

Uncertainty Quantification Patterns

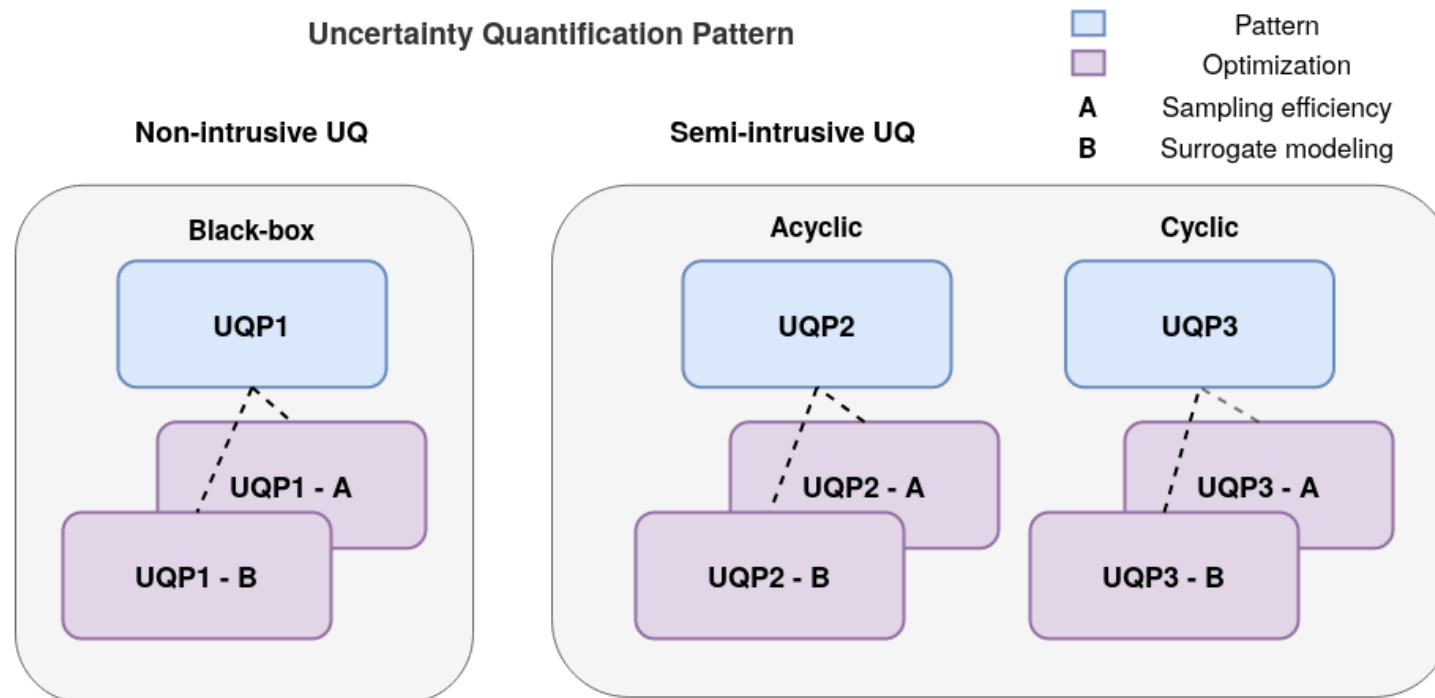
UKAEA NEPTUNE kickoff meeting
18-01-2021

Wouter Edeling
CWI Amsterdam

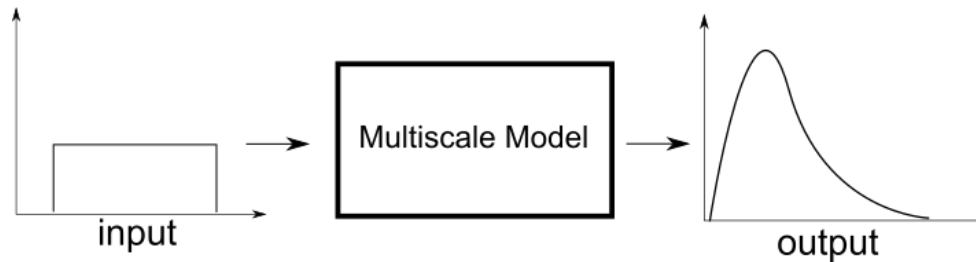
- **VECMA** = Verified Exascale Computing for Multiscale Applications (www.vecma.eu)
- **Main goals:**
 - Automate VVUQ for diverse multiscale applications.
 - Exploit peta / (emerging) exascale HPC resources.
- **Application partners**
 - Fusion (Max Planck Institute of Plasma Physics)
 - Material Science (UCL)
 - Biomedicine (UCL, UvA)
 - Migration (Brunel University)
 - Climate Modelling (CWI)
 - HPC partners: Bull Atos, PSNC, LRZ
- **Main deliverable: VECMA toolkit**
 - Surrogate models for small-scale processes.
 - Forward uncertainty propagation.
 - Tools for submitting ensembles on HPC machines.

