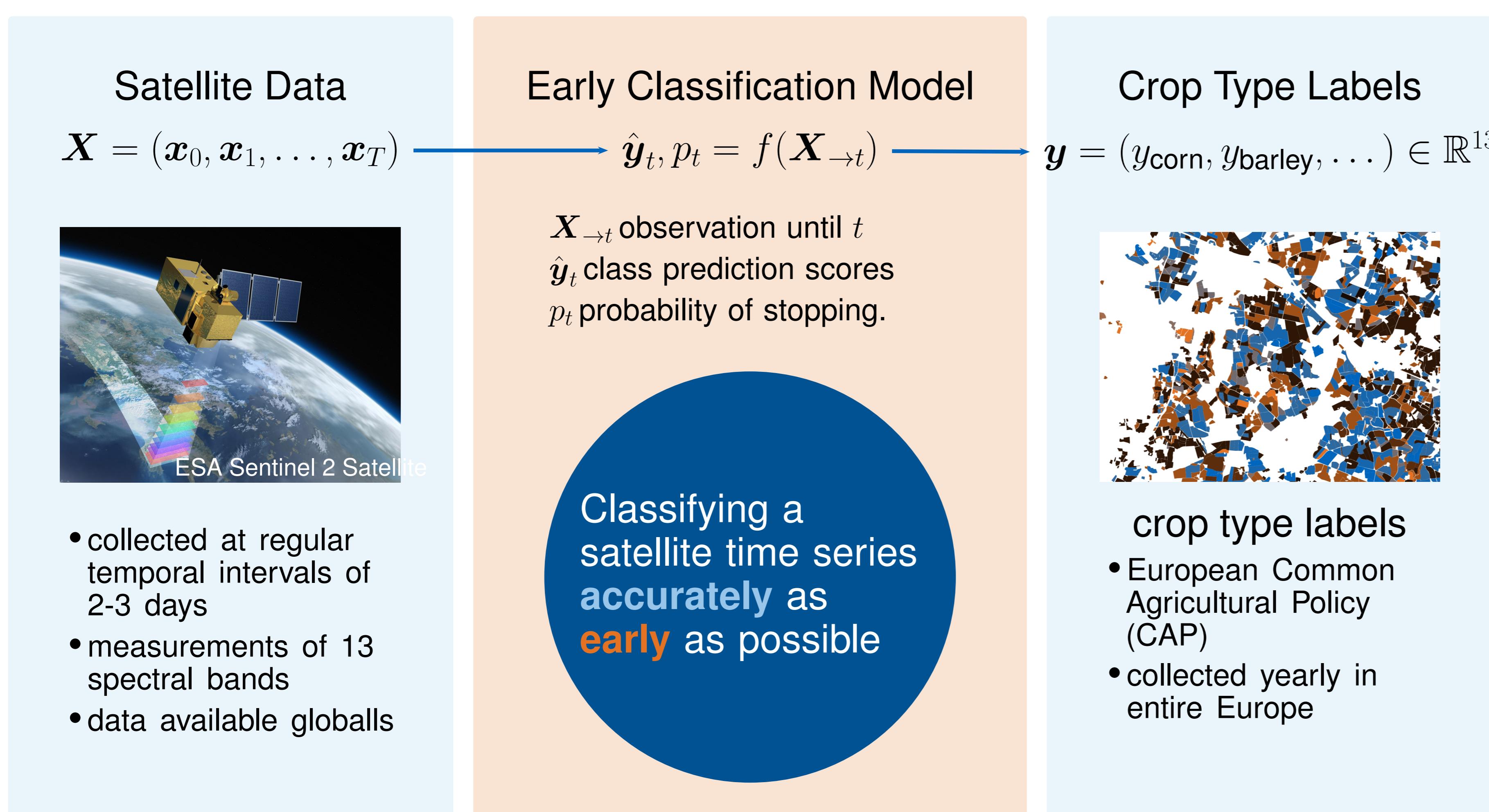


Early Classification for Agricultural Monitoring from Satellite Time Series

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