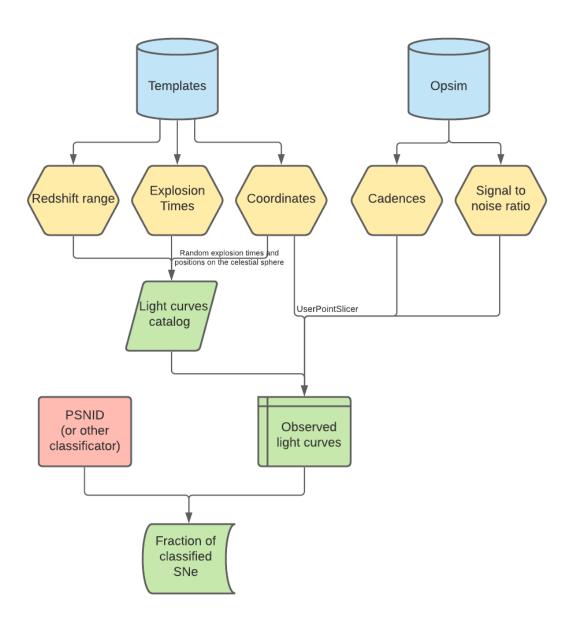
Supernova Rate Metric

Flow chart of the project:



The Supernova Rate Matric is a class object that gives as derivable the SN detection efficiency and classification efficiency from a given survey.

The metric is composed by three classes and a method:

- **template_lc**: class, it gives the k-corrected supernova light curve in g, r and i bands for a given redshift range;
- **generateSNPopSlicer**: method, Generate a population of SNe events, and put the info about them into a UserPointSlicer object

- **SNclassification_metric**: class, it simulates observed points of the observed light curves from LSST and gives the fraction of corrected classified SNe in function of type or redshift;

template lc:

GLOBAL PARAMETER:

- **templates**: dict, it is a dictionary where they are listed the templates type, subtype and fractions of each template per subgroup;
- z min, z max, ,z step: float, those parameter define the range and the step in redshift to perform the simulation;
- *extinction:* float, it is a value for the extinction, default =0;
- path: string, it is the path where to save the output file if requested, default ='\$HOME';
- **dataout:** boolean, if True the metric return a .txt file with the lc information, if False return a dictionary with magnitude epoch (respect the epoch of the maximum) for each filter. Default dataout=False.

All the coefficients needed for the transformation from a passband to another are stored in the dictionary parband:

```
self.band label= ['bandw','fwhm','avgwv','equvw','zpoint','abmag for vega']
#landolt & johnson buser and kurucz 78
self.bandpar['U']=[205.79,484.6,3652,542.62,4.327e-9, 0.76]
self.bandpar['B']=[352.94,831.11,4448,1010.3,6.09e-9, -0.11]
self.bandpar['V']=[351.01,826.57,5505,870.65,3.53e-9, 0.]
#landolt & cousin bessel 83
self.bandpar['R']=[589.71,1388.7,6555,1452.2,2.104e-9, 0.18]
self.bandpar['I']=[381.67,898.77,7900.4,1226,1.157e-9, 0.42]
# HAWK-I filter
self.bandpar['Y']=[0,1019.4,10226.9,0,5.74e-10, '?']
#bessel in bessel and brett 88
self.bandpar['J']=[747.1,1759.3,12370,2034,3.05e-10, '?']
self.bandpar['H']=[866.55,2040.6,16471,2882.8,1.11e-10, '?']
self.bandpar['K']=[1188.9,2799.6,22126,3664.3,3.83e-11, '?']
# ASIAGO PHOTOMETRIC DATABASE
self.bandpar['L']=[0.,9000.,34000,0.,8.1e-12, '?']
self.bandpar['M']=[0.,11000.,50000,0.,2.2e-12, '?']
self.bandpar['N']=[0.,60000.,102000,0.,1.23e-13, '?']
# sloan
self.bandpar['u']=[194.41,457.79, 3561.8, 60.587,3.622e-9, 0.92]
self.bandpar['g']=[394.17,928.19, 4718.9, 418.52,5.414e-9, -0.11]
self.bandpar['r']=[344.67,811.65, 6185.2, 546.14,2.472e-9, 0.14]
self.bandpar['i']=[379.57,893.82, 7499.8, 442.15,1.383e-9, 0.36]
self.bandpar['z']=[502.45,1183.2, 8961.5, 88.505,8.15e-10, 0.52]
# SWIFT A-> UW1, D --> UM2, S -> UW2
#self.bandpar['A']=[348.43,820.5,2650.6,770.45,3.818e-9]
#self.bandpar['D']=[189.46,446.14,2269.2,519.03,4.321e-9]
#self.bandpar['S']=[285.12,671.4,2136.7,639.45,4.825e-9]
self.bandpar['A']=[0.,693.,2634,0.,4.3e-9, '?'] # Poole et al. 2008 383, 627 self.bandpar['D']=[0.,498.,2231,0.,4.0e-9, '?'] # corrected for z-point self.bandpar['S']=[0.,657.,2030,0.,5.2e-9, '?']
```

