## 1 Generative modelling

Learn  $p_{\text{model}} \approx p_{\text{data}}$ , sample from  $p_{\text{model}}$ .

- Explicit density:
- Approximate:
- \* Variational: VAE, Diffusion
- \* Markov Chain: Boltzmann machine
- Tractable:
- \* Autoregressive: FVSBN/NADE/MADE, Pixel(c/R)NN, WaveNet/TCN, Autor. Transf.,
- \* Normalizing Flows
- Implicit density:
- Direct: Generative Adversarial Networks
- MC: Generative Stochastic Networks

Autoencoder:  $X \rightarrow Z \rightarrow X$ ,  $g \circ f \approx \text{id}$ , f and g are NNs. Optimal linear autoencoder is PCA. Undercomplete: |Z| < |X|, else overcomplete. Overcomp. is for denoising, inpainting. Latent space should be continuious and interpolable. Autoencoder spaces are neither, so they are only good for reconstruction.

## 2 Variational AutoEncoder (VAE)

Sample *z* from prior  $p_{\theta}(z)$ , to decode use conditional  $p_{\theta}(x \mid z)$  defined by a NN.

 $D_{\text{KL}}(P||Q) := \int_{x} p(x) \log \frac{p(x)}{q(x)} dx$ : KL divergence, measure similarity of prob. distr.  $D_{\text{KL}}(P||Q) \neq D_{\text{KL}}(Q||P), D_{\text{KL}}(P||Q) \geq 0$ 

Likelihood  $p_{\theta}(x) = \int_{z} p_{\theta}(x \mid z) p_{\theta}(z) dz$  is hard to maximize, let encoder NN define  $q_{\phi}(z \mid x)$ ,  $\log p_{\theta}(x^{i}) =$ 

 $\mathbb{E}_{z} \left[ \log p_{\theta}(x^{i} \mid z) \right] - D_{\text{KL}}(q_{\phi}(z \mid x^{i}) || p_{\theta}(z)) + D_{\text{VL}}(q_{\phi}(z \mid x^{i}) || p_{\theta}(z \mid x^{i})) \right]$ Red is intractable

 $D_{\text{KL}}(q_{\phi}(z \mid x^i) || p_{\theta}(z \mid x^i))$ . Red is intractable, use  $\geq 0$  to ignore it; Orange is reconstruction loss, clusters similar samples; Purple makes posterior close to prior, adds cont. and interp. Orange – Purple is **ELBO**, maximize it.

 $x \xrightarrow{\text{enc}} \mu_{z|x}, \Sigma_{z|x} \xrightarrow{\text{sample}} z \xrightarrow{\text{dec}} \mu_{x|z}, \Sigma_{x|z} \xrightarrow{\text{sample}} \hat{x}$ Backprop through sample by reparametr.:  $z = \mu + \sigma \epsilon$ . For inference, use  $\mu$  directly.

Disentanglement: features should correspond to distinct factors of variation. Can be done with semi-supervised learning by making z conditionally independent of given features y. 2.1  $\beta$ -VAE

Disentangle by  $\max_{\theta,\phi} \mathbb{E}_x \left[ \mathbb{E}_{z \sim q_{\phi}} \log p_{\theta}(x \mid z) \right]$  s.t.  $D_{\text{KL}}(q_{\phi}(z \mid x) || p_{\theta}(z)) < \delta$ , with KKT:  $\max \text{Orange} - \beta \text{Purple}$ .