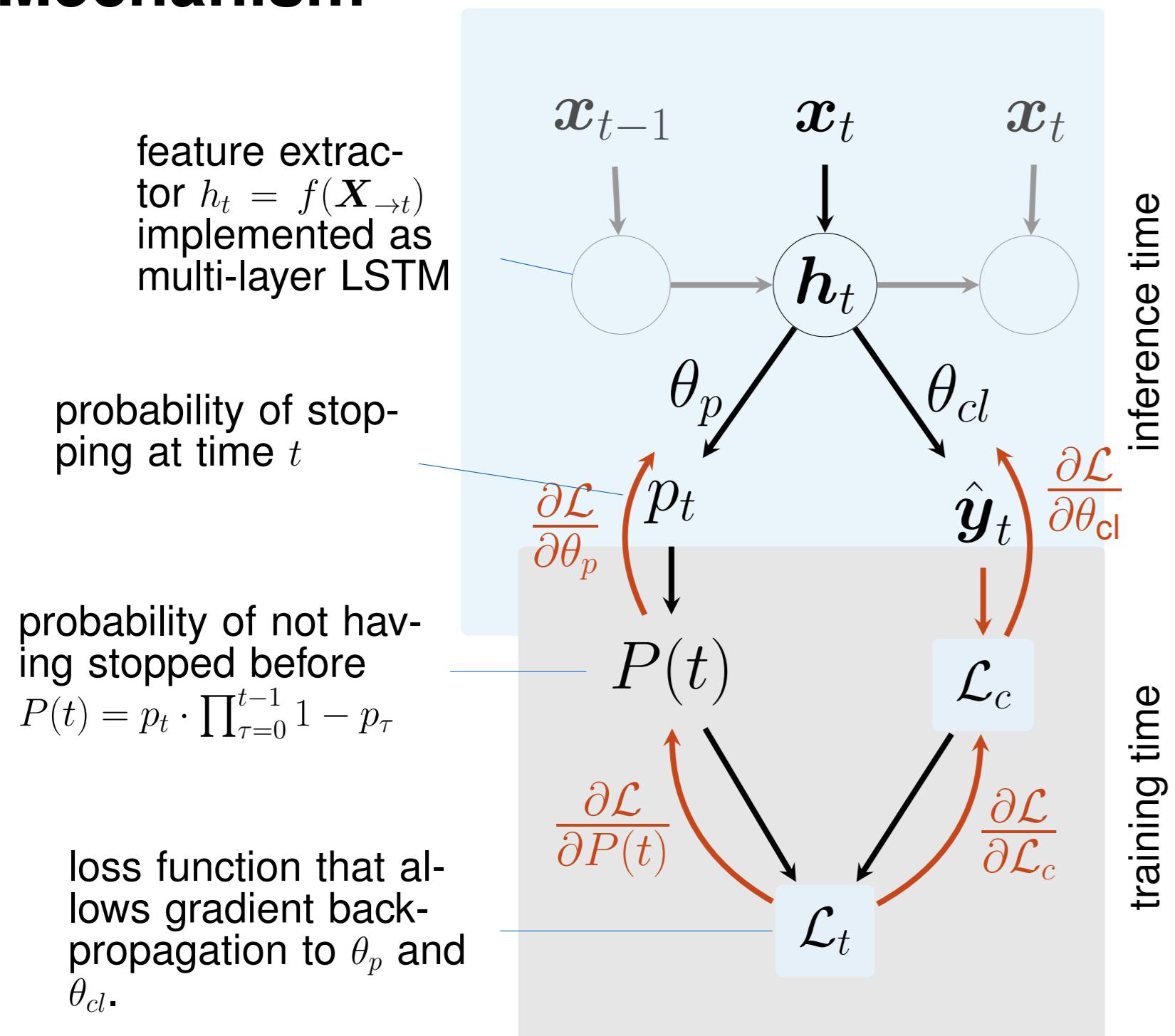
Objective



Method

Based on previous work (Rußwurm et al., 2019) applied to crop type mapping from remote sensing data.