the transient template is then read from a file, e.g. the format of the template is:

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IIP jd_expl= 46849.8
ABg= 0.79 .00 ABi= 0.00 .00 mu= 18.49 .00
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```

the output is a dictionary:

```
sndata = {'sn':sn, 'sntype':sntype, 'galaxy':galaxy, 'bands':bands,
             'ABg':abg, 'ABg err':abg err, 'ABi':abi,
                                                            'ABi err':abi err,\
             'mu':mu, 'mu_err':mu_err, 'jd_expl':jd_expl, \
             'jdmax':jdmax, 'jdmax err':jdmax err, 'magmax':magmax,\
             'magmax err':magmax_err, 'format':'OLD',\
             'jd':jd, 'mag':mag, 'mag_err':mag_err, 'source':source}
       Cardelli
                                                                                       passband:
The
                 law
                        is
                              used
                                      to
                                            estimate
                                                      the
                                                             absorption
                                                                         for
                                                                               each
def AX(self, band='',AB='',R V=3.1):
    if not band: band = raw input('<< Band ? ')</pre>
    if AB=='': AB = float(raw input('<< Ab absorption ? '))</pre>
    abfac = self.cardelli(self.bandpar[band][self.band_label.index('avgwv')],R_V)\
            /self.cardelli(self.bandpar['B'][self.band label.index('avgwv')],R V)
    return AB*abfac
```

Then the kcor is read from template table for given redshift ranges and given bands:

```
def kcor_read(self, sn,tsn,): ########
     kph, kz, kcor, kiko = \{\}, \{\}, \{\}, \{\}
     ff = open(kcor dir+'/kcor/kk/'+sn+'.kcor')
     righe = ff.readlines()
     kkph = [float(x) for x in righe[1].split()]
                   # read correction for specific reshift template
     ian = []
     for i,r in enumerate(righe):
    if '***' in r: ign.append(i)
     for i in ign:
         gn = righe[i].split()[0]
         kiko[gn] = np.array([float(k) for k in righe[i+1].split()])
     ff = open(kcor_dir+'/kcor/kk/'+tsn['kkclass']+'.kk')
     righe = ff.readlines()
                                              read kcor for SN class
     igf = []
     for i,r in enumerate(righe):
        if '---' in r: igf.append(i-1)
     for n,i in enumerate(igf):
         gf = righe[i].split()[0]
         kz[gf],kcor[gf] = [],[]
         il = len(righe)
         if n<len(igf)-1: i1 = igf[n+1]</pre>
         kph[gf] = np.array([float(p) for p in righe[i+1].split()[1:]])
         for r in righe[i+2:i1]:
             kz[gf].append(float(r.split()[0]))
             kcor[gf].append(np.array([float(k) for k in r.split()[1:]]))
     ff.close()
     return kkph, kiko, kph, kz, kcor
and finally we estimate the koorr at the redshift we decided through an interpolation:
 def kcor_interpolate(self, tph,z,kph,kz,kcor):
      if len(kz)>1:
           jz = np.searchsorted(kz,z)-1
           if jz < len(kz)-1:
                il = np.where(kcor[jz]<100)
                kl = np.interp(tph,kph[il],kcor[jz][il])
                iu = np.where(kcor[jz+1]<100)
               _ku = np.interp(tph,kph[iu],kcor[jz+1][iu])
                _kcor = _kl+(z-kz[jz])*(_ku-_kl)/(kz[jz+1]-kz[jz])
           else:
               il = np.where(kcor[jz]<100)</pre>
                kcor = np.interp(tph,kph[il],kcor[jz][il])
      else:
           il = np.where(kcor[0]<100)
           kcor = np.interp(tph,kph[il],kcor[0][il])
      return kcor
and we correct the template magnitude and phase for the relative kcor to have the rest frame magnitude:
 def mag observer frame(self, tph,tabsmag,tzed,z,kcor,kiko,tEXT):
      phobs = tph*(1-tzed+float(z))
      magobs = tabsmag+kcor+kiko+cosmo.mu(float(z))+tEXT
      return phobs, magobs
```

