# Using nested classes as associated types.

- Authors omitted for double-bind review.
- 3 Unspecified Institution.

#### — Abstract

- 5 Lorem ipsum dolor sit amet, consectetur adipiscing elit. Praesent convallis orci arcu, eu mollis
- 6 dolor. Aliquam eleifend suscipit lacinia. Maecenas quam mi, porta ut lacinia sed, convallis ac
- <sup>7</sup> dui. Lorem ipsum dolor sit amet, consectetur adipiscing elit. Suspendisse potenti.
- 8 2012 ACM Subject Classification Dummy classification
- 9 Keywords and phrases Dummy keyword
- Digital Object Identifier 10.4230/LIPIcs.CVIT.2016.23

### 1 Introduction

22

33

34

Associated types are a powerful form of generics, now integrated in both Scala and Rust.
They are a new kind of member, like methods fields and nested classes. Associated types behave as 'virtual' types: they can be overridden, can be abstract and can have a default.
However, the user has to specify those types and their concrete instantiations manually; that is, the user have to provide a complete mapping from all virtual type to concrete instantiation.
When the number of associated types is small this poses no issue, but it hinders designs where the number of associated types is large. In this paper we examine the possibility of completing a partial mapping in a desirable way, so that the resulting mapping is sound and also robust with respect to code evolution.

The core of our design is to reuse the concept of nested classes instead of relying of a new kind of member for associated types. An operation, call Redirect, will redirect some nested classes in some external types. To simplify our formalization and to keep the focus on the core of our approach, we present our system on top of a simple Java like languages, with only final classes and interfaces, when code reuse is obtained by trait composition instead of conventional inheritance. We rely on a simple nominal type system, where subtyping is induced only by implementing interfaces; in our approach we can express generics without having a polymorphic type system. To simplify the treatment of state, we consider fields to be always instance private, and getters and setters to be automatically generated, together with a static method of(...) that would work as a standard constructor, taking the value of the fields and initializing the instance. In this way we can focus our presentation to just (static) methods, nested classes and implements relationships. Expanding our presentation to explicitly include visible fields, constructors and sub-classing would make it more complicated without adding any conceptual underpinning. In our proposed setting we could write:

```
SBox={String inner;
37
     method String inner(){..}//implicit
38
     static method SBox of(String inner){..}}//implicit
39
40
     Box={Elem inner}//implicit Box(Elem inner) and Elem inner()
41
42
     Elem={Elem concat(Elem that)}
     static method Box merge(Box b, Elem e){return Box.of(b.inner().concat(e));}
43
  Result=myTrait <Box=SBox>//equivalent to trait <Box=SBox, Elem=String>
45
     ...Result.merge(SBox.of("hello "), "world");//hello world
```

50

51

56

57

58

59

60

67

71

72

73

75

76

77

78

80

81

83

85

86

87

89

90

93

95

96

Here class SBox is just a container of Strings, and myTrait is code encoding Boxes of any kind of Elem with a concat method. By instantiating myTrait<Box=SBox>, we can infer Elem=String, and obtain the following flattened code, where Box and Elem has been removed, and their occurrences are replaced with SBox and String.

```
Result={static method SBox merge(SBox b,String e){
     return SBox.of(b.inner().concat(e));}}
55
```

Note how Result is a new class that could have been written directly by the programmer, there is no trace that it has been generated by myTrait. We will represent trait names with lower-case names and class/interface names with upper-case names. Traits are just units of code reuse, and do not induce nominal types.

We could have just written Result=myTrait<Elem=String>, obtaining

```
Result={
     Box={String inner}
63
     static method Box merge(Box b,String e){
       return Box.of(b.inner().concat(e));}}
65
```

Note how in this case, class Result.Box would exists. Thanks to our decision of using nested classes as associated types, the decision of what classes need to be redirected is not made when the trait is written, but depends on the specific redirect operation. Moreover, our redirect is not just a way to show the type system that our code is correct, but it can change the behaviour of code calling static methods from the redirected classes.

This example show many of the characteristics of our approach:

- (A) We can redirect mutually recursive nested classes by redirecting them all at the same time, and if a partial mapping is provided, the system is able to infer the complete mapping.
- (B) Box and Elem are just normal nested classes inside of myTrait; indeed any nested class can be redirected away. In case any of their (static) methods was implemented, the implementation is just discarded. In most other approaches, abstract/associated/generic types are special and have some restriction; for example, in Java/Scala static methods and constructors can not be invoked on generic/associated types. With redirect, they are just normal nested classes, so there are no special restrictions on how they can be used. In our example, note how merge calls Box.of(..).
- (C) While our example language is nominally typed, nested classes are redirected over types satisfying the same structural shape. We will show how this offers some advantages of both nominal and structural typing.

