

Dijkstra's Algorithm Verification

Yazhe Feng

March 4, 2019

1 Dijkstra's Algorithm

1.1 Pseudocode

Given input graph g and source node s with types:

g : Graph gsize weight
 s : Node gsize

We denote (u, v) as an edge from node u to v , $weight(u, v)$ as the weight of edge (u, v) . We define *unexplored* as the list of unexplored nodes, and *dist* as the list storing distance from s to each node $n \in g$

(initially *unexplored* contains all nodes in graph g)
unexplored : List(Node gsize)
unexplored = $\{v : v \in g\}$

(node value is used to index *dist*, initially distance of all nodes are infinity except the source node)
dist : List weight
 $dist[s] = 0, dist[a] = infinity, \forall a \in g, a \neq s$

The Dijkstra's Algorithm runs as follows: Given graph g and source node s , *dist* stores the distance value from s to all nodes in g calculated by the Dijkstra's algorithm, $dist[v]$ gives the corresponding distance value of v from s . We index *unexplored* and *dist* by the number of iterations. Specifically, denote u_i as the node being explored at the i^{th} iteration, and denote $dist_i$, $unexplored_i$ as the value of distance list and unexplored list at the beginning of the i^{th} iteration. Then during each iteration the Dijkstra's Algorithm calculates *dist*, *unexplored*, *explored* as follows:

choose $u_k \in unexplored_k$ **and** $\forall u' \in unexplored_k, dist_k[u_k] \leq dist_k[u']$
 $unexplored_{k+1} = unexplored_k - \{u_k\}$
for ($\forall v \in g$) {
 $dist_{k+1}[v] = \begin{cases} \min(dist_k[v], (dist_k[u_k] + weight(u_k, v))), & (u_k, v) \in g \\ dist_k[v] & otherwise \end{cases}$
}
}

1.2 Assumptions

1. Weight of edges are positive
2. Distance value can only be zero, infinity, or summation of edge weights
3. All nodes n and edge e are valid: $n, e \in g$

2 Definition

Definition 2.1. Path

(We adopt the definition of path presented in the *Discrete Mathematics with Applications* book by SUSANNA S. EPP.)

A path from node v to w is a finite alternating sequence of adjacent vertices and edges of G , which does not contain any repeated edge or vertex. A path from v to w has the form:

$$ve_0v_0e_1v_2\dots v_{n-1}e_nw$$

where e_i is an edge in g with endpoints v_{i-1}, v_i . We denote the set of paths from v to w as $path(v, w)$.

Definition 2.2. Prefix of Path

Given a path from node v to w : $p(v, w) = ve_0v_0e_1v_2\dots v_{n-1}e_nw$, the prefix of this $v - w$ path is defined as the subsequence of $p(v, w)$ that starts with v and ends with some node $w' \in p(v, w)$ (w' is a vertex in the sequence $p(v, w)$).

Definition 2.3. Length of Path

The length of a path $p = ve_0v_0e_1v_2\dots v_{n-1}e_nw$ is the sum of the weights of all edges in p . We write:

$$length(p) = \sum weight(e_i), \forall e_i \in p.$$

Definition 2.4. Shortest Path

Denote $\Delta(s, v)$ as the shortest path from s to v , and $\delta(v)$ as the length of $\Delta(s, v)$. $\Delta(s, v)$ must fulfill:

$$\begin{aligned} \Delta(s, v) &\in path(s, v) \\ \text{and} \\ \forall p' \in path(s, v), \delta(v) = length(\Delta(s, v)) &\leq length(p') \end{aligned}$$

3 Proof of Correctness

3.1 Proof of Termination

The inner for loop is guaranteed to terminate as the algorithm goes through each adjacent node exactly once. As the size of list `unexplored` decreases by one during each iteration of the while loop, the algorithm is guaranteed to terminate.

3.2 Proof of Correctness

Denote *explored* as the list of nodes in g but not in *unexplored*, i.e., *explored* stored all nodes whose neighbors have been updated by the algorithm. We index *explored* by the number of iterations, such that $explored_i$ denotes the value of *explored* at the beginning of the i^{th} iteration.

Lemma 3.1. Given any two nodes v, w , the prefix of the shortest path $\Delta(v, w)$ is also a shortest path.

