Dataset4-Capital_Punishment_output_4

October 7, 2021

```
[1]: # Parameters
std = 1
mean = 0
```

1 Dataset 4 - Capital Punishment

1.1 Parameters

```
[2]: #ABC_Generator
std = 1
mean = 1
prior = 0

#Discriminator
hidden_nodes = 7
```

1.2 Import Libraries and Dataset

```
[3]: import warnings
  warnings.filterwarnings('ignore')

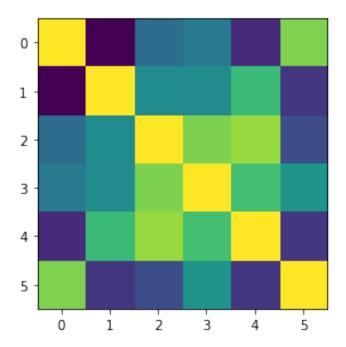
[4]: import cpunishDataset
```

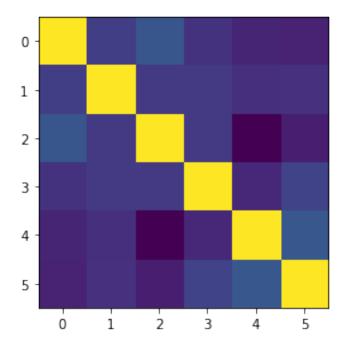
```
import cpunishDataset
import train_test
import ABC_train_test
import network
import statsModel
import performanceMetrics
import dataset
import sanityChecks

import torch
from torch import nn
from torch.utils.data import Dataset , DataLoader
import numpy as np
import matplotlib.pyplot as plt
import seaborn as sns
from statistics import mean
```

```
import pandas as pd
%matplotlib inline
```

[5]: #Load the dataset X,Y = cpunishDataset.cpunish_data() n_features = 6





2 Stats Model

[6]: [coeff,y_pred] = statsModel.statsModel(X,Y)

No handles with labels found to put in legend.

OLS Regression Results

============	:==========		=======================================
Dep. Variable:	EXECUTIONS	R-squared:	0.409
Model:	OLS	Adj. R-squared:	-0.098
Method:	Least Squares	F-statistic:	0.8073
Date:	Thu, 07 Oct 2021	Prob (F-statistic):	0.595
Time:	15:03:06	Log-Likelihood:	-16.184
No. Observations:	14	AIC:	46.37
Df Residuals:	7	BIC:	50.84
Df Model:	6		
Covariance Type:	nonrobust		
	=======================================		

========			:======	=======	========	========
	coef	std err	t	P> t	[0.025	0.975]
const	0	0.291	0	1.000	-0.687	0.687
x1	-0.3071	0.167	-1.835	0.109	-0.703	0.089
x2	-0.0727	0.210	-0.347	0.739	-0.569	0.423
x3	-0.0780	0.406	-0.192	0.853	-1.039	0.883
x4	0.2846	0.539	0.528	0.614	-0.989	1.558
x5	0.6329	0.622	1.017	0.343	-0.839	2.104

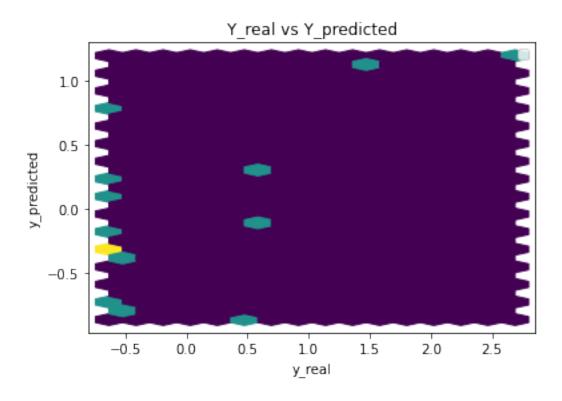
x6	-0.1115	1.356	-0.082	0.937	-3.318	3.095
Omnibus:		0.50	Q Durbir	======= n-Watson:	=======	0.960
Prob(Omnibu	13).	0.30		e-Bera (JB):		0.285
Skew:		0.31	-			0.867
Kurtosis:		2.69	6 Cond.	No.		8.10
========	:========	========	=======		========	=======

Notes:

[1] Standard Errors assume that the covariance matrix of the errors is correctly specified.