A variation of redirect, able to only redirect a single nested class, was already presented in literature. While points (B) and (C) already applies to such redirect, we will show how supporting (A) greatly improve their value.

The formal core of our work is in defining

- ValidRedirect, a computable predicate telling if a mapping respect the structural shapes and nominal subtype relations.
- BestRedirect, a formal definition of what properties a procedure expanding a partial 92 mapping into a complete one should respect.
  - **ChoseRedirect**, an efficient algorithm respecting those properties.

We first formally define our core language, then we define our redirect operator and its formal properties. Finally we motivate our model showing how many interesting examples of generics and associated types can be encoded with redirect. Finally, as an extreme application, we show how a whole library can be adapted to be injected in a different environment.

102

103

104

105

106

107

108

109

110

112

113

114

115

116

118

119

120

121

122

123

124

125

126

127

128

129

131

132

133

134

135

137

139

## **2** Language grammar and well formedness

We apply our ideas on a simplified object oriented language with nominal typing and (nested) interfaces and final classes. Instead of inheritance, code reuse is obtained by trait composition, thus the source code would be a sequence of top level declarations D followed by a main expression; a lower-case identifier t is a trait name, while an upper case identifier C is a class name. To simplify our terminology, instead of distinguishing between nested classes and nested interfaces, we will call  $nested\ class$  any member of a code literal named by a class identifier C. Thus, the term class may denote either an  $interface\ class$  (interface for short) or a  $final\ class$ .

```
e \coloneqq x \mid e. \, m(es) \mid T. \, m(es) \mid e. \, x \mid \mathtt{new} \ T(es)
                                                               expression
                                                                              T ::= \mathtt{This}\, n.\, Cs
                                                                                                                 types
                                                             code literal Tx := Tx
L := \{ \text{ interface } Tz; Ms \} \mid \{ Tz; Mz ; K \}
                                                                                                           parameter
M := static? T m(Txs) e? | private? C = E
                                                                              D := id = E
                                                                  member
                                                                                                         declaration
K ::= (Txz)?
                                                                      state
                                                                               id := C \mid t
                                                                                                       class/trait id
E ::= L \mid t \mid E_1 \leftarrow E_2 \mid E \leftarrow Cs = T > T
                                                             Code Expr.
                                                                                v := new T(vs)
```

In the context of nested classes, types are paths. Syntactically, we represent them as relative paths of form  $\mathtt{Thisn}.Cs$ , where the number n identify the root of our path:  $\mathtt{This0}$  is the current class,  $\mathtt{This1}$  is the enclosing class,  $\mathtt{This2}$  is the enclosing enclosing class and so on.  $\mathtt{Thisn}.Cs$  refers to the class obtained by navigating throughout Cs starting from  $\mathtt{Thisn}$ . Thus,  $\mathtt{This0}$  is just the type of the directly enclosing class. By using a larger then needed n, there could be multiple different types referring to the same class. Here we expect all types to be in the normalized form where the smallest possible n is used.

Code literals L serve the role of class/interface bodies; they contain the set of implemented interfaces Tz, the set of members Mz and their (optional) state. In the concrete syntax we will use **implements** in front of a non empty list of implemented interfaces and we will omit parenthesis around a non empty set of fields. To simplify our formalism, we delegate some sanity checks well formedness, and we assume all the fields in the state K to have different names; no two methods or nested classes with the same name (m or C) are declared in a code literal, and no nested class is named **This**n for any number n; in any method headers, all parameters have different names, and no parameter is named **this**.

A class member M can be a (private) nested class or a (static) method. Abstract methods are just methods without a body. Well formed interface methods can only be abstract and non-static. To facilitate code reuse, classes can have (static) abstract methods, code composition is expected to provide an implementation for those or, as we will see, redirect away the whole class. We could easily support private methods too, but to simplify our formalism we consider private only for nested classes. In a well formed code literal, in all types of form  ${\tt Thisn.} Cs.C.Cs'$ , if C denotes a private nested class, then Cs is empty. We assume a form of alpha-reaming for private nested classes, that will consistently rename all the paths of form  ${\tt Thisn.} C.Cs'$ , where  ${\tt Thisn.} C$  refer to such private nested class. The trivial definition of such alpha rename is given in appendix.

Expressions are used as body of (static) methods and for the main expression. They are variables x (including this) and conventional (static) method calls. Field access and new expressions are included but with restricted usage: well formed field accesses are of form this.x in method bodies and v.x in the main expression, while well formed new expressions have to be of form new ThisO(xs) in method bodies and of form v in the main expression. Those restrictions greatly simply reasoning about code reuse, since they require different classes to only communicate by calling (static) methods. Supporting unrestricted fields and constructors would make the formalism much more involved without adding much of a

,. 4

143

144

145

146

147

148

149

150

153

158

159

160

161

163

164

169

171

conceptual difficulty. Values are of form new T(vs).