Proof. We will prove Lemma 3.1 by contradiction.

Consider any node q in the sequence of $\Delta(v, w)$, we have $\Delta(v, w) = ve_0v_0e_1v_2...v_iqv_j...v_{n-1}e_nw$. Suppose the prefix of $\Delta(v, w)$ from v to q , denote as $p(v, q)$, is not the shortest path from v to q . Then we know $p(v, q) = ve_0v_0e_1v_2...v_iq$ is a path from v to q and $length(p(v, q)) > length(\Delta(v, q))$.

Based on the definition of shortest path, we know:

$$length(\Delta(v, w)) \leq length(p), \forall p \in path(v, w)$$

Denote the path after the node q as $p(q, w) = qv_j...v_{n-1}e_nw$, since $\Delta(v, w) = ve_0v_0e_1v_2...v_iqv_j...v_{n-1}e_nw$, then $\Delta(v, w) = p(v, q) + p(q, w)$, and that $length(\Delta(v, w)) = length(p(v, q)) + length(p(q, w))$. Then we have:

$$length(\Delta(v, w)) = length(p(v, q)) + length(p(q, w)) \leq length(p), \forall p \in path(v, w)$$

Since $p(v, q)$ is not the shortest path from v to q by assumption, then based on the definition of shortest path, $length(p(v, q)) < length(\Delta(v, w))$. Hence there exists another $v - w$ path $p'(v, w)$ such that:

$$\begin{aligned} p'(v, w) &\in path(v, w) \\ p'(v, w) &= \Delta(v, q) + p(q, w) \\ length(p'(v, w)) &= length(\Delta(v, q)) + length(p(q, w)) \\ &< length(p(v, q)) + length(p(q, w)) \\ \text{i.e. } length(p'(v, w)) &< length(\Delta(v, w)) \end{aligned}$$

Hence we have reached a contradiction. Thus by the principle of prove by contradiction, for any the prefix $p(v, q)$ of $\Delta(v, w)$ is the shortest path from v to q . Lemma 3.1 holds. \square

Lemma 3.2. After the n^{th} iteration for $n \geq 1$, for all node $v \in explored_{n+1}$, if $dist_{n+1}[v] \neq infinity$, then $dist_{n+1}[v]$ is the length of some $s - v$ path, i.e, $path(s, v) \neq \emptyset$.

Proof. We will prove Lemma 3.2 by inducting on the number of iterations.

Let $P(n)$ be: After the n^{th} iteration, $n \geq 1$, for all node $v \in g$, if $dist_{n+1}[v] \neq infinity$, then $dist_{n+1}[v]$ is the length of some $s - v$ path.

Base Case: We shall show $P(1)$ holds.

Based on the algorithm, initially $dist_1[s] = 0$ and for all node $v \in g, v \neq s, dist_1[v] = infinity$, then s is the only node whose distance value is not infinity. Based on the definition of path, the path from the source node s to itself is s , $path(s, s) = \{s\}$. Hence $P(1)$ holds.

Inductive Hypothesis: Suppose $\forall i, 1 \leq i \leq k$, $P(i)$ holds. That is, after the i^{th} iteration, $1 \leq i \leq k$, for all nodes $v \in g$, if $dist_{i+1}[v] \neq infinity$, then $dist_{i+1}[v]$ is the length of some $s - v$ path.

Inductive Step: We shall show $P(k+1)$ holds.

For node u_{k+1} being explored during the $(k+1)^{th}$ iteration, based on the algorithm, $dist_{k+1}[u_{k+1}]$ is calculated as:

$$dist_{k+2}[u_{k+1}] = \begin{cases} \min(dist_{k+1}[u_{k+1}], dist_{k+1}[u_{k+1}] + weight(u_{k+1}, u_{k+1})), & (u_{k+1}, u_{k+1}) \in g \\ dist_{k+1}[u_{k+1}] & otherwise \end{cases}$$

Since the distance value from u_{k+1} to itself is 0, then $dist_{k+2}[u_{k+1}] = dist_{k+1}[u_{k+1}]$, and that $dist_{k+2}[u_{k+1}]$ and $dist_{k+1}[u_{k+1}]$ are the length of the same $s - u_{k+1}$ path if there exists one.

