Routing Algorithms

- IP v6
- Routing algorithms
  - Link state
  - Distance Vector

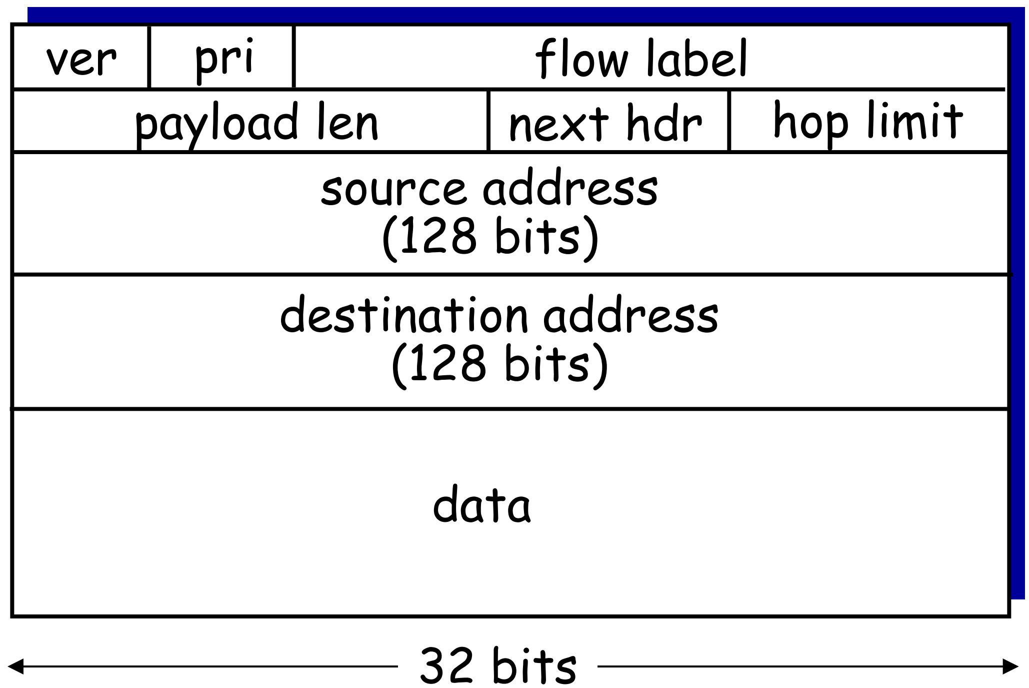
IPv6

- Initial motivation: 32-bit address space soon to be completely allocated.
- Additional motivation:
  - header format helps speed processing/forwarding
  - header changes to facilitate QoS

  IPv6 datagram format:
  - fixed-length 40 byte header
  - no fragmentation allowed

IPv6 Header (Cont)

Priority: identify priority among datagrams in flow
Flow Label: identify datagrams in same "flow."
(concept of"flow" not well defined).
Next header: identify upper layer protocol for data



Other Changes from IPv4

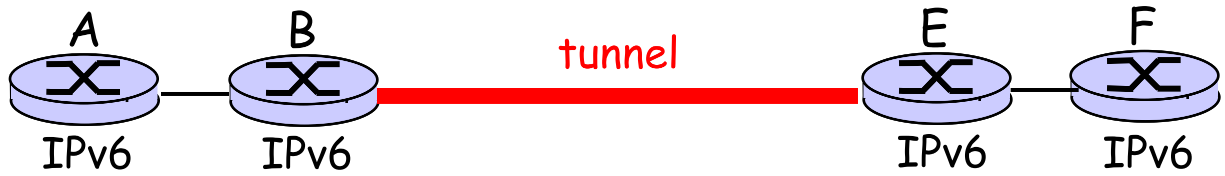
- *Checksum:* removed entirely to reduce processing time at each hop
- *Options:* allowed, but outside of header, indicated by "Next Header" field
- *ICMPv6:* new version of ICMP
  - additional message types, e.g. "Packet Too Big"
  - multicast group management functions

Transition From IPv4 To IPv6

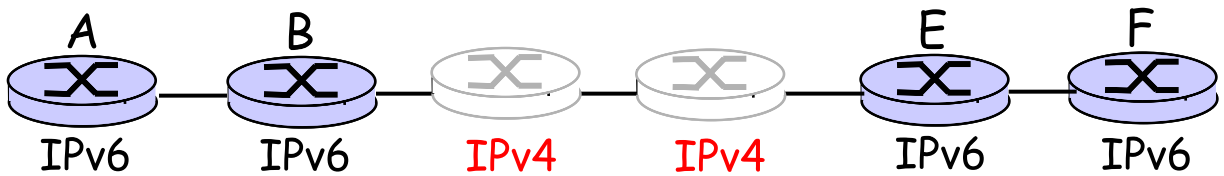
- Not all routers can be upgraded simultaneous
  - no "flag days"
  - How will the network operate with mixed IPv4 and IPv6 routers?
- *Tunneling:* IPv6 carried as payload in IPv4 datagram among IPv4 routers

Tunneling

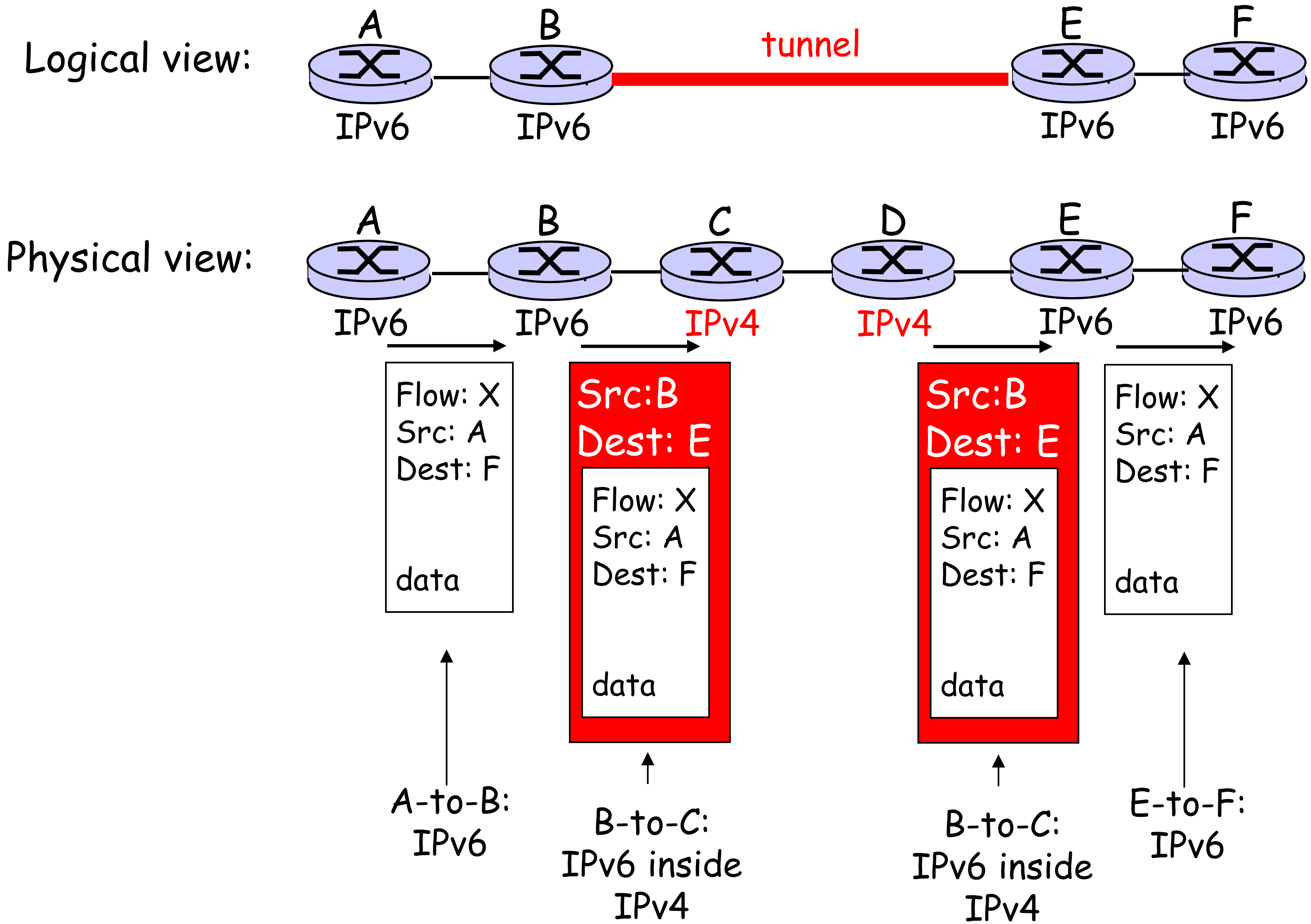
Logical view:



Physical view:



Tunneling

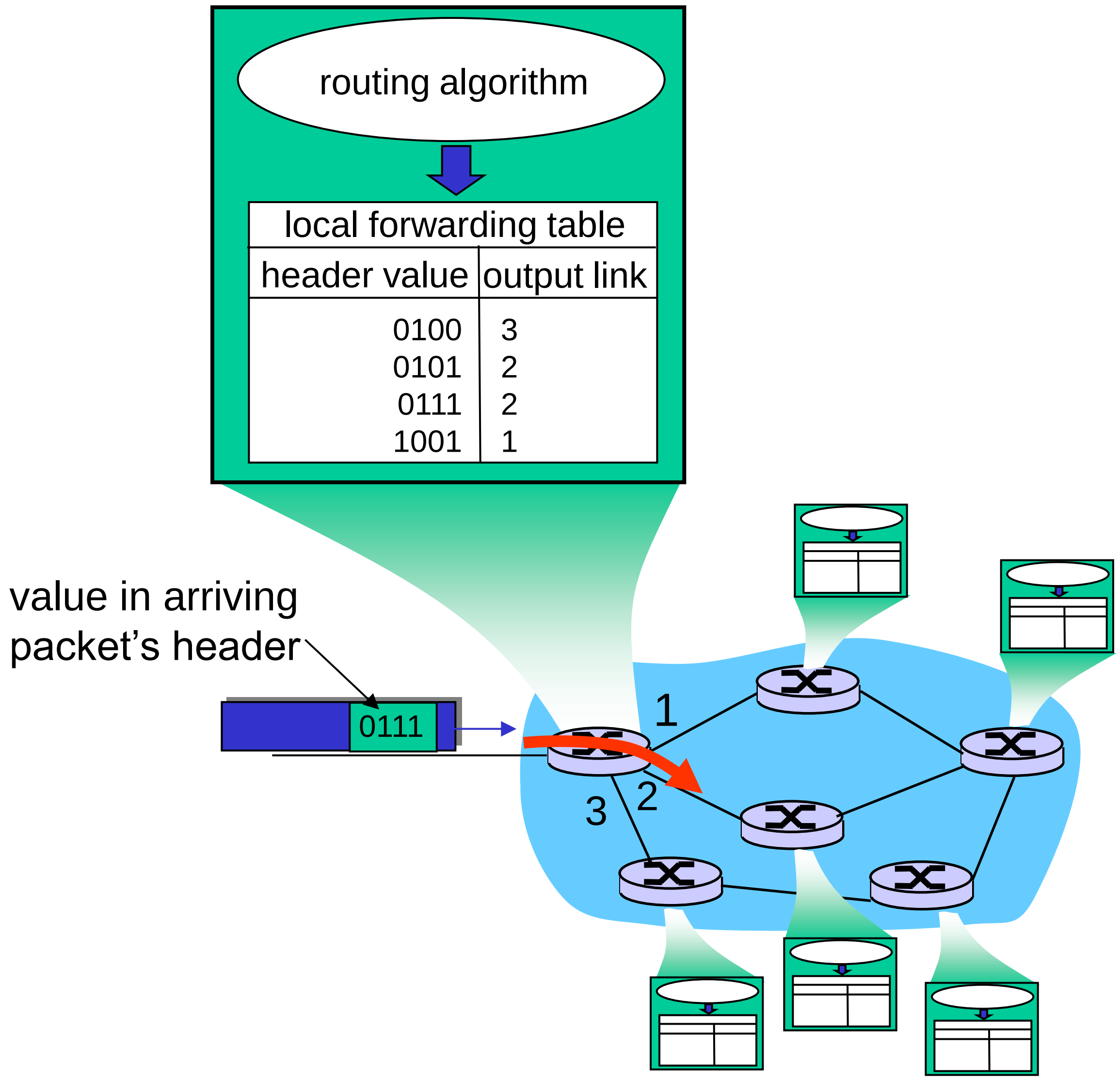

Logical view:
A
B
tunnel
E
F
IPv6
IPv6
IPv6
IPv6
Physical view:
A
B
C
D
E
F
IPv6
IPv6
IPv4
IPv4
IPv6
IPv6
Flow: X
Src: A
Dest: F
data
Src:B
Dest: E
Flow: X
Src: A
Dest: F
data
Src:B
Dest: E
Flow: X
Src: A
Dest: F
data
Flow: X
Src: A
Dest: F
data
A-to-B:
IPv6
B-to-C:
IPv6 inside
IPv4
B-to-C:
IPv6 inside
IPv4
E-to-F:
IPv6

Network Layer

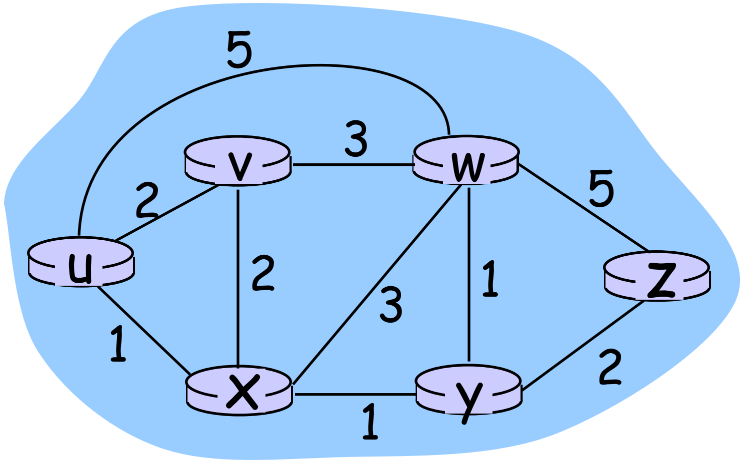
Routing algorithms

- Link state
- Distance Vector

Interplay between routing, forwarding



Graph abstraction



Graph: G = (N,E)

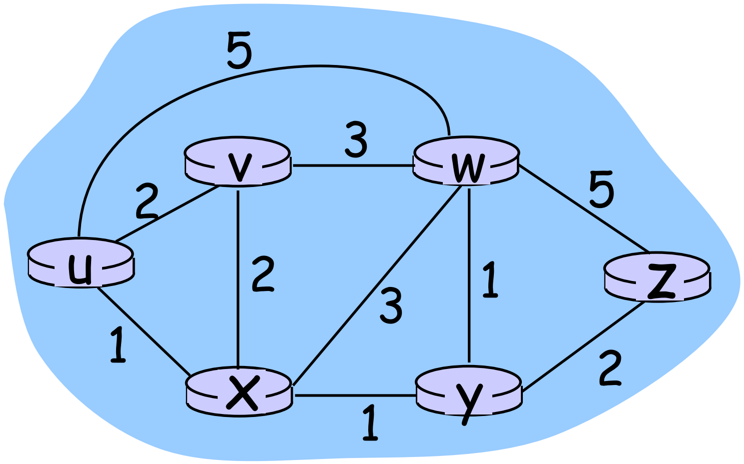
N = set of routers = { u, v, w, x, y, z }

E = set of links ={ (u,v), (u,x), (v,x), (v,w), (x,w), (x,y), (w,y), (w,z), (y,z) }

Remark: Graph abstraction is useful in other network contexts

Example: P2P, where N is set of peers and E is set of TCP connections

Graph abstraction: costs



- $c(x,x')$ = cost of link (x,x')

  - e.g., $c(w,z) = 5$

- cost could always be 1, or inversely related to bandwidth, or inversely related to congestion

Cost of path $(x_1, x_2, x_3, \ldots, x_p) = c(x_1,x_2) + c(x_2,x_3) + \ldots + c(x_{p-1},x_p)$

Question: What's the least-cost path between u and z ?

Routing algorithm: algorithm that finds least-cost path

Routing Algorithm classification

Global or decentralized information?

Global:

- all routers have complete topology, link cost info
- "link state" algorithms

Decentralized:

- router knows physically-connected neighbors, link costs to neighbors
- iterative process of computation, exchange of info with neighbors
- "distance vector" algorithms

Static or dynamic?