For brevity, in the concrete syntax we assume a syntactic sugar declaring a static of method (that serve as a factory) and all fields getters; thus the order of the fields would induce the order of the factory arguments. In the core calculus we just assume such methods to be explicitly declared.

Finally, we examine the shape of a nested class: **private**? C=E. The right hand side is not just a code literal but a code composition expression E. In trait composition, the code expression will be reduced/flattened to a code literal L during compilation. Code expressions denote an algebra of code composition, starting from code literal L and trait names t, referring to a literal declared before by t=E. We consider two operators: conventional preferential sum  $E_1 \leftrightarrow E_2$  and our novel redirect E < Cs = T >.

### 2.1 Compilation process/flattening

The compilation process consists in flattening all the E into L, starting from the innermost leftmost E. This means that sum and redirect work on LVs: a kind of L, where all the nested classes are of form C=LV. The execution happens after compilation and consist in the conventional execution of the main expression e in the context of the fully reduced declarations, where all trait composition has been flatted away. Thus, execution is very simple and standard and behaves like a variation of FJ[] with interfaces instead of inheritance, and where nested classes are just a way to hierarchically organize code names. On the other side, code composition in this setting is very interesting and powerful, where nested classes are much more than name organization: they support in a simple and intuitive way expressive code reuse patterns. To flatten an E we need to understand the behaviour of the two operators, and how to load the code of a trait: since it was written in another place, the syntactic representation of the types need to be updated. For each of those points we will first provide some informal explanation and then we will proceed formalizing the precise behaviour.

### 2.1.1 Redirect

Redirect takes a library literal and produce a modified version of it where some nested classes has been removed and all the types referencing such nested classes are now referring to an external type. It is easy to use this feature to encode a generic list:

```
172
   list={
173
     Elem={}
174
      static This0 empty() = new This0(Empty.of())
175
      boolean isEmpty() = this.impl().isEmpty()
176
     Elem head() = this.impl.asCons().tail()
177
      ThisO tail()=this.impl.asCons().tail()
178
      ThisO cons(Elem e) = new ThisO(Cons.of(e, this.impl)
179
      private Impl={interface
                                  Bool isEmpty() Cons asCons()}
180
      private Empty={implements
181
                                  This1
        Bool isEmpty()=true Cons asCons()=../*error*/
182
183
        ()}//() means no fields
      private Cons={implements This1
184
                                Cons asCons()=this
        Bool isEmpty()=false
185
        Elem elem Impl tail }
186
      Impl impl
187
188
189
   IntList=list<Elem=Int>
190
   IntList.Empty.of().push(3).top()==4 //example usage
191
```

This would flatten into

212

213

223

224

232

233

234

236

237

```
list={/*as before*/
195
    //IntList=list < Elem=Int >
196
   IntList={
197
      //Elem={} no more nested class Elem
198
      static This0 empty() = new This0(Empty.of())
199
      boolean isEmpty() = this.impl().isEmpty()
      Int head() = this.impl.asCons().tail()
201
      ThisO tail()=this.impl.asCons().tail()
202
     ThisO cons(Int e)=new ThisO(Cons.of(e, this.impl)
203
      private Impl={interface
                                Bool isEmpty() Cons asCons()}
204
      private Empty={/*as before*/}
205
      private Cons={implements This1
206
                               Cons asCons()=this
        Bool isEmpty()=false
207
208
        Int elem Impl tail }
      Impl impl
209
      }//everywhere there was "Elem", now there is "Int"
319
```

Redirect can be propagated in the same way generics parameters are propagate: For example, in Java one could write code as below,

to denote a class containing a list of a certain kind of **Shapes**. In our approach, one could write the equivalent

```
225
226 shapeGroup={
227  Shape={implements Shape}
228  List=list<Elem=Shape>
229  List shapes
230  ..}
```

With redirect, shapeGroup follow both roles of the two Java examples; indeed there are two reasonable ways to reuse this code

Triangolation=shapeGroup<Shape=Triangle>, if we have a Triangle class and we would like the concrete list type used inside to be local to the Triangolation, or Triangolation=shapeGroup<List=Triangles>, if we have a preferred implementation for the list of triangles that is going to be used by our Triangolation. Those two versions would flatten as follow:

```
//Triangolation=shapeGroup <Shape=Triangle>
239
240
   Triangolation={
      List=/*list with Triangle instead of Elem*/
241
      List shapes
242
243
      ..}
    //Triangolation=shapeGroup <List=Triangles>
245
246
    //exapands to shapeGroup<List=Triangles,Shape=Triangle> \,
    Triangolation={
247
      Triangles shapes
248
348
```

As you can see, with redirect we do not decide a priori what is generic and what is not in a class.

Redirect can not always succeed. For example, if we was to attempt shapeGroup<List=Int>
the flattening process would fail with an error similar to a invalid generic instantiation.

