Atvidade_3

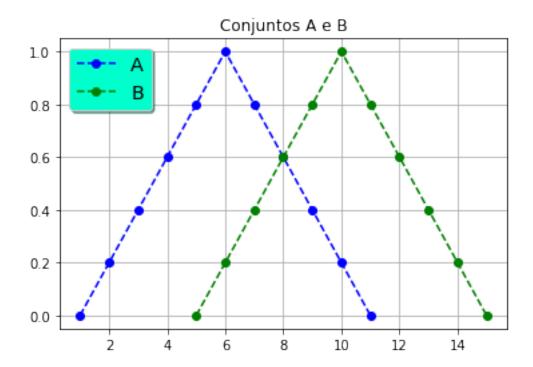
September 25, 2018

1 4. Relações Fuzzy

```
In [1]: from mpl_toolkits.mplot3d import Axes3D
    import matplotlib.pyplot as plt
    from matplotlib import cm
    from matplotlib.ticker import LinearLocator, FormatStrFormatter
    from matplotlib.collections import PolyCollection
    from matplotlib.colors import colorConverter
    import numpy as np
```

1.1 Criação dos conjuntos Fuzzy A e B

1.1.1 Representação 2D de A e B



1.2 Produto cartesiano

```
In [90]: # obtenho um array 3d a partir dos meus conjuntos fuzzy A e B
    new_set_3d = produto_cartesiano(A,B)
```

1.2.1 Representação 3D de A e B

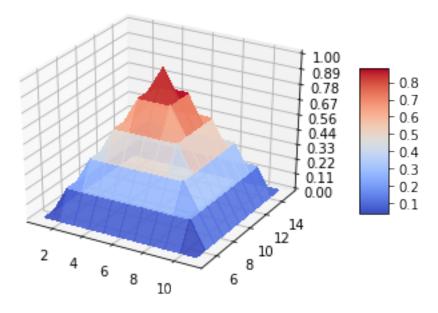
```
In [91]: def plot_conjuntos_3D(X,Y,Z):
    fig = plt.figure()
    ax = fig.gca(projection='3d')

# Plot the surface.
    surf = ax.plot_surface(X, Y, Z, alpha=0.9, cmap=cm.coolwarm, linewidth=0, antialis

# Customize the z axis.
    # ax.set_zlim(-1.01, 1.01)
    ax.zaxis.set_major_locator(LinearLocator(10))
    ax.zaxis.set_major_formatter(FormatStrFormatter('%.02f'))

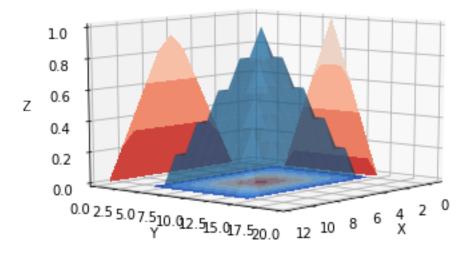
# Add a color bar which maps values to colors.
    fig.colorbar(surf, shrink=0.5, aspect=5)
```

In [92]: plot_conjuntos_3D(new_set_3d[:,:,0],new_set_3d[:,:,1],new_set_3d[:,:,2])



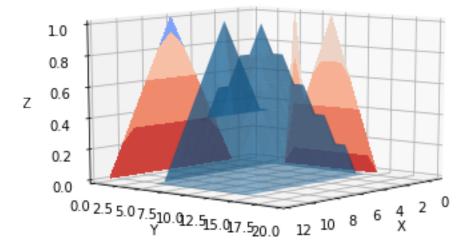
1.3 Projeção

```
In [98]: def plotar_conjunto_projetado(X, Y, Z):
                 fig = plt.figure()
                 ax = fig.gca(projection='3d')
                 ax.plot_surface(X, Y, Z, alpha=0.5) #,
                 cset = ax.contourf(X, Y, Z, zdir='z', offset=0, cmap=cm.coolwarm)
                 cset = ax.contourf(X, Y, Z, zdir='x', offset=0, cmap=cm.coolwarm)
                 cset = ax.contourf(X, Y, Z, zdir='y', offset=0, cmap=cm.coolwarm)
                 ax.set_xlabel('X')
                 ax.set_xlim(-1, 12)
                 ax.set_ylabel('Y')
                 ax.set_ylim(0, 20)
                 ax.set_zlabel('Z')
                 ax.view_init(10, 40)
                 ax.set_zlim(0, 1)
In [99]: plotar_conjunto_projetado(np.copy(new_set_3d[:,:,0]),
                         np.copy(new_set_3d[:,:,1]),
                         np.copy(new_set_3d[:,:,2]))
```



```
In [93]: def plotar_projecao(X, Y, Z):
```

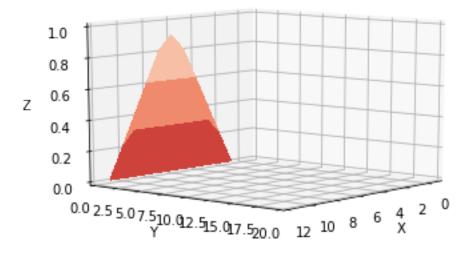
```
fig = plt.figure()
ax = fig.gca(projection='3d')
for i in range(X.shape[0]):
    for j in range(X.shape[1]):
        Z[i][1] = max(A[i][1],B[j][1])
ax.plot_surface(X, Y, Z, alpha=0.5) #,
\#cset = ax.contourf(X, Y, Z, zdir='z', offset=0, cmap=cm.coolwarm)
cset = ax.contourf(X, Y, Z, zdir='x', offset=0, cmap=cm.coolwarm)
cset = ax.contourf(X, Y, Z, zdir='y', offset=0, cmap=cm.coolwarm)
ax.set_xlabel('X')
ax.set_xlim(-1, 12)
ax.set_ylabel('Y')
ax.set_ylim(0, 20)
ax.set_zlabel('Z')
ax.view_init(10, 40)
ax.set_zlim(0, 1)
```

1.4 Extensão cilíndrica

1.4.1 Conjunto Fuzzy A no eixo X

```
In [96]: plotar_projecao_cil_1(new_set_3d[:,:,0],new_set_3d[:,:,1],new_set_3d[:,:,2])
```



2 Referências

- create 3-dimensional arraysPot 3d WITH MATPLOTLIB