Dataset2-Dummy_Linear_output_14

October 7, 2021

1 Dataset 2 : Dummy Linear Data

1.1 Parameters

General Parameters

1. Number of Samples

Discriminator Parameters

1. Size: number of hidden nodes

ABC-Generator parameters are as mentioned below: 1. mean : 1 ($\beta \sim N(\beta^*, \sigma)$ where β^* are coefficients of statistical model) or 0 ($\beta \sim N(0, \sigma)$ 2. std : $\sigma = 1, 0.1, 0.01$ (standard deviation) 3. prior: 0 (Correct) or 1 (Misspecified)

```
[1]: n_samples = 100

#Discriminator Parameters
hidden_nodes = 25

#ABC Generator Parameters
meanVal = 1
std = 1
prior = 0
```

```
[2]: # Parameters
sample_size = 10000
std = 1
mean = 0.1
prior = 0
```

1.2 Import Libraries

```
[3]: import train_test
import ABC_train_test
import linearDataset
import network
import statsModel
import performanceMetrics
```

```
import dataset
import sanityChecks

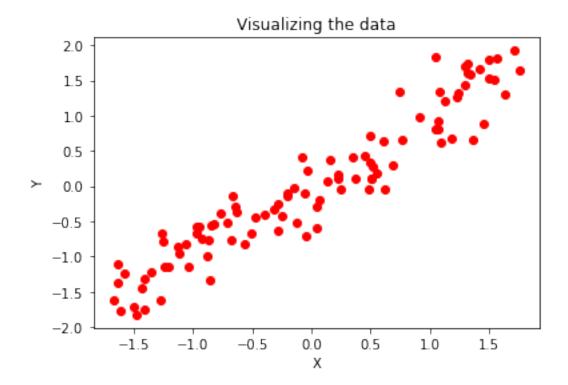
import torch
import matplotlib.pyplot as plt
import seaborn as sns
from scipy.stats import norm
from torch.utils.data import Dataset,DataLoader
from statistics import mean
from sklearn.metrics import mean_squared_error,mean_absolute_error
from torch import nn
import numpy as np
import warnings
warnings.filterwarnings('ignore')
```

1.3 Dataset

Generate the linear dataset

```
y = m * x + c + e where m = 1, c = 0.5 and e \sim N(0, 1)
x \sim 10 * U(-0.5, 0.5)
```

```
X Y
0 -0.840081 -1.463260
1 1.407469 0.729693
2 0.966175 1.665507
3 -1.664791 -2.054066
4 4.421772 5.846094
```



1.4 Stats Model

The statistical model is assumed to be $Y = \beta X + \mu$ where $\mu \sim N(0, 1)$

```
[5]: [coeff,y_pred] = statsModel.statsModel(X,Y)
```

No handles with labels found to put in legend.

OLS Regression Results

====== Dep. Variable: Y R-squared (uncentered): 0.903 Model: OLS Adj. R-squared (uncentered): 0.902 Method: Least Squares F-statistic: 917.4 Date: Thu, 07 Oct 2021 Prob (F-statistic): 7.21e-52 15:54:53 Time: Log-Likelihood:

-25.446
No. Observations: 100 AIC:

52.89

Df Residuals: 99 BIC:

55.50

Df Model: 1
Covariance Type: nonrobust

=========		========	=======			========	
	coef	std err	t	P> t	[0.025	0.975]	
x1	0.9501	0.031	30.289	0.000	0.888	1.012	
Omnibus:		0	.911 Dur	 bin-Watson:		1.791	
<pre>Prob(Omnibus):</pre>		0	.634 Jar	que-Bera (JB)):	0.912	
Skew:		-0	.055 Pro	b(JB):		0.634	
Kurtosis:		2	.545 Con	d. No.		1.00	

