

# Dataset2-Dummy\_Linear\_output\_23

October 7, 2021

## 1 Dataset 2 : Dummy Linear Data

### 1.1 Parameters

General Parameters

1. Number of Samples

Discriminator Parameters

1. Size : number of hidden nodes

ABC-Generator parameters are as mentioned below: 1. mean : 1 (  $\beta \sim N(\beta^*, \sigma)$  where  $\beta^*$  are coefficients of statistical model) or 0 (  $\beta \sim N(0, \sigma)$  ) 2. std :  $\sigma = 1, 0.1, 0.01$  (standard deviation) 3. prior: 0 (Correct) or 1 (Misspecified)

```
[1]: n_samples = 100

#Discriminator Parameters
hidden_nodes = 25

#ABC Generator Parameters
meanVal = 1
std = 1
prior = 0
```

```
[2]: # Parameters
sample_size = 10000
std = 1
mean = 0.1
prior = 1
```

### 1.2 Import Libraries

```
[3]: import train_test
import ABC_train_test
import linearDataset
import network
import statsModel
import performanceMetrics
```

```

import dataset
import sanityChecks

import torch
import matplotlib.pyplot as plt
import seaborn as sns
from scipy.stats import norm
from torch.utils.data import Dataset, DataLoader
from statistics import mean
from sklearn.metrics import mean_squared_error, mean_absolute_error
from torch import nn
import numpy as np
import warnings
warnings.filterwarnings('ignore')

```

### 1.3 Dataset

Generate the linear dataset

$y = m * x + c + e$  where  $m = 1$ ,  $c = 0.5$  and  $e \sim N(0, 1)$

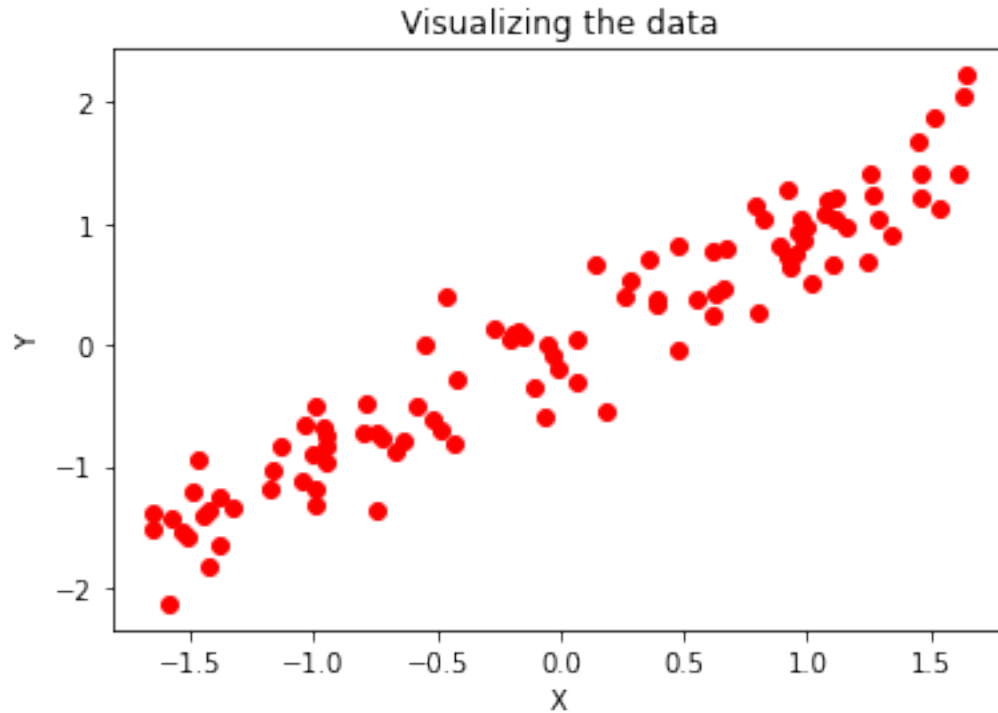
$x \sim 10 * U(-0.5, 0.5)$

```

[4]: X, Y = linearDataset.linear_data(n_samples)
     n_features = 1

```

|   | X         | Y         |
|---|-----------|-----------|
| 0 | -2.067190 | -2.301303 |
| 1 | 1.077960  | 1.520078  |
| 2 | 4.283251  | 4.277616  |
| 3 | -4.190384 | -4.727391 |
| 4 | -1.332660 | -0.468900 |



## 1.4 Stats Model

The statistical model is assumed to be  $Y = \beta X + \mu$  where  $\mu \sim N(0, 1)$

```
[5]: [coeff,y_pred] = statsModel.statsModel(X,Y)
```

No handles with labels found to put in legend.

### OLS Regression Results

```
=====
=====
Dep. Variable:                Y    R-squared (uncentered):
0.911
Model:                        OLS    Adj. R-squared (uncentered):
0.910
Method:                        Least Squares    F-statistic:
1012.
Date:                          Thu, 07 Oct 2021    Prob (F-statistic):
8.76e-54
Time:                          16:16:48    Log-Likelihood:
-20.996
No. Observations:              100    AIC:
43.99
Df Residuals:                  99    BIC:
46.60
```

```

Df Model:                                1
Covariance Type:                        nonrobust
=====
              coef      std err          t      P>|t|      [0.025      0.975]
-----
x1              0.9544      0.030     31.813      0.000      0.895      1.014
=====
Omnibus:                0.022   Durbin-Watson:                1.798
Prob(Omnibus):           0.989   Jarque-Bera (JB):            0.024
Skew:                    0.004   Prob(JB):                0.988
Kurtosis:                2.924   Cond. No.                1.00
=====

```

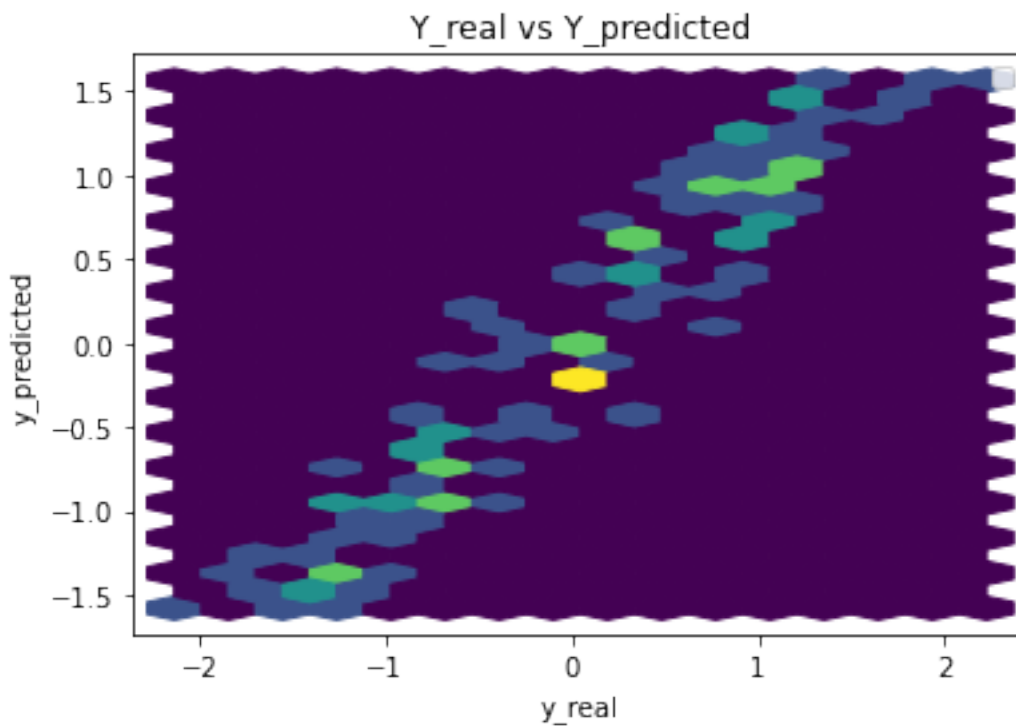
Notes:

[1]  $R^2$  is computed without centering (uncentered) since the model does not contain a constant.

