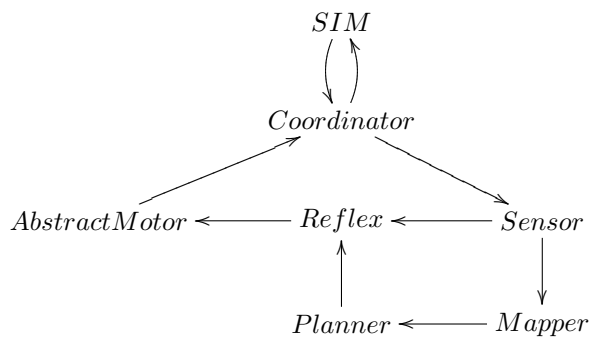


# Draft Workplan

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## 1 Specification



## 2 Planning

### 2.1 Milestones

This subsection will describe the milestones, and what deliverables we will provide.

#### 2.1.1 Milestone #1

A list of deliverables:

Drive around: We want the program to be able to direct the robot through the environment. We will not yet focus on the ability to follow lines or walls.

Avoid collision: The robot should be able to avoid collision with objects and walls. It will stop, turn a random corner, and drive on. This way it will cover most of the area without colliding.

Classes needed to be implemented for this:

- Coördinator
- Sensor
- Reflexes
- Motor

- 3    Functional Design**
- 4    Different Components and Test**
- 5    Deliverables**