If $dist_{k+2}[u_{k+1}] \neq infinity$, then $dist_{k+1}[u_{k+1}] = dist_{k+2}[u_{k+1}] \neq infinity$. Since $k \leq k$ and $dist_{k+1}[u_{k+1}] \neq infinity$, then based on the inductive hypothesis, $dist_{k+1}[u_{k+1}]$ is the length of some $s - u_{k+1}$ path, and hence $dist_{k+2}[u_{k+1}]$ is the length of some $s - u_{k+1}$ path.

Then for all node $v \in g$ other than u_{k+1} , there are two cases: (1) $(u_{k+1}, v) \in g$; (2) u_{k+1} does not have an edge to v . We will prove $P(k+1)$ holds in both cases separately.

Case (1): $(u_{k+1}, v) \in g$

Based on the algorithm, as $(u_{k+1}, v) \in g$, $dist_{k+2}[v] = \min(dist_{k+1}[v], dist_{k+1}[u_{k+1}] + weight(u_{k+1}, v))$.

- If $dist_{k+1}[v] < dist_{k+1}[u_{k+1}] + weight(u_{k+1}, v)$, then $dist_{k+2}[v] = dist_{k+1}[v]$. Then if $dist_{k+2}[v] \neq infinity$, we have $dist_{k+1}[v] \neq infinity$, and that $dist_{k+2}[v]$ and $dist_{k+1}[v]$ are the length of the same $s - v$ path if there exists one. Since $dist_{k+1}[v] \neq infinity$, the inductive hypothesis implies that $dist_{k+1}[v]$ is the length of some $s - v$ path, hence $dist_{k+2}[v]$ is the length of some $s - v$ path. $P(k+1)$ holds.
- If $dist_{k+1}[v] \geq dist_{k+1}[u_{k+1}] + weight(u_{k+1}, v)$, then $dist_{k+2}[v] = dist_{k+1}[u_{k+1}] + weight(u_{k+1}, v)$. If $dist_{k+2}[v] \neq infinity$, then it follows that $dist_{k+1}[u_{k+1}] = dist_{k+2}[v] - weight(u_{k+1}, v) \neq infinity$. Then the inductive hypothesis implies that $dist_{k+1}[u_{k+1}]$ must be the length of some $s - u_{k+1}$ path, denote as $p(s, u_{k+1})$. Since there is an edge $(u_{k+1}, v) \in g$, then $dist_{k+2}[v] = dist_{k+1}[u_{k+1}] + weight(u_{k+1}, v)$ must be the length of the $s - v$ path through u_{k+1} . $P(k+1)$ holds.

Hence $P(k+1)$ holds under under **Case(1)**.

Case (2): u_{k+1} does not have an edge to v

Under this case, our algorithm indicates that $dist_{k+2}[v] = dist_{k+1}[v]$, and that $dist_{k+1}[v]$ and $dist_{k+2}[v]$ are the length of the same $s - v$ path if there exists one. If $dist_{k+1}[v] = dist_{k+2}[v] \neq infinity$, then based on the inductive hypothesis, $dist_{k+1}[v]$ is the length of some $s - v$ path, and hence $dist_{k+2}[v]$ is the length of some $s - v$ path. $P(k+1)$ holds under **Case(2)**.

We have proved $P(k+1)$ holds for u_{k+1} and both cases for all nodes $v \in g$ other than u_{k+1} . Hence by the principle of prove by induction, $P(n)$ holds. Thus **Lemma 3.2** holds. \square

Lemma 3.3. For any node $v \in g$, if after the i^{th} iteration, $dist_{i+1}[v] = \delta(v)$, then for each proceeding j^{th} iteration, $j > i$, $dist_{j+1}[v] = dist_{i+1}[v] = \delta(v)$.

Proof. We will prove Lemma 3.3 by induction on the number iterations after the i^{th} iteration.

Let $P(n)$ be: For any node $v \in g$, if after the i^{th} iteration, $dist_{i+1}[v] = \delta(v)$, then for the $(i+n)^{th}$ iteration, $n \geq 1$, $dist_{i+n+1}[v] = dist_{i+1}[v] = \delta(v)$

Base Case: We shall show $P(1)$ holds.