Static:

- routes change slowly over time

Dynamic:

- routes change more quickly
  - periodic update
  - in response to link cost changes

Network Layer

Routing algorithms

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A Link-State Routing Algorithm

Dijkstra's algorithm

- net topology, link costs known to all nodes
  - accomplished via "link state broadcast"
  - all nodes have same info
- computes least cost paths from one node ('source") to all other nodes
  - gives *forwarding table* for that node
- iterative: after k iterations, know least cost path to k dest.'s

Notation:

- c(x,y): link cost from node x to y; = ∞ if not direct neighbors
- D(v): current value of cost of path from source to dest. v
- p(v): predecessor node along path from source to v
- N': set of nodes whose least cost path definitively known

Dijsktra's Algorithm

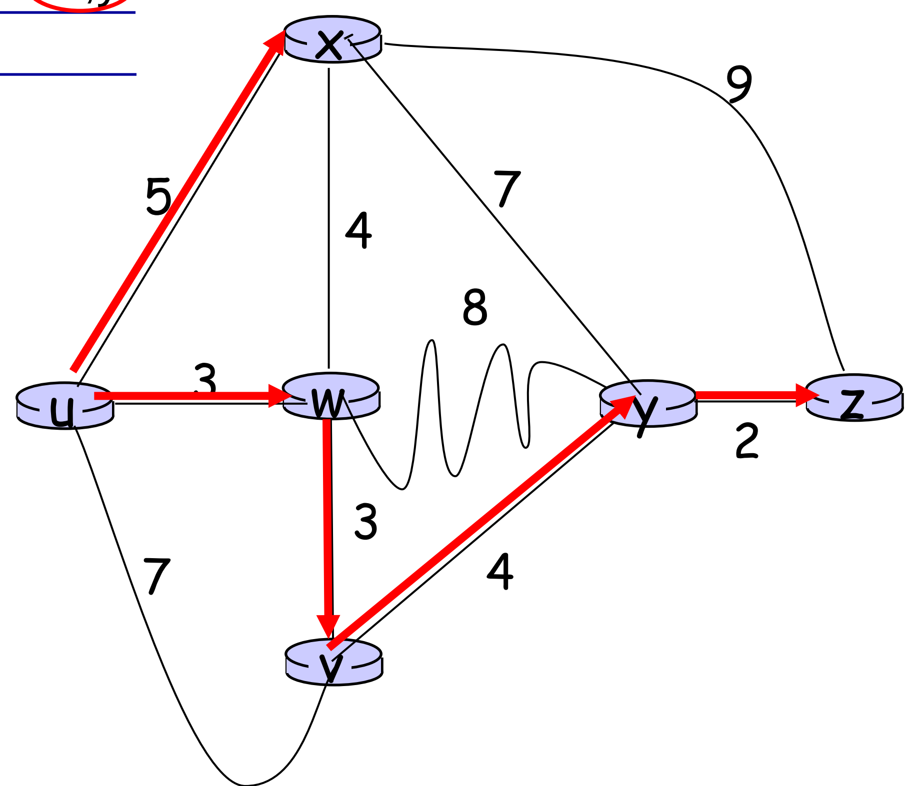
```
Initialization:
  N' = {u}
  for all nodes v
    if v adjacent to u
        then D(v) = c(u,v)
    else D(v) = ∞

Loop
   find w not in N' such that D(w) is a minimum
   add w to N'
   update D(v) for all v adjacent to w and not in N' :
       D(v) = min( D(v), D(w) + c(w,v) )
   /* new cost to v is either old cost to v or known
    shortest path cost to w plus cost from w to v */
until all nodes in N'
```

Dijkstra's algorithm: example

Step	N'	D(v) p(v)	D(w) p(w)	D(x) p(x)	D(y) p(y)	D(z) p(z)
0	u	7,u	3,u	5,u	∞	∞
1	uw	6,w		5,u	11,w	∞
2	uwx	6,w			11,w	14,x
3	uwxv				10,v	14,x
4	uwxvy					12,y
5	uwxvyz					

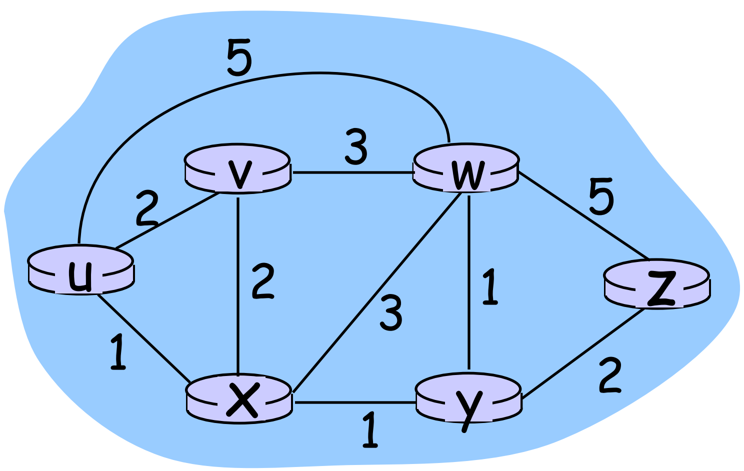
Notes:

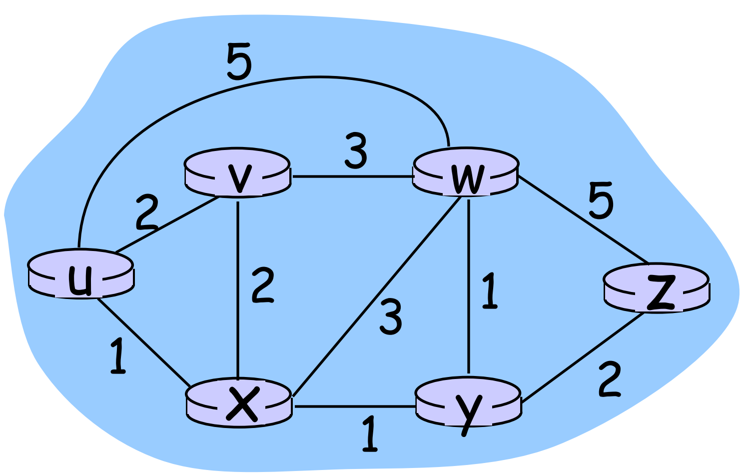
- construct shortest path tree by tracing predecessor nodes
- ties can exist (can be broken arbitrarily)



Dijkstra's algorithm: another example

Step	N'	D(v),p(v)	D(w),p(w)	D(x),p(x)	D(y),p(y)	D(z),p(z)
0	u	2,u	5,u	1,u	∞	∞
1	ux	2,u	4,x		2,x	∞
2	uxy	2,u	3,y			4,y
3	uxyv		3,y			4,y
4	uxyvw					4,y
5	uxyvwz					

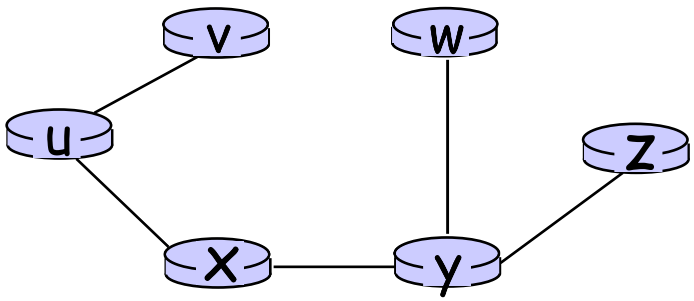




5
3
2
5
u
v
w
z
2
1
3
1
x
y
2
1

Dijkstra's algorithm: example (2)

Resulting shortest-path tree from u:



Resulting forwarding table in u:

destination	link
v	(u,v)
x	(u,x)
y	(u,x)
w	(u,x)
z	(u,x)

Network Layer

Routing algorithms

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- Distance Vector

Distance Vector Algorithm

Bellman-Ford Equation (dynamic programming)

