

ROS Operation Test

1. Open terminals
2. Start ROSMaster: type: Roscore
3. `roslaunch rospy_tutorials talker`
4. `rqt_graph`
5. `roslaunch rospy_tutorials listener`
6. `rqt_graph`
7. `roslaunch turtlesim turtlesim_node`
8. `rqt_graph`
9. `roslaunch turtlesim turtle_teleop_key`
10. `rqt_graph`