257

259

260

262

263

265

266

267

268

269

270

271

272

273

274

276

277

278

279

291

292

294

300

302

Subtype is a fundamental feature of object oriented programming. Our proposed redirect operator do not require the type of the target to perfectly match the structural type of the internal nested classes; structural subtyping is sufficient. This feature adds a lot of flexibility to our redirect, however completing the mapping (as happens in the example above) is a challenging and technically very interesting task when subtyping is took into account. This is strongly connected with ontology matching and will be discussed in the technical core of the paper later on.

#### Preferential sum and examples of sum and redirect working 2.1.2 together

The sum of two traits is conceptually a trait with the sum of the traits members, and the union of the implemented interfaces. If the two traits both define a method with the same name, some resolution strategy is applied. In the symmetric sum [] the two methods need to have the same signature and at least one of them need to be abstract. With preferential sum (sometimes called override), if they are both implemented, the left implementation is chosen. Since in our model we have nested classes, nested classes with the same name will be recursively composed.

We chose preferential sum since is simpler to use in short code examples. <sup>1</sup> Since the focus of the paper is the novel redirect operator, instead of the well known sum, we will handle summing state and interfaces in the simplest possible way: a class with state can only be summed with a class without state, and an interface can only be summed with another interface with identical methods signatures.

In literature it has been shown how trait composition with (recursively composed) nested classes can elegantly handle the expression problem and a range of similar design challenges. Here we will show some examples where sum and redirect cooperate to produce interesting code reuse patterns:

```
280
   listComp=list<+{
281
     Elem:{ Int geq(Elem e)}//-1/0/1 for smaller, equals, greater
282
      static Elem max2(Elem e1, Elem e2)=if e1.geq(e2)>0 then e1, else e2
283
284
     Elem max(Elem candidate)=
        if This.isEmpty() then candidate
285
        else this.tail().max(This.max2(this.head(),candidate))
286
287
     Elem min(Elem candidate) = . . .
      This0 sort()=...
288
288
```

As you can see, we can extends our generic type while refining our generic argument: Elem of listComp now needs a geq method.

While this is also possible with conventional inheritance and F-Bound polymorphism, we think this solution is logically simpler then the equivalent Java

```
295
   class ListComp<Elem extends Comparable<Elem>> extends LinkedList<Elem>{
296
     ../*body as before*/
297
298
```

Another interesting way to use sum is to modularize behaviour delegation: consider the following (not efficient for the sake of compactness) implementation of set, where the way to compare elements is not fixed:

symmetric sum is often presented in conjunction with a restrict operator that makes some methods abstract.

```
set:{
304
      Elem:{}
305
      List=list <Elem=Elem>
306
      static This0 empty() = new This0(List.empty())
307
      Bool contains (Elem e) = ... /*uses eq and hash*/
308
      Int size()=..
309
      This add(Elem e) = ...
310
311
      This remove(Elem e)=.
      Bool eq(Elem e1, Elem e2) // abstract
312
      Int hash(Elem e)//abstract
313
      List asList //to allow iteration
314
315
    eqElem={
316
      Elem={ Bool equals(Elem e)/*abstract*/}
317
      Bool eq(Elem e1,Elem e2)=e1.equals(e2)
318
319
    hashElem={
320
      Elem={ Int hash(Elem e) /*abstract*/}
321
322
      Int hash(Elem e) = e.hash()
323
    Strings=(set<+eqElem<+eqHash)<Elem=String>
324
    LongStrings=(set<+eqElem)<Elem=String> <+{</pre>
325
326
      Int hash(String e)=e.size()
      }//for very long strings, size is a faster hash
327
```

Note how (set<+eqElem<+eqHash)<Elem=String> is equivalent to set<Elem=String> <+eqElem<Elem=String> <+eqHash<Elem
Consider now the signature Bool equals(Elem e). This is different from the common signature Bool equals(Object e). What is the best signature for equals is an open research question, where most approaches advise either the first or the second one. Our eqElem, as is wrote, can support both: Strings would be correctly define both if String.equals signature has a String or an Object parameter.EXPAND on method subtyping.

#### 2.2 Moving traits around in the program

329

330

331

333

334

337

338

339

340

341

343

344

345

346

348

349

p := DLs; DVs

It is not trivial to formalize the way types like  $\mathtt{This1.A.B}$  have to be adapted so that when code is moved around in different depths of nesting the refereed classes stay the same. This is needed during flattening, when a trait t is reused, but also during reduction, when a method body is inlined in the main expression, and during typing, where a method body is typed depending on the signature of other methods in the system.