Define

$d_x(y)$:= cost of least-cost path from x to y

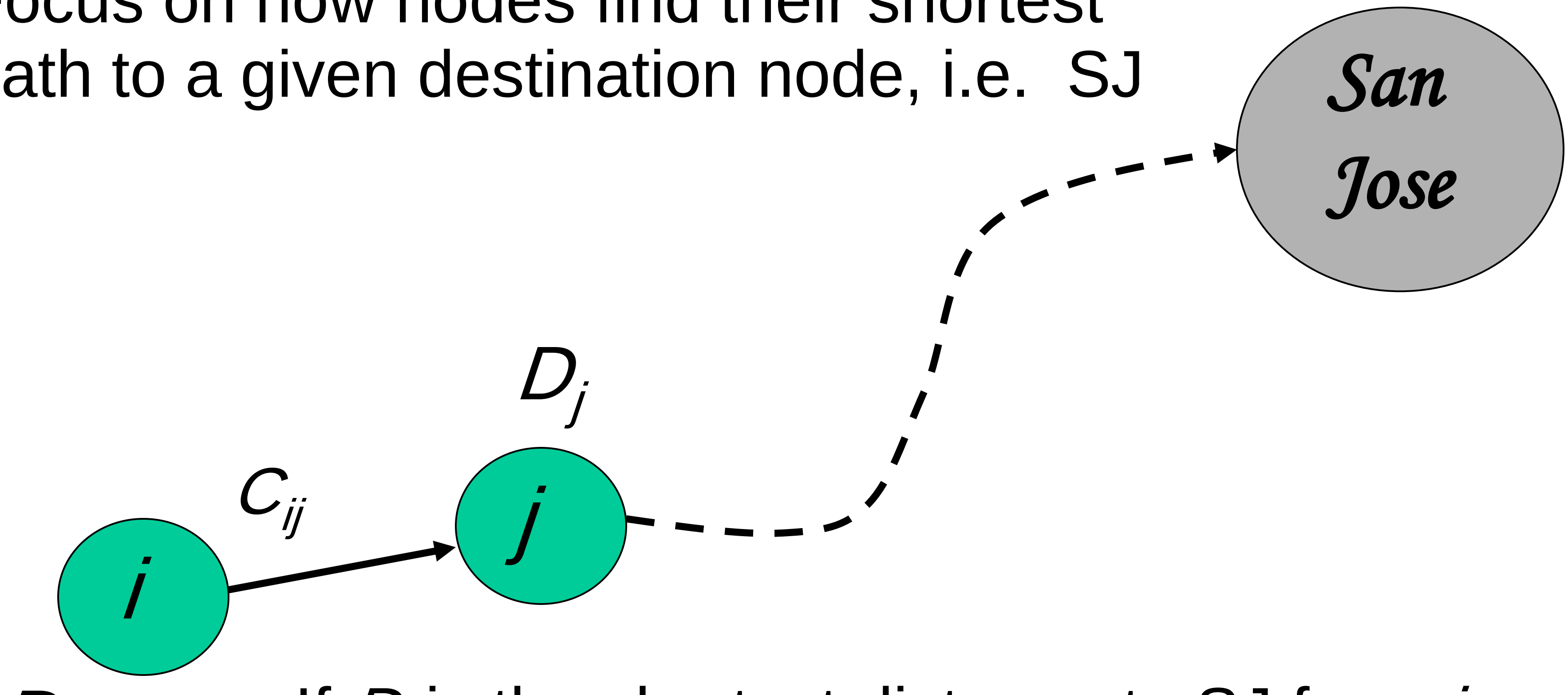
Then

$$\boxed{d_x(y) = \min_v \{c(x,v) + d_v(y)\}}$$

where min is taken over all neighbors v of x

Shortest Path to SJ

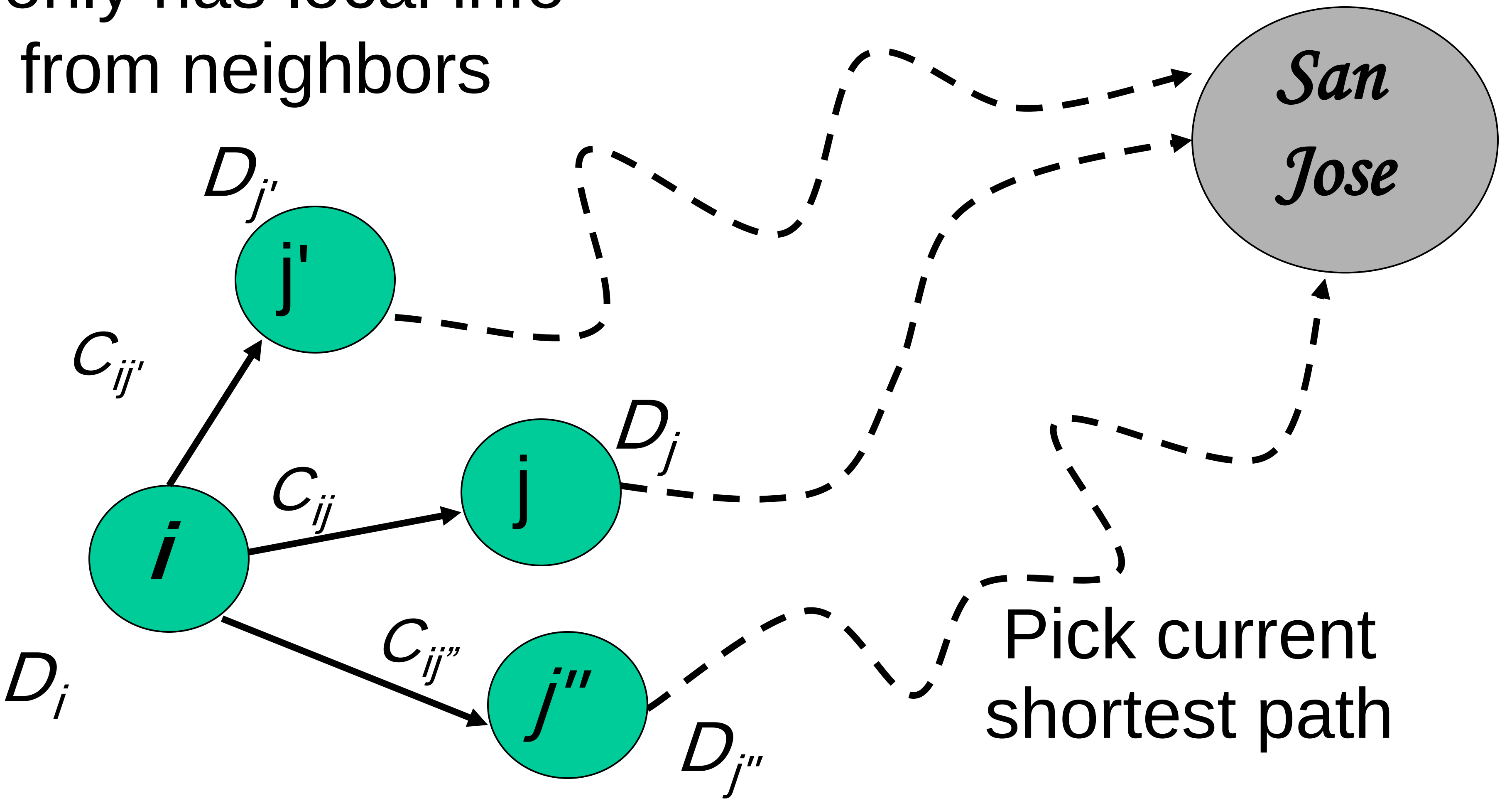
Focus on how nodes find their shortest path to a given destination node, i.e. SJ



If D_i is the shortest distance to SJ from i and if j is a neighbor on the shortest path, then $D_i = C_{ij} + D_j$