[2] Standard Errors assume that the covariance matrix of the errors is correctly specified.

Parameters: x1 0.954409

dtype: float64



Performance Metrics

Mean Squared Error: 0.08910344039581332

Mean Absolute Error: 0.2355714923115581

Manhattan distance: 23.557149231155808  
Euclidean distance: 2.985019939561767

## 1.5 Generator and Discriminator Networks

### Generator Model

A simple generator consisting of 2 input nodes and an output node

```
[6]: class Generator(nn.Module):
      def __init__(self,n_input):
          super().__init__()
          self.output = nn.Linear(n_input,1)

      def forward(self, x):
          x = self.output(x)
          return x
```

### Discriminator Model

Discriminator Model consisting of 2 input nodes,1 hidden layer and one output node.The input to the discriminator will be  $(x, y_{real})$  and  $(x, y_{pred})$

```
[7]: class Discriminator(nn.Module):
      def __init__(self,n_input,n_hidden):

          super().__init__()
          self.hidden = nn.Linear(n_input,n_hidden)
          self.output = nn.Linear(n_hidden,1)
          self.relu = nn.ReLU()

      def forward(self, x):
          x = self.hidden(x)
          x = self.relu(x)
          x = self.output(x)
          return x
```

### ABC Generators

1. *Correctly Specified Prior* : The 1st ABC Generator is defined as  $Y = m * X + c + e$  where  $m \sim N(\mu, \sigma)$  ,  $c = 0.5$  and  $e \sim N(0,1)$
2. *Misspecified Prior* : The 2nd ABC Generator is defined as  $Y = 1 + m * X + c + e$  where  $m \sim N(\mu, \sigma)$  ,  $c = 0.5$  and  $e \sim N(0,1)$

Here  $\mu$  and  $\sigma$  are parameters and can take the values  $\mu = 0,1$  and  $\sigma = 1,0.1,0.01$

```
[8]: def ABC_Generator_Correct(X,mu,sigma,batch_size,device):
      m = np.random.normal(mu,sigma)
      c = 0.5
      X = X.numpy().reshape(1,batch_size)[0]
      Y = m*X + c + np.random.normal(0,1,size = batch_size)
```

```

X = torch.from_numpy(X).reshape(batch_size,1)
Y = torch.from_numpy(Y).reshape(batch_size,1)
gen_input = torch.cat((X,Y),dim = 1).to(device)
return gen_input

```

```

[9]: def ABC_Generator_Misspecified(X,mu,sigma,batch_size,device):
    m = np.random.normal(mu,sigma)
    c = 0.5
    X = X.numpy().reshape(1,batch_size)[0]
    Y = 1 + m*X + c + np.random.normal(0,1,size = batch_size)
    X = torch.from_numpy(X).reshape(batch_size,1)
    Y = torch.from_numpy(Y).reshape(batch_size,1)
    gen_input = torch.cat((X,Y),dim = 1).to(device)
    return gen_input

```

## 1.6 GAN Model

```

[10]: real_dataset = dataset.CustomDataset(X,Y)
device = torch.device('cuda' if torch.cuda.is_available() else 'cpu')

```

```

[11]: generator = Generator(n_features+1)
discriminator = Discriminator(n_features+1,hidden_nodes)

criterion = torch.nn.BCEWithLogitsLoss()
gen_opt = torch.optim.Adam(generator.parameters(), lr=0.01, betas=(0.5, 0.999))
disc_opt = torch.optim.Adam(discriminator.parameters(), lr=0.01, betas=(0.5, 0.
↪999))

```

```

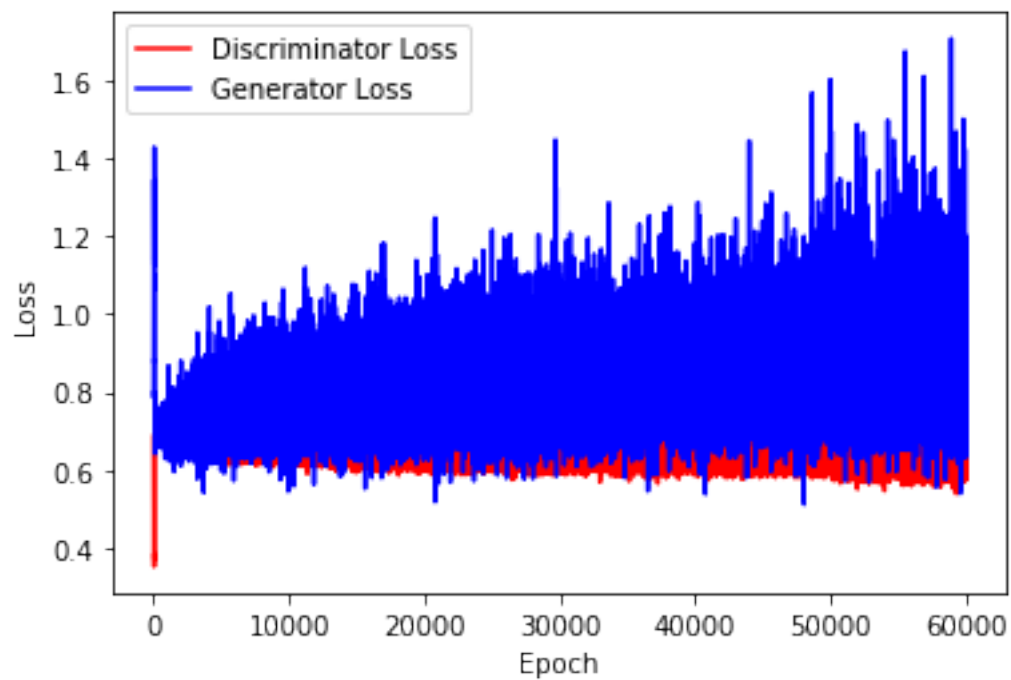
[12]: n_epochs = 30000
batch_size = n_samples//2

