

# Biometrics in the Bush Capital

Using a linear mixed model based wavelet transform to model non-smooth trends  
arising from designed experiments

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# What's in a title?

Non-smooth trends arising from designed experiments

Linear mixed model based wavelet transform

**Using** LMM based wavelet transform to model non-smooth trends

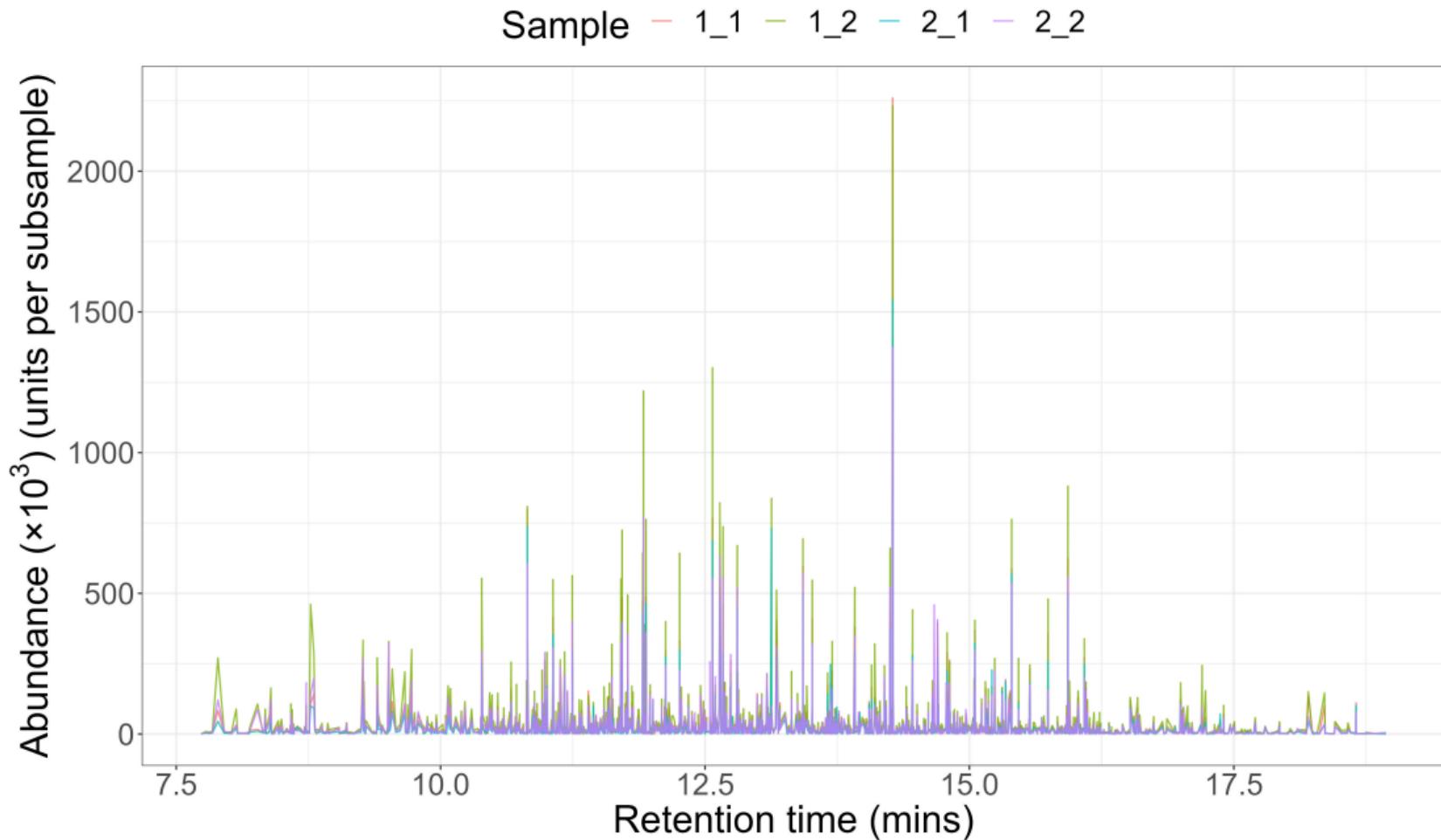


# A motivating example

Mass spectrometry (MS) based barley malt proteomics experiment (Forknall et al., 2023)