During the $(i+1)^{th}$ iteration, suppose u_{i+1} is the node being explored, then $dist_{i+2}[v]$ is calculated as:

$$dist_{i+2}[v] = \begin{cases} \min(dist_{i+1}[v], dist_{i+1}[u_{i+1}] + weight(u_{i+1}, v)), & (u_{i+1}, v) \in g \\ dist_{i+1}[v] & otherwise \end{cases}$$

If $(u_{i+1}, v) \in g$, then if $dist_{i+1}[u_{i+1}]$ is the length of some $s - u_{i+1}$ path, then $(dist_{i+1}[u_{i+1}] + weight(u_{i+1}, v))$ is the length of some $s - v$ path. Since $dist_{i+1}[v] = \delta(v)$, then based on the definition of shortest path, $dist_{i+1}[v] \leq dist_{i+1}[u_{i+1}] + weight(u_{i+1}, v)$, and hence $dist_{i+2}[v] = dist_{i+1}[v] = \delta(v)$.

If u_{i+1} does not have an edge to v , then $dist_{i+2}[v] = dist_{i+1}[v] = \delta(v)$.

Hence in either cases, $dist_{i+2}[v] = dist_{i+1}[v] = \delta(v)$. $P(1)$ holds.

Inductive Hypothesis: Suppose $P(k)$ holds, that is, if after the i^{th} iteration, $dist_{i+1}[v] = \delta(v)$, then for the $(i+k)^{th}$ iteration, $n \geq 1$, $dist_{i+k+1}[v] = dist_{i+1}[v] = \delta(v)$.

Inductive Step: We shall show $P(k+1)$ holds.

For the node u_{i+k+1} being explored during the $(i+k+1)^{th}$ iteration, there are two cases: (1) $(u_{i+k+1}, v) \in g$; (2) u_{i+k+1} does not have an edge to v . We will show that $P(k+1)$ holds under both cases separately.

Case 1: $(u_{i+k+1}, v) \in g$

If u_{i+k+1} has an edge to v , then based on the algorithm, for $dist_{i+k+2}[v]$, we have:

$$dist_{i+k+2}[v] = \min(dist_{i+k+1}[v], dist_{i+k+1}[u_{i+k+1}] + weight(u_{i+k+1}, v))$$

Since based on our inductive hypothesis, $dist_{i+k+1}[v] = dist_{i+1}[v] = \delta(v)$, then if $dist_{i+k+1}[u_{i+k+1}]$ is the length of some $s - u_{i+k+1}$ path, then $(dist_{i+k+1}[u_{i+k+1}] + weight(u_{i+k+1}, v))$ is the length of some $s - v$ path, and hence $dist_{i+k+1}[v] = \delta(v) \leq (dist_{i+k+1}[u_{i+k+1}] + weight(u_{i+k+1}, v))$. Then:

$$\begin{aligned} dist_{i+k+2}[v] &= \min(dist_{i+k+1}[v], dist_{i+k+1}[u_{i+k+1}] + weight(u_{i+k+1}, v)) \\ &= dist_{i+k+1}[v] \\ &= dist_{i+1}[v] = \delta(v) \end{aligned}$$

$P(k+1)$ holds under **Case 1**.

Case 2: u_{i+k+1} does not have an edge to v

Since u_{i+k+1} does not have an edge to v , then $dist_{i+k+2}[v] = dist_{i+k+1}[v]$. Based on the inductive hypothesis, $dist_{i+k+1}[v] = dist_{i+1}[v] = \delta(v)$. then $dist_{i+k+2}[v] = dist_{i+1}[v] = \delta(v)$. $P(k+1)$ holds for **Case (2)**.

Thus $P(k+1)$ holds. By the principle of prove by induction, $P(n)$ holds. Lemma 3.3 proved. \square

Lemma 3.4. Assume g is a connected graph, that the source node s has a path to every node in g . After the n^{th} iteration of the algorithm for $n \geq 1$, for all node $v \in explored_{n+1}$, we have:

1. $\delta(v) \leq \delta(v'), \forall v' \in unexplored_{n+1}$.

$$2. \text{dist}_{n+1}[v] = \delta(v)$$

Proof. We will prove **Lemma 3.4** by inducting on the number of iterations.