Mechanism



Rußwurm, M., Lefèvre, S., County, N., Emonet, R., Körner, M., and Tavenard, R. End-to-end learning for early classification of time series. arXiv preprint arXiv:1901.10681, 2019.

Application

Agriculture

Early Crop Detection

- early assessment of cultivated crops
- basis for early crop yield estimation

Extraction of Crop Phenology

- extraction of vegetation specific events
- monitoring time of classification
- regional or temporal variations

Generalization

- end-to-end trainable
- applicable globally
- no region-specific expert knowledge

Loss function

composite loss function

$$\mathcal{L}(\mathbf{x}, \mathbf{y}) = \sum_{t=0}^T P(t; \delta_{\rightarrow t}) \mathcal{L}_t(\mathbf{X}_{\rightarrow t}, \mathbf{y})$$

A Loss function including accuracy and earliness

$$\mathcal{L}_t(\mathbf{X}_{\rightarrow t}, \mathbf{y}) = \alpha \mathcal{L}_c(\mathbf{X}_{\rightarrow t}, \mathbf{y}) - (1 - \alpha) \mathcal{R}_e(t, \hat{y}_t^+)$$

$$\mathcal{L}_c = -\log(\hat{y}_t^+)$$

cross entropy loss for accurate classifications

$$\mathcal{R}_e(t, \hat{y}_t^+) = \hat{y}_t^+ (1 - \frac{t}{T})$$

reduces loss for earlier classifications $1 - \frac{t}{T}$ if the correct class \hat{y}_t^+ has been predicted

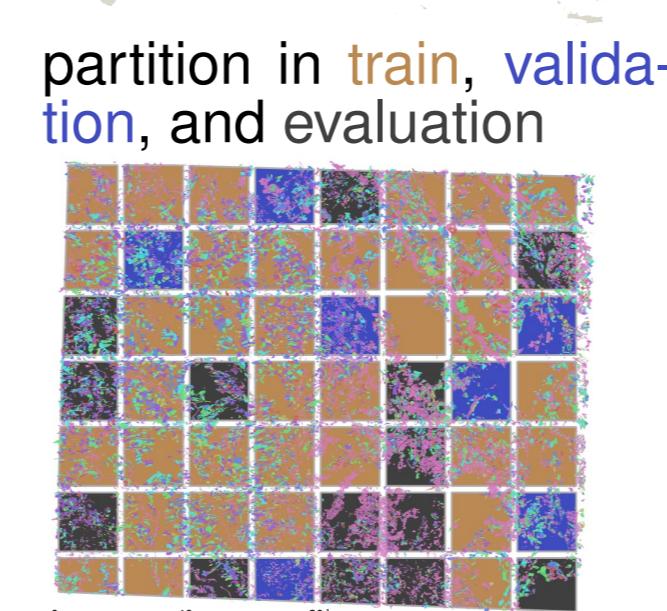
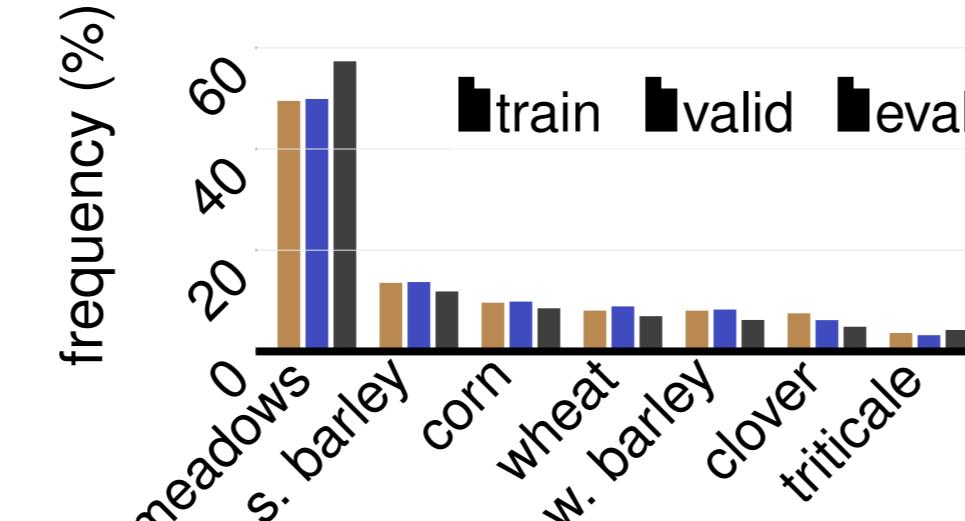
Dataset and Area of Interest

