

Technische Universität München

## BGCE Project: CAD – Integrated Topology Optimization

BGCE Final Milestone Meeting

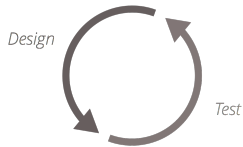
S. Joshi, J.C. Medina, F. Menhorn,  
S. Reiz, B. R  th, E. Wannerberg, A. Yurova

March 1, 2016



# Motivation

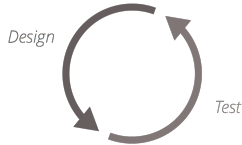
Current Design Process:



- Iterative and redundant
- Time consuming

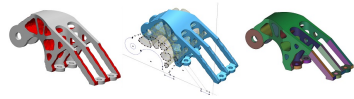
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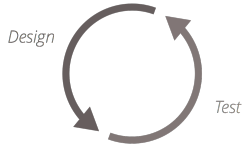
## Topology optimization



- Promoted by additive manufacturing

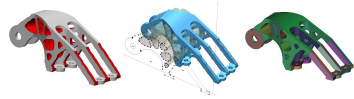
# Motivation

## Current Design Process:



- Iterative and redundant
- Time consuming

## Topology optimization



- Promoted by additive manufacturing

## Focus:

Convert optimized geometry to **lightweight** and **scalable** CAD formats

# Contents

## 1. Product Presentation

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## 3. Product Presentation

## 4. Overview: Workflow

## 5. Topology optimization

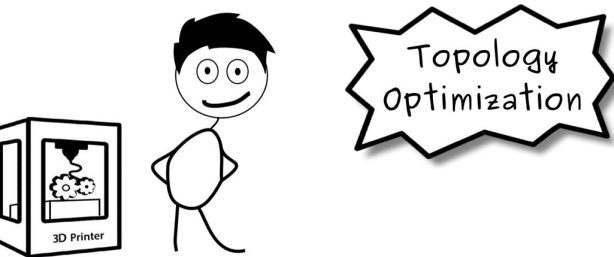
### 5.1 Internal structure

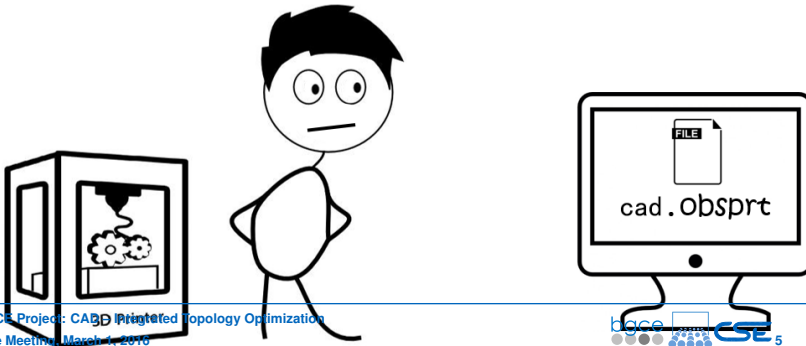
### 5.2 User view

## 6. Surface Extraction

### 6.1 Dual Contouring

### 6.2 Projection and Parametrization





# How hard is it to design a lamp?

## Problem:

- The Engineer designer pendulum

## Desired:

⇒ One click optimization



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- Top-Opt algorithms are a one way street

## Desired:

- ⇒ One click optimization
- ⇒ A full circle optimization process

# How hard is it to design a lamp?

## Problem:

- The Engineer designer pendulum
- Top-Opt algorithms are a one way street
- Exotic input file types

## Desired:

- ⇒ One click optimization
- ⇒ A full circle optimization process
- ⇒ Standardized input files

## What they get

- One-step solution process
- Full 3-D optimization via Finite Elements
- Production-ready output geometry

# DEMO

# Features

## Fully integrated design process

- CAD to CAD
- Turnkey
- Standardized I/O

# Features

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- Turnkey
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## Control to the user