- ▶ **Multi-phase experiment (Brien & Bailey, 2006):**
  - ▶ *Phase 1: Malt Sample Collection*
    - ▶ Two separate grain samples collected at commencement of malting processing ( $g = 2$ )
  - ▶ *Phase 2: MS Processing*
    - ▶ Two subsamples taken from each grain sample ( $s = 2$ )
    - ▶ Individual subsamples processed using MS based proteomics technique
- ▶ **Proteome composition via MS**
  - ▶ Same 1811 peptides detected/quantified from each subsample.
  - ▶ Peptides detected at unique, non-equidistant retention times ( $t = 1811$ ).
  - ▶ Data set = 7,244 peptide abundance observations ( $n = g s t = 7,244$ ).







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## The linear mixed model (LMM) based wavelet transform

$$\mathbf{y} = \mathbf{X}\boldsymbol{\tau} + \mathbf{Z}_d\mathbf{u}_d + \mathbf{Z}_t\mathbf{u}_w + \mathbf{e}$$

- ▶  $\mathbf{y}$  is an  $n \times 1$  vector of abundance observations.
- ▶  $\boldsymbol{\tau}$  is a vector of fixed effects, with associated design matrix  $\mathbf{X}$ .
- ▶  $\mathbf{u}_d$  is a vector of random effects describing the experimental design structure, with associated design matrix  $\mathbf{Z}_d$ .
- ▶  $\mathbf{e}$  is an  $n \times 1$  vector of residual error effects.



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- 
- ▶  $\mathbf{u}_w$  is a  $t \times 1$  vector of random effects resulting from the LMM based wavelet transform.
  - ▶ These effects describe the non-smooth response of abundance as a function of retention time.
  - ▶  $\mathbf{Z}_t$  is an  $n \times t$  design matrix, necessary to respect multiple abundance observations at each retention time.



## The linear mixed model (LMM) based wavelet transform

$$\mathbf{y} = \mathbf{X}\boldsymbol{\tau} + \mathbf{Z}_d\mathbf{u}_d + \mathbf{Z}_w\mathbf{u}_w + \mathbf{e}$$

- ▶ Random and residual error effects are assumed to follow a normal distribution with a zero mean vector and variance-covariance matrix:

$$\text{var} \begin{pmatrix} \mathbf{u}_d \\ \mathbf{u}_w \\ \mathbf{e} \end{pmatrix} = \begin{bmatrix} \mathbf{G}_d & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{G}_w & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \mathbf{R} \end{bmatrix}.$$

- ▶ Form of  $\mathbf{u}_w$  and  $\mathbf{G}_w$  is our focus and will be investigated further.



