

# DCF: An Efficient and Robust Density-Based Clustering Method

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# Problem Statement

## Introduction

**Mode-seeking clustering** associates each point to a mode of the underlying probability density function.

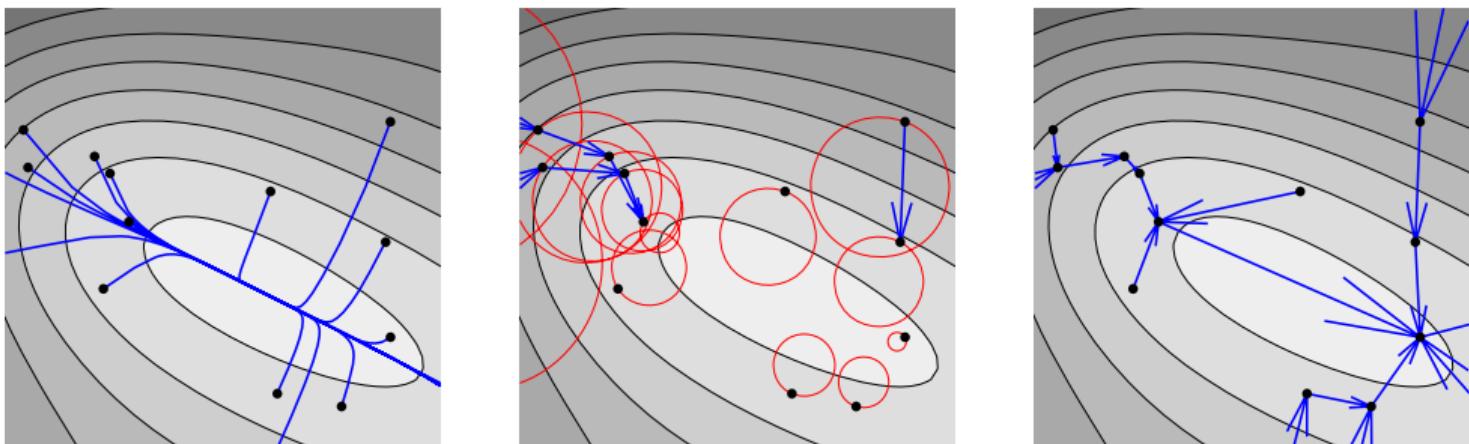


Figure: 1 of Vedaldi and Soatto 2008.

# Problem Statement

## Introduction

**Mode-seeking clustering** associates each point to a mode of the underlying probability density function.

### Benefits:

- Detect clusters with arbitrary structure.
- Number of clusters not required as an input.

### Challenges:

- Point modes are not robust.
- Parameter tuning is hard to assess.
- High computational complexity.

**Can we develop a fast, flexible and robust mode-seeking method?**

# Our Contribution

## Introduction

We introduce **Density Core Finding (DCF)** aiming at improving the applicability and efficiency of Density Peaks Clustering (DPC).

By directing the peak-finding method to detect modal sets, our algorithm is:

- ① applicable to large datasets,
- ② capable of detecting clusters of varying density,
- ③ competent at deciding the correct number of clusters.

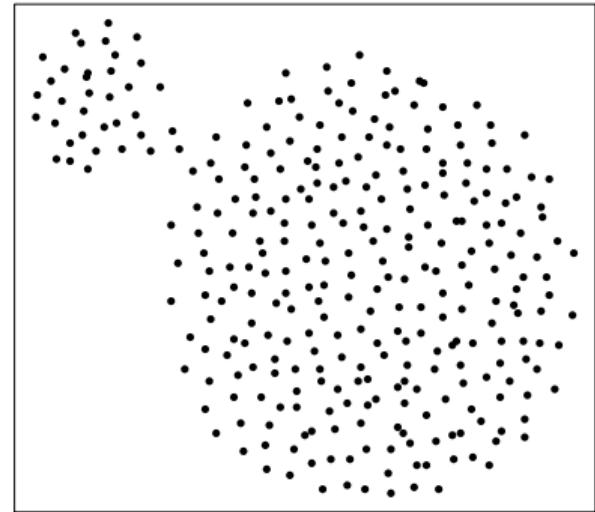
# Density Peaks Clustering

## Preliminaries

“Cluster centers ..are surrounded by neighbors with lower local density ..and they are at a relatively large distance from any points with a higher local density.”

- Rodriguez and Laio 2014

- DPC is a mode-seeking clustering algorithm.
- Cluster centers are selected using a heuristic known as the peak-finding criterion.
- Non-center instances are assigned to clusters using a hill-climbing method.