Parameters: const 0.000000

x1 -0.307149 x2 -0.072734 x3 -0.077971 x4 0.284622 x5 0.632853 x6 -0.111469 dtype: float64



Performance Metrics

Mean Squared Error: 0.5910184401346179 Mean Absolute Error: 0.6107560111864074 Manhattan distance: 8.550584156609704 Euclidean distance: 2.876501027617521

3 Generator and Discriminator Networks

GAN Generator

```
[7]: class Generator(nn.Module):
    def __init__(self,n_input):
        super().__init__()
        #Input to Output Layer Linear Transformation
        self.output = nn.Linear(n_input,1)

def forward(self, x):
    #Pass the input tensor through the operations
    x = self.output(x)
    return x
```

GAN Discriminator

```
[8]: class Discriminator(nn.Module):
    def __init__(self,n_input,hiddenNodes):
        super().__init__()
        self.hidden = nn.Linear(n_input,hiddenNodes)
        self.output = nn.Linear(hiddenNodes,1)
        #Define LeakyRelu Activation and sigmoid output
        self.sigmoid = nn.Sigmoid()
        self.leakyRelu = nn.LeakyReLU()

    def forward(self, x):
        #Pass the input tensor through the operations
        x = self.hidden(x)
        x = self.leakyRelu(x)
        x = self.output(x)
        x = self.sigmoid(x)
        return x
```

ABC Generator

The ABC generator is defined as follows:

```
Y = 1 + \beta_1 x_1 + \beta_2 x_2 + \beta_2 x_3 + ... + \beta_n x_n + N(0, \sigma) where \sigma = 0.1
\beta_i \sim N(0, \sigma^*) when \mu = 0 else \beta_i \sim N(\beta_i^*, \sigma^*) where \beta_i^* s are coefficients obtained from stats model Parameters: \mu and \sigma^*
```

```
if mean == 0:
    weights = np.random.normal(0,variance,size=(coeff_len,1))
    weights = torch.from_numpy(weights).reshape(coeff_len,1)
else:
    weights = []
    for i in range(coeff_len):
        weights.append(np.random.normal(coeff[i],variance))
    weights = torch.tensor(weights).reshape(coeff_len,1)

y_abc = torch.matmul(x_batch,weights.float())
gen_input = torch.cat((x_batch,y_abc),dim = 1).to(device)
return gen_input
```

4 GAN Model

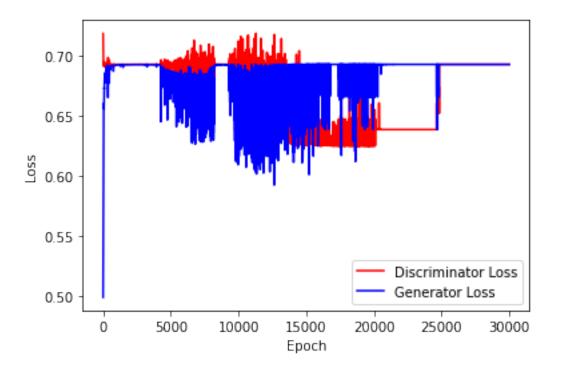
```
[10]: real_dataset = dataset.CustomDataset(X,Y)
    device = torch.device('cuda' if torch.cuda.is_available() else 'cpu')

[11]: generator = Generator(n_features+2)
    discriminator = Discriminator(n_features+2,hidden_nodes)

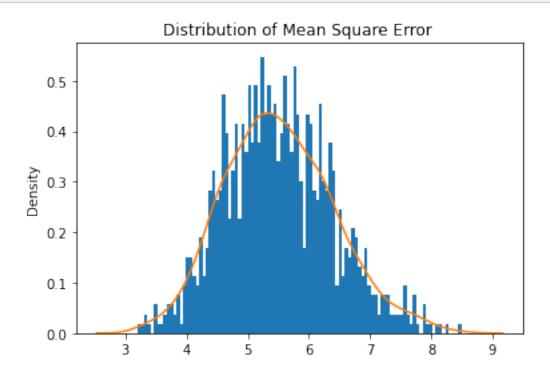
    criterion = torch.nn.BCEWithLogitsLoss()
    gen_opt = torch.optim.Adam(generator.parameters(), lr=0.01, betas=(0.5, 0.999))
    disc_opt = torch.optim.Adam(discriminator.parameters(), lr=0.01, betas=(0.5, 0.999))

[12]: sample_size = len(real_dataset)
    n_epochs = 30000
    batch_size = sample_size

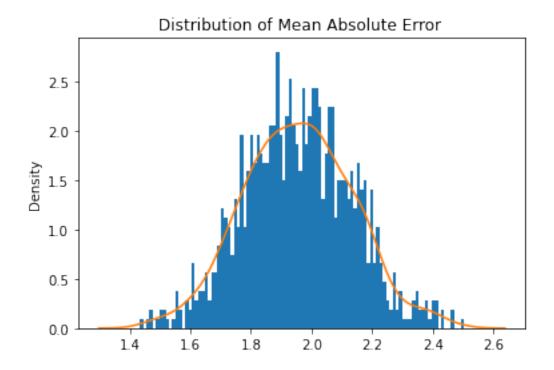
[13]: train_test.
    otraining_GAN(discriminator,generator,disc_opt,gen_opt,real_dataset,batch_size,unepochs,criterion,device)
```