```

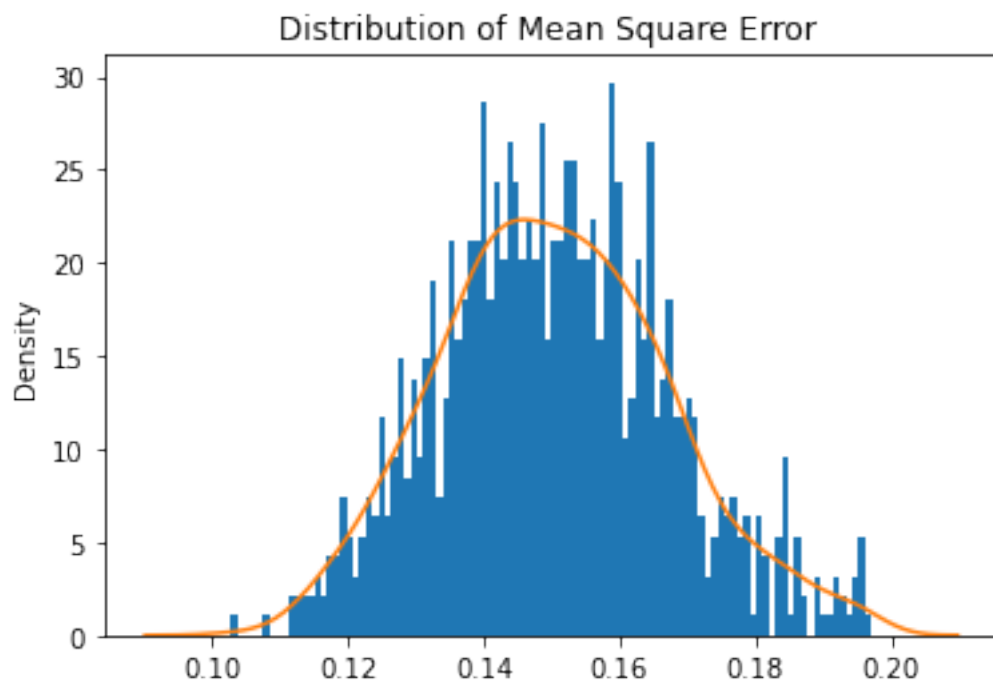
```

[13]: train_test.
↪training_GAN(discriminator,generator,disc_opt,gen_opt,real_dataset,batch_size,
↪n_epochs,criterion,device)

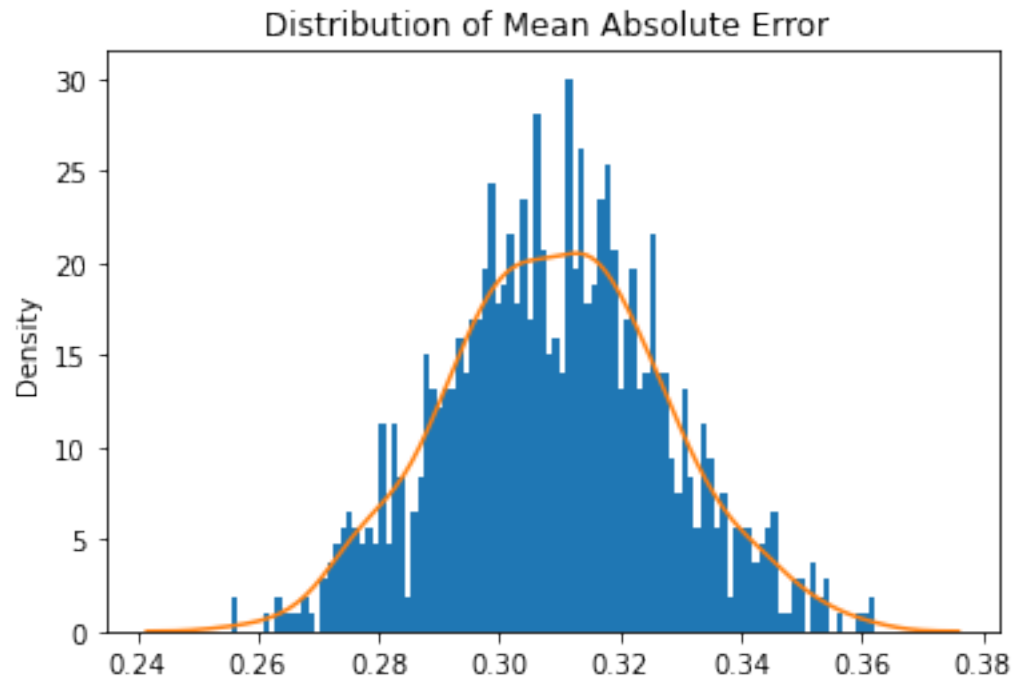
```



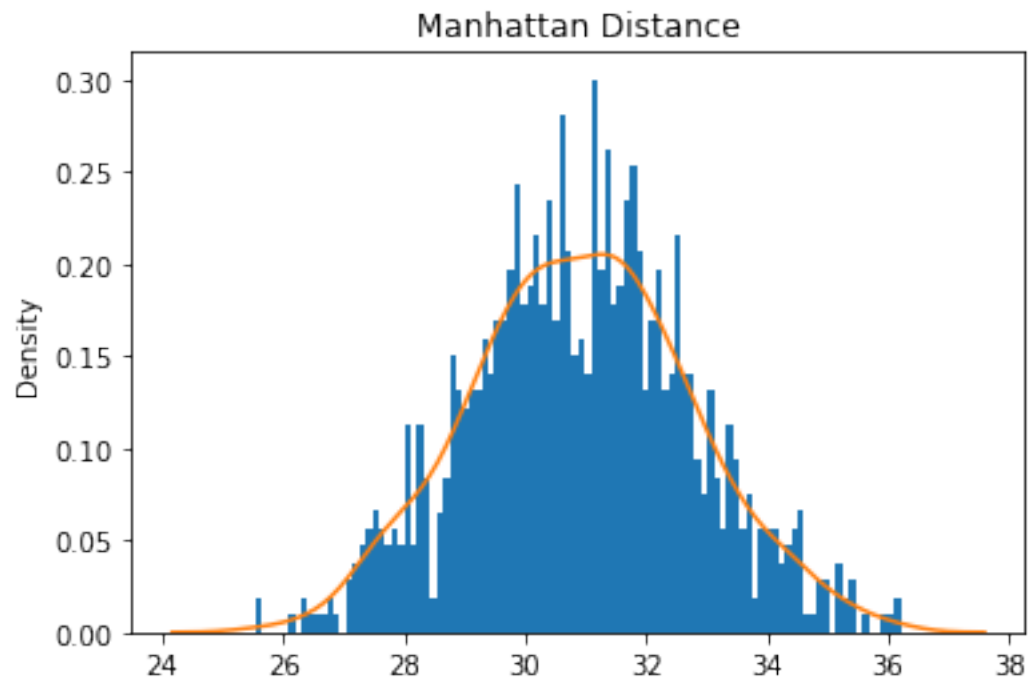
```
[14]: train_test.test_generator(generator,real_dataset,device)
```