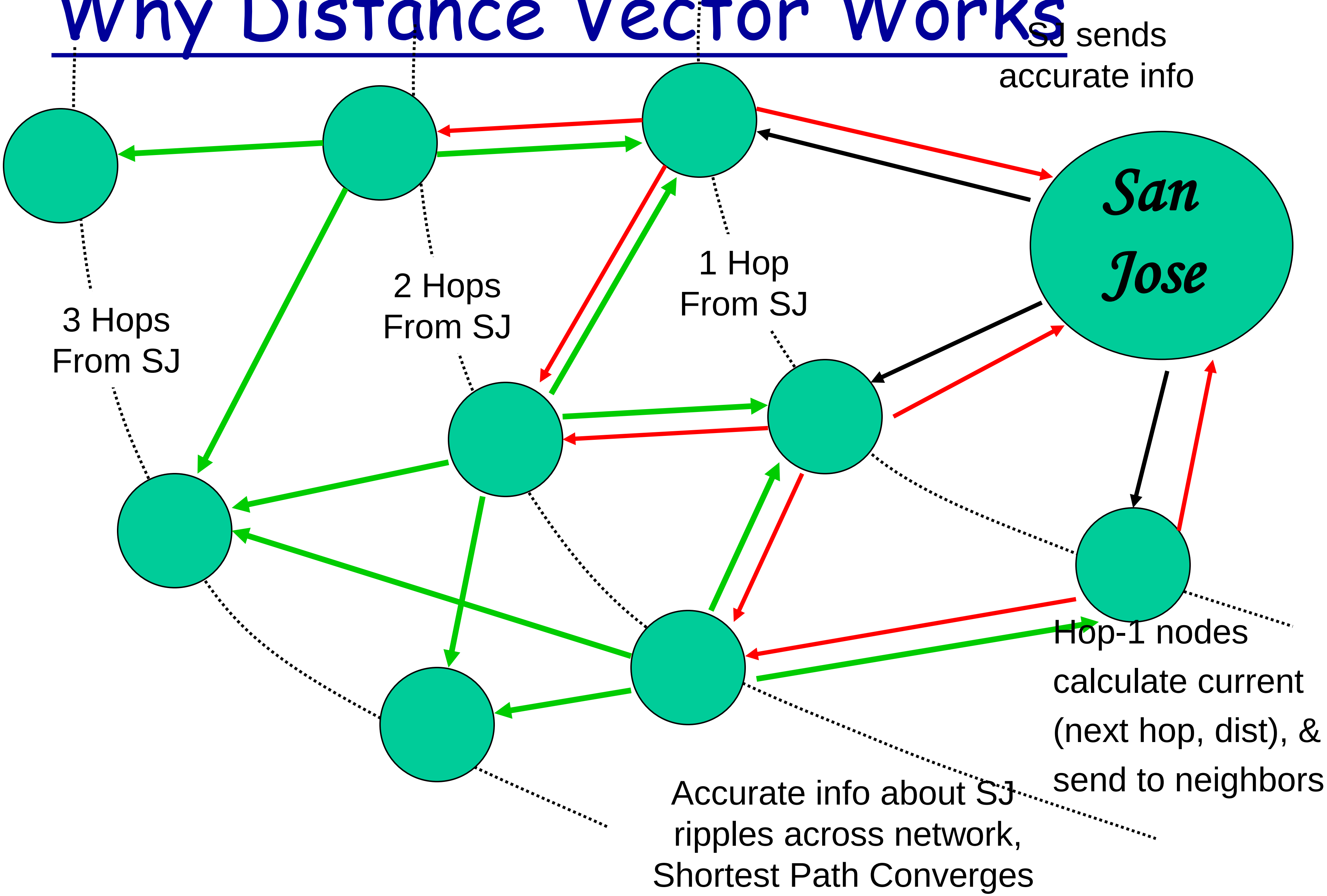
But we don't know the shortest paths

i only has local info from neighbors

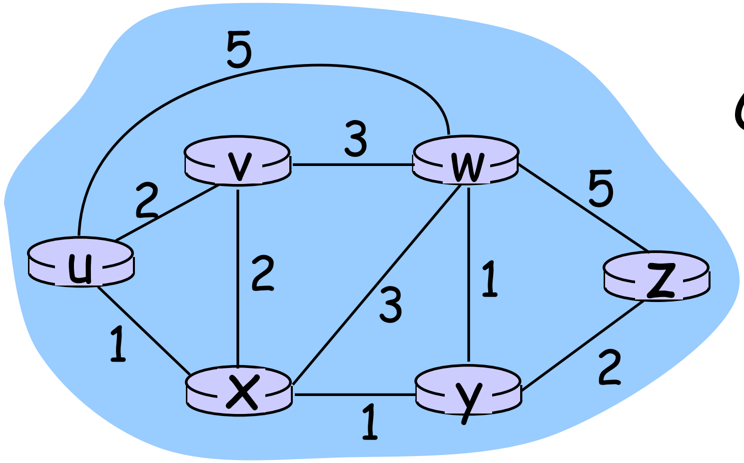


Pick current shortest path

Why Distance Vector Works



Bellman-Ford example



Clearly, $d_v(z) = 5$, $d_x(z) = 3$, $d_w(z) = 3$

B-F equation says:

$$
\begin{aligned}
d_u(z) &= \min \{ c(u,v) + d_v(z), \\
&\qquad c(u,x) + d_x(z), \\
&\qquad c(u,w) + d_w(z) \} \\
&= \min \{2 + 5, \\
&\qquad 1 + 3, \\
&\qquad 5 + 3\} = 4
\end{aligned}
$$

Node that achieves minimum is next hop in shortest path ➔ forwarding table

Distance Vector Algorithm

- $D_x(y)$ = estimate of least cost from x to y
  - x maintains distance vector $\mathbf{D}_x = [D_x(y): y \in N]$
- node x:
  - knows cost to each neighbor v: $c(x,v)$
  - maintains its neighbors' distance vectors. For each neighbor v, x maintains $\mathbf{D}_v = [D_v(y): y \in N]$

Distance vector algorithm (4)

Basic idea:

- from time-to-time, each node sends its own distance vector estimate to neighbors
- when x receives new DV estimate from neighbor, it updates its own DV using B-F equation:

$$D_x(y) \leftarrow \min_v\{c(x,v) + D_v(y)\} \quad \text{for each node } y \in N$$

- under minor, natural conditions, the estimate $D_x(y)$ *converge to the actual least cost* $d_x(y)$

Distance Vector Algorithm (5)

Iterative, asynchronous: each local iteration caused by:

- local link cost change
- DV update message from neighbor

Distributed:

- each node notifies neighbors *only* when its DV changes
  - neighbors then notify their neighbors if necessary

Each node:

wait for (change in local link cost or msg from neighbor)

recompute estimates

if DV to any dest has changed, *notify* neighbors

Distance Vector Algorithm

- $c(x,v)$ = cost for direct link from x to v
  - Node x maintains costs of direct links $c(x,v)$
- $D_x(y)$ = estimate of least cost from x to y
  - Node x maintains distance vector $\mathbf{D}_x = [D_x(y): y \in N]$
- Node x maintains its neighbors' distance vectors
  - For each neighbor v, x maintains $\mathbf{D}_v = [D_v(y): y \in N]$
- Each node v periodically sends D_v to its neighbors
  - And neighbors update their own distance vectors
  - $D_x(y) \leftarrow \min_v\{c(x,v) + D_v(y)\}$ for each node $y \in N$
- Over time, the distance vector D_x converges

```
Initialization:
   for all destinations y in N:
      Dx(y) = c(x,y)    /* if y is not a neighbor then c(x,y) = ∞ */
   for each neighbor w
      Dw(y) = ? for all destinations y in N
   for each neighbor w
      send distance vector Dx = [Dx(y): y in N] to w

loop
   wait (until I see a link cost change to some neighbor w or
         until I receive a distance vector from some neighbor w)

   for each y in N:
      Dx(y) = minv{c(x,v) + Dv(y)}

   if Dx(y) changed for any destination y
      send distance vector Dx = [Dx(y): y in N] to all neighbors

forever
```

$$D_x(y) = \min\{c(x,y) + D_y(y),\ c(x,z) + D_z(y)\}$$
$$= \min\{2+0\ ,\ 7+1\} = 2$$

$$D_x(z) = \min\{c(x,y) + D_y(z),\ c(x,z) + D_z(z)\}$$
$$= \min\{2+1\ ,\ 7+0\} = 3$$