- Resolution
- Smoothness
- Localized Optimization

# Features

## Fully integrated design process

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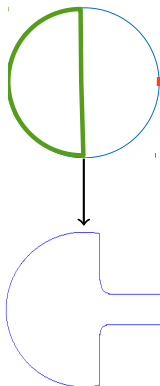
## Control to the user

- Resolution
- Smoothness
- Localized Optimization

## 100% open source

## Overview: Workflow

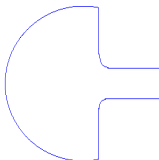
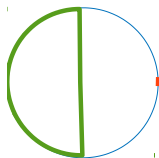
What the user sees





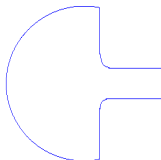
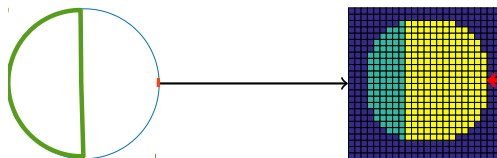
## Overview: Workflow

CAD design including specification of loads and fixtures



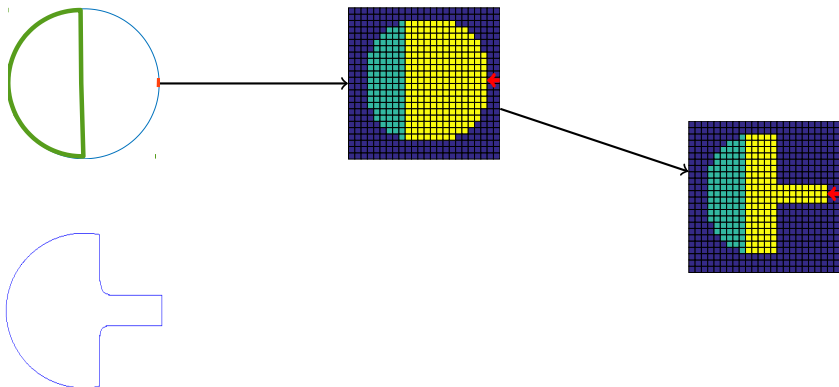
## Overview: Workflow

Voxelized topology



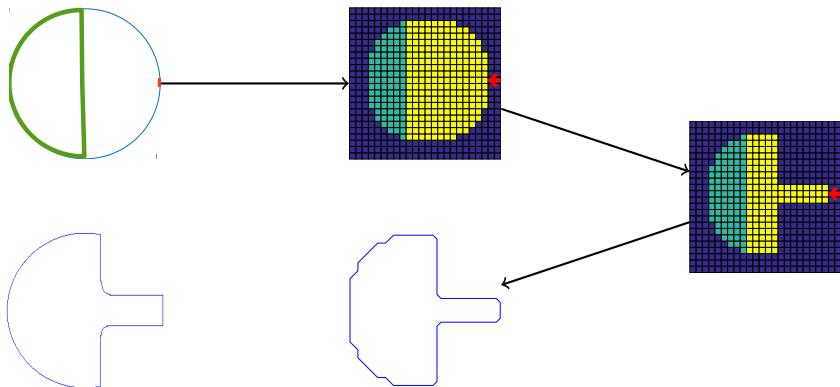
## Overview: Workflow

Optimized topology