# Density Peaks Clustering

## Preliminaries

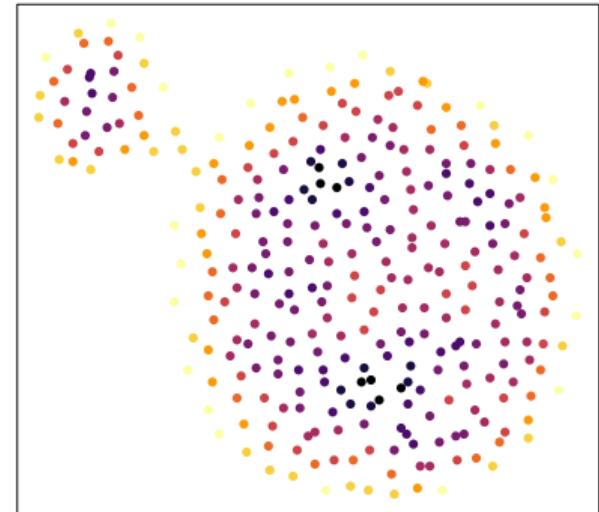
“Cluster centers ..are surrounded by neighbors with lower local density ..and they are at a relatively large distance from any points with a higher local density.”

- Rodriguez and Laio 2014

For every  $x \in \mathbb{R}^d$ , let  $d_j$  be the distance from  $x$  to  $x_j$ .

The density estimate is given as

$$f(x) := \sum_j \mathbb{1}(\text{distance } d_j < \text{distance } d_c).$$



# Density Peaks Clustering

## Preliminaries

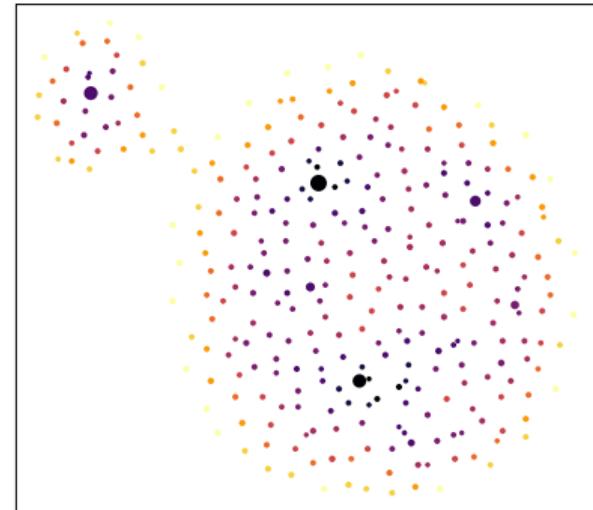
“Cluster centers ..are surrounded by neighbors with lower local density ..and they are at a relatively large distance from any points with a higher local density.”

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$\delta(x)$  is the distance to the nearest neighbor of higher local density.

We define the peak-finding criterion as

$$\gamma(x) = f(x) \cdot \delta(x).$$



# Density Peaks Clustering

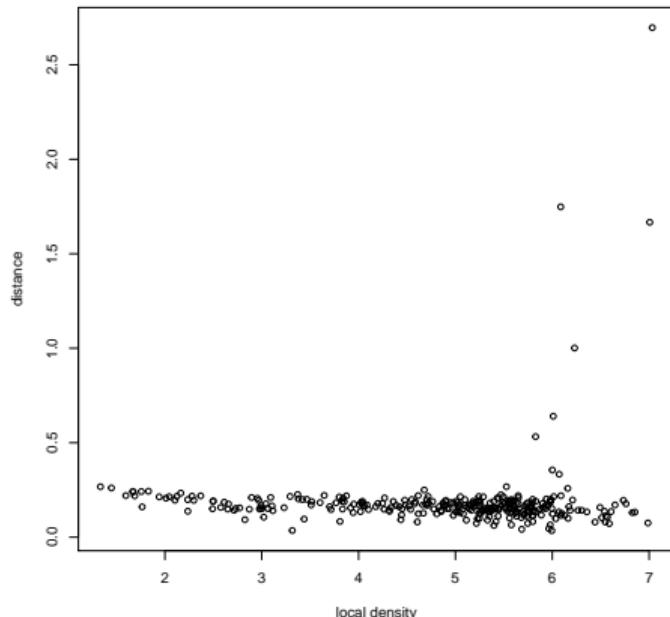
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“Cluster centers ..are surrounded by neighbors with lower local density ..and they are at a relatively large distance from any points with a higher local density.”

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In the work of Rodriguez & Laio, cluster centers are selected manually from the decision graph:

$$\{(f(x), \delta(x)) : x \in X\}.$$



# Density Peaks Clustering

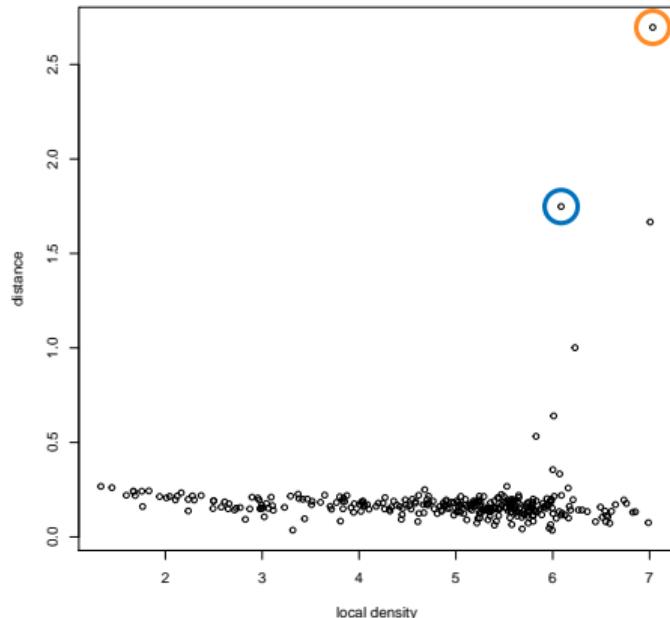
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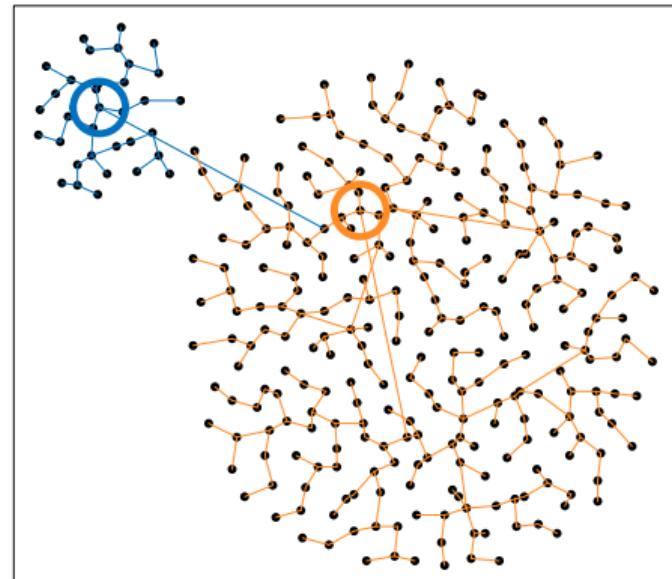
# Density Peaks Clustering

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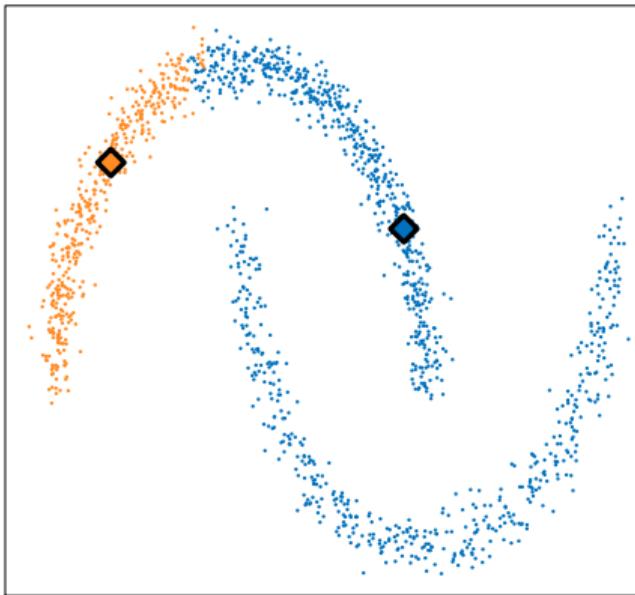
Finally, all non-center instances are assigned to the same cluster as their nearest neighbor of higher density.



# Cluster Cores

## Preliminaries

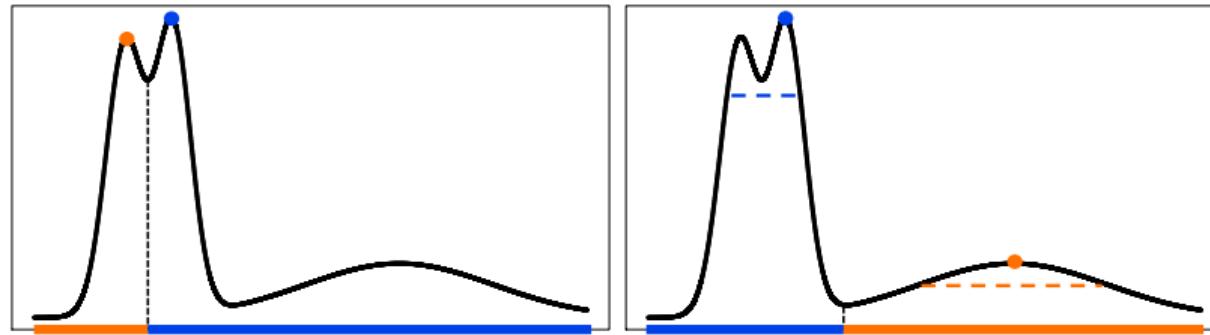
**Problem:** DPC regularly fails when data contains both high- and low-density clusters.



- ① Peak-finding criterion erroneously selects multiple centers from high-density clusters.
- ② The allocation mechanism incorrectly assigns all points in the low-density cluster.