generateSNPopSlicer:

GLOBAL PARAMETER:

- **templates**= dict, it is a dictionary where they are listed the templates type, subtype and fractions of each template per subgroup;
- t start: float, first epoch of the epochs range from which the explosion times are drawn
- t end: float, final epoch of the epochs range from which the explosion times are drawn
- **n events :** int The number of SNe events to generate
- seed: float The seed passed to np.random
- z min: float or int Minimum reshift
- z max: float or int Maximum redshift
- **zstep:** float or int redshift step
- **coo**: dict, specifics coordinate where to perform the simulation

The supernova templates are simulated at each redshift in the redshift range defined as [zmin : zstep : zmax] calling the class template_lc. Than from uniform distribution within the range [t_start, t_end] are drawn the epochs when the SNe explode. Finally the coordinates where to simulate the SNe are given by the dictionary coo, or are drawn by a uniform distribution over the celestial sphere.

```
# The SN template light curves are simulated at the redshifts in the redshift range
    # K-correction is applied at each redshift z
if not os.path.exists('./template'):
   os.makedirs('./template')
zmin = zmin
zmax = zmax
zstep = zstep
temp = template_lc(sn_group= templates, z_min=zmin,z_max= zmax,z_step=zstep)
obs template = temp.run()
zrange = temp.zrange
filtri = temp.filtri
for j, z in enumerate(zrange):
        for ty in templates:
            for sty in templates[ty]:
                for sn in templates[ty][sty][0]:
                    asciifile = './template/snlc_{}_z={}_DDF.ascii'.format(sn,str(z))
                    ff = open(asciifile,'w')
                    if ty in ['Ia','Ibc']:
                                               endTime = 50.*(1+z)
                                               endTime =100.*(1+z)
                    else:
                    for f in filtri:
                        for i,p in enumerate(obs_template['phobs'][sn][z][f]):
                            if obs_template['phobs'][sn][z][f][i] > endTime: break
                            ff.write('\{:.2f\} \ \{:.3f\} \ \{\}\n'.format(p,obs\_template['magobs'][sn][z][f][i],f))
                    ff.close()
explosion_times = np.random.uniform(low=t_start, high=t_end, size=n_events)
# Set up the slicer to evaluate the catalog we just made
if coo:
   slicer = slicers.UserPointsSlicer(coo['ra'], coo['dec'], latLonDeg=True, badval=0)
else:
   ra, dec = sample_sphere(n_events, seed=seed)
    slicer = slicers.UserPointsSlicer(ra, dec, latLonDeg=True, badval=0)
# Add any additional information about each object to the slicer
slicer.slicePoints['explosion times'] = explosion times
slicer.slicePoints['zrange'] = zrange
return slicer
```

SNclassification metric:

GLOBAL PARAMETER:

Survey Parameters:

- *mjdCol*= MJD observations column name from Opsim database (DEFAULT = observationStartMJD)
- *m5Col*= Magnitude limit column name from Opsim database (DEFAULT = fiveSigmaDepth)
- *filterCol*= Filters column name from Opsim database (DEFAULT = filter)
- *exptimeCol* = Column name for the total exposure time of the visit(DEFAULT = visitExposureTime)

- **nightCol** = The night's column of the survey (starting at 1) (DEFAULT = night)
- **vistimeCol** = Column name for the total time of the visit (DEFAULT = visitTime)
- **RACol**= RA column name from Opsim database (DEFAULT = fieldRA)
- **DecCol**= Dec column name from Opsim database (DEFAULT = fieldDec)
- surveyDuration= Survey Duration (DEFAULT = 10)
- *surveyStart*= Survey start date (DEFAULT = None)

Detection parameters:

- detectSNR= dictionary with SNR threshold for each filter (DEFAULT = {'u': 5, 'g': 5, 'r': 5, 'z': 5, 'y': 5})
- *nFilters*= None or list of filters constrained for the classification threshold (DEFAULT = None)
- *ndetect*= integer, threshold number of points detected on the lightcurve (aside from the filters) (DEFAULT = 3)

Classification parameters

- *nclass*= integer, threshold number of points detected on the lightcurve (aside from the filters) to be classified (DEFAULT = 3)

OUTPUT:

- dataout = True, Dictionary containing the coordinates of all the SNe detected, the time of explosions and the number of detected and no-detected along with the number of classifies, un-classified and mis-classified SNe for each type
- *dataout* = False, fraction of correctly classified SNe

Methods from the class are:

- 1. read lightCurve:
 - a. input: ascii file with epoch, mag and filter for each template;
 - b. output: two deliverables, an array with epoch, mag and filter; the transient duration. both are given as input to the second method.
- 2. *make_lightCurve*:
 - a. input- the outputs of the first method,
 - b. output- interpolation of the template with the survey epochs.
- 3. sim mag noise:
 - a. input- magnitude and snr
 - b. output- simulated observations with errors
- 4. coadd:
 - a. input- opsim's metadata
 - b. output- coadd of exposures within the same night and relative magnitude limit.

```
def read lightCurve(self, asciifile):
      ""Reads in an ascii file, 3 columns: epoch, magnitude, filter
     Returns
     numpy.ndarray
         The data read from the ascii text file, in a numpy structured array with columns
         'ph' (phase / epoch, in days), 'mag' (magnitude), 'flt' (filter for the magnitude).
     if not os.path.isfile(asciifile):
         raise IOError('Could not find lightcurve ascii file %s' % (asciifile))
      self.lcv_template = np.genfromtxt(asciifile, dtype=[('ph', 'f8'), ('mag', 'f8'), ('flt', 'S1')])
     self.transDuration = self.lcv_template['ph'].max() - self.lcv_template['ph'].min()
  def make_lightCurve(self, time, filters):
      """Turn lightcurve definition into magnitudes at a series of times.
     Parameters
     time : numpy.ndarray
         The times of the observations.
      filters : numpy.ndarray
         The filters of the observations.
     Returns
     numpy.ndarray
          The magnitudes of the object at the times and in the filters of the observations.
     lcMags = np.zeros(time.size, dtype=float)
      for key in set(self.lcv_template['flt']):
         fMatch_ascii = np.where(np.array(self.lcv_template['flt']) == key)[0]
         # Interpolate the lightcurve template to the times of the observations, in this filter.
         lc_ascii_filter = np.interp(time, np.array(self.lcv_template['ph'], float)[fMatch_ascii],
                                   np.array(self.lcv_template['mag'], float)[fMatch_ascii])
         lcMags[filters == key.decode("utf-8")] = lc_ascii_filter[filters == key.decode("utf-8")]
     lcMags += self.peakOffset
     return lcMags
def sim_mag_noise(self,mag, snr):
    noise = (snr)**(-1)
mag from dist = np.random.normal(mag, noise,1)
    return mag_from_dist
def coadd(self, data):
    Method to coadd data per band and per night
    Parameters
    data : `pd.DataFrame`
         pandas df of observations
    Returns
    coadded data : `pd.DataFrame`
    keygroup = [self.filterCol, self.nightCol]
    data.sort_values(by=keygroup, ascending=[
                        True, True], inplace=True)
    coadd_df = data.groupby(keygroup).agg({self.vistimeCol: ['sum'],
                                                  self.exptimeCol: ['sum'],
                                                  self.mjdCol: ['mean'],
                                                  self.RACol: ['mean'],
                                                  self.DecCol: ['mean'],
                                                  self.m5Col: ['mean']}).reset_index()
    coadd_df.columns = [self.filterCol, self.nightCol,
                            self.vistimeCol, self.exptimeCol, self.mjdCol,
                            self.RACol, self.DecCol, self.m5Col]
    coadd_df.loc[:, self.m5Col] += 1.25 * \
         np.log10(coadd_df[self.vistimeCol]/30.)
    coadd_df.sort_values(by=[self.filterCol, self.nightCol], ascending=[
                             True, True], inplace=True)
    return coadd_df.to_records(index=False)
```

