

Biometrics in the Bush Capital

Using a linear mixed model based wavelet transform to model non-smooth trends
arising from designed experiments

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AUSTRALIA

What's in a title?

Non-smooth trends arising from designed experiments

Linear mixed model based wavelet transform

Using LMM based wavelet transform to model non-smooth trends



A motivating example

Mass spectrometry (MS) based barley malt proteomics experiment (Forknall et al., 2023)

► Multi-phase experiment (Brien & Bailey, 2006):

► *Phase 1: Malt Sample Collection*

- Two separate grain samples collected at commencement of malting processing ($g = 2$)

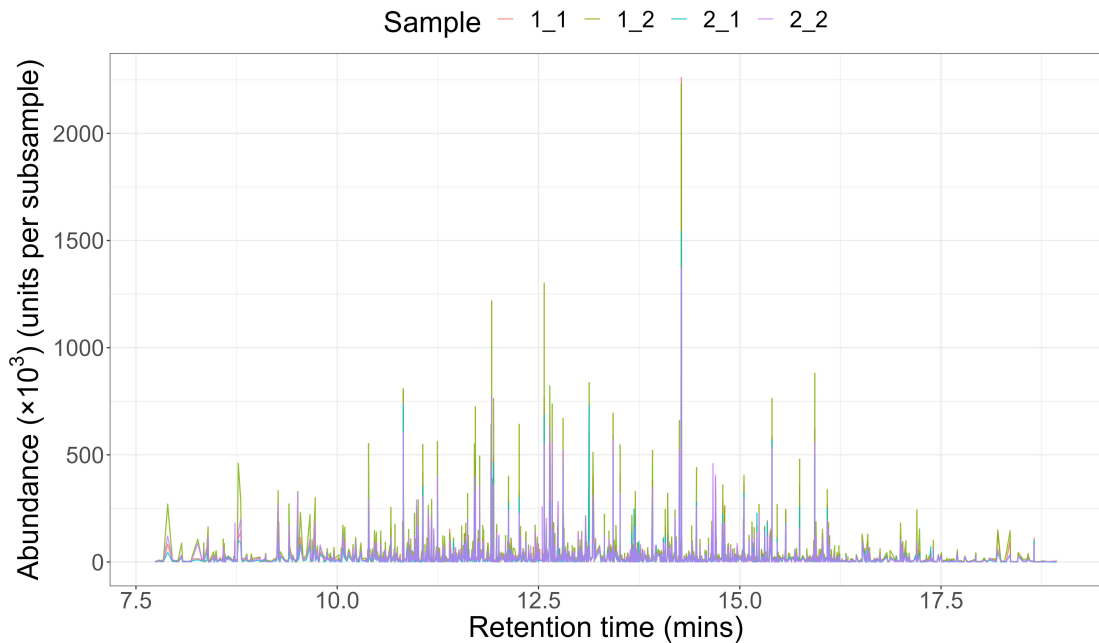
► *Phase 2: MS Processing*

- Two subsamples taken from each grain sample ($s = 2$)
- Individual subsamples processed using MS based proteomics technique

► Proteome composition via MS

- Same 1811 peptides detected/quantified from each subsample.
- Peptides detected at unique, non-equidistant retention times ($t = 1811$).
- Data set = 7,244 peptide abundance observations ($n = g s t = 7,244$).





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The linear mixed model (LMM) based wavelet transform

$$\mathbf{y} = \mathbf{X}\boldsymbol{\tau} + \mathbf{Z}_d\mathbf{u}_d + \mathbf{Z}_t\mathbf{u}_w + \mathbf{e}$$

- ▶ \mathbf{y} is an $n \times 1$ vector of abundance observations.
- ▶ $\boldsymbol{\tau}$ is a vector of fixed effects, with associated design matrix \mathbf{X} .
- ▶ \mathbf{u}_d is a vector of random effects describing the experimental design structure, with associated design matrix \mathbf{Z}_d .
- ▶ \mathbf{e} is an $n \times 1$ vector of residual error effects.

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-
- ▶ \mathbf{u}_w is a $t \times 1$ vector of random effects resulting from the LMM based wavelet transform.
 - ▶ These effects describe the non-smooth response of abundance as a function of retention time.
 - ▶ \mathbf{Z}_t is an $n \times t$ design matrix, necessary to respect multiple abundance observations at each retention time.

