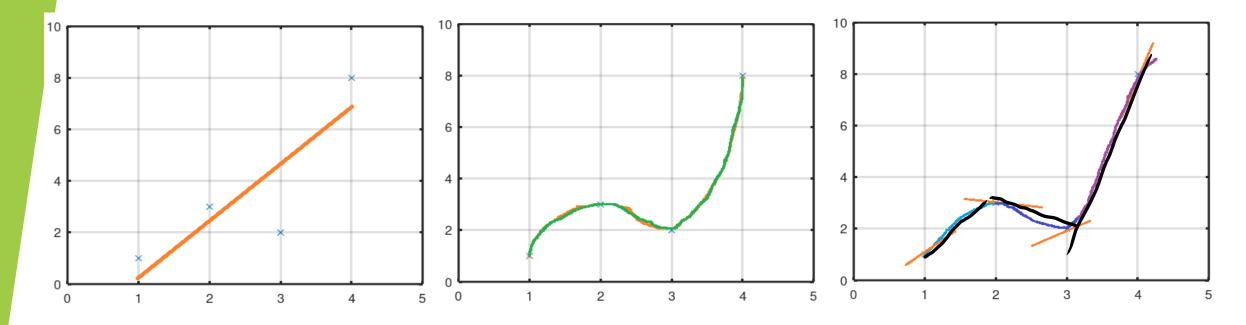
Numerical Modeling

Unit 2:Polynomial Approximations

Polynomial Interpolation



Trend

- Least Squares

Interpolation with one polynomial

- Lagrange
- Newton

Interpolation using splines

- cubic

Trend - Least Squares

Trend / Linear approximation using the least squares method

Find best fit: y = f(x) = ax + b for the set of points:

$$(x_0, y_0) (x_1, y_1) \dots (x_n, y_n)$$

Derive a and b on OneNote

$$\begin{cases} b = \bar{y} - a\bar{x} \\ a = \frac{n\sum x_i y_i - \sum x_i \sum y_i}{n\sum x_i^2 - \sum x_i^2} \end{cases}$$

Code using matlab/octave

find a 8 b so that 'err (e) is minimal

Lic
$$e = \sum (y_i - f(x_i))^2 = \sum (y_i - a \cdot x_i - b)^2$$

$$\int \frac{\partial e}{\partial a} = \sum 2 \cdot (y_i - ax_i - b) \cdot (x_i) = 0$$

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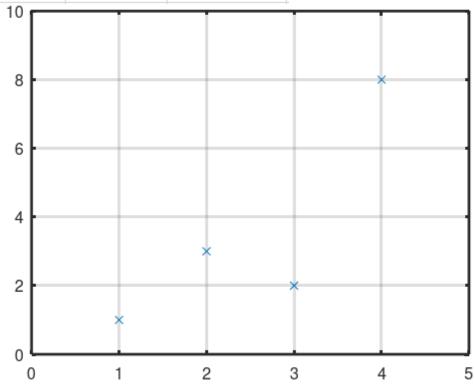
Polynomial Interpolation

Given the values	x0	x1	x2	 xn	roots
	y0	y1	y2	 yn	
	p0(x)	p2(x)	p3(x)	pn(x)	basis
	a0	a2	a3	an	coefficients
P(x)	a0*p0(x)	a1*p1(x)	a2*p2(x)	an*pn(x)	

$$P(x) = \sum_{i=0}^{N} a_i P_i(x)$$

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\mathbf{x} = [1, 2, 3, 4];

\mathbf{y} = [1, 3, 2, 8];
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Newton Interpolation

Newton Basis: $N_i(x) = (x - x_0) \dots (x - x_{i-1}) = \prod_{j=0}^{i-1} (x - x_i)$

Polynomial form: $P(x) = \sum_{i=0}^{n} f(x_i) N_i(x)$

Expansion for n degree polynomial

$$P_n(x) = a_0 + a_1(x - x_0) + a_2(x - x_0) (x - x_1) + \dots + a_n(x - x_0) (x - x_1) \dots (x - x_{n-1})$$