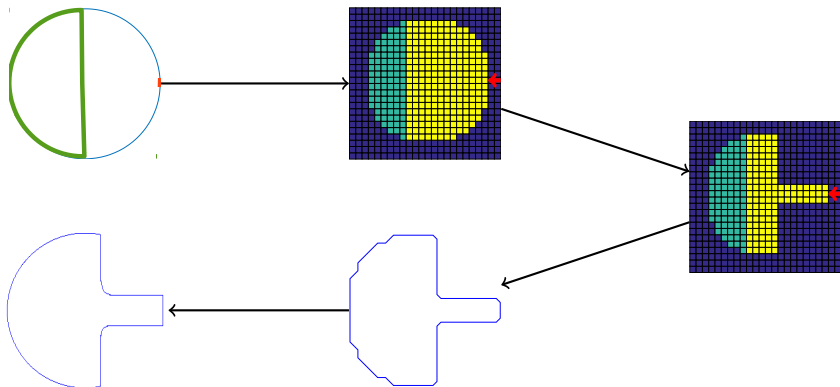
# Overview: Workflow

## Surface extraction



## Overview: Workflow

Fit B-Spline surface



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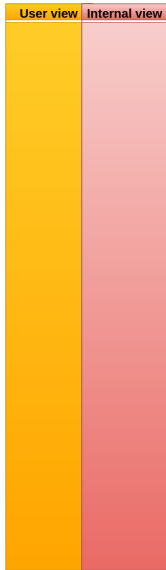
# Status

## Last milestone

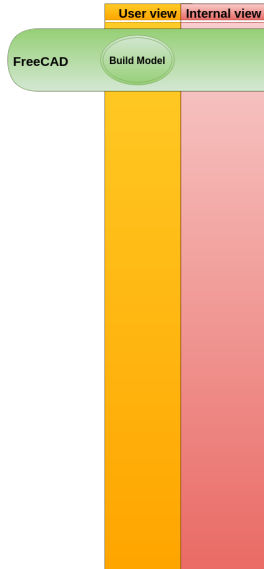
- ✓ Manual voxelization using CVMLCPP
- ✓ "Hard coded" script for ToPy input
- ✓ Topology optimized geometry using ToPy
- ✗ Recognition of boundary conditions

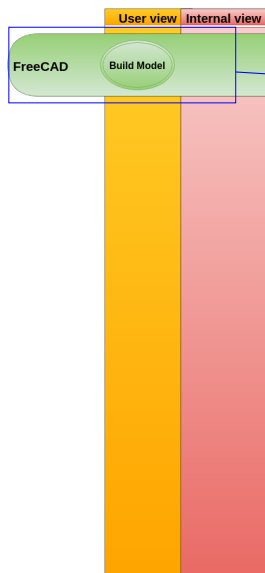
## Today

- ✓ Voxelization with OpenCascade
- ✓ Extraction of loads, fixtures and active elements through colouring
- ✓ Automatic "one click" pipeline to surface reconstruction

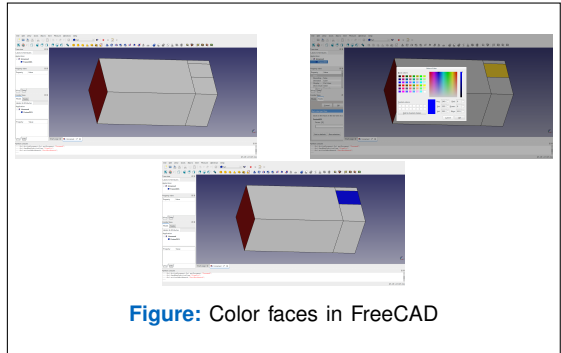
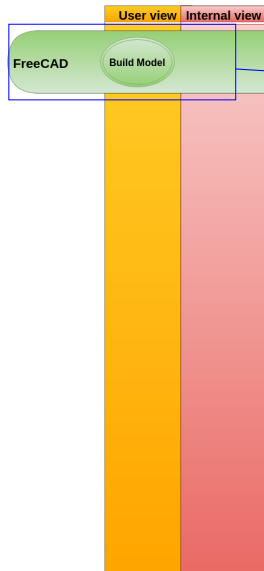