Mean Square Error: 0.15033600574235406

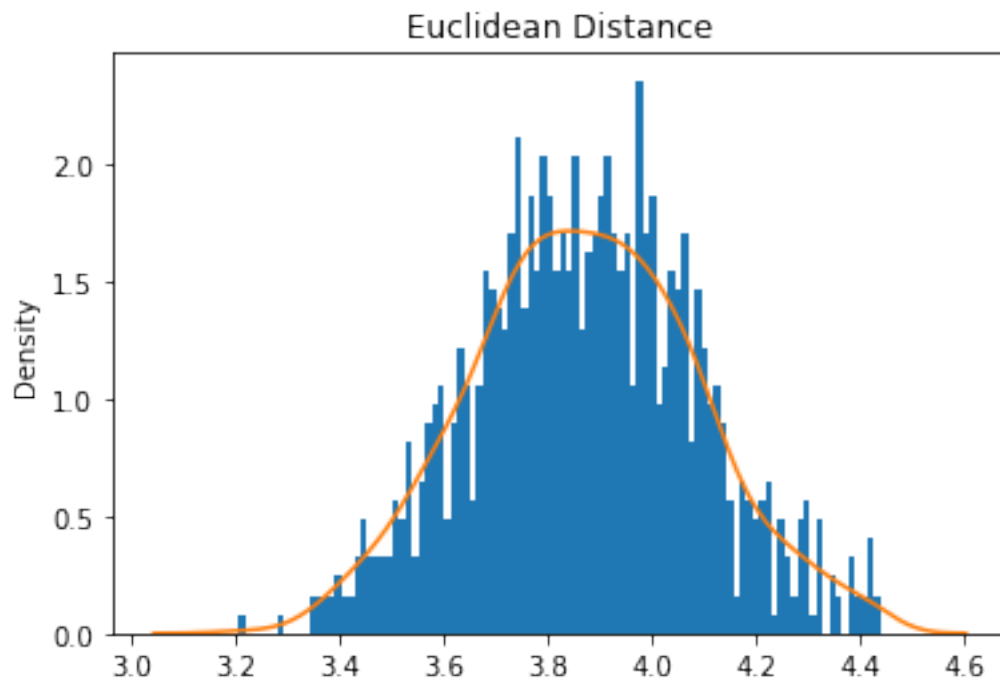


Mean Absolute Error: 0.30921951458516067





Mean Manhattan Distance: 30.921951458516066



Mean Euclidean Distance: 30.921951458516066

## 1.7 ABC - GAN Model

```
[15]: gen = Generator(n_features+1)
disc = Discriminator(n_features+1,hidden_nodes)

criterion = torch.nn.BCEWithLogitsLoss()
gen_opt = torch.optim.Adam(gen.parameters(), lr=0.01, betas=(0.5, 0.999))
disc_opt = torch.optim.Adam(disc.parameters(), lr=0.01, betas=(0.5, 0.999))
```

```
[16]: n_epoch_abc = 2000
batch_size = n_samples//2
```

```
[17]: def training_GAN(disc, gen,disc_opt,gen_opt,dataset, batch_size,
    ↪n_epochs,criterion,coeff,mean,std,prior,device):
    discriminatorLoss = []
    generatorLoss = []
    train_loader = DataLoader(dataset, batch_size=batch_size, shuffle=True)

    for epoch in range(n_epochs):
```

```

for x_batch,y_batch in train_loader:
    y_shape = list(y_batch.size())
    curr_batch_size = y_shape[0]
    y_batch = torch.reshape(y_batch,(curr_batch_size,1))

    #Create the labels
    real_labels = torch.ones(curr_batch_size,1).to(device)
    fake_labels = torch.zeros(curr_batch_size,1).to(device)

    #-----
    #Update the discriminator
    #-----
    disc_opt.zero_grad()

    #Get discriminator loss for real data
    inputs_real = torch.cat((x_batch,y_batch),dim=1).to(device)
    disc_real_pred = disc(inputs_real)
    disc_real_loss = criterion(disc_real_pred,real_labels)

    #Get discriminator loss for fake data
    gen_input = ☐
    ↪ABC_Generator_Misspecified(x_batch,mean,std,curr_batch_size,device)
    if(prior == 0):
        gen_input = ☐
    ↪ABC_Generator_Correct(x_batch,mean,std,curr_batch_size,device)
    generated_y = gen(gen_input.float())
    x_batch = x_batch.to(device)
    inputs_fake = torch.cat((x_batch,generated_y),dim=1).to(device)
    x_batch = x_batch.detach().cpu()
    disc_fake_pred = disc(inputs_fake)
    disc_fake_loss = criterion(disc_fake_pred,fake_labels)

    #Get the discriminator loss
    disc_loss = (disc_fake_loss + disc_real_loss) / 2
    discriminatorLoss.append(disc_loss.item())

    # Update gradients
    disc_loss.backward(retain_graph=True)
    # Update optimizer
    disc_opt.step()

    #-----
    #Update the Generator
    #-----
    gen_opt.zero_grad()

    #Generate input to generator using ABC pre-generator

```

```

        gen_input = □
↪ABC_Generator_Misspecified(x_batch,mean,std,curr_batch_size,device)
        if(prior == 0):
            gen_input = □
↪ABC_Generator_Correct(x_batch,mean,std,curr_batch_size,device)
            generated_y = gen(gen_input.float())
            x_batch = x_batch.to(device)
            inputs_fake = torch.cat((x_batch,generated_y),dim=1).to(device)
            x_batch = x_batch.detach().cpu()
            disc_fake_pred = disc(inputs_fake)

            gen_loss = criterion(disc_fake_pred,real_labels)
            generatorLoss.append(gen_loss.item())

            #Update gradients
            gen_loss.backward()
            #Update optimizer
            gen_opt.step()

            #Plotting the Discriminator and Generator Loss
            plt.plot(discriminatorLoss,color = "red",label="Discriminator Loss")
            plt.plot(generatorLoss,color="blue",label = "Generator Loss")
            plt.xlabel("Epoch")
            plt.ylabel("Loss")
            plt.legend()
            plt.show()

```

```

[18]: def test_generator(gen,dataset,coeff,w,std,prior,device):
        test_loader = DataLoader(dataset, batch_size=len(dataset), shuffle=False)
        mse=[]
        mae=[]
        distp1 = []
        distp2 = []
        for epoch in range(1000):
            for x_batch, y_batch in test_loader:
                gen_input = □
↪ABC_Generator_Misspecified(x_batch,w,std,len(dataset),device)
                if(prior == 0):
                    gen_input = □
↪ABC_Generator_Correct(x_batch,w,std,len(dataset),device)
                    generated_y = gen(gen_input.float())
                    generated_y = generated_y.cpu().detach()
                    generated_data = torch.reshape(generated_y,(-1,))
                    gen_data = generated_data.numpy().reshape(1,len(dataset)).tolist()
                    real_data = y_batch.numpy().reshape(1,len(dataset)).tolist()
                    #Plot the data
                    if(epoch%200==0):