To this aim we define a concept of program p, as a representation of the code as seen from a certain point inside of the source code. It is the most interesting form of the grammar, used for virtually all reduction and typing rules. On the left of the ; is a stack representing which (nested) declaration is currently being processed, the bottom (rightmost) DL represents the D of the source-program that is currently being processed. Th right of the ; represents the top-level declarations that have already been compiled, this is necessary to look up top-level classes and traits. That is, each of the  $DL_0 \dots DL_n$  represents the outer nested level 0..n, while the DVs component represent the already flattened portion of the program top level, that is the outer nested level n+1

program

```
DL := id = L \qquad \text{partially-evaluated-declaration} DV := id = LV \qquad \text{evaluated-declaration} Mid := C \mid m \qquad \text{member-id} \text{Thus, for example in the program} \mathbf{A} = \{()\}
```

```
t={ B={()}
                           This1.A m(This0.B b)}
354
     C={D={E=t}}
355
     H=t. <B=A>
356
     the flattened version for C.D.E will be { B={()} This3.A m(This0.B b)}, where the path
     This1.A is now This3.A while the path This0.B stays the same: types defined internally will
359
     stay untouched. The program p in the observation point E=t is
360
361
362
     t={ B={()}
                           This1.A m(This0.B b)}
363
     C={D={E=t}};
364
     C={D={E=t}},//this means, we entered in C
365
     D=\{E=t\}//this means, we entered in D
369
          To fetch a trait form a program, we will use notation p(t) = LV, to fetch a class we will
368
369
     To look up the definition of a class in the program we will use the notation p(T) = LV, which
370
     is defined by the following:,
                   (; , C = L, )(This 0.C.Cs) := L(Cs)
                (id = L, DLs; DVs)(This 0.Cs) := L(Cs)
          (id = L, DLs; DVs)(\mathtt{This}\,n + 1.Cs) \coloneqq DLs; DVs(\mathtt{This}\,n.Cs)
372
                                              LV(\emptyset) := LV
                                           L(C.Cs) := L_0(Cs) where L = interface? {\_; \_, C = L_0, \_; \_}
373
          This notation just fetch the referred LV without any modification. To adapt the paths
374
     we define T_{0\cdot\mathbf{from}(T_1)}, L_{\cdot\mathbf{from}(T)} and p_{\cdot\mathbf{minimize}(T)} as following:
               This n.Cs._{\mathbf{from}(\mathtt{This}\,m.C_1...C_k)} \coloneqq \mathtt{This}\,m.C_1...C_{(k-n)} \quad with \ n \leq k
               \mathtt{This} n. Cs._{\mathbf{from}(\mathtt{This} m. C_1...C_k)} \coloneqq \mathtt{This}(m+n-k). C_1 \ldots C_{(k-n)} Cs \quad \textit{with } n > k
                                         L_{\cdot \mathbf{from}(T)} \coloneqq L_{\cdot \mathbf{from}(T)_0}
          \{\texttt{interface}?Tz;\ Mz;\ K\}_{\mathbf{from}(T)_j} \coloneqq \{\texttt{interface}?Tz._{\mathbf{from}(T)_{j+1}};\ Mz._{\mathbf{from}(T)_{j+1}};\ K._{\mathbf{from}(T)_{j+1}}\}
376
                    \mathtt{This}(j+n).Cs_{0\cdot\mathbf{from}(T)_{j}} \coloneqq \mathtt{This}(j+k).Cs_{1} \quad \textit{with } \mathtt{This} n.Cs_{0\cdot\mathbf{from}(T)} = \mathtt{This} k.Cs_{1}
                             \mathbf{This} n. Cs._{\mathbf{from}(T)_{\ i}} \coloneqq \mathbf{This} n. Cs._{\mathbf{from}(T)} \quad \textit{with } n < j
                                    p._{\mathbf{minimize}(T)} \coloneqq T'....
377
     Finally, we we combine those to notation for the most common task of getting the value of a
378
     literal, in a way that can be understand from the current location: p[t] and p[T]:
379
          (DL_1 \dots DL_n; \_, t = LV, \_)[t] := LV \cdot_{\mathbf{from}(\mathbf{This}n)}
380
                                          p[T] := p_{\cdot \mathbf{minimize}(p(T) \cdot \mathbf{from}(T))}
381
382
383
```

## 3 Flattening

Aside from the redirect operation itself, compilation/flattening is the most interesting part, it is defined by reduction arrow  $Ds \Rightarrow Ds'$ , where eventually Ds' is going to reach form DVsand  $p; id \vdash E \Rightarrow E'$ , where eventually E' is going to reach form LV. The id represents the identifier of the type/trait that we are currently compiling, it is needed since it will be the name of This0, and we use that fact that that is equal to This1.id to compare types for equality. Rule (TOP) selects the leftmost id = E where E is not of form LV and DVz: a well

394

395

397

398

399

400

402

403

404

405

407

408

410

411

412

413

414

415

416

417

418

419

420

421

422

typed subset of the preceding declarations. E is flattened in the contex of such DVz, thus by rule (Trait) DVz must contain all the trait names used in E.