UQ Patterns

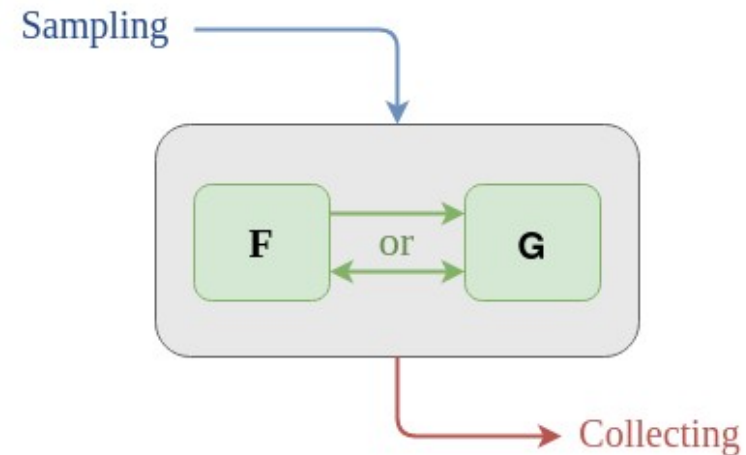
- UQ Pattern (**UQP**): generic UQ templates for **forward uncertainty propagation**
 - 2 levels of intrusion: non-intrusive & semi-intrusive
 - 2 types of multiscale model: acyclic & cyclic
 - 2 types of optimization: efficient sampling (A) & surrogate models (B)



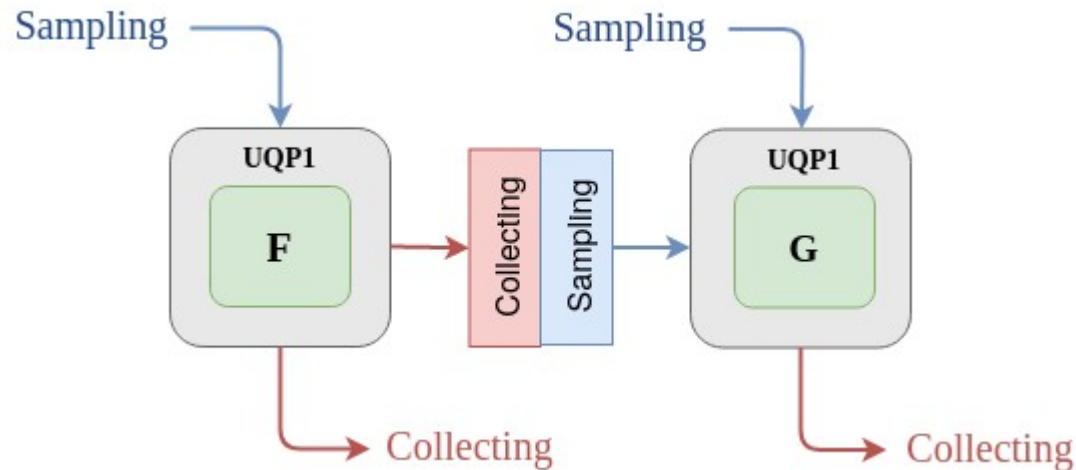
- Forward UQ: propagate uncertainties from the inputs to the output:



- A multiscale model is a **collection** of different submodels or codes.
- UQP1: ignore this, treat as black box:
 - Fully non-intrusive
 - Methods: Monte Carlo, stochastic collocation
 - Later: SC with efficient sampling (UQP1-A)