The linear mixed model (LMM) based wavelet transform

$$\mathbf{y} = \mathbf{X}\boldsymbol{\tau} + \mathbf{Z}_d\mathbf{u}_d + \mathbf{Z}_t\mathbf{u}_w + \mathbf{e}$$

- ▶ Random and residual error effects are assumed to follow a normal distribution with a zero mean vector and variance-covariance matrix:

$$\text{var} \left(\begin{bmatrix} \mathbf{u}_d \\ \mathbf{u}_w \\ \mathbf{e} \end{bmatrix} \right) = \begin{bmatrix} \mathbf{G}_d & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{G}_w & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \mathbf{R} \end{bmatrix}.$$

- ▶ Form of \mathbf{u}_w and \mathbf{G}_w is our focus and will be investigated further.

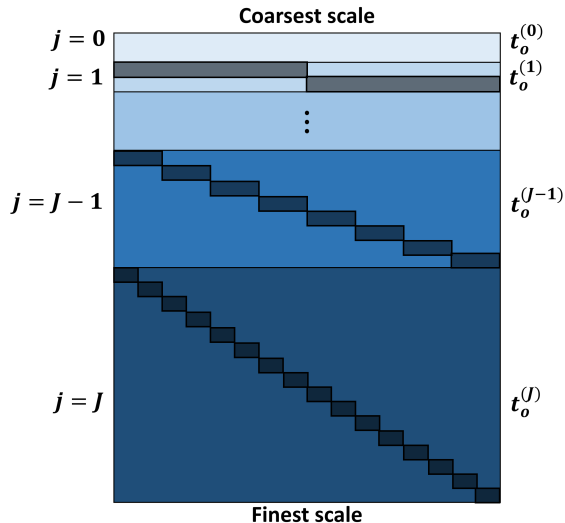
The wavelet transform

- ▶ *What is it?*
 - ▶ Mathematical construct proven to model non-smooth data, containing discontinuities.
- ▶ *How can I use it?*
 - ▶ Classical wavelets:
 - ▶ Built on framework of multiresolution analysis - relies on the Fourier transform.
 - ▶ Only applicable where observations are equidistant and dyadic ($\log_2(n)$ is integer) in number.
 - ▶ Second generation wavelets:
 - ▶ Implemented via 'lifting scheme' - retains multiscale properties of the classical transform.
 - ▶ Can be applied to non-equidistant observations, of any number.
- ▶ *Has it been incorporated into the LMM framework before?*
 - ▶ Classical wavelets:
 - ▶ Yes - Morris & Carroll, (2006); Wand & Ormerod, (2011).
 - ▶ Second generation wavelets:
 - ▶ Not until now!

The second generation wavelet transform

Wavelet scales

- ▶ Wavelet transform provides representation of data/effects at a series of **scales**.
- ▶ $J = \lceil \log_2(t) \rceil$ corresponds to the number of scales in the wavelet transform.
- ▶ $t_o^{(j)}$ is the number of wavelet functions/coefficients at each scale j .
- ▶ As j increases, $t_o^{(j)}$ increases, but support of wavelet functions decreases.
- ▶ This formulation allows for representation of non-smooth trends, as influence of spikes limited in terms of scale and location (Nason, 2008).
- ▶ Wavelet transform can be implemented through wavelet basis matrix, \mathbf{W}^{-1} .

