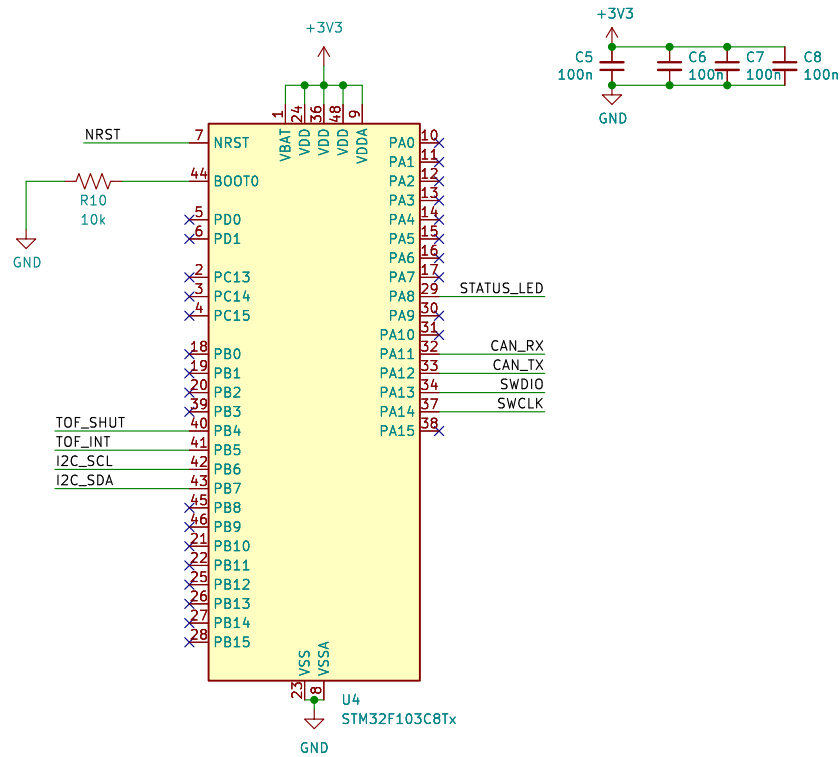
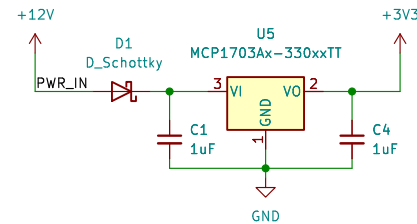


MICROCONTROLLER

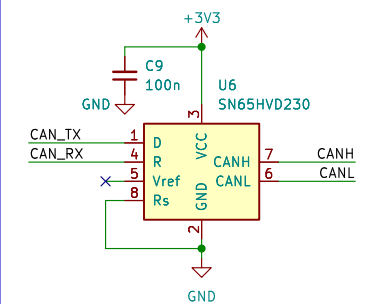


PWR REGULATION

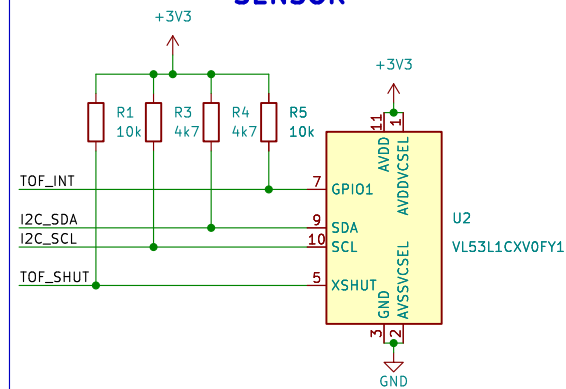


TODO(17/12/23): Beef up the filtering on this

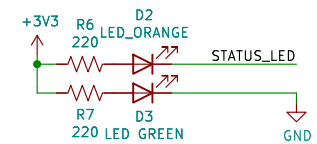
CAN BUS



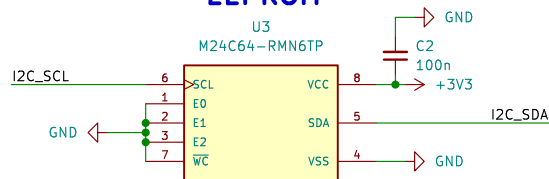
SENSOR



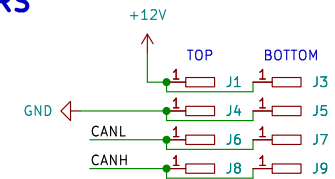
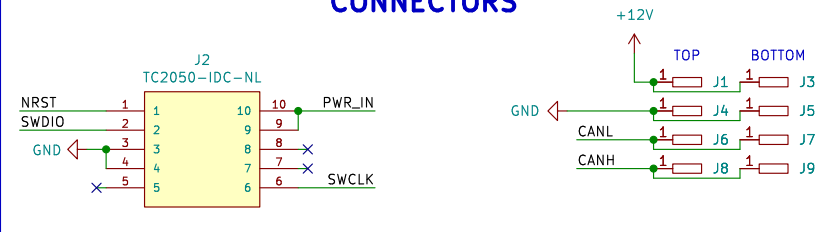
LEDS



EEPROM



CONNECTORS



<https://github.com/GrappleRobotics/LaserCAN>
<https://grappleroobotics.au>

Grapple Robotics

Sheet: /

File: LaserCAN-Board.kicad_sch

Title: LaserCAN

Size: A4

Date:

KiCad E.D.A. kicad 7.0.7

Rev: 3

Id: 1/1