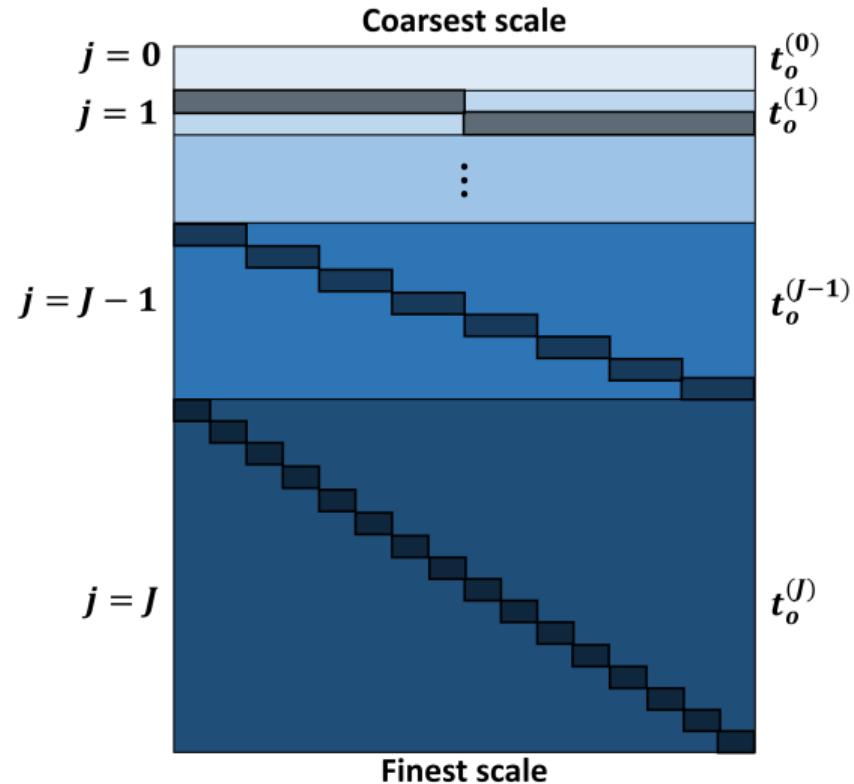
# The wavelet transform

- ▶ *What is it?*
  - ▶ Mathematical construct proven to model non-smooth data, containing discontinuities.
- ▶ *How can I use it?*
  - ▶ Classical wavelets:
    - ▶ Built on framework of multiresolution analysis - relies on the Fourier transform.
    - ▶ Only applicable where observations are equidistant and dyadic ( $\log_2(n)$  is integer) in number.
  - ▶ Second generation wavelets:
    - ▶ Implemented via 'lifting scheme' - retains multiscale properties of the classical transform.
    - ▶ Can be applied to non-equidistant observations, of any number.
- ▶ *Has it been incorporated into the LMM framework before?*
  - ▶ Classical wavelets:
    - ▶ Yes - Morris & Carroll, (2006); Wand & Ormerod, (2011).
  - ▶ Second generation wavelets:
    - ▶ Not until now!

# The second generation wavelet transform

## Wavelet scales

- ▶ Wavelet transform provides representation of data/effects at a series of **scales**.
- ▶  $J = \lceil \log_2(t) \rceil$  corresponds to the number of scales in the wavelet transform.
- ▶  $t_o^{(j)}$  is the number of wavelet functions/coefficients at each scale  $j$ .
- ▶ As  $j$  increases,  $t_o^{(j)}$  increases, but support of wavelet functions decreases.
- ▶ This formulation allows for representation of non-smooth trends, as influence of spikes limited in terms of scale and location (Nason, 2008).
- ▶ Wavelet transform can be implemented through wavelet basis matrix,  $\mathbf{W}^{-1}$ .



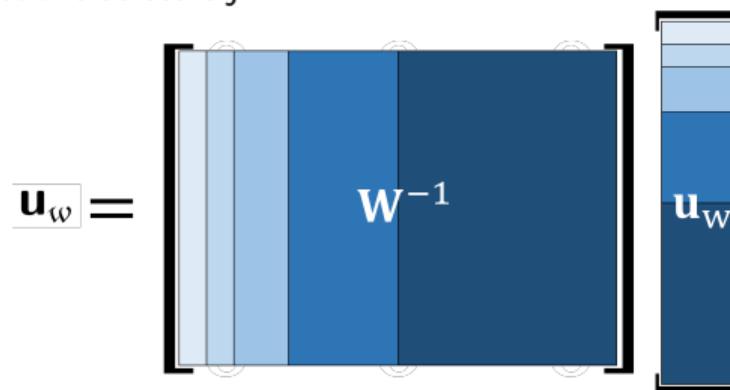


# The second generation wavelet transform

## Form of $\mathbf{u}_w$

$$\mathbf{u}_w = \mathbf{W}^{-1} \mathbf{u}_w$$

- ▶  $\mathbf{W}^{-1} = [\phi^{(0)} \quad \Psi^{(0)} \quad \Psi^{(1)} \quad \dots \quad \Psi^{(J-1)}]$  is the  $t \times t$  wavelet basis matrix.
  - ▶  $\phi^{(0)}$  and  $\Psi^{(j)}$  are  $t \times t_o^{(j)}$  matrices containing the values of the wavelet scaling function,  $\phi^{(0)}(x)$ , and wavelet functions,  $\psi^{(j)}(x)$ , at scale  $j$ .
- ▶  $\mathbf{u}_w = [\varphi \; \omega^{(0)\top} \; \omega^{(1)\top} \; \dots \; \omega^{(J-1)\top}]^\top$  is the  $t \times 1$  vector of wavelet coefficients.
  - ▶  $\varphi$  and  $\omega^{(j)}$  are  $t_o^{(j)} \times 1$  vectors of coefficients associated with the wavelet scaling function and wavelet functions at scale  $j$ .