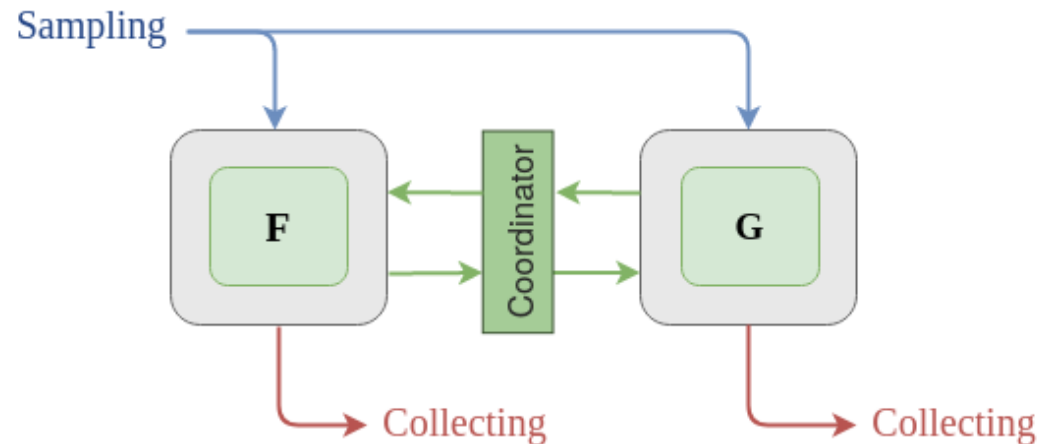


- UQP2: **acyclic** multiscale models
 - Uncertainty flows in one direction, no feedback
 - Semi-intrusive: don't modify submodels, do modify connection between submodels



- If we replace submodel G with a surrogate: UQP2-B.

- UQP3: **cyclic** multiscale models
 - Information is exchanged between submodels.
 - Also semi intrusive.



- Cyclic multi-scale models with efficient sampling/surrogates (UQP3-A/B):

A. Nikishova, *Semi-intrusive uncertainty propagation for multiscale models*, *J. Comp. Sci.*, 35, 80–90, 2019.

UQP speedup



- You can derive potential speedups of different UQPs
- Speedup of UQP2-A (wrt UQP1):

$$\frac{C_{\text{UQP1}_\mu}}{C_{\text{UQP2-A}_\mu}} = \frac{n^{d_M+d_\mu} C_\mu}{n^{d_\mu+d_y} C_\mu} = n^{d_M-d_y}.$$

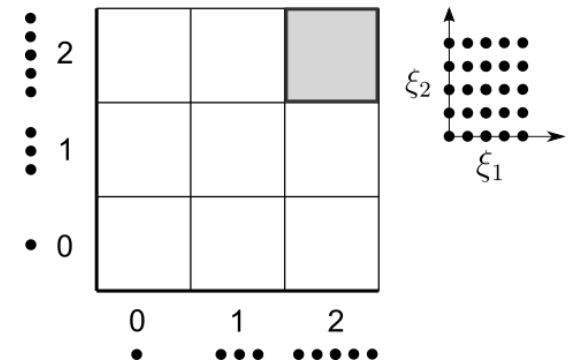
- For more information on the UQPs and their speedups:

D. Ye, L. Veen. A. Nikishova, *Uncertainty Quantification Patterns for Multiscale Models*, Roy Soc Phil Trans A (accepted), 2021.

- Let $q(\xi)$ be the output of some computational model.
- This talk: assess the impact of uncertainties in ξ on q
- Common techniques: (Quasi) MC, Polynomial Chaos, Stochastic Collocation:

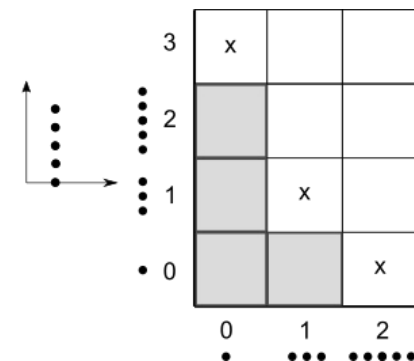
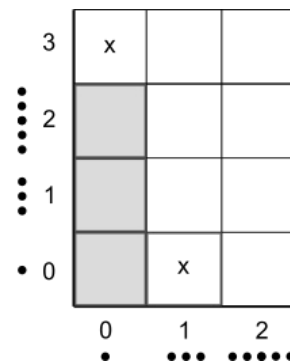
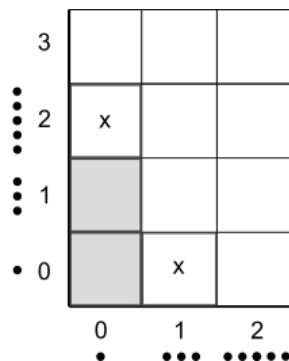
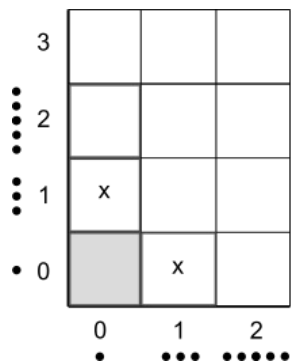
$$q(\xi) \approx \tilde{q}(\xi) = \sum_{j_1=1}^{m_1} \cdots \sum_{j_d=1}^{m_d} q(\xi_{j_1}, \dots, \xi_{j_d}) a_{j_1}(\xi_1) \otimes \cdots \otimes a_{j_d}(\xi_d)$$