# Cluster Cores

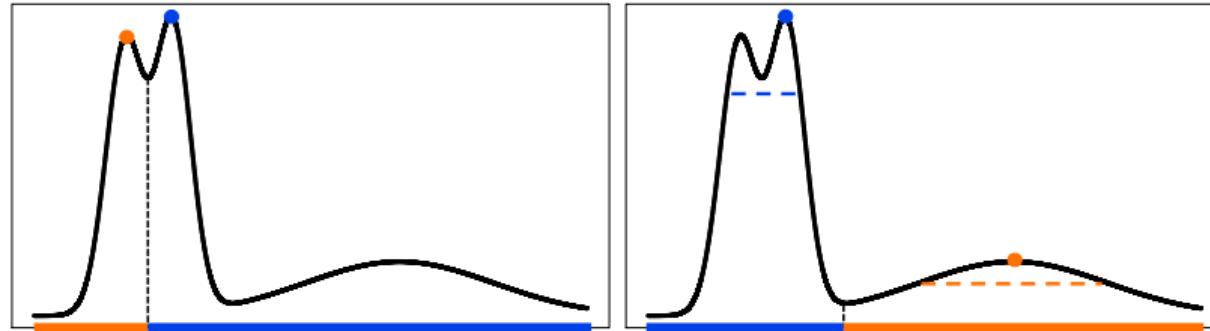
## Preliminaries



- Jiang and Kpotufe 2017; Jiang, Jang, and Kpotufe 2018 develop the notion of modal-sets for methods MCores and QuickShift++.
- Model locally high-density regions of the data with sets of arbitrary shape, size and density level.
- Parametrized by  $\beta \in (0, 1)$ , determining how much the density can fluctuate within a cluster.

# Cluster Cores

## Preliminaries



- For each instance  $x^*$  with local density  $f(x^*) = \lambda^*$ , an associated level set is found

$$\chi = \{x \in \mathbf{X} : f(x) \geq \lambda^* - \beta\lambda^*\}.$$

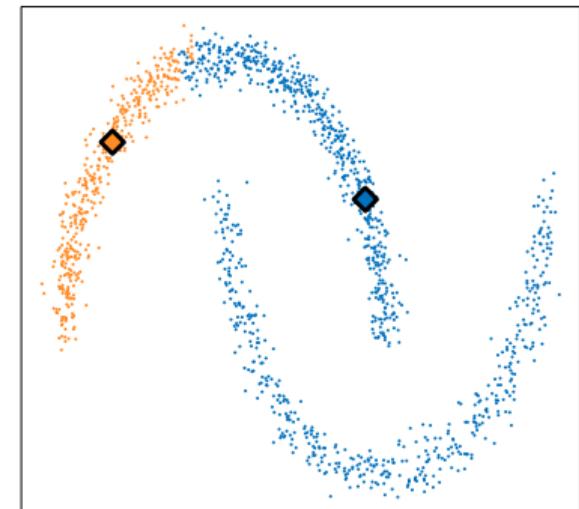
- If the subset of  $\chi$  containing  $x^*$  is disconnected from all previous modal-sets, it is accepted as a cluster core.

# Density Core Finding

## Our Proposal

**Solution:** Direct the peak-finding criterion to detect modal-sets.

- Reduces risk of selecting multiple centers from high-density cluster.
- Less sensitive to chance variation in empirical density estimate.

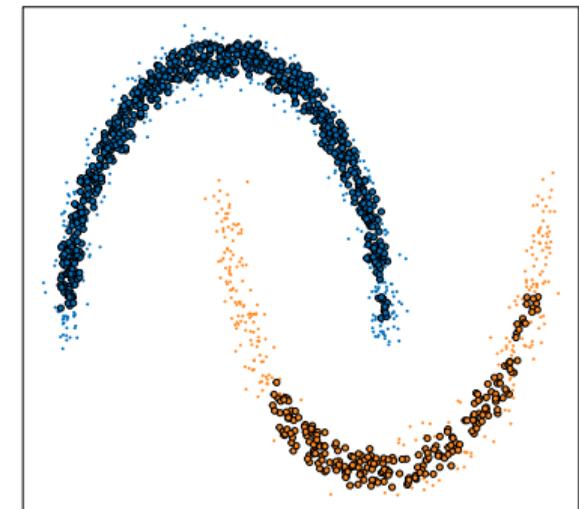


# Density Core Finding

## Our Proposal

**Solution:** Direct the peak-finding criterion to detect modal-sets.

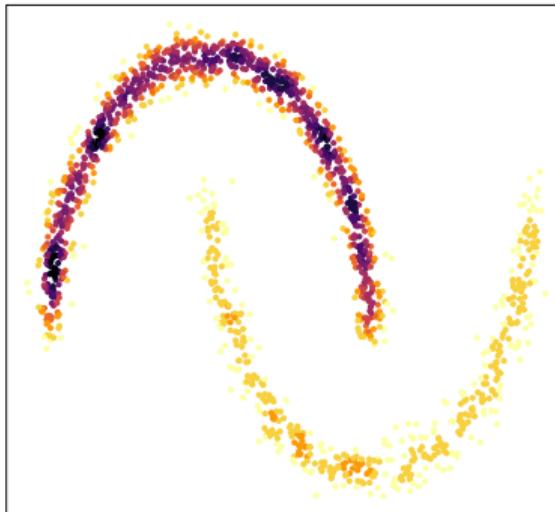
- Reduces risk of selecting multiple centers from high-density cluster.
- Less sensitive to chance variation in empirical density estimate.