# The second generation wavelet transform

## Form of $\mathbf{G}_w$

$$\mathbf{u}_w = \mathbf{W}^{-1} \mathbf{u}_w$$

Two options for  $\text{var}(\mathbf{u}_w)$ :

### 1. Simple wavelet transform:

- ▶ Simple variance component controls extent of ‘non-smoothness’.
- ▶  $\mathbf{u}_w \sim N(\mathbf{0}, \sigma_w^2 \mathbf{I}_t)$
- ▶  $\mathbf{G}_w = \sigma_w^2 \mathbf{W}^{-1} \mathbf{W}^{-1 \top}$



# The second generation wavelet transform

## Form of $\mathbf{G}_w$

$$\mathbf{u}_w = \mathbf{W}^{-1} \mathbf{u}_w$$

Two options for  $\text{var}(\mathbf{u}_w)$ :

### 2 Partitioned wavelet transform:

- ▶ Uses wavelet scale structure implicit in wavelet functions, allowing for heterogeneous wavelet variance at each wavelet scale:

$$\text{var}(\mathbf{u}_w) = \text{var} \left( \begin{bmatrix} \varphi \\ \omega^{(0)} \\ \omega^{(1)} \\ \vdots \\ \omega^{(J-1)} \end{bmatrix} \right) = \begin{bmatrix} \sigma_\varphi^2 & \mathbf{0} & \mathbf{0} & \dots & \mathbf{0} \\ \mathbf{0} & \sigma_{\omega^{(0)}}^2 \mathbf{I}_{t_o^{(0)}} & \mathbf{0} & \dots & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \sigma_{\omega^{(1)}}^2 \mathbf{I}_{t_o^{(1)}} & \dots & \mathbf{0} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \mathbf{0} & \mathbf{0} & \mathbf{0} & \dots & \sigma_{\omega^{(J-1)}}^2 \mathbf{I}_{t_o^{(J-1)}} \end{bmatrix}$$

- ▶  $\mathbf{G}_w = \sigma_\varphi^2 \boldsymbol{\phi}^{(0)} \boldsymbol{\phi}^{(0)\top} + \sum_{j=0}^{J-1} \sigma_{\omega^{(j)}}^2 \boldsymbol{\Psi}^{(j)} \boldsymbol{\Psi}^{(j)\top}$



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# Implementing LMM based wavelet transform