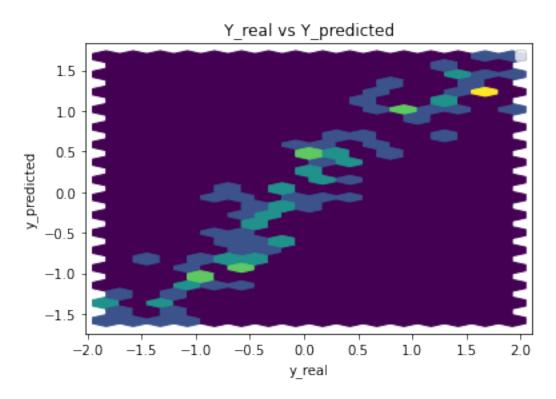
Notes:

[1] R^{2} is computed without centering (uncentered) since the model does not contain a constant.

[2] Standard Errors assume that the covariance matrix of the errors is correctly specified.

Parameters: x1 0.950054

dtype: float64



Performance Metrics

Mean Squared Error: 0.09739802543266751 Mean Absolute Error: 0.2557156831439636 Manhattan distance: 25.571568314396362 Euclidean distance: 3.120865672095925

1.5 Generator and Discriminator Networks

Generator Model

A simple generator consisting of 2 input nodes and an output node

```
[6]: class Generator(nn.Module):
    def __init__(self,n_input):
        super().__init__()
        self.output = nn.Linear(n_input,1)

def forward(self, x):
        x = self.output(x)
        return x
```

Discriminator Model

Discriminator Model consisting of 2 input nodes,1 hidden layer and one output node. The input to the discriminator will be (x, y_{real}) and (x, y_{pred})

```
[7]: class Discriminator(nn.Module):
    def __init__(self,n_input,n_hidden):
        super().__init__()
        self.hidden = nn.Linear(n_input,n_hidden)
        self.output = nn.Linear(n_hidden,1)
        self.relu = nn.ReLU()

    def forward(self, x):
        x = self.hidden(x)
        x = self.relu(x)
        x = self.output(x)
        return x
```

ABC Generators

- 1. Correctly Specified Prior: The 1st ABC Generator is defined as Y = m * X + c + e where $m \sim N(\mu, \sigma)$, c = 0.5 and $e \sim N(0, 1)$
- 2. Misspecified Prior : The 2nd ABC Generator is defined as Y=1+m*X+c+e where $m\sim N(\mu,\sigma)$, c=0.5 and $e\sim N(0,1)$

Here μ and σ are parameters and can take the values $\mu = 0, 1$ and $\sigma = 1, 0.1, 0.01$

```
[8]: def ABC_Generator_Correct(X,mu,sigma,batch_size,device):
    m = np.random.normal(mu,sigma)
    c = 0.5
    X = X.numpy().reshape(1,batch_size)[0]
    Y = m*X + c + np.random.normal(0,1,size = batch_size)
```

```
X = torch.from_numpy(X).reshape(batch_size,1)
Y = torch.from_numpy(Y).reshape(batch_size,1)
gen_input = torch.cat((X,Y),dim = 1).to(device)
return gen_input

[9]: def ABC_Generator_Misspecified(X,mu,sigma,batch_size,device):
m = np.random.normal(mu,sigma)
c = 0.5
```

Mer ABC_Generator_Misspecified(X,mu,sigma,batch_size,device):
 m = np.random.normal(mu,sigma)
 c = 0.5
 X = X.numpy().reshape(1,batch_size)[0]
 Y = 1 + m*X + c + np.random.normal(0,1,size = batch_size)
 X = torch.from_numpy(X).reshape(batch_size,1)
 Y = torch.from_numpy(Y).reshape(batch_size,1)
 gen_input = torch.cat((X,Y),dim = 1).to(device)
 return gen_input

