Numerical Modeling

Unit 3: Numerical Differentiation and Integration

- A1. Numerical Differentiation
 - for a function/data set f(x) we define the derivative in a point x_0 as:

$$f'(x_n) = \frac{df}{dx}(x_n) = \lim_{x \to x_n} \frac{f(x) - f(x_n)}{x - x_n}$$

- using Taylor expansion form we can express

$$f(x) = \sum_{k=0}^{n} \frac{f^{(k)}(x_0)}{k!} (x - x_0)^k + E(x - x_0)^{n+1}$$

One note ...

- A1. Numerical Differentiation
 - forward difference

$$f(x_{n+1}) = f(x_n) + f'(x_n)(x_{n+1} - x_n) + f''(x_n)\frac{(x_{n+1} - x_n)^2}{2!} + E(x_{n+1} - x_n)^3$$

$$f'(x_n) = \frac{f(x_{n+1}) - f(x_n)}{x_{n+1} - x_n} + O(x_{n+1} - x_n)$$

- backward difference

$$f(x_{n-1}) = f(x_n) + f'(x_n)(x_{n-1} - x_n) + f''(x_n)\frac{(x_{n-1} - x_n)^2}{2!} + E(x_{n-1} - x_n)^3$$

$$f'(x_n) = \frac{f(x_{n-1}) - f(x_n)}{x_{n-1} - x_n} + O(x_{n-1} - x_n)$$

- central difference



$$f'(x_n) = \frac{f(x_{n+1}) - f(x_{n-1})}{x_{n+1} - x_{n-1}} + O(x_{n+1} - x_n)^2$$

One note

- ▶ A2. Numerical Differentiation 3-point formula
 - for f'(x) by using Lagrange extension

$$f'(x_n) = \frac{1}{2h} [-3f(x_n) + 4f(x_{n+1}) - f(x_{n+2})] + E(h^2)$$

$$f'(x_n) = \frac{1}{2h} \left[-f(x_{n-1}) + f(x_{n+1}) \right] + E(h^2)$$

- ► A2. Numerical Differentiation 2nd degree
 - using Taylor expansion

$$f''(x_n) = \frac{1}{h^2} [f(x_{n-1}) - 2f(x_n) + f(x_{n+1})] + E(h^2)$$

One note ...

Numerical Integration

B2. Implementations

Midpoint Implementation

$$\int_{a}^{b} f(x)dx = hf(\frac{a+b}{2}) + O(h^3)$$

Trapezoidal Implementation



$$\int_{a}^{b} f(x)dx = h \frac{f(a) + f(b)}{2} + O(h^{3})$$

Simpson Implementation (from 2nd degree polynomial aproximation)

$$\int_{x_0}^{x_2} f(x)dx = h \frac{f(x_0) + 4f(x_1) + f(x_2)}{3} + O(h^5)$$

Numerical Integration

B1. Definitions

$$\int f(x)dx = \lim_{n \to \infty} \sum_{i=1}^{n} f(x_i)dx$$

$$\iint f(x,y)ds = \lim_{m,n \to \infty} \sum_{i=1}^{n} \sum_{j=1}^{m} f(x_i, y_j)ds$$



$$\int_{a m}^{b n} f(x,y) dxdy \stackrel{\sim}{=} \sum_{i=1}^{steps-y} \frac{steps-y}{i} h.k. f(a+i.h, m+j.k)$$