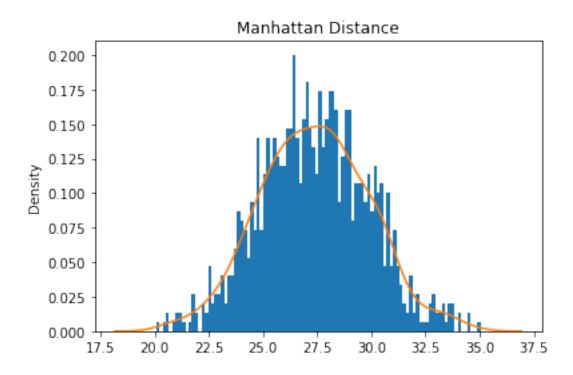
[14]: train_test.test_generator(generator,real_dataset,device)



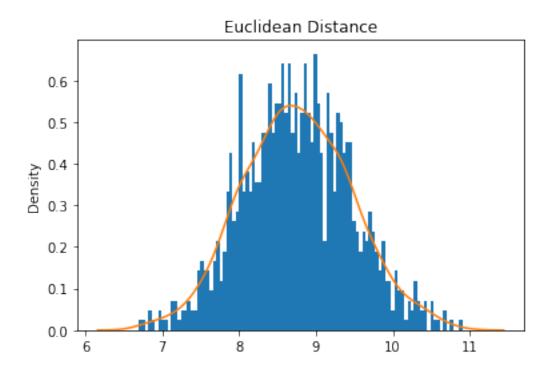
Mean Square Error: 5.5130342450474705



Mean Absolute Error: 1.9563203257481967



Mean Manhattan Distance: 27.388484560474755



Mean Euclidean Distance: 27.388484560474755

5 ABC GAN Model

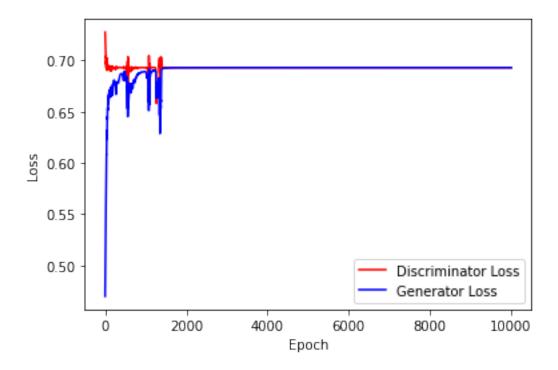
```
[15]: gen = Generator(n_features+2)
    disc = Discriminator(n_features+2,hidden_nodes)

    criterion = torch.nn.BCEWithLogitsLoss()
    gen_opt = torch.optim.Adam(gen.parameters(), lr=0.01, betas=(0.5, 0.999))