- Basic building blocks: **1D quadrature rules**
- Extended to d dimensions via tensor product
- Computational cost: m^d



Curse of dimensionality

- For many computational models: $\xi \in \mathbb{R}^d$ with $d \gg 10$
- In which case m^d is far too expensive
- UQP1-A: **dimension-adaptive sampling** (Gerstner & Griebel (2003))
- Basic idea:
 - **Initialize:** start with a single sample.
 - **Look ahead:** evaluate code in 'candidate directions'
 - **Rank order:** compute error metric for all directions
 - **Adapt:** only add direction with highest error to sampling plan



x = admissible forward neighbour

Ensemble execution

- 'Look-ahead' step: evaluate code in new directions: ensemble computation
- One possibility: FabSim3
 - Python3 automation toolkit.
 - Handles data transfer to and from HPC machine
 - One-line commands (command line or API)

run the UQ ensemble

```
fab.run_uq_ensemble(config, campaign.campaign_dir, script='Gray_Scott',  
                    machine="eagle_vecma", PilotJob = False)
```

- Other options: QCG-PilotJob or FabSim3 + QCG-PilotJob
- QCG-PJ: a single job allocation containing many smaller jobs (HTC)
 - Circumvents limitations on number of jobs

- Everything but job execution is handled by **EasyVVUQ**.
- EasyVVUQ: computes
 - distributions,
 - moments
 - Sobol sensitivity indices
- Jalal will talk about this.

```
#perform look-ahead step
sampler.look_ahead(analysis.l_norm)

#####
# Ensemble execution using FabSim3 #
#####

# run the UQ ensemble
fab.run_uq_ensemble(config, campaign.campaign_dir, script='ohagan',
                    machine="eagle_vecma", skip=skip, PilotJob = False)

#wait for jobs to complete and check if all output files are retrieved
#from the remote machine
fab.verify(config, campaign.campaign_dir,
            campaign._active_app_decoder.target_filename,
            machine="eagle_vecma", PilotJob=False)

#run the UQ ensemble
fab.get_uq_samples(config, campaign.campaign_dir,
                   number_of_samples=sampler._number_of_samples,
                   skip=skip,
                   machine='eagle_vecma')

#####
# End ensemble execution using FabSim3 #
#####

#adaptation step
analysis.adapt_dimension('f', data_frame, method='surplus')
```

