

## TP 10 : Revisions

**Exercise 1 (Bézier curves).** Write the function  $f(x) = 4x^3 - 6x^2 + 3x + 1$  for  $x \in [0, 1]$  as a cubic Bézier curve.

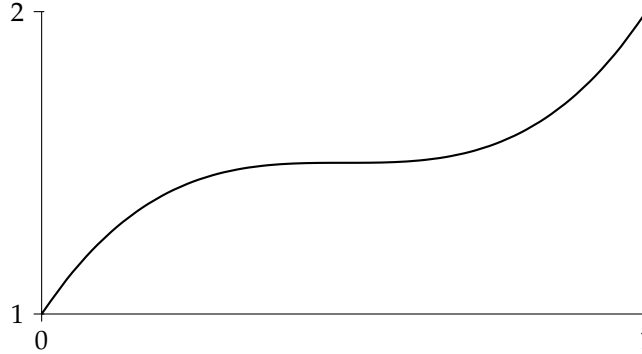


Figure 1: Graph of  $f(x) = 4x^3 - 6x^2 + 3x + 1$  for  $x \in [0, 1]$ .

**Exercise 2 (B-spline curves).** Given a degree  $k$ , control polygon  $\mathbf{d}_0, \dots, \mathbf{d}_n$ , and a knot vector (a non-decreasing sequence)  $t_0 \leq t_1 \leq \dots \leq t_m$  with  $m = n + k + 1$ , the *B-spline curve*  $\mathbf{S}(t)$  is defined as

$$\mathbf{S}(t) = \sum_{j=0}^n \mathbf{d}_j N_j^k(t), \quad t \in [t_k, t_{m-k}).$$

The  $N_j^k$  are the recursively-defined *B-spline basis functions*:

$$N_j^0(t) = \begin{cases} 1 & t \in [t_j, t_{j+1}) \\ 0 & \text{otherwise} \end{cases} \quad \text{and} \quad N_j^k(t) = \underbrace{\frac{t - t_j}{t_{j+k} - t_j}}_{w_{j,k}(t)} N_j^{k-1}(t) + \underbrace{\frac{t_{j+k+1} - t}{t_{j+k+1} - t_{j+1}}}_{1 - w_{j+1,k}(t)} N_{j+1}^{k-1}(t).$$

(De Boor algorithm). Fix a parameter  $t \in [t_i, t_{i+1}) \subset [t_k, t_{m-k})$ . For  $j = i - k, \dots, i$ , set  $\mathbf{d}_j^0 = \mathbf{d}_j$ . Compute

$$\mathbf{d}_j^{r+1} = (1 - w_{j,k-r}) \mathbf{d}_{j-1}^r + w_{j,k-r} \mathbf{d}_j^r$$

for  $r = 1, \dots, k$  and  $j = i - k + r, \dots, i$ . The weights are computed as follows:

$$w_{j,k-r} = \frac{t - t_j}{t_{j+k-r} - t_j}.$$

The curve point is  $\mathbf{S}(t) = \mathbf{d}_i^k$ .

Consider these five control points in  $\mathbb{R}^2$  (see Figure 2 on the next page):

$$\mathbf{d}_0 = \begin{bmatrix} -1 \\ 4 \end{bmatrix} \quad \mathbf{d}_1 = \begin{bmatrix} -3 \\ 0 \end{bmatrix} \quad \mathbf{d}_2 = \begin{bmatrix} 3 \\ -3 \end{bmatrix} \quad \mathbf{d}_3 = \begin{bmatrix} 4 \\ 1 \end{bmatrix} \quad \mathbf{d}_4 = \begin{bmatrix} 1 \\ 4 \end{bmatrix}$$

We are given four uniform knot vectors:

$$\begin{aligned} T_1 &= (t_0, \dots, t_6) = (0, 1, 2, 3, 4, 5, 6), \\ T_2 &= (t_0, \dots, t_7) = (0, 1, 2, 3, 4, 5, 6, 7), \\ T_3 &= (t_0, \dots, t_8) = (0, 1, 2, 3, 4, 5, 6, 7, 8), \\ T_4 &= (t_0, \dots, t_9) = (0, 1, 2, 3, 4, 5, 6, 7, 8, 9). \end{aligned}$$

Together with the control points  $\mathbf{d}_i$ , each knot vector  $T_j$  defines a unique B-spline curve  $\mathbf{S}_j(t)$ .