Let $P(n)$ be: After the n^{th} iteration of the algorithm for $n \geq 1$, for all node $w \in \text{explored}_{n+1}$: (1) $\delta(w) \leq \delta(w')$, $\forall w' \in \text{unexplored}_{n+1}$; (2) $\text{dist}_{n+1}[w] = \delta(w)$.

Base Case: We shall show $P(1)$ holds

Based on the algorithm, during the first iteration, the node with minimum distance value is the source node s with $\text{dist}_1[s] = 0$. Hence during the first iteration, only s is removed from unexplored_1 and added to explored_2 . Since all edge weights are non-negative, then the shortest distance value from s to s is indeed 0, hence $\text{dist}_2[s] = 0 = \delta(s)$ and $\delta(s) \leq \delta(v')$, $\forall v' \in \text{unexplored}_2$.

$P(1)$ holds.

Inductive Hypothesis: Suppose $P(i)$ is true for all $1 \leq i \leq k$. That is, after the i^{th} iteration for all $1 < i \leq k$, for all node $w \in \text{explored}_{i+1}$: (1) $\delta(w) \leq \delta(w')$, $\forall w' \in \text{unexplored}_{i+1}$; (2) $\text{dist}_{i+1}[w] = \delta(w)$;

Inductive Step: We shall show $P(k+1)$ holds. That is, for all node $w \in \text{explored}_{k+2}$, (1) $\delta(w) \leq \delta(w')$, $\forall w' \in \text{unexplored}_{k+2}$; (2) $\text{dist}_{k+2}[w] = \delta(w)$;

Suppose u_{k+1} is the node added into explored during the $(k+1)^{\text{th}}$ iteration, then $\text{explored}_{k+2} = \text{explored}_{k+1} \cup \{u_{k+1}\}$. We will show that (1) and (2) holds for all nodes in explored_{k+1} in **Part (a)**, and **Part (b)** proves (1) and (2) holds for u_{k+1} , so that (1) and (2) holds for all nodes in explored_{k+2} .

- **Part(a): WTP: After the $(k+1)^{\text{th}}$ iteration, $\forall w \in \text{explored}_{k+1}$, (1) and (2) holds.**

Consider each node $q \in (\text{explored}_{k+1} \cap \text{explored}_{k+2}) = \text{explored}_{k+1}$, q must be explored before the $(k+1)^{\text{th}}$ iteration. Suppose q is explored during the i^{th} iteration for some $i < k+1$, then based on our inductive hypothesis, $\text{dist}_{i+1}[q] = \delta(q)$, and $\delta(q) \leq \delta(q')$, $\forall q' \in \text{unexplored}_{i+1}$.

Proof of (1): Based on the algorithm, for each iteration, the algorithm explores exactly one node and never revisits any explored nodes. For each node $q \in \text{explored}_{k+1}$ mentioned above, since q is explored before the $(k+1)^{\text{th}}$ iteration, then $\text{unexplored}_{k+1} \subseteq \text{unexplored}_{i+1}$. Since $\delta(q) \leq \delta(q')$, $\forall q' \in \text{unexplored}_{i+1}$, and unexplored_{i+1} includes all node in unexplored_{k+1} , then $\delta(q) \leq \delta(q')$, $\forall q' \in \text{unexplored}_{k+1}$. (1) holds for explored_{k+1} .

Proof of (2): For all proceeding j^{th} iterations, $j > i$, suppose node q'' is the node being explored for the j^{th} iteration, then the value of $\text{dist}_{j+1}[q]$ is calculated as:

$$\text{dist}_{j+1}[q] = \begin{cases} \min(\text{dist}_j[q], \text{dist}_j[q''] + \text{weight}(q'', q)), & (q'', q) \in g \\ \text{dist}_j[q] & \text{otherwise} \end{cases}$$

Since $\text{dist}_{i+1}[q] = \delta(q) \leq \text{length}(p)$ for all path p from s to q , then for each proceeding j^{th} iteration after the i^{th} iteration, there does not exist such q'' such that $\text{dist}_j[q''] + \text{weight}(q'', q) < \delta(q) = \text{dist}_{i+1}[q]$. Hence $\text{dist}_{j+1}[q] = \delta(q) = \text{dist}_{i+1}[q]$, $\forall j > i$. Since $k+1 > i$, then for all $q \in S$, $\text{dist}_{k+1} = \delta(q) = \text{dist}_{i+1}[q]$. (2) holds for explored_{k+1} .