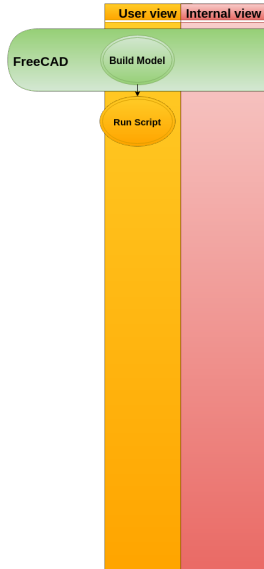


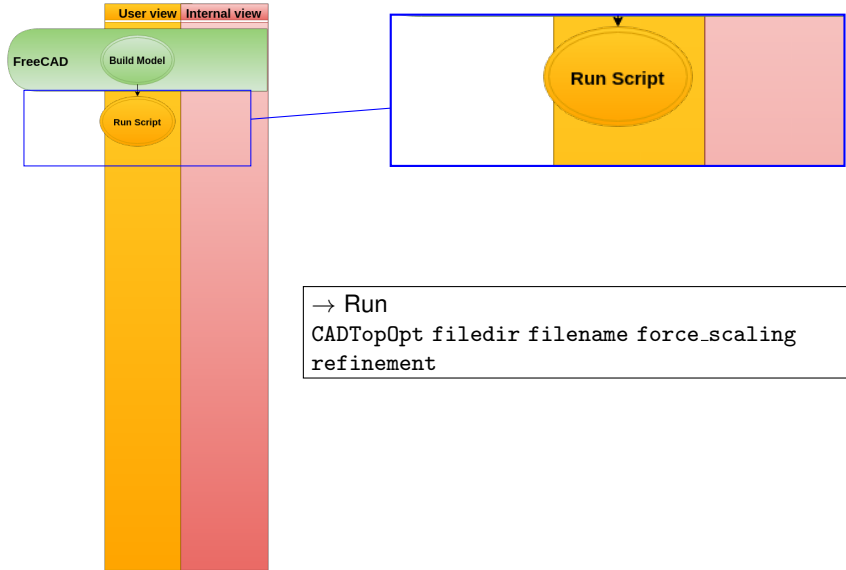


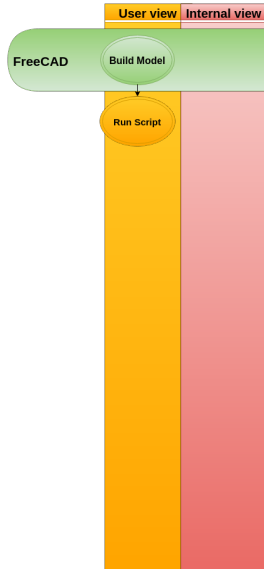


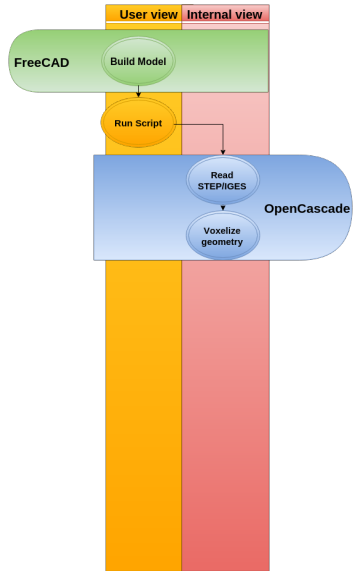
- Model geometry in your favorite CAD tool
- Colour faces for boundary conditions
  - Red** Fixture
  - Green** Active
  - RGB** RGB value in  $[0 \leq R < 255, 0 \leq G < 255, 0 \leq B < 255]$  for load vector
- Save model as STEP with Colours and IGES with Colours