```

```

        gen_data1 = generated_data.numpy().tolist()
        real_data1 = y_batch.numpy().tolist()
        plt.hexbin(real_data1,gen_data1,gridsize=(15,15))
        plt.xlabel("Y")
        plt.ylabel("Y_Pred")
        plt.show()

    meanSquaredError = mean_squared_error(real_data,gen_data)
    meanAbsoluteError = mean_absolute_error(real_data, gen_data)
    mse.append(meanSquaredError)
    mae.append(meanAbsoluteError)
    dist1 = ABC_train_test.minkowski_distance(np.array(real_data)[0],np.
→array(gen_data)[0], 1)
    dist2 = ABC_train_test.minkowski_distance(np.array(real_data)[0],np.
→array(gen_data)[0], 2)
    distp1.append(dist1)
    distp2.append(dist2)

#Distribution of Metrics
#Mean Squared Error
n,x,_=plt.hist(mse,bins=100,density=True)
plt.title("Distribution of Mean Square Error ")
sns.distplot(mse,hist=False)
plt.show()
print("Mean Square Error:",mean(mse))

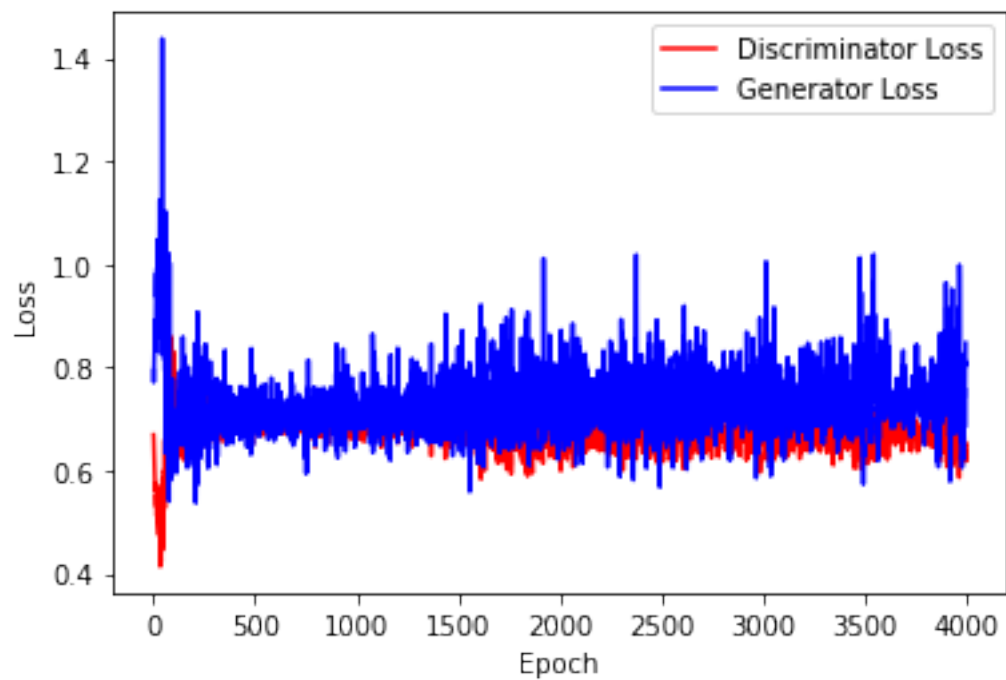
#Mean Absolute Error
n,x,_=plt.hist(mae,bins=100,density=True)
plt.title("Distribution of Mean Absolute Error ")
sns.distplot(mae,hist=False)
plt.show()
print("Mean Absolute Error:",mean(mae))

#Minkowski Distance 1st Order
n,x,_=plt.hist(distp1,bins=100,density=True)
plt.title("Manhattan Distance")
sns.distplot(distp1,hist=False)
print("Mean Manhattan Distance:",mean(distp1))
plt.show()

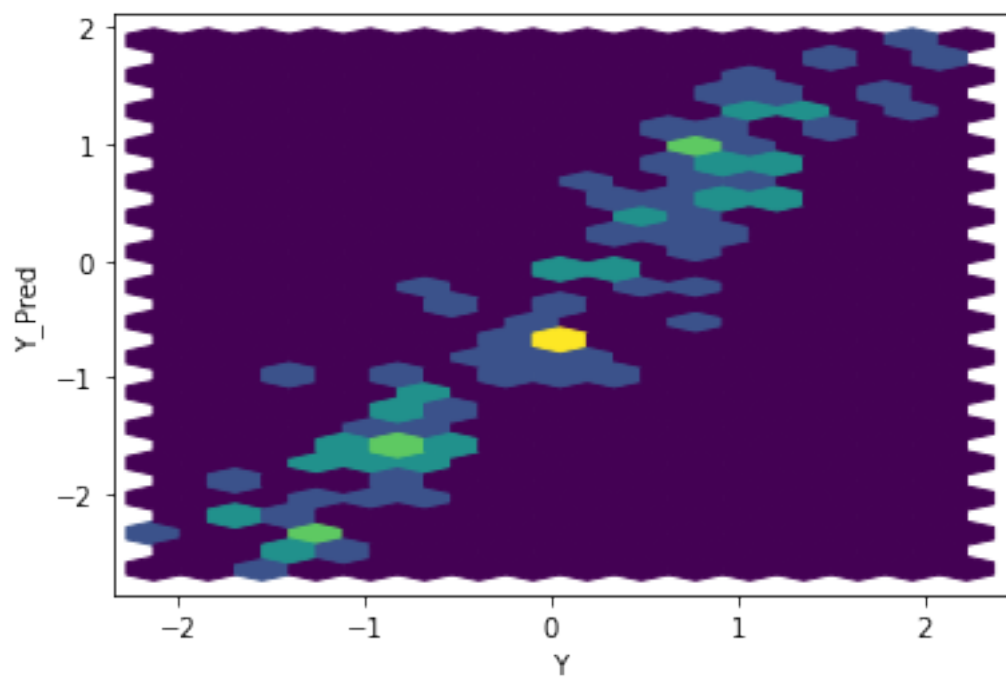
#Minkowski Distance 2nd Order
n,x,_=plt.hist(distp2,bins=100,density=True)
plt.title("Euclidean Distance")
sns.distplot(distp2,hist=False)
print("Mean Euclidean Distance:",mean(distp2))
plt.show()

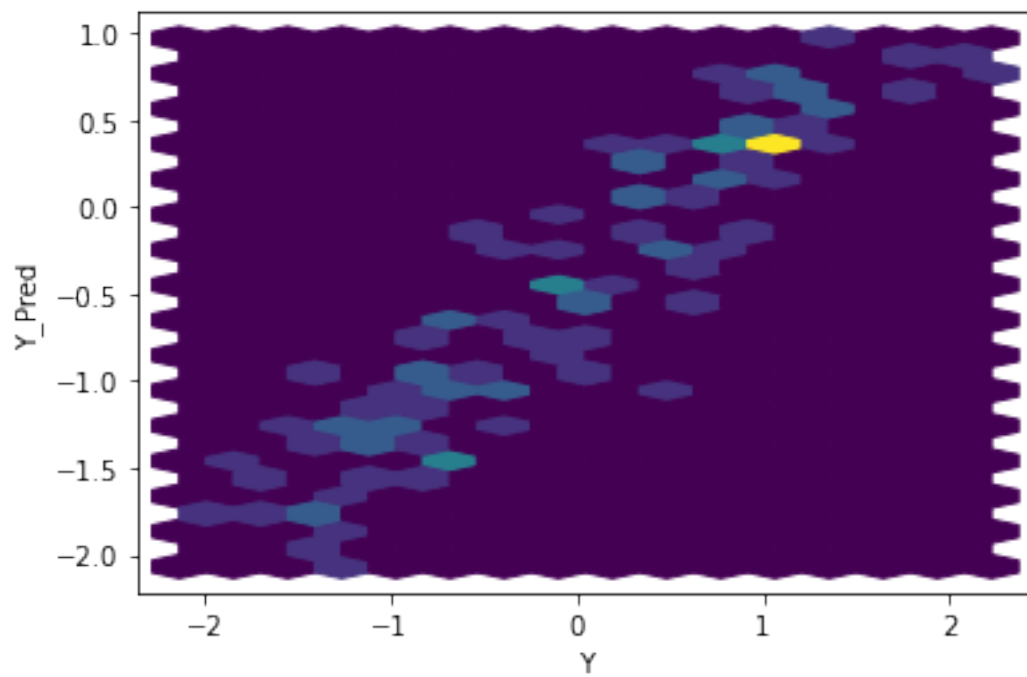
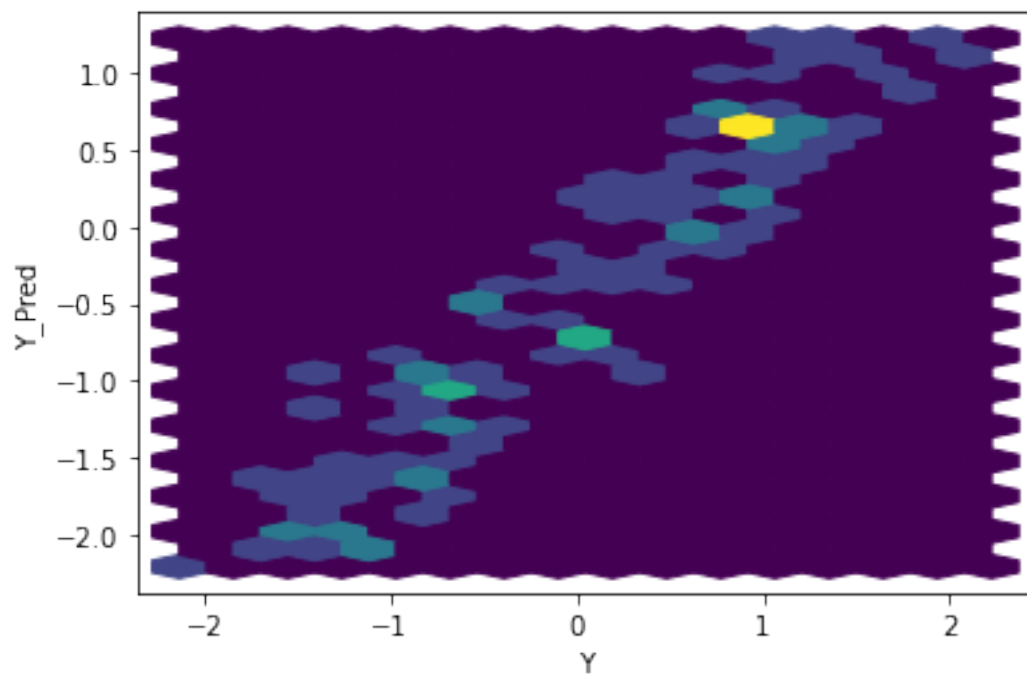
```