UQP1-A example: CovidSim

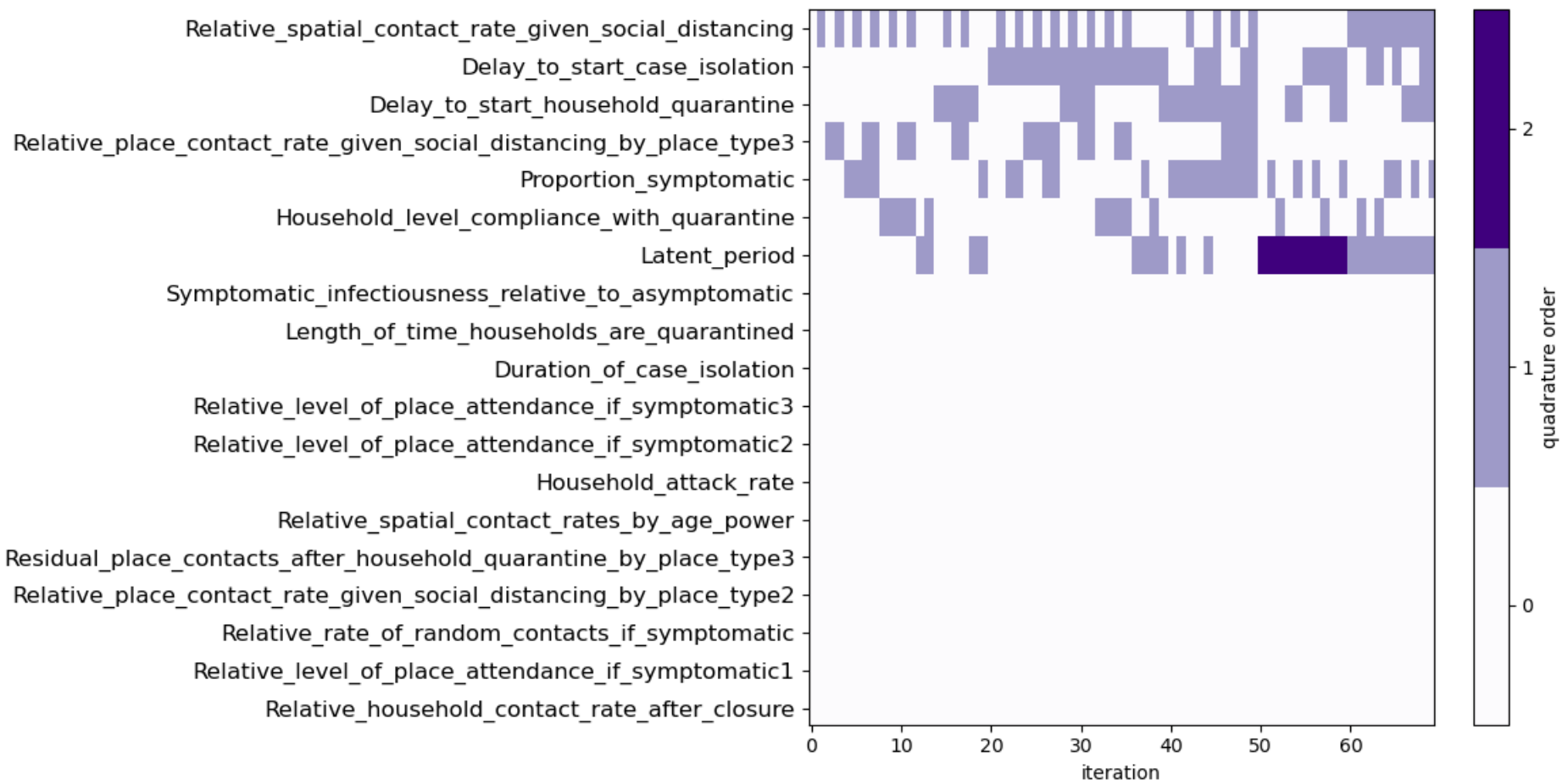


- CovidSim model from Imperial College (Ferguson, 2020)
 - Models effect of Non Pharmaceutical Interventions.
- On request of Royal Society's RAMP team we estimated parametric uncertainty.
- Computational cost single sample: max 10 minutes
 - Using 1 node with 28 cores at PSNC Eagle supercomputer.
- 940 input parameters, of which we identified 60 as interesting to vary
- Grouped these into 1) intervention, 2) disease and 3) geographic inputs.
- 3 separate UQ campaigns: every input that was refined at least once goes in the final campaign.
- Final UQ campaign: 19 input parameters.