For each template we at a given coordinate we estimate for all the explosion times we simulate the transient explode:

- the observed epochs
- the magnitude at those epochs

- the snr of the magnitudes at each epoch

Finally we compare the snr with the threshold defined at the beginning to have the epochs at which a point on the light curve is detected

If the number of point overcome the minimum requested for the set of filters for the light curve to be detected or also classified we count it for the estimation of the fraction of the SN detection efficiency.

```
for k,times in enumerate(slicePoints['explosion_times']):
                    sn list+=1
                    expldist.append(times)
                    indexlc = np.where((obs>= times) & (obs<=times+self.transDuration)) # we create a mask for all the
observation whitin the transient duration
                    lcEpoch = (obs[indexlc] - times) # define the dates of the phases from the explosion time
                    if np.size(indexlc)>0:
                         lcMags = self.make lightCurve(lcEpoch, obs filter[indexlc]) # Generate the observed light curve
magnitudes
                         lcSNR = m52snr(lcMags, obs_m5[indexlc])
                         lcpoints_AboveThresh = np.zeros(len(lcSNR), dtype=bool)
                         sim_mag_noise = np.vectorize(self.sim_mag_noise)
                        nfilt_det = []
nfilt_class = []
                         for f in self.observedFilter:
                             filtermatch = np.where(obs_filter[indexlc] == f)
                             lcpoints_AboveThresh[filtermatch] = np.where(lcSNR[filtermatch] >= self.detectSNR[f],True,False) #
we define a mask for the detected points on the light curve
                         Dpoints = np.sum(lcpoints AboveThresh) #counts the number of detected points
                         if Dpoints>=self.ndetect:
                             nDetected+=1
                         else:
                            nUnDetected+=1
                         if self.nFilters:
                             Dpoints =0
                             nfilt_class=[]
                             for f in self.nFilters:
                                 filtermatch = np.where(obs_filter[indexlc] == f)
epoch_filt=lcEpoch[filtermatch]
                                 mask_class = epoch_filt<30
                                 if any(mask_class):
                                    Dpoint_class += np.sum(lcpoints_AboveThresh[filtermatch][mask_class])
                                 else:
                                     Dpoint class += 0
                            if Dpoints>=self.nclass: nfilt class.append(True)
                             mask_class = lcEpoch<30
                             if any(mask class):
                                 Dpoint_class = np.sum(lcpoints_AboveThresh[mask_class])
                                 Dpoint_class = 0
```

