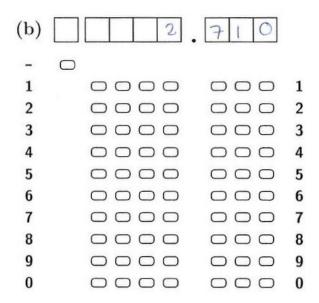


Figure 5.2: Student filled in answer with only character information.

5.1.2 Complete system

5.1.2.1 Marking statistics

Using this complete system an average time for each test is calculated to be 2.011 seconds.

5.1.2.2 Clashlist

A total of 6 out of the 25 test where reported as clashes. The two random images were both reported in the clash list. One test was reported due to it only having characters written in with no bubbles. Thus even though the system identified every character correctly, it had to low of a percentage faith in its answer and reported it to the clash list. The final two cases that was reported to the clash list was due to the character recognition determining a crossed out character as the intended character. An example of this is shown in Figure 5.3.

5.1.2.3 Incorrect automatic graded results

There were no automatically graded answers that was done incorrectly.

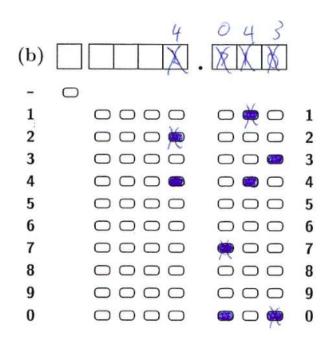


Figure 5.3: Crossed out character that confused the grading system.

5.1.3 Analysis or results

As is seen in the section below, the complete systems does not reduce the number of clashes for these 25 images. The complete system sometimes classifies a crossed out character is the intended character in that block. But because it is crossed out the system assigns a low certainty to that value, as the neural network is not to sure which digit it is. A drawback of the completed system is that it takes on average 2.011 seconds to grade a tests. This is due to the student number PGM taking on average 1.5 seconds to infer the correct student number. The complete system had no incorrectly automatically graded answers in contras to the 4 graded wrongly using the basic system. A reason to this is attributed to more evidence that gets considered in the complete system. Thus only if that evidence match up will the system be certain enough to accept its answer as the correct one. In the next section the complete system use used to grade a tutorial written by students.

5.2 Grading of tutorial tests

In this section the complete system is tested on the final tutorial test written by the student class. Thus the final version of the complete system was used in grading the students' tests. To analyse the results student feedback was recorded to locate tests that were graded incorrectly.

5.2.1 Marking statistics

For these tutorial test an average marking time per test of 2.3 seconds was recorded.

5.2.2 Clashlist

In total there were 67 clashes in the 888 tests. These 67 clashes are categorised in Table 5.1:

5.2.3 Incorrect automatic graded results

For this tutorial 888 test were written. To check through every test manually to find mistakes becomes impractical. Thus the students were asked to report any results that were marked wrong by the system. This is all the results that the system decided to automatically grade and in doing so graded the test wrong.

Only 1 result was reported where the software automatically marked the wrong answer to a test. The correct answer was -95.0 and the system marked the answer as 95.0, as seen in Figure 5.4. There might still be test that were marked wrong, but these test(s) were not reported.

For a more detailed description of the results from grading all 4 tutorial tests, refer to Appendix E.

5.2.4 Analysis or results

In conclusion it is noted that the complete system, with its machine learning capabilities, slightly reduces the number of tests that the user must mark manually from the previous basic system. About 7.5% of the tests in the tutorial had to be marked manually, due

Number of tests	Category description	
in category		
41	In these tests the system guessed the right values,	
	but with a certainty value below 90%. Some of the	
	cases was when the student number was only filled	
	in the character box. The software always	
	identified the correct student number, but was	
	below 90% sure of its overall test answer.	
15	In these tests the system could not distinguish	
	between a crossed out answer and correct answer.	
	This is due to the crossed out answer being	
	interpreted as a filled in answer.	
8	These tests have an answer with only character	
	information in them. The system tried to identify	
	each answer, but made a mistake in atleast one of the	
	digits.	
2	These images contained blank papers that did not	
	include test templates.	
1	In this test the grid of the test paper can not be	
	found. Thus the test could not be marked.	

Table 5.1: Table describing number of clashes in the different catagories.