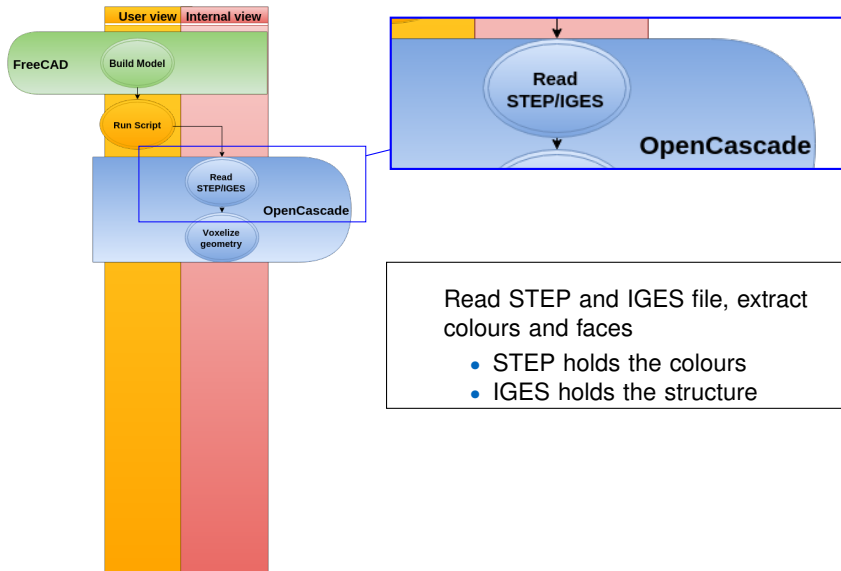




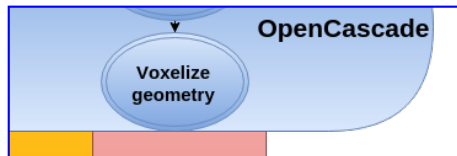
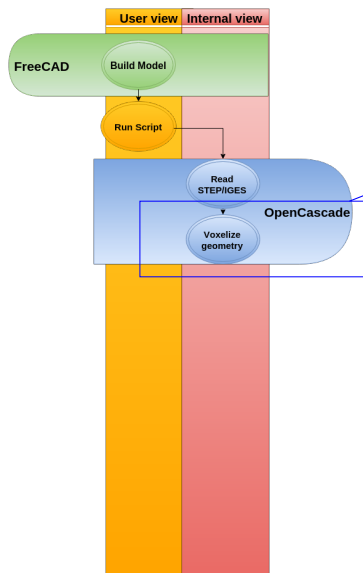




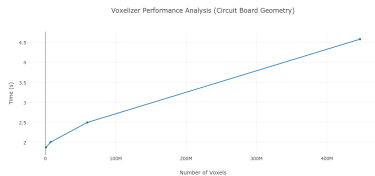




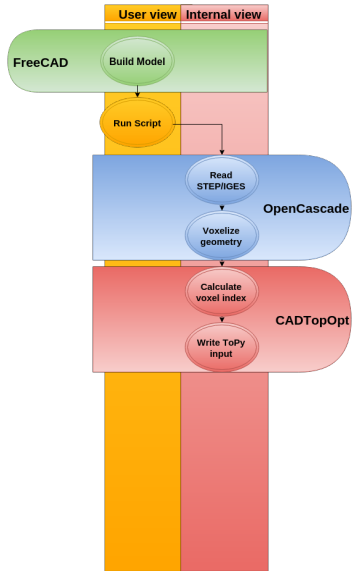


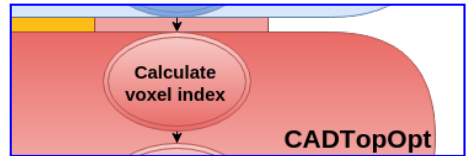
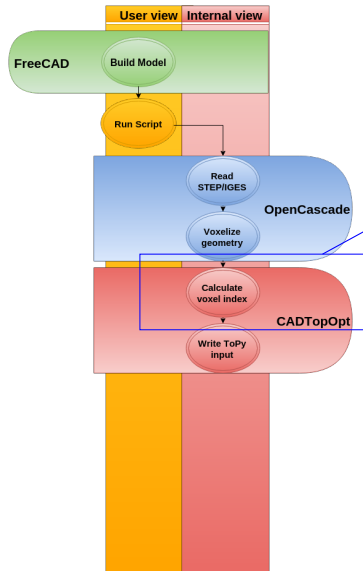