1.6 GAN Model

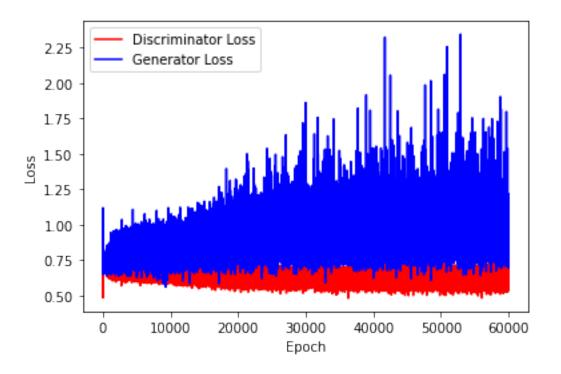
```
[10]: real_dataset = dataset.CustomDataset(X,Y)
device = torch.device('cuda' if torch.cuda.is_available() else 'cpu')
```

```
[12]: n_epochs = 30000
batch_size = n_samples//2
```

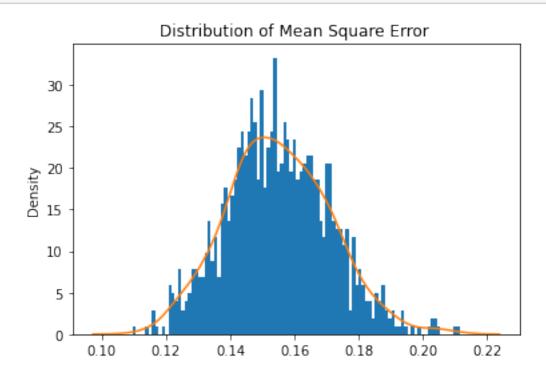
```
[13]: train_test.

→training_GAN(discriminator,generator,disc_opt,gen_opt,real_dataset,batch_size,

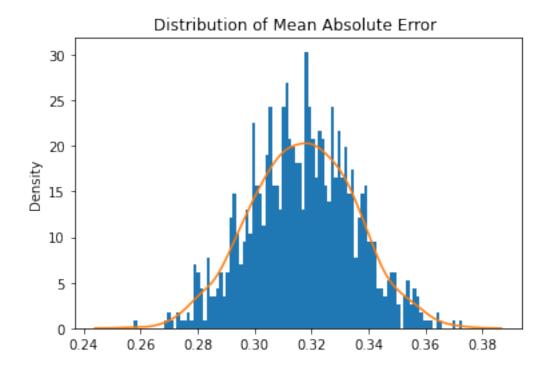
→n_epochs,criterion,device)
```



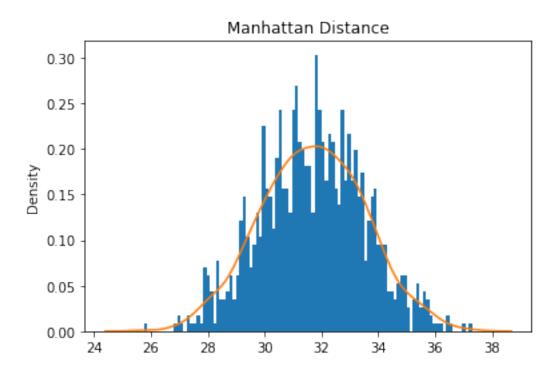
[14]: train_test.test_generator(generator,real_dataset,device)