Derive coefficients: OneNote

Lagrange Interpolation

$$y = f(x) = ax + b$$

 $(x_0, y_0) (x_1, y_1)$

$$\begin{cases} y_0 = ax_0 + b \\ y_1 = ax_1 + b \end{cases}$$

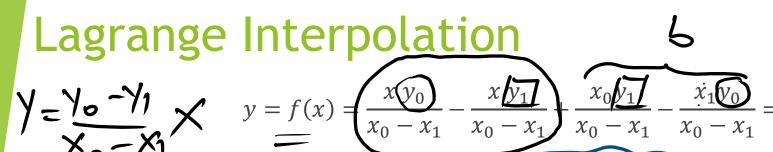
$$y_0 - y_1 = a(x_0 - x_1)$$

$$a = \frac{y_0 - y_1}{x_0 - x_1}$$

$$y_0 = \frac{y_0 - y_1}{x_0 - x_1} x_0 + b \Rightarrow b = y_0 - \frac{y_0 - y_1}{x_0 - x_1} x_0$$

$$\frac{y_0(x_0 - x_1)}{x_0 - x_1} - \frac{x_0(y_0 - y_1)}{x_0 - x_1} = \underbrace{\frac{y_0 x_0 - y_0 x_1 - x_0 y_0 + x_0 y_1}{x_0 - x_1}}_{x_0 - x_1} = \underbrace{\frac{x_0 y_1 - x_1 y_0}{x_0 - x_1}}_{x_0 - x_1} = b$$

$$f(x) = m \times f$$



$$y = \frac{x - x_1}{x_0 - x_1} y_0 + \frac{x - x_0}{x_1 - x_0} y_1$$

$$L_0(x) = \frac{1}{x_0 - x_1}$$

$$L_0(x_0) = 1 \quad L_0(x_1) = 0$$

$$L_1(x) = \frac{x - x_0}{x_1 - x_0}$$

$$L_1(x_0) = 0 \quad L_1(x_1) = 1$$

$$L_k = 0^{(x_i)} = 0 \text{ if } i \neq k$$

$$L_{k} = 0 = 1 \quad \text{if } i = k$$

$$L_{k}(x) = \frac{(x - x_{0}) \dots (x - x_{k-1})(x - x_{k+1}) \dots (x - x_{n})}{(x_{k} - x_{0}) \dots (x_{k} - x_{k-1})(x_{k} - x_{k+1}) \dots (x_{k} - x_{n})} = \prod_{\substack{i=0 \ i \neq k}}^{n} \frac{(x - x_{i})}{(x_{k} - x_{i})}$$

$$P(x) = \sum_{k=0}^{n} f(x_{k}) L_{k}(x)$$

Cubic Splines

Given a function f defined on [a,b] and a set of nodes $a=x_0 < x_1 < \cdots < x_n = b$, a **cubic spline interpolant** S for f is a function that satisfies the following conditions:

- S(x) is a cubic polynomial, denoted $S_j(x)$ on the subinterval $[x_j, x_{j+1}]$ for each j=0,1,...,n-1;
- $S(x_j) = f(x_j)$ for each j = 0,1,...,n;
- $S_{j+1}(x_{j+1}) = S_j(x_{j+1})$ for each j = 0,1,...,n-2;
- $S_{j+1}^1(x_{j+1}) = S_j^1(x_{j+1})$ for each j = 0, 1, ..., n-2;
- $S_{j+1}^2(x_{j+1}) = S_j^2(x_{j+1})$ for each j = 0, 1, ..., n-2;
- One of the following set of boundary conditions is satisfied:
 - $S^n(x_0) = S^n(x_n) = 0$ (free or natural baoundary)
 - $S^{1}(x_{0}) = f^{1}(x_{0})$ and $S^{1}(x_{n}) = f^{1}(x_{n})$ (clamped boundary)