# The Algorithm

## Our Proposal

**DCF Algorithm:** Detects clusters of arbitrary shape, size and density automatically and executes in  $O(n \log n)$ .



For every  $x \in \mathbb{R}^d$ , let  $r_k(x)$  denote the distance from  $x$  to its  $k$ -th nearest neighbor.

The density estimate is given as

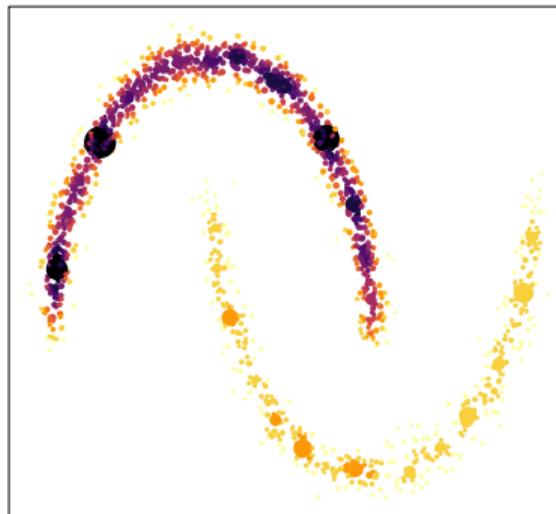
$$f_k(x) := \frac{k}{n \cdot \text{Vol}(B(x, r_k(x)))},$$

where  $v_d$  is the volume of the unit sphere in  $\mathbb{R}^d$ .

# The Algorithm

## Our Proposal

**DCF Algorithm:** Detects clusters of arbitrary shape, size and density automatically and executes in  $O(n \log n)$ .



$\delta_k(x)$  is the distance to the nearest neighbor of higher local density.

The peak-finding criterion is

$$\gamma_k(x) = f_k(x) \cdot \delta_k(x).$$

# The Algorithm

## Our Proposal

**DCF Algorithm:** Detects clusters of arbitrary shape, size and density automatically and executes in  $O(n \log n)$ .



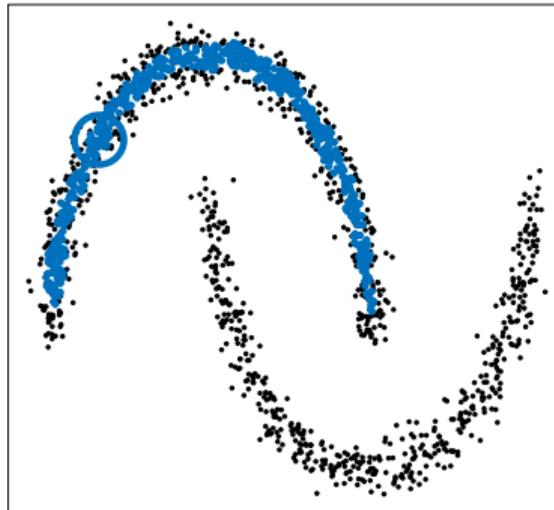
Selecting instances with maximal value of  $\gamma_k$  gives incorrect clustering.

Four points from high-density cluster have larger  $\gamma_k$  than the max in low-density cluster.

# The Algorithm

## Our Proposal

**DCF Algorithm:** Detects clusters of arbitrary shape, size and density automatically and executes in  $O(n \log n)$ .



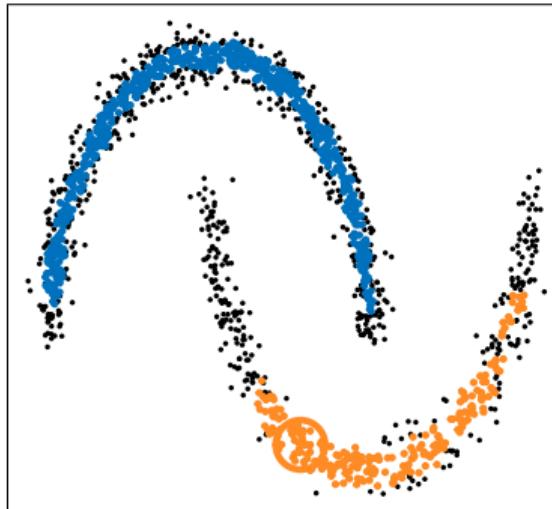
DCF finds  $x = \arg \max_{x \in X} \gamma_k(x)$  and sets  $\lambda := f_k(x)$ .

Taking  $A_\beta(x)$  to be the set of points connected to  $x$ , we add  $A_\beta(x)$  to the set of cluster cores and mark all points in  $A_\beta(x)$  as assessed.

# The Algorithm

## Our Proposal

**DCF Algorithm:** Detects clusters of arbitrary shape, size and density automatically and executes in  $O(n \log n)$ .



Find  $x = \arg \max_{x \in X} \{\gamma_k(x) : x \notin \text{Assessed}\}$ .