## Voxelize faces using OpenCascade



**Figure:** Scaling of voxelizer

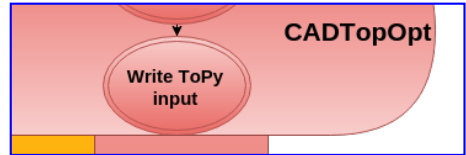




Different indexing for elements and nodes in ToPy

```
# =====
# === Discretisation of the design domain ===
# =====
# 2D: Y      3D: Y
# |          |
# +---X      +---X
#
#           Z
#
# 1---5---9
# | 1 | 5 |
# 2---6---10
# | 2 | 6 |
# 3---7---11
# | 3 | 7 |
# 4---8---12
#
```

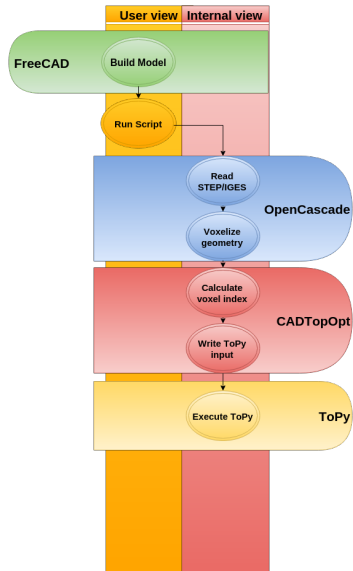
**Figure:** Indexing in ToPy [1]

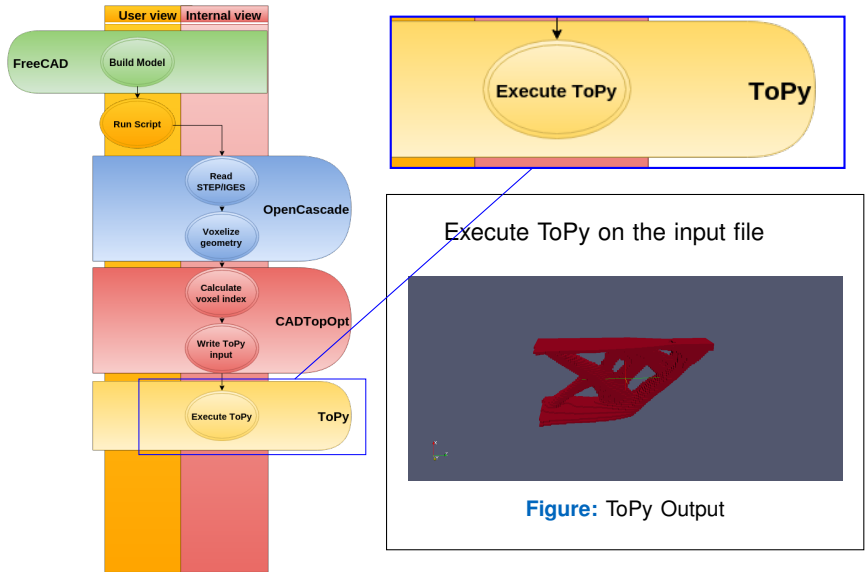


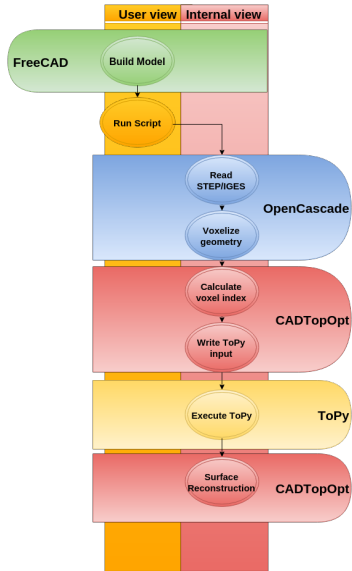
Each voxel index is specifically written