UQP1-A: adaptive grid refinement



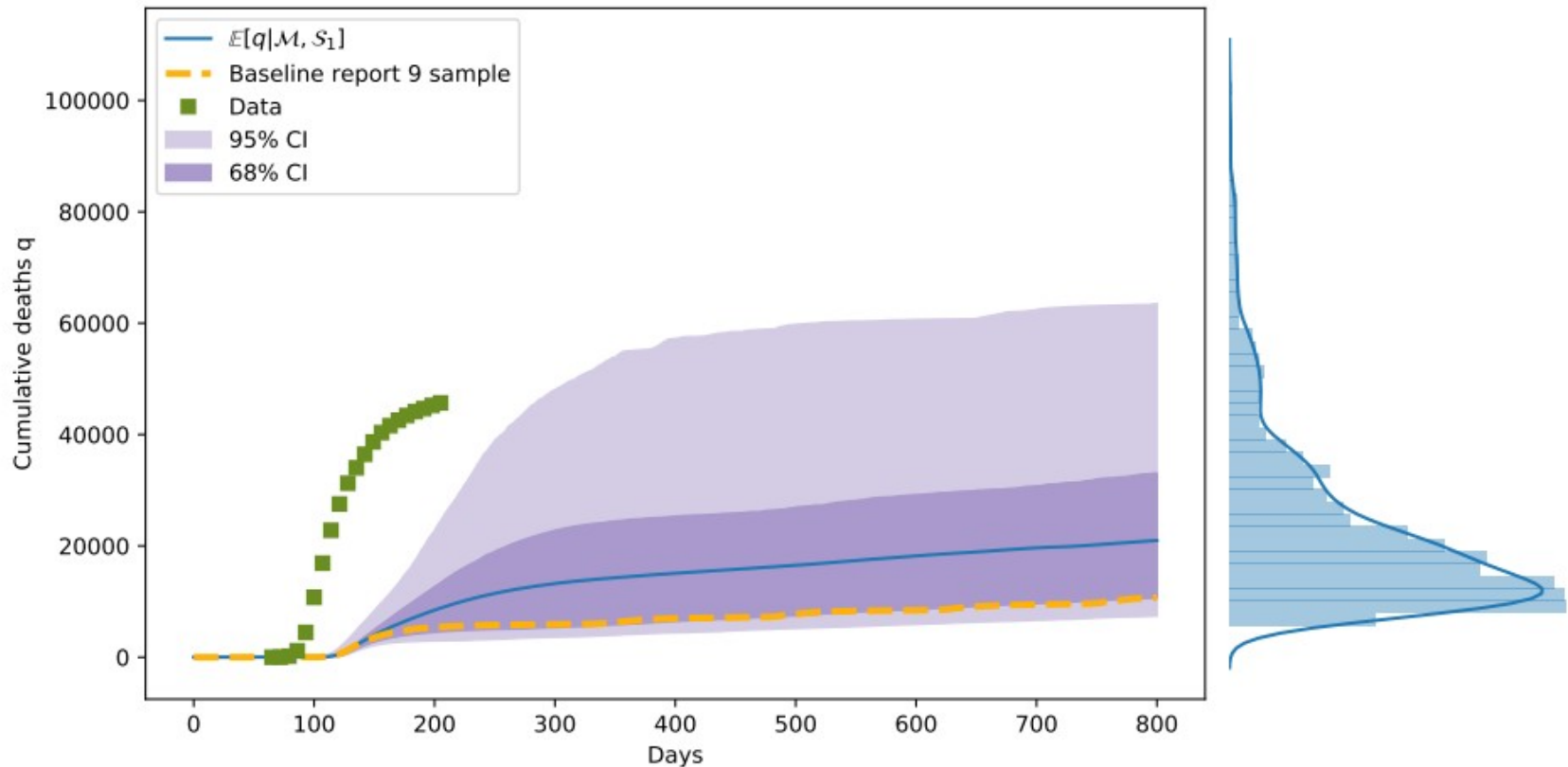
- 19 parameters: chose uniform input distribution.
- Refinement: effective