The (CTXV) rule is the standard context, the (L-ENTER) rule propegates compilation inside of nested-classes, (TRAIT) merely evaluates a trait reference to it's defined body, finally (SUM) and (REDIRECT) perform our two meta-operations by propagating to corresponding auxiliary definitions.  $LV_1 < +_{p'} LV_2 = LV_3$ . Rule (SUM) just delegate the work on the auxiliar notation defined on its right. As usual in definitions of sum operators, the implemented interfaces is the union of the interfaces of  $L_1$  and  $L_2$ , the members with the same domain are recursively composed while the members with disjoint domains are directly included. Since method and nested class identifiers must be unique in a well formed L and  $M_1 \leftarrow M_2$ being defined only if the identifier is the same, our definition forces dom(Mz) = dom(Mz')and  $dom(Mz_1)$  disjoint  $dom(Mz_2)$ . For simplicity here we require at most one class to have a state; if both have no state, the result will have no state, otherwise the result will have the only present state (the set  $\{empty, K?\}$  mathematically express this requirement in a compact way); we also allow summing only interfaces with interfaces and final classes with final classes. When two interfaces are composed both sides must define the same methods. This is because other nested classes inside  $L_1$  may be implementing such interface, and adding methods to such interface would require those classes to somehow add an implementation for those methods too. In literature there are expressive ways to soundly handle merging different state, composing interfaces with final classes and adding methods to interfaces, but they are out of scope in this work.

Member composition  $M_1 \leftarrow M_2$  uses the implementation from the right hand side, if available, otherwise if the right hand side is abstract, the body is took from the left side. Composing nested classes, not how they can not be **private**; it is possible to sum two literals only if their private nested classes have different private names. This constraint can always be obtained by alpha-renaming them.

We have two-top level reduction rules defining our language, of the form  $Dse^{--} > Ds'e$  which simply reduces the source-code. The first rule (compile) 'compiles' each top-level declaration (using a well-typed subset of allready compiled top-level declarations), this reduces the defining expression. The second rule, (main) is executed once all the top-level declarations have compiled (i.e. are now fully evaluated class literals), it typechecks the top-level declarations and the main expression, and then procedes to reduce it. In principle only one-typechecking is needed, but we repeat it to avoid declaring more rules.

```
Define Ds e --> Ds' e'
424
  _____
425
  DVs' |- Ok
426
  empty; DVs'; id | E --> E'
427
  (compile)----- DVs' subsetof DVs
  DVs id = E Ds e --> DVs id = E' Ds e
429
  DVs |- Ok
431
  DVs |- e : T
432
  DVs |- e --> e'
  (main)----- for some type T
434
  DVs e --> DVs e'
    gff
436
```

#### Figure 1 Flattening

```
Def: Ds \Rightarrow Ds' and p; id \vdash E \Rightarrow E', where \mathcal{E}_V := \square \mid \mathcal{E}_V \prec + E \mid LV \prec + \mathcal{E}_V \mid \mathcal{E}_V \prec Cs = T > \mathcal{E}_V \prec 
(TOP)
                                          DVz \subseteq DVs
                                            DVz \vdash \mathbf{Ok}
                                                                                                                                                                    (L-enter)
                                                                                                                                                                   \frac{p._{\mathbf{push}(id=L[C=E])}; C \vdash E \Rightarrow E'}{p; id \vdash L[C=E] \Rightarrow L[C=E']} \qquad \frac{(\text{TRAIT})}{p; id \vdash t \Rightarrow p[t]}
           empty; DVz; id \vdash E \Rightarrow E'
 DVs id=EDs \Rightarrow DVs id=E'Ds
                                                                                                                                Def: L_1 < +L_2 = L_3
                                                                                                                                          L_1 = interface? \{Tz_1; Mz, Mz_1; K?_1\}
                                                                                                                                          L_2 = interface? \{Tz_2; Mz', Mz_2; K?_2\}
(SUM)
                                                                                                                                          L_3 = \texttt{interface}? {Tz_1 \cup Tz_2; Mz \leftarrow Mz', Mz_1, Mz_2; K?}
                 LV_1 \leftarrow LV_2 = LV_3
                                                                                                                                          \{empty, K?_1, K?_2\} = \{empty, K?\}
p; id \vdash LV_1 \lt + LV_2 \Rightarrow LV_3
                                                                                                                                          if interface? = interface then mdom(L_1) = mdom(L_2)
                                                                                                                                Def: Tm(Txs)e?<+Tm(Txs)e = Tm(Txs)e
                                                                                                                                Def: Tm(Txs)e? \leftarrow Tm(Txs) = Tm(Txs)e?
                                                                                                                                Def: (C=L) < + (C=L') = C = L < + L,
(REDIRECT)
                                                       p' = p_{\cdot \mathbf{push}(C=L)}
                                          Csz = p'_{\cdot \mathbf{redirectSet}(R)}
                                                   p'·redirectable(Csz)
 R' = p' \cdot_{\mathbf{bestRedirection}(R[\mathbf{This}n = \mathbf{This}n + 1])}
            p: id \vdash LV \lt R \gt \Rightarrow R'(L_{\text{remove}(Csz)})
          L[C = E'] := interface? \{Tz; MVs C = E' Ms; K?\}
                     where L = interface? \{Tz; MVs C = Ms; K?\}
                     Ts \in p := \forall T \in Ts \bullet p(T) is defined
          \mathcal{E}_V ::= \square | \mathcal{E}_V \leftarrow E | LV \leftarrow \mathcal{E}_V | \mathcal{E}_V \leftarrow Cs = T > 0
                                                                                                                                                                                                                                                    context of library-evaluation
            \mathcal{E}_v := \square | \mathcal{E}_v . m(es) | v . m(vs \mathcal{E}_v es) | T . m(vs \mathcal{E}_v es)
```