Hence we have proved that both (1) and (2) holds for all nodes in explored_{k+1} .

- **Part(b): After the $(k+1)^{\text{th}}$ iteration, (1) and (2) holds for $\{u_{k+1}\}$.**

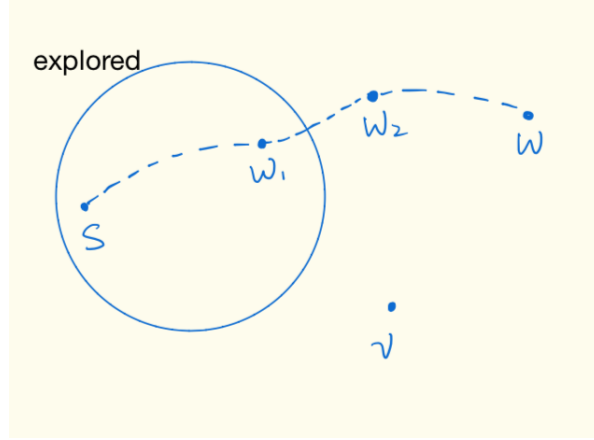
We want to show: (1) $\delta(u_{k+1}) \leq \delta(v')$, $\forall v' \in \text{unexplored}_{k+2}$, and (2) $\text{dist}_{k+1}[u_{k+1}] = \delta(u_{k+1})$.

1. $\delta(u_{k+1}) \leq \delta(v'), \forall v' \in \text{unexplored}_{k+2}$

We will prove (1) by contradiction. Suppose there exists $w \in \text{unexplored}_{k+2}$, such that $\delta(u_{k+1}) > \delta(w)$.

The assumption states that source s has a path to every node in g , then $\text{dist}_{k+1}[u_{k+1}] \neq \text{infinity}$. Thus **Lemma 3.2** implies that $\text{dist}_{k+1}[u_{k+1}]$ is the length of some $s - v$ path. Based on the definition of shortest path, $\delta(u_{k+1}) \leq \text{dist}_{k+1}[u_{k+1}]$. Since $\delta(u_{k+1}) > \delta(w)$ and $\delta(u_{k+1}) \leq \text{dist}_{k+1}[u_{k+1}]$, then we have $\delta(w) < \text{dist}_{k+1}[u_{k+1}]$ ([NE1]).

Consider the shortest path $\Delta(s, w)$ from s to w , $\delta(w) = \text{length}(\Delta(s, w))$. Since $w \notin \text{explored}_{k+2}$, then there must exist some node in $\Delta(s, w)$ that are not in explored_{k+2} . Suppose the first node along $\Delta(s, w)$ that is not in the explored_{k+2} list is w_2 , and the node right before w_2 in the s to w_2 subpath is w_1 , thus $w_1 \in \text{explored}_{k+2}$. The image below illustrates this construction:



Denote the subpath from s to w_1 in $\Delta(s, w)$ as $p(s, w_1)$, subpath from s to w_2 in $\Delta(s, w)$ as $p(s, w_2)$, and subpath w_2 to w as $p(w_2, w)$. Based on **Definition 2.2 Prefix of Path**, $p(s, w_1)$ is a prefix of $\Delta(s, w)$. Since $p(s, w_1)$ is the prefix of the shortest $s - w$ path, then based on **Lemma 3.1**, $p(s, w_1)$ is the shortest path from s to w_1 , $\Delta(s, w_1) = p(s, w_1)$, $\text{length}(p(s, w_1)) = \delta(w_1)$. Similarly, since $p(s, w_2) = p(s, w_1) + (w_1, w_2)$, then $p(s, w_2)$ is a prefix of $\Delta(s, w)$, and hence **Lemma 3.1** implies that $p(s, w_2)$ is the shortest path from s to w_2 . Then we have:

$$\begin{aligned}
 \Delta(s, w_2) &= p(s, w_2) = p(s, w_1) + (w_1, w_2) \\
 \delta(w_2) &= \text{length}(\Delta(s, w_2)) \\
 &= \text{length}(p(s, w_2)) \\
 &= \text{length}(p(s, w_1)) + \text{weight}(w_1, w_2) \\
 &= \delta(w_1) + \text{weight}(w_1, w_2) \quad ([E1])
 \end{aligned}$$