dimension of 7 during the 1st 70 iterations:



UQP1-A: CovidSim



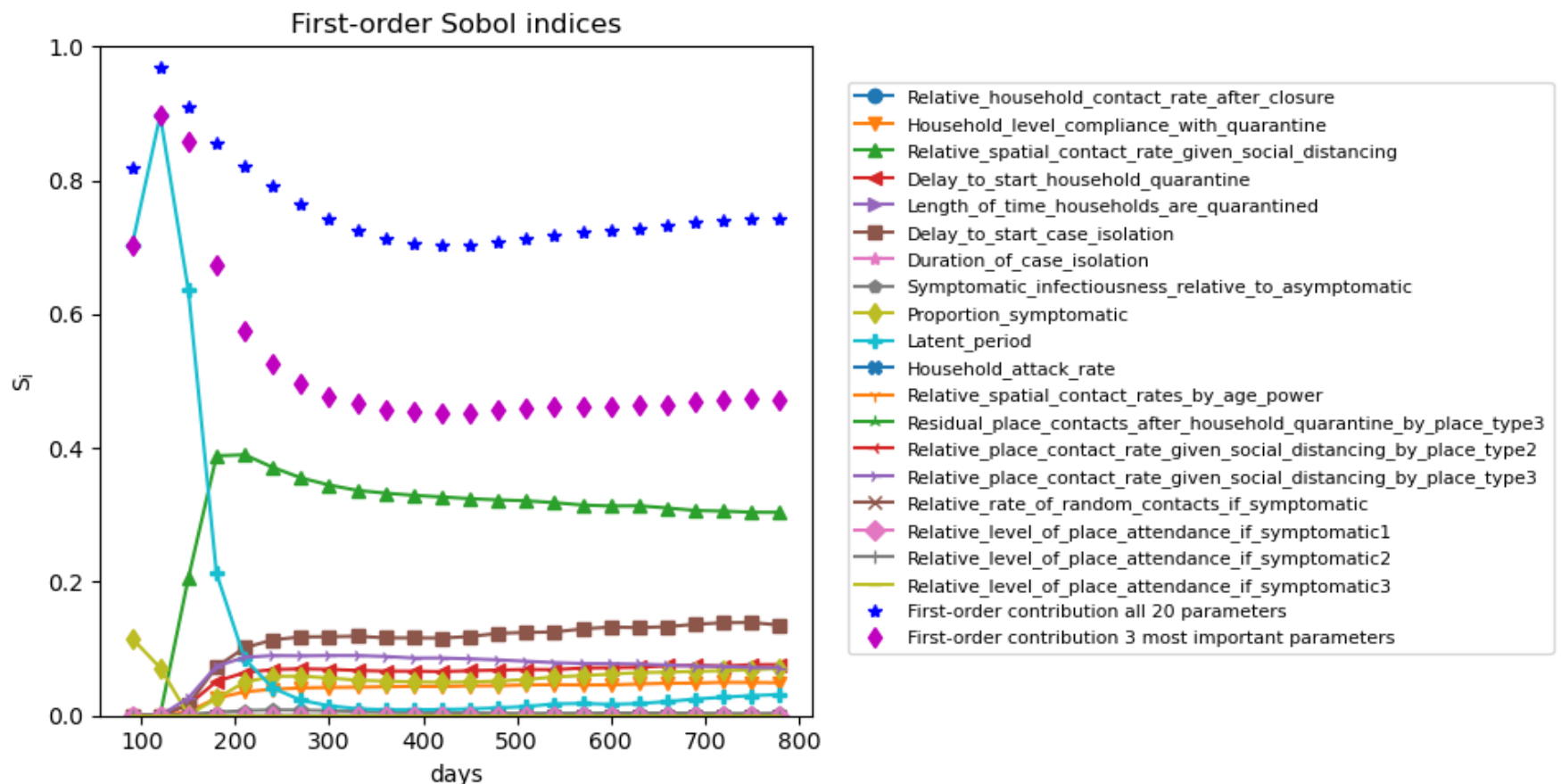
- Output distribution of cumulative death count