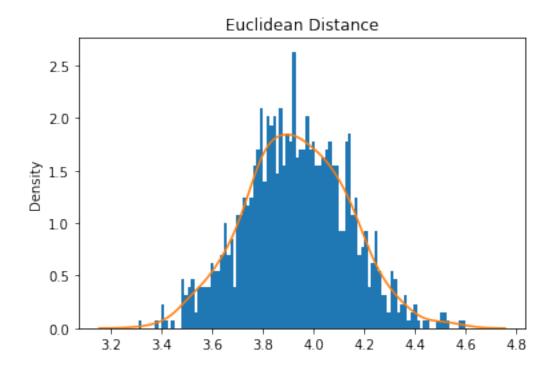
Mean Square Error: 0.15503096387655116



Mean Absolute Error: 0.3170201495877653



Mean Manhattan Distance: 31.702014958776534



Mean Euclidean Distance: 31.702014958776534

1.7 ABC - GAN Model

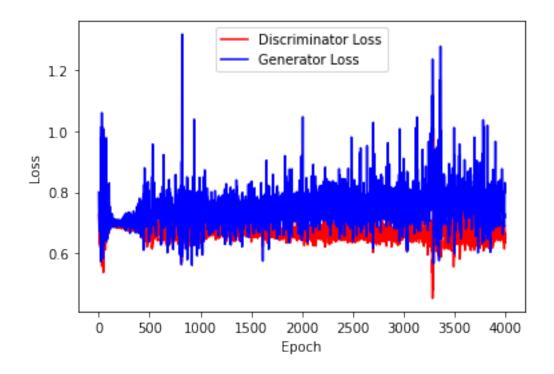
```
for x_batch,y_batch in train_loader:
          y_shape = list(y_batch.size())
          curr_batch_size = y_shape[0]
          y_batch = torch.reshape(y_batch,(curr_batch_size,1))
          #Create the labels
          real_labels = torch.ones(curr_batch_size,1).to(device)
          fake_labels = torch.zeros(curr_batch_size,1).to(device)
          #-----
          #Update the discriminator
           #-----
          disc_opt.zero_grad()
          #Get discriminator loss for real data
          inputs_real = torch.cat((x_batch,y_batch),dim=1).to(device)
          disc_real_pred = disc(inputs_real)
          disc_real_loss = criterion(disc_real_pred,real_labels)
          #Get discriminator loss for fake data
          gen_input =
→ABC_Generator_Misspecified(x_batch,mean,std,curr_batch_size,device)
          if(prior == 0):
              gen_input = _
→ABC_Generator_Correct(x_batch, mean, std, curr_batch_size, device)
          generated_y = gen(gen_input.float())
          x batch = x batch.to(device)
          inputs_fake = torch.cat((x_batch,generated_y),dim=1).to(device)
          x_batch = x_batch.detach().cpu()
          disc_fake_pred = disc(inputs_fake)
          disc_fake_loss = criterion(disc_fake_pred,fake_labels)
          #Get the discriminator loss
          disc_loss = (disc_fake_loss + disc_real_loss) / 2
          discriminatorLoss.append(disc_loss.item())
          # Update gradients
          disc_loss.backward(retain_graph=True)
          # Update optimizer
          disc_opt.step()
          #-----
          #Update the Generator
          #-----
          gen_opt.zero_grad()
          #Generate input to generator using ABC pre-generator
```

```
→ABC Generator Misspecified(x_batch, mean, std, curr_batch_size, device)
                  if(prior == 0):
                      gen input = |
       →ABC_Generator_Correct(x_batch,mean,std,curr_batch_size,device)
                  generated_y = gen(gen_input.float())
                  x_batch = x_batch.to(device)
                  inputs_fake = torch.cat((x_batch,generated_y),dim=1).to(device)
                  x_batch = x_batch.detach().cpu()
                  disc_fake_pred = disc(inputs_fake)
                  gen loss = criterion(disc fake pred,real labels)
                  generatorLoss.append(gen_loss.item())
                  #Update gradients
                  gen_loss.backward()
                  #Update optimizer
                  gen_opt.step()
          #Plotting the Discriminator and Generator Loss
          plt.plot(discriminatorLoss,color = "red",label="Discriminator Loss")
          plt.plot(generatorLoss,color="blue",label ="Generator Loss")
          plt.xlabel("Epoch")
          plt.ylabel("Loss")
          plt.legend()
          plt.show()
[18]: def test_generator(gen,dataset,coeff,w,std,prior,device):
          test_loader = DataLoader(dataset, batch_size=len(dataset), shuffle=False)
          mse=[]
          mae=[]
          distp1 = []
          distp2 = []
          for epoch in range(1000):
              for x_batch, y_batch in test_loader:
                  gen_input = _
       →ABC_Generator_Misspecified(x_batch,w,std,len(dataset),device)
                  if(prior == 0):
                      gen_input = _
       →ABC_Generator_Correct(x_batch, w, std, len(dataset), device)
                  generated_y = gen(gen_input.float())
                  generated_y = generated_y.cpu().detach()
                  generated_data = torch.reshape(generated_y,(-1,))
                  gen_data = generated_data.numpy().reshape(1,len(dataset)).tolist()
                  real_data = y_batch.numpy().reshape(1,len(dataset)).tolist()
                  #Plot the data
                  if(epoch\%200==0):
```