node x table

from \ cost to	x	y	z
x	0	2	7
y	∞	∞	∞
z	∞	∞	∞

from \ cost to	x	y	z
x	0	2	3
y	2	0	1
z	7	1	0

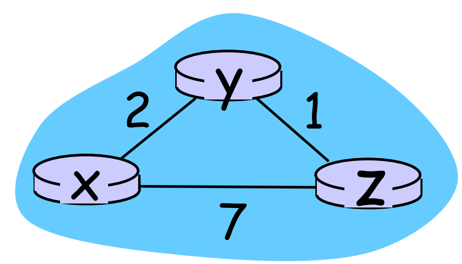
node y table

from \ cost to	x	y	z
x	∞	∞	∞
y	2	0	1
z	∞	∞	∞

node z table

from \ cost to	x	y	z
x	∞	∞	∞
y	∞	∞	∞
z	7	1	0

time



$$D_x(y) = \min\{c(x,y) + D_y(y),\ c(x,z) + D_z(y)\} = \min\{2+0\ ,\ 7+1\} = 2$$

$$D_x(z) = \min\{c(x,y) + D_y(z),\ c(x,z) + D_z(z)\} = \min\{2+1\ ,\ 7+0\} = 3$$

node x table

from \ cost to	x	y	z
x	0	2	7
y	∞	∞	∞
z	∞	∞	∞

from \ cost to	x	y	z
x	0	2	3
y	2	0	1
z	7	1	0

from \ cost to	x	y	z
x	0	2	3
y	2	0	1
z	3	1	0

node y table

from \ cost to	x	y	z
x	∞	∞	∞
y	2	0	1
z	∞	∞	∞

from \ cost to	x	y	z
x	0	2	7
y	2	0	1
z	7	1	0

from \ cost to	x	y	z
x	0	2	3
y	2	0	1
z	3	1	0

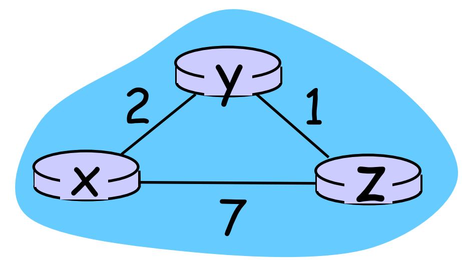
node z table

from \ cost to	x	y	z
x	∞	∞	∞
y	∞	∞	∞
z	7	1	0

from \ cost to	x	y	z
x	0	2	7
y	2	0	1
z	3	1	0

from \ cost to	x	y	z
x	0	2	3
y	2	0	1
z	3	1	0

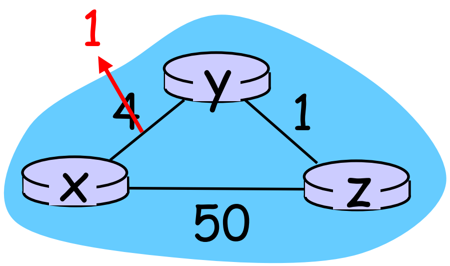
time



Distance Vector: link cost changes

Link cost changes:

- node detects local link cost change
- updates routing info, recalculates distance vector
- if DV changes, notify neighbors



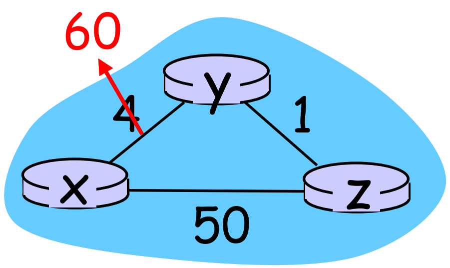
"good news travels fast"

t_0 : *y* detects link-cost change, updates its DV, informs its neighbors.

t_1 : *z* receives update from *y*, updates its table, computes new least cost to *x* , sends its neighbors its DV.

t_2 : *y* receives *z*'s update, updates its distance table. *y*'s least costs do *not* change, so *y* does *not* send a message to *z*.

Distance Vector: link cost changes



Link cost changes:

- good news travels fast
- bad news travels slow - "count to infinity" problem!
- 44 iterations before algorithm stabilizes.

Poisoned reverse:

- If Z routes through Y to get to X :
  - Z tells Y its (Z's) distance to X is infinite (so Y won't route to X via Z)
- will this completely solve count to infinity problem?

Routing Protocol

Hierarchical routing

our routing study thus far - idealization
- all routers identical
- network "flat"

… *not* true in practice

scale: with 600 million destinations:
- can't store all dest's in routing tables!
- routing table exchange would swamp links!

administrative autonomy
- internet = network of networks
- each network admin may want to control routing in its own network

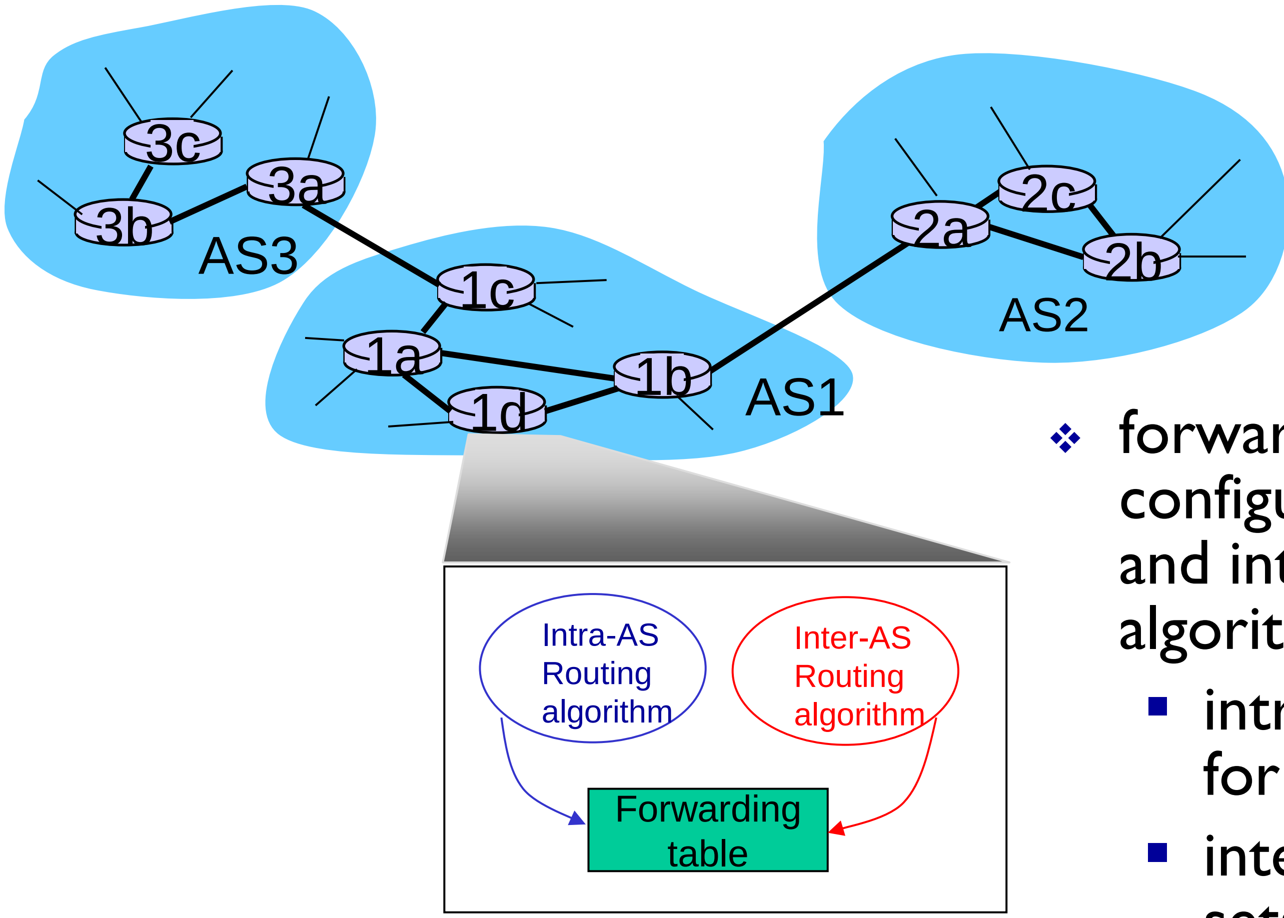
Hierarchical routing

- aggregate routers into regions, "autonomous systems" (AS)
- routers in same AS run same routing protocol
  - "intra-AS" routing protocol
  - routers in different AS can run different intra-AS routing protocol

gateway router:

- at "edge" of its own AS
- has link to router in another AS

Interconnected ASes



- forwarding table configured by both intra- and inter-AS routing algorithm
  - intra-AS sets entries for internal dests
  - inter-AS & intra-AS sets entries for external dests