Hollfeld region Bavaria

- 49k field parcels
- 6 main crop types
- covering 40km by 30 km
- central Germany

regions with labels and location of dataset.

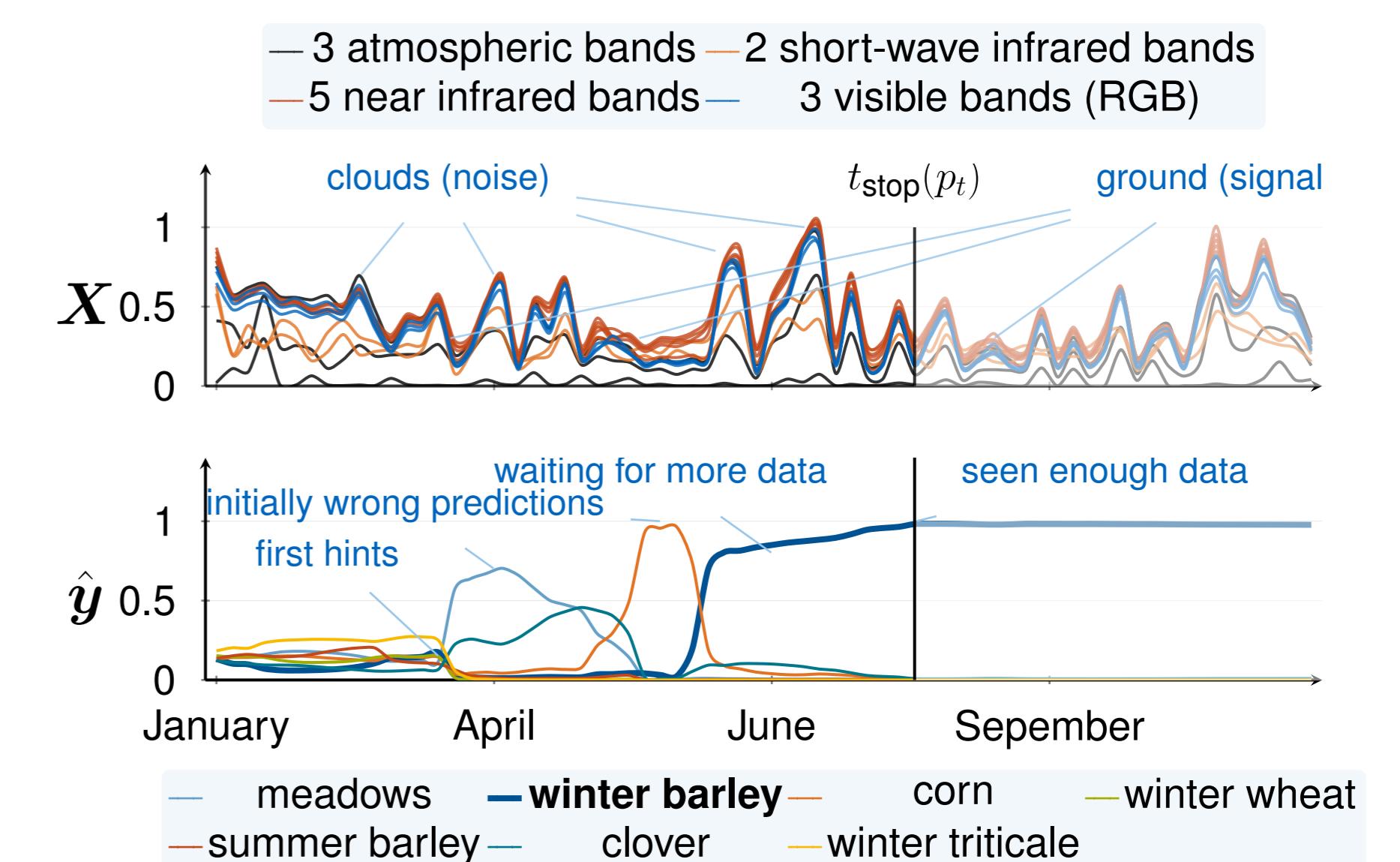
Challenge: Class imbalance