The light curves that satisfy the requirements for the classification are stored in a text file to pass to PSNID.

```
snname='LSST_{}_{}_{}_DDF.dat'.format(sn,z,np.round(times,2))
                         if self.nFilters:
                             if np.sum(nfilt_class) == np.size(self.nFilters):
                                 listout.append(snname+'\n')
                                 classifiable += 1
                         else:
                             if Dpoint_class>=self.nclass:
                                 classifiable += 1
                                 listout.append(snname+'\n')
                         if snname+'\n' in listout:
                             lc = {}
                             lc["Mags"] = lcMags
                             lc["filter"] = obs_filter[indexlc]
                             lc["SNR"] = lcSNR
                             lc["Epoch"] = obs[indexlc]
                             lc['detect'] = lcpoints_AboveThresh
                             # producing a file to pass to PSNID for the classification
                             mag = {}
jd = {}
merr = {}
                             snr={}
                             output = 'SURVEY: LSST \n'
                             output += 'SNID: {}_{}_{} \n'.format(sn,z,k)
                             output += 'IAUC:
                             output += 'RA: '+str(fieldRA)+' deg \n'
output += 'DECL: '+str(fieldDec)+' deg \n'
output += 'MWEBV: 0.0 MW E(B-V) \n'
output += 'REDSHIFT_FINAL: '+z+' +- '+'%5.3f' % self.z[2]+' (CMB)\n'
output += 'FILTERS: {} \n'.format(filterN)
output += '\n'
                                                  UNKNOWN \n'
                             output += '\n'
                             output += '# =======\n'
                             output += '# TERSE LIGHT CURVE OUTPUT\n'
                             output += '#\n'
                             output += 'NOBS: {} \n'.format(np.size(lcMags[lcpoints_AboveThresh]))
                             output += 'NVAR: 8 \n'
output += 'VARLIST: MJD FLT FIELD FLUXCAL FLUXCALERR
                                                                                                    MAG
                                                                                                             MAGERR \n'
                                                                                             SNR
                             lcMags = sim_mag_noise(lcMags_temp[lcpoints_AboveThresh],lcSNR_temp[lcpoints_AboveThresh])
                             lcSNR = m52snr(lcMags,obs_m5[indexlc][lcpoints_AboveThresh])
                             for f in filterNames:
                                 filtermatch = np.where(obs_filter[indexlc] == f)
                                 detect= np.array(lc['detect'][filtermatch])
                                 mag[f] = lcMags[filtermatch][detect]
                                 jd[f] = obs[indexlc][filtermatch][detect]
snr[f] = lcSNR[filtermatch][detect]
                                 merr[f] = 2.5*np.log10(1+1/snr[f])
                                 for h, j in enumerate(jd[f]):
                                      fl = 10**(-0.4*(mag[f][h]))*lel1
                                      if snr[f][h]>1:
                                         flerr = fl/snr[f][h]/1.3
                                      else:
                                          flerr = fl/1.1
                                     output += 'OBS: %9.3f %s NULL %7.3f %7.3f %7.3f %7.3f %7.3f \n' %
ofile =
ofile.close()
```

