#### Technische Universität München

# **BGCE Project: CAD – Integrated Topology Optimization**

**BGCE First Milestone Meeting** 

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### **Motivation**

## **Current Design Process:**



- Iterative and redundant
- Time consuming



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### Topology optimization



 Promoted by additive manufacturing



#### **Motivation**

#### **Current Design Process:**



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### Topology optimization



 Promoted by additive manufacturing

#### Focus:

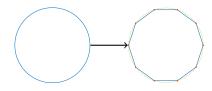
Convert optimized geometry to lightweight and scalable CAD formats



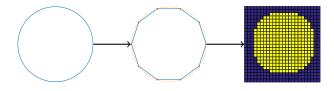
# CAD design



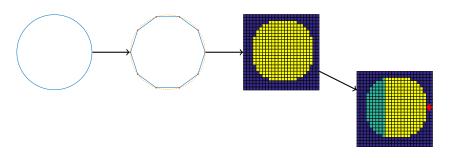
## STL interface



# Voxelized topology

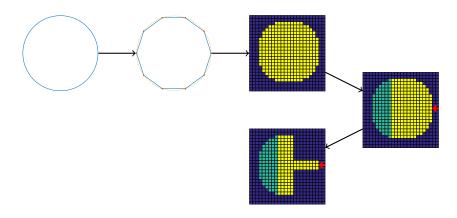


## Specification of loads and fixtures

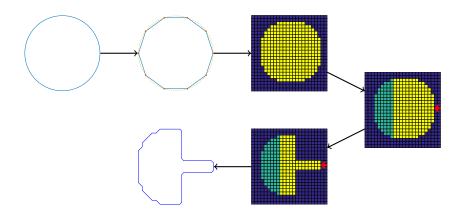




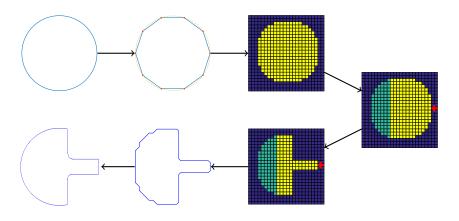
## Optimized topology

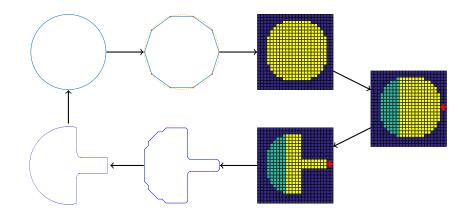


#### Surface extraction



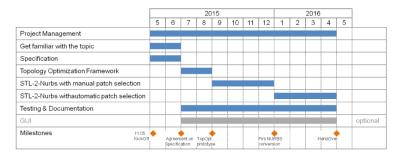
## Parametrized CAD-geometries





### **Schedule & Milestones**

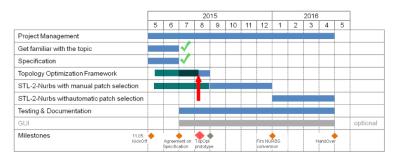
#### Schedule:





#### **Schedule & Milestones**

#### Schedule: (current)





# **Divide and Conquer**



**Project Manager** 



**Project Supervisor** 











Benjamin Rüth Juan Carlos Medina **Surface Extraction** 









**Surface Fitting** 

# **Project management**



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### **Status DRAFT**

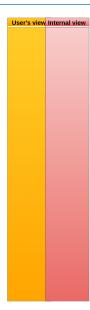
#### Last milestone

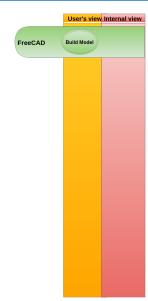
- Manual voxelization using CVMLCPP
- √ "Hard coded" script for ToPy input
- Topology optimized geometry using ToPy
- Recognition of boundary conditions