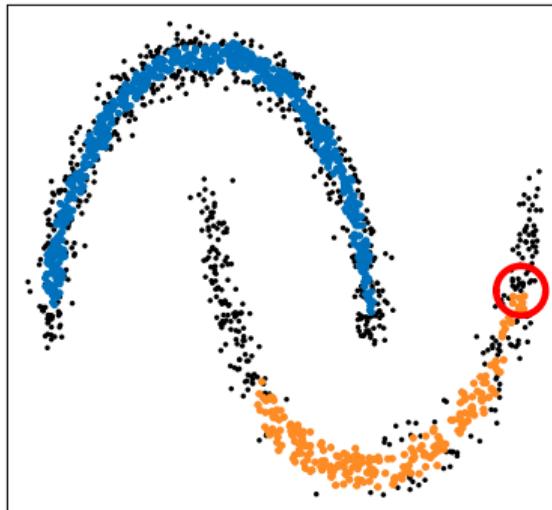
Set  $\lambda := f_k(x)$ , identify the points connected to  $x$  as  $A_\beta(x)$  and mark all points in  $A_\beta(x)$  as assessed.

If  $A_\beta(x)$  is disjoint from all cluster cores, add  $A_\beta(x)$  to  $\widehat{\mathcal{M}}$ .

# The Algorithm

## Our Proposal

**DCF Algorithm:** Detects clusters of arbitrary shape, size and density automatically and executes in  $O(n \log n)$ .

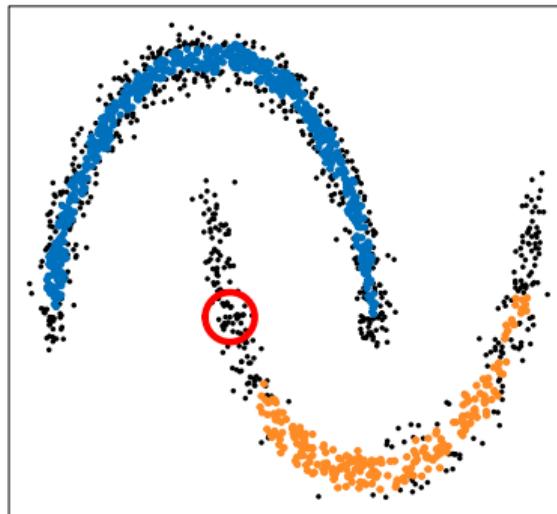


The search procedure terminates when every  $x \in \mathcal{X}$  has been assessed.

# The Algorithm

## Our Proposal

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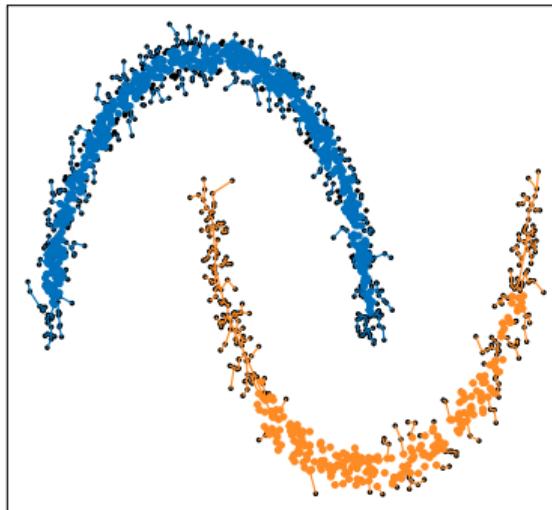


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# The Algorithm

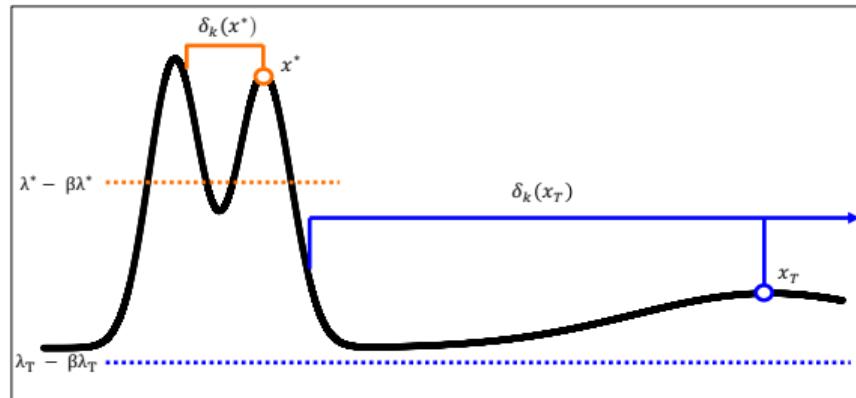
## Our Proposal

**DCF Algorithm:** Detects clusters of arbitrary shape, size and density automatically and executes in  $O(n \log n)$ .



Finally, all non-core instances are assigned to the same cluster as their nearest neighbor of higher density.

# Mode Recovery Analysis



The point  $x^*$  is assessed iff.  
 $\gamma_k(x^*) > \gamma_k(x_T)$ .