    disc_opt = torch.optim.Adam(disc.parameters(), lr=0.01, betas=(0.5, 0.999))

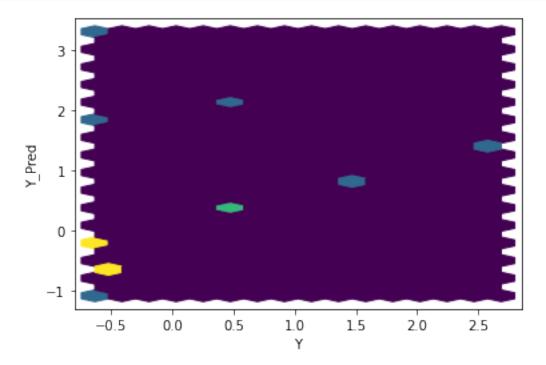
[16]: n_epoch_abc = 10000
    batch_size = sample_size

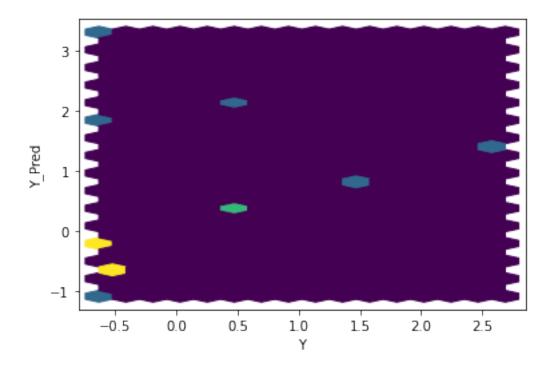
[17]: ABC_train_test.training_GAN(disc, gen,disc_opt,gen_opt,real_dataset,__
```

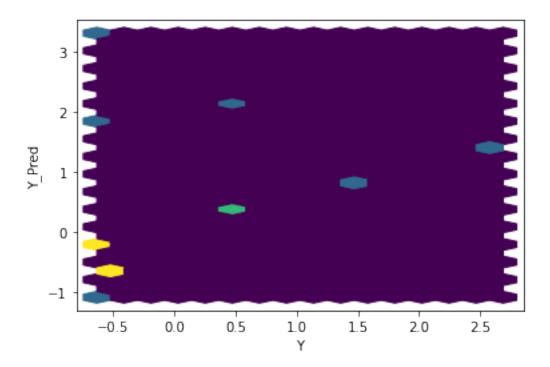
→batch_size, n_epoch_abc,criterion,coeff,mean,std,device)

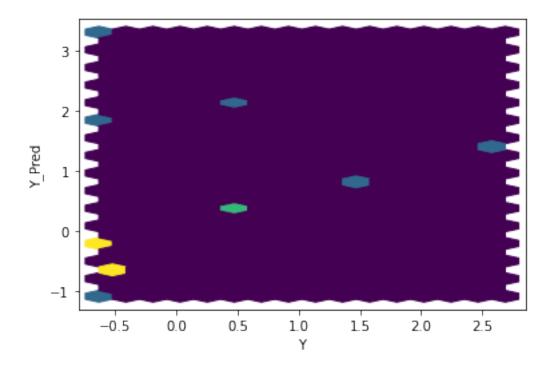


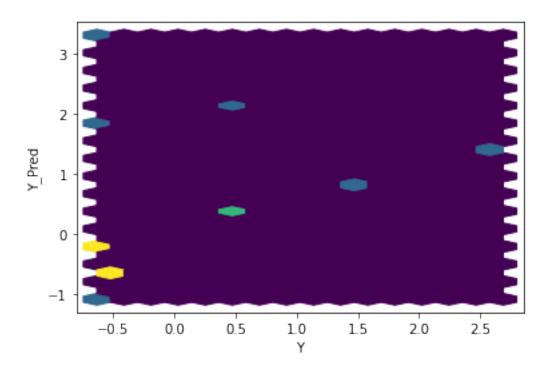
[18]: ABC_train_test.test_generator(gen,real_dataset,coeff,mean,std,device)

