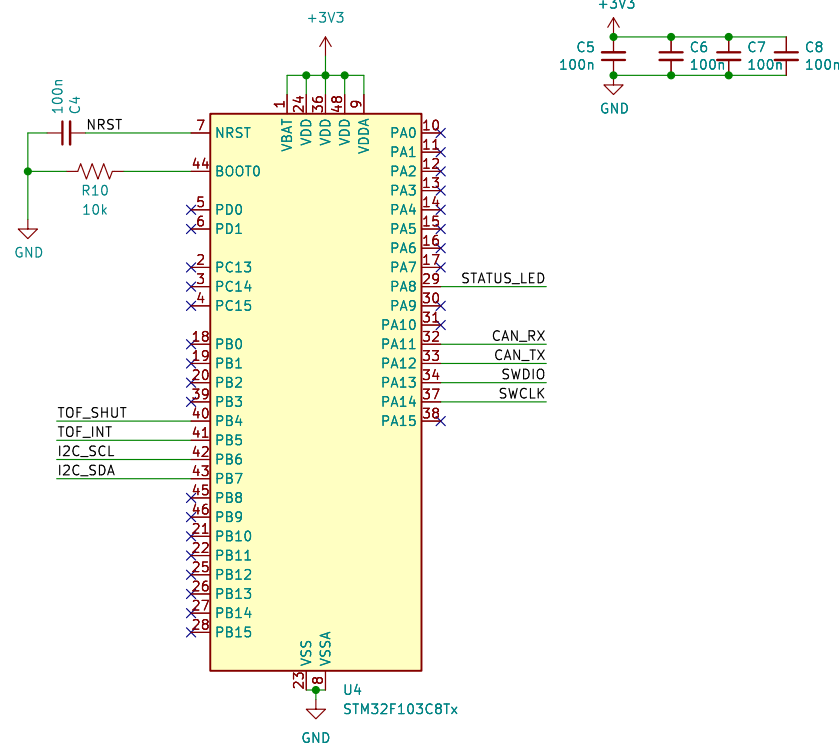
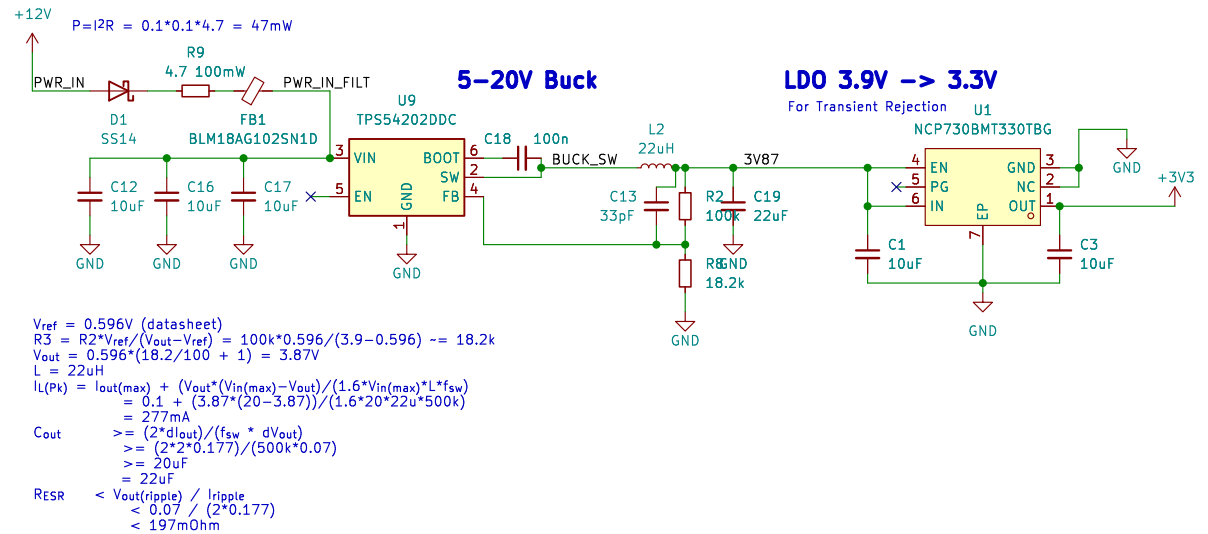


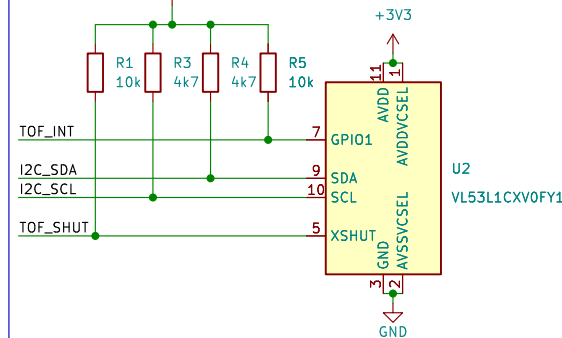
MICROCONTROLLER



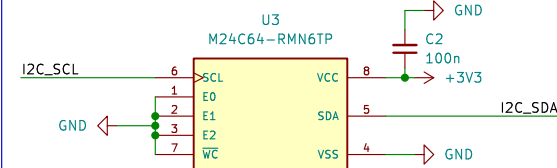
PWR REGULATION



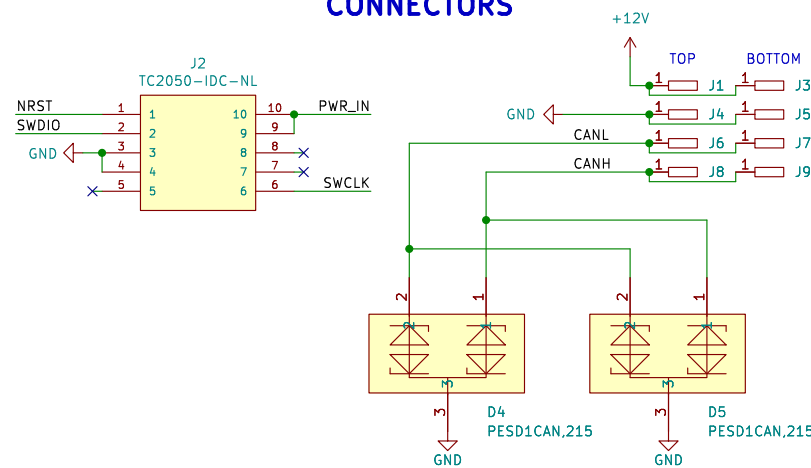
SENSOR



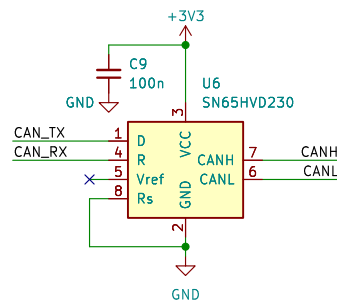
EEPROM



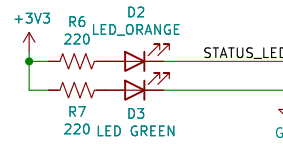
CONNECTORS



CAN BUS



LEDS



- H1 MountingHole
- H2 MountingHole

<https://github.com/GrappleRobotics/LaserCAN>
<https://grappleroobotics.au>
Grapple Robotics
 Sheet: /
 File: LaserCAN-Board.kicad_sch

Title: LaserCAN

Size: A3
 KiCad E.D.A. kicad 7.0.7

Date:

Rev: 3

Id: 1/1