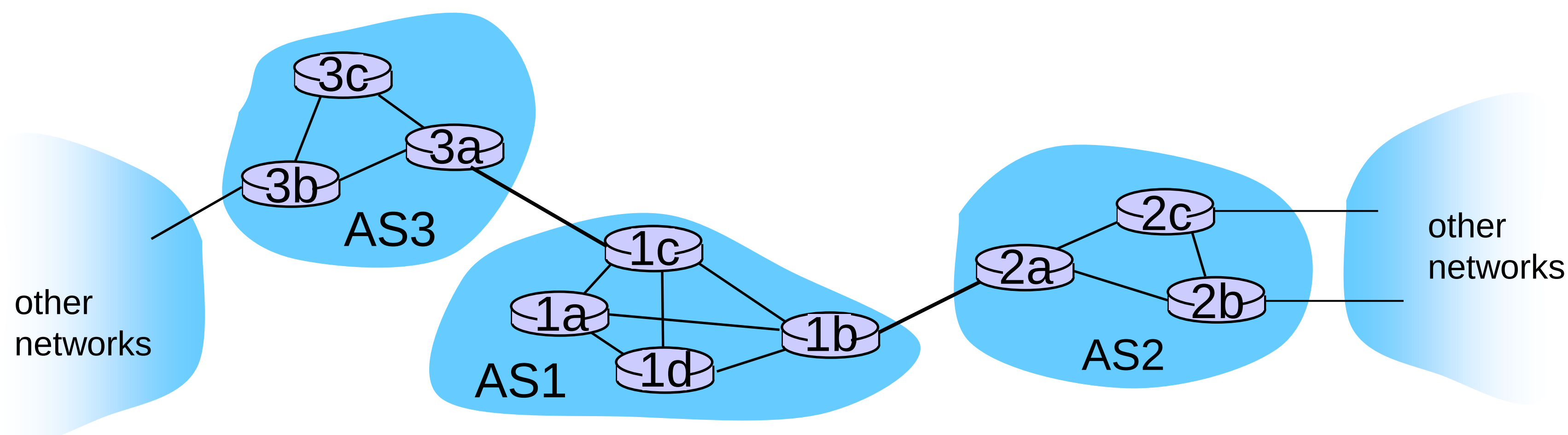
Inter-AS tasks

- suppose router in AS1 receives datagram destined outside of AS1:
  - router should forward packet to gateway router, but which one?

AS1 must:

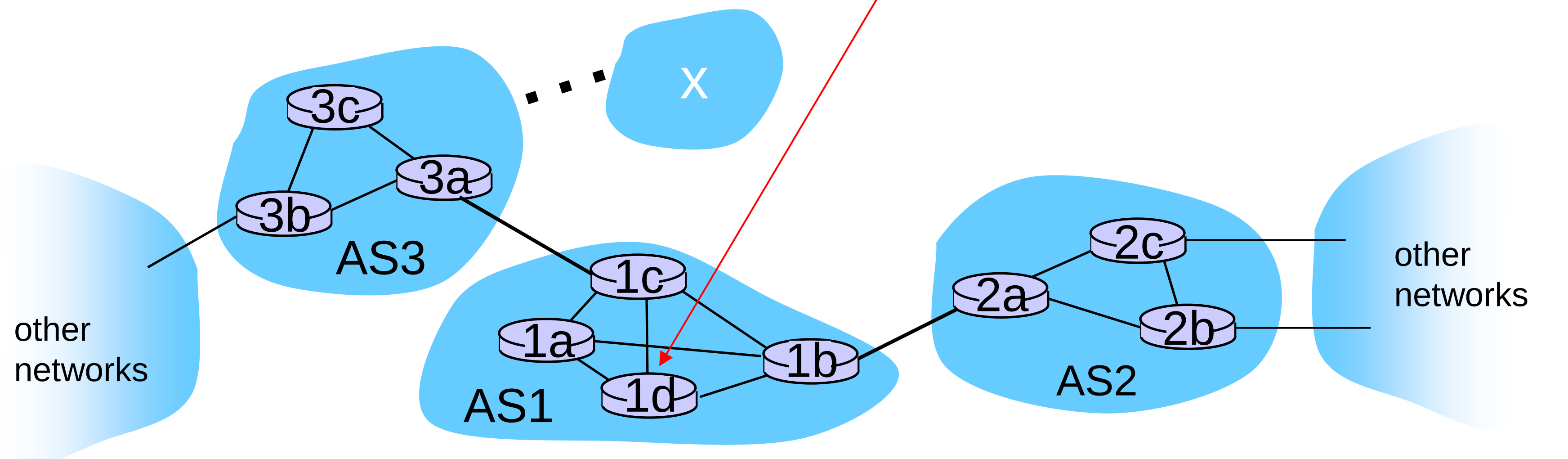
1. learn which dests are reachable through AS2, which through AS3
2. propagate this reachability info to all routers in AS1

job of inter-AS routing!



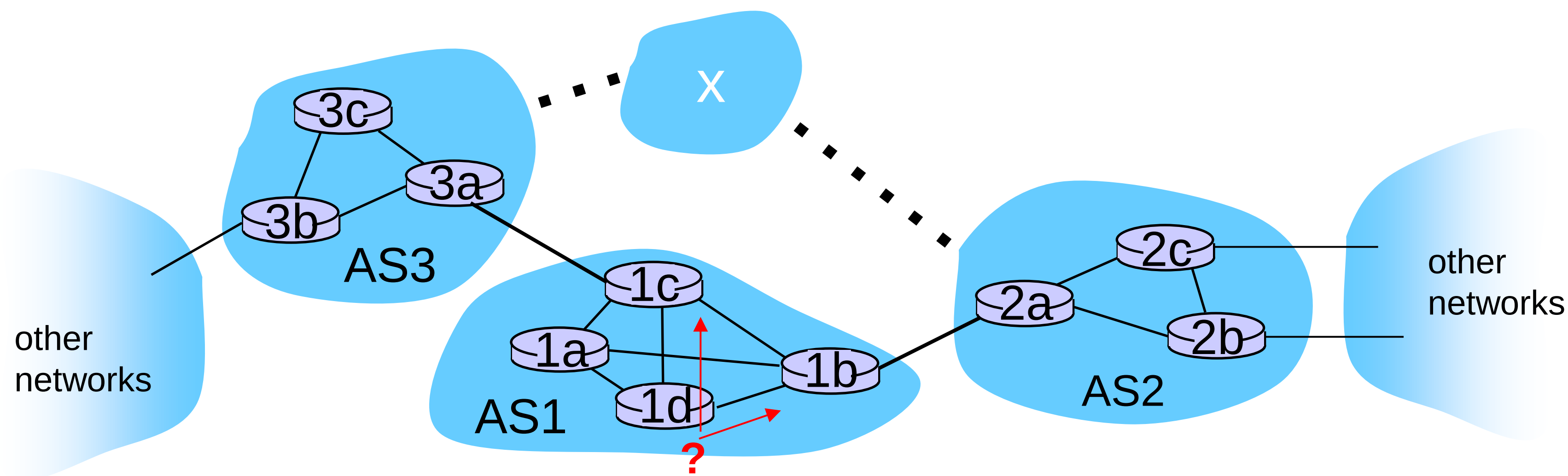
Example: setting forwarding table in router 1d

- suppose AS1 learns (via inter-AS protocol) that subnet *x* reachable via AS3 (gateway 1c), but not via AS2
  - inter-AS protocol propagates reachability info to all internal routers
- router 1d determines from intra-AS routing info that its interface *I* is on the least cost path to 1c
  - installs forwarding table entry *(x,I)*



Example: choosing among multiple ASes

- now suppose AS1 learns from inter-AS protocol that subnet *x* is reachable from AS3 *and* from AS2.
- to configure forwarding table, router 1d must determine which gateway it should forward packets towards for dest x
  - this is also job of inter-AS routing protocol!

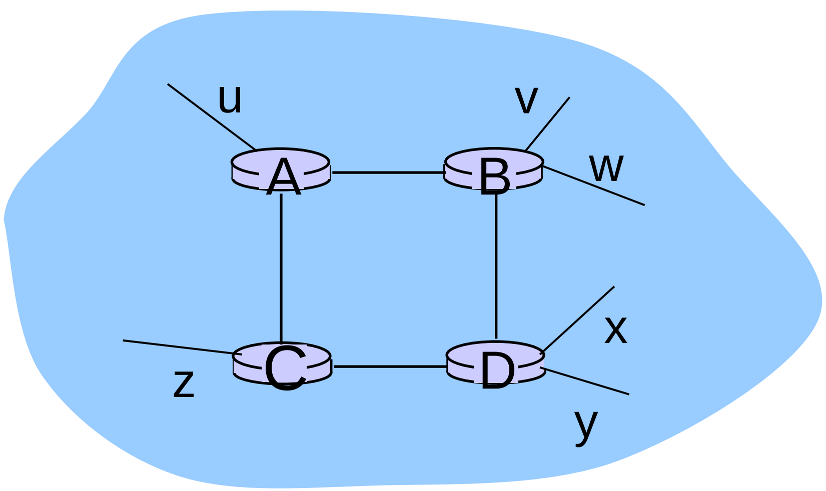


Intra-AS Routing

- also known as *interior gateway protocols (IGP)*
- most common intra-AS routing protocols:
  - RIP: Routing Information Protocol
  - OSPF: Open Shortest Path First
  - IGRP: Interior Gateway Routing Protocol (Cisco proprietary)

RIP (Routing Information Protocol)