### 4 Type System

438

439

450

454

The type system is split into two parts: type checking programs and class literals, and the typechecking of expressions. The latter part is mostly convential, it involves typing judgments of the form  $p; Txs \vdash e : T$ , with the usual program p and variable environement Txs (often called  $\Gamma$  in the literature). rule (Dsok) type checks a sequence of top-level declarations by simply push each declaration onto a program and typecheck the resulting program. Rule pok typechecks a program by check the topmost class literal: we type check each of it's members (including all nested classes), check that it properly implements each interface it claims to, does something weird, and finanly check check that it's constructor only referenced existing types,

483

485

486

487

488

489

```
D1; Ds |- Ok ... Dn; Ds|- Ok
   (Ds ok) ----- Ds = D1 ... Dn
   Ds |- Ok
457
   p |- M1 : Ok .... p |- Mn : Ok
459
   p |- P1 : Implemented .... p |- Pn : Implemented
   p |- implements(Pz; Ms) /*WTF?*/
                                               if K? = K: p.exists(K.Txs.Ts)
   (p ok) ----- p.top() = interface? {P1...Pn; M1, ..., Mn; K7
462
   p |- 0k
464
   p.minimize(Pz) subseteq p.minimize(p.top().Pz)
465
   amt1 _ in p.top().Ms ... amtn _ in p.top().Ms
   (P implemented) ----- p[P] = interface {Pz; amt1 ... ar
467
   p |- P : Implemented
468
469
   (amt-ok) ----- p.exists(T, Txs.Ts)
470
   p |- T m(Tcs) : Ok
472
  p; ThisO this, Txs |- e : T
473
   (mt-ok) ----- p.exists(T, Txs.Ts)
474
   p \mid - T m(Tcs) e : Ok
475
  C = L, p \mid - Ok
477
   (cd-0k) -----
   p \mid - C = L : OK
480
```

Rule (*Pimplemented*) checks that an interface is properly implemented by the programtop, we simply check that it declares that it implements every one of the interfaces superinterfaces and methods. Rules (amt - ok) and (mt - ok) are straightforward, they both check that types mensioned in the method signature exist, and ofcourse for the latter case, that the body respects this signature.

To typecheck a nested class declaration, we simply push it onto the program and typecheck the top-of the program as before.

The expression type system is mostly straightforward and similar to feartherwieght Java, notable we use p[T] to look up information about types, as it properly 'from's paths, and use a classes constructor definitions to determine the types of fields.

```
p; Txs |- e0.m(e1 ... en) : T'
503
  (field)
504
  p; Txs |- e : T
  ----- p[T].K = constructor(_ T' x _)
506
  p; Txs |- e.x : T'
507
508
509
  (new)
  p; Txs |- e1 : T1 ... p; Txs |- en : Tn
511
  -----p[T].K = constructor(T1 x1 ... Tn xn)
  p; Txs |- new T(e1 ... en)
514
515
516
  (sub)
  p; Txs |- e : T
517
  ----- T' in p[T].Pz
  p; Txs |- e : T'
519
520
521
  (equiv)
522
  p; Txs |- e : T
  ----- T =p T'
  p; Txs |- e : T'
```

## 5 Graph example

527

529

548

549

550

551

We now consider an example where Redirect simplifies the code quite a lot: We have a **Node** and **Edge** concepts for a graph. The **Node** have a list of **Edges**. A isConnected function takes a list of **Nodes**. A getConnected function takes **Node** and return a set of **Nodes**.

```
530
   graphUtils={
     Edges:list<+{Node start() Node end()}</pre>
532
     Node: {Edges connections()}
533
     Nodes:set<Elem=Node>//note that we do not specify equals/hash
534
      static Bool isConnected(Nodes nodes)=
535
       if(nodes.size()=0) then true
536
        else getConnected(nodes.asList().head()).size()==nodes.size()
      static Nodes getConnected(Node node) = getConnected(node, Nodes.empty())
538
539
      static Nodes getConnected(Node node, Nodes collected)=
        if(collected.contains(node)) then collected
540
        else connectEdges(node.connections(),collected.add(node))
541
542
      static Nodes connectEdges(Edges e, Nodes collected) =
       if( e.isEmpty()) then collected
543
        else connectEdges(e.tail(),collected.add(e.head().end()))
544
545
```