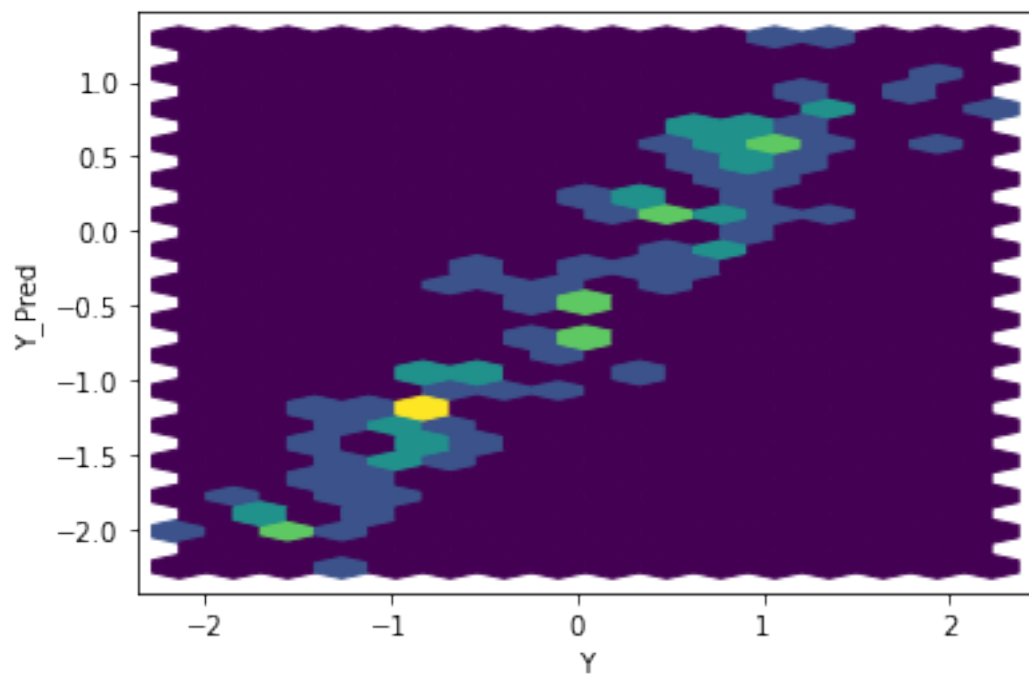
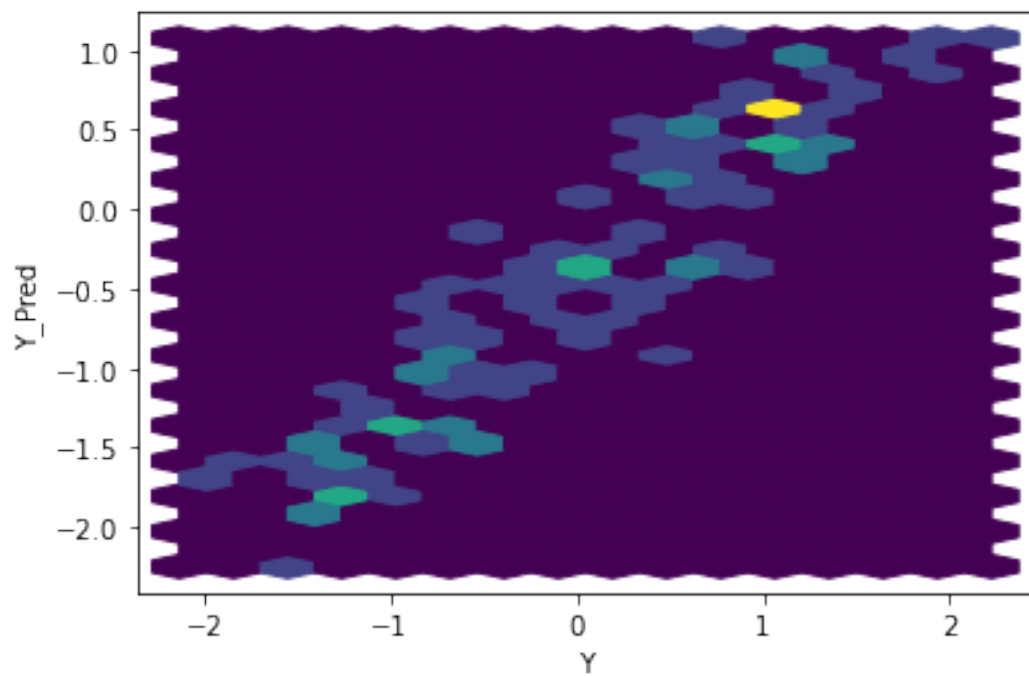
[19]: training\_GAN(disc,gen,disc\_opt,gen\_opt,real\_dataset,batch\_size,n\_epoch\_abc,criterion,coeff,mea