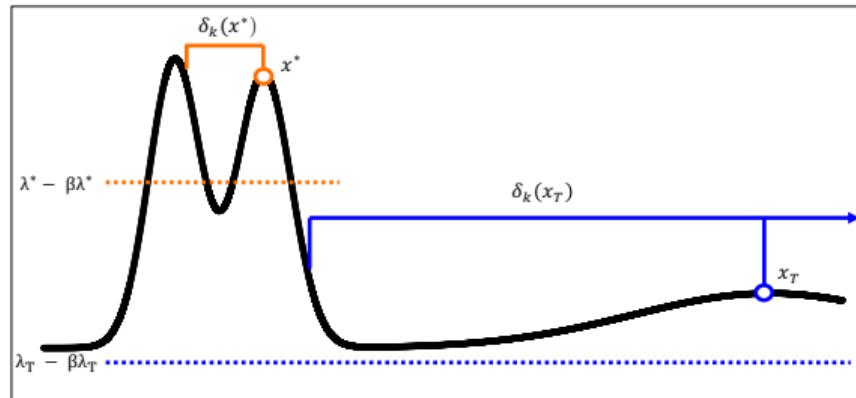
As  $\delta_k(x_T)$  is not bounded, we cannot guarantee all modes will be found.

Theoretical results demonstrate why this is unlikely to hinder performance.

## Proposition 1

*Any cluster that corresponds to a connected component in the mutual k-NN graph will be recovered by DCF.*

# Mode Recovery Analysis



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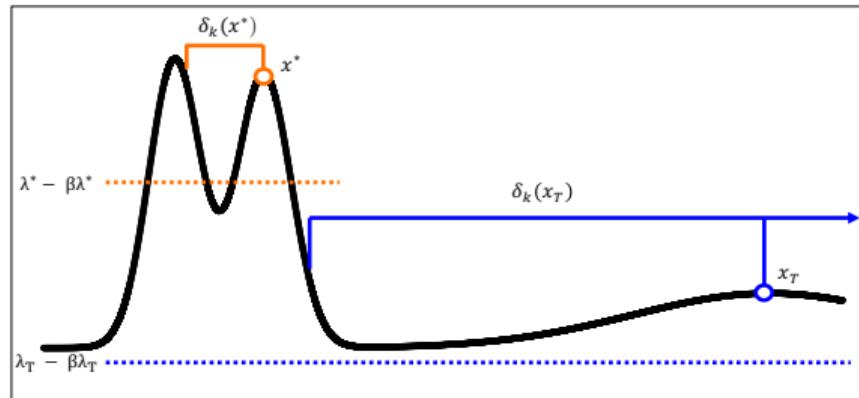
Theoretical results demonstrate why this is unlikely to hinder performance.

## Proposition 2

*The probability  $x_T$  being connected to the remainder of the graph decreases as the magnitude of  $\delta_k(x_T)$  increases.*

[Adapted from Prop. 6 of Maier, Hein, and von Luxburg 2009]

# Mode Recovery Analysis



The point  $x^*$  is assessed iff.  
 $\gamma_k(x^*) > \gamma_k(x_T)$ .

As  $\delta_k(x_T)$  is not bounded, we cannot guarantee all modes will be found.

Theoretical results demonstrate why this is unlikely to hinder performance.

## Proposition 3

If DCF terminates at  $x_T$  with termination density level  $\lambda_T - \beta\lambda_T$ ,  $\lambda_T - \beta\lambda_T$  is at least as low as the lowest dip in density between clusters in  $\mathbf{X}$ .

# Set Up

## Experiments

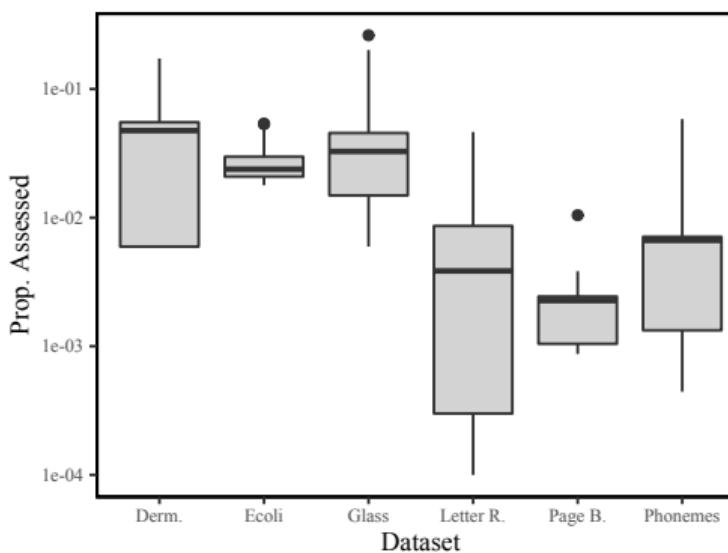
- We compare the performance of DCF with:
  - QuickShift++ (QSP)
  - Density Peaks Clustering (DPC)
  - Adaptive DPC (ADP)
  - Comparative DPC (CDP)
  - DBSCAN (DBS)
  - HDBSCAN (HDB)
- DCF is assessed on six real-world datasets, five UCI datasets and the Phonemes dataset.
- The clusterings are assessed using Adjusted Rand Index (ARI) and Adjusted Mutual Information (AMI) as well as the time taken to execute.

