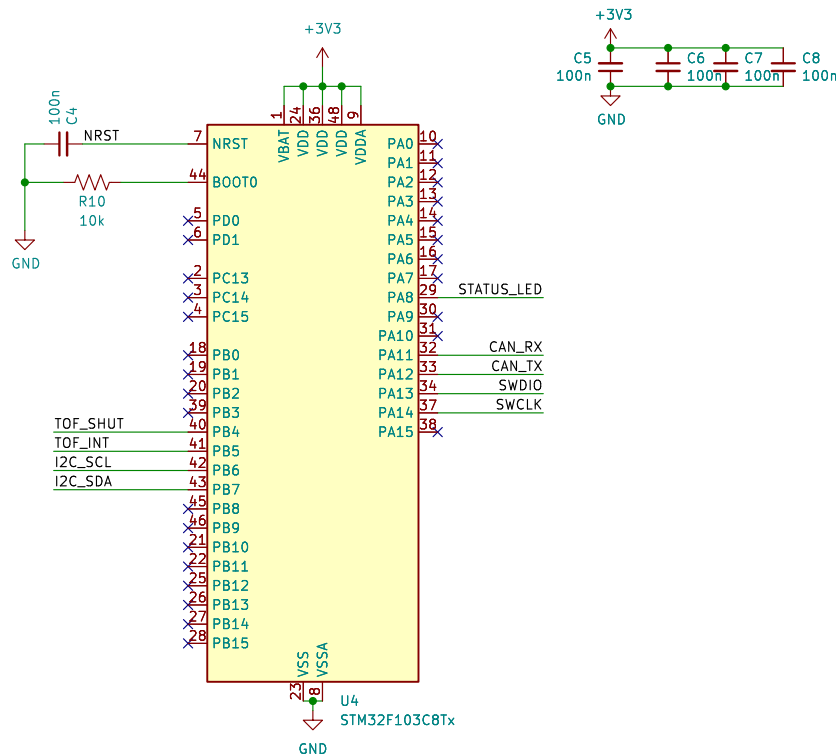
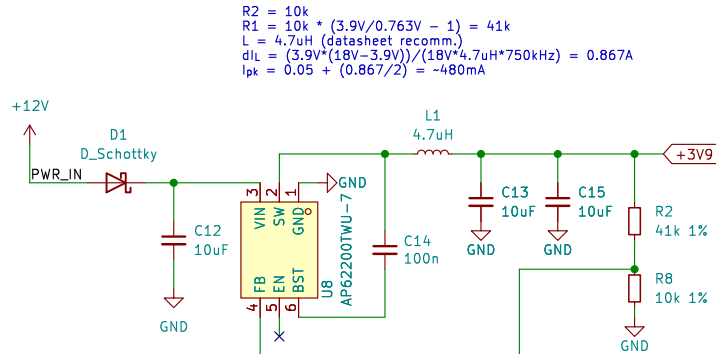


MICROCONTROLLER

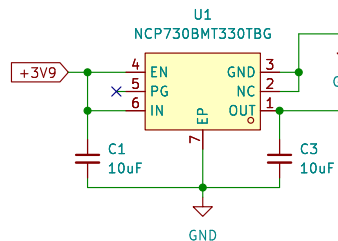


PWR REGULATION

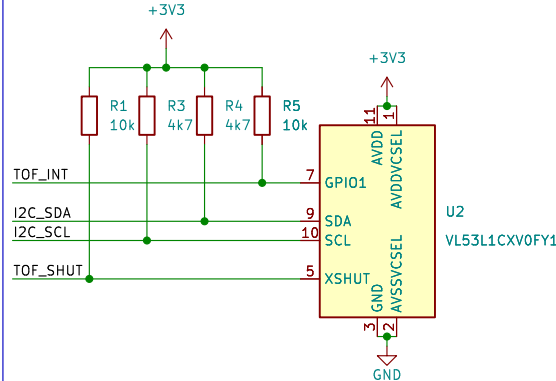


LDO 3.9V -> 3.3V

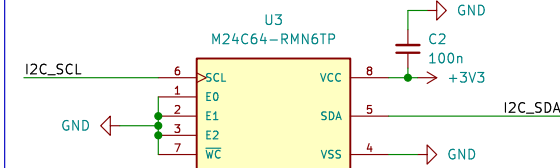
For Transient Rejection



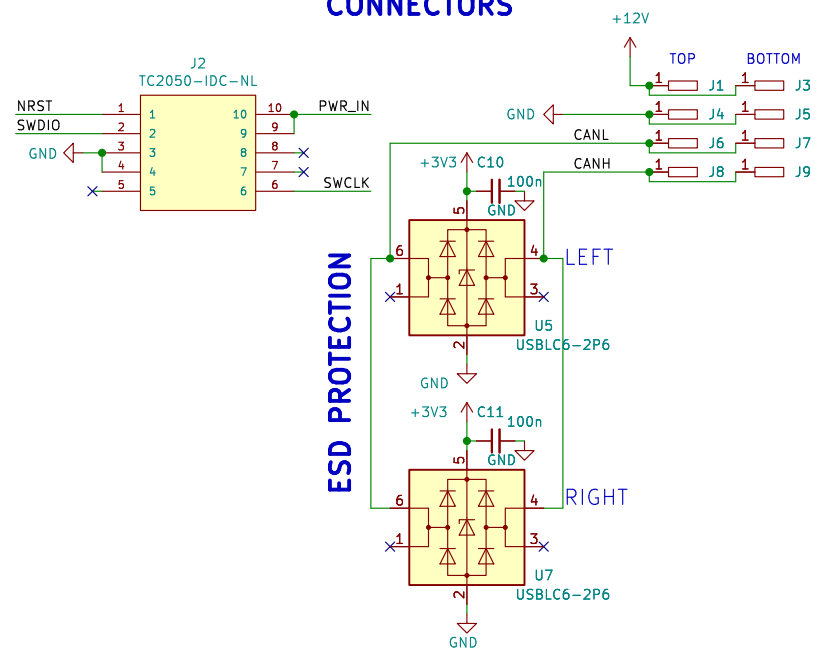
SENSOR



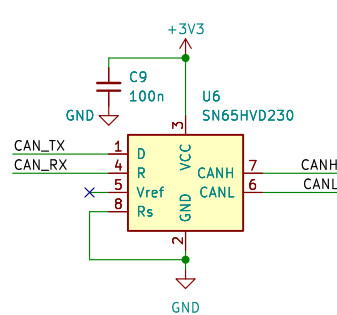
EEPROM



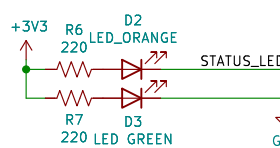
CONNECTORS



CAN BUS



LEDS



<https://github.com/GrappleRobotics/LaserCAN>
<https://grappleroobotics.au>

Grapple Robotics

Sheet: /
File: LaserCAN-Board.kicad_sch

Title: LaserCAN

Size: A3
KiCad E.D.A. kicad 7.0.7

Date:
Id: 1/1

Rev: 3