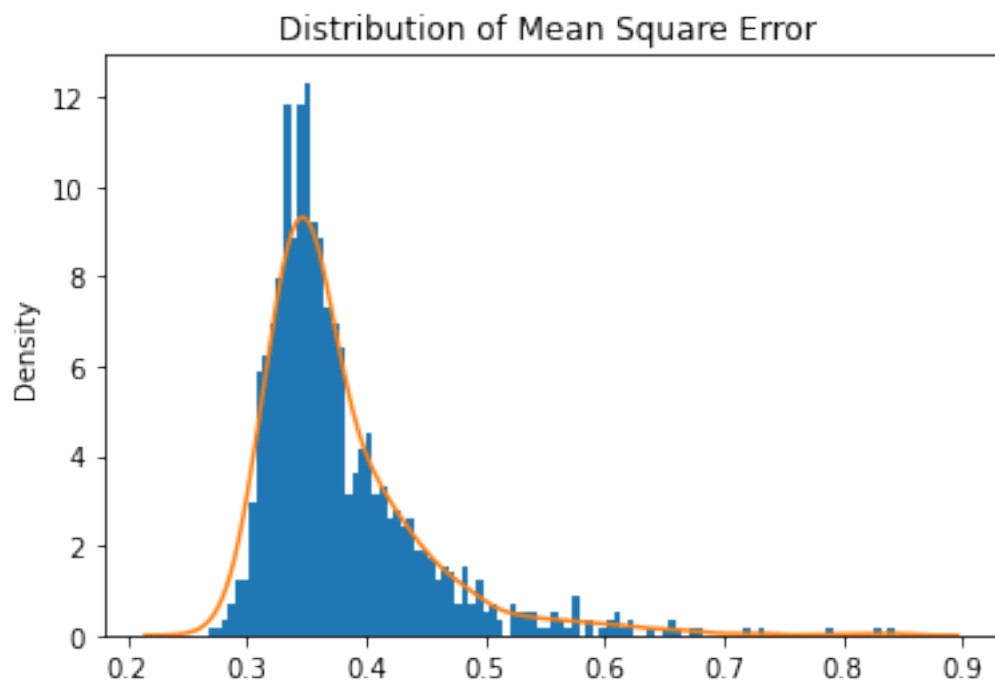


```
[20]: test_generator(gen,real_dataset,coeff,meanVal,std,prior,device)
```

