University of Glasgow | School of Computing Science

Visual Control of a Hexapod Robot

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Abstract

We show how to produce a level 4 project report using latex and pdflatex using the style file l4proj.cls

Education Use Consent

I hereby give my permission for this project to be shown to other University of Glasgow students and to be distributed in an electronic format. **Please note that you are under no obligation to sign this declaration, but doing so would help future students.**

Name: _____ Signature: _____

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a random graph in DIMACS format with vertices numbered 1 to n inclusive. It can be run from the