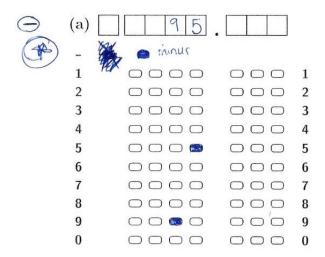


Figure 5.4: Incorrectly identified answer as 95.

to the system being unsure of its answers. The system does however have a high probability of grading tests correctly if they are done automatically. A reason for this can be attributed to the fact that the system correlates two pieces of evidence to predict the correct answer. Thus both the character and bubble information has to be interpreted incorrectly for the system to automatically grade a answer incorrectly.

Thus overall the system could graded 92.5% of all the test correctly and automatically. From the remaining 7.5% only 1 test or 0.1% of the tests was found to be graded wrongly. For the remaining 7.4% of the tests the system was not certain enough to grade these test automatically. The system did classify most of the clashlist test correctly. This means the system could possible have graded 97.1% of the tests correctly. This can be done by changing a threshold value, but allows the other 2.9% of the tests to be classified incorrectly.

Chapter 6

Summary and conclusions

6.1 Project summary

In this project an automatic test grading system is developed with the aim of grading student test using a special template. Firstly research was done into excising methods of grading test automatically. It was found that these software packages normally uses only image processing methods to graded bubbles on a paper. For this project additional machine learning capabilities was also built into the system. This allows for a better estimation of what the student wanted to write down on the paper.

6.2 How this final year project benefits society

In the African society there is a great number of individuals who does not have access to quality educational opportunities. The educational systems these individuals do have are normally of pour grade with limited teaching assistance. Educators who are available are not accessible to learners to provide quality education. Automatic Mark Recognition software like the one developed in this project allows for a great number of tests to be assessed automatically in a short time span. This gives educators the power to handle bigger classes and thus provide more learners the opportunity for a better education.

6.3 What the student learned

During the execution of this project, the student learned that time management is important to complete an project in due time. Time management also allows an individual

to continuously asses how he/she is doing with respect to a schedule. This not only increases performance, but also self confidence in the final product. Finally the student learned how to develop a software package under a deadline. This project also allowed the student to gain a basic knowledge a a broad range of fields including image processing, neural networks and probabilistic graphical models.

6.4 Future improvements

To increase the speed of grading tests it should be considered to use a faster PGM library to inference the intended student number. This can be done by using Stellenbosch's emdw library. Next a improvement in estimating the bubble locations can be made by updating the orientation of the template as more bubble contours gets classified. This allows for example the final student number bubbles to be estimate extremely accurately. Further increases in test grading speed can be achieved by only doing image processing on the expected locations of the bubbles. This will bring some extra technical hurdles, but if solved can significantly increase the software's speed. Further the accuracy of the character recognition neural network can be increased by making use of Generative Adversarial Networks(GAN) to train the network on actually classified test results.

6.5 Conclusion: Summary and conclusions

For a tutorial setting with around 890 tests the system takes \pm 30 minutes to grade these tests automatically. This time is longer than other OCR software, but allows for less limited answers to be given by a student. An example of these answers are the system's capability to identify a student number by only referring to the characters written in the student number box.

In conclusion a test grading system was build that can automatically grade tests with a 97.1% accuracy. The reason for this accuracy not being at 100% is mainly due to some students crossing out answers only partially and thus confuses the system. An additional feature is implemented that transfers tests, the system uncertain about, to a user to manually grade using the software. In combination with this manually checked tests, the system achieves an overall accuracy of 99.8%. Thus on average only 1 test in every tutorial session of around 890 tests gets graded incorrectly.

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Appendix A

Project plan

The final year project plan is shown in Figure A.1. This idea of this Gantt chart plan was to give the student an indication of the progress of the final year project. It was last updated as a final adjustment to the project report.