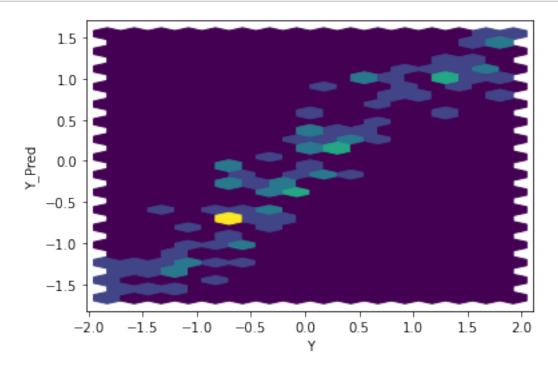
gen_input = _

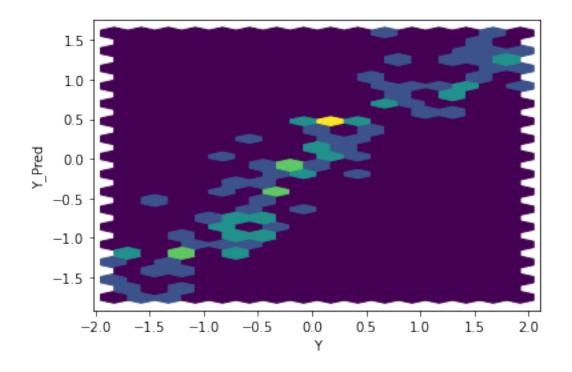
```
gen_data1 = generated_data.numpy().tolist()
               real_data1 = y_batch.numpy().tolist()
               plt.hexbin(real_data1,gen_data1,gridsize=(15,15))
               plt.xlabel("Y")
               plt.ylabel("Y_Pred")
               plt.show()
           meanSquaredError = mean_squared_error(real_data,gen_data)
           meanAbsoluteError = mean_absolute_error(real_data, gen_data)
           mse.append(meanSquaredError)
           mae.append(meanAbsoluteError)
           dist1 = ABC_train_test.minkowski_distance(np.array(real_data)[0],np.
→array(gen_data)[0], 1)
           dist2 = ABC_train_test.minkowski_distance(np.array(real_data)[0],np.
→array(gen_data)[0], 2)
           distp1.append(dist1)
           distp2.append(dist2)
   #Distribution of Metrics
   #Mean Squared Error
  n,x,_=plt.hist(mse,bins=100,density=True)
  plt.title("Distribution of Mean Square Error ")
  sns.distplot(mse,hist=False)
  plt.show()
  print("Mean Square Error:",mean(mse))
   #Mean Absolute Error
  n,x,_=plt.hist(mae,bins=100,density=True)
  plt.title("Distribution of Mean Absolute Error ")
  sns.distplot(mae,hist=False)
  plt.show()
  print("Mean Absolute Error:",mean(mae))
   #Minkowski Distance 1st Order
  n,x,_=plt.hist(distp1,bins=100,density=True)
  plt.title("Manhattan Distance")
   sns.distplot(distp1,hist=False)
  print("Mean Manhattan Distance:",mean(distp1))
  plt.show()
   #Minkowski Distance 2nd Order
  n,x,_=plt.hist(distp2,bins=100,density=True)
  plt.title("Euclidean Distance")
   sns.distplot(distp2,hist=False)
  print("Mean Euclidean Distance:",mean(distp2))
  plt.show()
```