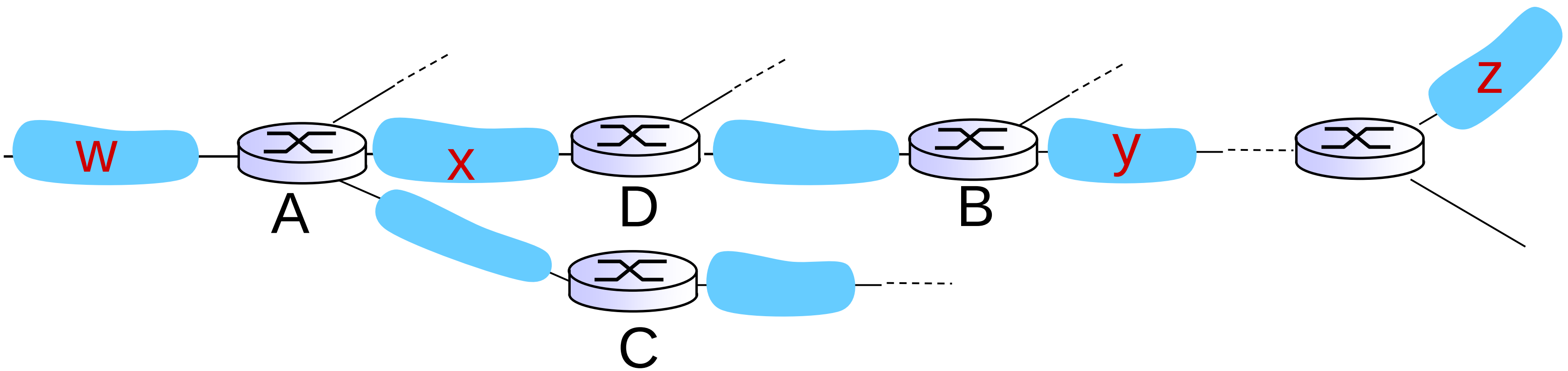
- included in BSD-UNIX distribution in 1982
- distance vector algorithm
  - distance metric: # hops (max = 15 hops), each link has cost 1
  - DVs exchanged with neighbors every 30 sec in response message (aka advertisement)
  - each advertisement: list of up to 25 destination *subnets* *(in IP addressing sense)*



from router A to destination *subnets:*

subnet	hops
u	1
v	2
w	2
x	3
y	3
z	2

RIP: example



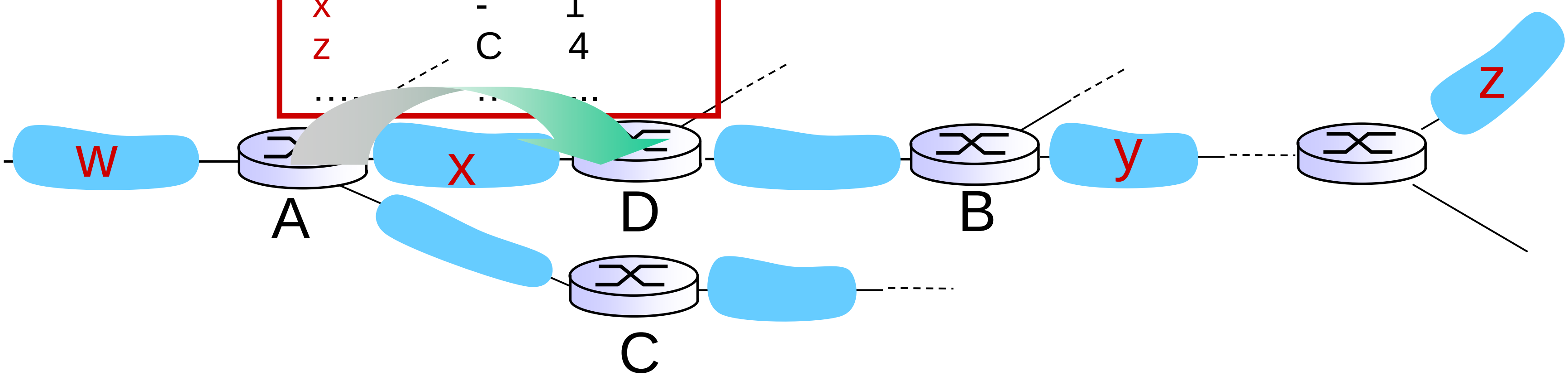
routing table in router D

destination subnet	next router	# hops to dest
w	A	2
y	B	2
z	B	7
x	--	1
….	….	….

RIP: example

A-to-D advertisement

dest	next	hops
w	-	1
x	-	1
z	C	4
….	…	...



routing table in router D

destination subnet	next router	# hops to dest
w	A	2
y	B	2
z	~~B~~ A	~~7~~ 5
x	--	1
….	….	....

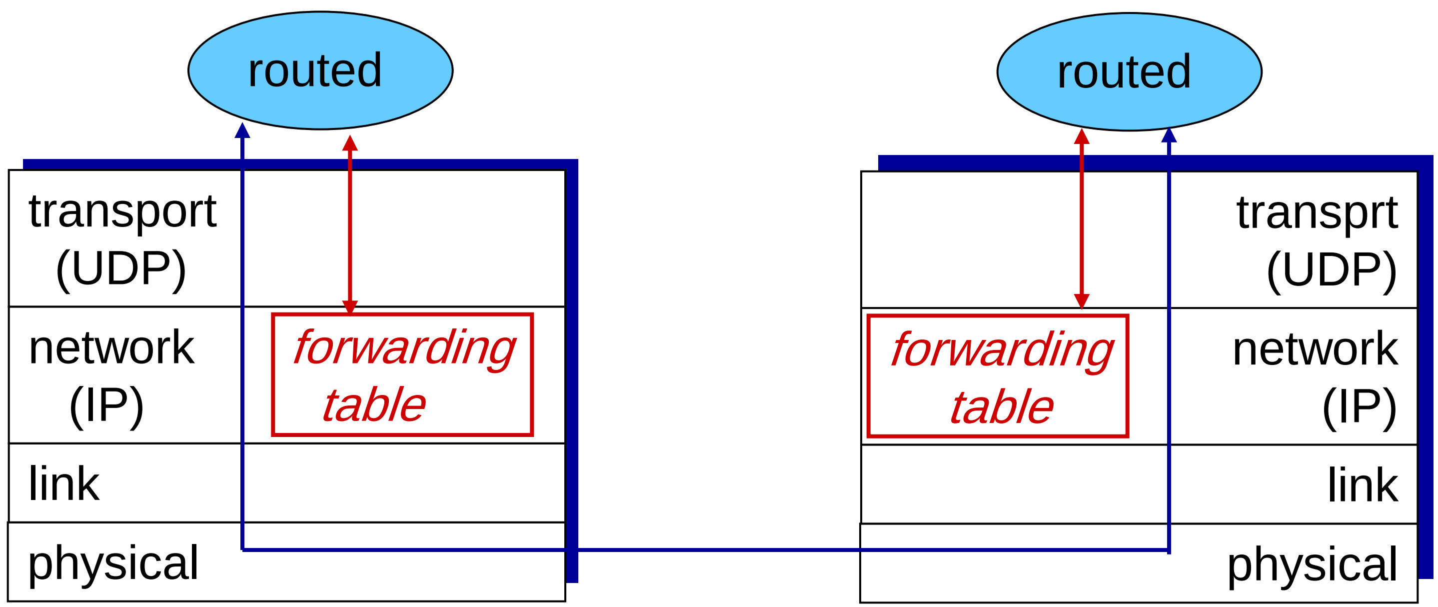
RIP: link failure, recovery

if no advertisement heard after 180 sec --> neighbor/link declared dead

- routes via neighbor invalidated
- new advertisements sent to neighbors
- neighbors in turn send out new advertisements (if tables changed)
- link failure info quickly (?) propagates to entire net
- *poison reverse* used to prevent ping-pong loops (infinite distance = 16 hops)

RIP table processing

- RIP routing tables managed by *application-level* process called route-d (daemon)
- advertisements sent in UDP packets, periodically repeated



OSPF (Open Shortest Path First)

- "open": publicly available
- uses link state algorithm
  - LS packet dissemination
  - topology map at each node
  - route computation using Dijkstra's algorithm
- OSPF advertisement carries one entry per neighbor
- advertisements flooded to *entire* AS
  - carried in OSPF messages directly over IP (rather than TCP or UDP
- *IS-IS routing* protocol: nearly identical to OSPF