Finally it is called PSNID for the classification and the output is then analysed to check the fraction of corrected classified, mis-classified and unclassified SNe. Ultimately a confusion matrix is estimated to store the measured fractions.

```
r = subprocess.check_output([os.environ['SNANA_DIR']+'/bin/psnid.exe',
os.environ['LSST_DIR']+'/PSNID_LSST_'+self.name+'.nml'], stderr=subprocess.STDOUT)
                                                                # we search for classification flags in the variable r
                                                             line= np.array(r.split())
custom_split = np.vectorize(self.custom_split)
types = np.where(line=b'type')
sn_t = custom_split(x=line[np.where(line==b'Done')[0]+3],c='_',index=0)
z_t = custom_split(x=line[np.where(line==b'Done')[0]+3],c='_',index=1)
                                                               float_z = np.vectorize(float)
z_t = float_z(z_t)
                                                               z = np.unique(z_t)
                                                               # confusion matrix
                                                               for zz in z:
                                                                              nClassified=0
                                                                            nClassified=0

CM[zz]['Ia']['Ia']=0

CM[zz]['Ibc']['Ia']=0

CM[zz]['II']['Ia']=0

CM[zz]['UKNOWN']['Ia']=0

CM[zz]['Ibc']['Ibc']=0

CM[zz]['Il']['Ibc']=0

CM[zz]['Il']['Ibc']=0

CM[zz]['Il']['Il']=0

CM[zz]['Il']['II']=0

CM[zz]['Il']['II']=0

CM[zz]['Il']['II']=0

CM[zz]['Il']['II']=0

CM[zz]['Il']['II']=0

CM[zz]['Il']['II']=0

CM[zz]['Il']['II']=0

CM[zz]['Il']['II']=0

CM[zz]['Il']['Il']=0

CM[zz]['Il']['Il']=0

CM[zz]['Il']['Il']=0
                                                                              z_index = np.inld(z_t,[zz])
type_z= line[types[0]+2][z_index]
                                                                              sn_Ia= np.inld(sn_t,Ia)[z_index]
sn_Ibc= np.inld(sn_t,Ibc)[z_index]
                                                                            sn_lbc= np.inld(sn_t,lbc)[z_index]
sn_Ilc= np.inld(sn_t,Il)[z_index]
sn_Ilc= np.inld(sn_t,Il)[z_index]
CM[zz]['la']['la']+=np.nansum(type_z[sn_Ia]==b'lbc')/(np.nansum(sn_Ia))
CM[zz]['lbc']['la']+=np.nansum(type_z[sn_Ia]==b'll')/(np.nansum(sn_Ia))
CM[zz]['UKNOWN']['la']+=np.nansum(type_z[sn_Ia]==b'll')/(np.nansum(sn_Ia))
CM[zz]['UKNOWN']['la']+=np.nansum(type_z[sn_Ibc]==b'la')/(np.nansum(sn_Ibc))
CM[zz]['la']['lbc']+=np.nansum(type_z[sn_Ibc]=b'la')/(np.nansum(sn_Ibc))
CM[zz]['Ilc']['lbc']+=np.nansum(type_z[sn_Ibc]=b'll')/(np.nansum(sn_Ibc))
CM[zz]['UKNOWN']['lbc']+=np.nansum(type_z[sn_Ibc]=b'UNKNOWN')/(np.nansum(sn_Ibc))
CM[zz]['la']['Il']+=np.nansum(type_z[sn_Il]=b'la')/(np.nansum(sn_Il))
CM[zz]['lbc']['Il']+=np.nansum(type_z[sn_Il]=b'lbc')/(np.nansum(sn_Il))
CM[zz]['Il']['Il']+=np.nansum(type_z[sn_Il]=b'lbc')/(np.nansum(sn_Il))
CM[zz]['UKNOWN']['Il']+=np.nansum(type_z[sn_Il]=b'll')/(np.nansum(sn_Il))
CM[zz]['UKNOWN']['Il']+=np.nansum(type_z[sn_Il]=b'll')/(np.nansum(sn_Il))
CM[zz]['UKNOWN']['Il']+=np.nansum(type_z[sn_Il]=b'UNKNOWN')/(np.nansum(sn_Il))
                                                                               CM[zz]=CM[zz].fillna(0)
                                                                              nClassified+=
np.nansum(type_z[sn_Ia]==b'Ia')+np.nansum(type_z[sn_Ia]==b'Ibc')+np.nansum(type_z[sn_Ia]==b'II')
                                                                              Ia]==b'Ia')+np.nansum(type_z[sn_Ia]==b'Ibc')+np.nansum(type_z[sn_Ia]==b'II')
+np.nansum(type_z[sn_Ibc]==b'Ia')+np.nansum(type_z[sn_Ibc]==b'Ibc')+np.nansum(type_z[sn_Ibc]==b'II')
+np.nansum(type_z[sn_II]==b'Ia')+np.nansum(type_z[sn_II]==b'Ibc')+np.nansum(type_z[sn_II]==b'II')
nUnclassified = classify['nriltered'][zz]['filtered_class']-nClassified
classify['nclassified'][zz]['classified']+= nClassified
classify['nclassified'][zz]['unclassified']+= nUnclassified
```