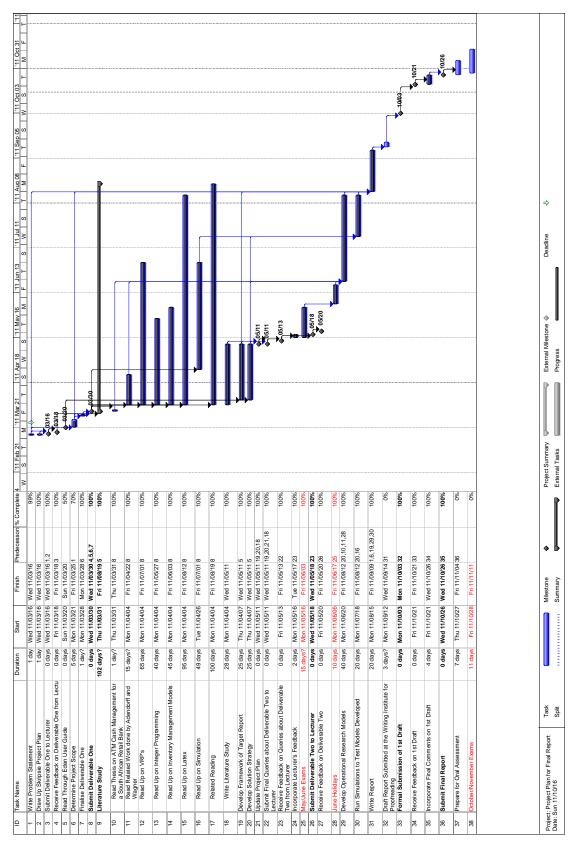


Figure A.1: Project plan for the final year project.

Appendix B

Outcome compliance

Maak die kulomme oucomes, chapters, description

Outcome	Reference	
	Sections	Pages
1. Problem solving: Demonstrate competence	All	All
to identify, assess, formulate and solve conver-		
gent and divergent engineering problems cre-		
atively and innovatively.		
5. Engineering methods, skills and tools,	2, 3, 4, 5, 6 &	10 - 62
including information technology: Demon-	7	
strate competence to use appropriate engineer-		
ing methods, skills and tools, including those		
based on information technology.		
6. Professional and technical communication:	All	All
Demonstrate competence to communicate ef-		
fectively, both orally and in writing, with engi-		
neering audiences and the community at large.		
9. Independent learning ability: Demonstrate	2, 3, 4 & 5	10 - 37
competence to engage in independent learning		
through well developed learning skills.		
10. Engineering professionalism: Demonstrate	8.3 & 8.4	66 - 67
critical awareness of the need to act profession-		
ally and ethically and to exercise judgment and		
take responsibility within own limits of compe-		
tence.		

Appendix C

Overview of system

In this chapter a graphical and mathematical derivation of the entire system is given.

A.b onder aan ;— vir sum over all derivation sit die all teken onder aan die sumation

C.1 System as a whole

As described in Chapter 1, the system can fundamentally be represented with 6 information nodes. These nodes are shown in Figure C.1. The student has certain information he/she wants to portray on the paper. This includes the 4 answers and student number the student wants to write down. Thus those 5 nodes gives rise to the image, representing the last node. Thus fundamentally the system is tasked with working out these 5 conditional probabilities: P(StudentNumber/Image), P(Answer1/Image),

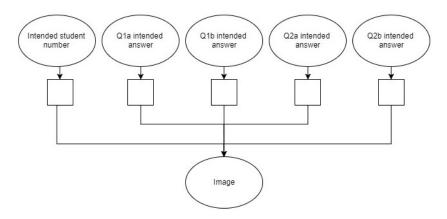


Figure C.1: System overview.

P(Answer2/Image), P(Answer3/Image) and P(Answer4/Image). The random variables StudentNumber and Answer(1 to 3) thus represent all the possible values that the student number and answers possibly can be. The image is a random variable representing the total number of possible states the image can represent. This value is in the order of 1240*1754*256 possible states. To practically represent this further assumptions are made in the following sections.

The aim of the software is to maximize the likelihood of those probability distributions indicating the correct answers. The reason the problem is represented in a probabilistic way is due to the fact that different images are going to be generated every time a test is written. This is true even when the same information is going to be portrayed. Everytime a student writes a test he/she is going to write in different ways. A probabilistic graphical model (PGM) is thus used to describe this system and its inner operations. For a more detailed explanation on PGM's, refer to Section 4.2. The blocks in Figure C.1 represent additional processing that is described in the following sections.

To calculate those 5 probabilities, some more detailed derivations are necessary. These derivations are described in the next section.

C.2 Deriving the intended student entry

C.2.1 Student answer

In Section 4.2.4 it was determined that the student answer can be calculated by combining the intended sign and digits of each column to form an answer. The reason for this could be attributed to the fact that these digits where independent of one another. This means that the intended digit in a certain column is not influenced by what the values in other columns are. In Equation C.1 this independence property can now be seen. To find the most probable answer only P(sign/Image) and P(digit(1-7)/Image) still needs to be calculated. Using the image processing techniques described in Section 3 the P(sign/Image) can simply be determined heuristically by determining the probability of the bubble being coloured in, underneath the sign. Thus the only values yet to calculate is P(digit/Image). This is described in Section C.3.