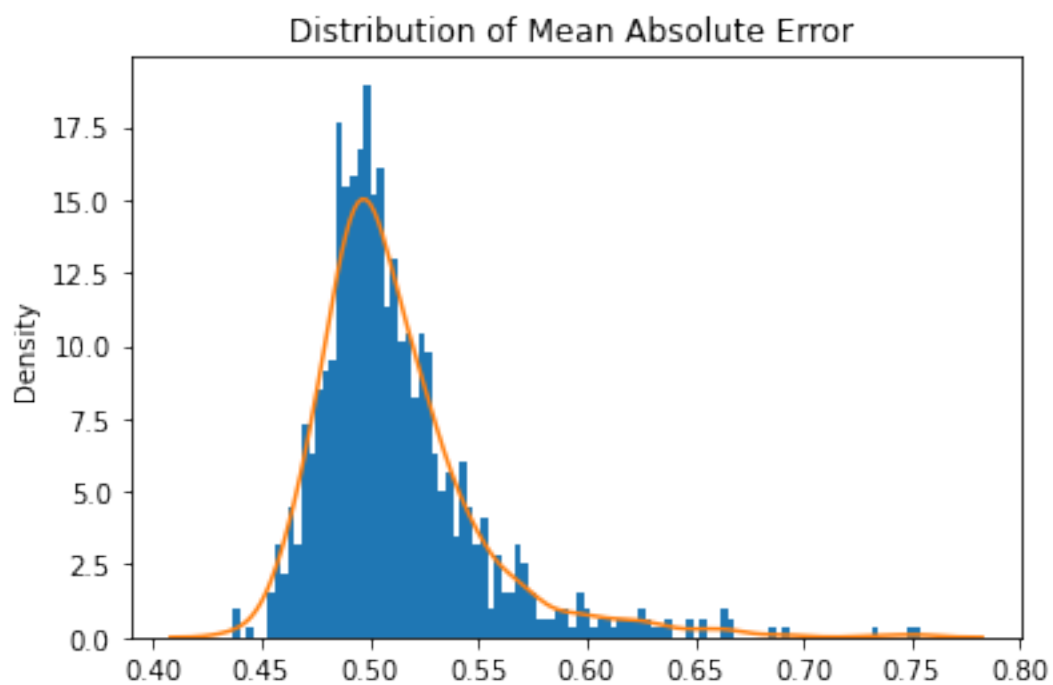






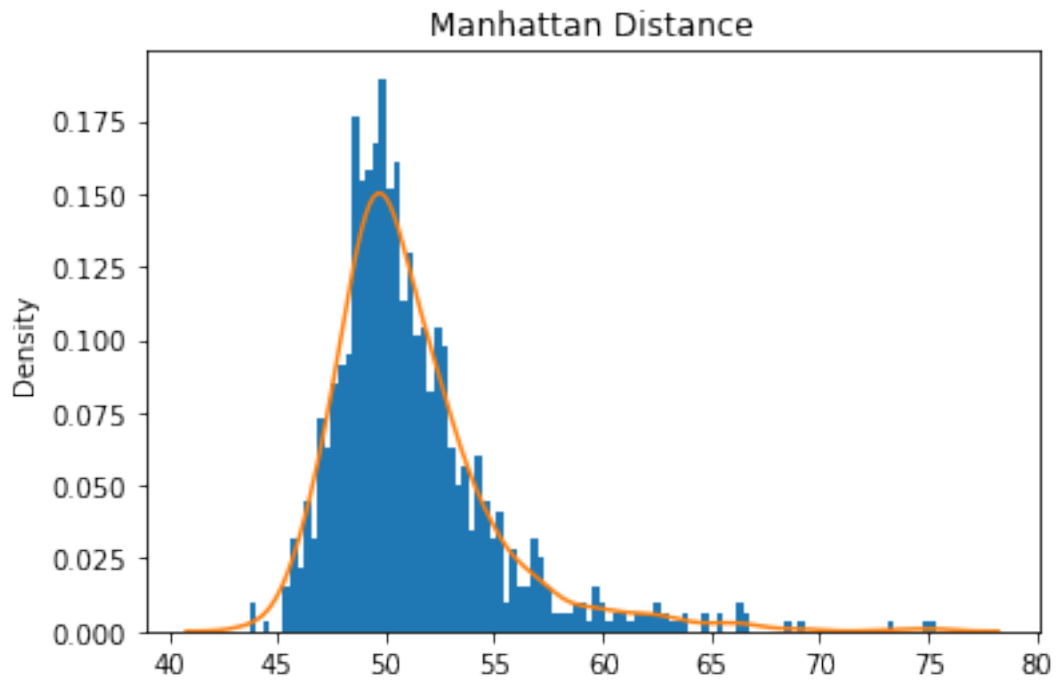


Mean Square Error: 0.3789827684924012

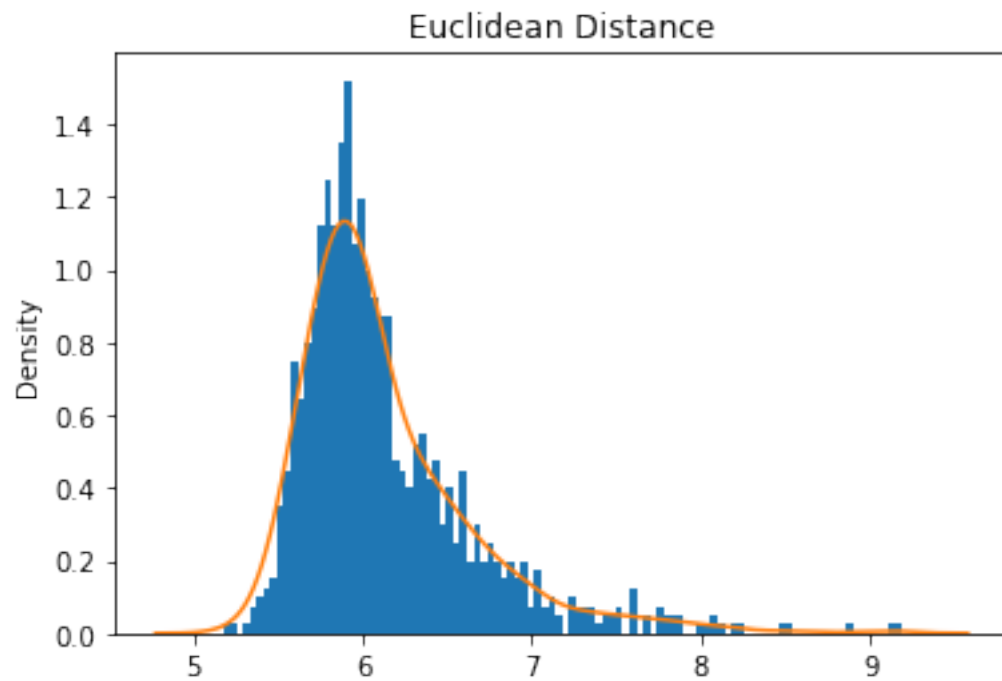




Mean Absolute Error: 0.5121396331794793  
Mean Manhattan Distance: 51.21396331794793



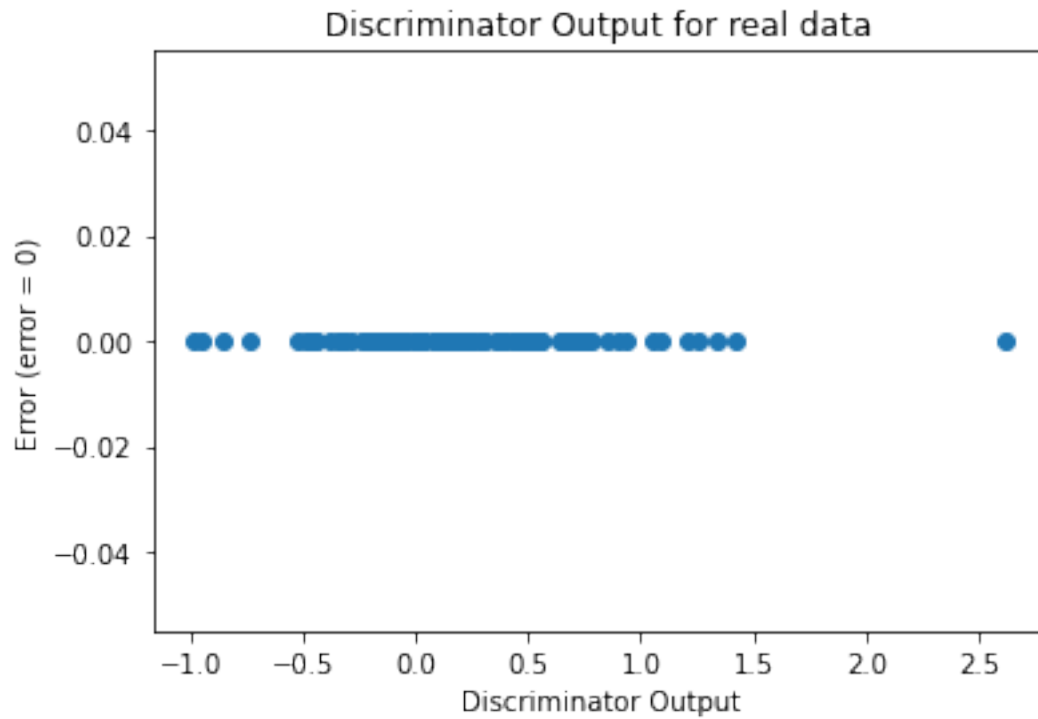
Mean Euclidean Distance: 6.133557487516052

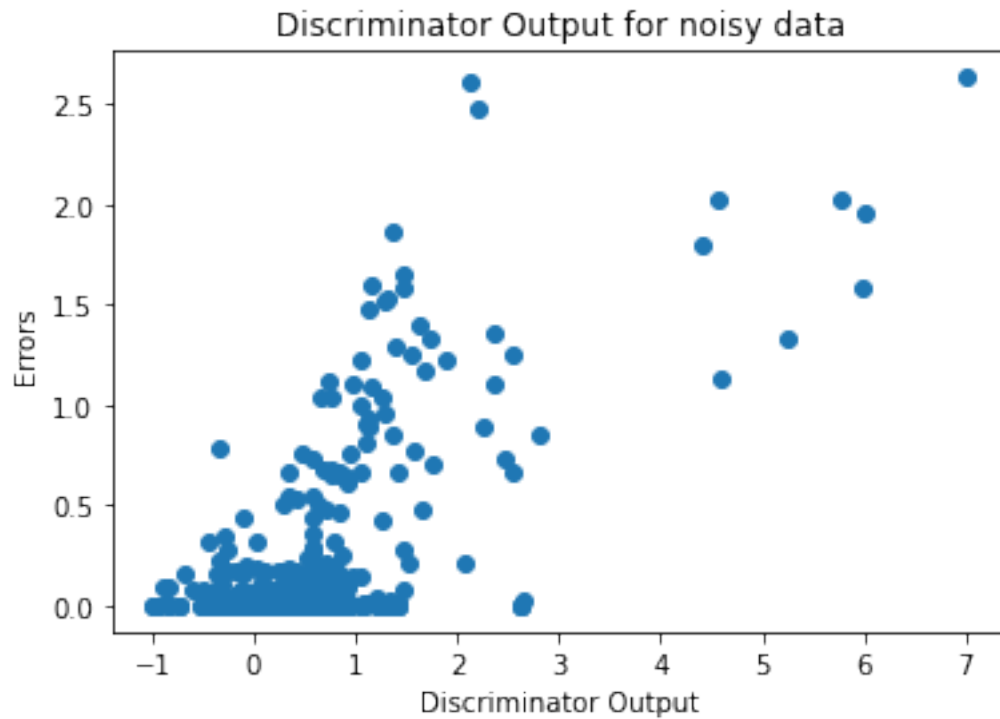


### 1.7.1 Sanity Check

We plot the discriminator output vs the noise in the input to verify that the discriminator functions correctly. We expect that discriminator output and noise are inversely proportional

```
[21]: sanityChecks.discProbVsError(real_dataset,disc,device)
```





### 1.7.2 Visualization of Trained GAN Generator

```
[22]: for name, param in gen.named_parameters():
      print(name,param)
```

```
output.weight Parameter containing:
tensor([[ 1.0149, -0.1799]], requires_grad=True)
output.bias Parameter containing:
tensor([-0.1873], requires_grad=True)
```