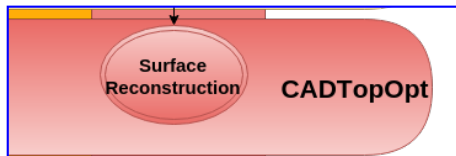
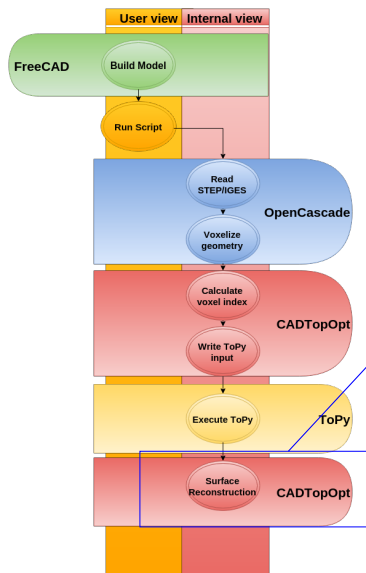
[illegible]

**Figure:** Script for ToPy

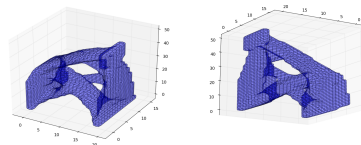






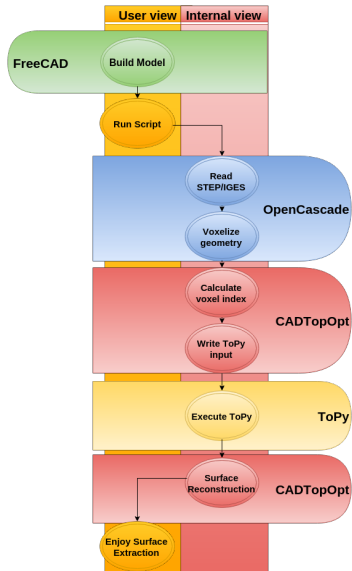


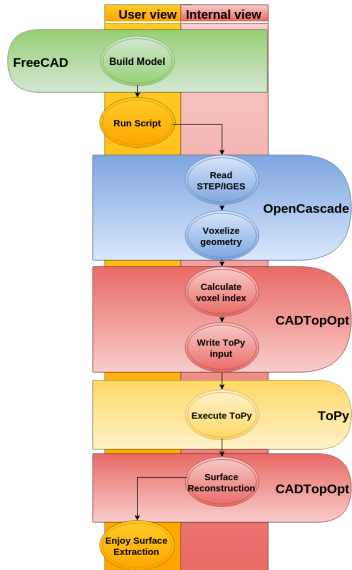
Run dual contouring algorithm



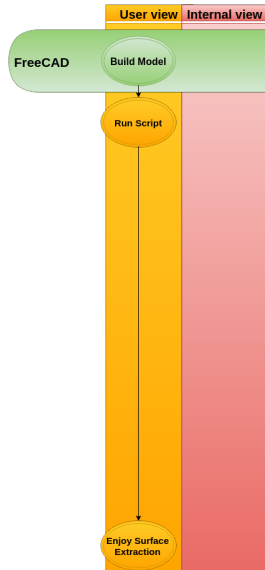
**Figure:** Surface extraction for Cantilever







But what does the user see?



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# Status

## Last milestone

- 🕒 Surface reconstruction with the VTK Toolbox

## Today

- ✓ Extraction of voxel data from Topy
- ✓ 3D Dual Contouring implementation
- ✓ Coarsening and non-manifold edge treatment
- ✓ Projection of datapoints onto quads and respective parametrization
- 🕒 Interface to NURBS

## From Voxel to Mesh Geometry

- Extract isosurface from voxel information
- Algorithms: Marching Cubes, Dual Contouring, Extended Models
- Problems with VTK's Marching Cube implementation