W. Edeling, H. Arabnejad, R. Sinclair et al., *The Impact of Uncertainty on Predictions of the CovidSim Epidemiological Code*, Nat. Comp. Sci. (accepted) 2021.

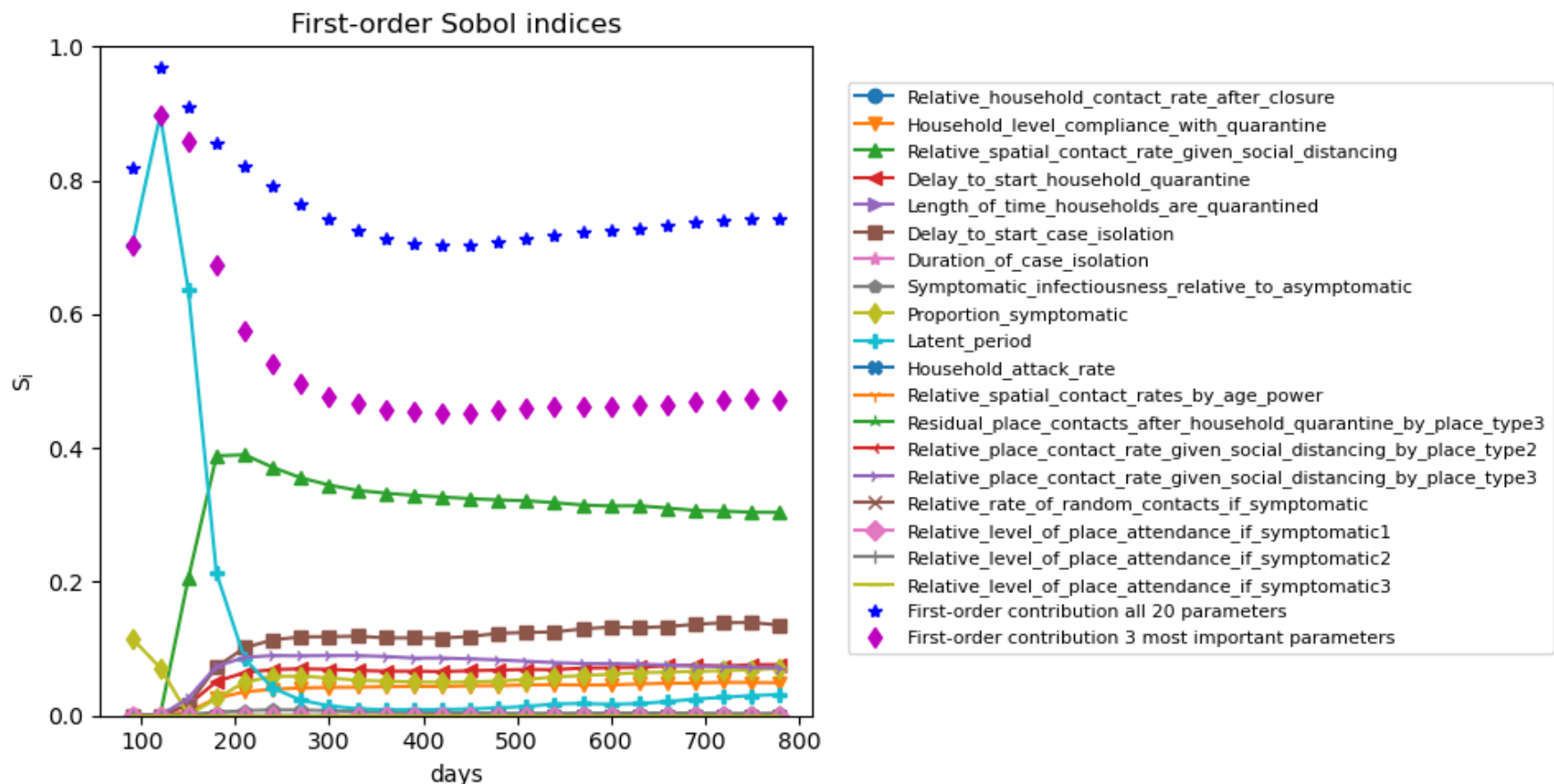
UQP1-A: Sensitivity analysis

- Sobol sensitivity indices can be obtained in a post processing step.
- First-order index $S_i \in [0, 1]$: fraction of the output variance the i-th input is responsible for:

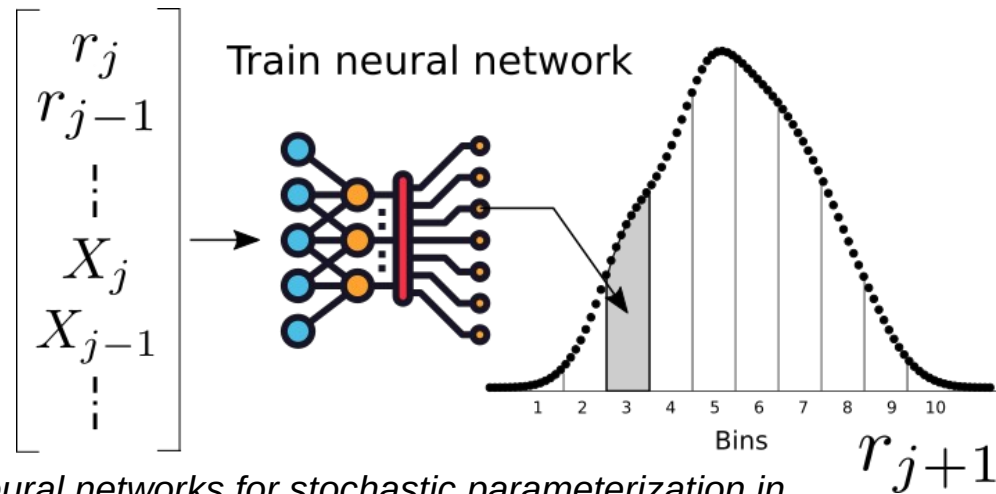
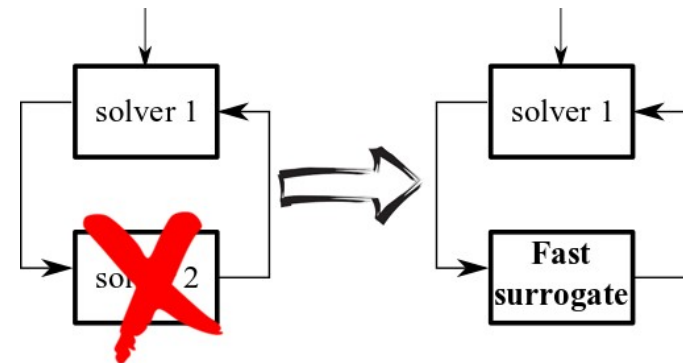


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- UQP3-B: cyclic multiscale model with a surrogate for the micro model.
- One type of surrogate: conditional resampling of training data via neural net.
- WE are in the process of building a toolbox for different (UQP3) surrogates: EasySurrogate
- Application to Lorenz 96:



D. Crommelin, W. Edeling, *Resampling with neural networks for stochastic parameterization in multiscale systems*, *Phys D (submitted)*, 2021.

Questions?