Results

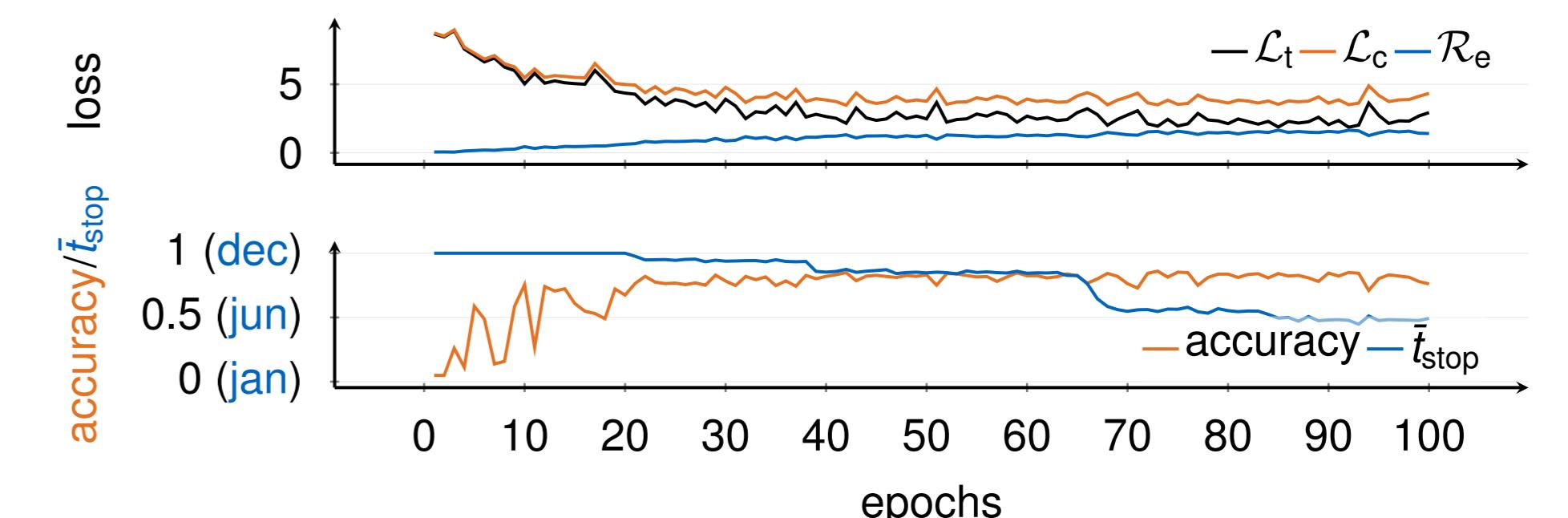
Qualitative Example

Single example showing reflectance data \mathbf{X} and predictions $\hat{\mathbf{y}}$ along with the stopping time $t_{\text{stop}} \sim \text{Ber}(p_t)$.