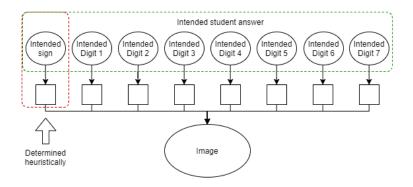


Figure C.2: Graphical setup of determining student answer.

$$P(Answer/Image) = P(sign/Image) * P(digit1/Image) * \dots * P(digit7/Image)$$
 (C.1)

C.2.2 Student number

As state in Section 4.2.4 the assumption of independence does not hold in the case of a student number. The reason for this is, because every 8 digit number is not equally likely to be a student number. Only student numbers that are valid will be considered as a possible state that the student number node can take on. This node will have +-900 states, depending on the number of student numbers. The student number graph can be seen in Figure C.3. Next a derivation for P(studentNumber/Image) is needed.

In the below equations, 'Digits' represents the 8 digit random variables. The first step is to apply Bayes rule as seen in Equation C.2.

$$P(StudentNumber, Digits/Image) = \frac{P(Image/StudentNumber, Digits) * P(StudentNumber, Digits)}{P(Image)}$$
(C.2)

When all the digits are known, the image becomes independent of the student number. This can be seen in Equation C.2. Also the chain rule states that Equation C.4 must be true.

$$P(Image/StudentNumber, Digits) = P(Image/Digits)$$
 (C.3)

$$P(StudentNumber, Digit) = P(Digit/StudentNumber) * P(StudentNumber)$$
 (C.4)

Next the Digit random variable is summed out to produce P(studentNumber/Image), as seen in Equation C.5.

$$P(StudentNumber/Image) = \sum_{D}^{All} \frac{P(Image/Digits) * P(Digit/StudentNumber) * P(StudentNumber)}{P(Image)}$$
(C.5)

Applying Bayes rule again the following equality can be presented, as seen in Equation C.6.

$$P(StudentNumber/Image) = P(Image/Digits) = \frac{P(Digits/Image) * P(Image)}{P(Digits)}$$
(C.6)

Thus the result can be seen in Equation C.7. P(StudentNumber) can be taken out of the sum, due to it being independent of Digits.

$$P(StudentNumber/Image) = P(StudentNumber) * \sum_{D}^{All} \frac{P(Digits/Image) * P(Digits/StudentNumber)}{P(Digits)}$$
(C.7)

P(StudentNumber) can be initialized as a equal distribution, because every student number is equal as likely to be in a given test. P(Digits/StudentNumber) is a value that is trained from data. This value symbolizes the probability that the user intended to write down a given digit given that student's student number. This number is thus strongly correlated with the student number. If the first digit of the student number is 1, Digit1 will have a high probability of being 1. The only values that still needs to be calculated are thus P(Digits/Image) = P(Digit1/Image) * ...*. This derivation is covered in the next section.

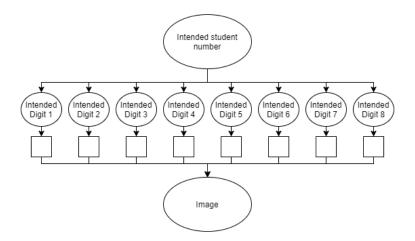


Figure C.3: Graphical setup of determining student number.

C.3 Deriving the estimated digit

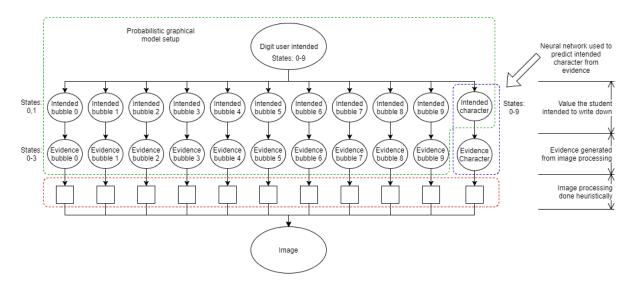


Figure C.4: Graphical setup of determining intended digit.

Appendix D Implementation/Algorithms

Algorithms used in this project.

D.1 Deep Convolutional Neural Network

Appendix E Validation and results

Validation and results of this system.