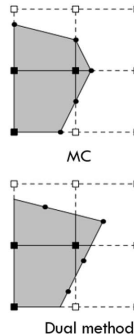
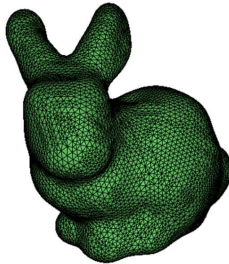
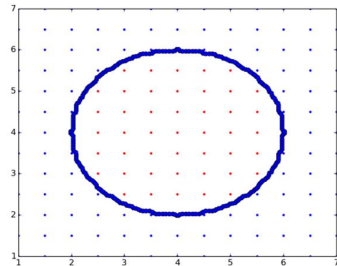
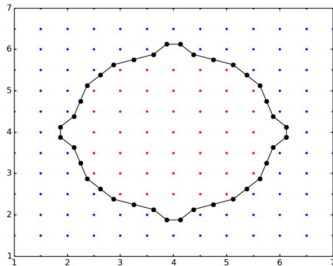


Figure: From [4],[5]

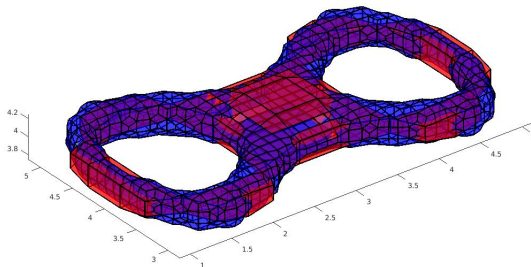
## Dual Contouring

- Python implementation — Use of powerful libraries, including VTK
- Output: Closed surface made out of *quads*
- Coarsening is needed for surface fitting algorithms



## Dual Contouring

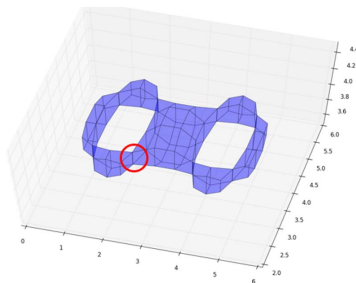
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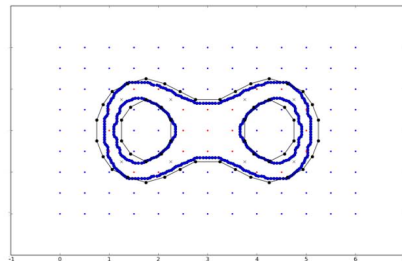
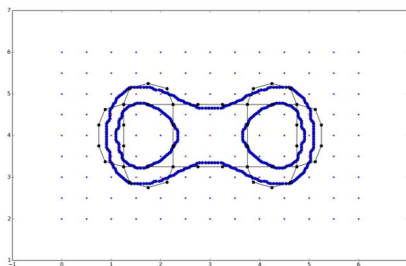
## Dual Contouring — Problems

- **Non-manifold edges** appear
- One edge can only belong to two quads for the surface to be closed
- Special treatments in the implementation to avoid them



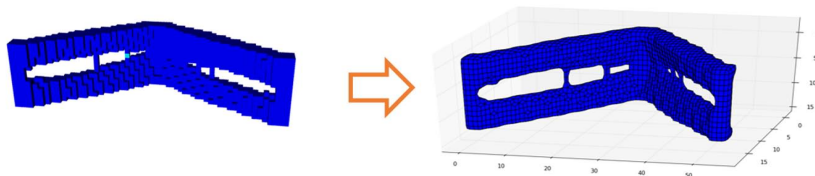
## Dual Contouring — Problems

- **Non-manifold edges** appear
- One edge can only belong to two quads for the surface to be closed
- Special treatments in the implementation to avoid them



## Dual Contouring — Input

- Interface between Topology Optimization and Surface Extraction
- Special implementation to use voxel data from ToPy as input



# Demo

## Projection and Parametrization

- Points from finer grid are projected to quads of the coarser grid
- Parameters  $u$  and  $v$  are found for each quad
- This information is needed for the algorithms in the last part of the pipeline