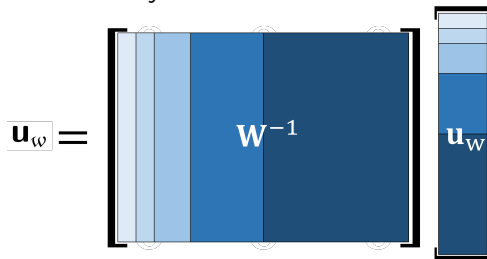


The second generation wavelet transform

Form of \mathbf{u}_w

$$\mathbf{u}_w = \mathbf{W}^{-1} \mathbf{u}_w$$

- ▶ $\mathbf{W}^{-1} = \begin{bmatrix} \phi^{(0)} & \Psi^{(0)} & \Psi^{(1)} & \dots & \Psi^{(J-1)} \end{bmatrix}$ is the $t \times t$ wavelet basis matrix.
 - ▶ $\phi^{(0)}$ and $\Psi^{(j)}$ are $t \times t_o^{(j)}$ matrices containing the values of the wavelet scaling function, $\phi^{(0)}(x)$, and wavelet functions, $\psi^{(j)}(x)$, at scale j .
- ▶ $\mathbf{u}_w = \begin{bmatrix} \varphi & \omega^{(0)\top} & \omega^{(1)\top} & \dots & \omega^{(J-1)\top} \end{bmatrix}^\top$ is the $t \times 1$ vector of wavelet coefficients.
 - ▶ φ and $\omega^{(j)}$ are $t_o^{(j)} \times 1$ vectors of coefficients associated with the wavelet scaling function and wavelet functions at scale j .





The second generation wavelet transform

Form of \mathbf{G}_w

$$\mathbf{u}_w = \mathbf{W}^{-1} \mathbf{u}_w$$

Two options for $\text{var}(\mathbf{u}_w)$:

1. Simple wavelet transform:

- ▶ Simple variance component controls extent of 'non-smoothness'.
- ▶ $\mathbf{u}_w \sim N(\mathbf{0}, \sigma_w^2 \mathbf{I}_t)$
- ▶ $\mathbf{G}_w = \sigma_w^2 \mathbf{W}^{-1} \mathbf{W}^{-1\top}$



The second generation wavelet transform

Form of \mathbf{G}_w

$$\mathbf{u}_w = \mathbf{W}^{-1} \mathbf{u}_w$$

Two options for $\text{var}(\mathbf{u}_w)$:

2 Partitioned wavelet transform:

- Uses wavelet scale structure implicit in wavelet functions, allowing for heterogeneous wavelet variance at each wavelet scale:

$$\text{var}(\mathbf{u}_w) = \text{var} \left(\begin{bmatrix} \varphi \\ \omega^{(0)} \\ \omega^{(1)} \\ \vdots \\ \omega^{(J-1)} \end{bmatrix} \right) = \begin{bmatrix} \sigma_\varphi^2 & \mathbf{0} & \mathbf{0} & \dots & \mathbf{0} \\ \mathbf{0} & \sigma_{\omega^{(0)}}^2 \mathbf{I}_{t_o^{(0)}} & \mathbf{0} & \dots & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \sigma_{\omega^{(1)}}^2 \mathbf{I}_{t_o^{(1)}} & \dots & \mathbf{0} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \mathbf{0} & \mathbf{0} & \mathbf{0} & \dots & \sigma_{\omega^{(J-1)}}^2 \mathbf{I}_{t_o^{(J-1)}} \end{bmatrix}$$

- $\mathbf{G}_w = \sigma_\varphi^2 \phi^{(0)} \phi^{(0)\top} + \sum_{j=0}^{J-1} \sigma_{\omega^{(j)}}^2 \boldsymbol{\psi}^{(j)} \boldsymbol{\psi}^{(j)\top}$

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Implementing LMM based wavelet transform