- (i) For each knot vector  $T_j$ : what is the *degree*  $k$  of the corresponding B-spline curve  $S_j$ ?
- (ii) For each knot vector  $T_j$ : (approximately) plot the corresponding B-spline basis functions  $N_i^k$  for  $i = 0, \dots, 4$ . What is the support for each basis function  $N_i^k$ ? (Support refers to the parameter interval where the function is non-zero.)
- (iii) For each curve  $S_j$ : what is the domain – the interval of definition?
- (iv) For each curve  $S_j$ : (approximately) plot the curve; to that end, you can use the grid provided in Figure 2. What is the degree of smoothness between curve's segments?
- (v) For the quadratic curve: evaluate the curve point  $t = 4.5$  using the De Boor algorithm.
- (vi) For the quadratic curve: what is the curve's tangent vector at the point computed in the previous question? ( $t = 4.5$ )

Consider now the knot vector

$$T_5 = (t_0, \dots, t_9) = (0, 0, 0, 0, 0, 1, 1, 1, 1, 1).$$

- (vii) What are the basis functions  $N_i^0$ ?
- (viii) What are the basis functions  $N_0^4, \dots, N_4^4$  for a quartic curve defined by  $\mathbf{d}_0, \dots, \mathbf{d}_4$  and  $T_5$ ?

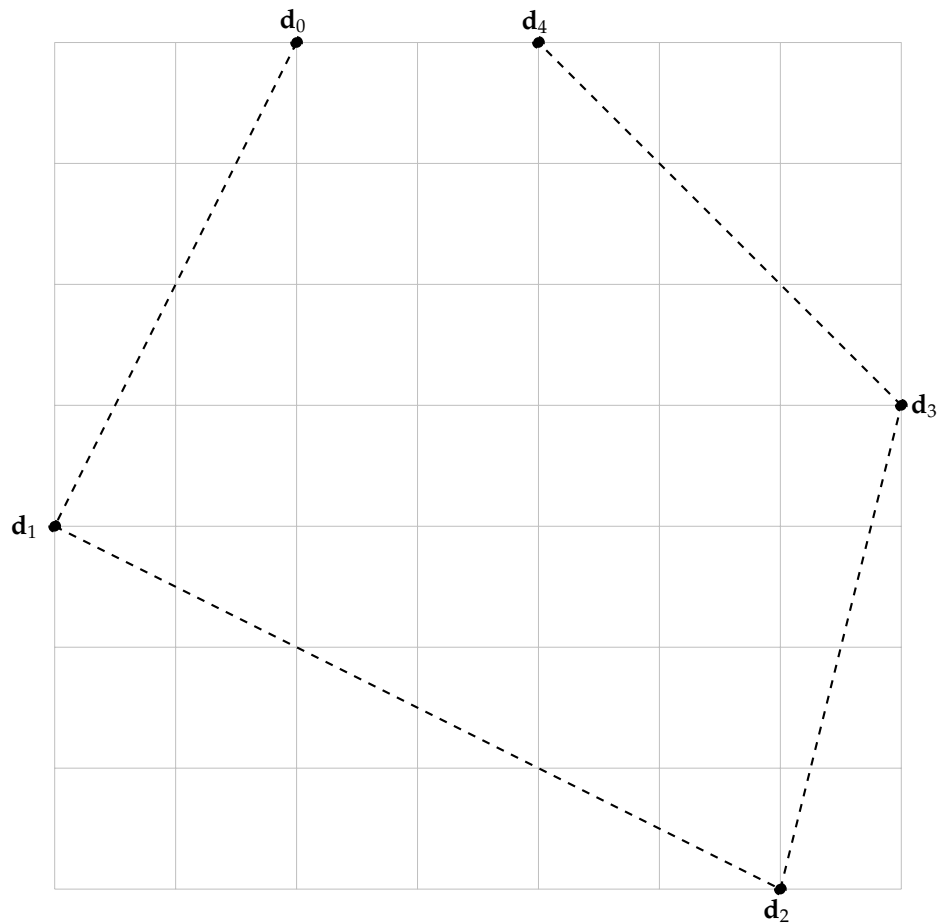


Figure 2: The control points  $\mathbf{d}_i$ . You can use this figure to plot the B-spline curves  $S_j(t)$ .