### Project Github Repository:

- Implementation of DCF in Python
- Code to replicate all experiments
- <https://github.com/tobinjo96/DCFcluster>

| <b>Dataset</b> | <b>Metric</b> | <b>DCF</b>  | <b>QSP</b>  | <b>DPC</b>  | <b>ADP</b> | <b>CDP</b>  | <b>DBS</b> | <b>HDB</b> |
|----------------|---------------|-------------|-------------|-------------|------------|-------------|------------|------------|
| Derm.          | ARI           | 0.72        | 0.70        | 0.22        | 0.59       | <b>0.73</b> | 0.44       | 0.47       |
|                | AMI           | <b>0.78</b> | <b>0.78</b> | 0.45        | 0.73       | 0.75        | 0.63       | 0.66       |
| Ecoli          | ARI           | <b>0.73</b> | <b>0.73</b> | 0.55        | 0.72       | 0.51        | 0.50       | 0.40       |
|                | AMI           | <b>0.68</b> | <b>0.68</b> | 0.50        | 0.65       | 0.55        | 0.48       | 0.41       |
| Glass          | ARI           | <b>0.31</b> | 0.30        | 0.20        | 0.26       | 0.25        | 0.25       | 0.25       |
|                | AMI           | <b>0.42</b> | 0.40        | 0.27        | 0.38       | 0.38        | 0.38       | 0.37       |
| Letter R.      | ARI           | 0.20        | 0.20        | <b>0.22</b> | 0.10       | 0.13        | 0.07       | 0.02       |
|                | AMI           | <b>0.59</b> | 0.58        | 0.53        | 0.33       | 0.42        | 0.46       | 0.45       |
| Page B.        | ARI           | <b>0.46</b> | <b>0.46</b> | 0.39        | 0.38       | 0.42        | 0.32       | 0.33       |
|                | AMI           | <b>0.30</b> | <b>0.30</b> | 0.27        | 0.26       | 0.29        | 0.18       | 0.20       |
| Phonemes       | ARI           | <b>0.76</b> | <b>0.76</b> | 0.71        | 0.70       | 0.56        | 0.44       | 0.36       |
|                | AMI           | <b>0.83</b> | 0.80        | 0.79        | 0.75       | 0.66        | 0.61       | 0.57       |

| Dataset   | DCF          | QSP   | DPC     | ADP     | CDP    | DBS         | HDB         |
|-----------|--------------|-------|---------|---------|--------|-------------|-------------|
| Derm.     | 0.07         | 0.03  | 4.65    | 2.5     | 0.32   | <b>0.01</b> | 0.02        |
| Ecoli     | 0.06         | 0.02  | 2.54    | 1.67    | 0.13   | <b>0.00</b> | 0.02        |
| Glass     | 0.03         | 0.05  | 0.61    | 0.24    | 0.11   | <b>0.00</b> | <b>0.00</b> |
| Letter R. | <b>12.79</b> | 19.21 | 2430.84 | 1002.42 | 372.14 | 19.94       | 25.53       |
| Page B.   | 0.73         | 1.61  | 123.27  | 43.26   | 14.59  | 1.23        | <b>0.68</b> |
| Phonemes  | <b>7.21</b>  | 8.79  | 1627.81 | 57.33   | 43.22  | 15.26       | 11.42       |



# Face Detection Application

*“Modern clustering problems require efficient detection of clusters with arbitrary shape, size and density.”*

- Face recognition is a central problem in computer vision.
- We apply DCF to numerical features extracted from two prominent face datasets.

| Name        | Instances | Dim | Identities |
|-------------|-----------|-----|------------|
| MS-Celeb-1M | 1,160,507 | 256 | 17,146     |
| YTB-Faces   | 155,282   | 256 | 1,595      |

# Face Detection Application

| Dataset   | Metric | DCF         | QSP  | OPT  |
|-----------|--------|-------------|------|------|
| MS-Celeb  | ARI    | <b>0.90</b> | 0.83 | -    |
|           | AMI    | <b>0.96</b> | 0.92 | -    |
| YTB-Faces | ARI    | <b>0.69</b> | 0.52 | 0.06 |
|           | AMI    | <b>0.91</b> | 0.88 | 0.15 |

| Dataset   | DCF             | QSP      | OPT      |
|-----------|-----------------|----------|----------|
| MS-Celeb  | <b>13202.00</b> | 39212.14 | -        |
| YTB-Faces | <b>2212.59</b>  | 4338.95  | 29631.24 |



# Bibliography I

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# Bibliography II

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& Mimi Zhang

Introduction

Preliminaries

Our Proposal

Analysis

Experiments

Application

Conclusion

References



- Vedaldi, Andrea and Stefano Soatto (2008). "Quick Shift and Kernel Methods for Mode Seeking". In: *Computer Vision – ECCV 2008*. Ed. by David Forsyth, Philip Torr, and Andrew Zisserman. Lecture Notes in Computer Science. Berlin, Heidelberg: Springer, pp. 705–718. DOI: [10.1007/978-3-540-88693-8\52](https://doi.org/10.1007/978-3-540-88693-8_52).