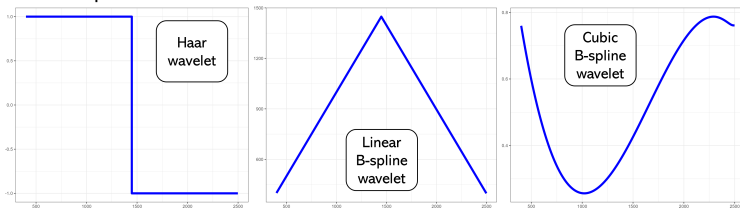
Software solutions

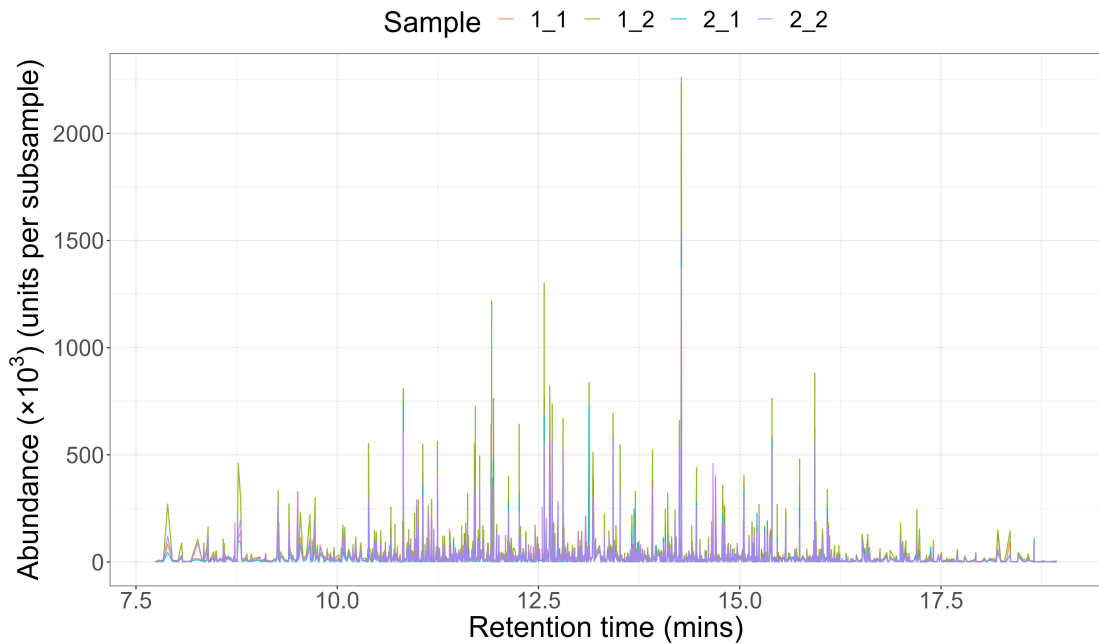
► LMM implementation:

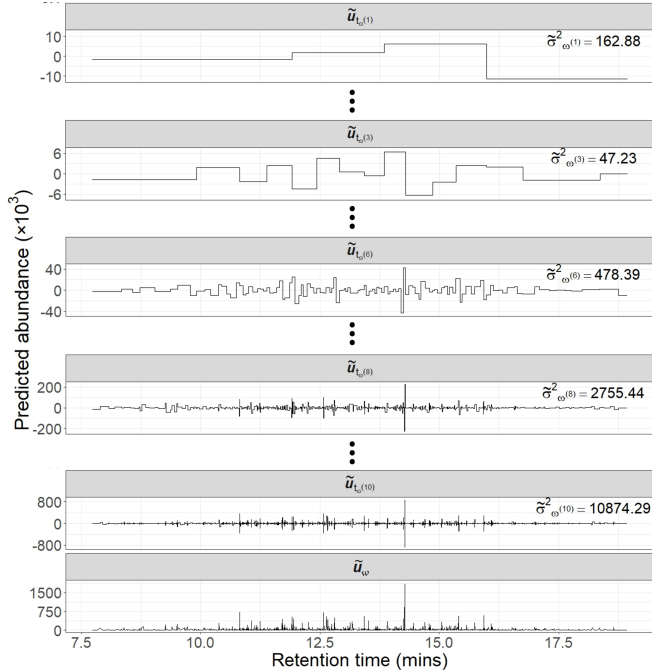
- Implementable in any LMM software or package that enables the user to specify their own design matrix, or matrix of basis functions.
- Successfully implemented in R using:
 - `asreml` (The VSNi Team, 2023),
 - `lmmSolver` (Boer, 2023),
 - `sommer` (Covarrubias-Pazaran, 2016).

► Second generation wavelet basis construction

- I developed an R package to construct the B-spline wavelet basis matrix (Jansen 2016, 2022).
- Package calculates \mathbf{W}^{-1} for:
 - Haar wavelet
 - Linear B-spline wavelet
 - Cubic B-spline wavelet







Wavelet variances

j	$\tilde{\sigma}_{\omega(j)}^2$
0	0.00
1	162.88
2	71.11
3	47.23
4	248.52
5	486.20
6	478.39
7	1454.10
8	2755.44
9	5651.23
10	10874.29

Future work

- ▶ Explore contribution of different scales of the wavelet transform - are all scales necessary?
- ▶ Potential to explore two dimensional setting - tensor wavelet transforms.
- ▶ Forthcoming methodology paper.

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