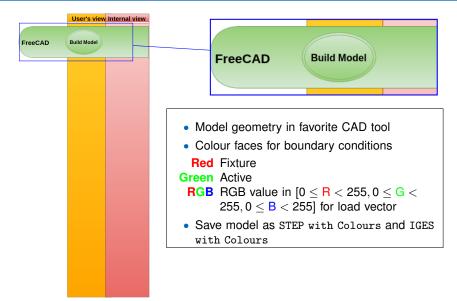
### **Today**

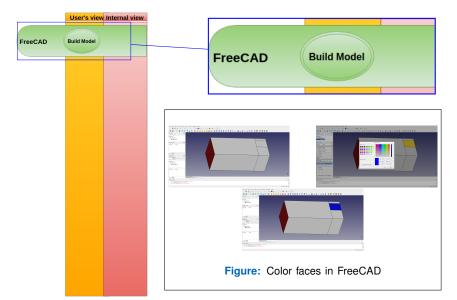
- √ Voxelization with OpenCascade
- Extraction of loads, fixtures and active elements through colouring
- ✓ Automatic "one click" pipeline to surface reconstruction

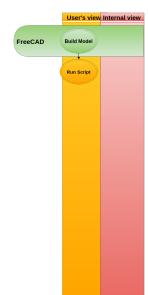




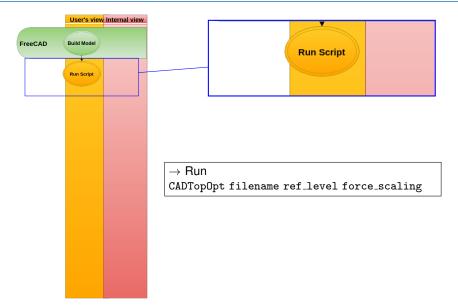


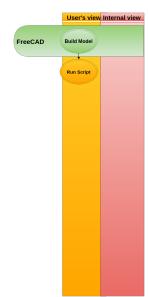


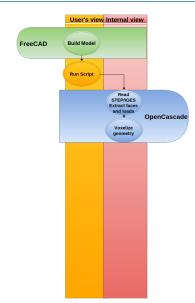




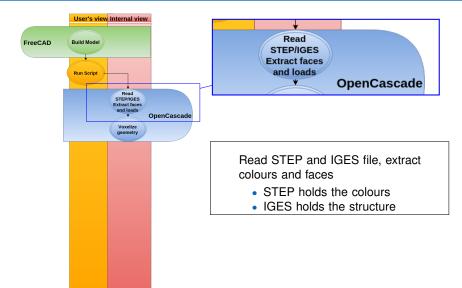




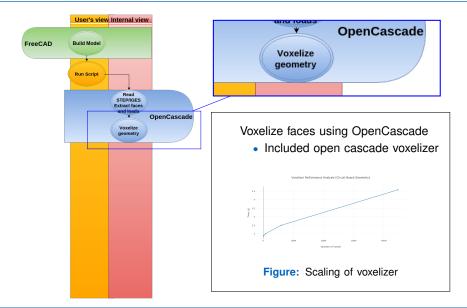


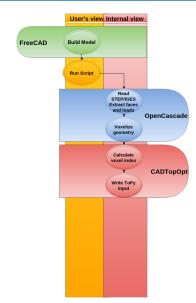




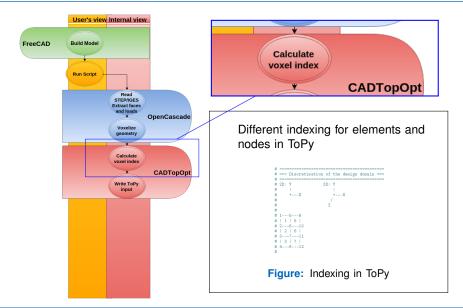




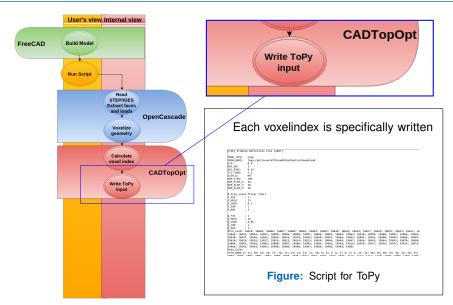


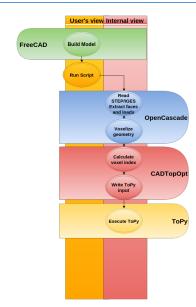


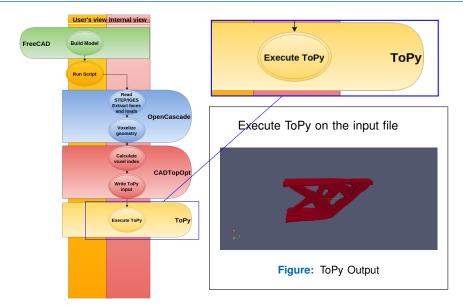


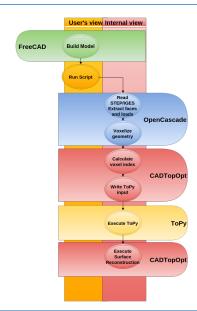




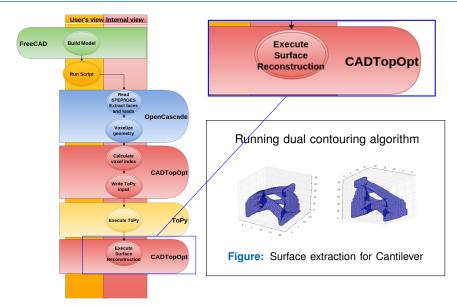


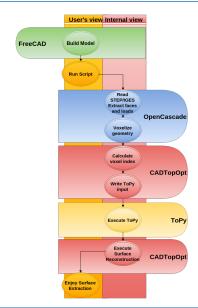


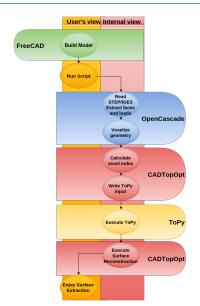






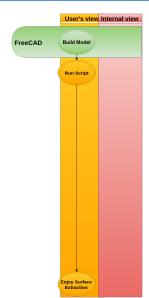






But what does the user see?





But what does the user see? This!

# The next steps MOVE TO LATER

- GUI for input
- Speed up ToPY
- Usage of different optimizers



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### What is done?