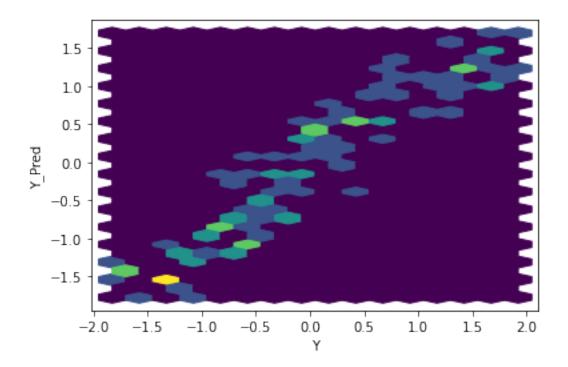
[19]: training_GAN(disc,gen,disc_opt,gen_opt,real_dataset,batch_size,n_epoch_abc,criterion,coeff,mea

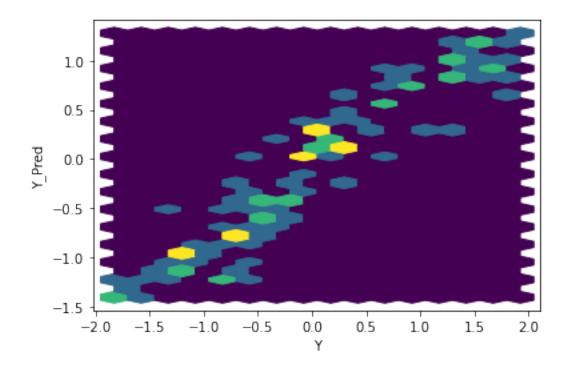


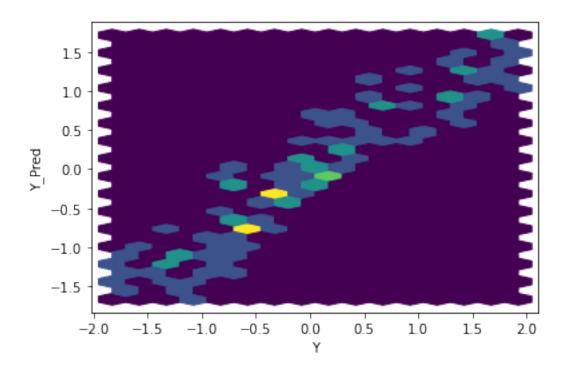
[20]: test_generator(gen,real_dataset,coeff,meanVal,std,prior,device)