For $\Delta(s, w)$ we have:

$$\begin{aligned}
 \delta(w) &= \text{length}(p_w) \\
 &= \text{length}(p(s, w_1)) + \text{weight}(w_1, w_2) + \text{length}(p(w_2, w)) \\
 &= \delta(w_1) + \text{weight}(w_1, w_2) + \text{length}(p(w_2, w))
 \end{aligned}$$

Since all edge weights are positive, then:

$$\delta(w_2) = \delta(w_1) + \text{weight}(w_1, w_2) \leq \delta(w) \text{ ([E2])}$$

Since $w_1 \in \text{explored}_{k+2}$, there are two cases to consider: $w_1 = u_{k+1}$ and $w_1 \neq u_{k+1}$. We will prove P(k+1) under both cases below.

Case 1: $w_1 = u_{k+1}$

When $w_1 = u_{k+1}$, then substitute w_1 by u_{k+1} in [E2], we have:

$$\begin{aligned} \delta(w_1) + \text{weight}(w_1, w_2) &= \delta(u_{k+1}) + \text{weight}(u_{k+1}, w_2) \leq \delta(w) \\ \text{i.e. } \delta(u_{k+1}) &\leq \delta(w) \end{aligned}$$

which contradicts with our assumption that $\delta(u_{k+1}) > \delta(w)$. Hence by the principle of prove by contradiction, $\delta(u_{k+1}) < \delta(w)$. (1) holds for P(k+1).

Case 2: $w_1 \neq u_{k+1}$

Since $w_1 \in \text{explored}_{k+2}$ and $w_1 \neq u_{k+1}$, w_1 is explored before the $(k+1)^{th}$ iteration. i.e., $w_1 \in \text{explored}_{k+1}$. Suppose w_1 is being explored during the i^{th} iteration, $i < k+1$, then based on the algorithm, the value of $\text{dist}_{i+1}[w_1]$ is calculated as:

$$\text{dist}_{i+1}[w_1] = \begin{cases} \min(\text{dist}_i[w_1], \text{dist}_i[w_1] + \text{weight}(w_1, w_1)), & (w_1, w_1) \in g \\ \text{dist}_i[w_1] & \text{otherwise} \end{cases}$$

Thus $\text{dist}_{i+1}[w_1] = \text{dist}_i[w_1]$. Since the inductive hypothesis implies that $\text{dist}_{i+1}[w_1] = \delta(w_1)$, then $\text{dist}_i[w_1] = \delta(w_1)$.

Since w_1 has an edge to w_2 , then $\text{dist}_{i+1}[w_2]$ must have been updated according as follows:

$$\begin{aligned} \text{dist}_{i+1}[w_2] &= \min(\text{dist}_i[w_2], \text{dist}_i[w_1] + \text{weight}(w_1, w_2)) \\ &= \min(\text{dist}_i[w_2], \delta(w_1) + \text{weight}(w_1, w_2)) \end{aligned}$$

Based on [E1] we know that $\delta(w_2) = \delta(w_1) + \text{weight}(w_1, w_2)$, then $\text{dist}_{i+1}[w_2] = \min(\text{dist}_i[w_2], \delta(w_2))$. If $\text{dist}_i[w_2] = \text{infinity}$, then $\text{dist}_{i+1}[w_2] = \min(\text{dist}_i[w_2], \delta(w_2)) = \delta(w_2)$. If $\text{dist}_i[w_2] \neq \text{infinity}$, then based on Lemma 3.2, $\text{dist}_i[w_2]$ is the length of some $s - w_2$ path. Since $\delta(w_2) \leq \text{length}(p), \forall p \in \text{path}(s, w_2)$, then $\text{dist}_{i+1}[w_2] = \min(\text{dist}_i[w_2], \delta(w_2)) = \delta(w_2)$. Hence in either cases, we conclude that $\text{dist}_{i+1}[w_2] = \delta(w_2)$.