- First part of the pipeline from CAD model to optimized voxel model:
  - CAD to STL with e.g. FreeCAD
  - STI to Voxels with CVMI CPP
  - Voxels to ToPy input with custom script
  - Topology optimized geometry with ToPy
  - (F) Surface reconstruction with VTKToolbox
- B–spline fitting
  - Automatic patch selection
  - Parametrization of obtained patches
  - √ B–spline fitting using least squares
  - (b) Smooth connection of patches

  - Conversion back to CAD.



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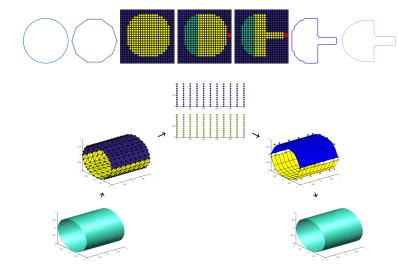




### What is next?

- Automation of the first part of the pipeline
- Integration of boundary conditions handling
- Implementation of remaining B-spline fitting steps (based on work of M.Eck & H.Hoppe)
- Further research on algorithms considering voxel geometry

# Thank you for your attention!





#### Literature

- William Hunter. "Predominantly solid-void three-dimensional topology optimisation using open source software"
- Gerrit Becker, Michael Schäfer, Antony Jameson. "An advanced NURBS fitting procedure for post-processing of grid-based shape optimizations"
- Matthias Eck, Hugues Hoppe. "Automatic Reconstruction of B-Spline Surfaces of Arbitrary Topological Type"