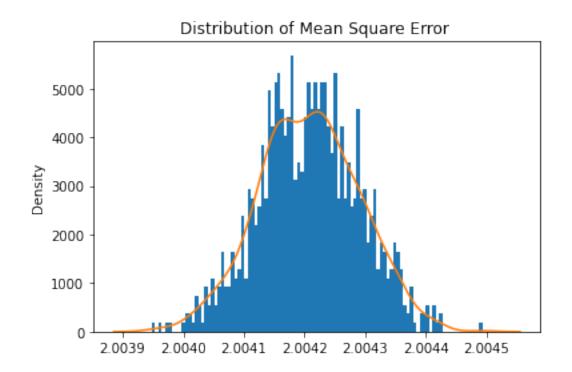




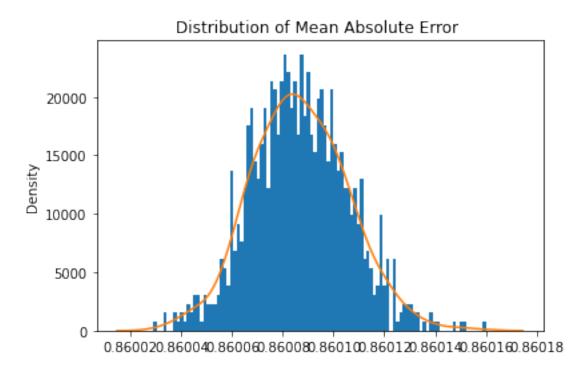




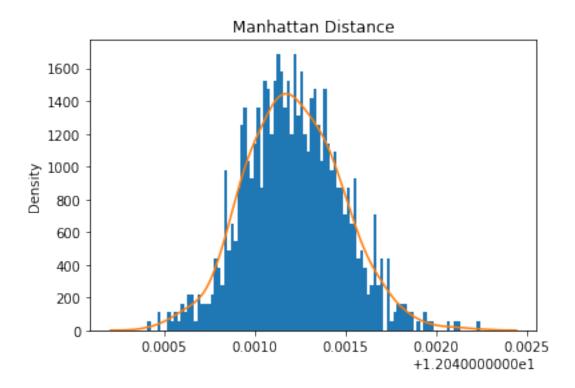




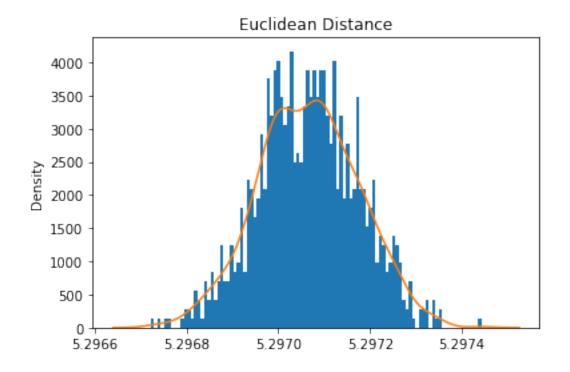
Mean Square Error: 2.004207386437904



Mean Absolute Error: 0.8600866886994668 Mean Manhattan Distance: 12.041213641792536

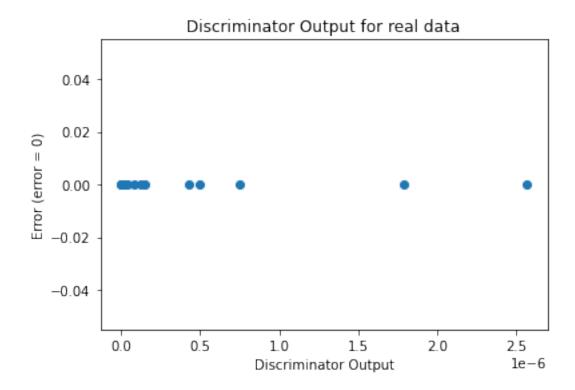


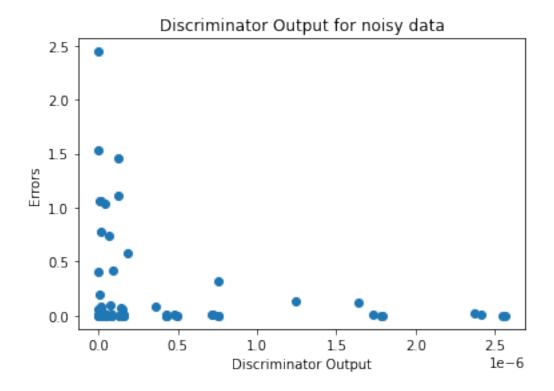
Mean Euclidean Distance: 5.297065545963925



Sanity Check

[19]: sanityChecks.discProbVsError(real_dataset,disc,device)





Visualisation of Trained GAN Generator