Since $\text{dist}_{i+1}[w_2] = \delta(w_2)$ and $i < k+1$, then based on Lemma 3.3, we have $\text{dist}_{k+1}[w_2] = \text{dist}_{i+1} = \delta(w_2)$. Based on [E2], $\delta(w_2) < \delta(w)$, then $\text{dist}_{k+1}[w_2] < \delta(w)$ [NE2]. Combining with [NE1], we have:

$$\begin{aligned} \delta(w) &< \text{dist}_{k+1}[u_{k+1}] \text{ (from [NE1])} \\ \text{dist}_{k+1}[w_2] &< \delta(w) \end{aligned}$$

Hence $\text{dist}_{k+1}[w_2] < \text{dist}_{k+1}[u_{k+1}]$ [NE2].

Based on our assumption, at the beginning of the $(k+1)^{th}$ generation, $u_{k+1}, w_2 \notin \text{explored}_{k+1}$

and u_{k+1} is selected by the algorithm, then we must have $dist_{k+1}[w_2] \geq dist_{k+1}[u_{k+1}]$, which contradicts with [NE2]. Hence by the principle of prove by contradiction, there does not exist $w \in unexplored_{k+2}$, such that $\delta(u_{k+1}) > \delta(w)$, i.e. $\delta(u_{k+1}) \leq \delta(w), \forall w \in unexplored_{k+2}$. Hence (1) holds for u_{k+1} .

2. After the $(k+1)^{th}$ iteration, $dist_{k+1}[u_{k+1}] = \delta(u_{k+1})$

We will prove this by contradiction.

Suppose $dist_{k+1}[u_{k+1}]$ is the length of some path p from s to u_{k+1} . Assume the shortest path from s to u_{k+1} is some path different from p , i.e. $\Delta(s, u_{k+1}) \neq p$, $\delta(u_{k+1}) \leq dist_{k+1}[u_{k+1}]$ ([b]). Suppose v' is the node just before u_{k+1} in $\Delta(s, u_{k+1})$.

$$\delta(u_{k+1}) = \delta(v') + weight(v', u_{k+1}) < dist_{k+1}[u_{k+1}]$$

Since all edge weights are non-negative, then: $\delta(v') \leq \delta(u_{k+1})$

Based on (1), after the $(k+1)^{th}$ iteration, for all nodes $q \in unexplored_{k+2}$, $\delta(q) \geq \delta(u_{k+1})$, and $\delta(v') \leq \delta(u_{k+1})$, then v' cannot be in $unexplored_{k+2}$. Since $unexplored_{k+1} = unexplored_{k+2} \cup u_{k+1}$, then $v' \notin unexplored_{k+1}$. Hence at the beginning of the $(k+1)^{th}$ iteration, v' is already explored. Since v' is explored before the $(k+1)^{th}$ iteration and v' has an edge to u_{k+1} , then the algorithm must have considered $(\delta(v') + weight(v', u_{k+1}))$ against $dist_{k+1}[u_{k+1}]$ and chose $\min((\delta(v') + weight(v', u_{k+1})), dist_{k+1}[u_{k+1}])$, which is $dist_{k+1}[u_{k+1}]$. Thus $dist_{k+1}[u_{k+1}] \leq (\delta(v') + weight(v', u_{k+1}))$, i.e. $dist_{k+1}[u_{k+1}] \leq \delta(u_{k+1})$, which contradicts with our assumption [b]. Hence by the principle of prove by contradiction, $dist_{k+1}[u_{k+1}] = \delta(u_{k+1})$. (2) holds for u_{k+1} .

Since we have proved both (1) and (2) for all nodes in $explored_{k+1}$ after the $(k+1)^{th}$ iteration, P(k+1) holds. Then by the principle of prove by induction, Lemma 3.4 holds. \square

Proof. **Prove of Correctness**

By applying Lemma 3.4 to the last iteration of the algorithm, we obtained that for all nodes n in the explored list, $dist[n]$ is indeed the shortest path distance value from source s to n , hence Dijkstra's algorithm indeed calculates the shortest path distance value from the source s to each node $n \in g$. \square