

$$\dot{s}(x,t) = a(x) \partial_x s + b(x) \partial_x^2 s + c(x) s$$

$$\dot{x} = a(x) \cdot x$$

1 Non-Flat Mutation Rates

$$\bar{r} \dot{x}_i = u_i r_{i-1} x_{i-1} + x_i (r_i (1 - u_{i+1}) - \bar{r})$$

$$r = \text{const.}$$

$$\dot{\rho}_i = u_i \rho_{i-1} - \rho_i u_{i+1}$$

$$\dot{\rho}(x,t) = u(x) \rho(x - \Delta x, t) - \rho(x,t) u(x + \Delta x, t)$$

$$= u(x) \left(\rho(x) - \Delta x \frac{\partial \rho}{\partial x} + \Delta x^2 \frac{\partial^2 \rho}{\partial x^2} \right) - \rho(x,t) \left(u(x) + \Delta x \frac{\partial u}{\partial x} + \Delta x^2 \frac{\partial^2 u}{\partial x^2} \right)$$

$$\Delta x = 1$$

$$\dot{\rho}(x,t) = -u \frac{\partial \rho}{\partial x} + u \frac{\partial^2 \rho}{\partial x^2} - \rho \left(\frac{\partial u}{\partial x} + \frac{\partial^2 u}{\partial x^2} \right)$$

$$\frac{\partial^2}{\partial x^2}(us) - 2 \cdot \frac{\partial s}{\partial x} \frac{\partial u}{\partial x}$$

Collecting up some terms.

$$\dot{\rho} = -\frac{\partial}{\partial x}(\rho u) + u \frac{\partial^2 \rho}{\partial x^2} - \rho \frac{\partial^2 u}{\partial x^2}$$

Fourier transform convention

$$\bar{\rho} = \int_{-\infty}^{\infty} \rho e^{-ikx} dx \quad (1)$$

$$\dot{\bar{\rho}} = -\int \frac{\partial}{\partial x}(\rho u) e^{-ikx} dx + \int u \frac{\partial^2 \rho}{\partial x^2} e^{-ikx} dx - \int \rho \frac{\partial^2 u}{\partial x^2} e^{-ikx} dx$$

$$\begin{aligned} \int \frac{\partial}{\partial x}(\rho u) e^{-ikx} dx &= [e^{-ikx} \rho u]_{-\infty}^{\infty} - \int (-ik) \rho u e^{-ikx} dx \\ &= ik \int \rho u e^{-ikx} dx \end{aligned}$$

Applying the convolution theorem:

$$F(f \cdot g) = F(f) * F(g)$$

$$f * g = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} g(y) f(x-y) dy$$

Need to prove these.

Applying this to the new differential equation.

$$\dot{\bar{\rho}} = -ik(\mathcal{F}(\rho) * \mathcal{F}(u)) + (\mathcal{F}(u) * \mathcal{F}(\frac{\partial^2 \rho}{\partial x^2})) - (\mathcal{F}(\rho) * \mathcal{F}(\frac{\partial^2 u}{\partial x^2}))$$

Using what we know for the differentials and Fourier bits.

$$(-k^2) \cdot \mathcal{F}(u)$$

$$\dot{\tilde{\rho}} = -ik(\tilde{\rho} * \tilde{u}) + (\tilde{u} * (-k^2)\tilde{\rho}) - (\tilde{\rho} * (-k^2)\tilde{u})$$

We can take out the factors of k^2 .

$$\begin{aligned}\dot{\tilde{\rho}} &= -ik(\tilde{\rho} * \tilde{u}) - k^2((\tilde{u} * \tilde{\rho}) + (\tilde{\rho} * \tilde{u})) \\ &= (-ik - 2k^2)(\tilde{\rho} * \tilde{u})\end{aligned}$$

Convolution is commutative.

Chose a simple $u = \cos(\frac{\pi}{2M}x)$.

$$\tilde{u} = \delta(k)$$

$$\begin{aligned}\tilde{u} &= \int \cos(\frac{\pi}{2M}x) e^{-ikx} dx \\ &= \frac{1}{2} \int (e^{i\frac{\pi}{2M}x} + e^{-i\frac{\pi}{2M}x}) e^{-ikx} dx \\ &= \frac{1}{2} \left(\delta(k - \frac{\pi}{2M}) + \delta(k + \frac{\pi}{2M}) \right)\end{aligned}$$

Convolution of a delta function just returns the same function with the variable shifted.

$$f(x) * \delta(x \pm a) = f(x \pm a) \quad (2)$$

$$\begin{aligned}\tilde{\rho} * \tilde{u} &= \tilde{\rho} * \frac{1}{2} \left(\delta(k - \frac{\pi}{2M}) + \delta(k + \frac{\pi}{2M}) \right) \\ &= \frac{1}{2} \left(\tilde{\rho}(k - \frac{\pi}{2M}) + \tilde{\rho}(k + \frac{\pi}{2M}) \right)\end{aligned}$$

Combining everything in one.

$$\dot{\tilde{\rho}} = -\frac{(ik + k^2)}{2} \left(\tilde{\rho}(k - \frac{\pi}{2M}) + \tilde{\rho}(k + \frac{\pi}{2M}) \right)$$

$$\underline{\underline{S}} = \begin{pmatrix} S_{k-2\pi/2M} \\ S_{k-\pi/2M} \\ S_k \end{pmatrix}$$

$$\dot{S}_k = \begin{pmatrix} \dots \end{pmatrix} \quad S_{k-1} \quad S_{k+1}$$

$$\underline{\underline{\dot{S}}} = \begin{pmatrix} \ddots & & & \\ & \ddots & & \\ & & \ddots & \\ & & & \ddots \end{pmatrix} \underline{\underline{S}}$$