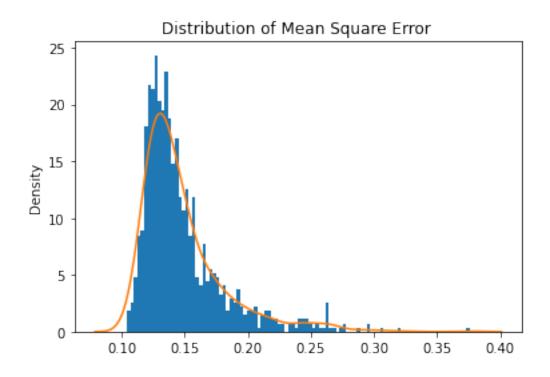




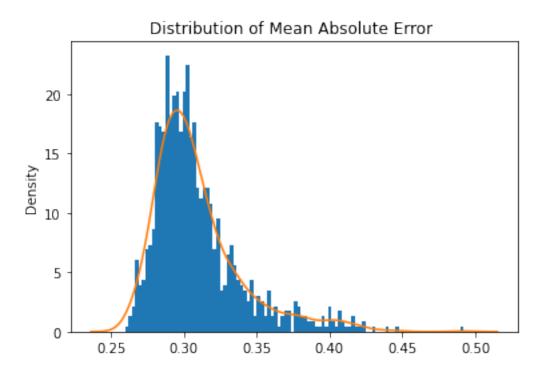




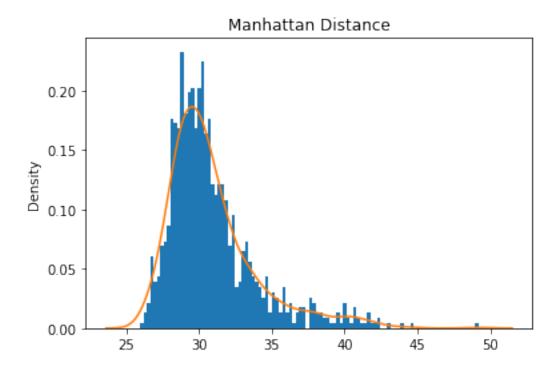




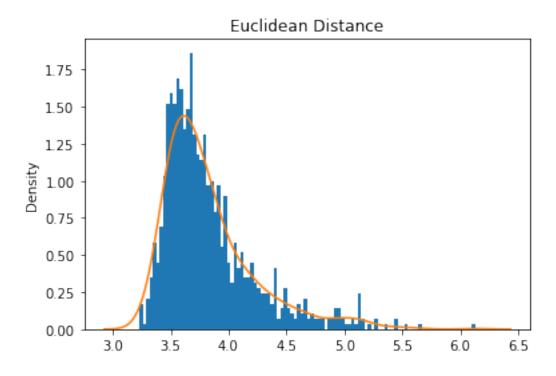
Mean Square Error: 0.14835449687882163



Mean Absolute Error: 0.3092937923701853
Mean Manhattan Distance: 30.929379237018527



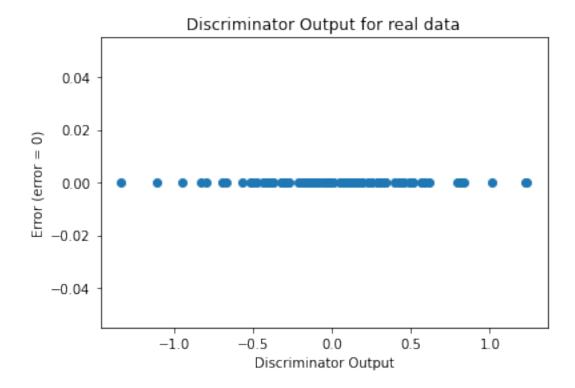
Mean Euclidean Distance: 3.8306294890601698

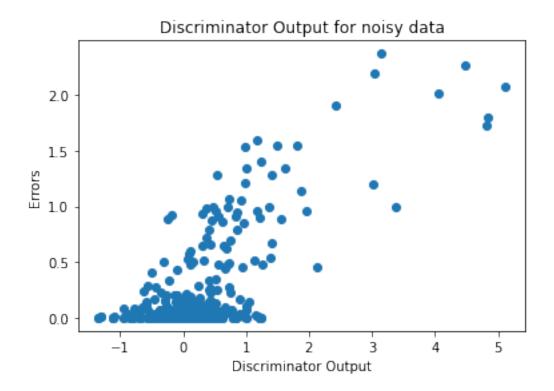


1.7.1 Sanity Check

We plot the discriminator output vs the noise in the input to verify that the discriminator functions correctly. We expect that discriminator output and noise are inversely proportional

[21]: sanityChecks.discProbVsError(real_dataset,disc,device)





1.7.2 Visualization of Trained GAN Generator

```
[22]: for name, param in gen.named_parameters(): print(name,param)
```

output.weight Parameter containing: tensor([[0.7981, 0.1482]], requires_grad=True) output.bias Parameter containing: tensor([-0.1494], requires_grad=True)