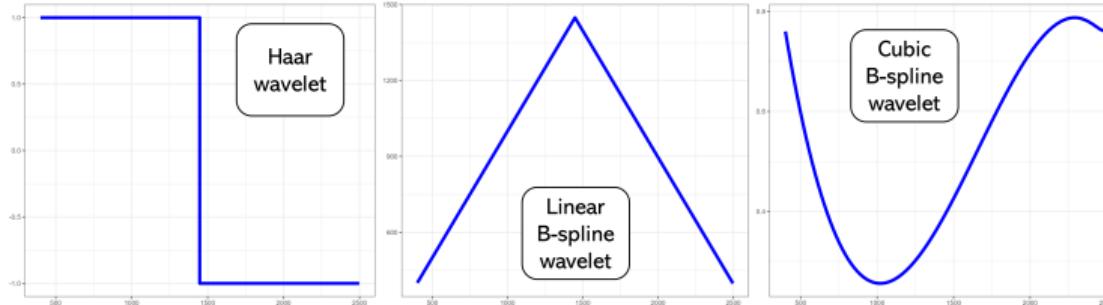
## Software solutions

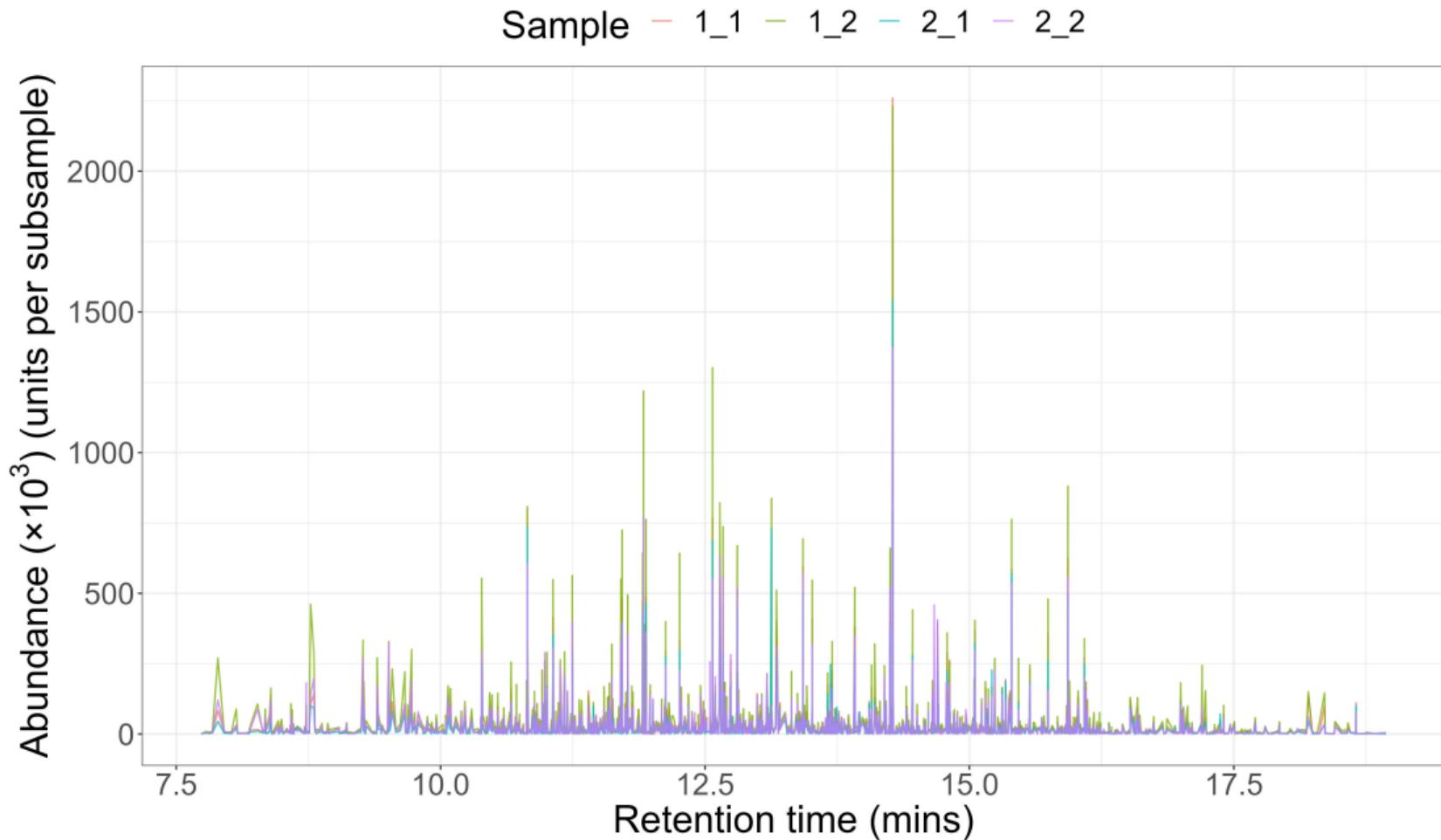
### ► LMM implementation:

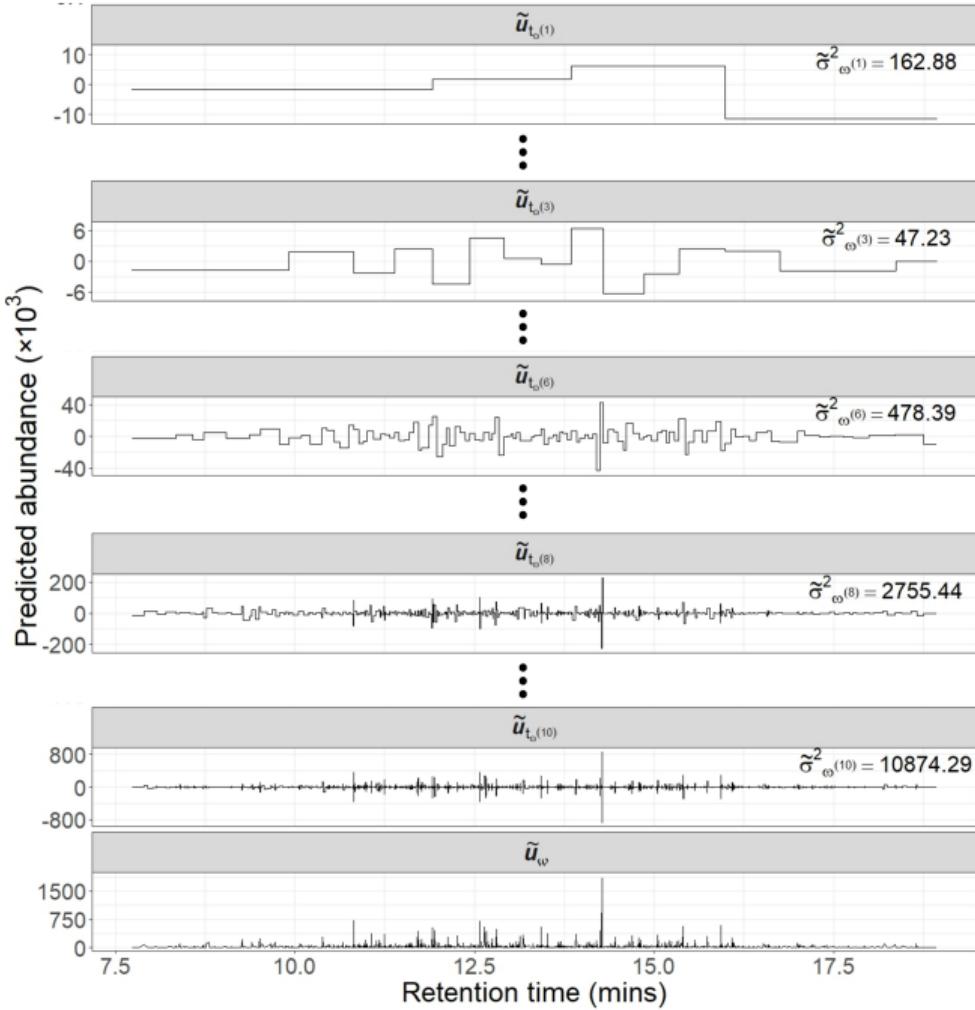
- Implementable in any LMM software or package that enables the user to specify their own design matrix, or matrix of basis functions.
- Successfully implemented in R using:
  - `asreml` (The VSNi Team, 2023),
  - `lmmSolver` (Boer, 2023),
  - `sommer` (Covarrubias-Pazaran, 2016).

### ► Second generation wavelet basis construction

- I developed an R package to construct the B-spline wavelet basis matrix (Jansen 2016, 2022).
- Package calculates  $\mathbf{W}^{-1}$  for:
  - Haar wavelet
  - Linear B-spline wavelet
  - Cubic B-spline wavelet







### Wavelet variances

$j$	$\tilde{\sigma}_{\omega^{(j)}}^2$
0	0.00
<b>1</b>	<b>162.88</b>
2	71.11
<b>3</b>	<b>47.23</b>
4	248.52
5	486.20
<b>6</b>	<b>478.39</b>
7	1454.10
<b>8</b>	<b>2755.44</b>
9	5651.23
<b>10</b>	<b>10874.29</b>



## Future work

- ▶ Explore contribution of different scales of the wavelet transform - are all scales necessary?
- ▶ Potential to explore two dimensional setting - tensor wavelet transforms.
- ▶ Forthcoming methodology paper.



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