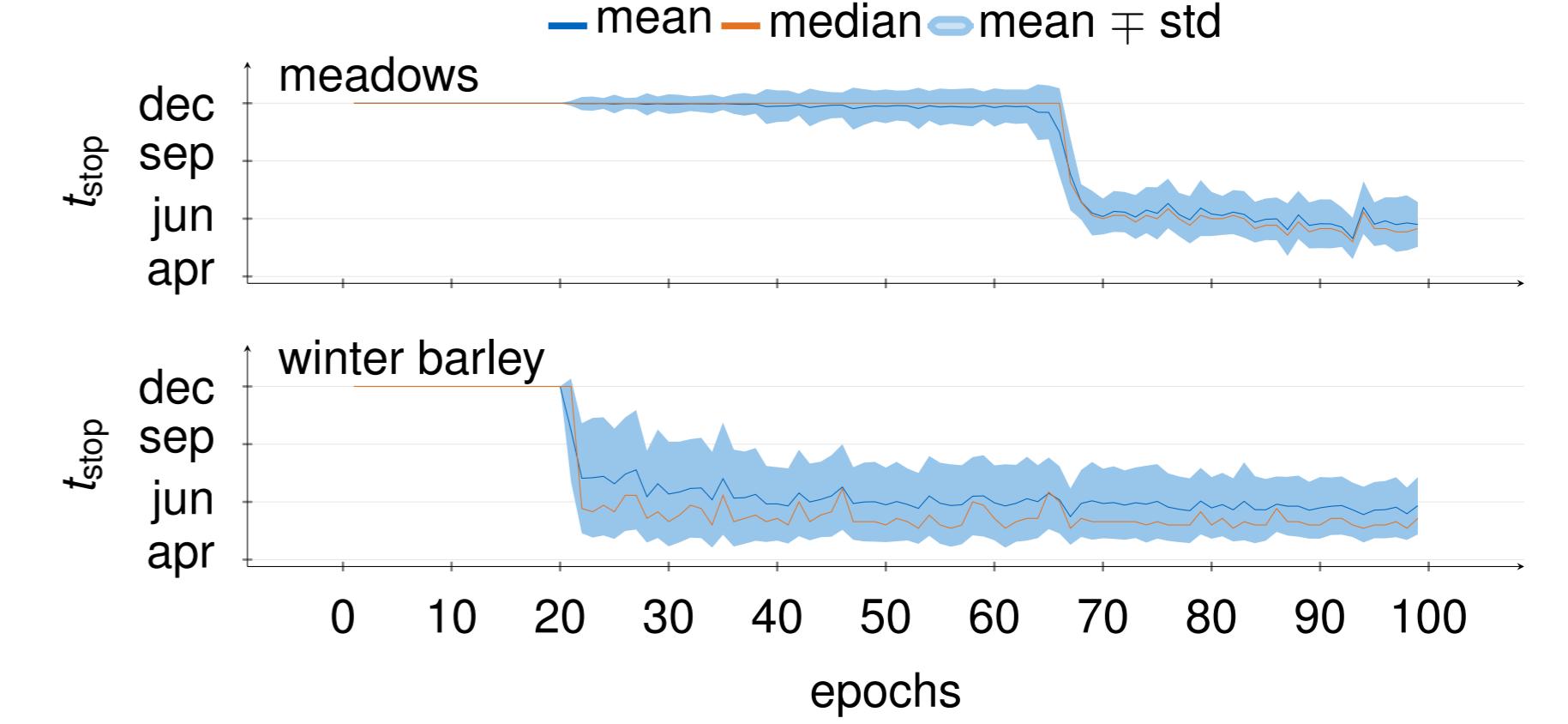
Losses during Training

The combined loss \mathcal{L}_t , as well as earliness \mathcal{L}_e and accuracy \mathcal{R}_e losses during training.



Stopping Condition Parameterization

Stopping times throughout the training grouped by crop category. The parameterization of early classification is learned for different crop types at different times during training.