We have shown the full code instead of omitting implementations to show that the code inside of an highly general code like the former is pretty conventional. Just declare nested classes as if they was the concrete desired types. Note how we can easly create a new Nodes@by doing Nodes.empty().

Here we show how to instantiate <code>graphUtils</code> to a graph representing cities connected by streets, where the streets are annotated with their length, and <code>Edges</code> is a priority queue, to optimize finding the shortest path between cities.

```
Map: {
555
      Street:{City start,City end, Int size}
556
      City:{}
557
      Streets: priorityQueue < Elem = Street > < + {
558
        Int geq(Street e1,Street e2)=e1.size()-e2.size()}
559
560
561
      Streets:{}
      City:{Streets connections, Int index}//index identify the node
      Cities:set<Elem=City><+{</pre>
563
        Bool eq(City e1,City e2) e1.index==e2.index
564
        Int hash(City e) e.index
565
566
      Cities cities
567
      //more methods
568
569
570
    MapUtils=graphUtils < Nodes = Map. Cities >
    //infers Nodes.List, Node, Edges, Edge
571
```

In Appending 2 we will show our best attempt to encode this graph example in Java, Rust and Scala. In short, we discovered... – towel1:.. //Map: towel2:.. //Map: lib: T:towel1 f1 ... fn

MyProgram: T:towel2 Lib:lib[.T=This0.T] ... -

### 6 extra

Features: Structural based generics embedded in a nominal type system. Code is Nominal, Reuse is Structural. Static methods support for generics, so generics are not just a trik to make the type system happy but actually change the behaviour Subsume associate types. After the fact generics; redirect is like mixins for generics Mapping is inferred-> very large maps are possible -> application to libraries

In literature, in addition to conventional Java style F-bound polymorphism, there is another way to obtain generics: to use associated types (to specify generic paramaters) and inheritence (to instantiate the paramaters). However, when parametrizing multiple types, the user to specify the full mapping. For example in Java interface A<B> B m(); inteface BString f(); class G<TA extends A<TB>, TB>//TA and TB explicitly listed String g(TA a TB b)return a.m().f(); class MyA implements A<MyB>... class MyB implements B .. G<MyA,MyB>//instantiation Also scala offers genercs, and could encode the example in the same way, but Scala also offers associated types, allowing to write instead....

Rust also offers generics and associated types, but also support calling static methods over generic and associated types.

We provide here a fundational model for genericty that subsume the power of F-bound polimorphims and associated types. Moreover, it allows for large sets of generic parameter instantiations to be inferred starting from a much smaller mapping. For example, in our system we could just write g=A= method B m() B= method B f() method B f() method B f() method B f() method B f()="Hello"; ... B g(A=MyA)/instantiation. The mapping A=MyA, B=MyB

We model a minimal calculus with interfaces and final classes, where implementing an interface is the only way to induce subtyping. We will show how supporting subtyping constitute the core technical difficulty in our work, inducing ambiguity in the mappings. As you can see, we base our generic matches the structor of the type instead of respecting a subtype requirement as in F-bound polymorphis. We can easily encode subtype requirements by using implements: Print=interface method String print(); g= A:implements

### 23:14 Using nested classes as associated types.

```
Print method A printMe(A a1,A a2) if(a1.print().size()>a2.print.size())return a1; return a2;
    \label{eq:myPrint} \mbox{MyPrint=implements Print .. g<A=MyPrint>//instantiation g<A=Print>//works too}
606
                    - example showing ordering need to strictly improve EI1: interface EA1: imple-
607
    ments\ EI1
        EI2: interface EA2: implements EI2
609
        EB: EA1 a1 EA1 a1
610
        A1: A2: B: A1 a1 A2 a2 [B = EB] // A1 -> EI1, A2 -> EA2 a // A1 -> EA1, A2 ->
611
    EI2 b // A1 -> EA1, A2 -> EA2 c
612
        a <= b \ b <= a \ c <= a, b \ a <= c
        hi Hi class
614
                          a := b \quad c
        aahiHiclassqaq \ a \coloneqq b \ c
615
                          a := b c
        }}][()]
616
         (TOP)
         a \underset{b}{\rightarrow} c \quad \forall i < 3a \vdash b : OK
             \forall i < 3a \vdash b : OK
                  1+2 \rightarrow 3
```