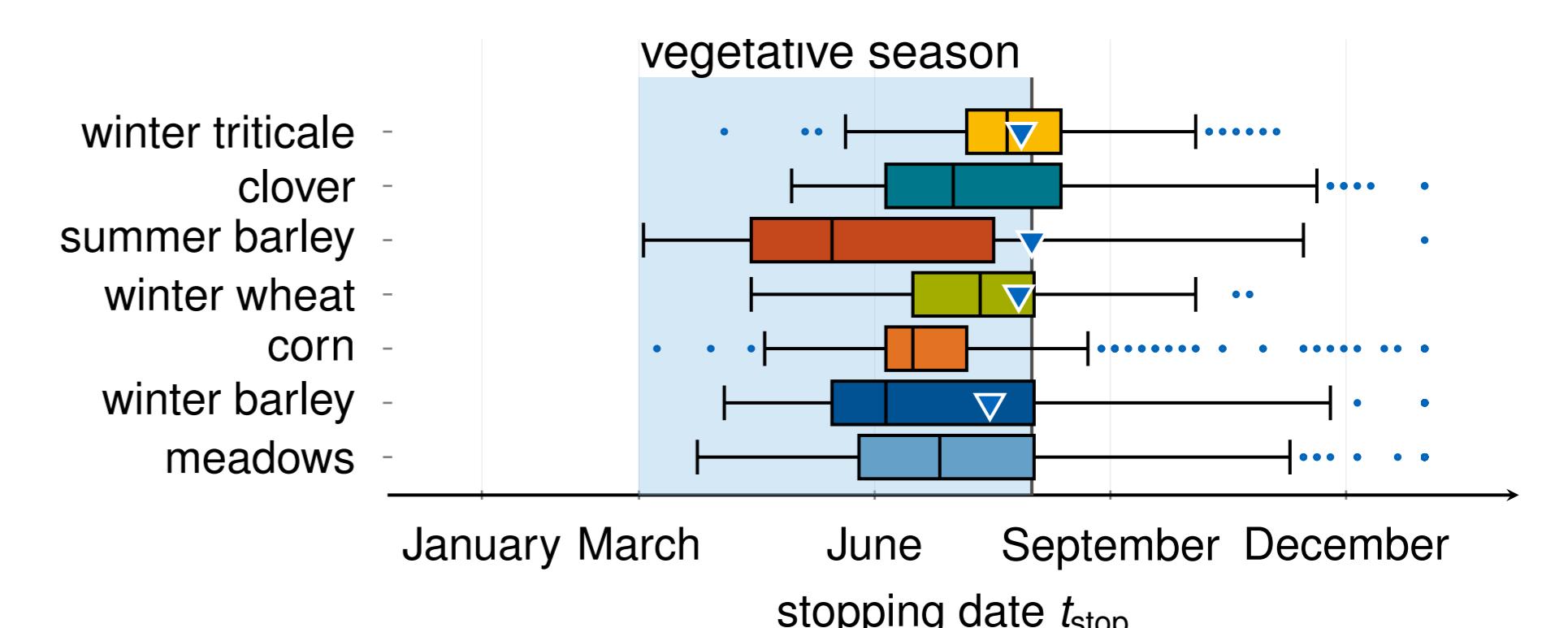
Balancing Earliness and Accuracy

Evaluating the effect of the trade-off parameter α on the accuracy and earliness (t_{stop}). Runs repeated three times to evaluated the stability of the results.

α	accuracy	\bar{t}_{stop}	precision	recall	f_1	κ
.0	.25 ± .22	.10 ± .17	.19 ± .20	.25 ± .17	.16 ± .20	.12 ± .19
.2	.81 ± .03	.40 ± .02	.70 ± .01	.74 ± .01	.71 ± .01	.71 ± .04
.4	.80 ± .09	.47 ± .03	.71 ± .02	.74 ± .01	.71 ± .02	.71 ± .10
.6	.85 ± .02	.88 ± .07	.73 ± .04	.74 ± .03	.73 ± .03	.77 ± .03
.8	.84 ± .01	.93 ± .05	.72 ± .02	.75 ± .01	.73 ± .02	.76 ± .02
1.0	.83 ± .03	1.00 ± .00	.72 ± .03	.75 ± .01	.72 ± .03	.75 ± .04

Extracting Vegetation Characteristics

Stopping time per crop category reveals characteristic variations in type of vegetation confirmed by date of harvest (▼) from local authorities.



Data & Code

https://github.com/rtavenar/early_rnn
<https://twitter.com/MarcCoru>
www.lmf.bgu.tum.de/vision

